

# EECS 442 Computer Vision, Fall 2016 Homework 1

**Due on Thursday, September 22, 2016 at 11:55pm.**

**Please submit your assignment on Canvas. Format PDF.**

Put your name on the top of the first page or it will not be graded!

## Problem 1

- (a) Derive the combined rotation and translation needed to transform world coordinate  $W$  into camera coordinate  $C$  as illustrated in figure 1. Notice that  $C_z$  and  $C_x$  belong to the plane defined by  $W_z$  and  $W_x$ .
- (b) Consider a square in the world coordinate system defined by the points  $a, b, c, d$ . Assume such a square has unit area. Show that the same square in the camera reference system has still unit area.
- (c) Are parallel lines in the world reference system still parallel in the camera reference system? Justify your answer.
- (d) Does the vector defined by  $a$  and  $b$  have the same orientation in both reference system? Justify your answer.

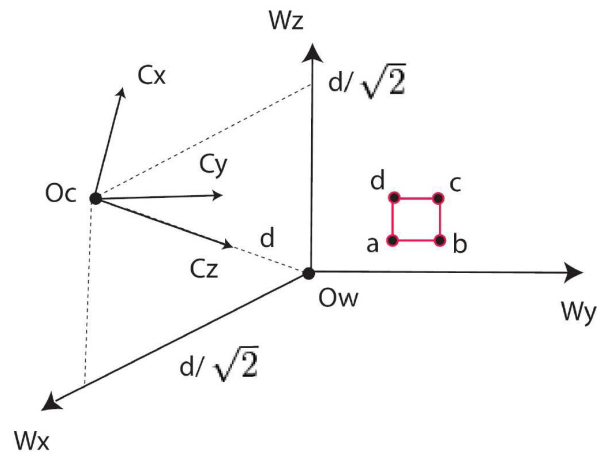


Figure 1

## Problem 2

Consider a perspective projection where a point

$$P = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

is projected onto an image plane  $\Pi'$  represented by  $k = f'$  as shown in figure 2. The first, second and third coordinate axes are denoted by  $\mathbf{i}, \mathbf{j}$ , and  $\mathbf{k}$ , respectively. Consider the projection of an infinitely long line

$$Q = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

in the world coordinate system where  $-\infty \leq t \leq -1$ . Calculate its two endpoints.

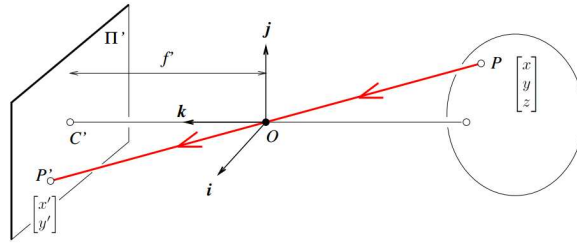


Figure 2

## Problem 3

Two points  $\mathbf{x}_1 = (1, 3)^\top$ ,  $\mathbf{x}_2 = (3, 1)^\top$  in  $\mathbb{R}^2$  are transformed to  $\mathbf{x}'_1$ ,  $\mathbf{x}'_2$  by a planar projective transformation  $H$

$$H = \begin{bmatrix} 1.520 & -1.902 & 1.000 \\ 3.300 & 23.490 & 3.000 \\ 1.000 & 3.000 & 1.000 \end{bmatrix}$$

- Find the line  $\mathbf{l}$  that passes through  $\mathbf{x}_1$  and  $\mathbf{x}_2$ .
- Find the line  $\mathbf{l}'$  that passes through  $\mathbf{x}'_1$  and  $\mathbf{x}'_2$ . You can use MATLAB to help with your computation.
- Derive an analytical expression that relates  $\mathbf{l}$  with  $\mathbf{l}'$  through  $H$ .