Task 1. Run the code below.

Below we have an example code that performs the task of predicting a sine function using a simple fully connected three-layer network from lab 8. Recently, the model was trained with randomly generated values during training. In this task, we will generate a set before training. Noise and errors that normally occur in training sets have been added to the set. **The task is to present the problem of network overfitting.** The problem occurs when the network learns individual cases "by heart". In such cases, erroneous data and outliers have a significant impact on the trained model. We want rather our network to generalize knowledge.

main code: lab9.py

```
model = Model(1024)
def data plot(title, x, y, y2=None):
  fig, ax = plt.subplots()
  ax.plot(x, y, 'o')
      ax.plot(x, y2, 'o')
  ax.legend(title)
  plt.show()
def data fun(batch=30, range = 2*torch.pi):
 x = torch.rand(batch, 1) *range
  return x, torch.sin(x)
x, y = data fun(150)
print("x=",x)
print("y=",y)
data_plot(["Fun test"], x, y)
```

```
def dataset_gen(batch=500, range = 2*torch.pi, noise=True, errors=True):
  x, y true = data fun(batch)
  y real = y true.clone()
  if noise:
  y real2 = y real.clone()
      num = .15
      idx = (torch.rand(int(batch*num))*batch).long()
     y real2[idx, :] += .1+torch.rand(int(batch*num), 1)*0.6
      idx = (torch.rand(int(batch*num))*batch).long()
      y real2[idx, :] -= .1+torch.rand(int(batch*num), 1)*0.6
  return x, y real2, y true
dataset = dataset gen(200)
data plot(["Real data", "Fun data"], *dataset)
def data gen(dataset, batch=30):
 size = dataset[0].size(0)
 idx = (torch.rand(batch)*size).long()
  return dataset[0][idx], dataset[1][idx], dataset[2][idx]
data plot(["Batch sample", "Fun"], *data gen(dataset))
device = "cuda" if torch.cuda.is available() else "cpu"
print("device: %s"%device)
model = model.to(device)
print("Train")
model.train()
optimizer = torch.optim.Adam(model.parameters(), lr=0.001)
loss fn = torch.nn.MSELoss(reduction="mean")
for epoche in range(30):
 err = 0
 true error = 0
  for step in range (50):
```

```
inputs, labels, ground true = data gen(dataset, 100)
      inputs = inputs.to(device)
      ground true = ground true.to(device)
      optimizer.zero grad()
      outputs = model(inputs)
      loss = loss fn(outputs, labels)
      loss.backward()
      optimizer.step()
      err += loss.item()
      true error += loss fn(outputs, ground true).item()
      print("\rerror = %f , real= %f"%(err, true error), end="")
  print("\repoch= %d error= %f, real=%f"%(epoche,err, true error))
model.eval()
x, y dataset, y true = dataset
y pred = model(x)
eval error = loss fn(y pred, y true).item()
print("eval dataset error: %f"%eval error)
data plot(["Pred(dataset x)", "Dataset(dataset x)"], x, y pred.detach(),
y dataset)
data plot(["Pred(dataset x)", "Fun(dataset x)"], x, y pred.detach(), y true)
model.eval()
x, y true = data fun(dataset[0].size(0))
y pred = model(x)
eval error = loss fn(y pred, y true).item()
print("eval random error: %f"%eval error)
data plot(["Pred(rand x)", "Fun(rand x)"], x, y pred.detach(), y true)
```

Task 2.

Change the number of network parameters. Investigate the effect of reducing the number of parameters of the neural network model and increasing it.

Task 3.

Investigate the effect of reducing or increasing the size of the entire dataset.

Task 4.

Investigate the effect of reducing or increasing the **batch** size

Task 5.

Modify the model and verify how the modification affects the results. Add another layer to the model and reduce the number of parameters the layers take. Verify the results.

Task 6.

Find the best set of parameters and shape of the neural network model.

Task 7.

Carry out exercise 6 for other data generating functions (Invent some other function).

Task 8.

Prepare a report.