

$f \leftarrow \text{target}$

$X_1, X_2, \dots$

$p(x|y)$

$\hookrightarrow$  density for  $X_t$ , conditional on

$X_{t-1} = y$

if we find some  $p(x|y)$  s.t.

$f$  is stationary w.r.t to  $p(x|y)$

then regardless of how we sample

$X_1, P_t \rightarrow f$  as  $t$  gets large

the question here:

how do we find such a transition kernel?

$\Rightarrow$  partially answered using the  
metropolis-hasting algorithm

① generate a proposal  
 $h(x|y)$

②  $a(x|y)$

$$a(x|y) = \min \left( 1, \frac{f(x) h(y|x)}{f(y) h(x|y)} \right)$$

Random Walk Metropolis:- Hastings

①  $X_t = y$

$$\Delta y \sim \text{MVN}(\vec{0}, \Sigma)$$

proposal  $y + \Delta y = x$

$$\begin{aligned} \underline{h(x|y)} &= f_{0, \Sigma}(x-y) \\ &= f_{0, \Sigma}(y-x) = \underline{h(y|x)} \end{aligned}$$

$$a(x|y) = \min \left( 1, \frac{f'(x) h(y|x)}{f(y) h(x|y)} \right)$$

$$= \min \left( 1, \frac{f'(x)}{f(y)} \right)$$

Hamiltonian Monte Carlo

$h(x|y)$  that always has  $a(x|y)$  of 100%.

that also gets for any

$$X_t = x \quad X_t \in \mathbb{R}^d$$

$p \in \mathbb{R}^d$  momentum vector

$$p \sim \text{MVN}(0, \Sigma) \quad p \perp X_t$$

$$H(x, p) = -\log(p_{x,p}(x, p))$$

$$= -\log(p_{e|x}(e|x) p(x))$$

-  $\tau(e)$

$$= -\log(p_e(e)) \quad \left\{ \begin{array}{l} \text{kinetic} \end{array} \right.$$

$$- \log(f(x))$$

$$\uparrow V(x) \quad \begin{array}{l} \text{potential} \\ \text{energy} \end{array}$$

$$x(s) \quad p(s) \quad \text{up until } K$$

$$\text{st} \quad H(x(s), p(s)) = c$$

$$0 = \frac{\partial H}{\partial s} = \frac{\partial H}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial H}{\partial p} \frac{\partial p}{\partial s}$$

$$= \frac{\partial V}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial T}{\partial p} \frac{\partial p}{\partial s}$$

$$\frac{\partial x}{\partial s} = \frac{\partial T}{\partial p} \quad \left\{ \begin{array}{l} - \frac{\partial V}{\partial x} = \frac{\partial p}{\partial s} \end{array} \right.$$

$$x(s) = x(0) + \int_0^s \frac{\partial T}{\partial p(u)} du$$

$$P(u) = P(0) - \int_0^u \frac{\partial V}{\partial x(u)} du$$

$$\frac{\partial T}{\partial P} = \sum^{-1} P$$

$$(X, P) \xrightarrow[\text{evolve system until } K]{} (Y, P_N)$$

$$h(y|x) = \exp(-T(P))$$

$$h(x|y) = \exp(-T(P_N))$$

$$f(x) = \exp(-V(x))$$

$$f(y) = \exp(-V(y))$$

$$a(y|x) = \min \left( 1, \frac{f(y) h(x|y)}{f(x) h(y|x)} \right)$$

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$$\begin{aligned}
&= \frac{\exp(-V(y) - T(P_y))}{\exp(-V(x) - T(P))} \\
&= \exp(H(x, P) - H(y, P_y)) \\
&= |
\end{aligned}$$

Need to do: solve differential  
equations numerically.

$\epsilon > 0$  relatively step-size  
leap frog integrator

$(x_0, p_0)$

$N$  steps of size  $\epsilon$  for  $x$

$$N\epsilon = K$$

$2N$  steps of size  $\epsilon$  for  $p$

$$p_{1/2} = p_0 - \frac{\epsilon}{2} \frac{\partial V}{\partial x}(x_0)$$

$$x_1 = x_0 + \epsilon \cdot \frac{\partial T}{\partial p}(p_{1/2})$$

$$= x_0 + \epsilon \cdot \Sigma^{-1} p_{1/2}$$

$$p_1 = p_{1/2} - \frac{\epsilon}{2} \frac{\partial V}{\partial x}(x_1)$$

$$p_{3/2} = p_1 - \frac{\epsilon}{2} \frac{\partial V}{\partial x}(x_1)$$

$$x_2 = x_1 + \epsilon \Sigma^{-1} p_{3/2}$$

$$p_2 = \dots$$

$$(x_N, p_N)$$

$$a(x_N | x_0) = \min \left( 1, \exp \left( H(x_0, p_0) - H(x_N, p_N) \right) \right)$$