

The *forth* Software Engineering Group 19 Project *status* meeting will be held in **Inggarni Wardli Room 4.62** at **3:30pm** on **Tuesday 1 September 2015**.

Agenda

Chair: Wei Jingwen

1 Present

- a1657343 Luo Yawen (Documentation Team)
- a1662541 Yang Jiajun (Programming Team)
- a1653772 Zhang Yun (Project Manager)
- a1671836 Wei Jingwen (Programming Team)
- a1690773 Wang Yuzhu (Documentation Team)
- a1146944 Zander Shaun Nathan (Documentation Team)

2 Absent with no Apologies

- a1651541 Lee So Min

3 Client

- *MesaMap* Company

4 Meeting Content

The group shall highlight and clarify with the client on the following items:

4.1 Robot Movement Demo

4.2 SRS Critique

1. Should use case diagram included in the SRS?
2. Except the robot operator, is there any other worker or external system using this system?
3. Does communication between robot and control center need to be encrypted?
4. Is there any requirement about performance requirement about the robot exploring the map? e.g, How long at maximum does it take the robot to finish exploration? How far does the robot travel before completing its exploration task?
5. Should data be cached in the robot? If so, how long should it save the data?
6. Should warnings such as low battery level be raised? If so, how to deliver them to users? Is it all right that the control center just show them on the GUI?
7. For priority of each requirement, do we need to describe and explain priorities specifically?
8. Do we need to add the anticipated achievement and error encountered? If so, in which part?
9. Can we implement some features that are not requested by the customer?
10. Should we use like use case, mode of operation, user class, object class and functional hierarchy in each system feature, or just one in one feature?

5 Next Meeting

Note: Next meeting to be held at **3:30pm** on **8 September, 2015**.