

# Data Science Fundamentals





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## Matrices





- Matrices are used to store and represent the data on the machine.
- A matrix is a rectangular structure with rows and columns to organize data. It can be described as A m\*n, where m represents the number of rows and n denotes the number of columns in the matrix. A matrix in linear algebra is used to express linear equations more compactly.

$$A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}_{2 \times 3}$$



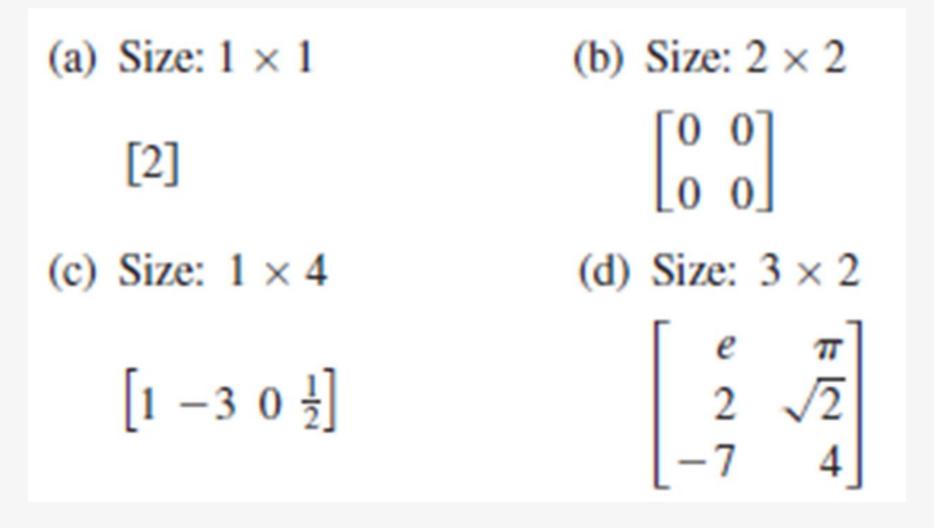
A matrix is a rectangular array if **m** and **n** are positive integers

```
\begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix} \qquad \begin{array}{c} m \text{ rows} \\ \end{array}
                                                                              n columns
```

- each entry of the matrix is a number.
- A matrix m\*n (read "m by n") has m rows (horizontal lines) and n columns (vertical lines).
- The entry a12 is located in row 1 and column 2. Index 1 is called the row subscript and index 2 is called the column subscript.



- If m = n, then the matrix is called a square matrix.
- The entries where the column subscript is equal to the row subscript are called the main diagonal entries.
- **Examples of matrices**



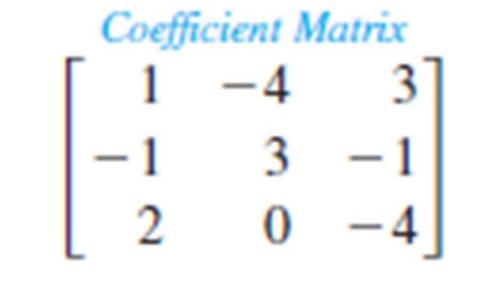


We can use matrices to represent systems of linear equations in two forms: An augmented matrix where the coefficients and constant terms are represented, and a coefficients matrix where only the coefficients are represented

$$x - 4y + 3z = 5$$

$$-x + 3y - z = -3$$

$$2x - 4z = 6$$



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Solving a system using elementary Row operations





## **Elementary Row Operations**

- An elementary row operation on an augmented matrix creates a new augmented matrix corresponding to a new (but equivalent) system of linear equations.
- Two matrices are said to be row-equivalent if one can be obtained from the other by a finite sequence of elementary row operations.
- **Elementary Row Operations** 
  - Interchange two rows.
  - 2. Multiply a row by a nonzero constant.
  - 3. Add a multiple of a row to another row.



## **Elementary Row Operations**

(a) Interchange the first and second rows.

Original Matrix

$$\begin{bmatrix} 0 & 1 & 3 & 4 \\ -1 & 2 & 0 & 3 \\ 2 & -3 & 4 & 1 \end{bmatrix}$$

New Row-Equivalent Matrix

$$\begin{bmatrix} 0 & 1 & 3 & 4 \\ -1 & 2 & 0 & 3 \\ 2 & -3 & 4 & 1 \end{bmatrix} \quad \begin{bmatrix} -1 & 2 & 0 & 3 \\ 0 & 1 & 3 & 4 \\ 2 & -3 & 4 & 1 \end{bmatrix} \qquad \begin{array}{c} R_1 \leftrightarrow R_2 \end{array}$$

Notation

$$R_1 \leftrightarrow R_2$$

(b) Multiply the first row by ½ to produce a new first row.

$$\begin{bmatrix} 2 & -4 & 6 & -2 \\ 1 & 3 & -3 & 0 \\ 5 & -2 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & -2 & 3 & -1 \\ 1 & 3 & -3 & 0 \\ 5 & -2 & 1 & 2 \end{bmatrix}$$
$$\begin{bmatrix} \frac{1}{2}R_1 \rightarrow R_1 \\ 1 & 3 & -3 & 0 \\ 5 & -2 & 1 & 2 \end{bmatrix}$$

Original Matrix New Row-Equivalent Matrix

$$\begin{bmatrix} 1 & -2 & 3 & -1 \\ 1 & 3 & -3 & 0 \\ 5 & -2 & 1 & 2 \end{bmatrix}$$

Notation

$$(\frac{1}{2})R_1 \rightarrow R_1$$

(c) Add −2 times the first row to the third row to produce a new third row.

New Row-Equivalent Matrix

$$\begin{bmatrix} 1 & 2 & -4 & 3 \\ 0 & 3 & -2 & -1 \\ 2 & 1 & 5 & -2 \end{bmatrix} \qquad \begin{bmatrix} 1 & 2 & -4 & 3 \\ 0 & 3 & -2 & -1 \\ 0 & -3 & 13 & -8 \end{bmatrix} \qquad R_3 + (-2)R_1 \rightarrow R_3$$

Notation

$$R_3 + (-2)R_1 \rightarrow R_3$$



# Solving a system using elementary row operations-Example

### **Examples:**

#### Linear System

$$x - 2y + 3z = 9$$
  
 $-x + 3y = -4$   
 $2x - 5y + 5z = 17$ 

Add the first equation to the second equation

$$x - 2y + 3z = 9$$
$$y + 3z = 5$$
$$2x - 5y + 5z = 17$$

#### Associated Augmented Matrix

$$\begin{bmatrix} 1 & -2 & 3 & 9 \\ -1 & 3 & 0 & -4 \\ 2 & -5 & 5 & 17 \end{bmatrix}$$

Add the first row to the second row to produce a new second row

$$\begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 2 & -5 & 5 & 17 \end{bmatrix} \qquad \begin{array}{c} R_2 + R_1 \rightarrow R_2 \end{array}$$



# Solving a system using elementary row operations-Example

Add -2 times the first equation to the third equation

$$x - 2y + 3z = 9$$

$$y + 3z = 5$$

$$-y - z = -1$$

Add the second equation to the third equation.

$$x - 2y + 3z = 9$$
$$y + 3z = 5$$
$$2z = 4$$

Add -2 times the first row to the third row to produce a new third row.

$$\begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & -1 & -1 & -1 \end{bmatrix}$$

$$R_3 + (-2)R_1 \rightarrow R_3$$

Add the second row to the third row to produce a new third row.

$$\begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

$$R_3 + R_2 \rightarrow R_3$$



# Solving a system using elementary row operations-Example

Multiply the third equation by ½

$$x - 2y + 3z = 9$$
$$y + 3z = 5$$
$$z = 2$$

Multiply the third row by ½ to produce a new third row

$$\begin{bmatrix} 1 & -2 & 3 & 9 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 1 & 2 \end{bmatrix} \qquad \begin{array}{c} (\frac{1}{2})R_3 \to R_3 \end{array}$$

- You can now use back substitution to get the same solution as the example we solved before.
- The last matrix is in a row-echelon form that we defined before.
  - $\triangleright$  The solution is x=1, y=-1, z=2

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## Gaussian Elimination





- It is a procedure for solving systems of linear equations
- Gaussian Elimination with Back-Substitution
  - 1. Write the augmented matrix of the system of linear equations.
  - 2. Use elementary row operations to rewrite the augmented matrix in row-echelon form.
  - 3. Write the system of linear equations corresponding to the matrix in row-echelon form, and use back-substitution to find the solution.



#### **Example**: Solve the system

$$x_{2} + x_{3} - 2x_{4} = -3$$

$$x_{1} + 2x_{2} - x_{3} = 2$$

$$2x_{1} + 4x_{2} + x_{3} - 3x_{4} = -2$$

$$x_{1} - 4x_{2} - 7x_{3} - x_{4} = -19$$

1. The augmented matrix for this system is

$$\begin{bmatrix} 0 & 1 & 1 & -2 & -3 \\ 1 & 2 & -1 & 0 & 2 \\ 2 & 4 & 1 & -3 & -2 \\ 1 & -4 & -7 & -1 & -19 \end{bmatrix}.$$



2. Obtain a leading 1 in the upper left corner and zeros elsewhere in the first column.

$$\begin{bmatrix} 1 & 2 & -1 & 0 & 2 \\ 0 & 1 & 1 & -2 & -3 \\ 2 & 4 & 1 & -3 & -2 \\ 1 & -4 & -7 & -1 & -19 \end{bmatrix}$$

The first two rows R1↔R2 are interchanged.

$$\begin{bmatrix} 1 & 2 & -1 & 0 & 2 \\ 0 & 1 & 1 & -2 & -3 \\ 0 & 0 & 3 & -3 & -6 \\ 1 & -4 & -7 & -1 & -19 \end{bmatrix}$$

Adding -2 times to the first row to the third row to produce a new third-row R3+(-2)R1 $\rightarrow$ R3



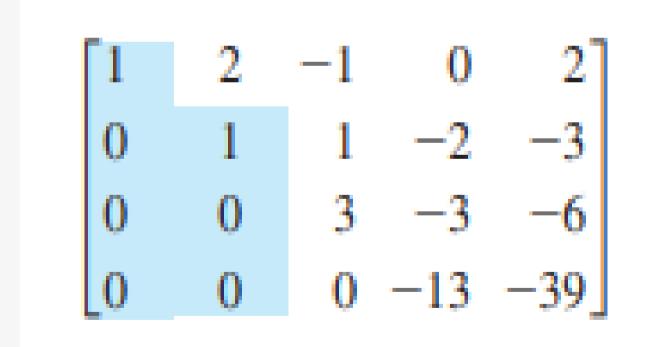
$$\begin{bmatrix} 1 & 2 & -1 & 0 & 2 \\ 0 & 1 & 1 & -2 & -3 \\ 0 & 0 & 3 & -3 & -6 \\ 0 & -6 & -6 & -1 & -21 \end{bmatrix}$$

Adding -1 times the first row to the fourth row to produce a new fourth row.

$$R4 + (-1) R1 \rightarrow R4$$



3. Now that the first column is in the desired form, you should change the second column as shown below



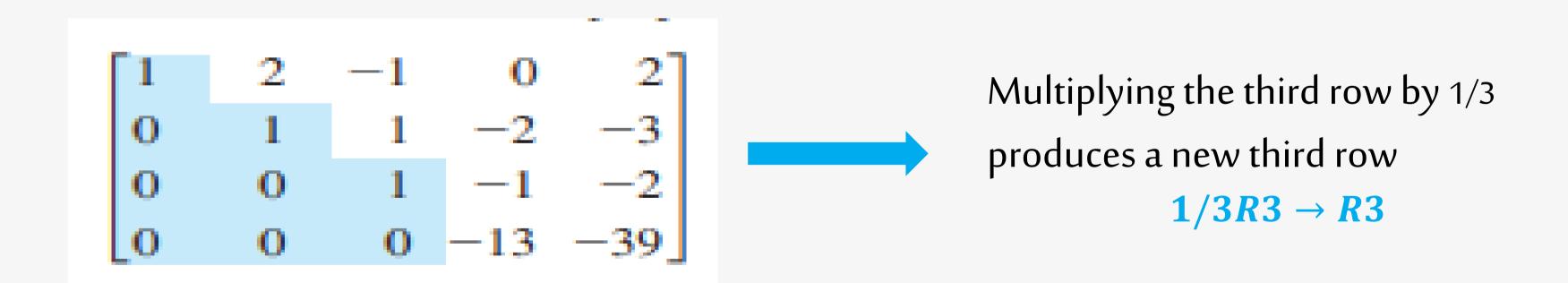


Adding 6 times the second row to the fourth row to produce a new fourth row.

$$R4 + (6) R2 \rightarrow R4$$



4. To write the third column in proper form, multiply the third row by 1/3





5. Similarly, to write the fourth column in proper form, you should multiply the fourth row by -1/13





Multiplying the fourth row by -1/13 produces a new fourth row.

$$-1/13R4 \rightarrow R4$$



The matrix is now in row-echelon form, and the corresponding system of linear equations is as shown below

$$x_1 + 2x_2 - x_3 = 2$$

$$x_2 + x_3 - 2x_4 = -3$$

$$x_3 - x_4 = -2$$

$$x_4 = 3$$

Using back-substitution, you can determine that the solution is

$$X1 = -1$$
,  $x2 = 2$ ,  $x3 = 1$ ,  $x4 = 3$ 



If during elimination you obtain a row with all zeros, then the system is inconsistent and has no solutions.

- Gauss Jordan Elimination:
  - It is the same as Gaussian Elimination but the reduction is continued until you reach a reduced row-echelon form.



- Homogenous Systems of linear equations.
  - A system where all the constant terms are zero.
  - •All homogenous systems must have at least one solution: The trivial solution where all variables are set to zero.
- Every homogeneous system of linear equations is consistent. Moreover, if the system has fewer equations than variables, then it must have an infinite number of solutions.









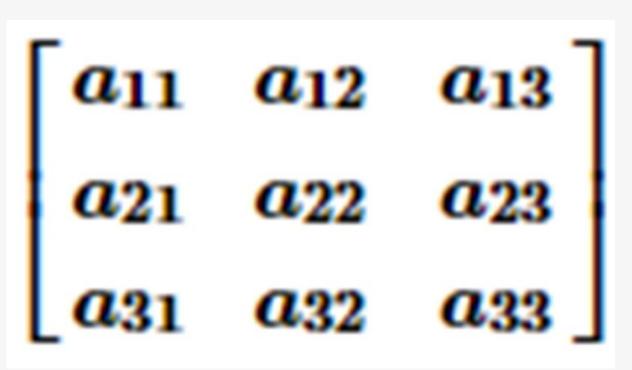
## **Matrix Operations**

- \*Matrix operations hold the basic arithmetic operations of addition, subtraction, and multiplication of matrices, which help combine two or more matrices to form a single matrix.
- we can also include the Transpose and Inverse of a matrix as operations on matrices that help to transform a specific matrix onto itself.



## **Matrix Operations**

- There are three ways to represent matrices
  - ✓ Using uppercase letters such as A, B, C,.
  - ✓ Using a representative element enclosed in brackets like:[ai][aj]
  - ✓ By a rectangular array of numbers:





## **Matrix Operations**

The Two matrices are equal if their corresponding elements are equal in two matrices.

Two matrices A = [aij] and B = [bij] are equal if they have the same size and aij = bij

- A matrix that has one column is called a column matrix or a column vector.
- A matrix that has one row is called a row matrix or a row vector.



#### **Matrices Addition**

- The addition of two matrices is done by adding each corresponding entry in each matrix.
- Both matrices must be of the same size
- **▶** Definition of Matrix Addition

If A=[aij] and B=[bij] are matrices of size  $m \times n$  then their sum is the  $m \times n$  matrix given by

$$A + B = [aij + bij]$$

The sum of two matrices of different sizes is undefined.



#### **Matrices Addition**

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} & b_{13} & \dots & b_{1n} \\ b_{21} & b_{22} & b_{23} & \dots & b_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ b_{m1} & b_{m2} & b_{m3} & \dots & b_{mn} \end{bmatrix} = \begin{bmatrix} a_{m} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{bmatrix}$$

$$\begin{bmatrix} a_{ij} \end{bmatrix}_{m \times n}$$

$$\begin{bmatrix} b_{ij} \end{bmatrix}_{m \times n}$$

$$\begin{bmatrix} b_{ij} \end{bmatrix}_{m \times n}$$

#### **Example**

$$\bullet \quad \begin{bmatrix} -1 & 2 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 3 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} -1+1 & 2+3 \\ 0+(-1) & 1+2 \end{bmatrix} = \begin{bmatrix} 0 & 5 \\ -1 & 3 \end{bmatrix}$$



### **Matrices Subtraction**

Subtraction of matrices is done by subtracting each corresponding entry in each matrix, and the two matrices must have the same number of rows and columns.

$$\begin{bmatrix} a_{n1} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix} - \begin{bmatrix} b_{11} & b_{12} & b_{13} & \dots & b_{1n} \\ b_{21} & b_{22} & b_{23} & \dots & b_{2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ b_{m1} & b_{m2} & b_{m3} & \dots & b_{mn} \end{bmatrix} = \begin{bmatrix} a_{11} - b_{11} & a_{12} - b_{12} & \dots & a_{1n} - b_{1n} \\ a_{21} - b_{21} & a_{22} - b_{22} & \dots & a_{2n} - b_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} - b_{m1} & a_{m2} - b_{m2} & \dots & a_{mn} - b_{mn} \end{bmatrix}$$

$$\begin{bmatrix} a_{11} - b_{11} & a_{12} - b_{12} & \dots & a_{1n} - b_{1n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} - b_{m1} & a_{m2} - b_{m2} & \dots & a_{mn} - b_{mn} \end{bmatrix}$$



## Scalar Multiplication

You can multiply a matrix A with a scalar c by multiplying each entry in A with scalar c.

O Definition of Scalar Multiplication

If A = [aij] is an m x n matrix and c is a scalar, then the scalar multiple of A by c is the m x n matrix given by

$$cA = [caij]$$



## Scalar Multiplication

Example

• 
$$m{A} = egin{bmatrix} m{1} & m{5} \ m{2} & -m{3} \end{bmatrix}$$

O Subtraction can be modeled as a combination of scalar multiplication and addition: A + (-1)B



## Scalar Multiplication

- The entry in the ith row and the jth column of the product AB is obtained by multiplying the entries in the ith row of A by the corresponding entries in the jth column of B and then adding the results.
  - Definition of Matrix Multiplication

If A = [aij] is an  $m \times n$  matrix and B = [bij] is an  $n \times p$  matrix, then the product AB is an  $m \times p$  matrix AB = [cij] Where

$$c_{ij} = \sum_{k=1}^{n} a_{ik} b_{kj} = a_{i1} b_{1j} + a_{i2} b_{2j} + a_{i3} b_{3j} + \cdots + a_{in} b_{nj}.$$



## Matrix Multiplication

Two matrices A and B are said to be compatible if the number of columns in A is equal to the number of rows in B.

#### Matrix multiplication Formula:

$$\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} \begin{bmatrix} j & k & I \\ m & n & o \\ p & q & r \end{bmatrix} = \begin{bmatrix} (aj+bm+cp) & (ak+bn+cq) & (al+bo+cr) \\ (dj+em+fp) & (dk+en+fq) & (dl+eo+fr) \\ (gj+hm+ip) & (gk+hn+iq) & (gl+ho+ir) \end{bmatrix}$$



## Matrix Multiplication

**Example:** Find the product AB of the two matrices

$$A = \begin{bmatrix} -1 & 3 \\ 4 & -2 \\ 5 & 0 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} -3 & 2 \\ -4 & 1 \end{bmatrix}.$$

$$AB = \begin{bmatrix} -1 & 3 \\ 4 & -2 \\ 5 & 0 \end{bmatrix} \begin{bmatrix} -3 & 2 \\ -4 & 1 \end{bmatrix} = \begin{bmatrix} -9 & 1 \\ -4 & 6 \\ -15 & 10 \end{bmatrix}.$$



### Matrix Multiplication

- Matrix multiplication is not commutative.
- They can be used to represent systems of linear equations.

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 = b_1$$

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 = b_2$$

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 = b_3$$

Can be written as the equation AX=B

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Properties of Matrices Operations





# Properties of Matrices Operations

Properties of Matrices Addition and scalar multiplication

If A, B, and C are  $m \times n$  matrices and c and d are scalars, then the following properties are true.

1. 
$$A + B = B + A$$

2. 
$$A + (B + C) = (A + B) + C$$

$$3. (cd)A = c(dA)$$

4. 
$$1A = A$$

5. 
$$c(A + B) = cA + cB$$

$$6. (c + d)A = cA + dA$$

Commutative property of addition

Associative property of addition

Associative property of multiplication

Multiplicative identity

Distributive property

Distributive property

When adding real numbers, the number 0 serves as the additive identity. Meaning that A + O = A where A is an equal-sized matrix with zero for all entries.

[3]



# Properties of Matrices Operations

- The matrix O with all zero entries is called a zero matrix.
- Properties of Zero Matrices

If A is an m x n matrix and c is a scalar, then the following properties are true.

1. 
$$A + O_{mn} = A$$
  
2.  $A + (-A) = O_{mn}$   
3. If  $cA = O_{mn}$ , then  $c = 0$  or  $A = O_{mn}$ .

-A in property two is called the additive inverse of A



# Properties of Matrices Operations

### > Properties of Matrix multiplication

If A, B, and C are matrices (with sizes such that the given matrix products are defined) and is a scalar, then the following properties are true.

$$1.A(BC) = (AB)C$$
 $2.A(B + C) = AB + AC$ 
 $3.(A + B)C = AB + BC$ 
 $4.c(AB) = (cA)B = A(cB)$ 

The multiplication AB is not equal to BA. Matrix multiplication is non-commutative

■ If AC = BC it does not mean that A = B









# The Identity matrix

It is a matrix with ones across the diagonal and zeros everywhere else

$$I_n = \begin{bmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix}$$

 $\triangleright$  If A is a matrix of size m x n, then the following properties are true.

1. 
$$AI_n = A$$

$$2. I_m A = A$$



# The Transpose of a matrix

The transpose of a matrix is formed by writing its columns as rows

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix},$$

$$A^{T} = \begin{bmatrix} a_{11} & a_{21} & a_{31} & \cdots & a_{m1} \\ a_{12} & a_{22} & a_{32} & \cdots & a_{m2} \\ a_{13} & a_{23} & a_{33} & \cdots & a_{m3} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{1n} & a_{2n} & a_{3n} & \cdots & a_{mn} \end{bmatrix}$$

$$Size: m \times n$$

$$Size: n \times m$$

$$A^{T} = \begin{bmatrix} a_{11} & a_{21} & a_{31} & \cdots & a_{m1} \\ a_{12} & a_{22} & a_{32} & \cdots & a_{m2} \\ a_{13} & a_{23} & a_{33} & \cdots & a_{m3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & a_{3n} & \cdots & a_{mn} \end{bmatrix}$$
Size:  $n \times m$ 



# The Transpose of a matrix

### **Example:**

$$A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}_{2 \times 3}$$

$$A^{T} = \begin{bmatrix} a & d \\ b & e \\ c & f \end{bmatrix}_{3 \times 2}$$

$$D = \begin{bmatrix} 0 & 1 \\ 2 & 4 \\ 1 & -1 \end{bmatrix} \qquad D^T = \begin{bmatrix} 0 & 2 & 1 \\ 1 & 4 & -1 \end{bmatrix}$$

$$D^T = \begin{bmatrix} 0 & 2 & 1 \\ 1 & 4 & -1 \end{bmatrix}$$



# The Transpose of a matrix

### > Properties of transposes

If A and B are matrices and c is a scalar, then the following properties are true.

1. 
$$(A^T)^T = A$$

2. 
$$(A + B)^T = A^T + B^T$$

3. 
$$(cA)^T = c(A^T)$$

4. 
$$(AB)^{T} = B^{T}A^{T}$$

Transpose of a transpose

Transpose of a sum

Transpose of a scalar multiple

Transpose of a product



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# THANKYOU