

# Ph20 - Assignment 3

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## Part 1

1. We implement the explicit Euler method, and use the script to plot  $x$  and  $v$  as functions of time, for initial conditions  $x(0) = 1$ ,  $v(0) = 0$ ,  $h = 0.01$  and  $t$  running from 0 to 20.

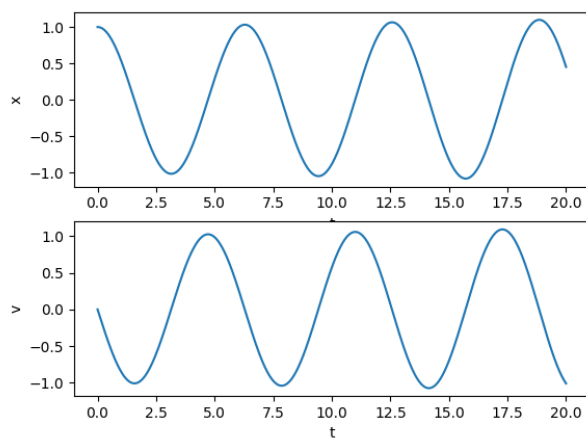


Figure 1: Plot of  $x$  and  $v$  as functions of time for initial conditions  $x(0) = 1$ ,  $v(0) = 0$ , and stepsize  $h = 0.01$ .

2. We observe that the analytical solution to the simple harmonic oscillation equation  $F = -kx$  for the initial conditions given is  $x = \cos(t)$  and  $v = -\sin(t)$ .

We can compare our numerical solution to the analytic solution by plotting the global errors  $x_{analytic}(t_i) - x_i$  and  $v_{analytic}(t_i) - v_i$  against time.

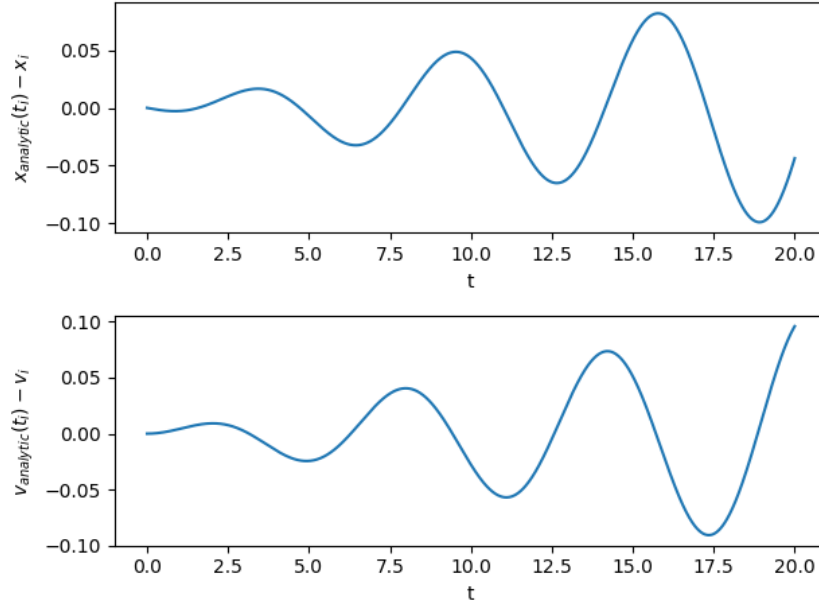


Figure 2: Plot of global errors against time for the explicit Euler method, with stepsize  $h = 0.01$ .

3. We now plot the maximum global error in  $x$  against  $h$ , integrating up to the same final time  $t = 20$ .

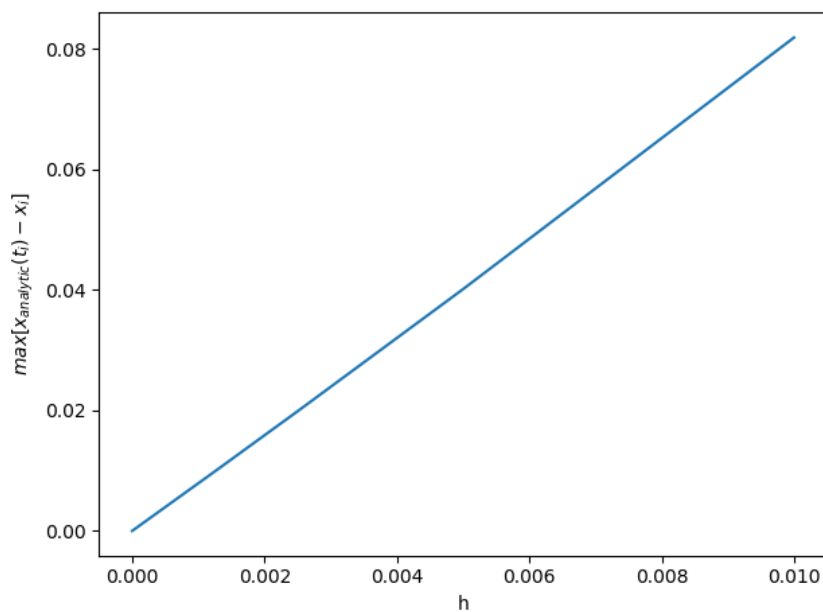


Figure 3: Plot of maximum global error in  $x$  against  $h$  for the explicit Euler method, integrating up to  $t = 20$  for each  $h$ .

The plot indicates that the truncation error is proportional to  $h$  for reasonable  $h$ .

4. We now plot the normalized total energy  $E = v^2 + x^2$  as a function of time:

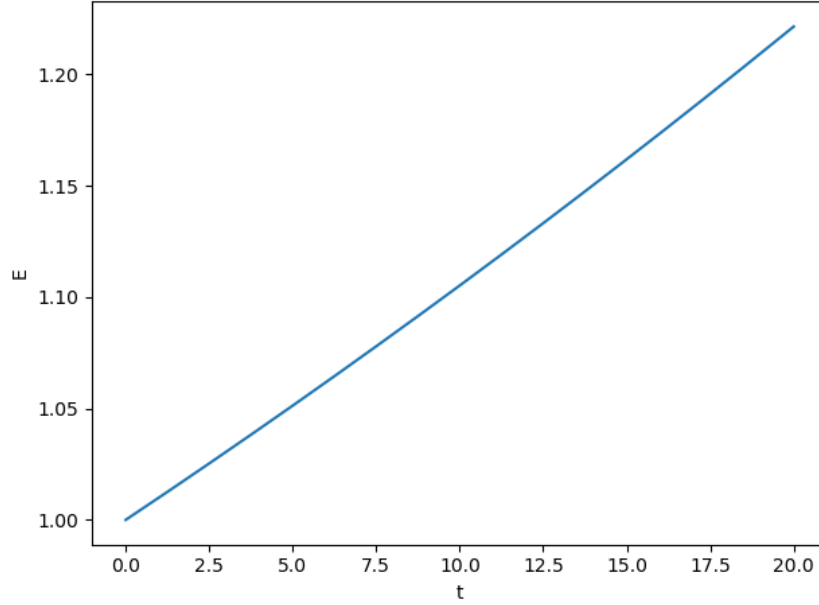


Figure 4: Normalized energy computed from the results of the explicit Euler method for the same initial conditions and with  $h = 0.01$  as before.

We observe that there is a linear increase with time of the normalized energy, similar to the behavior of the global error in with respect to  $h$ .

5. We implement the implicit Euler method using the recurrence relations:

$$\begin{aligned}x_i &= x_{i-1} + hv_{i-1} \\v_i &= -x_{i-1} + v_{i-1}\end{aligned}$$

We then plot the global error behavior and the normalized energy as we did for our implementation of the explicit Euler method, making sure to use the same  $h = 0.01$  for the normalized energy plot to draw a fair comparison.

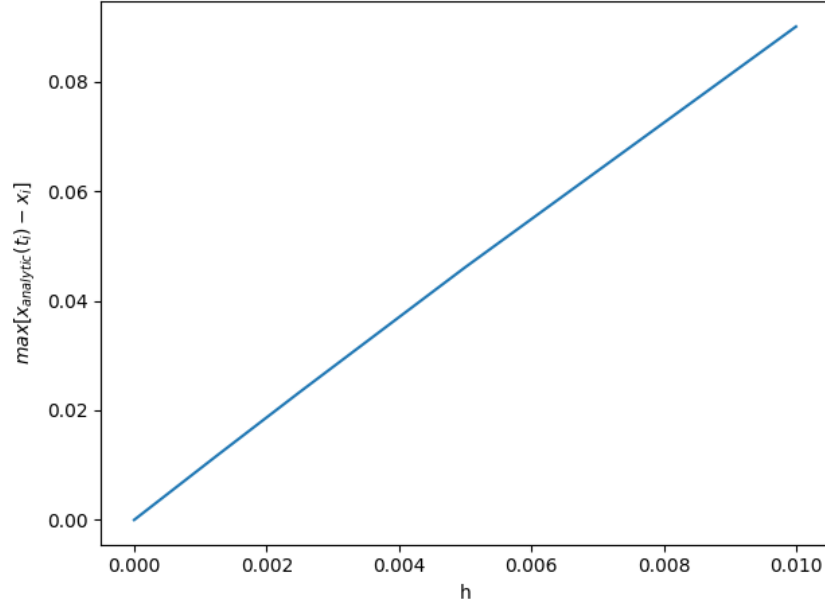


Figure 5: Plot of maximum global error in  $x$  against  $h$  for the implicit Euler method, integrating up to  $t = 20$  for each  $h$ .

We observe that the global error for the implicit Euler method behaves identically to the global error for the explicit Euler method.

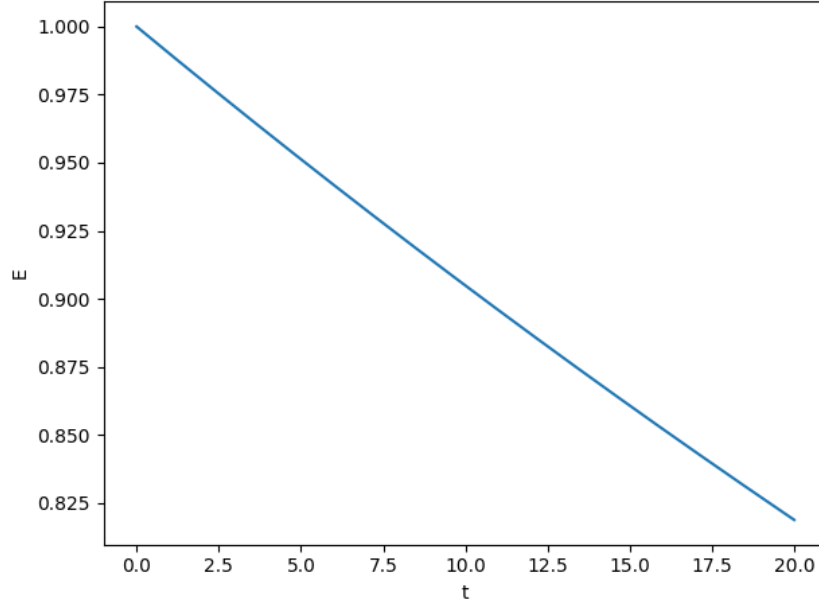


Figure 6: Normalized energy computed from the results of the implicit Euler method for the same initial conditions and with  $h = 0.01$  as before.

We observe that the normalized energy for the implicit Euler method decreases linearly in time, with gradient negative that for the explicit Euler method.

## Part 2

1. We plot our solutions in phase space (plotting  $v$  againsts  $x$ ) setting  $h = 0.01$  and integrating up to  $t = 20$ .

First, we do this for the analytical solution for the system:

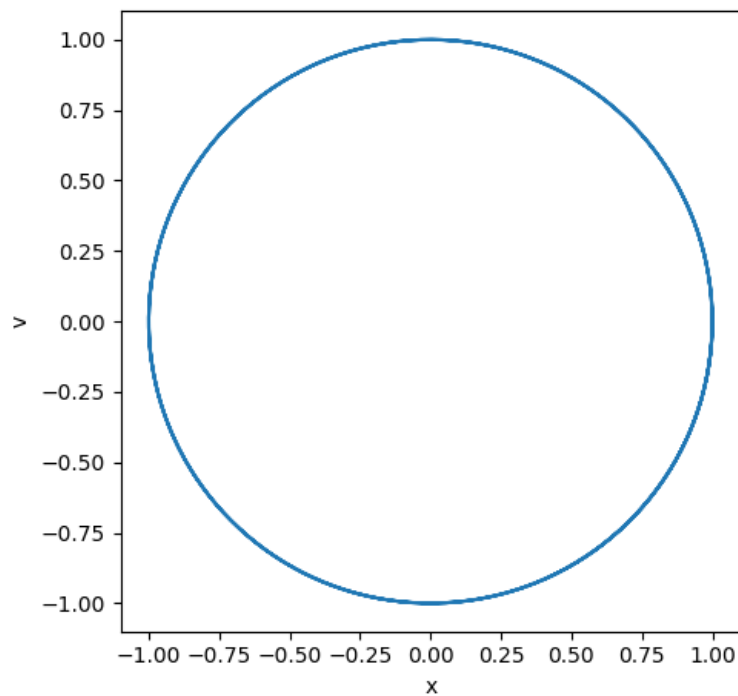


Figure 7: Plotting the analytic solution in phase space, up to  $t = 20$ .

This solution is exactly what we would expect, since  $E = x^2 + v^2$  is conserved.

We then plot the numerical solution obtained using the explicit Euler method:

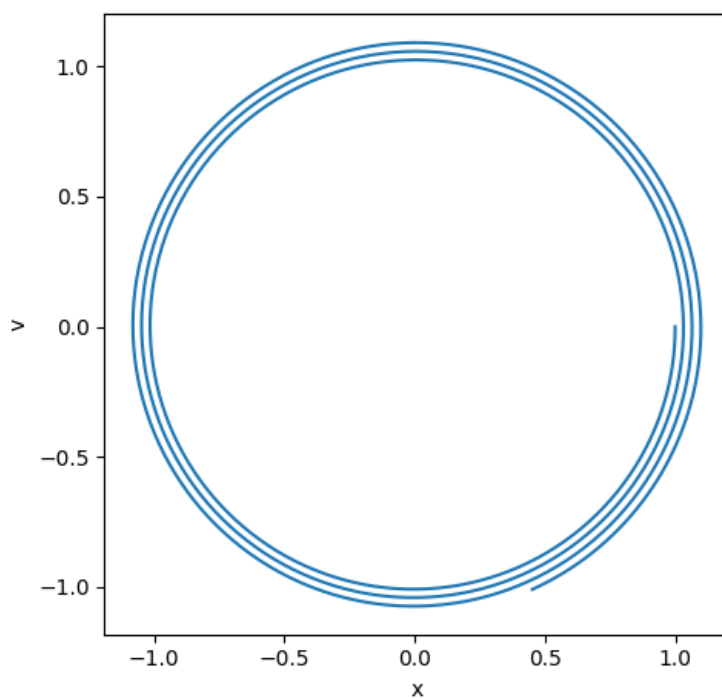


Figure 8: Plotting the numerical solution obtained using the explicit Euler method, integrating up to  $t = 20$ .

This is what we expect for this method, since errors are induced such that  $E$  increases linearly in time, i.e. trajectories in phase space spiral outwards.



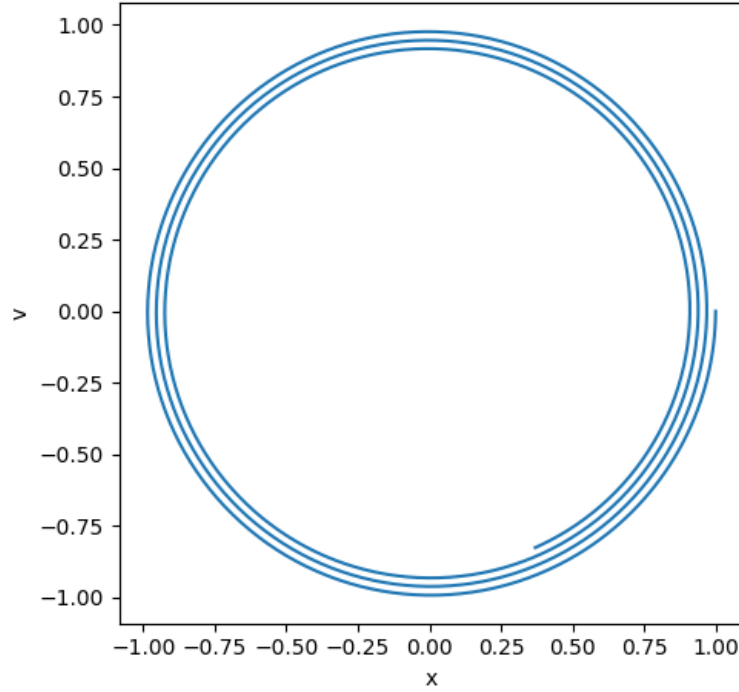


Figure 9: Plotting the numerical solution obtained using the implicit Euler method, integrating up to  $t = 20$ .

This is what we expect for this method, since errors are induced such that  $E$  increases linearly in time, i.e. trajectories in phase space spiral inwards.

2. We implement the symplectic Euler method, and again plot the numerical solution obtained in phase space, setting  $h = 0.01$  and integrating up to  $t = 20$ .

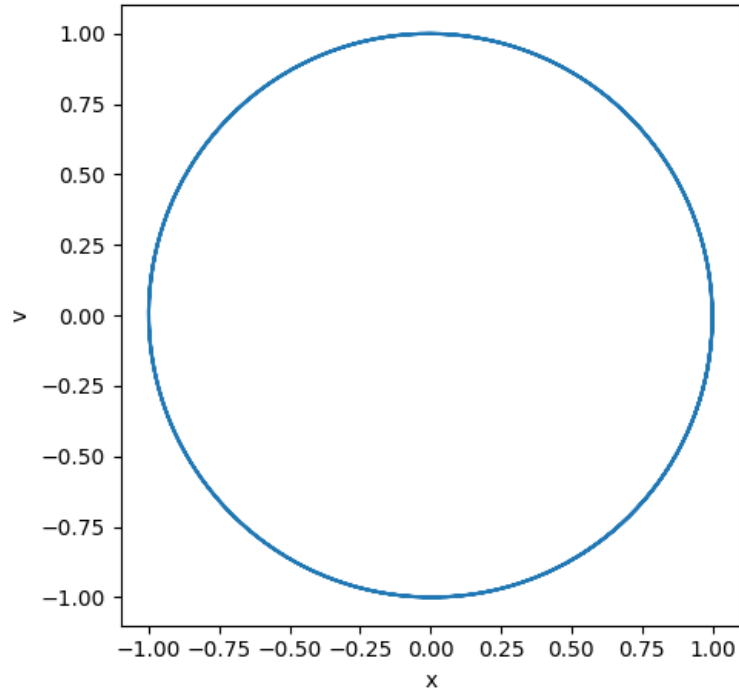


Figure 10: Plotting the numerical solution obtained using the symplectic Euler method, integrating up to  $t = 20$ .

This shows the behavior we expect from a symplectic method in that it conserves  $E$ , i.e. the curve in phase space is closed and bounded.

3. We now plot the evolution of  $E = x^2 + v^2$  with time, using the symplectic Euler method, setting  $h = 0.01$  and integrating to  $t = 20$ .

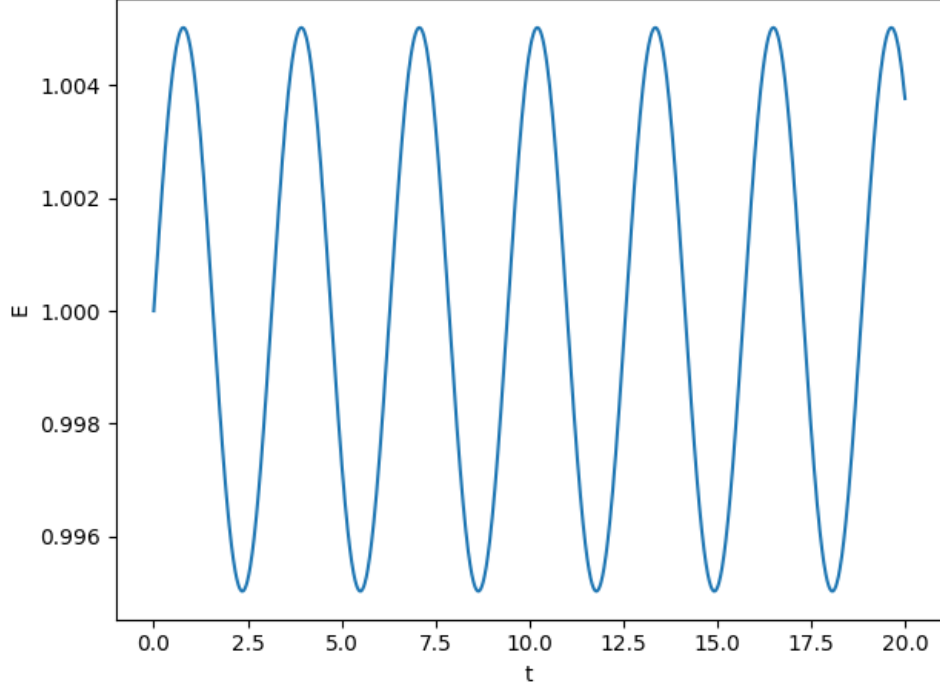


Figure 11: Normalized energy computed from the results of the symplectic Euler method for the same initial conditions and with  $h = 0.01$  as for all parts above, integrating up to  $t = 20$ .

We first note that the analytic solution for  $E$  with respect to time is obviously the line  $E = 1$  since  $E$  is conserved. We can therefore observe that the deviations from  $E = 1$  time-average to zero, as we expect from a symplectic solution. This is exactly what we saw in phase space: there are slight deviations from a perfect circle but the resulting curve is nevertheless closed and encloses the same area as the analytic phase space curve, indicating that deviation time-average to zero.