

NEAT and HyperNEAT

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Neuroevolution

Fixed Topology Evolution

- Searching the space of connection weights
- Topology is given, does not change during evolution

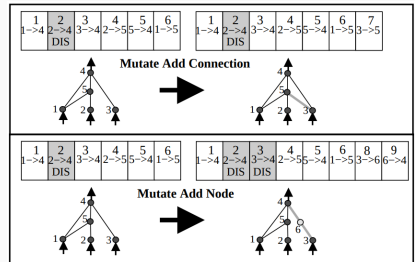
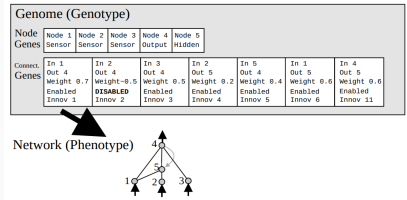
- Technical challenges:
 - good representation
 - not removing non-optimized network too early
 - minimisation of networks without need for a complexity function
- TWEANNs - Topology and Weight Evolving Artificial Neural Networks

NEAT

- NeuroEvolution of Augmenting Topologies
- Stanley and Miikkulainen, 2002
- solves all the issues aforementioned issues

Encoding and Mutation

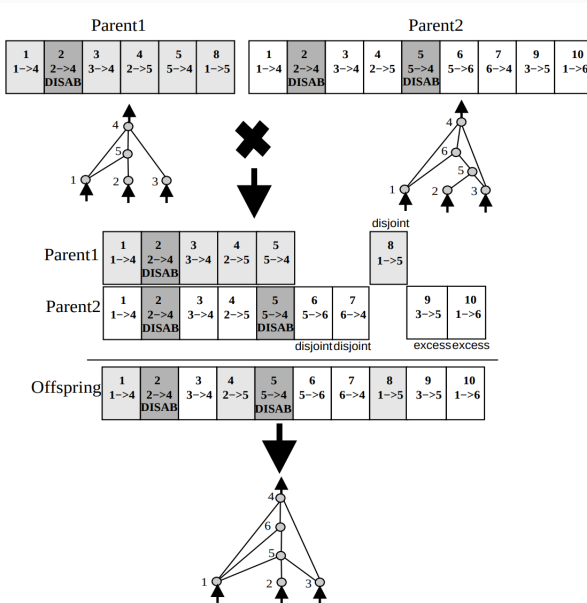
- linear representations of network connectivity
 - 2 types of genes (nodes and connections)
 - innovation number
 - node
- 3 types of mutation
 - connection weight mutation
 - new node
 - new connection



Historical Markings and Crossover

- innovation number
 - new gene via mutation → global innovation number++
 - used to line-up genomes during crossover
- crossover
 - matching genes randomly
 - all disjoint and excess genes

Crossover



Speciation

- population is divided into species based on compatibility history

$$\delta = \frac{c_1 E}{N} + \frac{c_2 D}{N} + c_3 \overline{W}$$

and compatibility threshold δ_t

- each population is assigned number of offsprings based on sum of its *adjusted* fitnesses

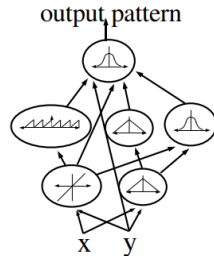
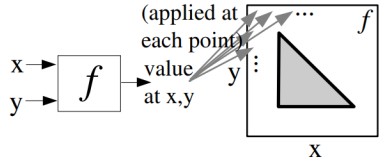
$$f'_i = \frac{f_i}{\sum_{j=1}^n sh(\delta(i, j))}$$

- novel topologies are protected from extinction

HyperNEAT

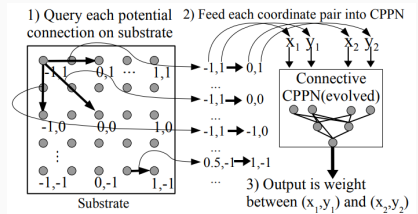
Compositional Pattern Producing Networks

- represent repeating patterns in cartesian space
- nodes are functions
- simple functions can be composed into networks producing complex patterns (repetition, symmetry)



HyperNEAT

- CPPNs evolved via NEAT
- nodes are given (2D grid)
- input: 2 points, output: weight of connection

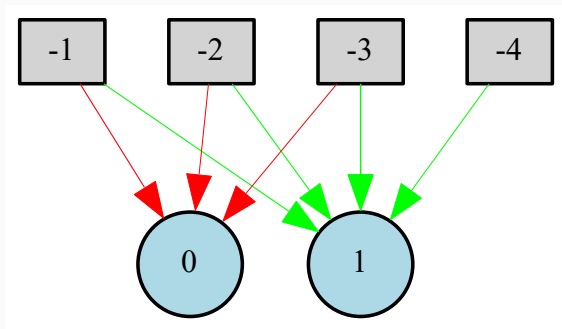


- types
 - 2D grid
 - 3D grid
 - sandwich (*state-space sandwich*)
 - circular
- placement of inputs and outputs can be exploited
- can be up/down-scaled

Performance and examples

- used environment - OpenAI Gym, Cartpole-v1
- our results (GIFs) - <https://imgur.com/a/4nLJ4oV>
- other methods -
<https://github.com/adibyte95/CartPole-OpenAI-GYM>

NEAT and cartpole



HyperNEAT and cartpole

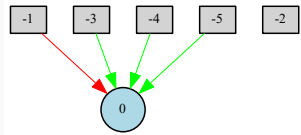


Figure 1: CPPN

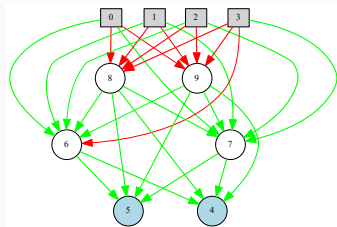


Figure 2: ANN

Comparison

Method	Evaluations	Generations	No. Nets
Ev. Programming	307,200	150	2048
Conventional NE	80,000	800	100
SANE	12,600	63	200
ESP	3,800	19	200
NEAT	3,600	24	150

Figure 3: Pole balancing results

Method	Evaluations	Generalization	No. Nets
CE	840,000	300	16,384
ESP	169,466	289	1,000
NEAT	33,184	286	1,000

Figure 4: Double pole balancing results

NEAT ablations

Method	Evaluations	Failure Rate
No-Growth NEAT (Fixed-Topologies)	30,239	80%
Nonspeciated NEAT	25,600	25%
Initial Random NEAT	23,033	5%
Nonmating NEAT	5,557	0
Full NEAT	3,600	0

Summary

- all components of NEAT are important
- NEAT is better than other EAs in imitating evolution by *"both optimizing and complexifying solutions"*
- good for complex problems
- HyperNEAT - good input of high dimension (Cartpole is too simple)
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