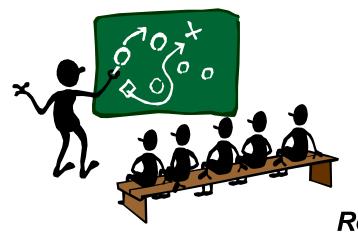
## Algorithms Chapter 1 & 2 Getting Started



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### **Algorithms**

#### Algorithm

- is any well-defined computational procedure
- takes some value or set of values as input
- produces some value or set of values as output
- → is a sequence of computational steps that transfer the input into the output
- An algorithm is a tool for solving a well-specified computational problem
- The problem statement
  - specifies the desired input/output relationship
  - → the algorithm is a specific procedure for achieving that I/O relationship

#### **Sorting Problem**

- Sorting problem
  - input: a sequence of n numbers  $\langle a_1, a_2, ..., a_n \rangle$
  - output: a permutation  $\langle a_1, a_2, ..., a_n \rangle$ of the input sequence such that  $a_1 \le a_2 \le ... \le a_n$
- For example
  - an instance of the problem - input: <31, 41, 59, 26, 41, 58>
  - output: <26, 31, 41, 41, 58, 59>
- An instance of the problem
  - consists of the input needed to compute a solution (output) to the problem

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#### **Correctness of Algorithm**

- Correct algorithm
  - halts with the correct output for every input instance
- A correct algorithm solves the given computational problem
- Incorrect algorithm
  - might halt with an incorrect output
  - might not halt for some input instances

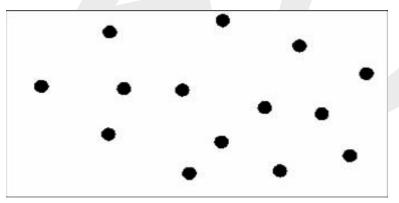
#### **Beyond the Correctness**

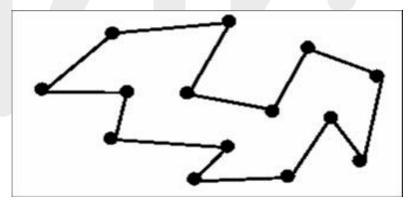
- Make the algorithm correct first
- Reality
  - computers are not infinitely fast
  - memory is not infinitely large
- In addition to correctness, a good algorithm should be efficient in both time and space

Correctness vs. Efficiency?

### **Traveling Salesman Problem (TSP)**

- **Input:** A set of points (cities) P together with a distance d(p, q) between any pair  $p, q \in P$
- Output: What is the shortest circular route that starts and ends at a given point and visits all the points



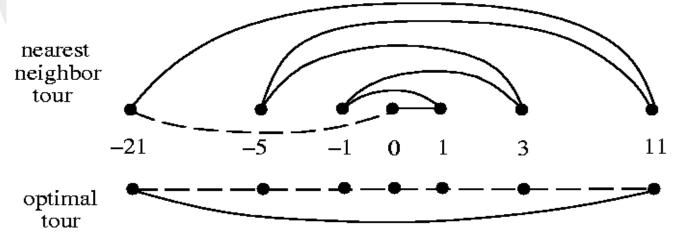


Correct and efficient algorithms?

#### **Nearest Neighbor Tour**

- 1. pick and visit an initial point  $p_0$
- 2.  $P \leftarrow p_0$
- $3. i \leftarrow 0$
- 4. **while** there are unvisited points **do**
- visit  $p_i$ 's nearest unvisited point  $p_{i+1}$
- $i \leftarrow i + 1$
- 7. return to  $p_0$  from  $p_i$
- Simple to implement and very efficient, but

incorrect!



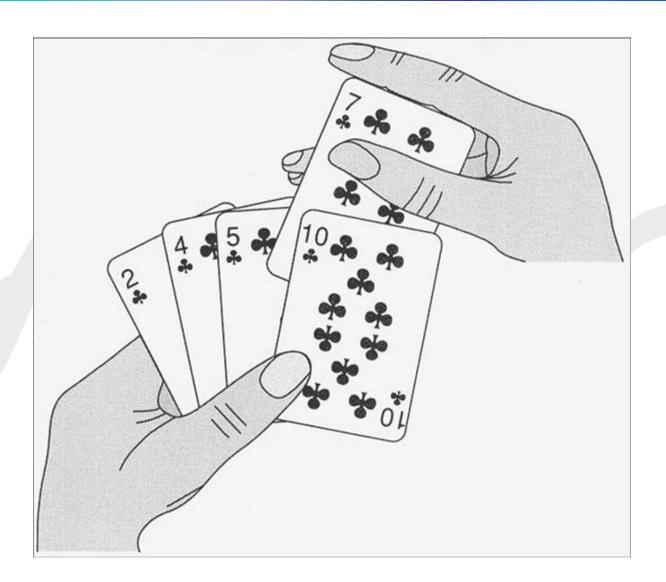
### A Correct but Inefficient Algorithm

- 1.  $d \leftarrow \infty$
- 2. for each of the n! permutations  $\pi_i$  of the n points
- 3. if  $(\cos t(\pi_i) \le a)$  then
- 4.  $d \leftarrow cost(\pi_i)$
- 5.  $T_{min} \leftarrow \pi_i$
- 6. return  $T_{min}$
- Correctness? Try all possible orderings of the points →
   Guarantee to end up with the shortest possible tour
- Efficiency? Try n! possible routes!
  - 120 routes for 5 points; 3,628,800 routes for 10 points
  - no known efficient and correct algorithm for TSP!
  - TSP is NP-complete
- Think Deep: What will you do?

#### **Sorting Problem**

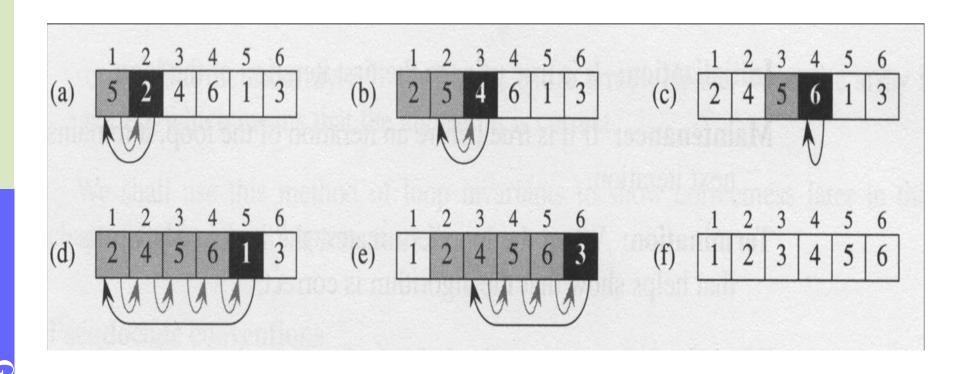
- Sorting problem
  - input: a sequence of n numbers  $\langle a_1, a_2, ..., a_n \rangle$
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- For example
  - input: <31, 41, 59, 26, 41, 58>
  - output: <26, 31, 41, 41, 58, 59>
- The numbers under sorting are also known as keys
- How to sort?

## **Sorting a Hand of Cards**



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#### **Insertion Sort**



Insertion sort is an efficient algorithm for sorting a small number of elements

#### **Pseudocode**

#### Insertion sort

```
Insertion-Sort(A)
1 for j \leftarrow 2 to length[A]
    do key \leftarrow A[ j]
        * Insert A[j] into the sorted sequence A[1..j-1]
3
         i \leftarrow j - 1
        while i > 0 and A[i] > \text{key}
5
6
             do A[i+1] \leftarrow A[i]
                  i \leftarrow i - 1
        A[i+1] \leftarrow \text{key}
```

### **Analyzing Algorithms**

- Analyzing an algorithm has come to mean predicting the resources that the algorithm requires
  - CPU time
  - memory space
- Assumption
  - single processor (not multiprocessor, not parallel computing)
  - RAM as memory (not disk)

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#### Running Time vs. Input Size

- The running time needed by Insertion-Sort depends on the input size
  - 10 numbers vs. 1 million numbers
- In general
  - input size → running time
  - the running time is typically described as a function of the input size
- How to calculate running time?
  - count the number of primitive operations (steps)
  - machine-independent

## **Analysis of Insertion Sort**

Insertion-sort(A)	cost	times
1 for $j \leftarrow 2$ to length[A]	C1	n
2 <b>do</b> key $\leftarrow$ A[ $j$ ]	<i>c</i> <sub>2</sub>	n-1
3 * Insert A[ j ] into the	0	
sorted sequence $A[1j-1]$		
$4 \qquad i \leftarrow j-1$	C4	n-1
5 <b>while</b> $i > 0$ and $A[i] > \text{key}$	<i>c</i> 5	$\sum_{j=2}^{n} t_j$
6 <b>do</b> $A[i+1] \leftarrow A[i]$	<i>c</i> 6	$ \int_{n}^{j=2} (t_{j} - 1) $ $ \int_{n}^{n} (t_{j} - 1) $
$7   i \leftarrow i - 1$	<i>c</i> 7	$ \sum_{j=2}^{n} (t_j - 1) $
8 $A[i+1] \leftarrow \text{key}$	<i>c</i> 8	n-1

 $t_j$ : the number of times the while loop test in Line 5 is executed for the value of j

### **Best-Case Analysis**

$$T(n) = c_1 n + c_2 (n-1) + c_4 (n-1) + c_5 \sum_{j=2}^{n} t_j + c_6 \sum_{j=2}^{n} (t_j - 1) + c_7 \sum_{j=2}^{n} (t_j - 1) + c_8 (n-1)$$

- T(n) does not solely depend on n
- Best case: the array is already sorted

$$-t_j = 1$$
 for  $j = 2, 3, ..., n$ 

$$T(n) = c_1 n + c_2 (n-1) + c_4 (n-1) + c_5 (n-1) + c_8 (n-1)$$

$$= (c_1 + c_2 + c_4 + c_5 + c_8)n - (c_2 + c_4 + c_5 + c_8)$$

- T(n) is a linear function of n

### **Worst-Case Analysis**

Worst case: the array is sorted in reverse order

$$-t_j=j$$

$$T(n) = c_1 n + c_2 (n-1) + c_4 (n-1) + c_5 (\frac{n(n+1)}{2} - 1) + c_5 ($$

$$c_{6}(\frac{n(n-1)}{2}) + c_{7}(\frac{n(n-1)}{2}) + c_{8}(n-1)$$

$$= (\frac{c_{5} + c_{6} + c_{7}}{2})n^{2} - (c_{1} + c_{2} + c_{4} + \frac{c_{5} - c_{6} - c_{7}}{2} + c_{8})n$$

$$- (c_{2} + c_{4} + c_{5} + c_{8})$$

- T(n) is a quadratic function of n

#### **Best/Worst/Average Cases**

- We usually concentrate on finding the worst-case running time
  - the longest running time for any input size of n
- Why?
  - worst case gives an upper bound
  - for some algorithms, the worst case occurs fairly often
    - e.g., searches in databases
  - the average case is *often* roughly as bad as the worst case
    - e.g., for insertion sort, T(n) is still a quadratic function of n

#### **Order of Growth**

- Why is the running time typically described as a function of the input size?
  - to know how the running time grows as the input size grows
- It is the rate of growth, or order of growth, of the running time that really interests us
- For insertion sort
  - the worst-case running time,  $\Theta(n^2)$
- Assume Algo1 with  $\Theta(n^2)$  and Algo2 with  $\Theta(n^3)$ 
  - Algo1 is considered more efficient than Algo2
  - i.e., for a large enough n, Algo1 runs faster than Algo2

#### **Divide-and-Conquer**

- Many algorithms are recursive
  - they call themselves recursively one or more times to deal with subproblems
- Divide-and-conquer paradigm
  - divide the problem into a number of subproblems
  - conquer the subproblems by solving them recursively
  - combine the solutions to the subproblems into the solution to the original problem

#### Merge Sort

- Divide-and-conquer
  - divide: divide the n-element sequence into
     2 subsequences of n/2 elements each
  - conquer: sort the 2 subsequences recursively
  - combine: merge the 2 sorted subsequences to produce the answer

## MERGE(A, p, q, r) (1/2)

- MERGE(A, p, q, r)
  - given that A[p .. q] and A[q+1 .. r] are 2 sorted subarrays
  - MERGE(A, p, q, r) produce a sorted A[p .. r] subarray
- 1  $n_1 \leftarrow q p + 1$
- $2 \quad n_2 \leftarrow r q$
- create array L[1.. $n_1 + 1$ ] and R[1.. $n_2 + 1$ ]
- for  $i \leftarrow 1$  to  $n_1$
- **do** L[i]  $\leftarrow$ A[p+i-1]
- for  $j \leftarrow 1$  to  $n_2$
- **do** R[ i ]  $\leftarrow$  A[ q + j ]
- 8  $L[n_1 + 1] \leftarrow \infty$
- 9  $R[n_2+1] \leftarrow \infty$



sentinels

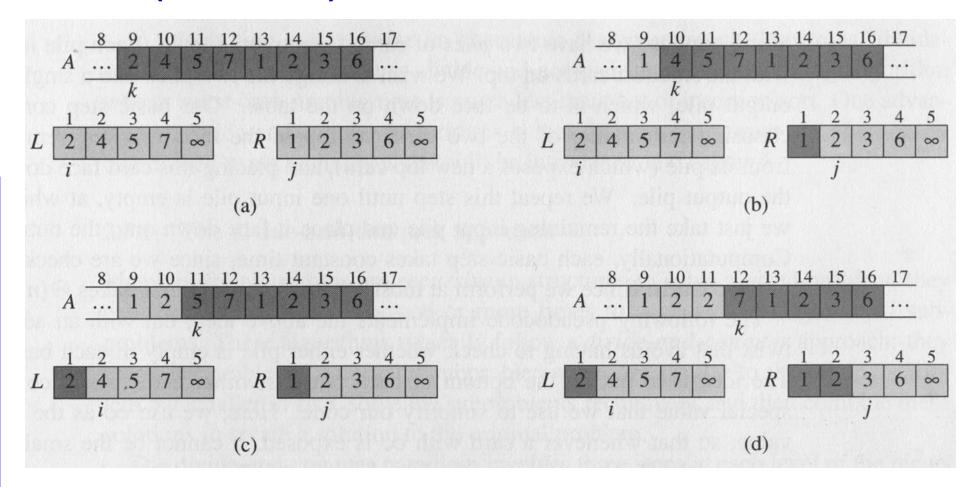
# idhuang@mail.nctu.edu.tw

## MERGE(A, p, q, r) (2/2)

```
10 i \leftarrow 1
                         Time: \Theta(n), n = number of elements
11 j \leftarrow 1
12 for k \leftarrow p to r
        do if L[i] \leq R[j]
13
                 then A[k] \leftarrow L[i]
14
15
            i \leftarrow i + 1
16
        else A[k] \leftarrow R[j]
17
           j \leftarrow j + 1
```

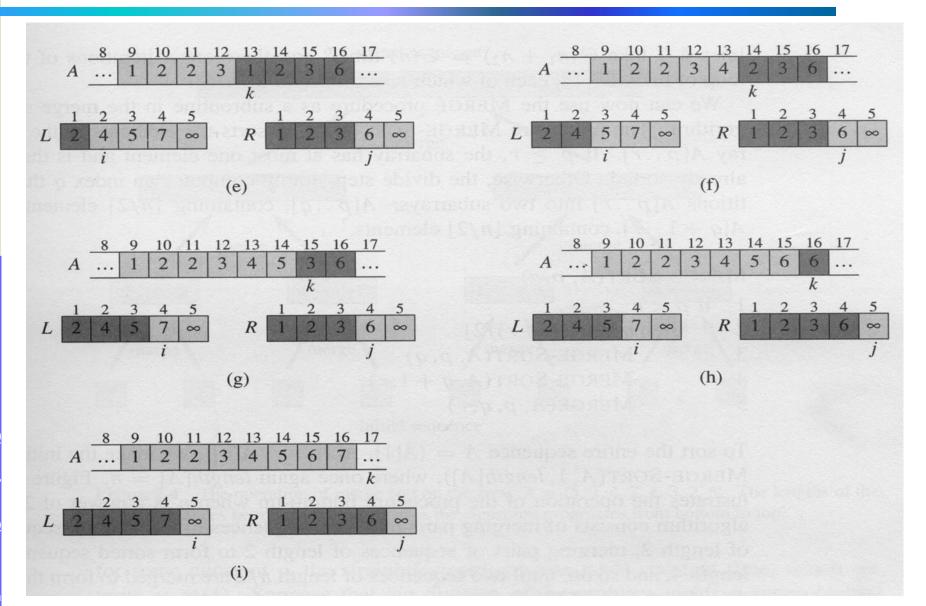
## Illustration of MERGE (1/2)

#### **MERGE(A, 9, 12, 16)**



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### Illustration of MERGE (2/2)

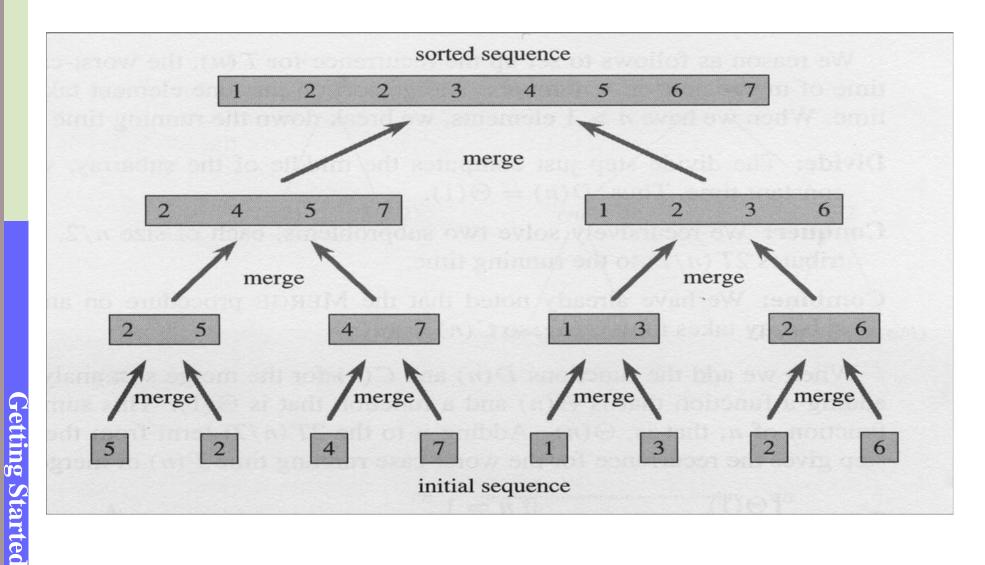


### Merge Sort

- MERGE-SORT(A, p, r)
  - sort the elements in A[p .. r]

```
1 \text{ if } p < r
       then q \leftarrow \lfloor (p+r)/2 \rfloor
              MERGE-SORT(A,p,q)
3
              MERGE-SORT(A,q+1,r)
              MERGE(A,p,q,r)
5
```

#### **Illustration of MERGE-SORT**



### **Analysis of Merge Sort (1/2)**

- The running time of a recursive algorithm can be expressed as a recurrence equation
  - discuss later in Chap 4
  - "master theorem" can be found in discrete math
- Analysis of merge sort

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1 \\ 2T(n/2) + \Theta(n) & \text{if } n > 1 \end{cases}$$

$$T(n) = \Theta(n \lg n)$$
 by the master theorem

Hence the merge sort is better than the insertion sort when n is large

## **Analysis of Merge Sort (2/2)**

