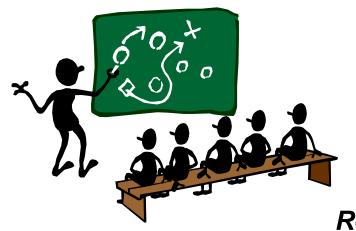
Algorithms – Chapter 7 Quick Sort



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Divide-and-Conquer Paradigm

- Like Merge Sort, Quick Sort is based on divideand-conquer paradigm
- Divide
 - partition the array A[p..r] into 2 (possibly empty)
 subarrays A[p..q-1] and A[q+1..r] such that
 - each element of $A[p..q-1] \le A[q]$ and each element of A[q+1..r] > A[q]
- Conquer
 - sort the 2 subarrays by Quick Sort recursively
- Combine
 - nothing to do here

Pseudo Code

QUICKSORT(A,p,r)

- 1 if p < r
- 2 then $q \leftarrow PARTITION(A, p, r)$
- 3 QUICKSORT(A, p, q-1)
- 4 QUICKSORT(A,q+1,r)

To sort an entire array A, use QUICKSORT(A, 1, length(A))

How to Partition

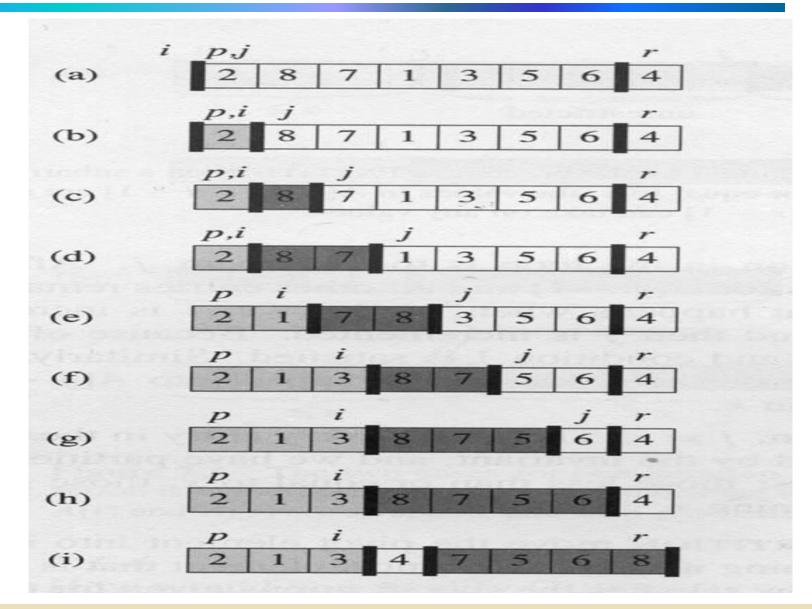
```
PARTITION(A, p, r)
```

```
1 x \leftarrow A[r]
```

* as a **pivot**

- $2 i \leftarrow p-1$
- 3 for $j \leftarrow p$ to r 1
- 4 **do if** $A[j] \leq x$
- 5 then $i \leftarrow i + 1$
- 6 exchange $A[i] \leftrightarrow A[j]$
- 7 exchange $A[i + 1] \leftrightarrow A[r]$
- 8 return i+1

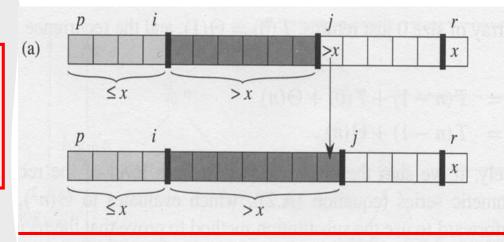
Example

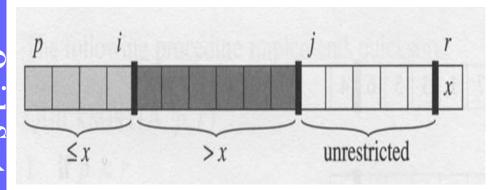


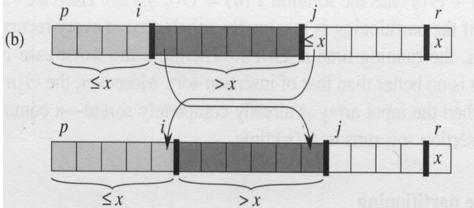
Loop Invariant

 At the beginning of each iteration of the loop of lines 3-6, for any array index k,

- 1. if $p \le k \le i$, then $A[k] \le x$.
- 2. if i + $1 \le k \le j 1$, then A[k] > x.
- 3. if k = r, then A[k] = x.







Time Complexity of Partition

PARTITION(A, p, r)

```
1 x \leftarrow A[r]
```

* as a **pivot**

$$2 i \leftarrow p-1$$

- 3 for $j \leftarrow p$ to r-1
- 4 **do if** $A[j] \le x$
- 5 then $i \leftarrow i + 1$
- 6 exchange $A[i] \leftrightarrow A[j]$
- 7 exchange $A[i + 1] \leftrightarrow A[r]$
- 8 return i+1

Time complexity: $\Theta(n)$, where n = r - p + 1

Worst Case of Quick Sort

- The runtime of Quick Sort depends on whether the partitioning is balanced or not
- Worst-case partitioning
 - partitioning produces one subarray with n-1 elements
 and the other subarray with 0 element

$$T(n) = T(n-1) + \Theta(n)$$

$$= \sum_{k=1}^{n} \Theta(k) = \Theta(\sum_{k=1}^{n} k) = \Theta(n^2)$$

Best Case of Quick Sort

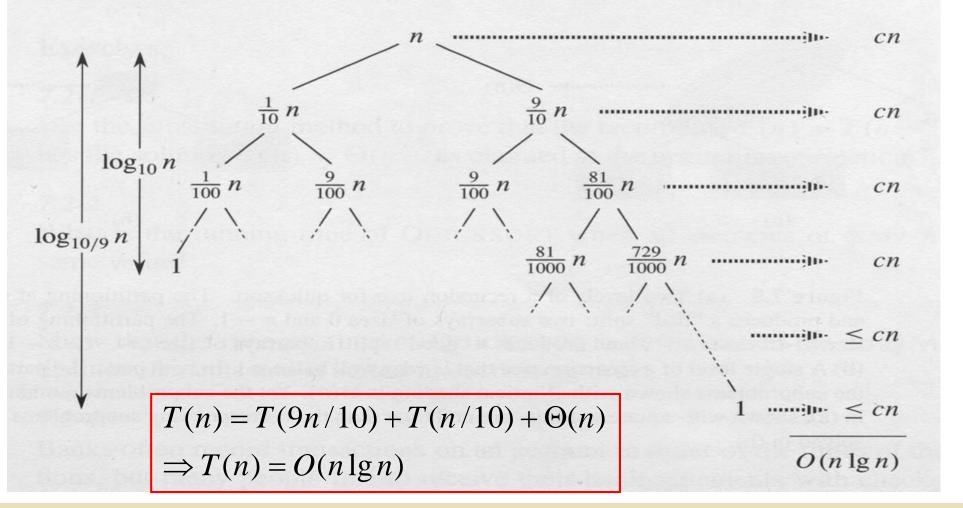
- Best-case partitioning
 - partitioning produces 2 subarrays, one is of size $\lfloor n/2 \rfloor$ and the other of size $\lceil n/2 \rceil 1$
 - perfect balance

$$T(n) = 2T(n/2) + \Theta(n)$$

 $\Rightarrow T(n) = \Theta(n \lg n)$

Not a Perfect Balance?

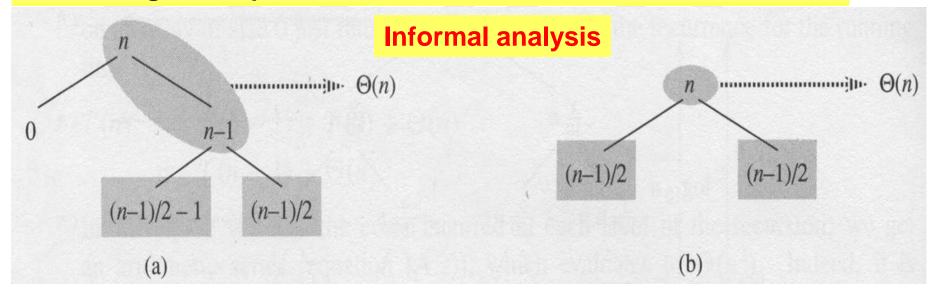
- With a 9-to-1 split
 - how about 99-to-1 split?



Average Case of Quick Sort

- Assume all permutations are equally likely
- It is expected
 - some partitioning are well balanced
 - some are fairly unbalanced

The average case performance is similar to that of the best case



Randomized Quick Sort

RANDOMIZED_PARTITION(A,p,r)

 $1 i \leftarrow RANDOM(p,r)$

random sampling

- 2 exchange $A[r] \leftrightarrow A[i]$
- 3 **return** PARTITION(A,p,r)

RANDOMIZED_QUICKSORT(A,p,r)

1 if p < r

- The split of the input array should be reasonably well balanced on average no matter what the initial input order is
- 2 then $q \leftarrow RANDOMIZED_PARTITION(A, p, r)$
- 3 RANDOMIZED_QUICKSORT(A, p, q 1)
- 4 RANDOMIZED_QUICKSORT(A, q + 1, r)

Precise Worst-Case Analysis

$$T(n) = \max_{0 \le q \le n-1} (T(q) + T(n-q-1)) + \Theta(n)$$

guess
$$T(n) \le cn^2$$

$$T(n) \le \max_{0 \le q \le n-1} (cq^2 + c(n-q-1)^2) + \Theta(n)$$

$$= c \max_{0 \le q \le n-1} (q^2 + (n-q-1)^2) + \Theta(n)$$

$$\le cn^2 - c(2n-1) + \Theta(n)$$

max value @ q = 0 or n-1

$$\leq cn^2$$

pick the constant c large enough so that the c(2n-1) term dominates the $\Theta(n)$ term.

$$\Rightarrow T(n) = \Theta(n^2)$$

Expected Runtime – Precise Analysis

- Each time PARTITON is called
 - a pivot element p is selected
 - p is never a pivot again for the future PARTITON calls
 - → at most n calls to PARTITION in QUICKSORT

Precise Analysis (1/5)

Lemma

Let X be the TOTAL number of comparisons performed in Line 4 of PARTITION over the entire execution of $Quick\ Sort$ on an n-element array. Then the runtime of $Quick\ Sort$ is O(n+X)

```
PARTITION(A, p, r)

1. x \leftarrow A[r]

2. i \leftarrow p - 1

3. for j \leftarrow p to r - 1 do

4. if A[j] \leq x

5. then i \leftarrow i + 1

6. exchange A[i] \leftrightarrow A[j]

7. exchange A[i+1] \leftrightarrow A[r]

8. return i+1
```

Precise Analysis (2/5)

- Assume A contains elements z₁, z₂, ..., z_n; with z_i being the i-th smallest element
- Define the set $Z_{ij} = \{z_i, z_{i+1}, ..., z_j\}$, i < j
- Fact
 - each pair of elements is compared at most once

Precise Analysis (3/5)

• Define $X_{ij} = I \{z_i \text{ is compared to } z_j\}$

$$X = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} X_{ij}$$

$$E[X] = E\left[\sum_{i=1}^{n-1} \sum_{j=i+1}^{n} X_{ij}\right]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E[X_{ij}]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \Pr\{z_i \text{ is compared to } z_j\}$$

Precise Analysis (4/5)

 z_i and z_j are compared iff the first element to be chosen as a pivot from Z_{ij} is either z_i or z_j

Pr{z_i is compared to z_j} = Pr{z_i or z_j is first pivot chosen from Z_{ij}} = Pr{z_i is first pivot chosen from Z_{ij}} + Pr{z_j is first pivot chosen from Z_{ij}} = $\frac{1}{j-i+1} + \frac{1}{j-i+1}$ = $\frac{2}{j-i+1}$ hard to understand!

$$\therefore E[X] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \frac{2}{j-i+1}$$

Precise Analysis (5/5)

$$E[X] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \frac{2}{j-i+1}$$

$$= \sum_{i=1}^{n-1} \sum_{k=1}^{n-i} \frac{2}{k+1}$$

$$< \sum_{i=1}^{n-1} \sum_{k=1}^{n} \frac{2}{k}$$

$$= \sum_{i=1}^{n-1} O(\lg n)$$

$$= O(n \lg n)$$

$$(k = j-i)$$

$$\sum_{k=1}^{n} \frac{1}{k} = \ln n + O(1)$$

For RANDOMIZED-PARTITION, the expected runtime of Quick Sort is O(nlgn)

Further Topics

- Problem 7-1 (p185)
 - the original version of Quick Sort
- Problem 7-4 (p188)
 - consider about the stack
- Problem 7-5 (p188)
 - median-of-3 partition
 - a way to improve RANDOMIZED-QUICKSORT

Quick Sort

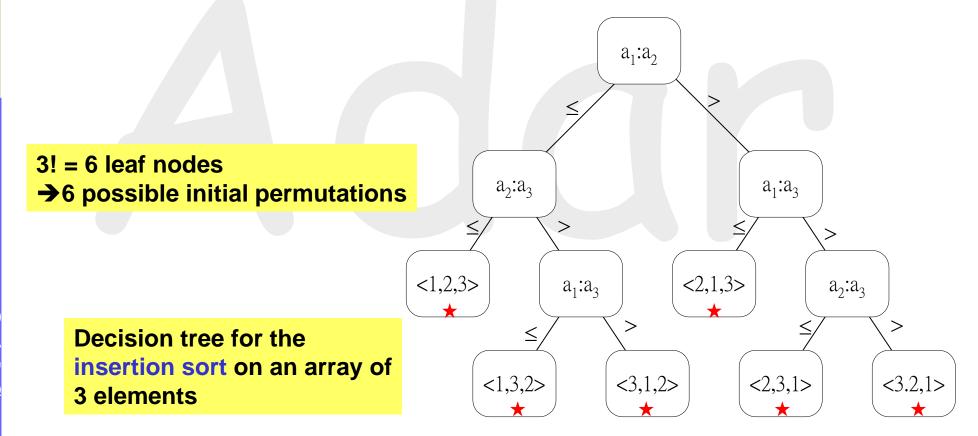
Comparison Sorts

- Comparison sorts
 - the sorted order they determined is based only on comparisons between the input elements
 - e.g., merge/heap/quick/insertion/bubble/shell sort
- Heap Sort and Merge Sort achieve O(nlgn) in the worst case

 Is it possible to find algorithms with even lower time complexity?

Decision Trees

- The number of comparisons in the worst case
 - the length of the longest path from the root of a decision tree to any of its reachable leaves



Lower Bound for the Worst Case

A decision tree of height h with I leaves

→
$$n! = I \le 2^h$$

$$\rightarrow$$
 h \geq lg(n!) = Ω (nlgn)

- Theorem
 - any comparison sort algorithm requires $\Omega(\text{nlgn})$ comparisons in the worst case
- Heap Sort and Merge Sort are asymptotically optimal comparison sorts