

Understanding the DWB codebase & Usage

Parameters specified in `DataSetParameters.py`

K , n ('window'), δ ('stride'), λ ('regObs'), η ('cyclicThresh'), s ('cluster_sig').

See comments in this file for more detail & references to appropriate equations in paper.

5 Model Estimation

Algorithm 1: Dynamical Wasserstein Barycenter (DWB) Time-Series Estimation

Input:

$y_\tau, \tau = 1 \dots T$: Time series observations

K : Number of pure states

Hyperparameters:

n : Window size, δ : Window stride

λ : Weight on data-fit term

s : Variance on prior for Θ

(μ_0, σ_0) : Mean, var. of $p(\Theta)$ reference dist.

η : Convergence threshold

Output:

$\Theta = \{\{m_k, S_k\}_{k=1}^K\}$: Pure-state emission params

$\Gamma = \{x_0, \{\gamma_t\}_{t=1}^T\}$: Initial state and innovations

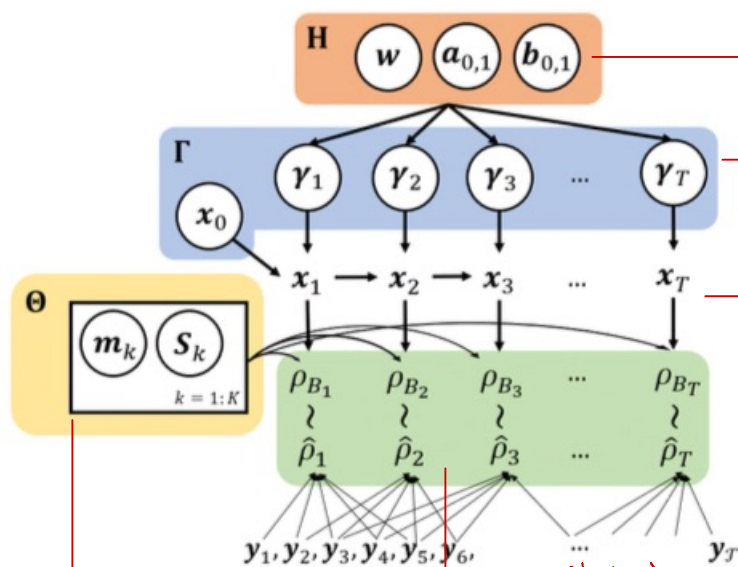
$X = \{x_t\}_{t=1}^T$: Wasserstein barycentric state vector
(Computed from Γ via (7))

$H = \{w, a_1, b_1\}$: Beta mixture parameters for transition dynamics

learned in
line 191 dwb.py
(muP, covP)

```

1 for  $t = 1, \dots, T$  where  $T = \lfloor \frac{T-(2n+1)}{\delta} \rfloor + 1$  do
2    $m_t = \frac{1}{(2n+1)} \sum_{i=1}^{2n+1} y_{\delta(t-1)+i}$ ; // Preprocessing of windowed
3    $S_t = \frac{1}{2n} \sum_{i=1}^{2n+1} (y_{\delta(t-1)+i} - m_t)(y_{\delta(t-1)+i} - m_t)^T$ ; // empirical distributions
4    $\hat{\rho}_t = \mathcal{N}(m_t, S_t)$ 
5 end
6  $c^{(0)} = F(\Gamma^{(0)}, \Theta^{(0)}, H^{(0)}, \{\hat{\rho}_t\}_{t=1}^T)$ ; // Cost function  $F$  defined in (9)
7 do
8    $\Gamma^{(n+1)}, H^{(n+1)} = \operatorname{argmin}_{\Gamma, H} F(\Gamma^{(n)}, \Theta^{(n)}, H^{(n)}, \{\hat{\rho}_t\}_{t=1}^T)$ ; // Adam
9    $\Theta^{(n+1)} = \operatorname{argmin}_{\Theta} F(\Gamma^{(n+1)}, \Theta^{(n)}, H^{(n+1)}, \{\hat{\rho}_t\}_{t=1}^T)$ ; // Riemannian line search
10   $c^{(n+1)} = F(\Gamma^{(n+1)}, \Theta^{(n+1)}, H^{(n+1)}, \{\hat{\rho}_t\}_{t=1}^T)$ 
11 while  $(c^{(n)} - c^{(n+1)}) > \eta$ ;
    
```



Sec 4.1 in paper

Sec 4.2 in paper

sec 3 in paper

eqns (6) & (9) in paper + sec 4.2 for prior on (4)

eqn (3) for weighted Barycentre eqn
8 sec 3 for empirical estimation

(learned)
hyperparameters
for the innov.
vectors (Beta dist)

Innovation
vectors which
determines
the state
vectors

State vector
indexed by sliding
window

Parameters (learned)
for pure state Gaussians

Model-predicted Wasserstein Barycentres
of pure states according to state vector
vs. empirically estimated Gaussians