

S : state at time t

S' : state at time $t+1$

state $\in [2d, n]$

$$D = [s^1, \dots, s^t, s^{t+1}, \dots]$$

Next steps
 ✓ modelling
 ○ tasks

DT: $\text{flatten}(S) \xrightarrow{[2d \times n, 1]} \boxed{\text{MLP}_\theta} \rightarrow S'$

NF: $\text{flatten}(s) \xrightarrow{[2d \times n, 1]} \boxed{\text{MLP}_\theta} \rightarrow f \xrightarrow{\text{solve}} \begin{bmatrix} s \\ s' \end{bmatrix} \xrightarrow{\boxed{\text{MLP}_\theta}} S'$

1. architecture
 2. hard to fit
 3. learn signal
 is small.

NBF: $\begin{matrix} s_1 \xrightarrow{[2d, 1]} \\ s_2 \xrightarrow{[2d, 1]} \\ s_3 \xrightarrow{[2d, 1]} \end{matrix} \rightarrow \boxed{\text{MLP}_\theta} \rightarrow \begin{bmatrix} p_1 \\ p_2 \\ p_3 \end{bmatrix} \xrightarrow{[nE, 1]} \boxed{\text{MLP}_\phi} \rightarrow f \xrightarrow{\text{solve}} S'$

NR: $\begin{matrix} s_1 \rightarrow \\ s_2 \rightarrow \\ s_3 \rightarrow \\ * s_4 \dots \end{matrix} \rightarrow \boxed{\text{MLP}_\theta} \rightarrow \begin{matrix} e_1 \circ e_3 \rightarrow \\ e_2 \circ e_1 \rightarrow \\ e_3 \circ e_1 \rightarrow \\ e_3 \circ p_2 \rightarrow \end{matrix} \rightarrow \boxed{\text{MLP}_\phi} \rightarrow \begin{matrix} f_{12} \oplus \rightarrow f_1 \\ f_{13} \\ f_{21} \oplus \rightarrow f_2 \\ f_{23} \\ f_{31} \oplus \rightarrow f_3 \\ f_{32} \end{matrix} \xrightarrow{\text{solve}} S'$

* LMPL e. f. Attention