

Diff Geo II: Problem Set III

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Abstract

This work contains solutions for the problem set III.

Question 1-1.

1. Suppose that $a: (M, g) \rightarrow (N, h)$ is an isometry.
 - Show that a takes geodesics to geodesics.
 - Suppose that M is connected. Show that if $b: (M, g) \rightarrow (N, h)$ is an isometry and $x \in M$ is such that $a(x) = b(x)$ and $a_*(v) = b_*(v)$ for all $v \in T_x M$, then $a = b$.

Solution.

Let γ be a geodesic in M . Then,

$$D_{t(\gamma)} \dot{\gamma} = 0.$$

As a is an isometry, and a_* is linear,

$$D_{t(a \circ \gamma)} a \circ \dot{\gamma} = a_*(D_{t(\gamma)} \dot{\gamma}) = 0,$$

because local isometries preserve metric tensor components, and Christoffel symbols in coordinates. Hence, $a \circ \gamma$ is a geodesic.

Let $U = \{q \in M : da = db\}$. Note that U is closed, and $p \in U$. But, U is open, since for any $q \in U$, any normal neighborhood of q , N , must be contained in U , as for any $s \in N$, there exists $v \in T_q M$, such that $\gamma_v(1) = s$, so

$$a(s) = \gamma_{da(v)}(1) = \gamma_{db(v)}(1) = b(s).$$

Hence U is clopen, and $U = M$. □

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Question 1-2.

2. Suppose that M and N are connected Riemannian manifolds and that $a: M \rightarrow N$ is a map that preserves the distance function (i.e., $d_M(x, y) = d_N(a(x), a(y))$ for all $x, y \in M$). Show that a preserves the Riemannian metric (i.e., $\langle v, w \rangle_M = \langle a_*(v), a_*(w) \rangle_N$ for all $x \in M$ and $v, w \in T_x M$). (First show that a is smooth; this can be done using the smoothness of the exponential map.)

Solution.

Suppose for the moment that a is smooth. Let $v \in TM$, and set $\gamma(t) = \exp_p(tv)$. For t small enough, we know that γ has a constant speed. Therefore,

$$|v||t - s| = d_M(\gamma(t), \gamma(s)) = d_N(F \circ \gamma(t), F \circ \gamma(s))$$

for any t, s small enough. Hence,

$$|Da(v)| = \left| \frac{d(F \circ \gamma)}{dt} \right|_{t=0} = \lim_{t \downarrow 0} \frac{d_M(\gamma(t), \gamma(0))}{|t|} = |\dot{\gamma}(0)| = |v|.$$

Therefore, a is a Riemannian isometry, if we show that a is smooth. For now, assume that a is in fact bijective, which is necessary. Let $p \in M$. and $q = a(p)$. Then, at q choose a radial coordinate from a normal neighborhood $(r_{q_1}, \dots, r_{q_n})$, and choose $a(p_i) = q_i$ for all i . Then,

$$r_{q_i} \circ a(x) = d(a(x), q_i) = d(x, p_i)$$

for all x . By distance preserving property, we can choose p_i and q_i such that $r_{p_i}(x) = d(x, p_i)$ is smooth at p for all i . Hence, $r \circ a$ is smooth at p , so a is smooth. \square

Question 1-3.

3. Suppose that M is a compact Riemannian manifold.
- (a) Prove that there is an $\epsilon > 0$ such that every closed curve of length $< \epsilon$ is null-homotopic.
 - (b) Suppose that $\gamma : S^1 \rightarrow M$ is a closed curve. Prove that there is a piecewise-smooth curve γ' that is homotopic to γ and such that $\ell(\gamma') \leq \ell(\gamma)$.
 - (c) If $\gamma : S^1 \rightarrow M$ is a closed curve, the free homotopy class of γ is the set of curves that are homotopic to γ . Show that this set has a minimal-length element and that this element is a geodesic.

Solution.

(a) Consider the cover of M obtained by for each point $p \in M$, choose a uniformly normal neighborhood of p . Then, via compactness, we can extract a finite subcover from the cover, which we denote by $\{N_i\}_{i \leq n}$. Now, set $\epsilon = \frac{1}{2} \min_i \epsilon(N_i)$, where $\epsilon(N_i)$ s are chosen such that for each i , and each point in N_i is contained in a geodesic ball of radius $\epsilon(N_i)$. Then, by corollary 6.11 from John M lee, we know that the Riemannian distance and the radial distance are the same, so any closed curve of length ϵ must lie inside a geodesic ball. Therefore, for any closed curve γ of length less than ϵ , we can find \exp_p such that $\exp_p^{-1}(\gamma)$ maps into $B(0, \epsilon)$ in $T_p M$ and $\gamma(0) = p$. With the homotopy map

$$H(s, t) = \exp_p^{-1} \gamma(t)$$

for $s, t \in [0, 1] \times [0, 1]$, we see that $\exp_p^{-1}(\gamma)$ is nullhomotopic. Since \exp_p is a diffeomorphism, so it is a homeomorphism, and we see that γ is nullhomotopic as well.

(b) We cover the gamma with finitely many uniformly normal neighborhoods. On the lifted paths, we can do a straight line homotopy with the straight line from the origin to $\exp_p(\gamma(1))$. Then, the inverse image of the homotopic path pieced together will form a piecewise smooth curve, that is still homotopic to γ . Since the Riemannian distance is same as the radial function, in normal neighborhoods, and we have chosen to do a straight line homotopy with the straight line from the origin to $\exp_p(\gamma(1))$, $L(\gamma') \leq L(\gamma)$.

(c) We denote the free homotopy class of γ as \mathfrak{H} , and set $L = \inf_{\gamma' \in \mathfrak{H}} L(\gamma')$. From (b), we can choose a minimizing sequence $\{\gamma_n\} \subset \mathfrak{H}$ such that γ_n is piecewise smooth, and unit speed. Then,

$$d(\gamma_n(t_1), \gamma_n(t_2)) \leq L(\gamma_n|_{[t_1, t_2]}) \tag{1}$$

$$\leq |t_1 - t_2| \tag{2}$$

for each n and $t_1, t_2 \in S^1$, where (1) holds by definition of Riemannian distance, and (2) holds by the choice of unit speed parametrization, Therefore, $\{\gamma_n\}$ are 1-Lipschitz family. Furthermore, for any metric ball in S^1 , denoted by B ,

$$\gamma_n(B) \subset M$$

for each n trivially, so by Arzela-Ascoli, we can extract a subsequence, which we still denote as $\{\gamma_n\}$, converges uniformly to some γ^* . We now claim that the γ^* is homotopic to γ , $L(\gamma^*) = L$, and geodesic. Using the uniformly normal covering as in a, and via compactness, we can have some small $\delta > 0$, such that for each $p \in M$, there exists a geodesic ball of radius δ . Now, choose γ_{n_0} from $\{\gamma_n\}$ such that γ_{n_0} is uniformly $\frac{\delta}{2}$ away from γ^* . Then, we see that we can form a piecewise homotopy between γ_{n_0} and γ^* with finite number of geodesic balls, using straight line homotopy available at the tangent spaces. This shows that the uniform convergence preserves the property of being homotopic to γ , so γ^* is homotopic to γ . Now, to prove that γ^* is indeed a minimal length element, since $L(\gamma_n) \rightarrow L$, it suffices to show that $L(\gamma_n) \rightarrow L(\gamma)$, which is equivalent to

$$\int_{S_1} |\dot{\gamma}_n(t)| dt \rightarrow \int_{S_1} |\dot{\gamma}^*(t)| dt.$$

Since each γ_n is piecewise smooth, and γ_n converges uniformly γ , we formally expect that

$$|\dot{\gamma}_n(\cdot)| \rightarrow |\dot{\gamma}^*(\cdot)| \text{ almost everywhere.}$$

and $\dot{\gamma}_n(\cdot)$ are L^1 . Then, by DCT, we would have the desired conclusion. The limit object should be locally minimizing curve, which implies that it is a geodesic. \square