Ehsan Hosseini

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EDUCATION

2010 – 2014 B.S. in Electrical Engineering (Control),

Electrical and Computer Engineering Department, University of

Tehran, Tehran, Iran, (Last year GPA 16.03/20)

2006 – 2010 High School Diploma and Pre-University Course, Mathematics

and Physics,

Allame Tabatabai High school, Tehran, Iran

(Diploma GPA 19.60/20.00)

2005-2006 Marsden High School,

West Ryde, Sydney, Australia

RESEARCH INTEREST

- Game Theory and Optimal Control
- Cyber-physical Systems
- Non-linear Control
- Robotics and Mechatronics
- Renewable Energy Systems

HONORS & AWARDS

Spring 2012 Rank 2nd in AUTRONIC electronic design competition
Summer 2011 Rank 1st in robotic competition in university of Tehran

Fall 2010 Recognized exceptional talent by NODET

Fall 2010 Received full governmental fellowship for bachelor studies

Summer 2010 Rank top 0.1% of the Nationwide Matriculation Exam (Konkoor)

RESEARCH & PRACTICAL EXPERIENCES

Spring 2014 Game Theory research- I worked on evolutionary game

theory concepts and its application in targeted cancer therapy. I found some mathematical conditions that maximize the chance of succeed in anticancer drugs. Under supervision of Dr H.Kebreai.

Fall 2013 Advance control project – I worked on modeling and

analyzing a VTOL aircraft and linearizing for implementing state space and designing a state feedback for stabilization and control, and comparing it with PID classic controllers. Under supervision of

Dr H.Kebreai.

Sumer 2013 Advance Robotic lab – I worked on several robotic projects

with graduate students. My major activities was programming under Linux for arm microprocessors and control the motors and sensors via wireless communication and I2C protocol. Under

supervision of Dr H.Moradi.

Spring 2013 Mechatronics lab – I worked on designing and implementing a

complete mechatronic system "Inverse pendulum". Modeling the physical system, extracting state equation, linearization, designing discrete time controller, designing PCB and constructing the plant.

Under supervision of Dr T.Abbasian.

Fall 2012 Mechatronics workshop- I built a complete path finder robot

from lathing mechanical parts to designing and assembling

electrical parts. Under supervision of Dr M.Fakhrai.

TEACHING EXPERIENCE

Fall 2014 Automatic Control (Linear Control Systems) – Teacher Assistant

Lecturer: Dr M.Ayati

Spring 2014 Digital and non-linear control systems – Teacher Assistant

Lecturer: Dr A.Rahimi Kian

Spring 2014 Industrial Electronic Lab – Teacher Assistant

Lecturer: Prof S.Farhangi

WORK EXPERIENCES

Internship:

Summer 2013 Renewable Energy Organization of Iran – Wind Energy office

Thesis: Wind Turbines control and monitoring systems, DCS & SCADA

Advisor: Prof S.Farhangi

Tutoring:

2012-2013 Advance robotic instructor – Saramad Co.

2011-2014 Mathematics & physics tutor of high school students

INNOVATIONS

Using micro wind turbines in automobiles*

Advisor: Dr B.Asai

SELECTED TEAM PROJECTS

2012 Iranian Persian Ghazal III (solar car), University of Tehran

Expected to attend International competition

Dome Robot (Repair & Wash Domes), Mobile Robot lab, University of Tehran,

SKILLS

Computer Skills:

HDL (Hardware Description Language) Verilog

Programming Tools and Languages C, C++, Assembly

Simulating and Designing Tools Altium Designer, Matlab, Proteus,

Modelsim, Codevision, Quartus,

Multisim, Hspice, PSCAD

Miscellaneous Microsoft Office Package, AutoCAD

Operating Systems Linux, Windows

Microcontroller AVR, ARM

^{*}more information available upon request

Languages:

English: TOEFL iBT

Overall: 92

Reading: 24 Listening: 20 Speaking: 23 Writing: 25

GRE (General test)

Verbal: 149 - %41 Quantitative: 162 - %83

References

• Ashkan Rahimi Kian, Associate Professor, University of Tehran.

Email: arkian@ut.ac.ir

• Hamed Kebriai, Assistant Professor, University of Tehran.

Email: Kebriaei@ut.ac.ir

• Hadi Moradi, Assistant Professor, University of Tehran.

Email: moradih@ut.ac.ir

• Moosa Ayati, Assistant Professor, University of Tehran

Email: m.ayati@ut.ac.ir