

# Diff Geo II: Problem Set II

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## Abstract

This work contains solutions for the problem set II.

### Question 1-1.

1. In class, we used the fact that the curvature tensor can be expressed in terms of parallel transport. That is, we claimed that if  $q \in M$  and if  $\alpha: \mathbb{R}^2 \rightarrow M$  is a smooth map such that  $\frac{\partial \alpha}{\partial x} = X$ ,  $\frac{\partial \alpha}{\partial y} = Y$ , then for all  $Z \in T_q M$ , we have

$$R(X, Y)Z = \lim_{s \rightarrow 0} \frac{Z - p_{\gamma_s}(Z)}{s^2},$$

where  $\gamma_s: [0, 4] \rightarrow M$  is the image under  $\alpha$  of the boundary of an  $s \times s$  square, i.e.,

$$\gamma_s(t) = \begin{cases} \alpha(st, 0) & t \in [0, 1] \\ \alpha(s, s(t-1)) & t \in [1, 2] \\ \alpha(s(3-t), s) & t \in [2, 3] \\ \alpha(0, s(4-t)) & t \in [3, 4]. \end{cases}$$

Prove this fact.

(Hint: Construct a frame of vector fields  $V_1, \dots, V_m \in \mathbf{V}(\alpha)$  such that  $\nabla_X V_i = 0$  and  $\nabla_Y V_i(u_1, 0) = 0$ . Any vector field  $W$  along  $\gamma_s$  can be expressed as a linear combination of the  $V_i$  — when is  $W$  parallel?)

### Solution.

Let  $s > 0$ . Set

$$V_i(\alpha(s_1, s_2)) = P_{\alpha(0, s_2), \alpha(s_1, s_2)} \circ P_{q, \alpha(0, s_2)}(V_i(q))$$

for all  $1 \leq i \leq m$  and  $(s_1, s_2) \in [0, s] \times [0, s]$ . As  $\frac{\partial \alpha}{\partial x} = X$ ,  $\frac{\partial \alpha}{\partial y} = Y$ , we have

$$\nabla_X V_i = 0 \quad \text{and} \quad \nabla_Y V_i(u_1, 0) = 0$$

for all  $i$ . Then, we see that any  $W \in V(\gamma)$  can only change along 2nd part of the path. We compute

$$\begin{aligned} V_i(q)(P_\gamma W(q) - W(q)) &= \langle V_i, W \rangle_{\gamma_s(2)} - \langle V_i, W \rangle_{\gamma_s(1)} \\ &= \int_0^s \partial_t \langle V_i, W \rangle dt = \int_0^s V_i \cdot \nabla_Y W(1, t) dt \\ &= \int_0^s V_i \cdot \nabla_Y W(1, t) dt - \int_0^s \partial_r (V_i \cdot \nabla_Y W(r, t)) dr dt \\ &= - \int_0^s \int_0^s V_i \cdot \nabla_X \nabla_Y W(r, t) dr dt \end{aligned}$$

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for all  $i$ . Now, with  $W(0,0) = Z$ , and  $[X,Y] = 0$ , letting  $s \downarrow 0$ , gives

$$\lim_{s \downarrow 0} \frac{\langle Z - P_\gamma(Z), V_i \rangle}{s^2} = \langle R(X,Y)Z, V_i \rangle$$

for all  $i$ , and hence,

$$R(X,Y)Z = \lim_{s \downarrow 0} \frac{Z - P_\gamma(Z)}{s^2}.$$

□

**Question 1-2.**

2. Suppose that  $M$  is a two-dimensional Riemannian manifold with curvature tensor  $R$ .

(a) Use the symmetries of the curvature tensor to show that if  $p \in M$ ,  $V, W \in T_p M$ , then

$$K = \frac{\langle R(V, W)W, V \rangle}{\|V\|^2\|W\|^2 - 2\langle V, W \rangle^2}$$

is independent of  $V$  and  $W$ .

(b) Prove that if  $K$  is as above, then

$$R(X, Y)Z = K(\langle Y, Z \rangle X - \langle X, Z \rangle Y)$$

for all  $X, Y, Z \in T_p M$ .

**Solution.**

I believe there is a typo in the problem: 2 in the denominator should be gone.

(a) Let  $E_1, E_2$  be orthonormal frame, so  $V = V^1 E_1 + V^2 E_2$  and  $W = W^1 E_1 + W^2 E_2$ . Then,

$$\begin{aligned} \langle R(V, W)W, V \rangle &= \langle R(V^1 E_1 + V^2 E_2, W^1 E_1 + W^2 E_2)W, V \rangle \\ &= \langle V^1 W^2 R(E_1, E_2)W, V \rangle + \langle V^2 W^1 R(E_2, E_1)W, V \rangle \\ &= (V^1 W^2 - V^2 W^1)(W^1 V^2 \langle R(E_1, E_2)E_1, E_2 \rangle + W^2 V^1 \langle R(E_1, E_2)E_2, E_1 \rangle) \\ &= -(V^1 W^2 - V^2 W^1)^2 \langle R(E_1, E_2)E_1, E_2 \rangle \end{aligned} \quad (1)$$

where (1), in particular, holds by  $R(E_1, E_1)W = R(E_2, E_2)W = 0$ . Furthermore,

$$\|V\|^2\|W\|^2 - \langle V, W \rangle^2 = (V^1 W^2 - V^2 W^1)^2$$

and hence

$$\begin{aligned} K &= \frac{-(V^1 W^2 - V^2 W^1)^2 \langle R(E_1, E_2)E_1, E_2 \rangle}{(V^1 W^2 - V^2 W^1)^2} \\ &= \langle R(E_1, E_2)E_2, E_1 \rangle \end{aligned}$$

Therefore, we see that  $K$  only depend on the chosen frame, so  $K$  is independent of  $V$  and  $W$ .

(b) We compute

$$\begin{aligned} R(X, Y)Z &= \sum_{i,j,k=1}^2 X^i Y^j Z^k R(E_i, E_j)E_k \\ &= (X^1 Y^2 Z^1 - X^2 Y^1 Z^1)R(E_1, E_2)E_1 + (X^1 Y^2 Z^2 - X^2 Y^1 Z^2)R(E_1, E_2)E_2 \end{aligned}$$

and

$$\begin{aligned}
K(<Y, Z>X - <X, Z>Y) &= <R(E_1, E_2)E_2, E_1>X(Y^1Z^1 + Y^2Z^2) \\
&- <R(E_1, E_2)E_2, E_1>Y(X^1Z^1 + X^2Z^2) \\
&= <R(E_1, E_2)E_2, E_1>(X^1Y^2Z^2 - X^2Z^2Y^1)E_1 \\
&+ <R(E_1, E_2)E_2, E_1>(Y^1Z^1X^2 - X^1Y^2Z^1)E_2
\end{aligned}$$

Therefore,

$$\begin{aligned}
<R(X, Y)Z, E_1> &= <R(E_1, E_2)E_2, E_1>(X^1Y^2Z^2 - X^2Y^1Z^2) \\
&= <K(<Y, Z>X - <X, Z>Y), E_1>
\end{aligned}$$

Similarly,

$$<R(X, Y)Z, E_2> = <K(<Y, Z>X - <X, Z>Y), E_2>.$$

As the equality holds for the basis elements, we have

$$R(X, Y)Z = K(<Y, Z>X - <X, Z>Y)$$

as required. □

**Question 1-3.**

3. Find a sequence  $\gamma_i: [0, 1] \rightarrow S^2$  of piecewise-smooth curves with the same endpoints such that the  $\gamma_i$  converge to a piecewise-smooth curve  $\gamma$ , but the parallel transport maps  $P_{\gamma_i}: T_p M \rightarrow T_q M$  do not converge to the map  $P_\gamma$ .

**Solution.**

All triangles in the discussion are great circle triangles. From class, we saw that the parallel transport along a path of triangle, starting at a vertex and coming back to the chosen vertex, is given by a rotation of  $\theta - \pi$  where  $\theta$  is the sum of three angles of the triangle, formed by the path. To discuss pointwise convergence, we choose the geodesic distance on  $S^2$ . Let  $p$  be the north pole of  $S^2$ . Then, choose a triangle path, starting at  $p$  and coming back to  $p$  such that  $\theta - \pi > 0$ . Now, for each  $i \in \mathbb{N}$ , choose a triangle path,  $\gamma_i^*$ , whose angle sum is  $\theta'$ , yet  $\theta - \pi = k\theta'$  for some  $k \in \mathbb{N}$ , and the path of the triangle is contained in  $B(p, \frac{1}{i})$ , and set  $\gamma_i = (\gamma_i^*)^k$ , which is the standard path composition of  $\gamma_i^*$   $k$  times. Then, set  $\gamma$  be the trivial path from  $p$  to  $p$  itself. Then, we see that  $\gamma_i$  converges to  $\gamma$  pointwise, as for any  $t \in [0, 1]$ , for any  $\epsilon > 0$ , there exists  $i$  such that  $d(\gamma_i(t), \gamma(t)) < \epsilon$ , whenever  $n \geq i$ . Furthermore,  $P_{\gamma_i}$  is given by a rotation of  $\theta - \pi > 0$ , yet  $P_\gamma = I$ , so we see that  $P_{\gamma_i}$  does not converge to  $P_\gamma$  as a linear map. Hence, we have the desired construction.  $\square$

### Question 1-4.

Let  $M \subset \mathbb{R}^3$  be the cone

$$M = \{(r \cos \theta \sin \phi, r \sin \theta \sin \phi, r \cos \phi) \mid r > 0, \theta \in [0, 2\pi)\}$$

as in the first problem set.

4. Construct an isometry from the complement of the line  $\theta = 0$  to a subset of  $\mathbb{R}^2$ . Use this isometry to calculate the parallel transport map  $P_{0,2\pi}$  from problem 5 of the first problem set.

### Solution.

Cutting the cone and unfolding it, and using elementary geometry tell us that, in order to have an isometry, we must satisfy  $r \sin(\phi)\theta = r\theta'$ , because the radius of the circle changes from  $r \sin(\phi)$  to  $r$ , by unfolding. As a parallel transport along any curve in  $\mathbb{R}^2$  is an identity, we have that a parallel transport on the image is given by  $(\cos(\theta'), -r \sin(\theta'); \sin(\theta'), -r \cos(\theta'))$ . I don't quite recover the parallel transport computed in the last homework, by naively composing the isometry map, with the transport on the image yet. I will try more later!