s_2 $w_1[y]$ $r_2[y]$ pc_1 a_1

 $r_2[z] w_3[z] pc_2$

 $S_1 = W_1[X] W_3[X] pa_1 a_1$ $S_2 = W_1[Y] r_2[Y] pc_2 c_2$

 $r_2[z] w_3[z] pc_2 c_2$