

AI Assignment2

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Example 1:

```
?- run.  
true.  
  
?- depth_first_search('jaipur','pune').  
  
The DFS-discovered path is:  
[jaipur, --> ,delhi, --> ,bhubaneshwar, --> ,cochin, --> ,trivandrum, --> ,  
nagpur, --> ,chandigarh, --> ,patna, --> ,baroda, --> ,pune]  
  
The path's total cost is: 10599  
true .  
  
?- best_first_search('jaipur','pune').  
  
The BFS-discovered path is:  
jaipur --> pune  
  
The path's total cost is: 1371  
true .
```

Example 2:

```
?- run.  
true.  
  
?- best_first_search('delhi','patna').  
  
The BFS-discovered path is:  
delhi --> patna  
  
The path's total cost is: 1086  
true .  
  
?- depth_first_search('nagpur','cochin').  
  
The DFS-discovered path is:  
[nagpur, --> ,cochin]  
  
The path's total cost is: 1608  
true
```

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Code:

```
assignment.pl
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assignment.pl
run :-
csv_read_file('graph.csv', Distances, [functor(distance)]), maplist(assert,Distances),
csv_read_file('graph.csv', DisHeuristics,[functor(heuristic)]), maplist(assert,DisHeuristics).

next_node(Current, Next, Path) :-
    distance(Current, Next,Dist),
    not(member(Next, Path)),
    assert(cost(Dist)).

% Depth First Search
depth_first_search(Initial_city,Target_city) :- depth_first(Initial_city, Target_city, [Initial_city]).

depth_first(Target_city, Target_city, _) :-
    assert(cities(Target_city)),distance_list_conversion(List),nl,
    write("The DFS-discovered path is: "),nl,
    write(List), cost_list_conversion(CostList),cost_summation(CostList,TotalCost),nl,nl,
    write("The path's total cost is: "),
    write(TotalCost).

depth_first(Initial_city, Target_city, Visited) :-
    next_node(Initial_city, Next_node, Visited),assert(cities(Initial_city)),assert(cities(" --> ")),
    depth_first(Next_node, Target_city, [Next_node|Visited]).

% converting distances further into a list format
distance_list_conversion([Px|Tail]):- retract(cities(Px)), distance_list_conversion(Tail).
distance_list_conversion([]).

% converting distances further into a list format
cost_list_conversion([Px|Tail]):- retract(cost(Px)), cost_list_conversion(Tail).
cost_list_conversion([]).

% converting distances further into a list format
cost_list_conversion_bfs([Px|Tail]):- retract(cost_bfs(Px)), cost_list_conversion_bfs(Tail).

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assignment.pl
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assignment.pl
% converting distances further into a list format
cost_list_conversion_bfs([Px|Tail]):- retract(cost_bfs(Px)), cost_list_conversion_bfs(Tail).
cost_list_conversion_bfs([]).

% cost summation on each of the steps is store in following variables
cost_summation([],0).
cost_summation([T|R],M) :- cost_summation(R,S), M is T+S.

% Best First Search
best_first_search(Initial_city,Target_city) :-
    heuristic(Initial_city,Target_city,Value), nl,
    write("The BFS-discovered path is: "),nl,
    write(Initial_city),bestFirstSearch(Initial_city,Target_city,[Value-Initial_city],[]).

bestFirstSearch(X,X,_) :- nl,nl,
    write("The path's total cost is: "),
    cost_list_conversion_bfs(CostListBfs),cost_summation(CostListBfs,NetCost),
    write(NetCost).

bestFirstSearch(_,_,[]) :- write("No more items exist on the Open List.").

bestFirstSearch(Initial_city,Target,OpenList,ClosedList) :-
    [Head1 | Tail] = OpenList,
    _-Initial_cityNode = Head1,

    findall(Value-NextNode, (distance(Initial_cityNode,NextNode,_), Initial_cityNode \== NextNode, not(member(NextNode,ClosedList))),heuristic(NextNode,Target,Value)),NN),

    append(NN,Tail,UpdatedOpenList),
    keysort(UpdatedOpenList,SortedOpenList),
    [HeadNode|_] = SortedOpenList,

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```

```
assignment.pl
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assignment.pl

% Best First Search
best_first_search(Initial_city,Target_city) :-
    heuristic(Initial_city,Target_city,Value), nl,
    write("The BFS-discovered path is: "),nl,
    write(Initial_city),bestFirstSearch(Initial_city,Target_city,[Value-Initial_city],[]).

bestFirstSearch(X,X,_,_) :- nl,nl,
    write("The path's total cost is: "),
    cost_list_conversion_bfs(CostListBfs,cost_summation(CostListBfs,NetCost),
    write(NetCost).

bestFirstSearch(_,_,[],_) :- write("No more items exist on the Open List.").

bestFirstSearch(Initial_city,Target,OpenList,ClosedList) :-
    [Head1 | Tail] = OpenList,
    _-Initial_cityNode = Head1,
    findall(Value-NextNode,(distance(Initial_cityNode,NextNode,_), Initial_cityNode \== NextNode, not(member(NextNode,ClosedList)),heuristic(NextNode,Target,Value)),NN),
    append(NN,Tail,UpdatedOpenList),
    keysort(UpdatedOpenList,SortedOpenList),
    [HeadNode|_] = SortedOpenList,
    _-BestNextNode = HeadNode,
    write(" --> "),write(BestNextNode),
    distance(Initial_city,BestNextNode,Dist),
    assert(cost_bfs(Dist)),
    bestFirstSearch(BestNextNode,Target,SortedOpenList,[Initial_city|ClosedList]).

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Thank You