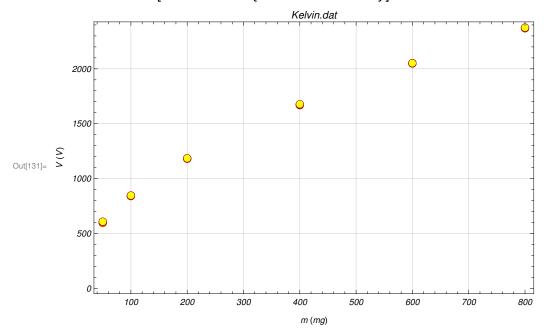
# Ph 6 - Experiment 7 (The Kelvin Absolute Voltmeter)





#### (\* Converting into V/kg \*)

All 30 points transformed.

ln[135]:= (\* Squaring voltage values to obtain expected linear relationship \*) xnew[x\_, y\_] := x

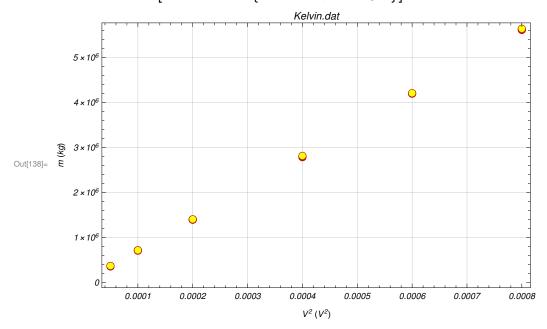
ynew[x\_, y\_] := x ynew[x\_, y\_] := y^2

DataTransform[]

(\* Use Undo[] if you don't like the results. \*)

All 30 points transformed.

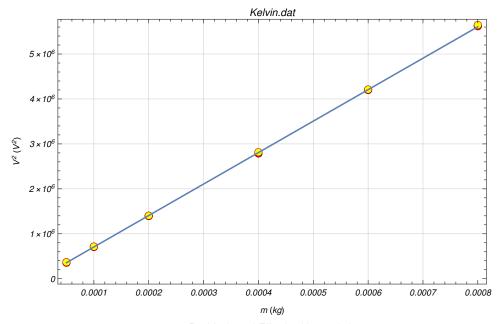


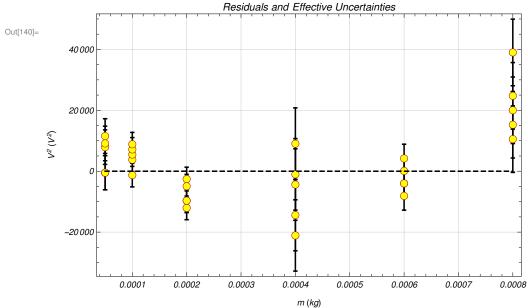


## Fitting the $V^2$ against m data against a linear model

#### In[139]:= LinearFit[]







#### Conclusions from fit

From the low  $\tilde{\chi}^2$  value (2.828) of the linear fit and the relatively small intercept (and therefore small offset), we can deduce that the  $V^2 \propto m$  holds over our range of measurements. In fact, our fit determines the proportionality constant up to an error of  $\pm$  0.0604%, whereby our residuals are of the order of  $10^4$  but our transformed data points for  $V^2$  have values on the order of  $10^6$ . We therefore conclude that the

data supports the proposed relationship  $V^2 \propto m$  given the fit we have obtained and considering the uncertainties inherent to the system (see last section).

### Experimental determination of $\epsilon_0$ and c

Recall the relationship  $V^2 = \text{km}$ ,  $k = \frac{2 \text{ gd}^2}{\pi r^2 \epsilon_0}$ . From this, we can find  $\epsilon_0$  from the slope k using  $\epsilon_0 = \frac{2 \text{ gd}^2}{\pi r^2 k}$ .

We can then find the uncertainty in our value for  $\epsilon_0$  by propagating the errors:

```
\frac{\Delta \epsilon_0}{\epsilon_0} = \left[ \left( \frac{\Delta a}{g} \right)^2 + \left( \frac{2\Delta d}{d} \right)^2 + \left( \frac{2\Delta r}{r} \right)^2 + \left( \frac{\Delta k}{k} \right)^2 \right]^{\frac{1}{2}}. Using data from the calibration card:
```

```
ln[141]:= g = 9.7957;
           errg = 0.001;
           d = 0.00309;
           errd = 0.00005;
           reff = 0.03073;
           errreff = 0.00001;
           k = 6.99929 * 10^9;
           errk = 4.22733 * 10^6;
           \epsilon = \frac{2 g d^2}{\pi \operatorname{reff}^2 k}
           erre = e * Sqrt \left[ \left( \frac{errg}{g} \right)^2 + \left( 2 \frac{errd}{d} \right)^2 + \left( 2 \frac{erreff}{reff} \right)^2 + \left( \frac{errk}{k} \right)^2 \right]
Out[149]= 9.00852 \times 10^{-12}
Out[150]= 2.91649 \times 10^{-13}
```

We therefore have an estimate of  $\epsilon_0 = (9.0085 \pm 0.2916) \times 10^{-12} \, \text{Fm}^{-1}$ . From this, we can use the permeability of free space,  $\mu_0 = 4 \pi \times 10^{-7} \text{ Hm}^{-1}$  to estimate the speed of light in a vacuum, c.

In[151]:= 
$$\mu = 4 \pi * 10^{-7}$$
;  

$$C = \frac{1}{\text{Sqrt}[\mu \, \epsilon]}$$

$$\text{errc} = c * \frac{\text{erre}}{\epsilon}$$
Out[152]= 2.97213 × 10<sup>8</sup>
Out[153]= 9.62222 × 10<sup>6</sup>

We then estimate  $c = (2.9721 \pm 0.0962) \times 10^8 \text{ ms}^{-1}$ .

## Major limiter to accuracy

Given the use of S-1 precision masses and an accurate constant-voltage power supply and careful leveling of the apparatus, it can be concluded that the major limiter to the accuracy of this experiment is the sensitivity to environmental noise inherent to the system.

In fact, by considering a parallel plate capacitor maintained under constant voltage, we observe that a small change in the distance between the plates (for instance, due to vibrations of the table due to sound or transmitted via the floor) will cause the force between the capacitor places to increase, with  $\frac{F}{A} = \frac{1}{2} \epsilon_0 \frac{V^2}{\sigma^2}$  as derived in the pre-lab. Therefore, the equilibrium point at which the force equals the weight of the mass used is an unstable equilibrium - when in the neighborhood of the equilibrium point, a small disturbance causing the top plate to move slightly past the equilibrium point will in turn cause the force between the plates to increase, accelerating the top plate downwards, which in turn increases the force between the plates and this feeds into itself until the pin stops the top plate from moving any further.

This unstable equilibrium is useful - our method of taking data points is based around it, in that moving just past the equilibrium results in the top plate moving all the way down and hitting the pin, which is the observation that we use to take data points. However, it also introduces errors in our experiments, as small disturbances when in the neighborhood of the equilibrium point can cause the top plate to move all the way down at an incorrect voltage randomly.