

Dynamics of the COVID-19 Spread by Modified Graphical Network Analysis

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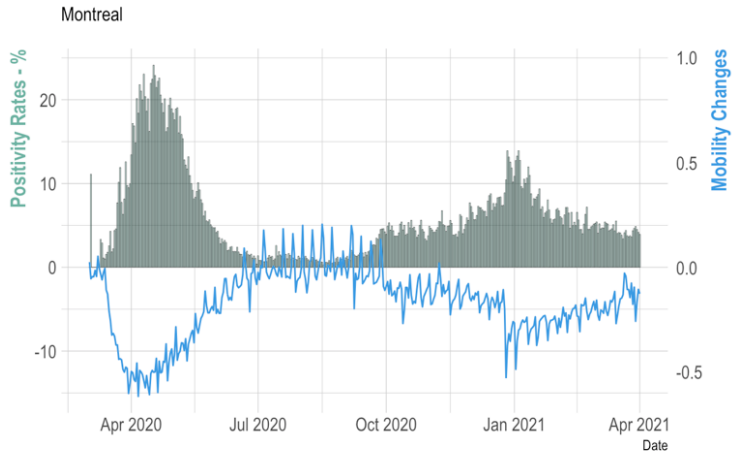
Motivation

- ▶ Can we recover the short-term temporal dynamics in the relationship between two (or more) time-series signals with minimum assumptions (about data structure, model)?
- ▶ For example, a method is needed to identify the number of days required to generate an intended effect on positivity rates (PR) following the mobility restrictions.
- ▶ Although the evidence unambiguously indicates successful mobility restrictions have the largest effect on curbing the pandemic (before vaccines), studies looking at the dynamics of these confinement policies are rare.
- ▶ This method can be implemented to any two time-series signals (**with a known direction of correlation**) to recover dynamic correlations.

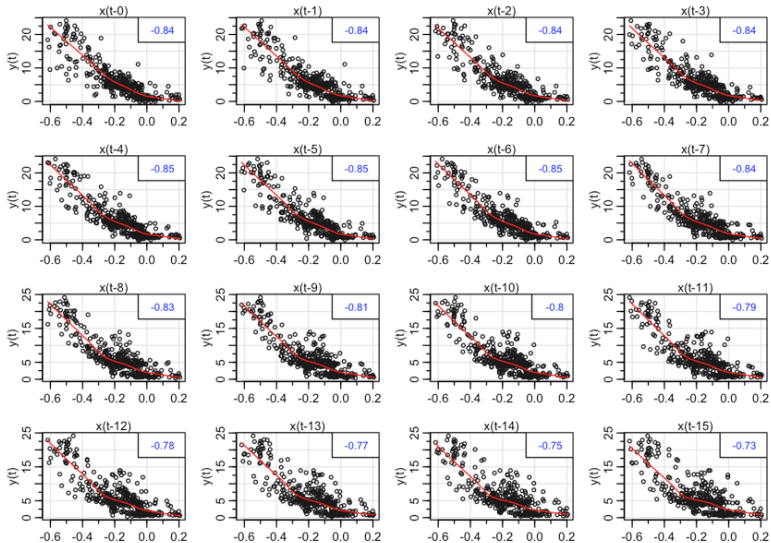
Summary

- ▶ Two time-series signals: X_t and Y_t and both are $I(0)$,
- ▶ $X_t \rightarrow Y_{t+s}$ and $s \neq 0$ and $s \in \{1 : 21\}$,
- ▶ Find s^* that maximizes the partial correlation between X_t and Y_{t+s}
- ▶ Since s^* is not constant (time-varying relationship), sliding-window correlations are calculated
- ▶ Window length can be found by a wavelet analysis (as in TVFC literature)
- ▶ Since the algorithm searches for s^* in the window, we need to be sure that it represents the genuine association between two series. It must be distinguishable from lagged synchrony that would occur by chance.
- ▶ Regularization and statistical significance can solve (or reduce) this problem

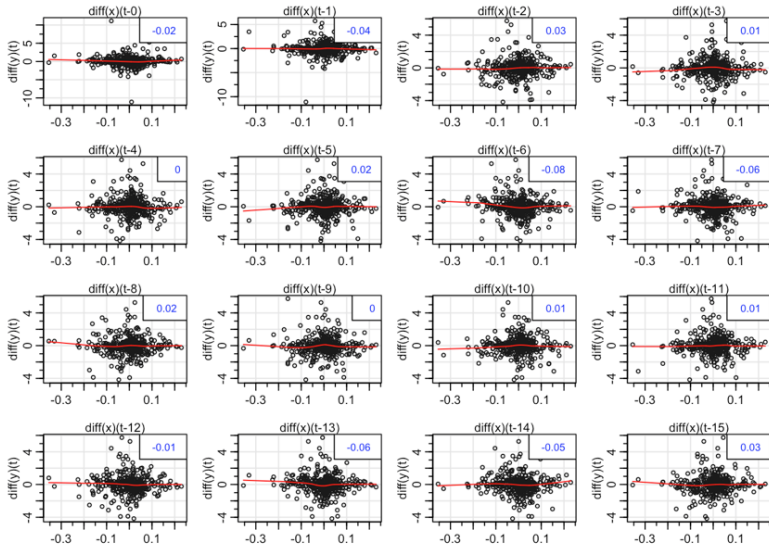
Example: PR vs. Mobility



Cross-Correlations - Level



Cross-Correlations - (diff)



Why correlations have no meaning?

- ▶ Reverse causality: mobility reduction as a response to spikes in cases.
- ▶ Mobility shows its effect on PR dynamically (over time).
- ▶ They are zero-order cross-correlations
- ▶ There is no static relationship. For instance, 7 day-lag could be too short or too long in different windows.
- ▶ Contacts are not homogeneous across individuals and locations.

COVID-19: Effect of mobility on PR

- ▶ We use only observed data: Positivity Rate (cases/tests) and Mobility index (Facebook)
- ▶ Take them as two time-series signals and see if we can recover any meaningful relationship between them
- ▶ We use Montreal, as it is the most detailed COVID-19 Data (not publicly available)

TVFC

- ▶ Recently, **time-varying functional connectivity** (TVFC) has emerged as a major topic in the resting-state BOLD fMRI literature.
- ▶ TVFC uses running correlations between pairs of stochastic time series to identify their low-frequency evolution, which gives an idea about the functional organization of the brain
- ▶ Other fields, like Environmental Science, Behavioral Psychology, and Finance use rolling correlations as their main tool
- ▶ TVFC measures **simultaneous associations** between two series in sliding-windows
- ▶ The problem of “window-size” still remains as a main challenge in both methods:
 - ▶ **very long windows eventually measure static connectivity.**
 - ▶ **shorter windows can increase sensitivity for detecting short transition states but at the expense of decreasing the signal-to-noise ratio**

Modified TVFC

- ▶ **Ground truth:** the mobility changes must predict the events of infection measured by PR, only if mobility changes occur before the events of PR.
- ▶ Estimate the association with dynamically selected delays
- ▶ So that the only one lag (i.e., the time difference in starting points of both series) maximizes the strength of their positive association.

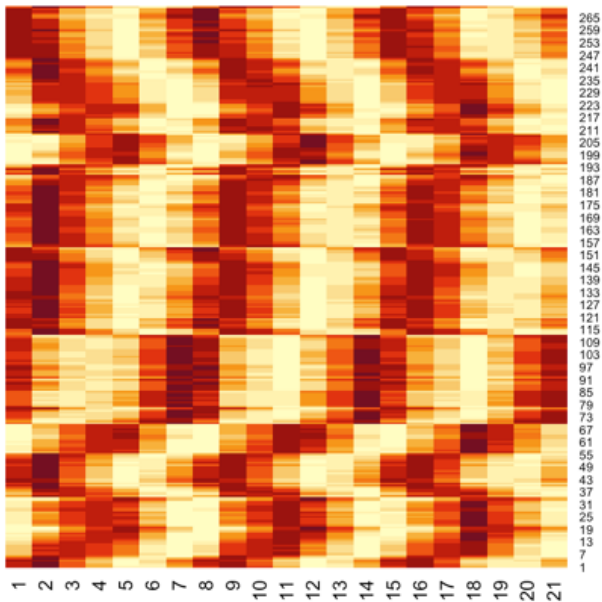
Algorithm

Original Series		Lagged Series							
		Lag 1		lag 2		...	lag 21		
MOB	PR	MOB	PR	MOB	PR		MOB	PR	
1	1	1	2	1	3	...	1	22	
2	2	2	3	2	4	...	2	23	
3	3	3	4	3	5	...	3	24	
4	4	4	5	4	6	...	4	25	
5	5	5	6	5	7	...	5	26	
6	6	6	7	6	8	...	6	27	
7	7	7	8	7	9	...	7	28	
8	8	8	9	8	10	...	8	29	
9	9	9	10	9	11	...	9	30	
10	10	10	11	10	12	...	10	31	
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	
389	389	388	388	387	387	...	368	368	

Rolling Windows	Correlation Matrix (windows x lags)					Summary of each row				
	cor1	cor2	...	cor21		Max	Lag at Max	Med	Q25	Q75
Window 1	Red	Red	...	Red		Red	Red	Red	Red	Red
Window 2	Blue	Blue	...	Blue		Blue	Blue	Blue	Blue	Blue
Window 3	Green	Green	...	Green		Green	Green	Green	Green	Green
Window 4	:	:	:	:		:	:	:	:	:
Window 5	:	:	:	:		:	:	:	:	:
Window 6	:	:	:	:		:	:	:	:	:
:	:	:	:	:		:	:	:	:	:

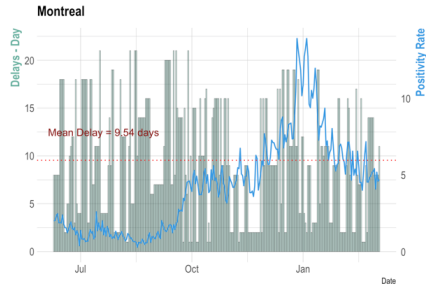
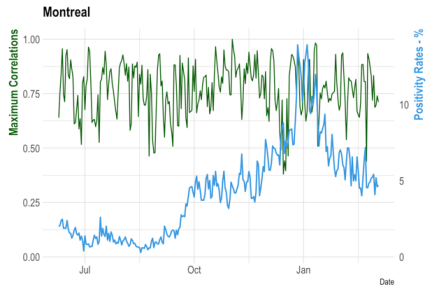
Heatmap

Heatmap Matrix - Rank(2) Approx



Starting days of 7-day rolling windows

Maximums and Delays



Shortcomings

- ▶ Correlations are not partial: intermediate lags are not controlled
- ▶ Even with a well-grounded epidemiological “truth” and with de-trended $I(0)$ series, we need to know:
 - ▶ Whether the genuine association between two series is distinguishable from lagged synchrony that would occur by chance.
 - ▶ Whether correlations are out of 95% CI

Partial Correlations

- ▶ Most studies look at the **synchronous temporal correlations** among regions of interest (bivariate or multivariate). See [Brain Imaging Methods](#).
- ▶ When it's bivariate and synchronous, zero-order correlations with sliding time-window based analysis are just fine
- ▶ When it's multivariate, $n > p$ is required for non-singular covariance matrix to obtain partial correlations.
- ▶ When $n \ll p$, a regularized inverse covariance (precision) matrix is needed
- ▶ Regularization leads to a network analysis that identifies the set of substantial connections (edges) between variables (nodes) and eliminates others
- ▶ Mostly used in genomics, finance, psychology, neuroscience to identify the “edges”.
- ▶ With a proper visualization of the network, it's called **Gaussian Graphical Method**, if MVN.

Delay-coordinate embedding

Original Series		Lagged Series							
Series		Lag 1		...	lag 5		...	lag 21	
MOB	PR	MOB	PR		MOB	PR		MOB	PR
1	1	1	2		1	6	...	1	22
2	2	2	3		2	7	...	2	23
3	3	3	4		3	8	...	3	24
4	4	4	5		4	9	...	4	25
5	5	5	6		5	10	...	5	26
6	6	6	7		6	11	...	6	27
7	7	7	8		7	12	...	7	28
8	8	8	9		8	13	...	8	29
9	9	9	10		9	14	...	9	30
10	10	10	11		10	15	...	10	31
⋮	⋮	⋮	⋮		⋮	⋮	⋮	⋮	⋮
389	389	388	388		387	387	...	368	368

Embedded Data Matrix for Window 1 and Lag 5

Zero-order

Control Variables

Window 1

for Fully Partial Correlation for Lag5

PR5	MOB	PR	PR1	PR2	PR3	PR4	MOB1	MOB2	MOB3	MOB4
6	1	1	2	3	4	5	2	3	4	5
7	2	2	3	4	5	6	3	4	5	6
8	3	3	4	5	6	7	4	5	6	7
9	4	4	5	6	7	8	5	6	7	8
10	5	5	6	7	8	9	6	7	8	9
11	6	6	7	8	9	10	7	8	9	10
12	7	7	8	9	10	11	8	9	10	11

Dimension for each

Rolling

Partial Correlation Matrix (n x p)

Windows

cor1 ... cor5 ... cor21

1	7x3	7x11	7x42
2	7x3	7x11	7x42
3	7x3	7x11	7x42
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮

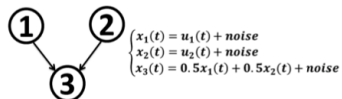
m -dimensional **reconstruction-space** vectors

$$\vec{R}(t) = [y(t), y(t-\tau), y(t-2\tau), \dots, y(t-(m-1)\tau)]$$

The standard strategy for state-space reconstruction is delay-coordinate embedding, where a series of past values of a single scalar measurement y from a dynamical system are used to form a vector that defines a point in a new space.

Regularization

- ▶ Even if $n > p$, we can use regularization to identify “significant” partial correlations
- ▶ **Berkson’s paradox** could be an issue



```
> x1 <- rnorm(100)
> x2 <- rnorm(100)
> x3 <- 0.5*x1+0.5*x2 + rnorm(100)
> mat <- cbind(x1, x2, x3)
> S <- cov(mat)
> -cov2cor(solve(S))
```

	x1	x2	x3
x1	-1.0000000	-0.4076111	0.6085341
x2	-0.4076111	-1.0000000	0.5647095
x3	0.6085341	0.5647095	-1.0000000

```
> |
```

Although there is no link between Node 1 (PR) and Node 2 (mob), the partial correlation between these two nodes could be high and significant - **Regularization may correct the paradox and reduce the noise-to-signal ratio** (Nie et al. 2015).

Regularization for GGM

- ▶ $n > p$ or $n < p$, **we want to find a sparse graph** capturing the conditional dependence between the entries of a Gaussian random vector
- ▶ In GGM, the graph structure can be expressed only through its precision matrix, Ω .



Formally, let $\hat{\Omega}$ denote a generic estimate of the precision matrix and consider its transformation to a partial correlation matrix $\hat{\mathbf{P}}$. Then the following relations can be shown to hold for all pairs $\{Y_j, Y_i\} \in \mathcal{V}$ with $j \neq i$:

$$(\hat{\mathbf{P}})_{ji} = 0 \iff (\hat{\Omega})_{ji} = 0 \iff Y_j \perp Y_i \mid \mathcal{V} \setminus \{Y_j, Y_i\}$$

What do we want?

Original Series		Lagged Series									
MOB	PR	Lag 1		...		lag 5		...		lag 21	
		MOB	PR	MOB	PR	MOB	PR	MOB	PR	MOB	PR
1	1	1	2	1	6	...	1	22			
2	2	2	3	2	7	...	2	23			
3	3	3	4	3	8	...	3	24			
4	4	4	5	4	9	...	4	25			
5	5	5	6	5	10	...	5	26			
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9	9	9	10	9	14	...	9	30			
10	10	10	11	10	15	...	10	31			
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮			
389	389	388	388	387	387	...	368	368			

Embedded Data Matrix for Window 1 and Lag 5

Zero-order		Control Variables									
Window 1		for Fully Partial Correlation for Lag5									
PR5	MOB	PR	PR1	PR2	PR3	PR4	MOB1	MOB2	MOB3	MOB4	
6	1	1	2	3	4	5	2	3	4	5	
7	2	2	3	4	5	6	3	4	5	6	
8	3	3	4	5	6	7	4	5	6	7	
9	4	4	5	6	7	8	5	6	7	8	
10	5	5	6	7	8	9	6	7	8	9	
11	6	6	7	8	9	10	7	8	9	10	
12	7	7	8	9	10	11	8	9	10	11	

Sparsified P. Correlation Matrix for Window 1 & Lag 5

	PR5	MOB	PR	PR1	PR2	PR3	PR4	MOB1	MOB2	MOB3	MOB4
PR5	1	✓	x	x	x	✓	x	✓			
MOB		1									
PR0			1								
PR1				1							
PR2					1						
PR3						1					
PR4							1				
MOB1								1			
MOB2									1		
MOB3										1	
MOB4											1

2nd Stage Partial Correlation Matrix

	PR5	MOB	PR3	MOB1	MOB2
PR5	1	?			
MOB		1			
PR3			1		
MOB1				1	
MOB2					1

Correlations Matrix (windows x lags)

Windows	cor1	cor2	...	cor5	...	cor21
1	0.00	0.05	...	?	...	0.51
2						
⋮	⋮	⋮	⋮	⋮	⋮	⋮
269	⋮	⋮	⋮	⋮	⋮	⋮

Ridge or GLasso?

- ▶ The true (graphical) model need not be (extremely) sparse.
- ▶ We may prefer a regularization that shrinks the estimated elements of the precision matrix proportionally
- ▶ [Wieringen & Peeters \(2016\)](#) demonstrate that the alternative ridge estimators yield **more stable** networks vis-à-vis the graphical lasso, in particular **for more extreme p/n ratios**.
- ▶ They provide empirical evidence in the graphical modeling setting of what is tacitly known from regression (subset selection) problems: **ridge penalties coupled with post-hoc selection may outperform the lasso**.

Steps

- ▶ Ridge penalty shrinks the estimated elements of Ω , but cannot shoot them to zero.
- ▶ Hence, it requires a specific post-hoc **thresholding** for sparsity
- ▶ Steps:
 - ▶ Estimating the elements of Ω with the optimal penalty parameter λ^*
 - ▶ Thresholding with λ^* (False Discovery Rate - Efron)
 - ▶ Recovering partial coefficients from Ridge estimates
 - ▶ 2-Stage estimation
 - ▶ De-biasing
 - ▶ Re-estimations

Re-Estimation (De-biasing) - Intuition

Original Series		Lagged Series									
MOB	PR	Lag 1		...		lag 5		...		lag 21	
		MOB	PR			MOB	PR			MOB	PR
1	1	1	2			1	6			1	22
2	2	2	3			2	7			2	23
3	3	3	4			3	8			3	24
4	4	4	5			4	9			4	25
5	5	5	6			5	10			5	26
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8	8	8	9			8	13			8	29
9	9	9	10			9	14			9	30
10	10	10	11			10	15			10	31
⋮	⋮	⋮	⋮			⋮	⋮			⋮	⋮
389	389	388	388			387	387			368	368

Embedded Data Matrix for Window 1 and Lag 5

Zero-order

Control Variables

Window 1

for Fully Partial Correlation for Lag5

PR5	MOB	PR	PR1	PR2	PR3	PR4	MOB1	MOB2	MOB3	MOB4
6	1	1	2	3	4	5	2	3	4	5
7	2	2	3	4	5	6	3	4	5	6
8	3	3	4	5	6	7	4	5	6	7
9	4	4	5	6	7	8	5	6	7	8
10	5	5	6	7	8	9	6	7	8	9
11	6	6	7	8	9	10	7	8	9	10
12	7	7	8	9	10	11	8	9	10	11

Sparsified P. Correlation Matrix for Window 1 & Lag 5

	PR5	MOB	PR	PR1	PR2	PR3	PR4	MOB1	MOB2	MOB3	MOB4
PR5	1	✓	x	x	x	✓	x	✓	✓	x	x
MOB	✓	1	x	✓	x	✓	✓	x	x	x	✓
PR0			1								
PR1				1							
PR2					1						
PR3						1					
PR4							1				
MOB1								1			
MOB2									1		
MOB3										1	
MOB4											1

$$\tilde{\Omega} = \begin{pmatrix} \Omega_{a,a} & \Omega_{a,-a} \\ \Omega_{-a,a} & \Omega_{-a,-a} \end{pmatrix} \quad \tilde{\Omega} = \begin{pmatrix} \Omega_{b,b} & \Omega_{b,-b} \\ \Omega_{-b,b} & \Omega_{-b,-b} \end{pmatrix}$$

$$\tilde{\Omega}_{-a,a} = -\tilde{\Omega}_{a,a} \hat{\beta}^{a,ne_a} \quad \tilde{\Omega}_{-b,b} = -\tilde{\Omega}_{b,b} \hat{\beta}^{b,ne_b}$$

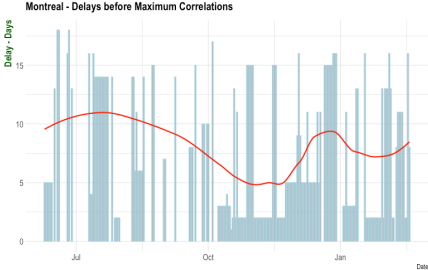
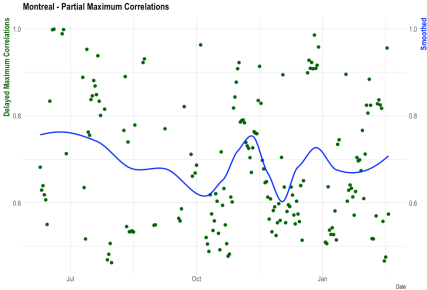
$$\hat{\Omega}_{a,b} = \hat{\Omega}_{b,a} = \text{sign}(\hat{\beta}_b^{a,ne_a}) \sqrt{|\tilde{\Omega}_{a,b} \tilde{\Omega}_{b,a}|}$$

The 2-stage partials slightly overestimate the de-biased estimates

Why Composite Likelihood method (CLM)?

- ▶ Ridge and Glasso require de-biasing, but it doesn't have an established literature
- ▶ Or 2-step partials are similar to 2-step LASSO and may not be reliable in terms of their asymptotic properties.
- ▶ CLM is the perfect fit that removes the need for de-biasing and provides reliable asymptotic properties

Results



Elasticities

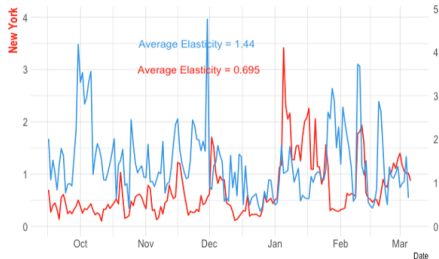
► Zero-order correlations:

- We first use the full partial-correlation (delay-coordinate embedding) matrix
- Apply the ridge-sparsity to see if mob is not “sparsified”
- Use non-sparsified mobs for zero-order correlations (i.e., remove all intermediate lagged PR and mob columns)
- Apply the significance test to identify the significant correlations in each window/lag: keep the significant ones.

► Elasticities:

- $\epsilon = \frac{\partial PR/PR}{\partial R/R} = r \frac{s_{pr}}{s_r} \frac{\bar{R}}{\bar{PR}}$
- When r is in the neighborhood of 1, the spread will be more sensitive or less (i.e., $\epsilon \lesseqgtr 1$) depending on two facts: the spread of COVID-19 is more or less variable than the mobility $\left(\frac{S_{PR}}{S_R}\right)$ and the magnitude of restrictions relative to how widespread PR is $\left(\frac{\bar{R}}{\bar{PR}}\right)$

Counterfactual Elasticities



Counterfactuals for Montreal are calculated in each rolling window with a dynamic lag optimization:

$$r^M \left[\frac{SPR}{SR} \right]^M \left[\frac{\bar{R}}{\bar{PR}} \right]^{NYC}$$

Differences between NYC and Montreal

	NYC	Montreal
Sensitivity = $sd(PR)/sd(R)$	11.9525200	18.3261807
Significance = $mean(R)/mean(PR)$	0.1112559	0.0291587
Beta = $cov(PR, R)/var(R)$	7.9307361	14.0195609
Correlation	0.7082259	0.7758325
Elasticity = Beta x Significance	0.6953200	0.4207255
Counterfactual Elasticity	0.6953200	1.4404136

What it tells us . . .

In order to have this much jump in the elasticity for Montreal, two things have to be true in NYC relative to Montreal:

- (1) the magnitude of the decline in mobility should be much higher relative to the rise in spread (\bar{R}/\overline{PR});
- (2) the mobility should have a much higher temporal variation relative to positivity rates (S_{PR}/S_R).

Given that the mobility metrics rather measure the people's behavioral response to the spread, these differences imply the following possibilities in Montreal:

- (1) the average reduction in mobility relative to the spread might not have been enough in terms of its magnitude and speed;
- (2) a significantly lower public sensitivity to the COVID-19 spread.

Concluding remarks

- ▶ We develop a method that can be used to capture the spatiotemporal dynamics of the relations between two variables (if the direction of correlations are known!)
- ▶ We show that the effect of (same) mobility restrictions on positivity rates vary by time and location
- ▶ We measure this dynamic relationship by correlation (nature of relationship) and elasticity (utilization of the relationship) for Montreal, NYC, Toronto, and Nova Scotia
- ▶ We show the main results for Montreal and compare it with NYC.
- ▶ We apply a counterfactual simulation to show why Montreal is different than NYC