

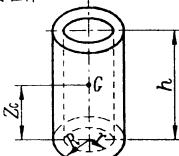
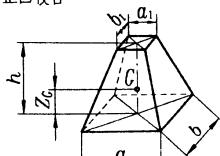
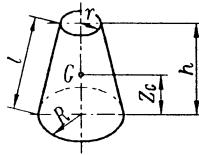
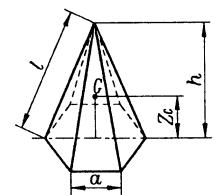
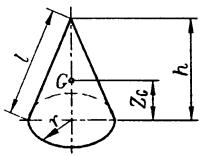
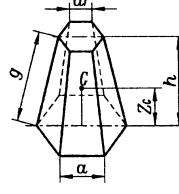
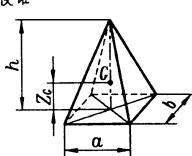
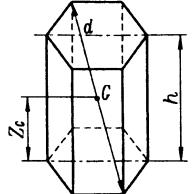
第1章 常用资料、数据和一般标准

G1 常用几何体的体积、面积及重心位置 (表 G1-1)

表 G1-1 常用几何体的体积、面积及重心位置

图 形	体积 V 、底面积 A 、侧面积 A_0 、全面积 A_n 、重心位置 G 的计算公式	图 形	体积 V 、底面积 A 、侧面积 A_0 、全面积 A_n 、重心位置 G 的计算公式
正方体 	$V = a^3$ $A = a^2$ $A_0 = 4a^2$ $A_n = 6a^2$ $d = \sqrt{3}a$ $(d \text{ 为对角线})$ $Z_G = \frac{a}{2}$	球缺体 	$V = \frac{p}{6}h(3a^2 + h^2)$ $= \frac{p}{3}h^2(3r - h)$ $A = pa^2$ $A_0 = 2prh = p(a^2 + h^2)$ $A_n = p(2rh + a^2) = p(h^2 + 2a^2)$ $Z_G = \frac{h(4r - h)}{4(3r - h)}$
长方体 	$V = abh$ $A = ab$ $A_0 = 2h(a + b)$ $A_n = 2(ab + ah + bh)$ $d = \sqrt{a^2 + b^2 + h^2}$ $(d \text{ 为对角线})$ $Z_G = \frac{h}{2}$	椭球体 	$V = \frac{4}{3}pabc$ <p>重心 G 在椭球中心</p>
球体 	$V = \frac{4}{3}p r^3$ $A_n = 4p r^2$ <p>重心 G 与球心重合</p>	圆环体 	$V = 2p^2 Rr^2 = \frac{p^2}{4} Dd^2$ $A_n = 4p^2 Rr = p^2 Dd$ <p>重心 G 在圆环中心</p>
半球体 	$V = \frac{2}{3}p r^3$ $A = p r^2$ $A_0 = 2p r^2$ $A_n = 3p r^2$ $Z_G = \frac{3}{8}r$	圆柱体 	$V = \pi r^2 h$ $A_0 = 2\pi r h$ $A_n = 2\pi r(r + h)$ $Z_G = \frac{h}{2}$

(续)

图 形	体积 V 、底面积 A 、侧面积 A_0 、全面积 A_n 、重心位置 G 的计算公式	图 形	体积 V 、底面积 A 、侧面积 A_0 、全面积 A_n 、重心位置 G 的计算公式
空心圆柱体 	$V = \pi h (R^2 - r^2)$ $A = \pi (R^2 - r^2)$ $A_0 = 2\pi h (R + r)$ $A_n = 2\pi (R + r)(R - r + h)$ $Z_G = \frac{h}{2}$	正四棱台 	$V = \frac{h}{6} (2ab + ab_1 + a_1b + 2a_1b_1)$ $A_1 = a_1b_1$ $A = ab$ $A_0 = \frac{1}{2} [(b_1 + b)\sqrt{4h^2 + (a - a_1)^2} + (a_1 + a)\sqrt{4h^2 + (b - b_1)^2}]$ $A_n = A + A_1 + A_0$ $Z_G = \frac{h(ab + ab_1 + a_1b + 3a_1b_1)}{2(2ab + ab_1 + a_1b + 2a_1b_1)}$
圆台 	$V = \frac{\pi}{3} h (R^2 + r^2 + Rr)$ $A_0 = \pi l (R + r)$ $A_n = \pi (R^2 + r^2) + A_0$ $l = \sqrt{(R - r)^2 + h^2}$ $Z_G = \frac{h(R^2 + 2Rr + 3r^2)}{4(R^2 + Rr + r^2)}$	正六棱锥 	$V = \frac{1}{3} Ah = \frac{\sqrt{3}}{2} a^2 h$ $A = \frac{3\sqrt{3}}{2} a^2$ $A_0 = \frac{3}{2} a \sqrt{4l^2 - a^2}$ $A_n = A + A_0$ $Z_G = \frac{h}{4}$
圆锥体 	$V = \frac{1}{3} \pi r^2 h$ $A = \pi r^2$ $A_0 = \pi r l$ $A_n = \pi r(r + l)$ $l = \sqrt{r^2 + h^2}$ $Z_G = \frac{h}{4}$	正六棱台 	$V = \frac{hA}{3} \left[1 + \frac{a_1}{a} + \left(\frac{a_1}{a} \right)^2 \right]$ $A_1 = \frac{3\sqrt{3}}{2} a_1^2$ $A = \frac{3\sqrt{3}}{2} a^2$ $A_0 = 3g(a_1 + a)$ $A_n = A + A_1 + A_0$ $Z_G = \frac{h(a^2 + 2a_1a + 3a_1^2)}{4(a^2 + a_1a + a_1^2)}$ <p>(A_1 为顶面积, g 为斜高)</p>
正四棱锥 	$V = \frac{1}{3} abh$ $A = ab$ $A_0 = \frac{1}{2} (b\sqrt{4h^2 + a^2} + a\sqrt{4h^2 + b^2})$ $A_n = ab + \frac{1}{2} (b\sqrt{4h^2 + a^2} + a\sqrt{4h^2 + b^2})$ $Z_G = \frac{h}{4}$	正六棱柱 	$V = \frac{3\sqrt{3}}{2} a^2 h$ $A = \frac{3\sqrt{3}}{2} a^2$ $A_0 = 6ah$ $A_n = 3\sqrt{3}a^2 + 6ah$ $d = \sqrt{h^2 + 4a^2}$ <p>(d 为对角线)</p> $Z_G = \frac{h}{2}$

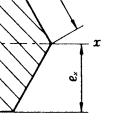
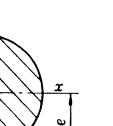
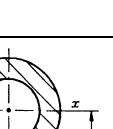
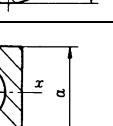
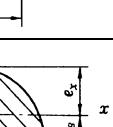
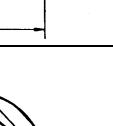
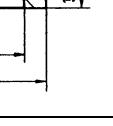
G2 常用力学公式

G2.1 常用截面的力学特性(表 G1-2、表 G1-3)

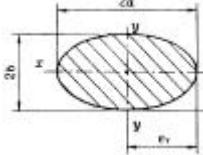
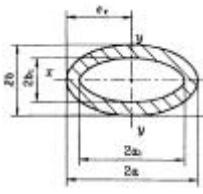
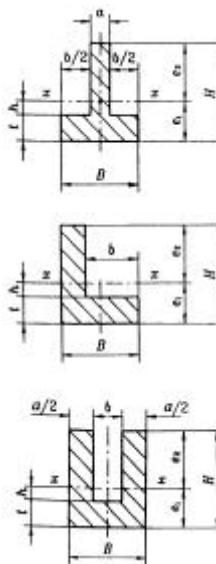
表 G1-2 常用截面的几何及力学特性

截面形状	面积 A	惯性矩 I	截面系数 $W = \frac{I}{e}$	回转半径 $i = \sqrt{\frac{I}{A}}$	形心距离 e
	a^2	$\frac{a^4}{12}$	$W_x = \frac{a^2}{6}$ $W_{x1} = 0.1179a^3$	$\frac{a}{\sqrt{12}} = 0.289a$	$e_x = \frac{a}{2}$ $e_{x1} = 0.7071a$
	$a^2 - b^2$	$\frac{a^4 - b^4}{12}$	$W_x = \frac{a^4 - b^4}{6a}$ $W_{x1} = 0.1179 \frac{a^4 - b^4}{a}$	$0.289\sqrt{a^2 + b^2}$	$e_x = \frac{a}{2}$ $e_{x1} = 0.7071a$
	ab	$\frac{ab^3}{12}$	$\frac{ab^2}{6}$	$\frac{b}{\sqrt{12}} = 0.289b$	$\frac{b}{2}$
	$b(H-h)$	$I_x = \frac{b(H^3 - h^3)}{12}$ $I_y = \frac{b^3(H-h)}{12}$	$W_x = \frac{b(H^3 - h^3)}{6H}$ $W_y = \frac{b^2(H-h)}{6}$	$i_x = \sqrt{\frac{H^2 + Hh + h^2}{12}}$ $i_y = 0.289b$	$e_x = \frac{H}{2}$ $e_y = \frac{b}{2}$
	$\frac{H}{2}(a+b)$	$\frac{a^2 + b^2 + 4ab}{36(a+b)}H^3$	$W_{xa} = \frac{H^2(a^2 + 4ab + b^2)}{12(a+2b)}$ $W_{xb} = \frac{H^2(a^2 + 4ab + b^2)}{12(2a+b)}$	$\frac{H}{3(a+b)} \times \sqrt{\frac{a^2 + 4ab + b^2}{2}}$	$\frac{H(2a+b)}{3(a+b)}$
	$\frac{bH}{2}$	$\frac{bH^3}{36}$	$W_{xa} = \frac{bH^2}{24}$ $W_{xb} = \frac{bH^2}{12}$	$\frac{H}{3\sqrt{2}} = 0.236H$	$\frac{H}{3}$

(续)

截面形状	面积 A	惯性矩 I	截面系数 $W = \frac{I}{e}$	回转半径 $i = \sqrt{\frac{I}{A}}$	形心距离 e
	$A = 2.598C^2$ $C = R$	$I_x = 0.5413R^4$ $I_y = I_x$	$W_x = 0.625R^3$ $W_y = 0.5413R^3$	$i_x = 0.4566R$	$e_x = 0.866R$ $e_y = R$
	$\frac{\pi d^2}{4}$	$\frac{\pi d^4}{64}$	$\frac{\pi d^3}{32}$	$\frac{d}{4}$	$\frac{d}{2}$
	$\frac{\pi}{4}(D^2 - d^2)$	$\frac{\pi}{64}(D^4 - d^4)$	$\frac{\pi}{32} \left(\frac{D^4 - d^4}{D} \right)$	$\frac{\sqrt{D^4 + d^4}}{4}$	$\frac{D}{2}$
	$a^2 - \frac{\pi d^2}{4}$	$\frac{1}{12} \left(a^4 - \frac{3\pi d^4}{16} \right)$	$\frac{1}{6a} \left(a^4 - \frac{3\pi d^4}{16} \right)$	$\sqrt{\frac{16a^4 - 3\pi d^4}{48(4a^2 - \pi d^2)}}$	$\frac{a}{2}$
	$\frac{\pi d^2}{8}$	$I_x = 0.00686d^4$ $I_y = \frac{\pi d^4}{128}$	$W_x = 0.0239d^4$ $W_y = \frac{\pi d^3}{64}$	$i_x = 0.1319d$ $i_y = \frac{d}{4}$	$e_x = 0.2878d$ $y_s = 0.2122d$
	$\frac{\pi(D^2 - d^2)}{8}$	$I_x = 0.00686(D^4 - d^4)$ $I_y = \frac{\pi(D^4 - d^4)}{128}$	$W_y = \frac{\pi d^3}{64} \left(1 - \frac{d^4}{D^4} \right)$	$i_x = \sqrt{\frac{I_x}{A}}$ $i_y = \sqrt{\frac{I_y}{F}}$ $= \frac{1}{4} \sqrt{D^2 + d^2}$	$y_s = \frac{2(D^2 + Dd + d^2)}{3\pi(D+d)}$
	$A = \frac{1}{2} [rl - c(r-h)]$ $c = 2\sqrt{h(2r-h)}$ $r = \frac{c^2 + 4h^2}{8h}$ $I_{x1} = \frac{lr^3}{8} - \frac{r^4}{8} \sin a \cos a$ $I_y = \frac{r^4}{8} \left(\frac{ap}{180^\circ} - \sin a - \frac{2}{3} \sin a \sin^2 \frac{a}{2} \right)$	$a = \frac{57.296l}{r}$ $h = r - \frac{1}{2} \sqrt{4r^2 - c^2}$ $J_x = J_{x1} - Ay_s^2$ $W_x = \frac{J_x}{r - y_s}$	$i_x = \sqrt{\frac{I_x}{A}}$	$y_s = \frac{c^3}{12A}$	

(续)

截面形状	面积 A	惯性矩 I	截面系数 $W = \frac{I}{e}$	回转半径 $i = \sqrt{\frac{I}{A}}$	形心距离 e
	pab	$I_x = \frac{pab^3}{4}$ $I_y = \frac{pa^3b}{4}$	$W_x = \frac{pab^2}{4}$ $W_y = \frac{pa^2b}{4}$	$i_x = \frac{b}{2}$ $i_y = \frac{a}{2}$	$e_x = b$ $e_y = a$
	$p(ab - a_1b_1)$	$I_x = \frac{p}{4}(ab^3 - a_1b_1^3)$ $I_y = \frac{p}{4}(a^3b - a_1^3b_1)$	$W_x = \frac{p(ab^3 - a_1b_1^3)}{4b}$ $W_y = \frac{p(a^3b - a_1^3b_1)}{4a}$	$i_x = \sqrt{\frac{I_x}{A}}$ $i_y = \sqrt{\frac{I_y}{A}}$	$e_x = b$ $e_y = a$
	$BH - b(e_2 + h)$	$I_x = \frac{Be_1^3 + ae_2^3 - bh^3}{3}$	$W_{x1} = \frac{I_x}{e_1}$ $W_{x2} = \frac{I_x}{e_2}$	$\sqrt{\frac{Be_1^3 + ae_2^3 - bh^3}{3[BH - b(e_2 + h)]}}$	$e_1 = \frac{aH^2 + bt^2}{2(aH + bt)}$ $e_2 = H - e_1$

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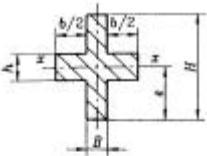
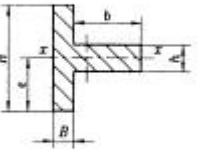
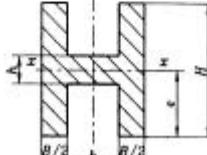
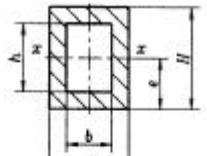
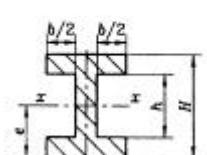
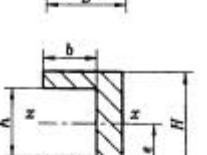
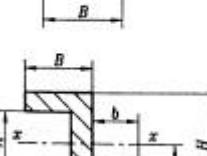
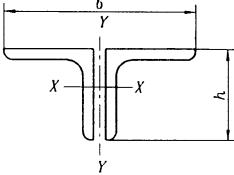
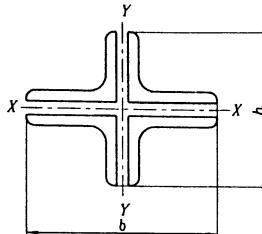
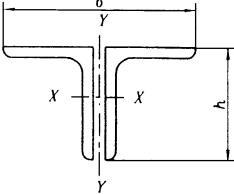
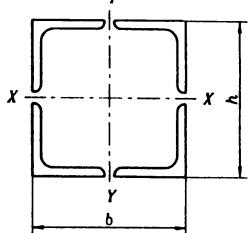
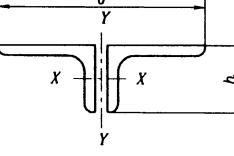
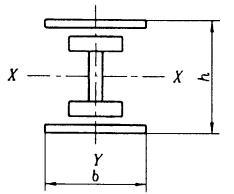
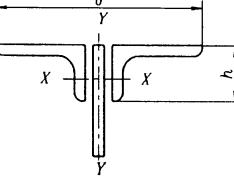
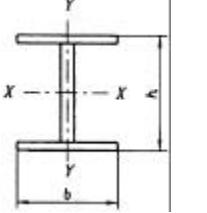
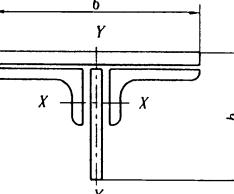
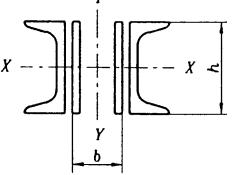
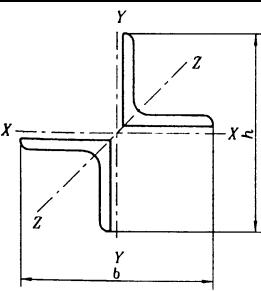
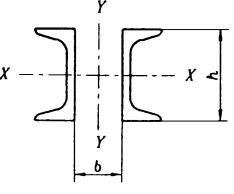
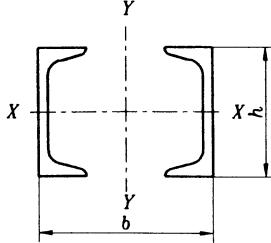
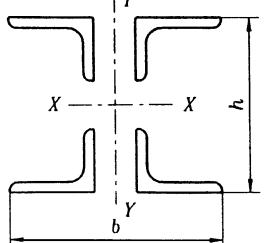
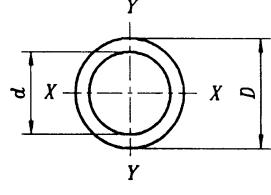
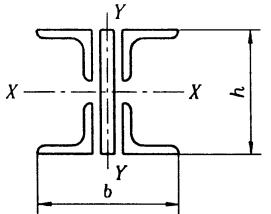
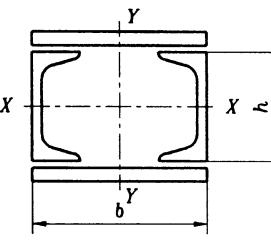
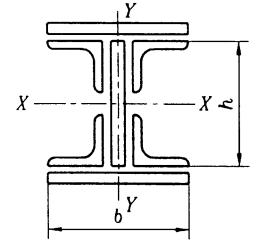
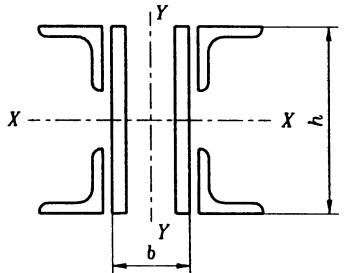
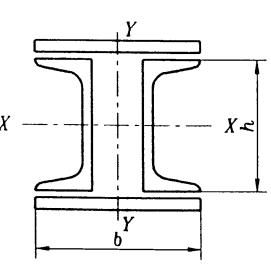
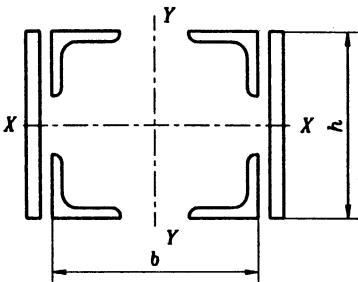
截面形状	面积 A	惯性矩 I	截面系数 $W = \frac{I}{e}$	回转半径 $i = \sqrt{\frac{I}{A}}$	形心距离 e
  	$BH + bh$	$I_x = \frac{BH^3 + bh^3}{12}$	$W_x = \frac{BH^3 + bh^3}{6H}$	$\sqrt{\frac{BH^3 + bh^3}{12(BH + bh)}}$	$\frac{H}{2}$
   	$BH - bh$	$I_x = \frac{BH^3 - bh^3}{12}$	$W_x = \frac{BH^3 - bh^3}{6H}$	$i_x = \sqrt{\frac{BH^3 - bh^3}{12(BH - bh)}}$	$\frac{H}{2}$

表 G1-3 主要组合截面的回转半径

截面形状	回转半径	截面形状	回转半径
	$i_X = 0.30h$ $i_Y = 0.215h$		$i_X = 0.21h$ $i_Y = 0.21b$
	$i_X = 0.32h$ $i_Y = 0.20b$		$i_X = 0.43h$ $i_Y = 0.43b$
	$i_X = 0.28h$ $i_Y = 0.24b$		$i_X = 0.42h$ $i_Y = 0.22b$
	$i_X = 0.30h$ $i_Y = 0.17b$		$i_X = 0.39h$ $i_Y = 0.20b$
	$i_X = 0.26h$ $i_Y = 0.21b$		$i_X = 0.35h$ $i_Y = 0.56b$
	$i_X = 0.21h$ $i_Y = 0.21b$ $i_Z = 0.185h$		$i_X = 0.38h$ $i_Y = 0.60b$

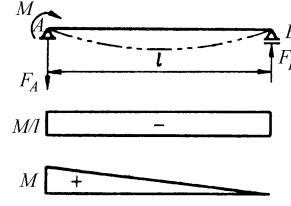
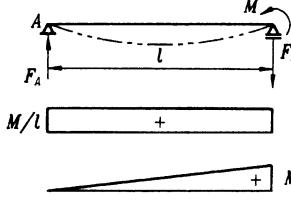
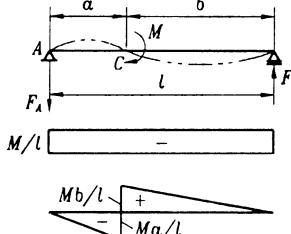
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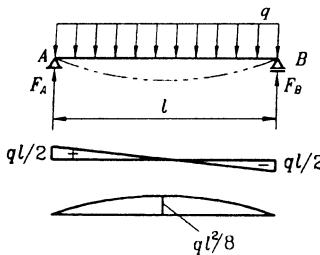
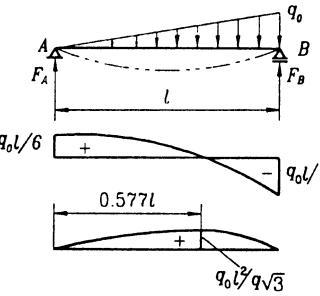
截面形状	回转半径	截面形状	回转半径
	$i_X = 0.38h$ $i_Y = 0.44b$		$i_X = 0.45h$ $i_Y = 0.24b$
	$i_X = 0.35d_{cp}$ $d_{cp} = \frac{D+d}{2}$		$i_X = 0.40h$ $i_Y = 0.21b$
	$i_X = 0.44h$ $i_Y = 0.38b$		$i_X = 0.45h$ $i_Y = 0.235b$
	$i_X = 0.37h$ $i_Y = 0.54b$		$i_X = 0.44h$ $i_Y = 0.32b$
	$i_X = 0.37h$ $i_Y = 0.45b$		

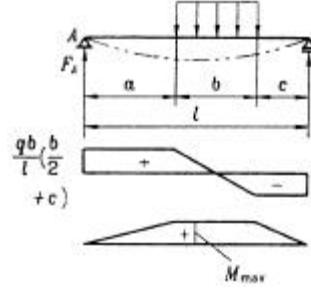
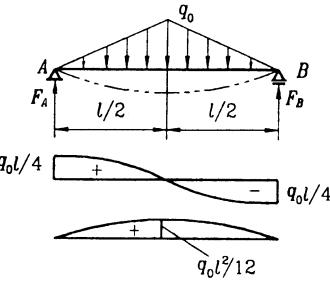
G2.2 受静载荷梁的支点反力、弯矩和变形计算公式 (表 G1-4、表 G1-5)

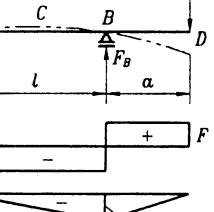
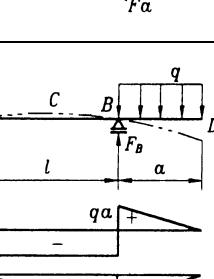
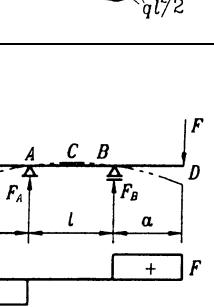
表 G1-4 常用静定梁的支点反力、弯矩和变形计算公式

序号	载荷情况及剪力图弯矩图	支点反力	弯矩方程	挠度曲线方程	最大挠度	梁端转角
1	<p>Diagram of a beam A-B with a central downward force F. The beam is supported by a roller at A and a pin at B. The length is l. The deflection curve is a parabola opening downwards. The deflection $y(x)$ is shown at a distance x from A. The maximum deflection y_{\max} is at the center ($l/2$).</p>	$F_A = F_B = \frac{F}{2}$	$0 \leq x \leq l/2:$ $M(x) = \frac{Fx}{2}$	$0 \leq x \leq l/2:$ $y = \frac{-Fl^3}{48EI} \left(\frac{3x}{l} - \frac{4x^3}{l^3} \right)$	在 $x = l/2$ 处: $y_{\max} = \frac{-Fl^3}{48EI}$	$q_A = -q_B = \frac{-Fl^2}{16EI}$
2	<p>Diagram of a beam A-B with a central downward force F. The beam is supported by a roller at A and a pin at B. The length is l. The beam is divided into two segments of length a and b. The deflection curve is a parabola opening downwards.</p>	$F_A = \frac{Fb}{l}$ $F_B = \frac{Fa}{l}$	$0 \leq x \leq a:$ $M(x) = \frac{Fbx}{1}$ $a \leq x \leq l:$ $M(x) = \frac{Fbx}{1} - F(x-a)$	$0 \leq x \leq a:$ $y = \frac{-Fbx}{6EI} (l^2 - x^2 - b^2)$ $0 \leq x \leq l:$ $y = \frac{-Fb}{6EI} \times \left[(l^2 - b^2)x - x^3 + \frac{(x-a)^3}{b} \right]$	若 $a > b$, 在 $x = \sqrt{\frac{l^2 - b^2}{3}}$ 处: $y_{\max} = \frac{-Fb(l^2 - b^2)^{3/2}}{9\sqrt{3}EI}$ 在 $x = l/2$ 处: $y = \frac{-Fb(3l^2 - 4b^2)}{48EI}$	$q_A = \frac{-Fab(l+b)}{6EI}$ $q_B = \frac{Fab(l+a)}{6EI}$
3	<p>Diagram of a beam A-B with a central downward force F. The beam is supported by a roller at A and a pin at B. The length is l. The beam is divided into three segments of length a, a, and $l-a$. The deflection curve is a parabola opening downwards.</p>	$F_A = F_B = F$	$0 \leq x \leq a:$ $M(x) = Fx$ $a \leq x \leq l-a:$ $M = Fa$	$0 \leq x \leq l:$ $y = \frac{-Fx}{6EI} [3a(l-a) - x^2]$ $0 \leq x \leq l-a:$ $y = \frac{-Fa}{6EI} [3x(l-x) - a^2]$	在 $x = l/2$ 处: $y_{\max} = \frac{-Fa}{24EI} (3l^2 - 4a^2)$	$q_A = -q_B$ $= \frac{-Fa^2}{2EI} (l-a)$

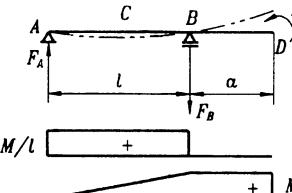
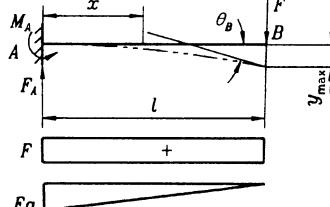
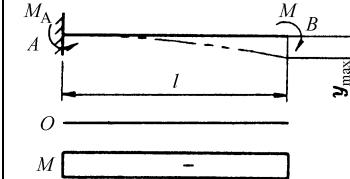
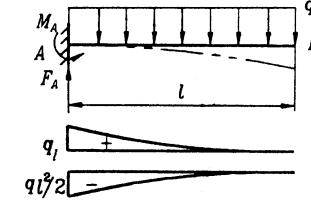
序号	载荷情况及剪力图弯矩图	支点反力	弯矩方程	挠度曲线方程	最大挠度	梁端转角
4		$F_A = F_B = \frac{M}{l}$	$M(x) = M \left(1 - \frac{x}{l}\right)$	$y = \frac{-Ml^2}{6EI} \left(\frac{2x}{l} - \frac{3x^2}{l^2} + \frac{x^3}{l^3}\right)$	<p>在 $x = \left(1 - \frac{1}{\sqrt{3}}\right)l$ 处: $y_{\max} = \frac{-Ml^2}{9\sqrt{3}EI}$</p> <p>在 $x = l/2$ 处: $y = \frac{-Ml^2}{16EI}$</p>	$q_A = \frac{-Ml}{3EI}$ $q_B = \frac{Ml}{6EI}$
5		$F_A = F_B = \frac{M}{l}$	$M(x) = \frac{Mx}{l}$	$y = \frac{-Ml^2}{6EI} \left(\frac{x}{l} - \frac{x^3}{l^3}\right)$	<p>在 $x = \frac{1}{\sqrt{3}}$ 处: $y_{\max} = \frac{-Ml^2}{9\sqrt{3}EI}$</p> <p>在 $x = l/2$ 处: $y = \frac{-Ml^2}{16EI}$</p>	$q_A = \frac{-Ml}{6EI}$ $q_B = \frac{Ml}{3EI}$
6		$F_A = F_B = \frac{M}{l}$	$0 \leq x \leq a: M(x) = \frac{-Mx}{l}$ $a \leq x \leq l: M(x) = M \left(1 - \frac{x}{l}\right)$	$0 \leq x \leq a: y = \frac{Mx}{6EI} (l^2 - 3b^2 - x^2)$ $a \leq x \leq l: y = \frac{-M(l-x)}{6EI} [l^2 - 3a^2 - (l-x)^2]$	<p>在 $x = \sqrt{(l^2 - 3b^2)/3}$ 处: $y_{1\max} = \frac{M(l^2 - 3b^2)^{3/2}}{9\sqrt{3}EI}$</p> <p>在 $x = \sqrt{(l^2 - 3a^2)/3}$ 处: $y_{2\max} = \frac{-M(l^2 - 3a^2)^{3/2}}{9\sqrt{3}EI}$</p>	$q_A = \frac{M(l^2 - 3b^2)}{6EI}$ $q_B = \frac{M(l^2 - 3a^2)}{6EI}$ $q_C = \frac{-M}{6EI} (3a^2 + 3b^2 - l^2)$

序号	载荷情况及剪力图弯矩图	支点反力	弯矩方程	挠度曲线方程	最大挠度	梁端转角
7		$F_A = F_B = \frac{ql}{2}$	$M(x) = \frac{qx}{2}(l-x)$	$y = \frac{-qx}{24EI}(l^3 - 2lx^2 + x^3)$	在 $x = l/2$ 处: $y_{\max} = \frac{-5ql^4}{384EI}$	$q_A = -q_B = \frac{-ql^3}{24EI}$
8		$F_A = \frac{q_0 l}{6}$ $F_B = \frac{q_0 l}{3}$	$M(x) = \frac{q_0 l x}{6} \left(1 - \frac{x^2}{l^2}\right)$	$y = \frac{-q_0 l^4}{360EI} \times \left(\frac{7x}{l} - \frac{10x^3}{l^3} + \frac{3x^5}{l^5}\right)$	在 $x = 0.519l$ 处: $y_{\max} = -0.00652 \frac{q_0 l^3}{EI}$	$q_A = \frac{-7q_0 l^3}{360EI}$ $q_B = \frac{q_0 l^3}{45EI}$

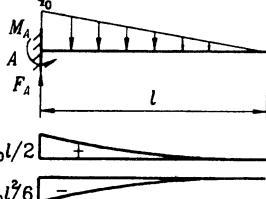
序号	载荷情况及剪力图弯矩图	支点反力	弯矩方程	挠度曲线方程	最大挠度	梁端转角
9		$F_A = \frac{qb}{l} \left(\frac{b}{2} + c \right)$ $F_B = \frac{qb}{l} \left(\frac{b}{2} + c \right) - \frac{q}{2} (x-a)^2$	$0 \leq x \leq a: M(x) = \frac{qb}{l} \left(\frac{b}{2} + c \right) x$ $a \leq x \leq a+b: M(x) = \frac{qb}{l} \left(\frac{b}{2} + c \right) x - \frac{q}{2} (x-a)^2$ $在 x = a + \frac{b}{l} \left(\frac{b}{2} + c \right) 处: M_{max} = \frac{qb}{l} \left(\frac{b}{2} + c \right) \times \left[a + \frac{b}{2l} \left(\frac{b}{2} + c \right) \right]$	$0 \leq x \leq a: y = \frac{-qbx}{6EI} \left(\frac{b}{2} + c \right)$ $\times \left[l^2 - \left(\frac{b}{2} + c \right)^2 - \frac{b^2}{4} - x^2 \right]$ $a \leq x \leq a+b: y = \frac{-qb}{6EI} \left\{ \left(\frac{b}{2} + c \right) x \times \left[l^2 - \left(\frac{b}{2} + c \right)^2 - \frac{b^2}{4} - x^2 \right] + \frac{l}{4b} (x-a)^4 \right\}$ $a+b \leq x \leq l: y = \frac{-qb}{6EI} (a+b)(l-x) \times \left[l^2 - \left(a + \frac{b}{2} \right)^2 - \frac{b^2}{4} - (l-x)^2 \right]$	$在 a \leq x \leq a+b 处: 令 y' = 0, 求出 x 的数值解, 代入 y 方程即得 y_{max}$	$q_A = \frac{-qb}{6EI} \left(\frac{b}{2} + c \right) \times \left[l^2 - \left(\frac{b}{2} + c \right)^2 - \frac{b^2}{4} \right]$ $q_B = \frac{qb}{6EI} (a+b) \times \left[l^2 - \left(a + \frac{b}{2} \right)^2 - \frac{b^2}{4} \right]$
10		$F_A = F_B = \frac{q_0 l}{4}$	$0 \leq x \leq l/2: M(x) = \frac{q_0 l x}{12} \left(3 - \frac{4x^2}{l^2} \right)$	$0 \leq x \leq l/2: y = \frac{-q_0 l^4}{960EI} \left(\frac{25x}{l} - \frac{40x^3}{l^3} + \frac{16x^5}{l^5} \right)$	$在 x = l/2 处: y_{max} = \frac{-q_0 l^4}{120EI}$	$q_A = -q_B = \frac{-5q_0 l}{192EI}$

序号	载荷情况及剪力图弯矩图	支点反力	弯矩方程	挠度曲线方程	最大挠度	梁端转角
11		$F_A = \frac{Fa}{l}$ $F_B = \frac{F(a+l)}{l}$	$0 \leq x \leq l:$ $M(x) = \frac{-Fax}{l}$ $l \leq x \leq l+a:$ $M(x) = -F(l+a-x)$	$0 \leq x \leq l:$ $y = \frac{Fal^2}{6EI} \left(\frac{x}{l} - \frac{x^3}{l^3} \right)$ $l \leq x \leq l+a:$ $y = \frac{F}{6EI} [al^2x - ax^3 + (a+l) \times (x-l)^3]$	在 $x = l+a$ 处: $q_A = \frac{Fal}{6EI}$ $q_B = \frac{-Fal}{3EI}$ 在 $x = l/2$ 处: $y_{max} = \frac{-Fa^2}{3EI}(l+a)$ $q_D = \frac{-Fa}{6EI}(2l+3a)$	
12		$F_A = \frac{qa^2}{2l}$ $F_B = qa \left(1 + \frac{a}{2l} \right)$	$0 \leq x \leq l:$ $M(x) = \frac{-qa^2}{2l}x$ $l \leq x \leq l+a:$ $M(x) = \frac{-q}{2}(l+a-x)^2$	$0 \leq x \leq l:$ $y = \frac{qa^2l^2}{12EI} \left(\frac{x}{l} - \frac{x^3}{l^3} \right)$ $l \leq x \leq l+a:$ $y = \frac{-qa^2}{12EI} \left[l^2x + x^3 - \frac{(a+2l)(x-l)^3}{a} - \frac{l}{2a^2}(x-l)^4 \right]$	在 $x = l/2$ 处: $q_A = \frac{qa^2l}{12EI}$ $q_B = \frac{-qa^2l}{6EI}$ 在 $x = l+a$ 处: $y_{max} = \frac{-qa^3}{24EI}(3a+4l)$ $q_D = \frac{-qa^2}{6EI}(l+a)$	
13		$F_A = F_B = F$	$0 \leq x \leq a:$ $M(x) = -Fx$ $a \leq x \leq l+a:$ $M = -Fa$	$0 \leq x \leq a:$ $y = \frac{-F}{6EI} [a^2(2a+3l) - 3a \times (a+l)x + x^2]$ $a \leq x \leq l+a:$ $y = \frac{F}{6EI} [3a(a+l)x - a^2 \times (2a+3l) - x^3 + (x-a)^3]$	$y_D = y_E = \frac{-Fa^2(2a+3l)}{6EI}$ 在 $x = a+l/2$ 处: $y_C = \frac{Fal^2}{8EI}$	$q_A = -q_B = \frac{Fal}{2EI}$ $q_E = -q_D = \frac{Fa(l+a)}{2EI}$

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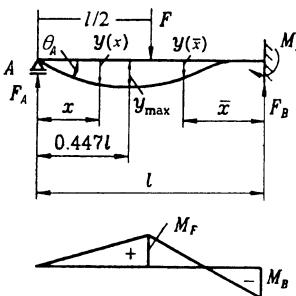
序号	载荷情况及剪力图弯矩图	支点反力	弯矩方程	挠度曲线方程	最大挠度	梁端转角
14		$F_A = F_B = \frac{M}{l}$	$0 \leq x \leq l: M(x) = \frac{M}{l}x$ $l \leq x \leq l+a: M_{\max} = M$	$0 \leq x \leq l: y = \frac{-Ml^2}{6EI} \left[\frac{x}{l} - \frac{x^3}{l^3} \right]$ $l \leq x \leq l+a: y = \frac{M}{6EI} (l-3x)(l-x)$	在 $x = l/2$ 处: $y = \frac{-Ml^2}{16EI}$ $y_D = \frac{M}{6EI} (2la + 3a^2)$	$q_A = \frac{-Ml}{6EI}$ $q_B = \frac{Ml}{3EI}$ $q_D = \frac{M}{3EI} (l + 3a)$
15		$F_A = F$ $M_A = Fl$	$M(x) = F(x-l)$	$y = \frac{-Fl^3}{6EI} \left(\frac{3x^2}{l^2} - \frac{x^3}{l^3} \right)$	在 $x = l$ $y_{\max} = \frac{-Fl^3}{3EI}$	$q_B = \frac{-Fl^2}{2EI}$
16		$M_A = M$	$M(x) = -M$	$y = \frac{-Mx^2}{2EI}$	在 $x = l$ 处: $y_{\max} = \frac{-Ml^2}{2EI}$	$q_B = \frac{-Ml}{EI}$
17		$F_A = ql$ $M_A = \frac{ql^2}{2}$	$M(x) = q \left(lx - \frac{l^2 + x^2}{2} \right)$	$y = \frac{-ql^4}{24EI} \left(\frac{6x^2}{l^2} - \frac{4x^3}{l^3} + \frac{x^4}{l^4} \right)$	在 $x = l$ 处: $y_{\max} = \frac{-ql^4}{8EI}$	$q_B = \frac{-ql^3}{6EI}$

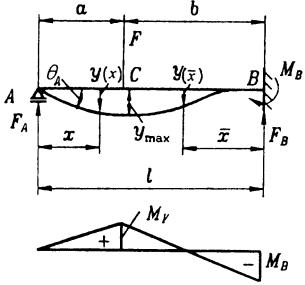
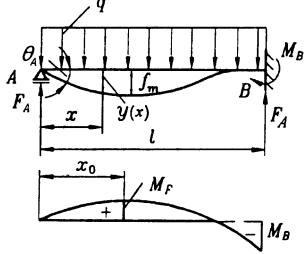
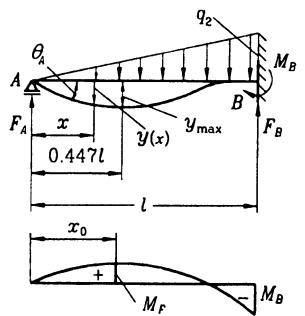
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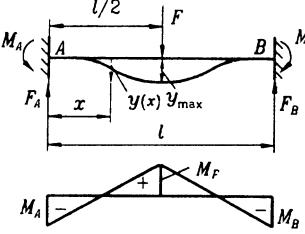
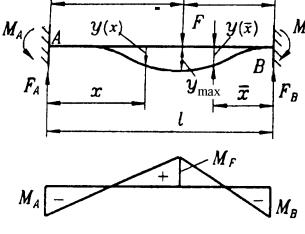
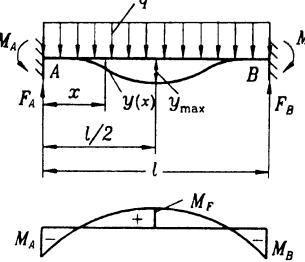
序号	载荷情况及剪力图弯矩图	支点反力	弯矩方程	挠度曲线方程	最大挠度	梁端转角
18		$F_A = \frac{q_0 l}{2}$ $M_A = \frac{q_0 l^2}{6}$	$M(x) = \frac{q_0 l}{6} \left(\frac{3x}{l} - \frac{3x^2}{l^2} + \frac{x^3}{l^3} - 1 \right)$	$y = \frac{-q_0 l^4}{120 EI} \left(\frac{10x^2}{l^2} - \frac{10x^3}{l^3} + \frac{5x^4}{l^4} - \frac{x^5}{l^5} \right)$	在 $x = l$ 处: $y_{\max} = \frac{-q_0 l^4}{30 EI}$	$q_B = \frac{-q_0 l^3}{24 EI}$

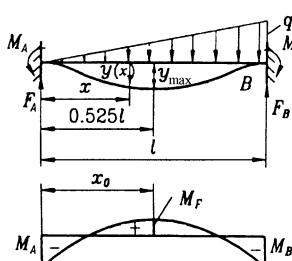
注:式中 x 为从梁左端起量的坐标(参见序号 1.15 图), E 为材料弹性模量, I 为惯性矩.下同。

表 G1-5 静不定梁的支点反力、弯矩和变形计算公式

载荷、挠曲线和弯矩图	支点反力、弯矩	挠度曲线方程	挠度	梁端转角
	$F_A = \frac{5}{16} F, F_B = \frac{11}{16} F$ $M_B = -\frac{3}{16} Fl$ $M_F = \frac{5}{32} Fl$	$0 \leq x \leq l/2:$ $y(x) = \frac{-Fl^3}{96 EI} \left[3\frac{x}{l} - 5\left(\frac{x}{l}\right)^3 \right]$ $0 \leq \bar{x} \leq l/2:$ $y(\bar{x}) = \frac{-Fl^3}{96 EI} \left[9\left(\frac{\bar{x}}{l}\right)^2 - 11\left(\frac{\bar{x}}{l}\right)^3 \right]$	在 $x = 0.447l$ 处: $y_{\max} = \frac{-Fl^3}{48\sqrt{5} EI}$ 在 $x = l/2$ 处: $y = \frac{-7Fl^3}{768 EI}$	$q_A = \frac{Fl^2}{32 EI}$

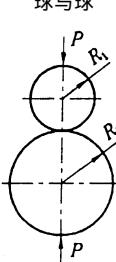
载荷、挠曲线和弯矩图	支点反力、弯矩	挠度曲线方程	挠度	梁端转角
	$F_A = F \left(\frac{b}{l} \right)^2 \left(1 + \frac{a}{2l} \right)$ $F_B = F \left(\frac{a}{l} \right)^2 \left(1 + \frac{b}{2l} + \frac{3b}{2a} \right)$ $M_B = -F \frac{ab}{l} \left(1 - \frac{b}{2l} \right)$ $M_F = F \frac{ab^2}{l^2} \left(1 + \frac{a}{2l} \right)$	$0 \leq x \leq a:$ $y(x) = \frac{-Flb^2}{4EI} \left[\frac{a}{l} \frac{x}{l} - \frac{2}{3} \left(1 + \frac{a}{2l} \right) \left(\frac{x}{l} \right)^3 \right]$ $0 \leq \bar{x} \leq b:$ $y(\bar{x}) = \frac{-Fl^2 a}{4EI} \left[\left(1 - \frac{a^2}{l^2} \right) \left(\frac{\bar{x}}{l} \right)^2 - \left(1 - \frac{a^2}{3l^2} \right) \left(\frac{\bar{x}}{l} \right)^3 \right]$	<p>当 $b = 0.586l$ 时 在 C 截面处:</p> $y_{\max} = -0.0098 \frac{Fl^3}{EI}$ <p>在 $x = a$ 处:</p> $y = \frac{-Fa^2 b^3}{4EI l^2} \left(1 + \frac{a}{3l} \right)$	$q_A = \frac{Fab^2}{4Ell}$
	$F_A = \frac{3}{8} ql, F_B = \frac{5}{8} ql$ $M_B = -\frac{1}{8} ql^2$ $M_F = \frac{9}{128} ql^2$ <p>在 $x_0 = \frac{3}{8} l$</p>	$y(x) = \frac{-ql^4}{48EI} \left[\frac{x}{l} - 3 \left(\frac{x}{l} \right)^3 + 2 \left(\frac{x}{l} \right)^4 \right]$	<p>在 $x = 0.4215l$ 处:</p> $y_{\max} = \frac{-ql^4}{185EI}$	$q_A = \frac{ql^3}{48EI}$
	$F_A = \frac{1}{10} q_2 l, F_B = \frac{4}{10} q_2 l$ $M_B = -\frac{1}{15} q_2 l^2$ $M_F = 0.0298 q_2 l^2$ <p>在 $x_0 = 0.447l$</p>	$y(x) = \frac{-q_2 l^4}{120EI} \left[\frac{x}{l} - 2 \left(\frac{x}{l} \right)^3 + \left(\frac{x}{l} \right)^5 \right]$	<p>在 $x = 0.447l$ 处:</p> $y_{\max} = \frac{-q_2 l^4}{419EI}$	$q_A = \frac{q_2 l^3}{120EI}$

载荷、挠曲线和弯矩图	支点反力、弯矩	挠度曲线方程	挠度	梁端转角
	$F_A = F_B = \frac{1}{2}F$ $M_A = M_B = -\frac{1}{8}Fl$ $M_F = \frac{1}{8}Fl$	$0 \leq x \leq l/2:$ $y(x) = \frac{-Fl^3}{48EI} \left[3\left(\frac{x}{l}\right)^2 - 4\left(\frac{x}{l}\right)^3 \right]$	<p>在 $x = l/2$ 处:</p> $y_{\max} = \frac{-Fl^3}{192EI}$	—
	$F_A = F \left(\frac{b}{l} \right)^2 \left(1 + 2 \frac{a}{l} \right)$ $F_B = F \left(\frac{a}{l} \right)^2 \left(1 + 2 \frac{b}{l} \right)$ $M_A = -Fa \left(\frac{b}{l} \right)^2$ $M_B = -Fb \left(\frac{a}{l} \right)^2$ $M_F = 2Fl \left(\frac{a}{l} \right) \left(\frac{b}{l} \right)^2$	$0 \leq x \leq b:$ $y(x) = \frac{-Flb^2}{6EI} \left[3 \frac{a}{l} \left(\frac{x}{l} \right)^2 - \left(1 + \frac{2a}{l} \right) \left(\frac{x}{l} \right)^3 \right]$ $0 \leq x \leq b:$ $y(\bar{x}) = \frac{-Fla^2}{6EI} \left[3 \frac{b}{l} \left(\frac{\bar{x}}{l} \right)^2 - \left(1 + \frac{2b}{l} \right) \left(\frac{\bar{x}}{l} \right)^3 \right]$	<p>若 $a > b$,</p> <p>在 $x = \frac{2al}{3a+b}$ 处:</p> $y_{\max} = \frac{-2F}{3EI} \frac{a^3b^2}{(3a+b)^2}$ <p>在 $x = a$ 处:</p> $y = \frac{-Fa^3b^3}{3EI l^3}$	—
	$F_A = F_B = \frac{1}{2}ql$ $M_A = M_B = -\frac{1}{12}ql^2$ $M_F = \frac{1}{24}ql^2$	$y(x) = \frac{ql^4}{24EI} \left[\left(\frac{x}{l} \right)^2 - 2\left(\frac{x}{l} \right)^3 + \left(\frac{x}{l} \right)^4 \right]$	<p>在 $x = l/2$ 处:</p> $y_{\max} = \frac{-ql^4}{384EI}$	—

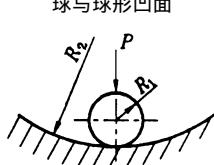
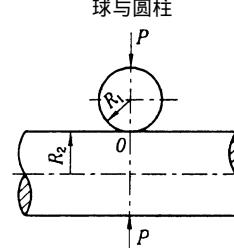
载荷、挠曲线和弯矩图	支点反力、弯矩	挠度曲线方程	挠度	梁端转角
	$F_A = \frac{3}{20} q_2 l$ $F_B = \frac{7}{20} q_2 l$ $M_A = -\frac{1}{30} q_2 l^2$ $M_B = -\frac{1}{20} q_2 l^2$ $M_F = 0.0214 q_2 l^2$ $x_0 = 0.548l$	$y(x) = \frac{q_2 l^4}{120 EI} \left[2\left(\frac{x}{l}\right)^2 - 3\left(\frac{x}{l}\right)^3 + \left(\frac{x}{l}\right)^5 \right]$	在 $x = 0.525l$ 处: $y_{\max} = \frac{-q_2 l^4}{764 EI}$	—

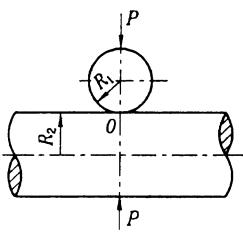
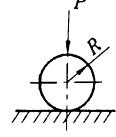
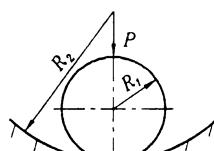
G2.3 常用零件的接触应力和接触变形计算公式 (表 G1-6、表 G1-7)

表 G1-6 常用零件接触应力和接触变形计算公式

接触情况	接触面积尺寸	最大接触应力 σ_{\max}	接触物体靠近位移值 Δ
 球与球	$a = b = 0.9086 \sqrt[3]{P \frac{R_1 R_2}{R_1 + R_2} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$	$0.5784 \sqrt[3]{P \frac{\left(\frac{R_1 + R_2}{R_1 R_2} \right)^2}{\left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}}$	$0.8255 \sqrt[3]{P^2 \frac{R_1 + R_2}{R_1 R_2} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}$
当 $E_1 = E_2 = E$, $\mu_1 = \mu_2 = 0.3$ 时			
	$a = b = 1.109 \sqrt[3]{\frac{P}{E} \frac{R_1 R_2}{R_1 + R_2}}$	$0.388 \sqrt[3]{P E^2 \left(\frac{R_1 + R_2}{R_1 R_2} \right)^2}$ $\tau_{\max} = \sigma_{\max} / 3 \quad \sigma_{1\max} = 0.133 \sigma_{\max}$	$1.231 \sqrt[3]{\left(\frac{P}{E} \right)^2 \frac{R_1 + R_2}{R_1 R_2}}$

(续)

接触情况	接触面积尺寸	最大接触应力 s_{\max}	接触物体靠近位移值 Δ
 球与球形凹面	$a = b = 0.9086 \sqrt[3]{P \frac{R_1 R_2}{R_2 - R_1} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$	$0.5784 \sqrt[3]{P \frac{\left(\frac{R_2 - R_1}{R_1 R_2} \right)^2}{\left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}}$	$0.8255 \sqrt[3]{P^2 \frac{R_2 - R_1}{R_1 R_2} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}$
	当 $E_1 = E_2 = E, \quad m_1 = m_2 = 0.3$ 时		
 球与圆柱	$a = b = 1.109 \sqrt[3]{P \frac{R_1 R_2}{E (R_2 - R_1)}}$	$0.388 \sqrt[3]{P E^2 \left(\frac{R_2 - R_1}{R_1 R_2} \right)^2}$ $\tau_{\max} = \sigma_{\max} / 3 \quad \sigma_{1\max} = 0.133 \sigma_{\max}$	$1.231 \sqrt[3]{\left(\frac{P}{E} \right)^2 \frac{R_2 - R_1}{R_1 R_2}}$
	$a = 1.145 n_a \sqrt[3]{P \frac{R_1 R_2}{2R_2 + R_1} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$ $b = 1.145 n_b \sqrt[3]{P \frac{R_1 R_2}{2R_2 + R_1} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$ $A = \frac{1}{2R_1} \quad B = \frac{1}{2} \left(\frac{1}{R_1} + \frac{1}{R_2} \right)$	$0.365 n_{\sigma} \sqrt[3]{P \frac{\left(\frac{2R_2 + R_1}{R_1 R_2} \right)^2}{\left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}}$	$0.655 n_{\delta} \sqrt[3]{P^2 \frac{2R_2 + R_1}{R_1 R_2} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}$
当 $E_1 = E_2 = E, \quad m_1 = m_2 = 0.3$ 时			

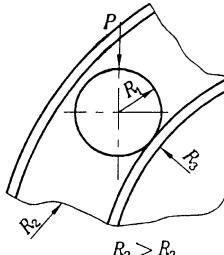
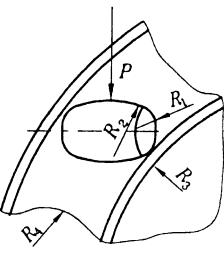
接触情况	接触面积尺寸	最大接触应力 s_{\max}	接触物体靠近位移值 Δ
球与圆柱	 $a = 1.397 n_a \sqrt[3]{\frac{P}{E} \frac{R_1 R_2}{2R_2 + R_1}}$ $b = 1.397 n_b \sqrt[3]{\frac{P}{E} \frac{R_1 R_2}{2R_2 + R_1}}$	$0.245 n_{\sigma} \sqrt[3]{P E^2 \left(\frac{2R_2 + R_1}{R_1 R_2} \right)^2}$	$0.977 n_{\delta} \sqrt[3]{\left(\frac{P}{E} \right)^2 \frac{2R_2 + R_1}{R_1 R_2}}$
球与平面	 $a = b = 0.9086 \sqrt[3]{P R \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$	$0.5784 \sqrt[3]{\frac{P}{R^2 \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}}$	$0.8255 \sqrt[3]{\frac{P^2}{R} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}$
	当 $E_1 = E_2 = E, \quad m_1 = m_2 = 0.3$ 时		
	$a = b = 1.109 \sqrt[3]{\frac{P}{E} R}$	$0.388 \sqrt[3]{P E^2 \frac{1}{R^2}}$ $\tau_{\max} = \sigma_{\max} / 3 \quad \sigma_{1\max} = 0.133 \sigma_{\max}$	$1.231 \sqrt[3]{\left(\frac{P}{E} \right)^2 \frac{1}{R}}$
球与圆柱凹面	 $a = 1.145 n_a \sqrt[3]{P \frac{R_1 R_2}{2R_2 - R_1} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$ $b = 1.145 n_b \sqrt[3]{P \frac{R_1 R_2}{2R_2 - R_1} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$ $A = \frac{1}{2} \left(\frac{1}{R_1} - \frac{1}{R_2} \right) \quad B = \frac{1}{2R_1}$	$0.365 n_{\sigma} \sqrt[3]{P \frac{\left(\frac{2R_2 - R_1}{R_1 R_2} \right)^2}{\left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}}$	$0.655 n_{\delta} \sqrt[3]{P^2 \frac{2R_2 - R_1}{R_1 R_2} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}$

(续)

接触情况	接触面积尺寸	最大接触应力 s_{\max}	接触物体靠近位移值 Δ
球与圆柱凹面	当 $E_1 = E_2 = E, m_1 = m_2 = 0.3$ 时		
	$a = 1.397 n_a \sqrt[3]{\frac{P}{E} \frac{R_1 R_2}{2R_2 - R_1}}$ $b = 1.397 n_b \sqrt[3]{\frac{P}{E} \frac{R_1 R_2}{2R_2 - R_1}}$	$0.245 n_{\sigma} \sqrt[3]{P E^2 \left(\frac{2R_2 - R_1}{R_1 R_2} \right)^2}$	$0.977 n_{\delta} \sqrt[3]{\left(\frac{P}{E} \right)^2 \frac{2R_2 - R_1}{R_1 R_2}}$
平行圆柱	接触带半宽		
	$b = 1.128 \sqrt{\frac{P}{l E} \frac{R_1 R_2}{R_1 + R_2} \left(\frac{1 - m_1^2}{E_1} + \frac{1 - m_2^2}{E_2} \right)}$	$0.5642 \sqrt{\frac{P}{l} \frac{\frac{R_1 + R_2}{R_1 R_2}}{\frac{1 - m_1^2}{E_1} + \frac{1 - m_2^2}{E_2}}}$	$\frac{2P}{pl} \left[\frac{1 - m_1^2}{E_1} \left(\ln \frac{2R_1}{b} + 0.407 \right) + \frac{1 - m_2^2}{E_2} \left(\ln \frac{2R_2}{b} + 0.407 \right) \right]$
当 $E_1 = E_2 = E, m_1 = m_2 = 0.3$ 时			
	$b = 1.522 \sqrt{\frac{P}{l E} \frac{R_1 R_2}{R_1 + R_2}}$	$0.418 \sqrt{\frac{P E}{l} \frac{R_1 + R_2}{R_1 R_2}}$	$0.5796 \frac{P}{l E} \left(\ln \frac{4R_1 R_2}{b^2} + 0.814 \right)$
圆柱与轴线平行的圆柱槽	接触带半宽		
	$b = 1.128 \sqrt{\frac{P}{l} \frac{R_1 R_2}{R_2 - R_1} \left(\frac{1 - m_1^2}{E_1} + \frac{1 - m_2^2}{E_2} \right)}$	$0.5642 \sqrt{\frac{P}{l} \frac{\frac{R_2 - R_1}{R_1 R_2}}{\frac{1 - m_1^2}{E_1} + \frac{1 - m_2^2}{E_2}}}$	
当 $E_1 = E_2 = E, m_1 = m_2 = 0.3$ 时			
	$b = 1.522 \sqrt{\frac{P}{l E} \frac{R_1 R_2}{R_2 - R_1}}$	$0.418 \sqrt{\frac{P E}{l} \frac{R_2 - R_1}{R_1 R_2}}$	$1.82 \frac{P}{l E} (1 - \ln b)$

接触情况	接触面积尺寸	最大接触应力 s_{\max}	接触物体靠近位移值 Δ
圆柱与平面	<p>接触带半宽</p> $b = 1.128 \sqrt{\frac{PR}{l} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$	$0.5642 \sqrt{\frac{\frac{P}{lR}}{\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2}}}$	
	当 $E_1 = E_2 = E, \mu_1 = \mu_2 = 0.3$ 时		
	$b = 1.522 \sqrt{\frac{PR}{lE}}$	$0.418 \sqrt{\frac{PE}{lR}}$ $t_{\max} = 0.301s_{\max}$	在两挤压面间圆柱直径的减小 $\Delta D = 1.159 \frac{P}{lE} \left(0.41 + \ln \frac{4R}{b} \right)$
垂直圆柱	$a = 1.145n_a \sqrt[3]{P \frac{R_1 R_2}{R_2 + R_1} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$ $b = 1.145n_b \sqrt[3]{P \frac{R_1 R_2}{R_2 + R_1} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)}$ $A = \frac{1}{2R_2}, B = \frac{1}{2R_1}$	$0.365n_{\sigma} \sqrt[3]{P \frac{\left(\frac{R_2 + R_1}{R_1 R_2} \right)^2}{\left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}}$	$0.655n_{\delta} \sqrt[3]{P^2 \frac{R_2 + R_1}{R_1 R_2} \left(\frac{1 - \mu_1^2}{E_1} + \frac{1 - \mu_2^2}{E_2} \right)^2}$
	当 $E_1 = E_2 = E, \mu_1 = \mu_2 = 0.3$ 时		
	$a = 1.397n_a \sqrt[3]{\frac{P}{E} \frac{R_1 R_2}{R_2 + R_1}}$ $b = 1.397n_b \sqrt[3]{\frac{P}{E} \frac{R_1 R_2}{R_2 + R_1}}$	$0.245n_{\sigma} \sqrt[3]{P E^2 \left(\frac{R_2 + R_1}{R_1 R_2} \right)^2}$	$0.977n_{\delta} \sqrt[3]{\left(\frac{P}{E} \right)^2 \frac{R_2 + R_1}{R_1 R_2}}$

(续)

接触情况	接触面积尺寸	最大接触应力 s_{\max}	接触物体靠近位移值 Δ
球与圆弧槽 (滚珠轴承)	 $a = 1.145 n_a \sqrt[3]{P \frac{\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2}}{\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3}}}$ $b = 1.145 n_b \sqrt[3]{P \frac{\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2}}{\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3}}}$ $\sigma_{\max} = 0.365 n_{\sigma} \sqrt[3]{P \frac{\left(\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3}\right)^2}{\left(\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2}\right)^2}}$	$A = \frac{1}{2} \left(\frac{1}{R_1} - \frac{1}{R_2} \right) \quad B = \frac{1}{2} \left(\frac{1}{R_1} + \frac{1}{R_3} \right)$ 当 $E_1 = E_2 = E, \mu_1 = \mu_2 = 0.3$ 时 $a = 1.397 n_a \sqrt[3]{\frac{P}{E} \frac{1}{\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3}}}$ $b = 1.397 n_b \sqrt[3]{\frac{P}{E} \frac{1}{\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3}}}$ $\sigma_{\max} = 0.245 n_{\sigma} \sqrt[3]{P E^2 \left(\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3} \right)^2}$	$0.655 n_{\delta} \sqrt[3]{P^2 \left(\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2} \right)^2} \times \sqrt[3]{\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3}}$ 当 $E_1 = E_2 = E, \mu_1 = \mu_2 = 0.3$ 时 $\Delta = 0.977 n_{\delta} \sqrt[3]{\left(\frac{P}{E} \right)^2 \left(\frac{2}{R_1} - \frac{1}{R_2} + \frac{1}{R_3} \right)^2}$
滚柱轴承	 $a = 1.145 n_a \sqrt[3]{P \frac{\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2}}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4}}}$ $b = 1.145 n_b \sqrt[3]{P \frac{\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2}}{\frac{1}{R_1} - \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4}}}$ $\sigma_{\max} = 0.365 n_{\sigma} \sqrt[3]{P \frac{\left(\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4}\right)^2}{\left(\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2}\right)^2}}$	$A = \left(\frac{1}{R_2} - \frac{1}{R_4} \right) \quad B = \frac{1}{2} \left(\frac{1}{R_1} + \frac{1}{R_3} \right)$ 当 $E_1 = E_2 = E, \mu_1 = \mu_2 = 0.3$ 时 $a = 1.397 n_a \sqrt[3]{\frac{P}{E} \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4}}}$ $b = 1.397 n_b \sqrt[3]{\frac{P}{E} \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4}}}$ $\sigma_{\max} = 0.245 n_{\sigma} \times \sqrt[3]{P E^2 \left(\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4} \right)^2}$	$0.655 n_{\delta} \sqrt[3]{P^2 \left(\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4} \right)^2} \times \sqrt[3]{\frac{1-\mu_1^2}{E_1} + \frac{1-\mu_2^2}{E_2}}$ 当 $E_1 = E_2 = E, \mu_1 = \mu_2 = 0.3$ 时 $\Delta = 0.977 n_{\delta} \times \sqrt[3]{\left(\frac{P}{E} \right)^2 \left(\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} - \frac{1}{R_4} \right)^2}$

注: 1. a —接触时接触面的椭圆长半轴; b —一点接触时接触面的椭圆短半轴, 线接触时接触面的半宽度; $s_{1\max}$ —最大拉应力。

2. A, B —椭圆方程系数; n_a, n_b, n_s, n_d —接触问题的系数, 见表 G1-7。

3. E, m —分别为材料的弹性模量和泊松比。

表 G1-7 接触问题的系数 n_a , n_b , n_o , n

$\frac{A}{B}$	n_a	n_b	n_s	n_d	$\frac{A}{B}$	n_a	n_b	n_s	n_d
1.0000	1.0000	1.0000	1.0000	1.0000	0.1739	1.916	0.6059	0.8614	0.8566
0.9623	1.013	0.9873	0.9999	0.9999	0.1603	1.979	0.5938	0.8504	0.8451
0.9240	1.027	0.9472	0.9997	0.9997	0.1462	2.053	0.5808	0.8386	0.8320
0.8852	1.042	0.9606	0.9992	0.9992	0.1317	2.141	0.5665	0.8246	0.8168
0.8459	1.058	0.9465	0.9985	0.9985	0.1166	2.248	0.5505	0.8082	0.7990
0.8059	1.076	0.9318	0.9974	0.9974	0.1010	2.381	0.5325	0.7887	0.7775
0.7652	1.095	0.9165	0.9960	0.9960	0.09287	2.463	0.5224	0.7774	0.7650
0.7238	1.117	0.9005	0.9942	0.9942	0.08456	2.557	0.5114	0.7647	0.7509
0.6816	1.141	0.8837	0.9919	0.9919	0.07600	2.669	0.4993	0.7504	0.7349
0.6384	1.168	0.8660	0.9890	0.9889	0.06715	2.805	0.4858	0.7338	0.7163
0.5942	1.198	0.8472	0.9853	0.9852	0.05797	2.975	0.4704	0.7144	0.6943
0.5489	1.233	0.8271	0.9805	0.9804	0.04838	3.199	0.4524	0.6909	0.6675
0.5022	1.274	0.8056	0.9746	0.9744	0.04639	3.253	0.4484	0.6856	0.6613
0.4540	1.322	0.7822	0.9669	0.9667	0.04439	3.311	0.4442	0.6799	0.6549
0.4040	1.381	0.7565	0.9571	0.9566	0.04237	3.373	0.4398	0.6740	0.6481
0.3518	1.456	0.7278	0.9440	0.9432	0.04032	3.441	0.4352	0.6678	0.6409
0.3410	1.473	0.7216	0.9409	0.9400	0.03823	3.514	0.4304	0.6612	0.6333
0.3301	1.491	0.7152	0.9376	0.9366	0.03613	3.594	0.4253	0.6542	0.6251
0.3191	1.511	0.7086	0.9340	0.9329	0.03400	3.683	0.4199	0.6467	0.6164
0.3080	1.532	0.7019	0.9302	0.9290	0.03183	3.781	0.4142	0.6387	0.6071
0.2967	1.554	0.6949	0.9262	0.9248	0.02962	3.890	0.4080	0.6300	0.5970
0.2853	1.578	0.6876	0.9219	0.9203	0.02737	4.014	0.4014	0.6206	0.5860
0.2738	1.603	0.6801	0.9172	0.9155	0.02508	4.156	0.3942	0.6104	0.5741
0.2620	1.631	0.6723	0.9121	0.9102	0.02273	4.320	0.3864	0.5990	0.5608
0.2501	1.660	0.6642	0.9067	0.9045	0.02033	4.515	0.3777	0.5864	0.5460
0.2380	1.693	0.6557	0.9008	0.8983	0.01787	4.750	0.3680	0.5721	0.5292
0.2257	1.729	0.6468	0.8944	0.8916	0.01533	5.046	0.3568	0.5555	0.5096
0.2132	1.768	0.6374	0.8873	0.8841	0.01269	5.432	0.3436	0.5358	0.4864
0.2004	1.812	0.6276	0.8766	0.8759	0.009934	5.976	0.3273	0.5112	0.4574
0.1873	1.861	0.6171	0.8710	0.8668	0.007018	6.837	0.3058	0.4783	0.4186
					0.003850	8.609	0.2722	0.4267	0.3579