

Wave Simulation Using Modern C++

Victor Barros Yan Cheng

## Motivation of this project

- One one hand, in today's classrooms, scientific computation is taught mostly in Python
- Students often believe C++ is expert-friendly and beginner-unfriendly. This is a
  deep-rooted idea that their teachers probably believe as well.
- On the other hand, programs for scientific computation, developed by experienced scientists and engineers, are often unreadable to novice researchers
- Numpy achieved such success because its many features are well-designed
- With old C++, reproducing these features are highly nontrivial
- Challenge 1: Can we use modern C++ to easily create features similar to what Numpy offers?
- Challenge 2: Can these new features make C++ programs for scientific computation more readable while maintaining the high performance?

## In our project, we focus on the wave simulation

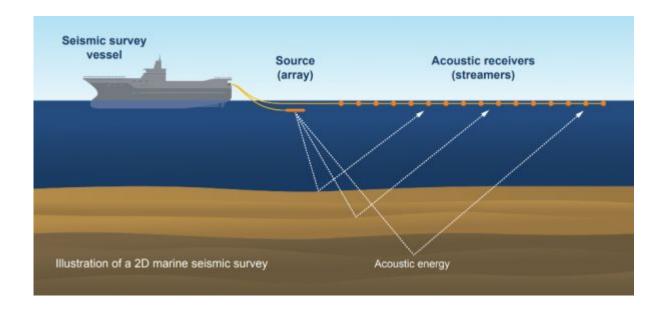
Wave simulation has application in geophysics, medical imaging, etc.

This requires solving the following equation numerically

$$\frac{1}{v^2} \frac{\partial^2 u}{\partial t^2} - \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) = f \quad \text{in } \mathbb{R}^2 \times (0, T)$$
$$u|_{t=0} = \frac{\partial u}{\partial t} \Big|_{t=0} = 0 \quad \text{in } \mathbb{R}^2.$$

- The numerical algorithm we use is the finite-difference time-domain (FDTD) method.

# Example: application in exploration geophysics



# Numerical Algorithm

```
def ricker(i s, j s, f=10, amp=le0, shift=0.1, extra=False):
   creates a source function (ricker pulse signal)
   f(t,x,y) = g(t) delta(x-x s) delta(y-y s)
   parameters:
   x s, y s: indices of location of the signal
   f: peak frequency
   amplitude: the default is 1
   shift: shifts the center to left or right
   return:
    3d array (discretized f(t,x,y))
   t = np.linspace(tmin, tmax, nt)
   pft2 = (np.pi * f * (t - shift))**2
   r = amp * (1 - 2 * pft2) * np.exp(-pft2)
   if (extra == True):
     pft2 = (np.pi * f M * (t - 2 * shift))**2
     r += 0.1 * amp * (1 - 2 * pft2) * np.exp(-pft2)
   x = np.zeros(nx)
   z = np.zeros(nz)
   x[i s] = 1.0
   z[j_s] = 1.0
   R, X, Z = np.meshgrid(r, x, z, sparse=True, indexing='ij')
   return R*X*Z
```

```
namespace waveSimCore
   //! Get the Ricker wavelet as a 3D Array
   boost::multi array<double, 3> ricker(int i s, int j s, double f, double amp, double shift,
                                         double tmin, double tmax, int nt, int nx, int nz)
        const double pi = 3.141592654;
        boost::multi array<double, 1> t = np::linspace(tmin, tmax, nt);
        boost::multi_array<double, 1> pft2 = np::pow(pi * f * (t - shift), 2.0);
        boost::multi array<double, 1> r = amp * (1.0 - 2.0 * pft2) * np::exp(-1.0 * pft2);
        int dimensions_x[] = {nx};
        boost::multi array<double, 1> x = np::zeros<double>(dimensions x);
        int dimensions_z[] = {nz};
        boost::multi array<double, 1> z = np::zeros<double>(dimensions z);
        x[i_s] = 1.0;
        z[i \ s] = 1.0;
        const boost::multi arrav<double. 1> axis[3] = {r. x. z};
        std::vector<boost::multi array<double, 3>> RXZ = np::meshgrid(axis, false, np::ij);
        boost::multi_array<double, 3> source = RXZ[0] * RXZ[1] * RXZ[2];
        return source;
```

- np::linspace
- arithmetic operations, np::pow, np::exp
- np::meshgrid: e.g. use 1D arrays x, y to create f(x,y) = x^2 + xy.

```
def dfdx(fx, dx):
   dfdx, = np.gradient(fx, dx, dz)
   return dfdx
def dfdz(fz, dz):
    _, dfdz = np.gradient(fz, dx, dz)
   return dfdz
def divergence(fx, fz, dx, dz):
   dfdx, = np.gradient(fx, dx, dz)
    _, dfdz = np.gradient(fz, dx, dz)
   return dfdx + dfdz
def laplacian(f, dx, dz):
   dfdx, dfdz = np.gradient(f, dx, dz)
   d2fdx2, d2fdxdz = np.gradient(dfdx, dx, dz)
   d2fdzdx, d2fdz2 = np.gradient(dfdz, dx, dz)
   return d2fdx2 + d2fdz2
def d2dt2(f, dt):
   dfdt, _, _ = np.gradient(f, dt, dt, dt)
   d2fdt2, _, _ = np.gradient(dfdt, dt, dt, dt)
   return d2fdt2
def dfdt(f, dt):
   dfdt, _, _ = np.gradient(f, dt, dt, dt)
   return dfdt
```

np::gradient

```
namespace waveSimCore
   //! Takes the partial derivative of a 2D matrix f with respect to x
    boost::multi_array<double, 2> dfdx(boost::multi_array<double, 2> f, double dx)
       std::vector<boost::multi array<double, 2>> grad f = np::gradient(f, {dx, dx});
       return grad f[0];
   //! Takes the partial derivative of a 2D matrix f with respect to z
    boost::multi_array<double, 2> dfdz(boost::multi_array<double, 2> f, double dz)
       std::vector<boost::multi_array<double, 2>> grad_f = np::gradient(f, {dz, dz});
       return grad_f[1];
    //! Takes the second partial derivative of a 2D matrix f with respect to x
    boost::multi array<double, 2> d2fdx2(boost::multi array<double, 2> f, double dx)
       boost::multi array<double, 2> df = dfdx(f, dx);
       boost::multi_array<double, 2> df2 = dfdx(df, dx);
       return df2;
    //! Takes the second partial derivative of a 2D matrix f with respect to z
    boost::multi array<double, 2> d2fdz2(boost::multi array<double, 2> f, double dz)
       boost::multi array<double, 2> df = dfdz(f, dz);
       boost::multi array<double, 2> df2 = dfdz(df, dz);
       return df2;
   //! Takes the divergence of a 2D matrices fx.fz with respect to x and z\n
   //! Returns dfx/dx + dfz/dz
   boost::multi array<double, 2> divergence(boost::multi array<double, 2> f1, boost::multi array<double, 2> f2,
                                            double dx. double dz)
       boost::multi array<double, 2> f x = dfdx(f1, dx);
       boost::multi array<double, 2> f z = dfdz(f2, dz);
       boost::multi_array<double, 2> div = f_x + f_z;
       return div:
```

## np: Comparison between np and Numpy

```
void test toy problem()
                                                                                              boost::multi array<double, 1 > x = np::linspace(0, 1, 100);
                                                                                              boost::multi array<double, 1> y = np::linspace(0, 1, 100);
def test toy problem():
  x = np.linspace(0,1,100)
  y = np.linspace(0,1,100)
                                                                                              const boost::multi array<double, 1> axis[2] = {x, y};
  XcY = np.meshgrid(x,y,sparse=False,indexing="ij")
                                                                                              std::vector<boost::multi array<double, 2>> XcY =
  dx = 1.0/100.0
                                                                                           np::meshgrid(axis, false, np::xy);
  dy = 1.0/100.0
  f = np.power(XcY[0], 2.0) + XcY[0] * np.power(XcY[1], 1.0)
                                                                                              double dx = 1.0 / 100.0:
  gradf = np.gradient(f,dx,dy)
                                                                                              double dv = 1.0 / 100.0:
  i = 10:
  i = 20:
                                                                                              boost::multi array<double, 2> f = np::pow(XcY[0], 2.0) + XcY[0] *
  print( "df/dx of f(x,y) = x^2 + xy at x = " + str(x[i]) + " and y = "
                                                                                           np::pow(XcY[1], 1.0);
+ str(y[i]) + " is equal to " + str(gradf[0][i][i]))
                                                                                             std::vector<boost::multi_array<double, 2>> gradf = np::gradient(f,
                                                                                           \{dx, dy\});
                                                                                             int i = 10:
                                                                                             int j = 20;
                                                                                             std::cout << "df/dx of f(x,y) = x^2 + xy at x = " << x[i] << " and <math>y =
                                                                                           " << y[i] << " is equal to " << gradf[0][i][i];
    Result:
                                                                                              std::cout << "\n";
    df/dx of f(x,y) = x^2 + xy at x = 0.101 and y = 0.202 is equal to 0.408
```

# Implementation of np

## np: a numpy-like library

## Problems with current options:

- Limited to 2 or 3 dimensions
- Inconsistent behavior
- Lack of compile-time safety
- Limited in data types (double only)





## np: a numpy-like library



### Main features

- Uses boost::multi\_array and expands upon it
- Supports n-dimensional arrays and operations
- Very compile-time safe
- Easily expandable
- Very similar syntax to python's np
- Based on the standard library (+boost)
- Supports all std::is\_arithmetic data types (most of the time)

# boost::multi arrav



- Margin for improvement

ostriaiti_array					
		\_			
Nested structure of arrays			2,0	2,1	2,2
Iterator provided					
- Requires division operation to obtain the indexes			1,0	1,1	1,2
Uses views for slicing (very complex)					
Size allocation makes for terrible syntax			0,0	0,1	0,2
Size allocation makes for ter	Tible Syntax				
B.A					

## Syntax:

## Two dimensional array:

boost::multi array<double, 2> XZ = np::meshgrid(axis, false, np::ij)[0];

### N-Dimensional array of arbitrary type:

boost::multi array<type, ND> n-dimensional-array;

# Major modern C++ features used

- Concepts & Constraints
- Templates
- Variadic Templates
- Constexpr
- std::chrono

#### Example:

//! Implements the numpy min function for an n-dimensional multi array template <typename T, long unsigned int ND> requires std::is\_arithmetic<T>::value inline constexpr T min(boost::multi\_array<T, ND> const &input\_array)

# Example: Implementing meshgrid

```
//! Implementation of meshgrid
//! TODO: Implement sparsing=true
//! If the indexing type is xy, then reverse the order of the first two elements of ci
//! if the number of dimensions is 2 or 3
//! In accordance with the numpy implementation
template <typename T, long unsigned int ND>
         requires std::is arithmetic<T>::value
inline constexpr std::vector<boost::multi array<T, ND>> meshgrid(const
boost::multi_array<T, 1> (&cinput)[ND], bool sparsing = false, indexing indexing type =
xy)
         using arrayIndex = boost::multi array<T, ND>::index;
         using oneDArrayIndex = boost::multi array<T, 1>::index;
         using ndIndexArray = boost::array<arrayIndex, ND>;
         std::vector<boost::multi array<T, ND>> output arrays;
         boost::multi array<T, 1> ci[ND];
         // Copy elements of cinput to ci, do the proper inversions
         for (std::size t i = 0; i < ND; i++)
                  std::size t source = i;
                  if (indexing type == xy && (ND == 3 || ND == 2))
                           if (i == 0)
                                    source = 1;
                           else if (i == 1)
                                    source = 0:
                           else
                                    source = i;
                  ci[i] = boost::multi array<T, 1>();
                  ci[i].resize(boost::extents[cinput[source].num elements()]);
                  ci[i] = cinput[source];
```

```
// Deducing the extents of the N-Dimensional output
         boost::detail::multi_array::extent_gen<ND> output_extents;
         std::vector<size t> shape_list;
         for (std::size t i = 0; i < ND; i++)
                  shape list.push back(ci[i].shape()[0]);
         std::copy(shape list.begin(), shape list.end(),
output extents.ranges .begin());
        // Creating the output arrays
         for (std::size t i = 0; i < ND; i++)
                  boost::multi array<T, ND> output array(output extents);
                  ndArrayValue *p = output array.data();
                  ndIndexArray index;
                  // Looping through the elements of the output array
                  for (std::size t j = 0; j < output array.num elements(); j++)
                           index = getIndexArray(output array, p);
                           oneDArrayIndex index 1d;
                           index 1d = index[i];
                           output array(index) = ci[i][index 1d];
                           ++p;
                  output arrays.push back(output array);
         if (indexing type == xy && (ND == 3 || ND == 2))
                  std::swap(output arrays[0], output arrays[1]);
         return output arrays:
                                                                          14
```

# Using

## Using the executable

Print help

\$./WaveSimPPExec -h

-h. --help

A wave propagation simulator written in C++. Usage: WaveSimPP [OPTION...] -d, --debug **Enable debugging** Render an animation at the end (default: true) --animate --render Render each of the frames at the end --export Export the data to a series of csv files -o, --output dir arg **Output directory path (default: output)** --output\_filename arg Output filename (default: output.mp4) --framerate arg Framerate of output video (default: 30) -v, --verbose Verbose output --source i arg Source i position (default: 50) --source j arg Source i position (default: 50) Number of time steps (default: 1000) --nt arg Number of x steps (default: 100) --nx arg --nz arg Number of z steps (default: 100) --dt arg Time step size (default: 0.001) --dx arg x step size (default: 0.01) z step size (default: 0.01) --dz arg Frequency of source (default: 10.0) -f, --frequency arg -a, --amplitude arg Amplitude of source (default: 1.0) -s, --shift arg Shift of source (default: 0.1) Radius of velocity profile (default: 150.0) -r, --radius arg -I, --num levels arg Number of levels in the filled contour plot (default: 100)

## Using as a library

```
// Create the source
boost::multi_array<double, 3> f = waveSimPPCore::ricker(source_is, source_js, f_M, amp, shift, tmin,
tmax, nt, nx, nz);

// Create the velocity profile
double r = 150.0;
boost::multi_array<double, 2> vel = waveSimPPCore::get_profile(xmin, xmax, zmin, zmax, nx, nz, r);

// Then we can proceed to solve the wave equation using the wave solver.

// Solve the wave equation
boost::multi_array<double, 3> u = waveSimPPCore::wave_solver(vel, dt, dx, dz, nt, nx, nz, f);
```

# Rendering

## Renderers: Internal (Matplot++)

### https://github.com/alandefreitas/matplotplusplus

#### Known issues: it is a limited library

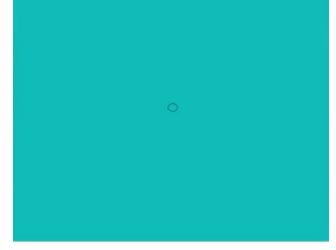
#### Render all frames as .csv file each:

void wavePlotter::Plotter::animate(std::string
output\_file\_name, int begin\_frame\_index, int
end\_frame\_index, int frame\_rate)

### Animating:

```
void wavePlotter::Plotter::renderFrame(int index)
{
    matplot::vector_2d Up = np::convert_to_matplot(this->u[index]);
    matplot::contourf(this->Xp, this->Zp, Up, this->levels);
    matplot::save(save_directory + "/contourf_" + format_num(index) + ".png");
}
```

#### Result:



## Renderers: External (matplotlib) Animating:

#### Render all frames as .csv file each:

```
void wavePlotter::Plotter::exportAllFrames(int
begin_frame_index, int end_frame_index)
```

#### **Loading frames in Python:**

```
frames = []
for i in range(999):
    filename = "build/output/frame_" + f'{i:08}' +".csv"
    frames.append(pd.read_csv(filename))
```

```
umax = np.max([df.max().max() for df in frames])
umin = np.min([df.min().min() for df in frames])
n_levels = 100
levels = np.linspace(umax,umin,100)
```

#### Result:

```
def make cartoon(u, vmin, vmax, num level=100, skip=10, size=25, interval=80,
cmap=None):
  # Insert geometric constants from the original problem here
  x = np.linspace(xmin, xmax, nx)
  z = np.linspace(zmin, zmax, nz)
  X, Z = np.meshgrid(x, z, indexing='ij')
  levels = np.linspace(vmin, vmax, num level)
  fig, ax = plt.subplots(figsize=(size, size))
  ax.contourf(X, Z, u[0], levels=levels, vmin=umin, vmax=umax, cmap=cmap)
  ax.set ylabel("z (m)")
  plt.gca().set aspect('equal', adjustable='box')
  def animate(i):
    i *= skip
    ax.clear()
    ax.text(0.45, 1.05, "t = {0:0.2f}".format(np.round(i*dt, 2)), transform=ax.transAxes)
    ax.contourf(X, Z, u[i], levels=levels, vmin=vmin, vmax=vmax, cmap=cmap)
    ax.invert yaxis()
    ax.set xlabel("x (m)")
    ax.set ylabel("z (m)")
    plt.close()
  return animation. FuncAnimation(fig., animate, interval=interval,
```

frames=int(len(u)/skip))

# Benchmarking

# Benchmarking: Wave Solving

System specs:

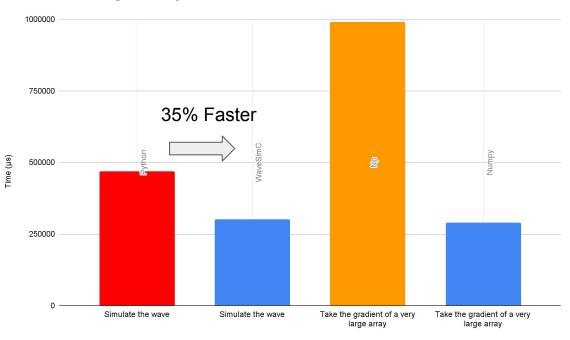
OS: Ubuntu 20 Running on Windows 11 WSL

CPU: Ryzen 5800H (8 Cores, 16 Threads)

RAM: 32GB DDR4

System Capped at 100W

#### **Benchmarks against Python**



Operation

# Infrastructure

## Version, Compiler and Build System

C++20

## **GCC 12**

- Large amount of C++20 features
- Standard in unix systems
- Free and open source

### CMAKE

- Widely used in unix systems
- Compatible with our external libraries
- Easy to use
- Free and open source





## Hosting: github

Github repository:

https://github.com/yc3855/COMSW4995

- Automatic checking of every commit through the use of github actions
- Bugs & features managed through github issues
- Open source and we aim to make it community driven





## Documentation: Doxygen + Netlify

- doxygen
- Automatic generation of documentation through in-code comments
- Generates PDF and HTML docs
- Support for markdown

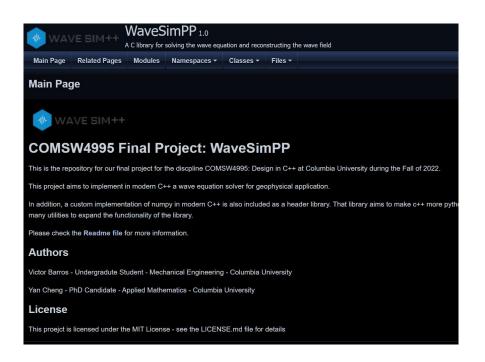
## Netlify:

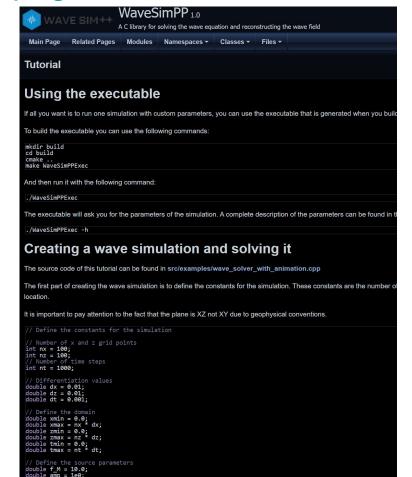
- Automatic deployment of static web pages
- Free for simple use

Online docs: <a href="https://wavesimc.vbpage.net/">https://wavesimc.vbpage.net/</a>

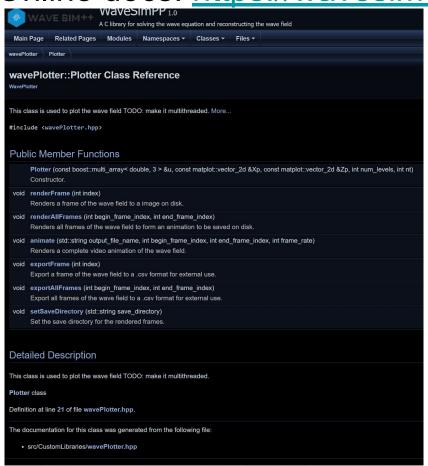


## Online docs: <a href="https://wavesimc.vbpage.net/">https://wavesimc.vbpage.net/</a>





Online docs: <a href="https://wavesimc.vbpage.net/">https://wavesimc.vbpage.net/</a>



```
mesharid()
 ::value constexpr std::vector< boost::multi_array< T, ND > > np::meshgrid ( const boost::multi_array< T, 1 >(&)_cinput[ND],
                                                                                                                              indexing type = xv
Implementation of mesharid TODO: Implement sparsing=true If the indexing type is xx, then reverse the order of the first two elements
Definition at line 184 of file np.hpp.
                    using arrayIndex = boost::multi_array<T, ND>::index;
using oneDArrayIndex = boost::multi_array<T, 1>::index;
                    using ndIndexArray = boost::array<arrayIndex, ND>;
                    std::vector<boost::multi_array<T, ND>> output_arrays;
                    boost::multi_array<T, 1> ci[ND];
                                                                 do the proper inversions
                     for (std::size t i = 0; i < ND; i++)
                         std::size_t source = i;
if (indexing_type == xy && (ND == 3 || ND == 2))
                               if (i == 0)
                              source = 1;
else if (i == 1)
                                    source = 0;
                                    source = i:
                         ci[i] = boost::multi_array<T, 1>();
ci[i].resize(boost::extents[cinput[source].num_elements()]);
ci[i] = cinput[source];
                    // Deducing the extents of the N-Dimensional output
boost::detail::multi_array::extent_gen<ND> output_extents;
std::vector<size t> shape_list;
for (std::size_t i = 0; i < ND; i++)</pre>
                         shape_list.push_back(ci[i].shape()[0]);
                     std::copy(shape_list.begin(), shape_list.end(), output_extents.ranges_.begin());
                     for (std::size t i = 0; i < ND; i++)
                         boost::multi_array<T, ND> output_array(output_extents);
                          ndArrayValue *p = output_array.data();
                          ndIndexArray index;
                                                    the elements of the output array
                            or (std::size_t j = 0; j < output_array.num_elements(); j++)
                              index = getIndexArray(output_array, p);
oneDArrayIndex index 1d;
index 1d = index[i];
output_array(index) = ci[i][index_1d];
                          output arrays.push back(output array);
                        (indexing_type == xy && (ND == 3 || ND == 2))
                         std::swap(output_arrays[0], output_arrays[1]);
```

# Plans for the future

## Plans for the future

- Implement a custom multi-dimensional array data structure
  - Improve performance and syntax
  - Would remove the dependency on boost

- Implement a custom rendering library
  - Address limitations of current options
  - Add gpu optimization

Further optimize functions



# Thank you