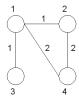
CS360 Assignment 8

23.1-2 Let G(V, E) be a connected, undirected graph with real valued weights w(u, v). Let A be a subset of E that is included in some MST for G, (S, V - S) be any cut of G that respects A, and (u, v) be a safe edge for A that crosses (S, V - S). Show that (u, v) is not necessarily a light edge. (Note: this is showing that the converse of Theorem 23.1 is not true.)

Consider the following graph:



Clearly an MST for this graph is:



If we let $S = \{1\}$ and $A = \emptyset$, then the cut $\{1\}, \{2,3,4\}$ trivially respects A. Furthermore, all three edges (1,2), (1,3), (1,4) are safe edges (since they are in the MST). However edge (1,4) is **not** a light edge and hence the converse of Theorem 23.1 is not true, i.e. light edge \Rightarrow safe edge, but safe edge \Rightarrow light edge).

23.2-4 Suppose all edge weights are integers in the range $1 \to |V|$. How fast can Kruskal's algorithm be made to run? What if the weights are integers in the range $1 \to W$ for a constant W?

The running time for a general implementation of Kruskal's algorithm consists of:

$$O(V)$$
 - Initialization $O(E \lg E)$ - Edge sorting + $O(E\alpha(V))$ - Edge processing $O(E \lg E)$

Knowing the range of the weights allows for the use of *counting sort* to improve the time for the sorting step - which is the dominant term in the general implementation. If the weights are in the range $1 \to |V|$, sorting of the edges using counting sort becomes O(n + k) = O(E + V). For connected graphs

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V=O(E) giving a sort time of O(E). Hence the total running time becomes $O(V)+O(E)+O(E\alpha(V))=O(E)+O(E)+O(E)+O(E\alpha(V))=O(E\alpha(V))$ If the weights are in the range $1\to W$ (where W is a constant), then sorting becomes O(n+k)=O(E+W)=O(E) (same as above) which again gives a running time of $O(E\alpha(V))$.

23.2-5 Suppose all edge weights are integers in the range $1 \to |V|$. How fast can Prim's algorithm be made to run? What if the weights are integers in the range $1 \to W$ for a constant W?

The running time for a general implementation of Prim's algorithm (assuming a Fibonacci heap implementation) consists of:

$$\begin{array}{c|cccc} & VO(\lg V) & - \text{ Extract-min for each vertex} \\ + & EO(1) & - \text{ Decrease key for each edge} \\ \hline & O(V\lg V+E) \end{array}$$

Implementing the queue as an array of linked-lists with one element per weight value changes the running time of Extract-min() which now consists of scanning the array for the first non-empty list element. (Note: Decrease-key() remains O(1) since it simply involves moving the element from one list to another.) If the weights range from $1 \to |V|$ then Extract-min() becomes O(V) per scan giving a total time $O(V(V) + E) = O(V^2)$ which is worse than using a heap!

However if the weights range from $1 \to W$ (where W is a constant), then Extract-min() becomes O(1) per scan giving a total time of O(V(1) + E) = O(V + E) = O(E) (for a connected graph) which turns out to be the best we can do.

24.1-1 Run the Bellman-Ford algorithm on the directed graph of Fig 24.4 using the vertex z as the source, relaxing edges in the same order as in the figure, giving the d and π values after each pass. Change the weight of edge (z, x) = 4 and rerun the algorithm with s as the source.

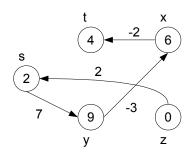
Considering edges in the order (t, x), (t, y), (t, z), (x, t), (y, x), (y, z), (z, x), (z, s), (s, t), (s, y) gives the following table:

			d					π		
pass	s	t	x	y	z	s	t	x	y	z
0	∞	∞	∞	∞	0	/	/	/	/	/
1	2	8	7	9	0	z	s	z	s	/
2	2	5	6	9	0	z	x	y	s	/
3	2	4	6	9	0	z	x	y	s	/
4	2	4	6	9	0	z	x	y	s	/

Checking edges

$$\begin{split} d[x] &= 6 &< d[t] = 4 + 5 \\ d[y] &= 9 &< d[t] = 4 + 8 \\ d[z] &= 0 &= d[t] = 4 - 4 * \\ d[t] &= 4 &= d[x] = 6 - 2 * \\ d[x] &= 6 &= d[y] = 9 - 3 * \\ d[z] &= 0 &< d[y] = 9 + 9 \\ d[x] &= 6 &< d[z] = 0 + 7 \\ d[s] &= 2 &= d[z] = 0 + 2 * \\ d[t] &= 4 &< d[s] = 2 + 6 \\ d[y] &= 9 &= d[s] = 2 + 7 * \end{split}$$

All edges are OK so routine returns TRUE. Note: All * edges (equalities) are ones that appear in the final graph shown below.



Setting edge (z, x) = 4 and rerunning the algorithm gives:

	d						π							
pass	s	t	x	y	z		s	t	\boldsymbol{x}	y	z			
0	0	∞	∞	∞	∞		/	/	/	/	/			
1	0	6	∞	7	∞		/	s	/	s	/			
2	0	6	(11)4	7	2		/	s	(t)y	s	/			
3	0	2	4	7	2		/	\boldsymbol{x}	y	s	t			
4	0	2	2	7	-2		/	\boldsymbol{x}	z	s	t			

Checking edges

$$\begin{split} d[x] &= 2 &< d[t] = 2 + 5 \\ d[y] &= 7 &< d[t] = 2 + 8 \\ d[z] &= -2 &= d[t] = 2 - 4 * \\ d[t] &= 2 &> d[x] = 2 - 2X \end{split}$$

Check fails so routine returns FALSE. Note: $\langle x, t, z \rangle$ is a negative weight cycle.

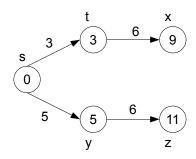
24.3-1 Run Dijkstra's algorithm on the directed graph of Figure 24.2 first using vertex s then vertex z as source. Show the d and π values and the vertices in S after each iteration.

Using vertex s

Q	S	d					π				
		s	t	x	y	z	s	t	x	y	z
< s, t, x, y, z>	Ø	0	∞	∞	∞	∞	/	/	/	/	/
< t, y, x, z >	< s >	0	3	∞	5	∞	/	s	/	s	/
$\langle y, x, z \rangle$	$\langle s, t \rangle$	0	3	9	5	∞	/	s	t	s	/
$\langle x, z \rangle$	$\langle s, t, y \rangle$	0	3	9	5	11	/	s	t	s	y
< z >	$\langle s, t, y, x \rangle$	0	3	9	5	11	/	s	t	s	y
Ø	< s, t, y, x, z>	0	3	9	5	11	/	s	t	s	y

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Giving the following graph:



Using vertex z

Q	S	d			π						
		s	t	x	y	z	s	t	x	y	z
$< z, s, t, x, y > $	Ø	∞	∞	∞	∞	0	/	/	/	/	
$\langle s, x, t, y \rangle$	< z >	3	∞	7	∞	0	z	/	z	/	
< t, x, y >	< z, s >	3	6	7	8	0	z	s	z	s	
$\langle x, y \rangle$	$\langle z, s, t \rangle$	3	6	7	8	0	z	s	z	s	
< y >	$\langle z, s, t, x \rangle$	3	6	7	8	0	z	s	z	s	/
Ø	$\langle z, s, t, x, y \rangle$	3	6	7	8	0	z	s	z	s	

Giving the following graph:

