

# 1 Goal

We would like to show that at each step the algorithm returns a correct result and at the end it returns a complete result.

## 1.1 Strategy

*beginning* *nth step* *final*

### 1.1.1 *beginning*

fff

### 1.1.2 *nth step*

- Move the terms to below to definitions
- Define beachline as an inductive, draws the similarity between its definition and balanced brackets

- Write how to move from a beachline to show the voronoi diagram up to the beachline is correct

We divide the plane into three regions :

1. The **cliff**: Everything (*sites*, *edges*, *cells*) in this region is complete and it doesn't affect anything below this line. This regions is characterized as anything doesn't belong to the.

**Proof:**

(*handwavy*) every site in this region must be enclosed by a cell since it disappeared from the beach-line by circle event(s). Then from triangle inequality, argue that nothing beyond its cell bleong to the site's region.

2. **Beach**: The region between the sweep-line and the beach-line.

3. **offshore** Below the sweep-line: This region has no affect on lies above it.

**Proof:**

Anything above the beach-line is closer to regions 2 and 3 than any site below the sweep-line.

4. **Events**

- *Site event* :

Adding a new site will affect the *offshore* and the *beach*

- *Circle event*:

- Definition : when three sites are equidistant to each other
- It happens at the top of the circle

- When adding a new site  $p$ , it's enough to check the three consecutive arcs where  $p$  is the right-most or the left-most.

**Proof:** Other circle events has been discovered before and when there are other circle events involves  $p$  but the arcs are not consecutive the they are necessarily has a lower priority, thus they will be discovered when an arc is removed and become consecutive.

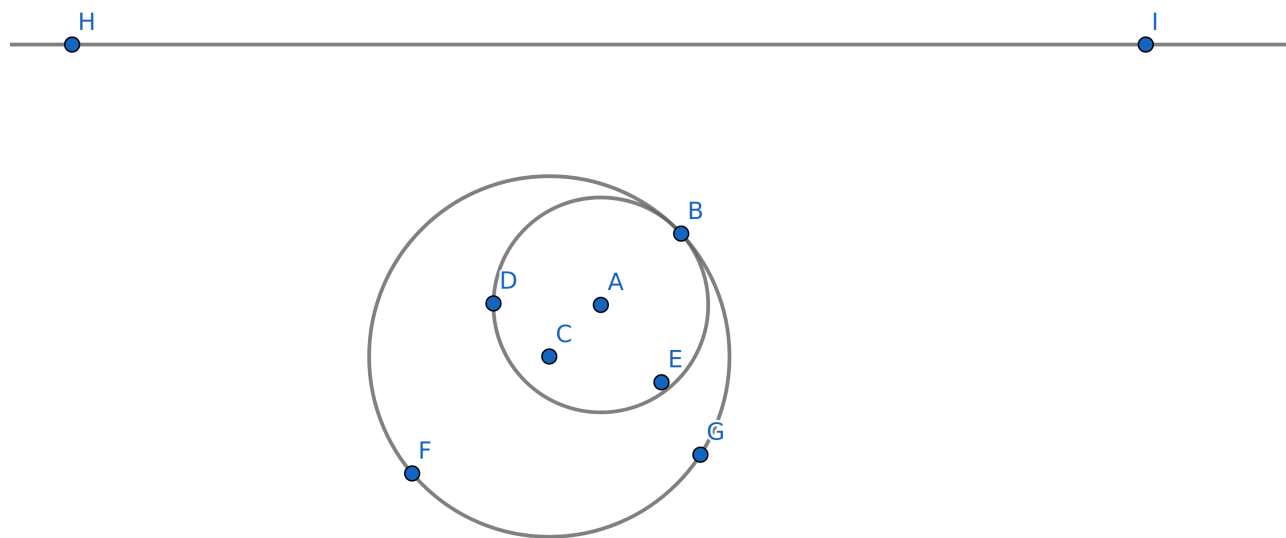


Figure 1: circle events

- moving the *sweepline*
  - How the three components will be affected
    - \* no event *event* is encountered: Update the intersection points and edges
    - \* *site event* update intersection points:
    - \* *circle event*
- overriding events

### 1.1.3 Final

## 2 Definitions

### 2.1 Cells

For any site, if the collection of edges that has the site as one of the focal points form a cycle. Also, each end of those edges are equidistant from three sites then this cell is convex and a valid Voronoi decomposition.

**Proof:** This cell is formed by an intersection of half-planes thus it's convex. Also, it's valid since if  $a, b$  are equidistant from  $p, q$  then the whole segment  $[a, b]$  is equidistant from  $p, q$ .

## 3 Functions

### 3.1 Parabola Functions

#### 3.1.1 Intersection of two arcs

Let  $p_1, p_2$  be two arcs and their intersections are  $a_1, b_1$  then as the sweepline moves there will be new intersections  $(a_1, b_1), (a_2, b_2), \dots (a_k, b_k)$  the line segments formed by  $a_i$ s lies on the same line similarly  $b_i$ s satisfy the same property.

The main method is to show that a solution belongs to two curves which boils down to algebraic manipulations.

### 3.2 Lines, Circles, and distances

## 4 Events

We assume that the algorithm has processed  $n$  events. We would like to check if we have given a correct decomposition then performing a site event or a circle event will preserve the correctness of the decomposition up to the cliff.

### 4.1 Bound on events length

If the beach-line is of length after a site event then at most there will be  $n - 2$  circle events. Thus, the queue length can't exceed  $n^2$  where  $n$  is the number of sites. Tightening this bound has no almost effect on the performance as it sole role to tell Coq the main function's recursion will terminate.