The *second* Software Engineering Group *19* Project *status* meeting will be held in **Ingkarni Wardli Room 4.62** at **3:30pm** on **Monday 18 August 2015**.

Agenda

Chair: Luo Yawen

1 Present

- a1657343 Luo Yawen (Documentation Team)
- a1662541 Yang Jiajun (Programming Team)
- a1653772 Yun Zhang (Project Manager)
- a1671836 Wei Jingwen (Programming Team)
- a1690773 Wang Yuzhu (Documentation Team)
- a1146944 Zander Shaun Nathan (Documentation Team)

2 Absent with no Apologies

- a1651541 Lee So Min

3 Client

- *MesaMap* Company

4 Objectives

4.1 Requirement Elicitation

Review the last meeting and if there are some unsure issues.

1. How do you define a no go zone? Colour? Shape?
2. Is the communications tower and operation base considered as a single building?
3. The robot need to work automatically, in what scenario does it need to work automatically?
4. How many different types of area, and how does the robot detects the different areas?
5. After finishing the map, dose the robot need to tell itself the no-go zones or it's just controlled by us?
6. If we lost communication between the robot and the operator, the robot should stop or go back?
7. When will be a suitable DTD available?
8. Dose the client provide a paper/card for representing of the terrain, or we construct it?
9. What does the reference mean in the template of SPMP? Is it the normal reference?
10. Will the base tower ever move? Will there only one?
11. Are cliffs only on the external edge of the mesa?
12. What is the communication way ? Wifi, or Bluetooth or cable?
13. What is the effective distance range of the central control brick?
14. For every single change in the procedure of the SEP, de we need to demonstrate it in documents or we just include the latest version?

4.2 Milestone

The group starts to allocate whole tasks and prepares the initial milestone to negotiate.

5 Next Meeting

Note: Next meeting to be held at **3:30pm** on **25 August, 2015**.

No.	Planned Features	Features Demonstrated (tick if same)
1	Finish Software Requirements Specification (SRS) 1st Draft - week 5	
2	Robot Movement Demo - week 6	
3	SRS feedback negotiation - week 6	
4	Finish Software Engineering and Project Software Project Management Plan (SPMP) 1st Draft - week 7	
5	Finish Software Design Document (SDD) 1st Draft - week 8	
6	SPMP feedback negotiation - week 8	
7	Robot Movement - week 9	
8	Software test - week 9	
9	Testing report - week 9	
10	SDD feedback negotiation - week 10	
11	Finish user manual - week 11	
12	Submit final draft - week 12	
13	Final project presentation - week 13	

Signature:
