

Quantum Physics At Any Cost Yury Deshko www.srelim.com ISBN 978-1-7948-2018-0 Copyright © 2025



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Which Gave Me Everything and More:
A Shelter, Opportunities and Inspiration,
And The Desire To Explore



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My friends, discussing the book with you was both illuminating and fun.

Finally, special acknowledgment must be given to my son, Daniel, for his help with fixing colors in many figures.

Yury Deshko Weehawken, New Jersey 2024



Preface

This book is the result of lectures delivered to curious, motivated, and studious high schoolers. The lectures ran during the years 2019-2024 in various formats, but mostly in class during a three week summer school organized by Columbia University Pre-College Programs. Additionally, the same lectures were taught remotely to selected students of Ukrainian Physics and Mathematics Lyceum.

The material has been designed to be accessible to people with solid background in high-school algebra and physics (mostly mechanics). Several years of teaching to a relatively diverse set of students proved that nearly all material can be efficiently absorbed by most, provided diligent work is done on exercises and problem. The last fact confirms a well-known truism: *No real learning occurs without practice*.

Exercises are essential part of this book. They are carefully selected to help readers get better understanding of the material and they are also fully solved. The difficulty of the exercises varies from simple to quite challenging.

This book *is not a standard textbook*. It differs from many excellent introductions into Quantum Physics in that it lacks the breadth and rigor

of the latter. However, this book serves a special purpose: It tries to act as the *bridge* between elementary and popular books and the more challenging college-level textbooks.

If a picture is worth a thousand words, then a formula is worth a couple of hundred words. This book contains pictures and formulas aplenty. Hopefully, the readers for whom this book is intended will enjoy both.

Some sections are marked with an asterisk, for example **Transposition***. Those sections contain material that is either optional or a bit more advanced that usual. These sections can be skipped without significant impact on the main message of the book.

At Any Cost

The subtitle of this book has been inspired by the letter from Max Karl Ernst Ludwig Planck to an American physicist Robert Williams Wood. Describing his desperate attempts to explain the experimental results on the electromagnetic radiation from hot materials, Max Planck wrote¹ (italics are mine):

Max Planck to Robert Wood

A theoretical interpretation therefore had to be found *at any cost*, no matter how high. It was clear to me that classical physics could offer no solution to this problem, and would have meant that all energy would eventually transfer from matter to radiation. ...This approach was opened to me by maintaining the two laws of thermodynamics. The two laws, it seems to me, must be upheld under all circumstances. For the rest, I was ready to sacrifice every one of my previous convictions about physical laws. ...[One] finds that the continuous loss of energy into radiation can be prevented by assuming that energy is forced at the outset to remain together in certain quanta. This was purely a formal assumption and I really did not give it much thought except that *no matter what the cost, I must bring about a positive result*.

Trying to provide a theoretical explanation at any cost, Max Planck introduced the idea of energy quanta, initiating the development of quantum ideas and becoming "the father of quantum physics."

¹Source!



1. Introduction

This quantum business is so incredibly important and difficult that everyone should busy himself with it.

A. Einstein in a letter to his friend Jakob Laub in 1908, as quoted by A. Wheeler in "The Mystery and The Message Of The Quantum"

Abstract In this chapter.

UANTUM PHYSICS IS A CENTURY-OLD BRANCH OF PHYSICS. ITS SUCCESS is unparalleled and yet quantum physics is unfinished in one sense: There is no clear and widely adopted consensus on what some of quantum ideas "really mean."

1.1 What Is Quantum Physics?

There are many characterizations of quantum physics. In essence, quantum physics is the part of physics which focuses on *quantum systems* – physical systems showing quantum behavior.

1.2 Brief Historical Context

The year 1900 is usually considered the birth year of quantum physics. On December 14 of 1900, at the meeting ????, the German physicist Max Karl Ernst Ludwig Planck presented his theoretical explanation of the spectrum of electromagnetic radiation emitted by hot bodies.

1802

1.2.1 Three Ages of Quantum

The evolution of quantum science and technology can be roughly divided into three stages: "Old quantum physics", modern quantum physics, and information-age quantum physics.

Old Quantum Physics Modern Quantum Physics Information Age

1.3 Who Needs Quantum Physics?

In October of 1912, Albert Einstein wrote in a letter to his physicist friend Arnold Sommerfeld:

Example of mybio environment

I am now exclusively occupied with the problem of gravitation theory and hope, with the help of a local mathematician friend, to overcome all the difficulties. One thing is certain, however, that never in my life have I been quite so tormented. A great respect for mathematics has been instilled within me, the subtler aspects of which, in my stupidity, I regarded until now as a pure luxury. Against this problem [of gravitation] the original problem of the theory of relativity is child's play.

In the period from 1905 to 1916 Einstein was feverishly working on the General Theory of Relativity – the next best theory of gravity since Newton. The mathematics of general relativity is based on the calculus of tensors, created by Italian mathematicians Ricci-Curbastro and Levi-Civita roughly a decade before Einstein started working on the problem of gravity.

1.4 Why is Quantum Physics Hard?

Now what are tensors more rigorously? Can we give a short definition to this concept? Let us take a look at several examples and see whether they shed sufficient light. The definitions given below differ from each other, but they simply convey *the same idea in different ways*. sectionChallenges To illustrate the concepts of functions, operators, their structures and properties, we will be using schematics like the one

1.4.1 Mathematics

To illustrate the concepts of functions, operators, their structures and properties, we will be using

1.4.2 Language

To illustrate the concepts of functions, operators, their structures and properties, we will be using schematics like the one

The Encyclopedia of Mathematics ¹ provides the following definition:

Definition 1.1 C Example of mydef environment

Tensor on a vector space V over a field k is an element t of the vector space

$$T^{p,q}(V) = (\otimes^p V) \otimes (\otimes^q V^*),$$

where $V^* = \text{Hom}(V, k)$ is the dual space of V.

To understand this defintion we first need to understand what *vector* space is, what *field* is, what *dual* means, and what is going on with superscripts and circles (e.g., in \otimes^q).

1.4.3 Concepts

To illustrate the concepts of functions, operators, their structures and properties, we will be using schematics like the one

1.5 Quantum Versus Classical

Sometimes to illustrate mathematical concepts and *relations between them*, we will use diagrams. Diagrams are helpful in highlighting some general features of *mathematical structures*.

A particular property of a car-point can then be represented using an arrow that connects the car-point to another point in the relevant set. We say that such an arrow *maps* points of one set into another set. The Figure 1.1(b) shows three maps: **mlg** gives the mileage for each car from the set Λ , **clr** gives the color for each car, and **smk** compares whether two cars have the same make.

Exercise 1.1

Extend the diagram from the Figure 1.1(b), adding a set of different car makes (e.g., Ford, Toyota, Fiat, etc.) Come up with a mapping from this set into the Boolean set B.

https://encyclopediaofmath.org/wiki/Tensor_on_a_
vector_space

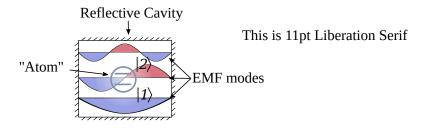


Fig. 1.1: Diagrams are used to graphically represent sets of objects and relationships between them. Arrows can connect (map) elements of one set with another. Such mappings may have names: **mlg** returns mileage for a given car, **clr** – color, and **smk** determines whether two cars are of the same make.

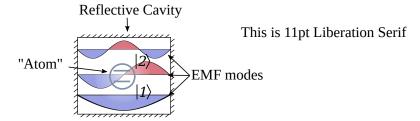
1.6 Quantum Puzzle

To illustrate the concepts of functions, operators, their structures and properties, we will be using schematics like the one shown in the Figure 1.2.

A simple schematic element is represented as a box with inputs and outputs. A box can have a name (label) which describes what the function does to its input. The number of inputs and outputs can vary depending on the complexity of a function.

Chapter Highlights

- Natural evolution of mathematical objects from numbers, through vectors, leads to tensors.
- Each successive tier of mathematical object in the progression "numbers, vectors, tensors" is more abstract and more powerful.
- Numbers, vectors, and tensors are all conceptually connected.



Schematics can be used to represent functions, operators, their compositions and struc-

ture.

Fig. 1.2:



2. Physics

Numbers are powerful mathematical objects. They are used to solve an endless list of problems that involve *quantities*. As mathematics and sciences progressed, natural numbers evolved into whole numbers, then into rational numbers and beyond.¹

✓ Prerequisite Knowledge

To fully understand the material of this chapter, readers should be comfortable with the following concepts:

- State
- Dynamical equations

2.1 Goals and Methods

Physics is a *human* activity pursuing the following major goals: *Describe*, *explain*, and *predict* phenomena comprising the observed world.

results can be applied in a wide range of fields. In part, the universality of mathematics stems from the *general* and *abstract* nature of mathematical concepts. Let us illustrate this using an example.

An astute farmer notices that 49 sacks of grains can be arranged in a square with each side having 7 sacks (see the Figure 2.1). When one sack is used up, the remaining 48 sacks can be arranged as a rectangle 6 by 8 sacks.

Exercise 2.1

Think how you would represent the generalized relations of the types

¹A superb account of this process is given in the book "Number: The Language of Science" by Tobias Dantzig.

49 objects can be arranged in a square 7x7. 48 objects

can be

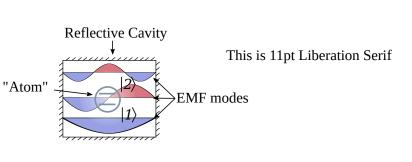
arranged

as

a

rectangle of 6x8.

Fig. 2.1:



2.2 Common Sense 21

given in the Figure ?? at the level of sets? What kind of diagrams would you draw?

2.2 Common Sense

Mathematics is a remarkably effective and universal discipline, its methods and results can be applied in a wide range of fields.

2.2.1 Detached Observer

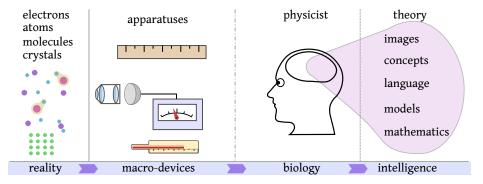


Fig. 2.2: Observers in classical view of the world are detached, separated from the "true" reality which they try to comprehend.

2.3 Deterministic Evolution

The completeness of a state is a very strong constraint. Not only it means "everything there is to know at a given moment", but also "know state now – know state always." The latter is an expression of *determinism*: the complete knowledge of a system is fully determined at all times once an initial state is known. However, state by itself is not sufficient to satisfy the latter requirement, it must be supplemented by the so called *dynamical equations*. These equations are specific to a physical system and encapsulate the laws that govern internal interactions. EXAMPLE?

Denoting the mathematical representation of the state as ξ , the evolution of the state between the moments of time T = t and T = t + Δt may be written as a functional dependence:

$$\xi_{t+\Delta t}$$
 = $U_{t+\Delta t,t} \, \xi_t$.

For $\Delta t > 0$ we determine the future state, while for $\Delta t < 0$ we determine the state in the past (relative to the moment t).

© Example

For circular motion the state is the angle $\xi = \phi$, and the evolution is given by a simple formula

$$\phi_{t+\Delta t} = U_{t+\Delta t,t} \, \phi_t = \omega \Delta t + \phi_t \, .$$

Notice that in this case the evolution function depends on the time difference Δt and not on each moment of time separately:

$$U_{t+\Delta t,t} = U_{\Delta t}$$
 .

It must be emphasized again, that the final state $\xi_f = \xi_{t+\Delta t}$ is determined by two factors: the initial state $\xi_i = \xi_t$ and the laws of physics encoded in the evolution function $U_{t+\Delta t,t}$.

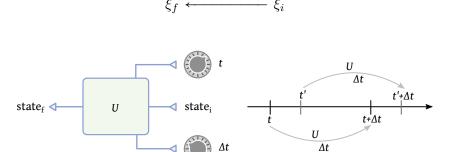


Fig. 2.3: Evolution operator transforms an initial state into the final state in time Δt .

The laws of physics are timeless², as illustrated by the Coulomb's law for the force between charges q and Q at a distance r apart: $F_C = kqQ/r^2$. The timeless nature of the physical laws requires that the same initial state ξ_i evolves into the same final state ξ_f regardless of when the evolution starts as long as the time interval between the beginning and the end of

²Technical term is *time-translation invariant*.

evolution is the same. Mathematically this is expressed as follows:

$$U_{\tau,t}\,\xi_i = U_{\tau',t'}\,\xi_i$$

for any initial state ξ_i , as long as $\tau' - t' = \tau - t = \Delta t$.

Thus, for any values of t and t', we have

$$U_{t+\Delta t,t} = U_{t'+\Delta t,t'}$$
.

This equation says that the evolution function U becomes insensitive to the values t and t', and only depends on Δt – the time interval between the beginning and the end of evolution. Therefore, we can write the following connection between the states at different moments:

$$\xi_{t+\Delta t} = U_{\Delta t} \, \xi_t \, .$$

This connection holds for any moment of time t and time interval Δt .

In physics the states are represented using numbers, vectors, functions, and similar mathematical objects. Common to all of these types of objects is a very basic property of "additivity" and "scalability". That is, one can – at least formally – add and subtract states, as well as multiply them by numbers. For example, for any two states ξ_1 and ξ_2 , one can write equations like

$$\xi_3 = 2\xi_1 + 3\xi_2$$
 or $\Delta \xi = \xi_2 - \xi_1$.

Depending on a particular representation of the state, the evolution function U might be a "usual" function, an operator, or something else entirely. Regardless of what the exact type of U is, its job is always the same – map initial state ξ_i at time t into the final state ξ_f at time $t+\Delta t$.

For Δt = 0 the evolution function U must be a simple *identity* function:

$$U_0 = I$$
.

Furthermore, for a continuous evolution, it is necessary for small changes in time δt to produce small changes in the state $\delta \xi$:

$$\xi_{t+\delta t} = U_{\delta t} \xi_t = \xi_t + \delta \xi \; .$$

For a continuous evolution of the state, the evolution function U must be continuous. This implies that for small time intervals it produces small

changes:

$$U_{\delta t} \approx I + \delta U = I + G \delta t$$
,

where G is called the *generator* of state evolution. The meaning of the generator is clear from its definition – it specifies how fast the state evolution happens: $G = \partial_t U$.

In terms of the generator, the evolution equation can be written using the relations

$$\delta \xi = \xi_{t+\delta t} - \xi_t = (I + G\delta t) \xi_t - \xi_t = G\delta t \xi_t.$$

Finally, dividing both sides by δt and using the ∂ -notation, we arrive at the Schrodinger-type of equation for the *continuous* state evolution:

$$\partial_t \xi = G \, \xi_t \,. \tag{2.1}$$

The equation (2.1) is a general form of state evolution equations used in physics. It appears in many cases where the dynamics of a system is described as a *continuous deterministic evolution*.

Deterministic Evolution Equations

Equations similar to (2.1) can be found in many physical theories. In quantum theory it is Schrodinger equation, which can be written as follows:

$$\partial_t |\Psi\rangle = -i\hat{H} |\Psi\rangle$$
.

2.4 Classical and Quantum

Mathematics is a remarkably effective and universal discipline, its methods and results can be applied in a wide range of fields.

2.5 State

State is a very important concept in physics. It means *complete* but *minimal* knowledge about possible behavior of a given system. By *minimal* knowledge we mean that if position of particle x is known, there is no need to know x^3 or any other one-to-one function of position. We only need to know and keep track of the *essential* information.

2.6 Measurement 25



Fig. 2.4: State is a minimal and complete knowledge about a physical system.

2.6 Measurement

Measurement is the source of our knowledge about the world. This is true for both classical and quantum physics.



Fig. 2.5: Three stages of measurement process: Preparation of a system in a certain state, followed by the interaction of the system with external system, ending with the measurement which extract the information.

2.7 Atoms

Classical physics predicts a continuous decay of unstable configuration of charges. What is observed is a spontaneous decay of stable configuration of charges. Quantum physics elegantly explains the latter.

2.8 Particles

Classical physics predicts a continuous decay of unstable configuration of charges. What is observed is a spontaneous decay of stable configuration of charges. Quantum physics elegantly explains the latter.

2.9 Polarization and Spin

Mathematics is a remarkably effective and universal discipline, its methods and results can be applied in a wide range of fields.

Chapter Highlights

- The power of mathematical concepts and methods increases with the level of abstraction.
- Learning new concepts often involves learning new terminology. The latter can create an artificial mental barrier.
- "Usual" numbers form a mathematical structure. The structure is revealed through various relations that exist between numbers.
- Relations between numbers are expressed using the concept of functions and operations (e.g., addition). Each operation is characterized by its arity – the number of arguments it accepts as an input.



3. Mathematics

In the previous chapter we learned about numbers and various relations between them. As a particular class of relations we discussed functions. We introduced *binary* and *unary* functions and different ways functions can be combined (*composed*) to produce new functions. We also learned that functions can be represented in various ways and that none of those different representations defines the concept of function completely. Each representation of a function highlighted some important aspect of it.

✓ Prerequisite Knowledge

To fully understand the material of this chapter, readers should be comfortable with the following concepts:

- State
- · Dynamical equations

3.1 Arrows

To arrive at the idea of vectors we will start with simple geometrical objects – arrows in a plane, as illustrated in the Figure 3.1.

Symbolically, we will denote vectors by placing an arrow over letters:

$$\vec{a}$$
, \vec{b} , \vec{c} ,..., $\vec{\alpha}$, $\vec{\beta}$.

3.1.1 Dirac Notation

3.2 Scalar Product

To arrive at the idea of vectors we will start with simple geometrical objects – arrows in a plane, as illustrated in the Figure 3.1.

Set of arrows starting at the same origin point O.

All imagin-able arrows taken

as one

set form

the

arrow

 $\overset{\text{space}}{\underset{A}{\Rightarrow}}$

Fig. 3.1:

Reflective Cavity

This is 11pt Liberation Serif

"Atom"

EMF modes

3.3 Operators 29

3.3 Operators

To arrive at the idea of vectors we will start with simple geometrical objects – arrows in a plane.

$$\langle \phi | \phi \rangle$$

and

$$|\phi\rangle\langle\phi|$$
.

3.3.1 Super-operators

3.4 Functionals

Another important type of function is called *functional*. A functional maps a function into a number. Let's consider several examples.

Total Mass

Suppose an astrophysicist is trying to model a spherically symmetric star and calculates *density* of the star as the function of distance from its center: $r \to \rho_r$. The total mass of the star can then be evaluated as the sum of masses of all spherical shells with thickness δr :

$$M = \int \delta V \rho_r = \int 4\pi r^2 \delta r \rho_r .$$

For a given function ρ_r this summation will result in a number – star's total mass. Such mapping $\rho_r \to M$ is an example of a functional.

Total Fuel

Consider a car moving on a straight highway between two points A and B. The amount of fuel the engine consumes at a given moment depends on the speed of the car at that moment and can be described by the function μ_v . Suppose the position of the car as the function of time x_t is known and are looking for the total fuel consumed during the travel. This can be done in three steps.

First, we find the speed of the car as the function of time by applying the operator ∂_t to x_t : $v_t = \partial_t x$. Second, we find the fuel consuption rate μ as the function of time by plugging v_t into μ_v : $f_t = \mu(v_t)$. Finally, we can find the total amount of consumed fuel as the sum

$$F = \int f_t \delta t$$
.

Combining all three steps into a single mathematical expression will

result in a more cumbersome formula:

$$F = \int \delta t \mu(\partial_t x).$$

This formula encodes a recipe for mapping any function x_t into a number F – an example of a functional.

Total Action

A body in a "freely fall" is moving with constant acceleration due to the force of gravity. Its speed increases as the body approaches the ground. If the body starts at rest at height H, its position along the vertical y axis depends on time as $y_t = H - gt^2/2$ and the velocity changes according to the equation v = -gt.

The potential energy $E_p = mgy$ of the body decreases, while its kinetic energy $E_k = mv^2/2$ grows. The total mechanical energy $E = E_p + E_k$ remains fixed according to the law of energy conservation. Thus, the potential energy of the body is transformed into the kinetic energy.

Another physical quantity is often important – the *imbalance* of kinetic energy over the potential energy:

$$L = E_k - E_p.$$

It does not remain constant, and for the case of a free fall we can easily find its time dependence:

$$L_t = mg^2t^2 - mgH \,.$$

Given L_t , we can calculate a fundamental physical quantity – total *action* of the process:

$$A = \int \delta t L_t$$
.

The summation extends to the moment t = T when the body reaches the ground (y = 0). This happens at $T = \sqrt{2H/g}$.

Performing the summation requires evaluation of two familiar sums:

$$\int t^2 \delta t = \frac{T^3}{3} \quad \text{and} \quad \int \delta t = T.$$

Substituting the values of T and simplifying, the expression for the total

3.4 Functionals 31

action takes the form

$$A = mgT(\frac{gT^2}{3} - H) = -\frac{mH}{3}\sqrt{2gH} = -\frac{mv_mH}{3}.$$

Here we used $v_m = gT = \sqrt{2Hg}$ – the maximal speed of the body at the end of the free fall process. Finally, denoting the maximum momentum of the body as $p_m = mv_m$, we obtain $A = -p_mH/3$. Note that the action can be expressed as the product of momentum and distance.

Action is a physical quantit of fundamental importance. It plays a prominent role in both classical mechanics (the principle of *stationary action*) and in quantum physics (the principle of *action quantization*). Both principles will be explored in details later in the book.

Exercise 3.1

Calculate the total action of a free fall process for an electron falling from the height 0.1 meter.

Assorted Examples

Examples of functionals given above involve evaluation of sums in order to find *total quantities* of various kinds:

$$Q = \int \delta x f_x$$
.

The total quantity Q depends on the behavior of the input function f_x over an extended range of x values. Simpler forms of functionals can also be used. For example:

$$\mathcal{M} f = f_0$$

returns the value of the input function f_x at zero. This functional, despite its trivial look, is very useful and widely used in physics and mathematics. Its rigorous mathematical form is called $Dirac\ delta\ function$.

Dirac Delta Function

The idea of delta function is simple: it describes the density of mass (or charge, probability, and so on) for a point-like particle. Formally, such density can be written as δ_x .

Since the total mass (charge, probability) is finite, the summation

of the density over the region where the particle might be must be a fixed number:

 $m = \int \delta x \delta_x .$

Another example of a simple functional is the maximum of a function:

$$\mathcal{X} f = \max f_x$$
.

Finally, one can map any function f_x into a number like so:

$$\mathcal{R} f = \frac{f_1}{1!} + \frac{f_{1/2}}{2!} + \frac{f_{1/3}}{3!} + \dots + \frac{f_{1/n}}{n!} + \dots$$

For $f = \sin we$ obtain $\mathcal{R} \sin \approx 1.1479$.

Exercise 3.2

For the functionals \mathcal{M} , \mathcal{X} , and \mathcal{R} check whether they are *linear*.

3.5 Spaces

To arrive at the idea of vectors we will start with simple geometrical objects – arrows in a plane.

 $\langle \phi | \phi \rangle$

and

$$|\phi\rangle\langle\phi|$$
.

3.6 Application: Circular Motion

Let us examine how the concepts and tools discussed above can be applied to a simple case of circular motion.

Consider a particle moving in a circle with the radius R, as shown in Figure X. If we choose the center of the circle as the reference point, we can specify the position of the particle using an arrow $|r\rangle$. During motion the direction of this arrow is constantly changing, but its length R remains the same.

After a short time interval δt , the position of the particle changes by $\delta |r\rangle$:

$$|r_t\rangle \rightarrow |r_{t+\delta t}\rangle = |r_t\rangle + \delta|r\rangle$$
.

The length of the path covered by the particle during the time interval δt can be approximated by the length of the arc $\delta L=R\delta\theta=v\delta t$. The arrow $\delta|r\rangle$ can be written as $\delta L|u\rangle$ where $|u\rangle$ is the vector of unit length pointing in the direction of motion. This unit vector can be constructed from $|r\rangle$ by scaling it down by R and then rotating counter-clockwise with the operator \widehat{J} :

$$\delta|r\rangle = R\delta\theta\widehat{J}\left(\frac{|r\rangle}{R}\right).$$

Since \widehat{J} is a linear operator, the R cancels and we can write

$$\frac{\delta|r\rangle}{\delta t} = \frac{\delta\theta}{\delta t}\widehat{J}|r\rangle \qquad \Longrightarrow \qquad \partial_t|r\rangle = \omega\widehat{J}|r\rangle,$$

where we introduced the angular speed $\omega = \partial_t \theta$. Finally, by applying the \widehat{J} operator to both sides of the last equation, we can cast it into the "Schrodinger" form:

$$\widehat{J}\partial_t|r\rangle = -\omega|r\rangle$$
.

Chapter Highlights

- Arrows in a plane provide a simple model for vectors.
- Arrows can be manipulated in ways analogous to numbers: Two arrows be added, an arrow can be "scaled" (stretched or compressed).
 Arrows form an algebra.
- Basis is an extremely important concept. Basis is a set of objects (arrows) that can be used to "build" all other similar objects (arrows).
 At the same time, basis can not be used to build itself – basis arrows are independent.



4. Classical Physics

I think we may ultimately reach the stage when it is possible to set up quantum theory without any reference to classical theory, just as we already have reached the stage where we can set up the Einstein gravitational theory without any reference to the Newtonian theory. But from the point of view of teaching students, I think one would always have to proceed by stages – not expect too much from them, teach them first the elementary theories and gradually develop their minds; and that will always involve working from the classical theory first.

P. A. M. Dirac, Lectures on Quantum Field Theory, Belfer Graduate School of Science, Yeshiva University, New York, 1966, p.43.

The concept of *operators* extends the idea of functions. An unary numeric function f takes some numeric value x as an input and produces another numeric value y:

$$f x = y$$
 or $x \xrightarrow{f} y$.

In mathematical jargon, f maps x into y.

☑ Prerequisite Knowledge

To fully understand the material of this chapter, readers should be comfortable with the following concepts:

- State
- Dynamical equations

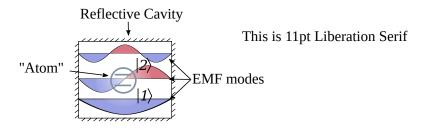


Fig. 4.1: Operators extend the idea of functions. (a) An unary function f can be applied to a number x to produce another number y. (b) An unary operator \widehat{F} can be applied to a vector \overrightarrow{a} to yield another vector \overrightarrow{b} .

4.1 System

An action of an operator ${\cal F}$ on arrows can be represented symbolically as an equation:

$$F\overrightarrow{a} = \overrightarrow{b}$$
.

Often a "hat" is placed on top of an operator¹, to emphasize that it is different from numeric function:

$$\widehat{F} \stackrel{
ightharpoonup}{a} = \stackrel{
ightharpoonup}{b}.$$

Simple Operators

It is easy to come up with examples of operators:

• Unit operator (or *identity* operator), such that

$$\widehat{I}\overrightarrow{a} = \overrightarrow{a}$$
.

• "Zeroing" operator that maps every vector into a zero vector:

$$\widehat{0} \stackrel{\rightarrow}{a} = \stackrel{\rightarrow}{0}$$
.

¹In Quantum Mechanics, for example.

4.2 Oscillator 37

To fully describe an operator, we must describe how it acts *on every* arrow.

Examples

Let us take a closer look at a couple of operators. While studying these examples we must keep in mind that the relations between components are *specific to basis* and will change if we change the basis. The question of how exactly the relation between components changes will be addressed later in Section ?? for the simplest types of operators.

■ Matrix

Here is an example of matrix:

$$\widehat{S} = \begin{pmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{pmatrix} = \begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix}.$$

Similar approach can be used to find the components of any linear operator.

4.2 Oscillator

An action of an operator F on arrows can be represented symbolically as an equation.

4.3 State

An action of an operator F on arrows can be represented symbolically as an equation.

4.4 Dynamics

An action of an operator F on arrows can be represented symbolically as an equation.

4.5 Hamiltonian

An action of an operator F on arrows can be represented symbolically as an equation.

4.6 Lagrangian

An action of an operator F on arrows can be represented symbolically as an equation.

4.7 Field

An action of an operator ${\cal F}$ on arrows can be represented symbolically as an equation.

4.8 Ideal Versus Real

An action of an operator ${\cal F}$ on arrows can be represented symbolically as an equation.

- Operators extends the idea of functions.
- Numeric functions (e.g., $\sin x$) act on numbers and yield other numbers. Operators may act on vectors to yield other vectors or numbers.
- Linear operators represent the simplest and yet powerful class of operators on vectors.
- Linear operators can be represented graphically or symbolically.



5. Quantum Physics

THE first type of operators – and corresponding tensors – that we encountered has a simple type:

$$\widehat{L} \stackrel{
ightharpoonup}{a} = \stackrel{
ightharpoonup}{b}$$
.

It is a linear unary function mapping vectors into vectors.

✓ Prerequisite Knowledge

To fully understand the material of this chapter, readers should be comfortable with the following concepts:

- State
- Dynamical equations

5.1 Quantum System

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\stackrel{\rightarrow}{a}\stackrel{\rightarrow}{b}=x$$
.

5.2 Quantum State

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\stackrel{\rightarrow}{a}\stackrel{\rightarrow}{b}=x$$
.

5.2.1 States Overlap

 $\langle \psi | \phi \rangle$.

5.3 Quantum Dynamics

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\overrightarrow{a}\overrightarrow{b} = x$$
.

5.4 Quantum Hamiltonian

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\stackrel{\rightarrow}{a}\stackrel{\rightarrow}{b}=x$$
.

5.5 Quantum Oscillator

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\stackrel{\rightarrow}{a}\stackrel{\rightarrow}{b}=x$$
.

5.6 Quantum Bit

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\,|\overrightarrow{a}\overrightarrow{b} = x$$
.

5.6.1 Physical Realization of Qubits

Recall that harmonic oscillator is any physical system with Hamiltonian

$$H = \frac{p^2}{2m} + \frac{kx^2}{2} \,.$$

Many concrete physical systems can be described using this Hamiltonian and thus provide specific *realizations* of the oscillator model. Similarly, many concrete physical systems realize the idea of a qubit.

5.7 Interacting Qubits

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\stackrel{\rightarrow}{a}\stackrel{\rightarrow}{b}=x$$
.

5.7.1 Computational Basis

$$|\Upsilon\rangle_1 = |0\rangle|0\rangle, |\Upsilon\rangle_2 = |0\rangle|1\rangle, |\Upsilon\rangle_3 = |1\rangle|0\rangle, |\Upsilon\rangle_4 = |1\rangle|1\rangle.$$

Q: Are there other states, which are also basis and product? Smth like

$$|\Xi\rangle = |+\rangle|+\rangle$$
.

5.7.2 Bell States

$$|\Phi\rangle^+\,,\quad |\Phi\rangle^-\,,\quad |\Psi\rangle^+\,,\quad |\Psi\rangle^-\,.$$

5.7.3 GHZ State

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\stackrel{\rightarrow}{a}\stackrel{\rightarrow}{b}=x$$
.

5.8 Quantum Field

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$|\sigma\rangle\langle\sigma|\stackrel{\rightarrow}{a}\stackrel{\rightarrow}{b}=x$$
.

We are looking for a binary operator $\widehat{\sigma}$ that yields a number based on two vectors:

$$\widehat{\sigma} \stackrel{\rightarrow}{a} \stackrel{\rightarrow}{b} = x$$
.

We will call this operator $\widehat{\sigma}$ *dol*-operator¹, based on the key letters of the phrase "degree of overlap".

• Reminder

When we say that an operator $\widehat{\Gamma}$ is given or known, we mean that we know how it acts on *any vector* \overrightarrow{a} :

$$\widehat{\Gamma} \stackrel{\rightarrow}{a} = x_a$$
.

¹This is not a standard terminology.

Array of equations:

$$\widehat{\Gamma}_1 \stackrel{\rightarrow}{e}_1 = 1 \tag{5.1}$$

$$\widehat{\Gamma}_1 \stackrel{\rightarrow}{e}_2 = 0 \tag{5.2}$$

$$\widehat{\Gamma}_1 \stackrel{\rightarrow}{e}_3 = 0 \tag{5.3}$$

$$\dots (5.4)$$

- Two vectors can be compared for similarity by calculating the "degree of overlap". The longer two vectors are and the closer their mutual direction the greater the overlap is.
- Degree of overlap can be described by a binary linear operator σ̂.
 This operator is closely related to the concept of scalar product of two vectors.
- When scalar product (or, equivalently, degree of overlap) is defined for vectors, each vector receives a "special relative" – conjugate vector
 that lives in different vector space, called conjugate or dual space.
- When the degree-of-overlap operator ô is partially applied, the result is a unary linear operator that yields a number for every input vector. Importantly, such an operator is also a vector, albeit not an arrow-like vector.



6. Applications

W are now ready to appreciate how tensors are used in "real life". In this chapter we will encounter examples of tensors that are used in mathematics, physics, and engineering.

✓ Prerequisite Knowledge

To fully understand the material of this chapter, readers should be comfortable with the following concepts:

- State
- Dynamical equations

6.1 Hydrogen-like Atoms

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \, .$$

6.1.1 Franck-Hertz Experiment

Franck and Hertz.

6.1.2 Stoke's Rule

Stoke's rule.

6.2 Quantum Dots

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \, .$$

6.3 Spontaneous Emission

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \,.$$

6.4 Stimulated Emission

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \,.$$

6.5 Lasers

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2}.$$

6.6 Photoeffect

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \,.$$

6.7 Black Body Radiation

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \, .$$

6.8 Conductors

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \, .$$

6.8.1 Heat Capacity

Einstein's model.

6.9 Entanglement

$$|\alpha\rangle\langle\beta|$$

$$E_n = -\frac{E_i}{n^2} \,.$$

δ -Notation

When a quantity x changes by a tiny amount, we will denote the change using small Greek letter δ (delta) as follows:

$$\delta x$$
 - tiny change of x .

A convenient way to write all components of a second rank tensor is to use table-like structure called *matrix*:

$$F^{\mu\nu} = \begin{pmatrix} F^{00} & F^{01} & F^{02} & F^{03} \\ F^{10} & F^{11} & F^{12} & F^{13} \\ F^{20} & F^{21} & F^{22} & F^{23} \\ F^{30} & F^{31} & F^{32} & F^{33} \end{pmatrix}.$$

In the matrix, the first index μ of $F^{\mu\nu}$ corresponds to the row, while the second index ν corresponds to the column. Both rows and columns are enumerated from 0 to 3.

Using matrix form, we can write the electromagnetic tensor in terms of the electric and magnetic fields:

$$F^{\mu\nu} = \begin{pmatrix} 0 & -\mathcal{E}^1 & -\mathcal{E}^2 & -\mathcal{E}^3 \\ \mathcal{E}^1 & 0 & -\mathcal{B}^3 & \mathcal{B}^2 \\ \mathcal{E}^2 & \mathcal{B}^3 & 0 & -\mathcal{B}^1 \\ \mathcal{E}^3 & -\mathcal{B}^2 & \mathcal{B}^1 & 0 \end{pmatrix}.$$

- Tensors find application in various areas of science and math.
- Geometrical properties of surfaces and spaces can be described using metric tensor.
- Physical properties of solids are often anisotropic depend on the direction of applied "force". Such properties are best described by

- various tensors: stress tensor, mobility tensor, piezoelectric tensor, and others.
- At the fundamental level electric and magnetic fields are united in a single physical object electromagnetic field. Electromagnetic field is described by an antisymmetric tensor of the second rank.



7. Implications

TE are now ready to appreciate the implications of quantum physics.

✓ Prerequisite Knowledge

To fully understand the material of this chapter, readers should be comfortable with the following concepts:

- State
- Dynamical equations

Discuss Mermins papers. Wheeler's ideas.

δ -Notation

When a quantity x changes by a tiny amount, we will denote the change using small Greek letter δ (delta) as follows:

 δx - tiny change of x.

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8. Appendix

E are now ready to appreciate the implications of quantum physics.

8.1 Physics

When a quantity x changes by a tiny amount, we will denote the change using small Greek letter δ (delta) as follows:

 δx - tiny change of x.

A convenient way to write all components of a second rank tensor is to use table-like structure called *matrix*.

8.1.1 Black Body Radiation

8.1.2 Notation

K and E_k – Kinetic energy of a system.

 Π and E_p – Potential energy of a system.

E – Total mechanical energy (E = E_K + E_P) written in terms of velocity v and position x.

H – Hamiltonian of a system: H = K + Π . Differs from E because kinetic energy written in terms of *momentum* p instead of velocity.

L – Lagrangian (Lagrange function) of a system: L = E_K – E_p . It is the "imbalance" of energies.

 Δx – Change of a value of a variable x.

 δx – "Tiny" change of a value of a variable x.

 ∂ – Rate of change.

 ∂_t – Rate of change with respect to time.

 ∂_x – Rate of change with respect to variable x (e.g. position).

 $\partial_t f$ – Rate of change of f with respect to t.

It means exactly the following

$$\partial_t f = \frac{\delta f}{\delta t} = \frac{f(t + \delta t) - f(t)}{\delta t}.$$

 ξ – State of a system in Hamiltonian dynamics. It is a vector with components $\xi = (x, p)$.

 \hat{J} – Operation (operator) of rotation by 90 degrees.

 $\hat{R}(\theta)$ – Operation (operator) of rotation by θ .

h – Quantum of action (Planck's constant). In SI units its numerical value is $h = 6.626 \times 10^{-34} (J \cdot s)$.

 \hbar – "Reduced Planck's constant". A convenience notation for often used combination $\hbar = h/(2\pi)$.

A – Action.

 Ψ – Quantum state.

 $|\Psi\rangle$ – Quantum state vector.

 ϕ , θ – Angle variables.

 ω – Angular speed (also angular velocity). Often it has the following meaning: $\omega = \partial_t \theta$.

 $\vec{e_1}, \vec{e_2}$ – Basis vectors. Usually they have unit length and point in mutually perpendicular directions.

z – Arbitrary *numeric* variable, \vec{z} – arbitrary *vector* variable, \hat{z} – arbitrary operator.

 $\overset{\circ}{A}$ – Angstrom, a unit of length in the world of atoms. $\overset{\circ}{1A}$ = $10^{-9}(m)$.

Hydrogen atom is about 1A in diameter.

c – Speed of light in vacuum.

 ν – Frequency of oscillations measured as the number of oscillations per second, in Hz.

8.1.3 Constants

Below is the list of various physical constants used in these notes.

 $q_e = 1.6 \times 10^{-19} (C)$ – Charge quantum (charge of an electron).

 $m_e = 9.1 \times 10^{-31} \, (kg)$ – rest-energy (aka mass) of an electron. $k = \frac{1}{4\pi\epsilon_0} = 9 \times 10^9 \, (N \cdot m^2/C^2)$ – Coulomb constant – force between two unit charges 1 meter apart.

 10^{-9} s = 1 nanosecond – the unit of time in atomic world. It is a "heartbeat" of atoms".

 $1(eV) = q_e(J) - 1$ electron-volt. It is the kinetic energy an electron

8.2 Mathematics 51

would acquire when accelerated by a simply 1V battery. A tiny value. $m_ec^2/q_e=0.5\,MeV$ – rest-energy of an electron measured in electron-volts. Roughly speaking, we will need half a million 1-volt batteries to accelerate an electron to make its kinetic energy comparable to its rest-energy.

 $k = 100 \, (N/m)$ is a spring constant of a spring that stretches by 0.1 of a meter when 1 kilogram mass is attached to it.

8.2 Mathematics

When a quantity x changes by a tiny amount, we will denote the change using small Greek letter δ (delta) as follows:

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 - tiny change of x .

A convenient way to write all components of a second rank tensor is to use table-like structure called *matrix*.

8.2.1	Greek Al	phabet
-------	----------	--------

$A \alpha$	alpha	$B\beta$	beta
$\Gamma \gamma$	gamma	$\Delta \delta$	delta
$\mathrm{E}\epsilon$	epsilon	$\mathrm{Z}\zeta$	zeta
${ m H}\eta$	eta	$\Theta \theta$	theta
$\operatorname{I}\iota$	iota	$K \kappa$	kappa
$\Lambda \lambda$	lambda	${ m M}\mu$	mu
$\mathrm{N} u$	nu	$\Xi \xi$	xi
Оо	omicron	$\Pi \pi$	pi
$P \rho$	rho	$\Sigma \sigma$	sigma
$\mathrm{T} au$	tau	Υv	upsilon
$\Phi\phi$	phi	$X \chi$	chi
$\Psi \psi$	psi	$\Omega \omega$	omega

Table 8.1: Greek Alphabet

In mathematics most often we use θ and ϕ for angles. Sometimes α and β are also used. Occasionally ψ is used to denote angle.

In physics λ is used to denote the wavelength of light, ν – frequency in Hertz (periods of oscillations per second), ω – angular speed (number

of radians of rotation per second).

The symbols Ψ and Φ are usually used to denote quantum state vectors.



9. Solutions

Exercise 1.1



Fig. 9.1: The set M contains all possible makes of cars: Ford, Toyota, etc.

The diagram in the Figure 9.1 shows the set M – the set of all possible makes of cars. A mapping ${\bf trk}$ returns true if a given car maker produces trucks.

Exercise 2.1

Any binary function can be viewed as a unary function if two inputs are replaced by a single input of a *pair of numbers*. Similarly for a function with two outputs. This idea is illustrated in the Figure 9.2(a): The function **swp** is viewed as a unary function which swaps the numbers in an *ordered pair*:

swp
$$(n, m) = (m, n)$$
.

Given the set \mathbb{Z} of whole numbers, we can create the set of all possible *ordered pairs* (n,m). This set can be denoted as follows:

$$(\mathbb{Z}, \mathbb{Z})$$
 or $\mathbb{Z} \times \mathbb{Z}$.

The latter notation is standard in mathematics, but the former way of writing is

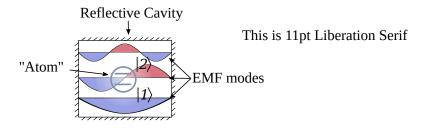


Fig. 9.2: (a) Two inputs (outputs) of a function can be replaced with a single input of a *pair* of numbers, turning a binary function into a unary one. (b) That.

also acceptable. We can similarly denote the set of all ordered triples:

$$(\mathbb{Z}, \mathbb{Z}, \mathbb{Z})$$
 or $\mathbb{Z} \times \mathbb{Z} \times \mathbb{Z}$.

With the notation introduced above, the action of functions with multiple inputs or outputs can be depicted on the level of sets. The Figure 9.2(b) shows how this works for the functions ${\bf swp}$ and ${\bf max}$.



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