

# NEAT and HyperNEAT

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# Neuroevolution

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# Fixed Topology Evolution

- Searching the space of connection weights
- Topology is given, does not change during evolution

- Technical challenges:
  - good representation
  - not removing non-optimized network too early
  - minimisation of networks without need for a complexity function
- TWEANNs - Topology and Weight Evolving Artificial Neural Networks

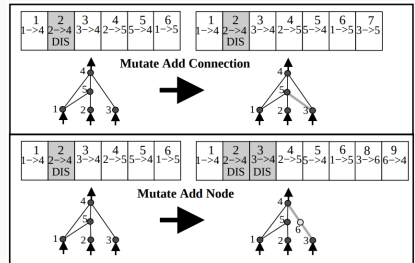
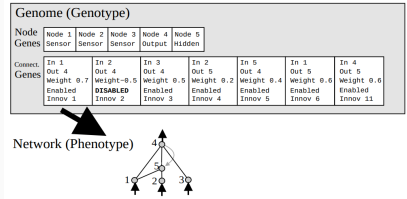
NEAT

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- NeuroEvolution of Augmenting Topologies
- Stanley and Miikkulainen, 2002
- solves all the issues aforementioned issues

# Encoding and Mutation

- linear representations of network connectivity
  - 2 types of genes (nodes and connections)
  - innovation number
  - node
- 3 types of mutation
  - connection weight mutation
  - new node
  - new connection

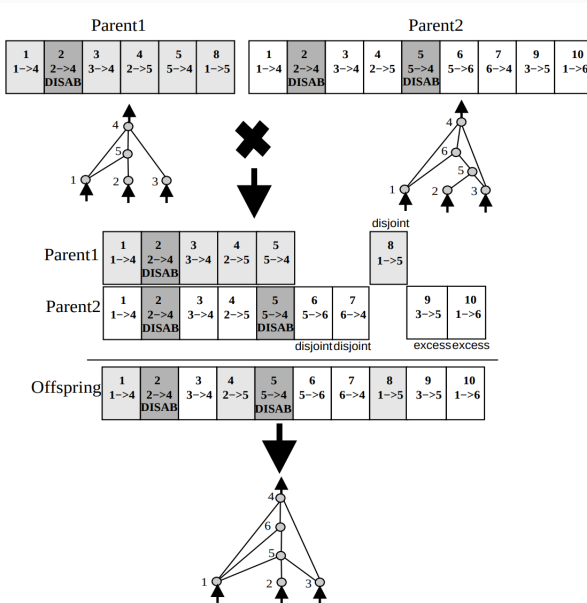


# Historical Markings and Crossover

- innovation number
  - new gene via mutation → global innovation number++
  - used to line-up genomes during crossover
- crossover
  - matching genes randomly
  - all disjoint and excess genes



# Crossover



# Speciation

- population is divided into species based on compatibility history

$$\delta = \frac{c_1 E}{N} + \frac{c_2 D}{N} + c_3 \overline{W}$$

and compatibility threshold  $\delta_t$

- each population is assigned number of offsprings based on sum of its *adjusted* fitnesses

$$f'_i = \frac{f_i}{\sum_{j=1}^n sh(\delta(i, j))}$$

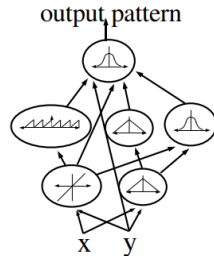
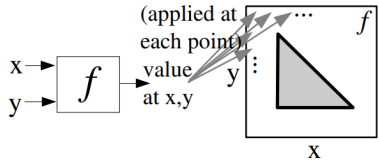
- novel topologies are protected from extinction

# HyperNEAT

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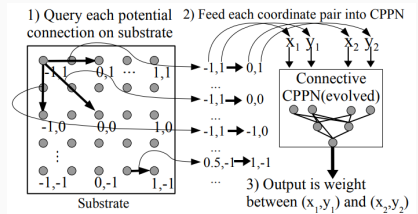
# Compositional Pattern Producing Networks

- represent repeating patterns in cartesian space
- nodes are functions
- simple functions can be composed into networks producing complex patterns (repetition, symmetry)



# HyperNEAT

- CPPNs evolved via NEAT
- nodes are given (2D grid)
- input: 2 points, output: weight of connection



- types
  - 2D grid
  - 3D grid
  - sandwich (*state-space sandwich*)
  - circular
- placement of inputs and outputs can be exploited
- can be up/down-scaled

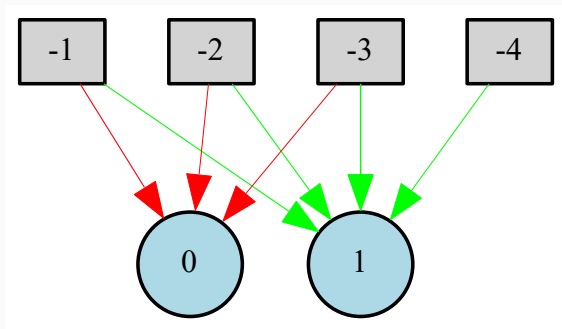
## Performance and examples

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- used environment - OpenAI Gym, Cartpole-v1
- our results (GIFs) - <https://imgur.com/a/4nLJ4oV>
- other methods -  
<https://github.com/adibyte95/CartPole-OpenAI-GYM>



## NEAT and cartpole



# HyperNEAT and cartpole

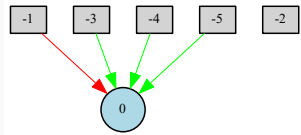


Figure 1: CPPN

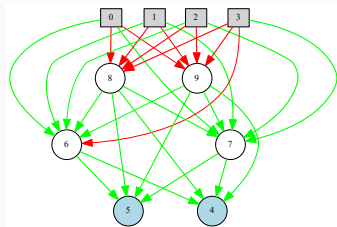


Figure 2: ANN

# Comparison

| Method          | Evaluations | Generations | No. Nets |
|-----------------|-------------|-------------|----------|
| Ev. Programming | 307,200     | 150         | 2048     |
| Conventional NE | 80,000      | 800         | 100      |
| SANE            | 12,600      | 63          | 200      |
| ESP             | 3,800       | 19          | 200      |
| NEAT            | 3,600       | 24          | 150      |

Figure 3: Pole balancing results

| Method | Evaluations | Generalization | No. Nets |
|--------|-------------|----------------|----------|
| CE     | 840,000     | 300            | 16,384   |
| ESP    | 169,466     | 289            | 1,000    |
| NEAT   | 33,184      | 286            | 1,000    |

Figure 4: Double pole balancing results