ECE260: Fundamentals of Computer Engineering

Datapath for a Simplified Processor

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Introduction

- What we've done so far:
 - Examined CPU performance factors
 - Instruction count, clock rate, and cycle per instruction (CPI)
 - Examined the instruction set for MIPS and how high-level languages are compiled into machine code
 - Examined how computers do arithmetic
- Now, we'll look inside the processor to see how it's implemented
 - Start by looking at a simplified MIPS processor
 - Includes only a basic subset of instructions (lw, sw, add, sub, and, or, slt, beq, j)
 - Later, we'll look at a more realistic MIPS processor
 - Includes more instructions and a *pipeline*

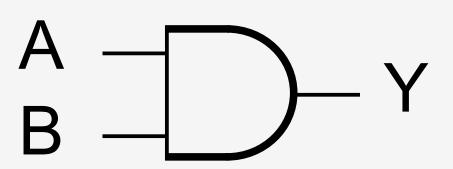
Logic Design Basics

- All information is encoded in binary
 - Low voltage = 0, High voltage = 1
 - One wire per bit
 - Multi-bit data encoded on multi-wire buses (e.g. 32-bit values travel on 32-bit buses)
- Two different types of logic elements in hardware designs
 - Combinational elements (a.k.a. combinational logic)
 - Operate on data values
 - Output is a function of input (same input always produces same output)
 - State elements (a.k.a. sequential logic)
 - Store information (e.g. registers and data memory)
 - Can be written/updated to update state

Combinational Elements

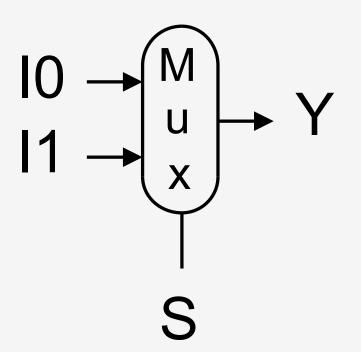
AND Gate

$$Y = A \& B$$



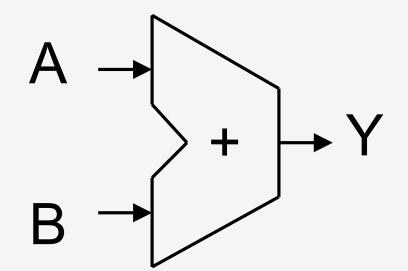
<u>Multiplexer</u>

$$Y = S ? I1 : I0$$



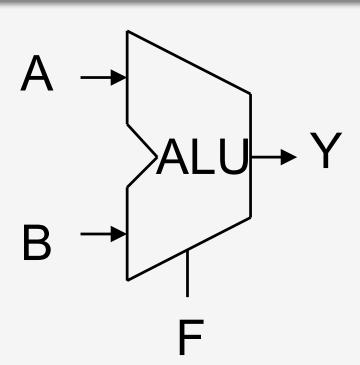
<u>Adder</u>

$$Y = A + B$$



Arithmetic Logic Unit

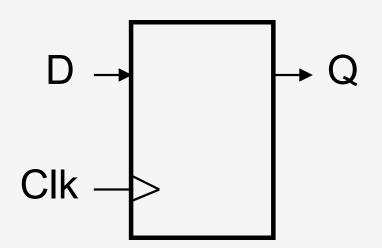
$$Y = F(A, B)$$



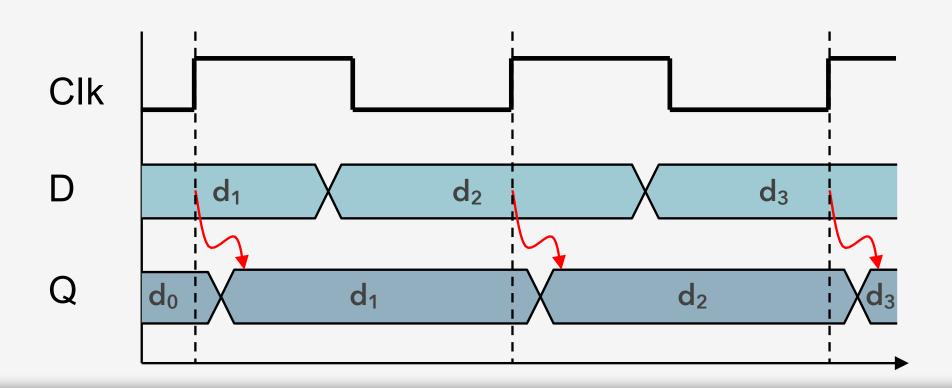
Sequential Elements (State Elements)

- A register stores data in a circuit (i.e. it maintains the state of a computation)
 - Uses a clock signal to determine when to update the stored value
 - An **edge-triggered** register updates its contents on a <u>clock edge</u>
 - Positive edge-triggered registers update when the clock changes from 0 to 1
 - Negative edge-triggered registers update when the clock changes from 1 to 0

A basic storage element, a positive edge-triggered D-type flip-flop; it can store a *single bit* of data Inputs are D and Clk; Output is Q



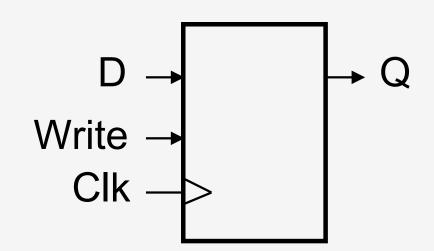
Shortly after a positive clock edge, the input D is stored in the flip-flop and it becomes visible on the output Q.



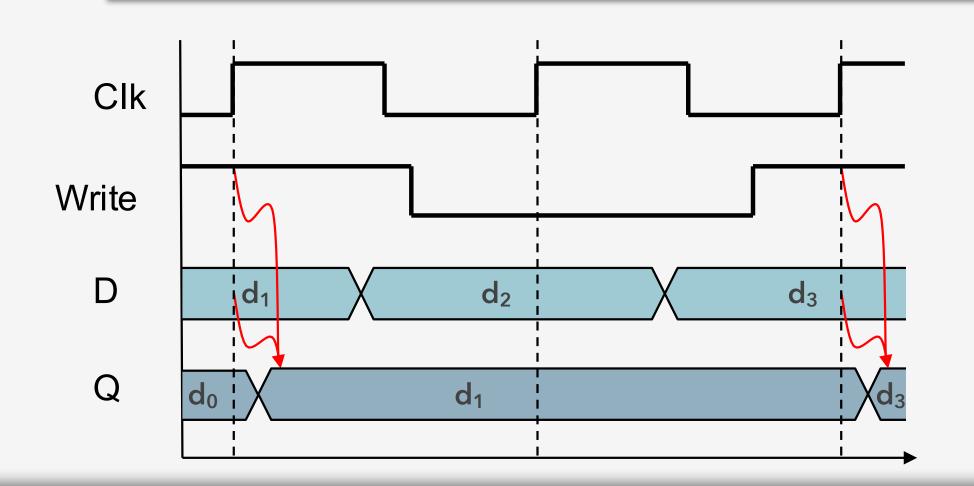
Sequential Elements with More Control

- The clock signal is ALWAYS ticking and may not always want to store new data in a register
- A register with write control allows data to be stored only when directed
 - Only updates register contents on clock edge AND when a write enable input is 1
 - Typically used when a stored value is still required

A positive edge-triggered D-type flip-flop with write enable input

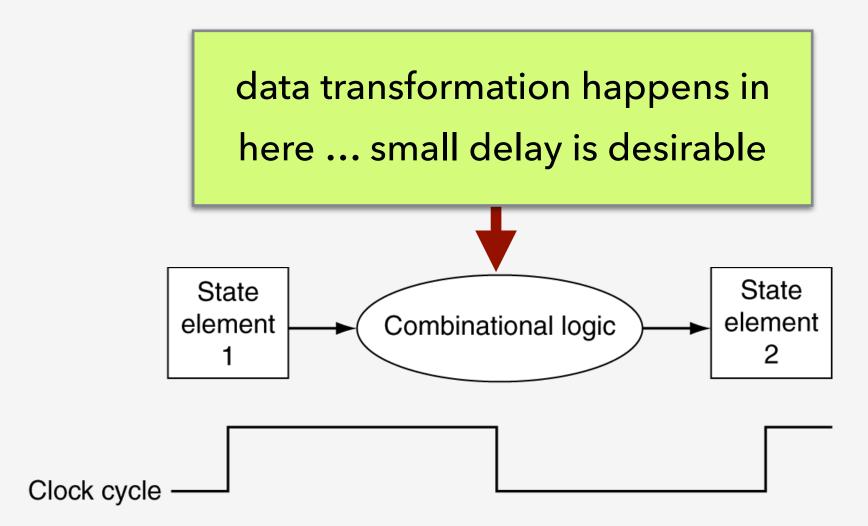


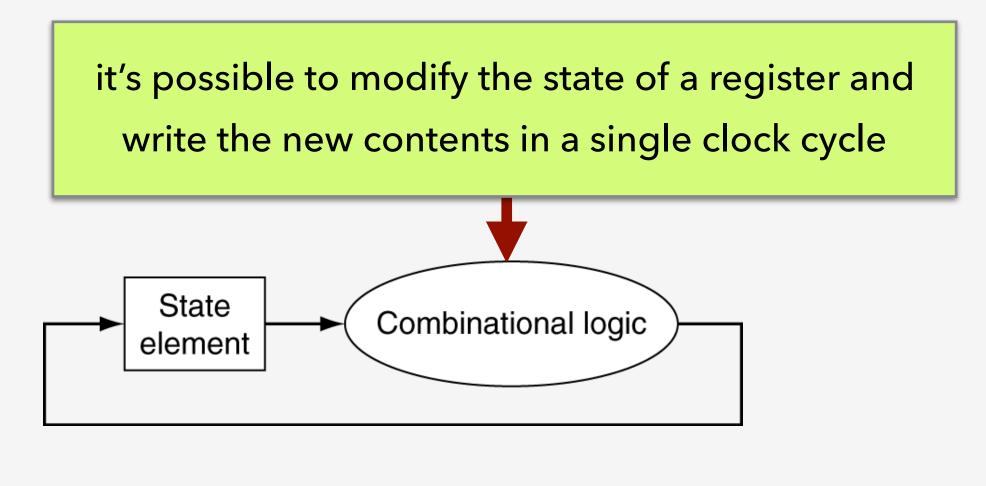
Shortly after a positive clock edge, the input D is stored in the flip-flop IF the write enable was asserted at the clock edge



Clocking Methodology

- Combinational logic transforms data during clock cycles
 - Between clock edges
 - Receives input data from state elements, sends new output to state elements
 - Combinational logic introduces delay (takes some time for data to pass through an AND gate!)
 - Total delay through combinational logic is sum of delay through all elements (and wire) on path
 - Longest combination logic delay determines clock period for entire processor!!

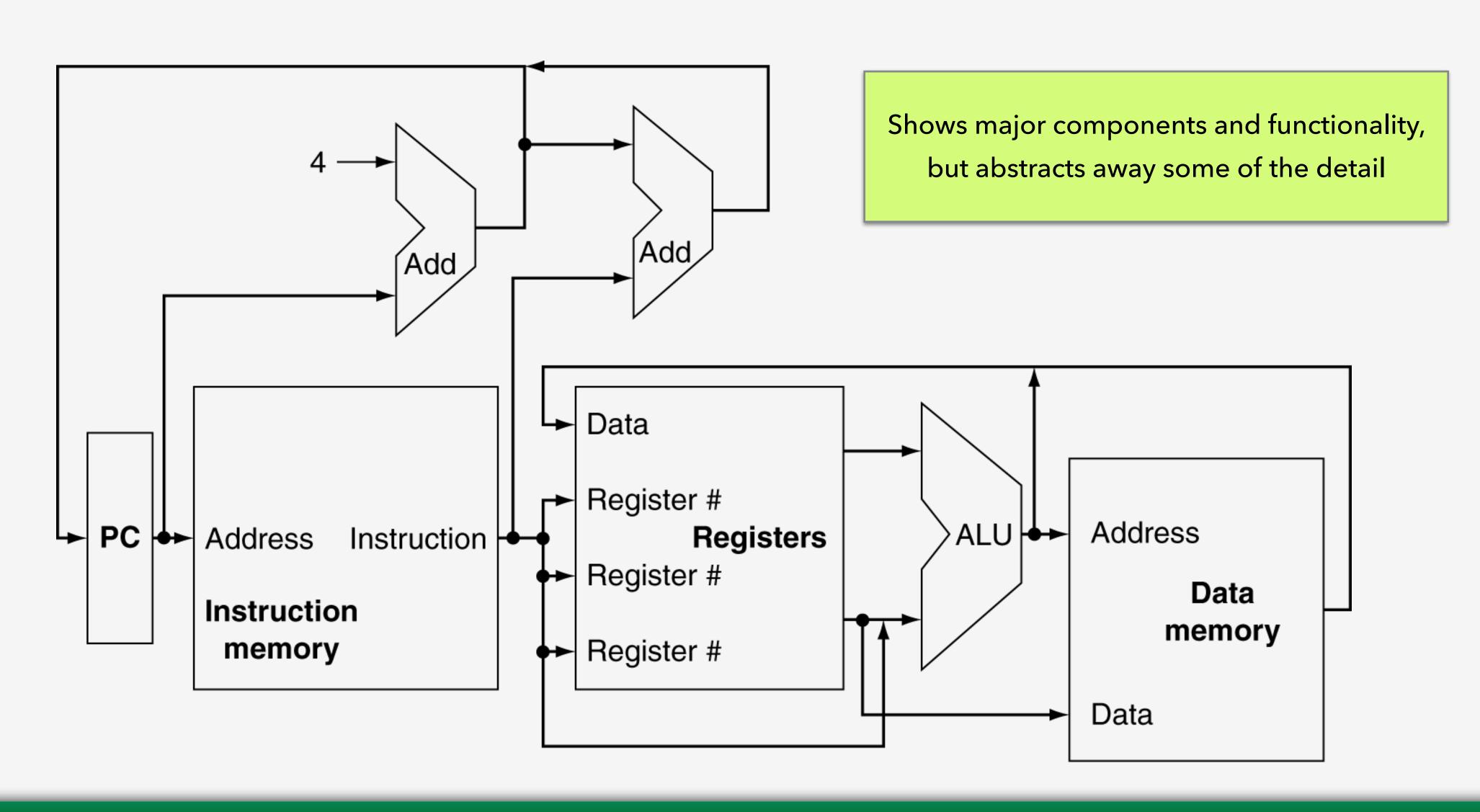




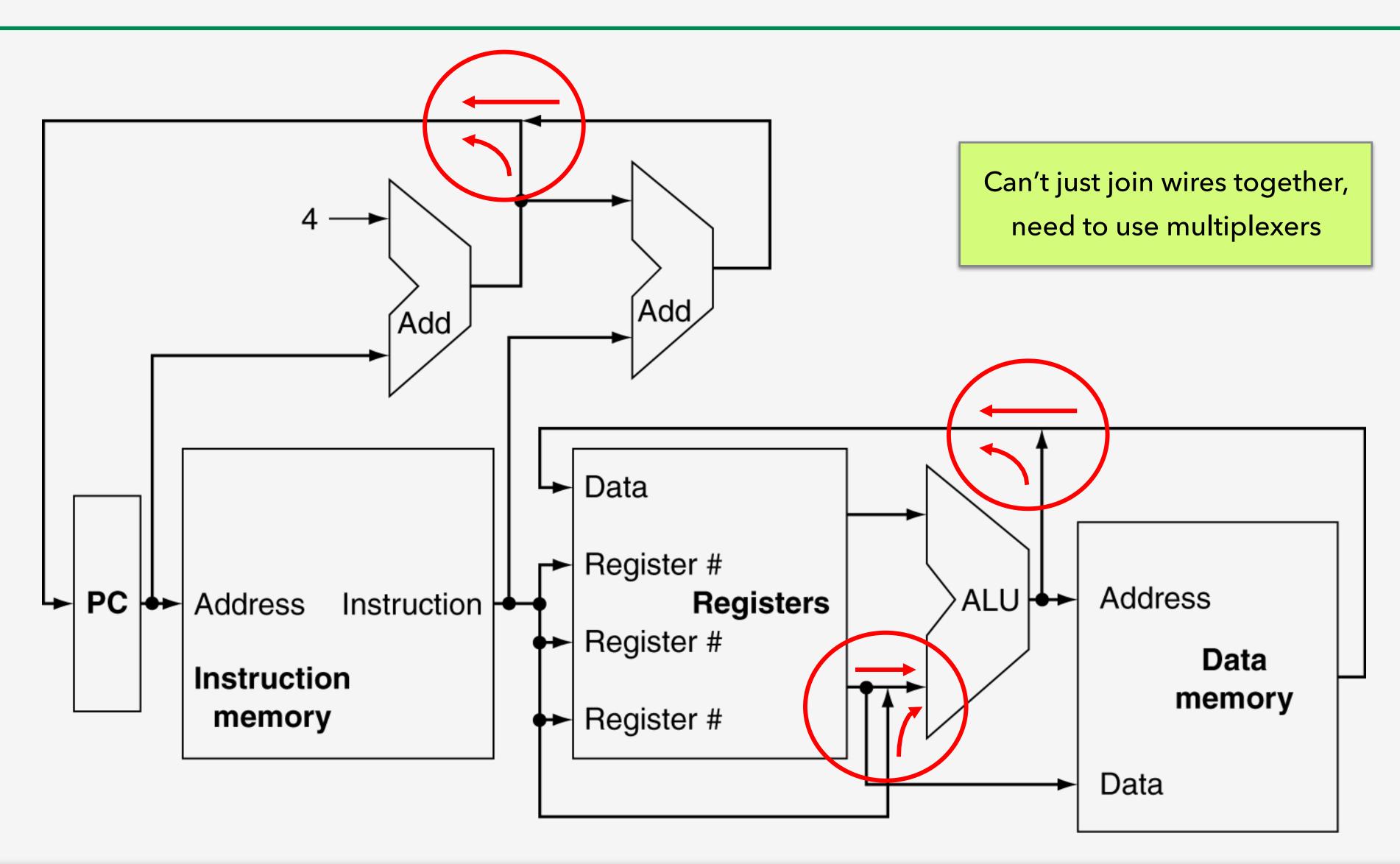
Executing Instructions on a Processor

- For all instructions, the first two steps are the same:
 - Use the Program Counter (PC) to access program memory and fetch an instruction
 - Read the source registers (one or two) to be used for the instruction encoded into instruction
- Depending on instruction class ...
 - Use the ALU to compute one of the following:
 - An arithmetic result (e.g. add, sub)
 - A memory address for a load/store (e.g. lw, sw)
 - A branch target address (e.g. beq)
 - Access data memory for load/store (only done for load/store instruction)
 - Update the PC
 - PC = PC + 4 OR PC = some branch target address

CPU Overview

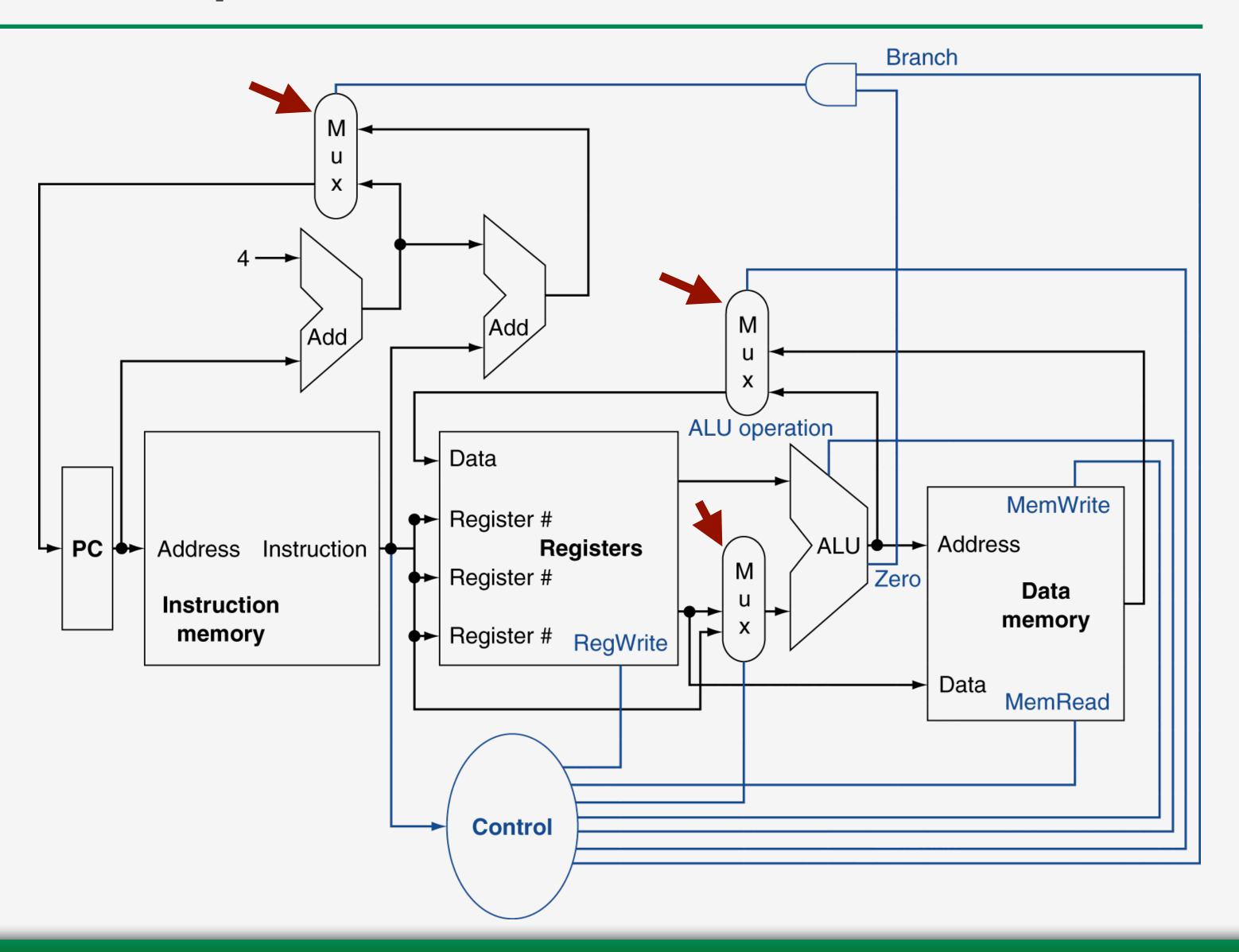


CPU Overview (continued)



CPU Overview with Multiplexers and Control

- Multiplexers use a control line to select an output from multiple different inputs
 - Three multiplexers added for this simplified version of MIPS
- Control uses information from the instruction word to assert/deassert various control lines
 - Steers data though muxes
 - Write enables for registers
 - Read/Write enable for memory
 - Specify ALU operation

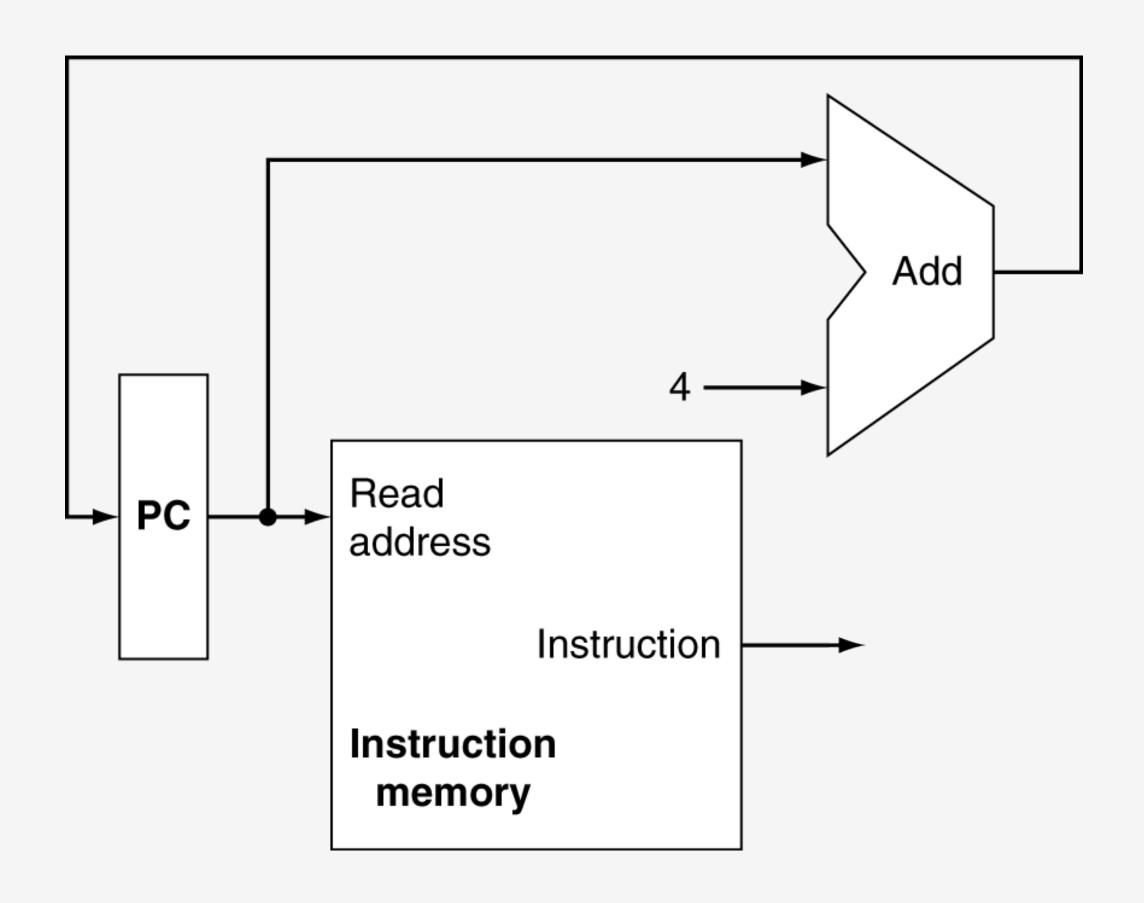


Building a Datapath

- Datapath element is a unit used to operate on or store data within a processor
 - Processor datapath is made up of multiple datapath elements
 - Registers, ALUs, multiplexers, memories, etc.
- We will incrementally build a datapath for a simplified MIPS processor
 - Examine how each datapath element is used
 - Examine which datapath elements are used for which instructions

Beginning of Datapath – Instruction Fetch

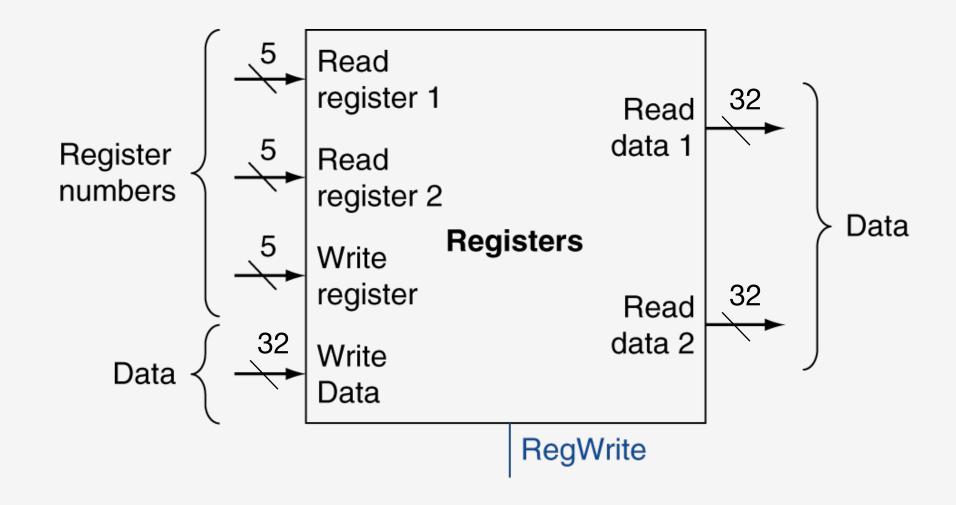
- Recall first step for all instructions:
 - Use the Program Counter (PC) to access program memory and fetch an instruction
 - Need a Program Counter (PC)
 - 32-bit register
 - Points to program memory
 - Need a memory
 - Stores program
 - Need an ALU (or simple adder) to increment the PC
 - Increments PC by 4 to point to next instruction

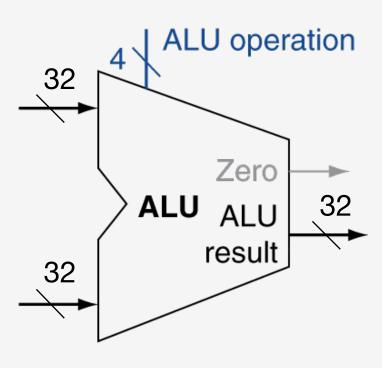


Supporting the R-Type Instruction Format

- For R-Type instructions, read two source registers, perform an ALU operation, and write the result to destination register
 - Need a collection of registers, called a *register file*
 - Need an ALU to perform arithmetic ops
 - A control signal specifies operation the to perform

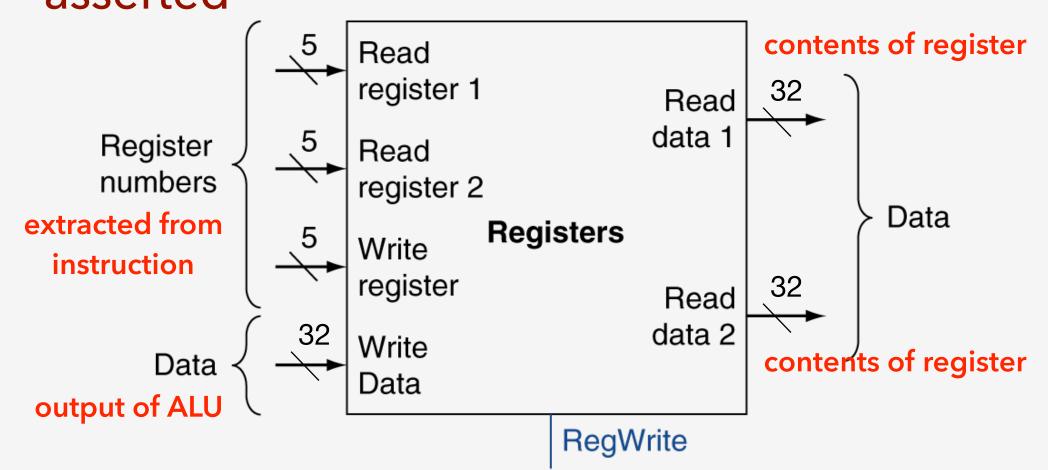
Example Instruction: add \$t0, \$t1, \$t2



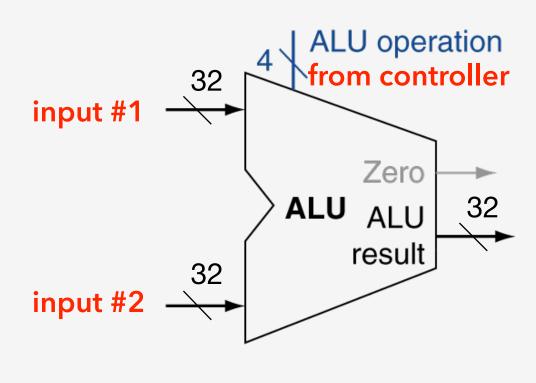


Supporting the R-Type Instruction Format (continued)

- Register File in detail:
 - Two 5-bit inputs specify source registers
 - Values stored in the specified source registers are output on "Read data 1/2"
 - One 5-bit input specifies destination register
 - Input "Write Data" is stored in "Write register" when write enable (RegWrite) is asserted



- ALU in detail:
 - Has two 32-bit inputs, one for each source operand
 - Has a single 32-bit output for the result of the arithmetic operation
 - A control signal specifies the ALU operation to perform
 - "Zero" output is asserted anytime a result is 0



Supporting Load/Store Instructions

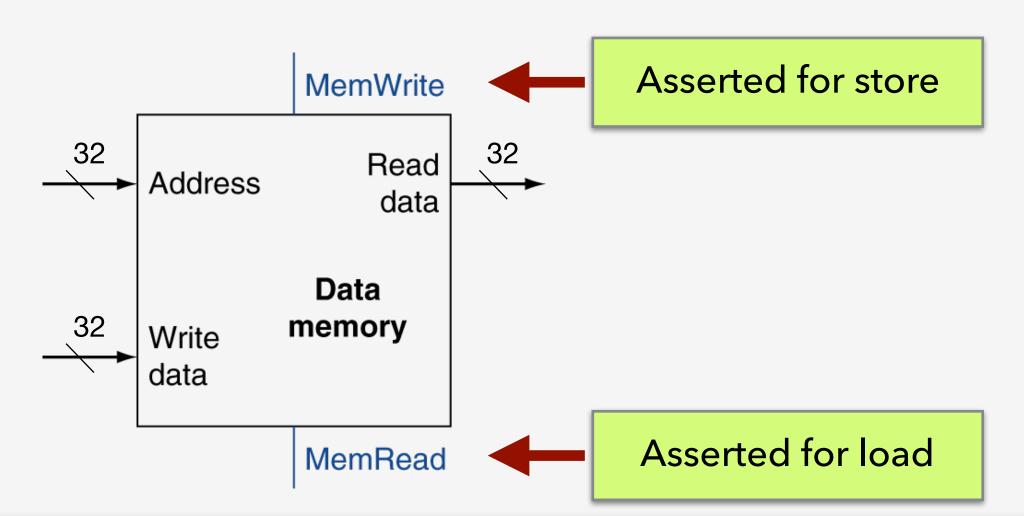
- Need a memory to write/read data to/from
- Must read register operands (two registers for a store, only one register for a load)
 - One register contains the base memory address to read/write
 - In case of store instruction, second register contains data to be written to memory
 - In case of load instruction, second register is destination for data read from memory
- Must calculate effective address using the 16-bit offset embedded in the instruction word
 - First, sign-extend the 16-bit offset (will need a sign-extension unit!)
 - Next, use the ALU to add the offset to the register containing the base address

Example Load Instruction: lw \$t0, 4(\$t1)

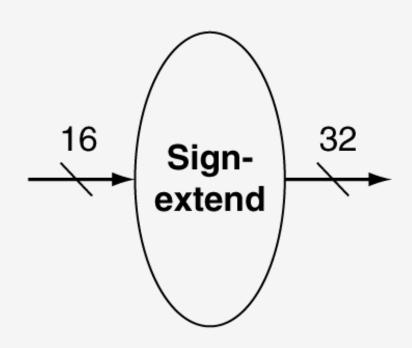
Example Store Instruction: sw \$s5, 16(\$s1)

Supporting Load/Store Instructions

- Data memory in detail:
 - Address input specifies the address that should be read/written
 - "Write data" input has data to be written during a store instruction
 - Ignored during a load instruction
 - "Read data" output has data read during load



- Sign-extension unit in detail:
 - Single 16-bit input
 - Single 32-bit output
 - Simply duplicates MSB of input (bit 15) into bits 31 downto 16 of output



Supporting Branch Instructions (only beq for now)

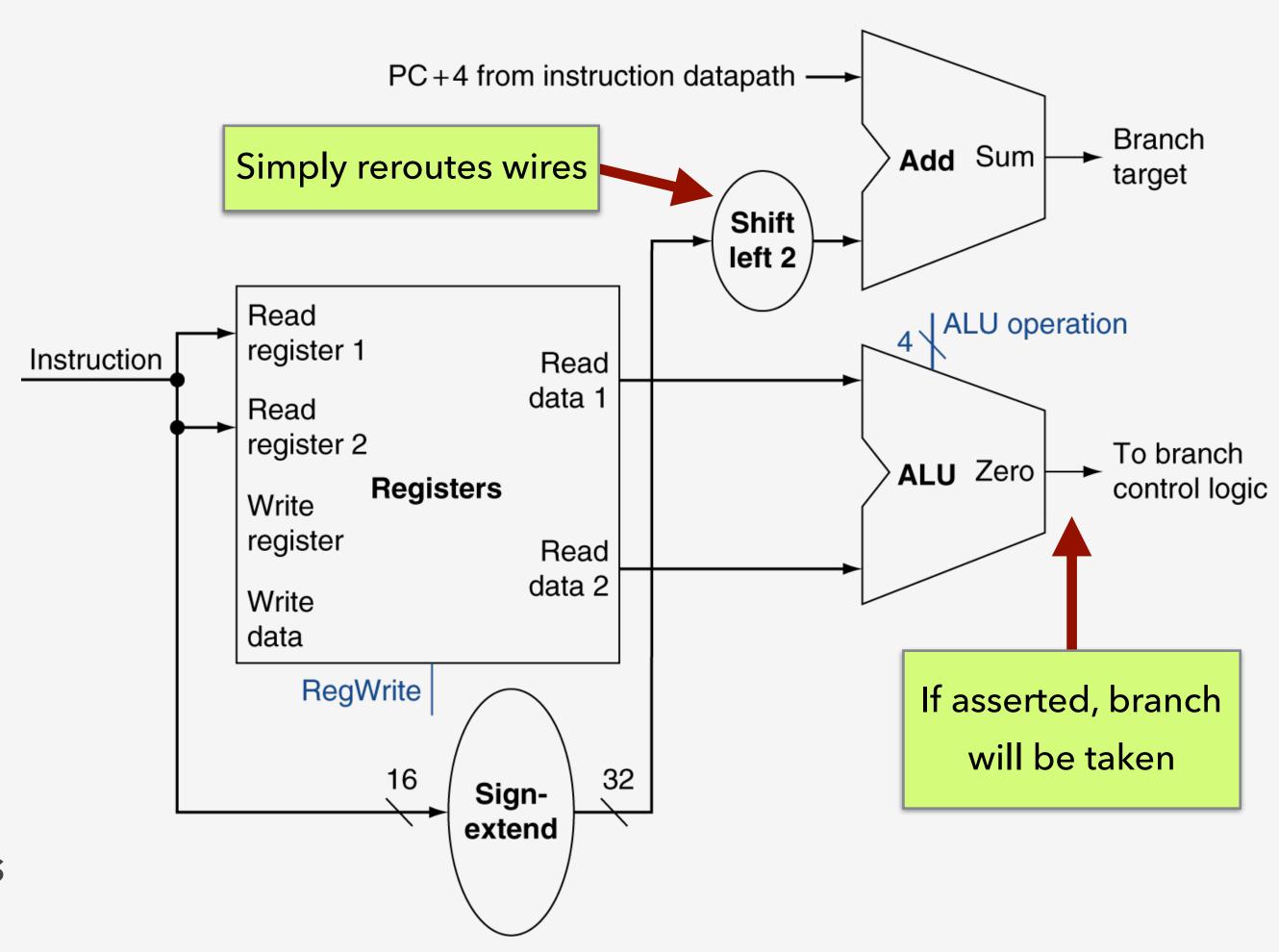
Compares two source registers

```
Example Instruction: beq $t1, $t2, offset
```

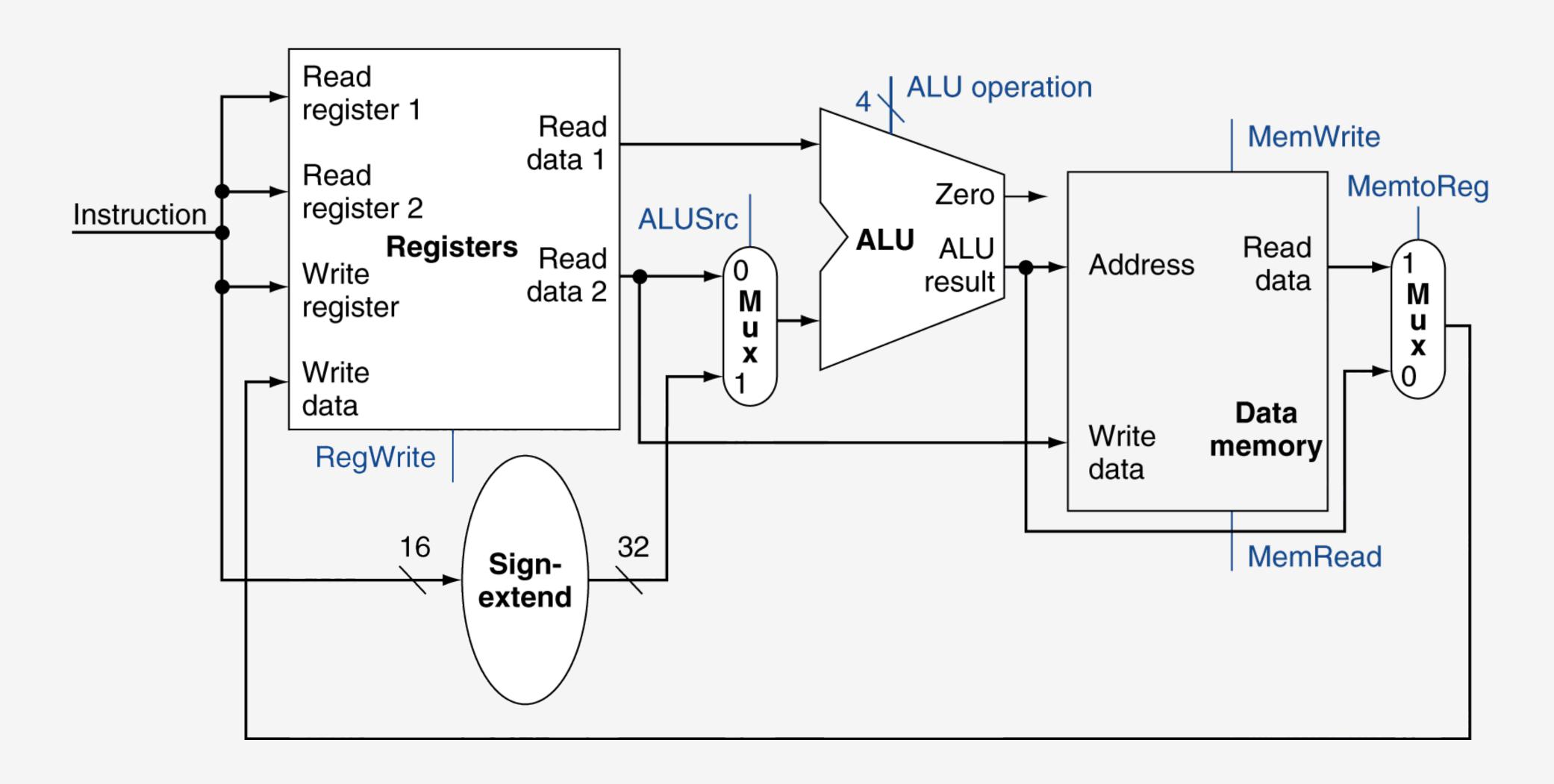
Instruction word contains 16-bit offset

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BranchAddr =
   { 14{immediate[15]}, immediate, 2'b0 }
PC = PC + 4 + BranchAddr
```

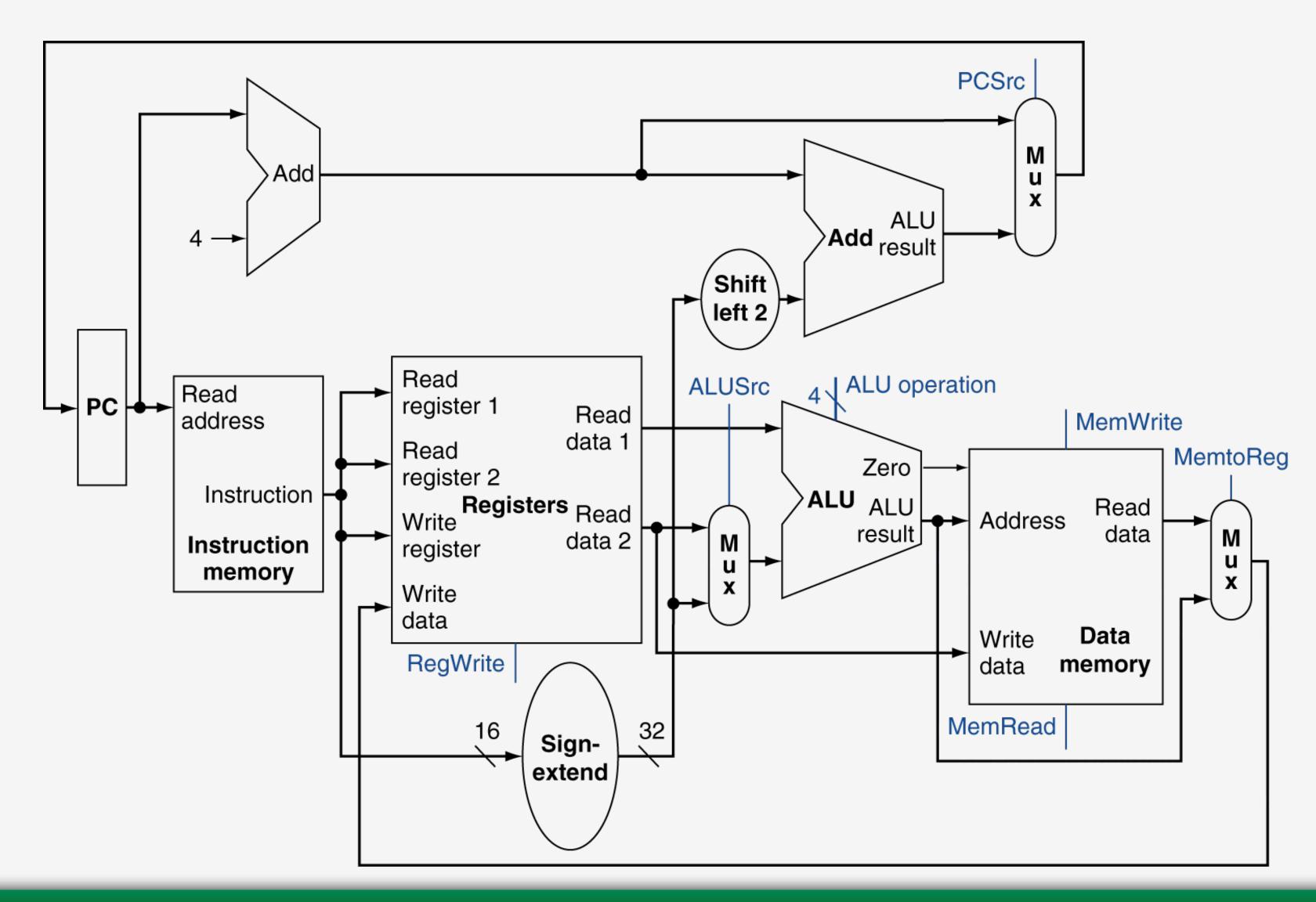
- ALU is used to determine if inputs are equal
 - Subtract sourceReg1 from sourceReg2
 If result is 0, regs are equal, take branch
 Otherwise, PC = PC + 4
- An Adder computes "Branch Target" address if case branch is taken



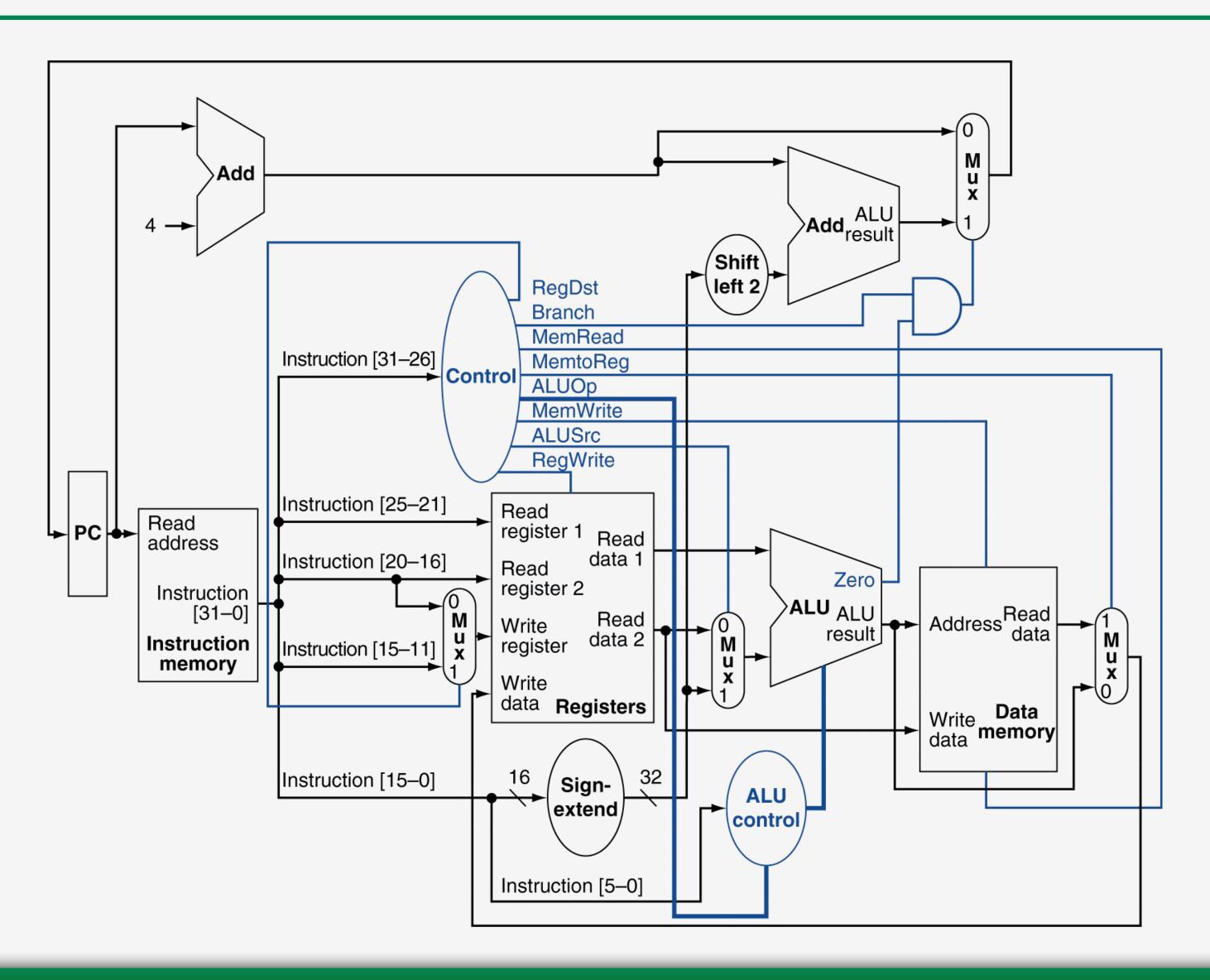
Putting it all together: R-Type/Load/Store Datapath



Complete Datapath for Simplified MIPS Processor



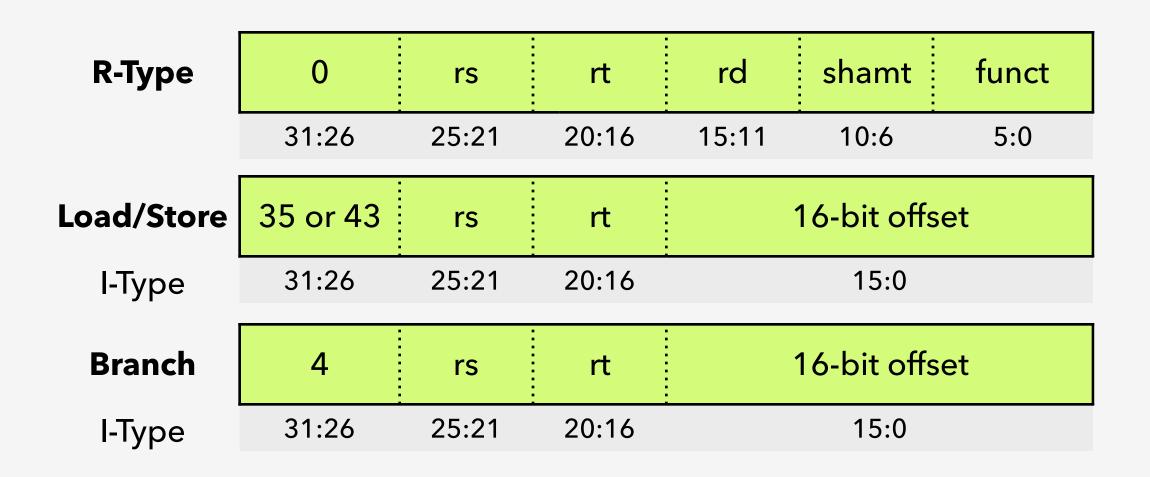
Complete Datapath With Control



The Main Control Unit

- Input is 6-bit opcode from 32-bit instruction
 - Control signals are all derived from the instruction
- Output includes many control signals
 - Control signals for various muxes
 - ALUOp for controlling various muxes and the ALU control unit
 - Read/Write signal to data memory
 - Write signal to register file
 - Branch instruction signal

- Bits 31:26 => opcode
- Bits 25:21 => source reg for all three ops
- Bits 20:16 => dest reg for load, source reg for store, branch, and R-type
- Bits 15:11 => dest reg for R-type
- Bits 15:0 => sign extend and add for branch and load/store



Controlling the ALU

ALU needs to perform different operations depending on the instruction

• For load/store instructions: ALU performs add

• For branch instructions: ALU performs subtract

• For R-type instructions: ALU performs operation specified in funct field (AND, OR, add, sub, ...)

- 4-bit "ALU Operation" input to ALU tells ALU what operation to perform
 - Need an ALU control unit to generate the 4-bit input to the ALU

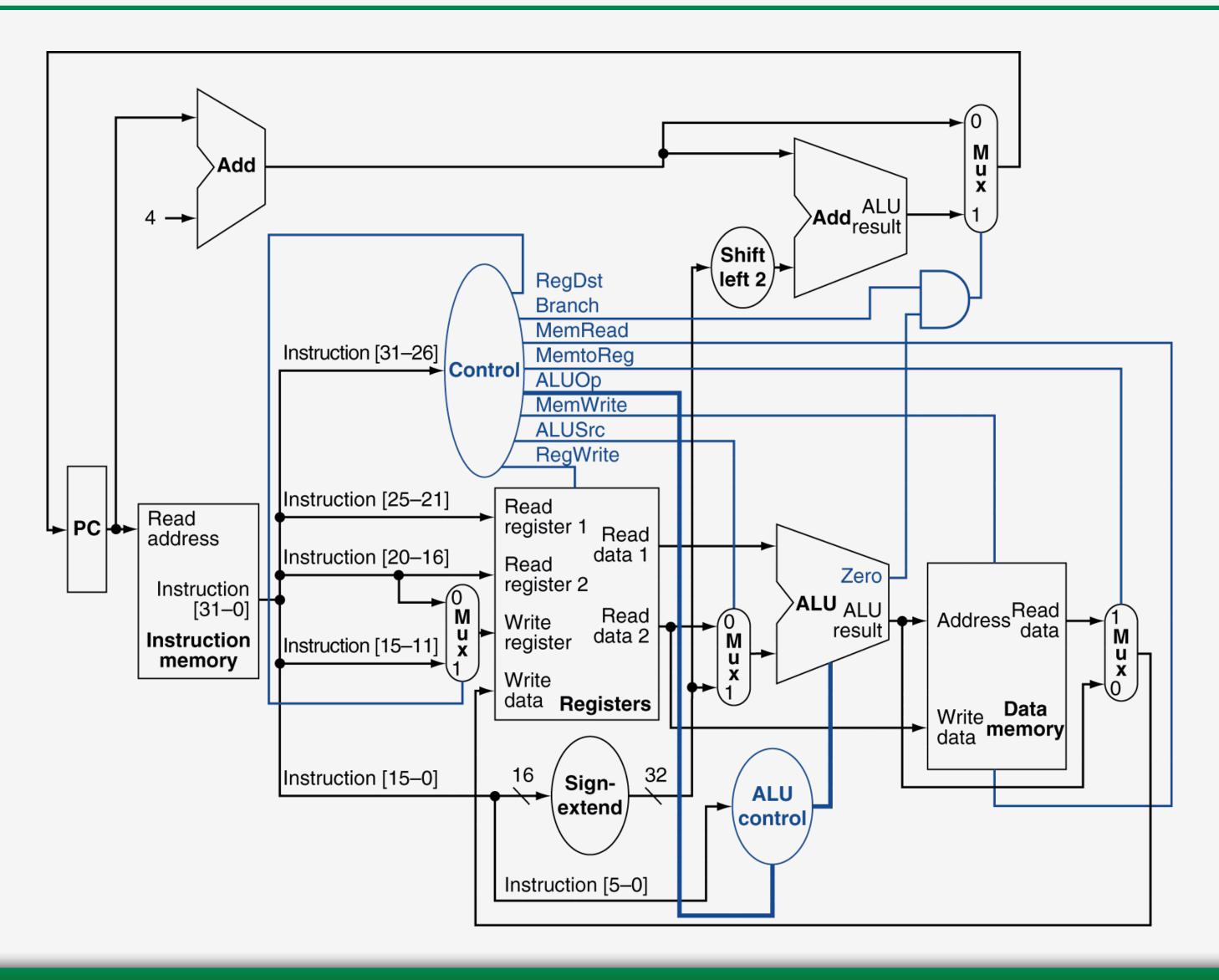
ALU control lines	Function		
0000	AND		
0001	OR		
0010	add		
0110	subtract		
0111	set on less than		
1100	NOR		

The ALU Control Unit

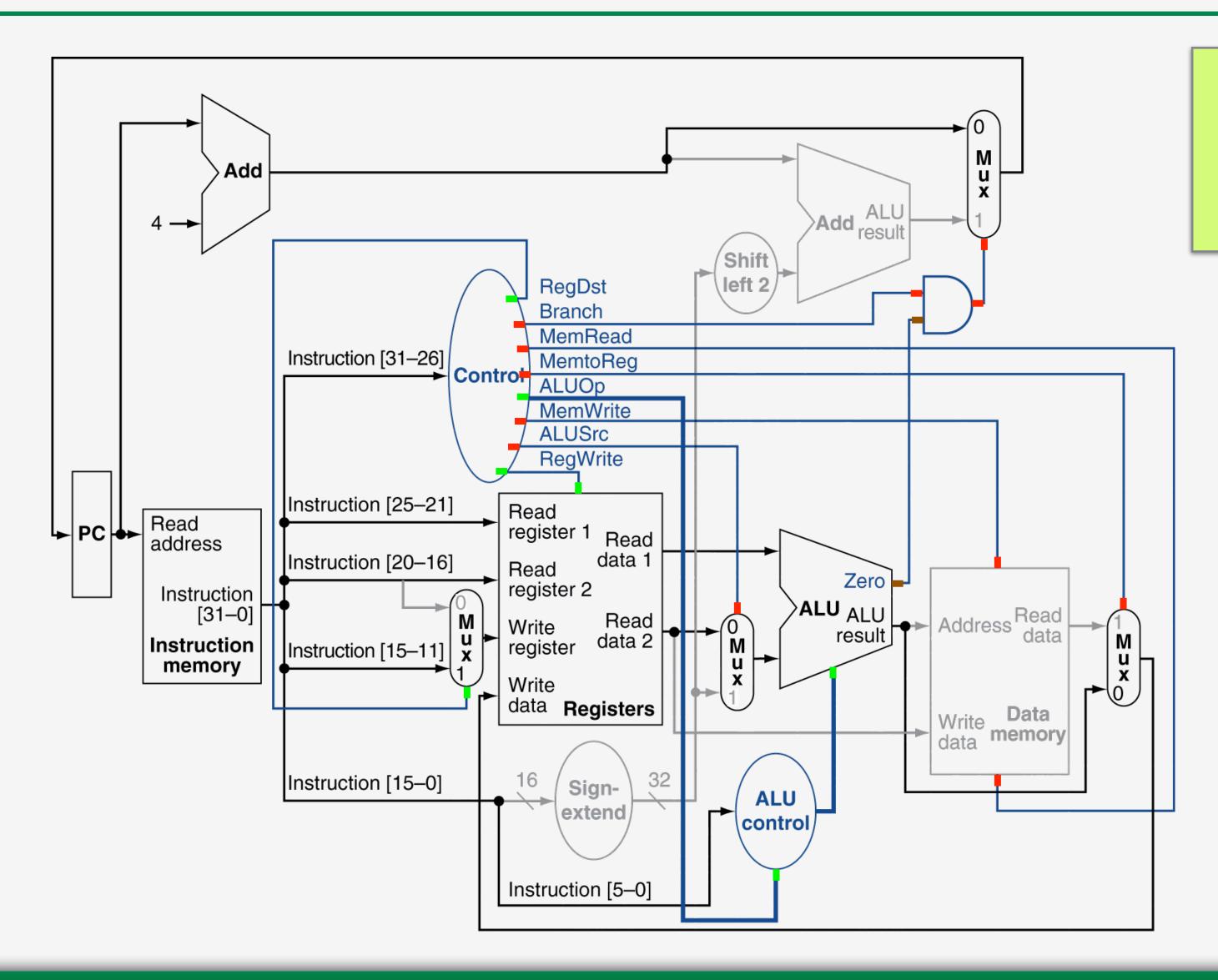
- Generates the 4-bit "ALU Operation" input for the ALU
- Inputs include:
 - 6-bit funct field directly from instruction word; used for R-type instructions only
 - Ignored for load/store/branch instructions since they don't have a funct field
 - 2-bit ALUOp value that is generated by a main control unit
 - ALUOp is derived from the opcode in the main control unit

Instruction opcode	ALUOp	Instruction operation	Function code	Desired ALU action	ALU control input
LW	00	load word	XXXXXX	add	0010
SW	00	store word	XXXXXX	add	0010
Branch equal	01	branch equal	XXXXXX	subtract	0110
R-type	10	add	100000	add	0010
R-type	10	subtract	100010	subtract	0110
R-type	10	AND	100100	AND	0000
R-type	10	OR	100101	OR	0001
R-type	10	set on less than	101010	set on less than	0111

Complete Datapath With Control (again)



Datapath During R-Type Instruction



Darker colored paths and hardware units are in use. Lighter colored paths are not in use.

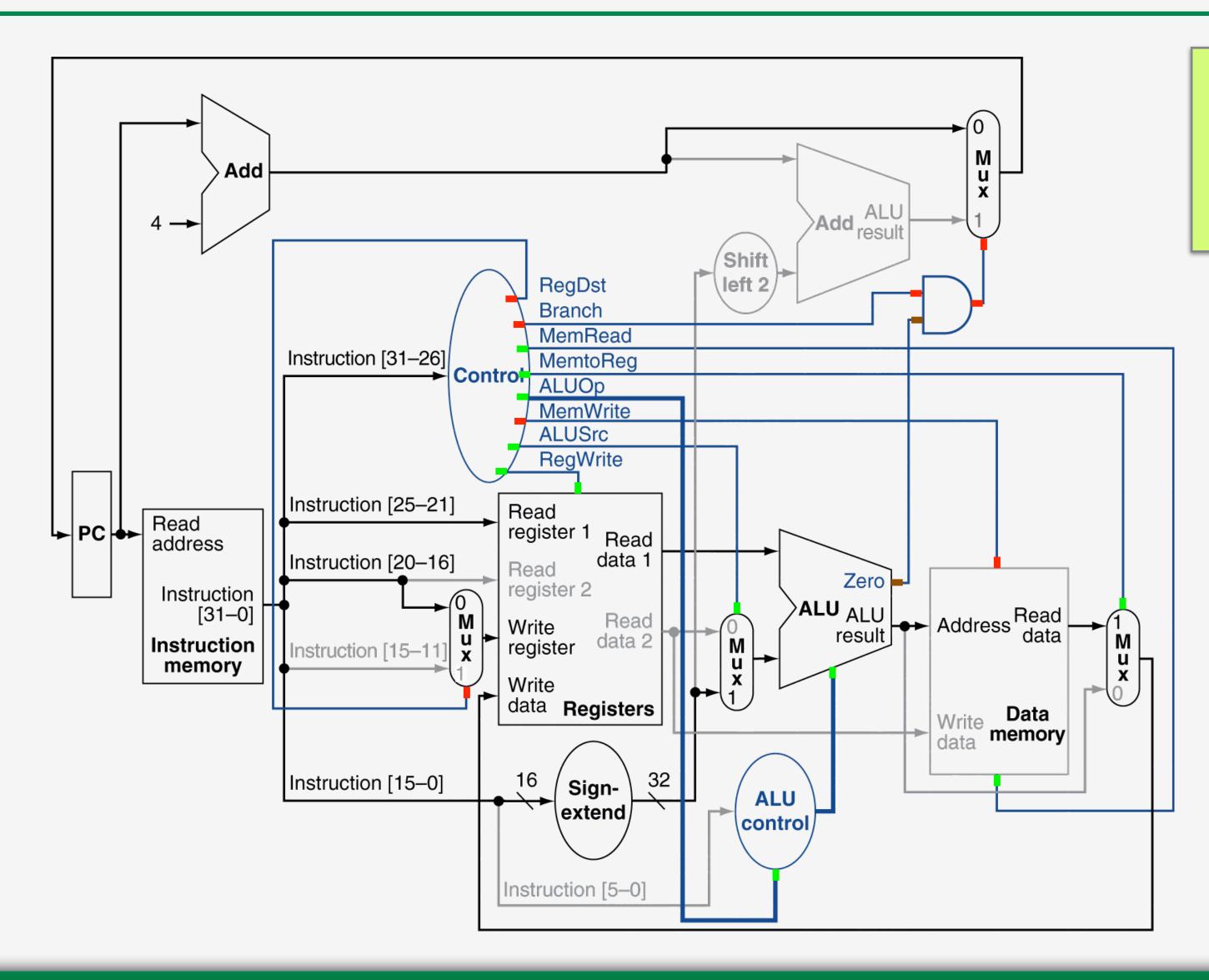
Control Lines:

asserted

not asserted

don't care

Datapath During Load Instruction



Darker colored paths and hardware units are in use. Lighter colored paths are not in use.

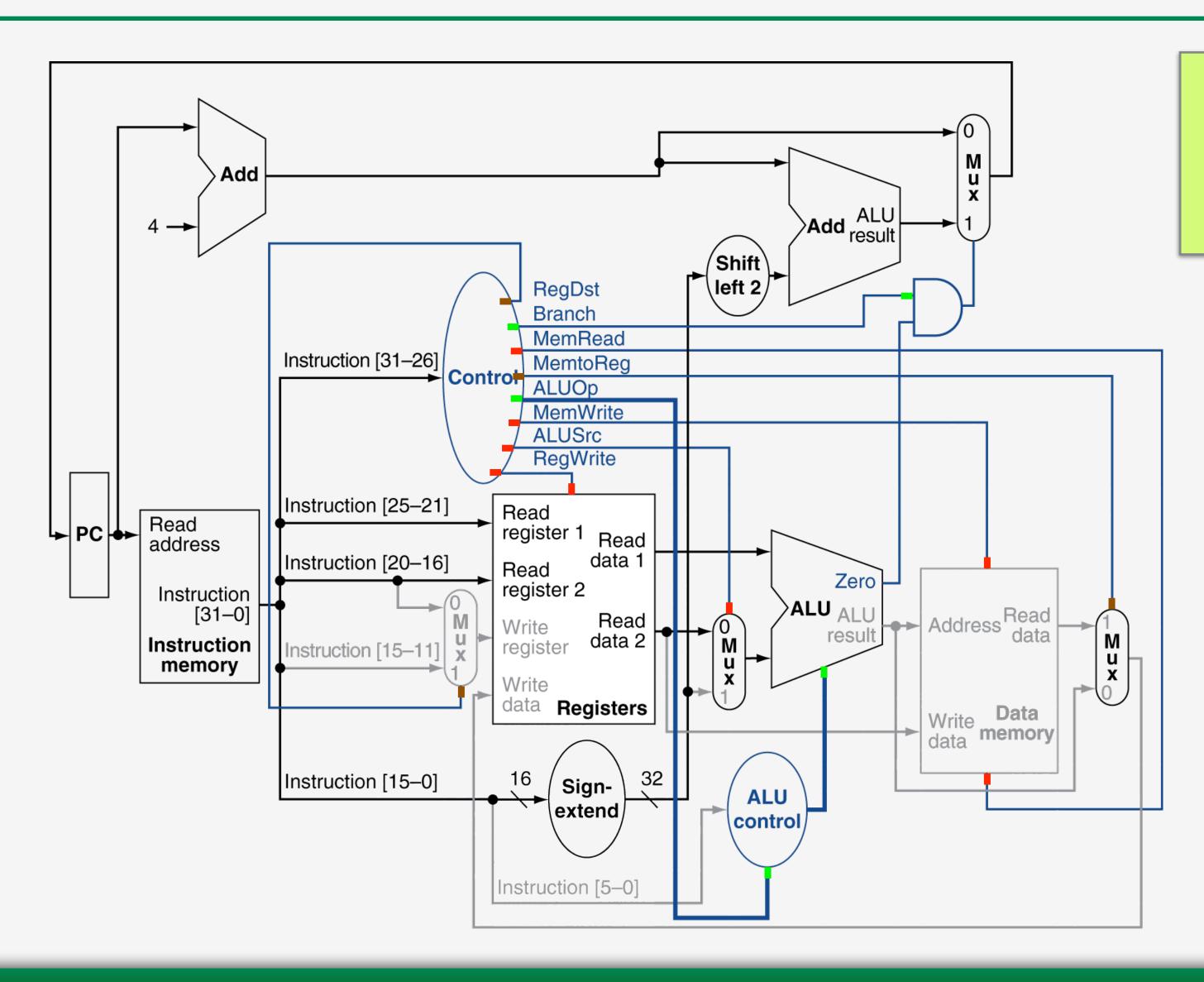
Control Lines:

asserted

not asserted

don't care

Datapath During Branch-on-Equal Instruction



Darker colored paths and hardware units are in use. Lighter colored paths are not in use.

Control Lines:

- asserted
- not asserted
- don't care

Zero output of ALU may or may not be asserted.