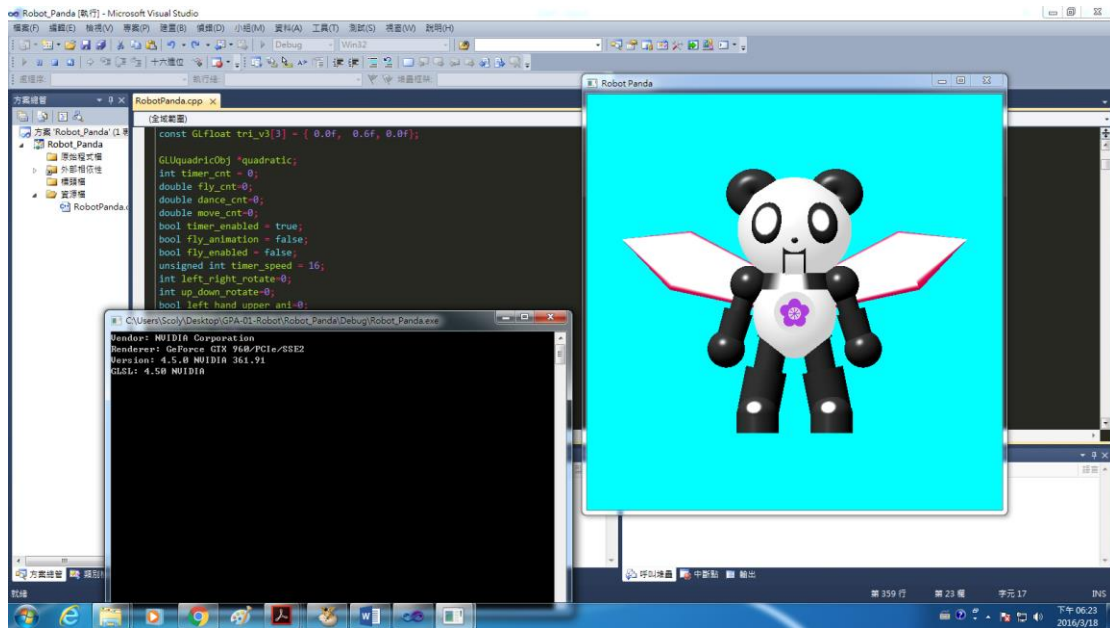


# AS1\_Report

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## ◆ Screenshot



## ◆ README

Manipulate:

- Control the position of the robot by ADWS
- Control the rotation of the robot by  $\uparrow \downarrow \leftarrow \rightarrow$
- Open the menu by right click on the window

Menu:

- Center: Center the robot
- Animation:
  - Fly: Fly
  - Dance: Dance
  - Stop: Stop the animation
- Exit: Leave the program

Note1: The rocket would beam out energy while flying

Note2: Changing animations would stop the current animation

Note3: Before starting animations, the robot would press the button in front of him.

Using Visual Studio 2010

## ◆ Part Relation Diagram

