



论文检索报告

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检索结果：被 SCI-E 收录文献 1 篇																									
#	作者	标题	来源出版物	文献类型	入藏号																				
1	Shen, Y; Yao, CK; Chen, B; Che, WW; Wu, ZG	H _∞ optimal output tracking control for Markov jump systems: A reinforcement learning-based approach	INTERNATIONAL JOURNAL OF ROBUST AND NONLINEAR CONTROL 2024, 34 (8): 5149-5167.	J Article	WOS:001163189100001																				
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<p>第 1 条，共 1 条：</p> <p>标题: H_∞ optimal output tracking control for Markov jump systems: A reinforcement learning-based approach</p> <p>作者: Shen, Y (Shen, Ying); Yao, CK (Yao, Cai-Kang); Chen, B (Chen, Bo); Che, WW (Che, Wei-Wei); Wu, ZG (Wu, Zheng-Guang)</p> <p>来源出版物: INTERNATIONAL JOURNAL OF ROBUST AND NONLINEAR CONTROL 卷: 34 期: 8 页: 5149-5167 提前访问日期: FEB 2024</p> <p>出版年: MAY 25 2024</p> <p>入藏号: WOS:001163189100001</p> <p>文献类型: Article 出版物类型: J</p> <p>作者地址: [Shen, Ying; Yao, Cai-Kang; Chen, Bo] Zhejiang Univ Technol, Dept Automat, Hangzhou 310023, Peoples R China.; [Shen, Ying; Yao, Cai-Kang; Chen, Bo] Zhejiang Univ Technol, Zhejiang Prov United Key Lab Embedded Syst, Hangzhou, Peoples R China.; [Che, Wei-Wei] Qingdao Univ, Inst Complex Sci, Shandong Key Lab Ind Control Technol, Qingdao, Peoples R China.; [Wu, Zheng-Guang] Zhejiang Univ, State Key Lab Ind Control Technol, Hangzhou, Peoples R China.</p> <p>所属机构: Zhejiang University of Technology; Zhejiang University of Technology; Qingdao University; Zhejiang University</p> <p>通讯作者地址: Chen, B (corresponding author), Zhejiang Univ Technol, Dept Automat, Hangzhou 310023, Peoples R China.</p> <p>电子邮件地址: bchen@aliyun.com</p> <p>出版商: WILEY 出版商城市: HOBOKEN 出版商地址: 111 RIVER ST, HOBOKEN 07030-5774, NJ USA</p> <p>Web of Science 类别: Automation & Control Systems; Engineering, Electrical & Electronic; Mathematics, Applied</p> <p>研究方向: Automation & Control Systems; Engineering; Mathematics</p> <p>IDS 号: NK2C6</p> <p>ISSN: 1049-8923 eISSN: 1099-1239</p> <p>基金资助机构和授权号: National Key Research and Development Program of China; Public Welfare Applied Research Project of Huzhou Science and Technology Bureau [2023GZ76]; National Natural Science Foundation of China [62103373]; Zhejiang Provincial Natural Science Foundation of China [LQ22F030012]; Fundamental Research Funds for the Provincial Universities of Zhejiang [RF-C2023007]; Key Research and Development Program of Ningbo [2023Z030]; [2022YFF0904503]</p> <p>基金资助致谢: This work was supported in part by the National Key Research and Development Program of China under grant 2022YFF0904503, in part by the Public Welfare Applied Research Project of Huzhou Science and Technology Bureau under grant 2023GZ76, in part by the National Natural Science Foundation of China under grant 62103373, in part by the Zhejiang Provincial Natural Science Foundation of China under grant LQ22F030012, in part by the Fundamental Research Funds for the Provincial Universities of Zhejiang under grant RF-C2023007, in part by the Key Research and Development Program of Ningbo under grant 2023Z030.</p> <p>JCR 期刊分区:</p> <table><tr><th>数据库</th><th>JCR 学科类别</th><th>类别排序</th><th>类别分区</th><th>指标年份</th></tr><tr><td>SCIE</td><td>AUTOMATION & CONTROL SYSTEMS</td><td>27/65</td><td>Q2</td><td>2022</td></tr><tr><td>SCIE</td><td>ENGINEERING, ELECTRICAL & ELECTRONIC</td><td>100/275</td><td>Q2</td><td>2022</td></tr><tr><td>SCIE</td><td>MATHEMATICS, APPLIED</td><td>12/267</td><td>Q1</td><td>2022</td></tr></table>						数据库	JCR 学科类别	类别排序	类别分区	指标年份	SCIE	AUTOMATION & CONTROL SYSTEMS	27/65	Q2	2022	SCIE	ENGINEERING, ELECTRICAL & ELECTRONIC	100/275	Q2	2022	SCIE	MATHEMATICS, APPLIED	12/267	Q1	2022
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