

Riemann Surfaces

Based on lectures by
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These notes are not endorsed by the lecturers. I have revised them outside lectures to incorporate supplementary explanations, clarifications, and material for fun. While I have strived for accuracy, any errors or misinterpretations are most likely mine.

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1 Introduction

Definition 1.1 (Riemann surface). A Riemann surface is a 1-dimensional complex manifold.

Definition 1.2 (Riemann surface). A Riemann surface is a topological space X together with open subsets $\{U_k\}_{k \in I}$ of X with $\cup_{k \in I} U_k = X$ together with maps $f_i: U_i \rightarrow \mathbb{C}$ such that

- (1) Each f_i is a homeomorphism onto its image.
- (2) If $U_i \cap U_j \neq \emptyset$ then $f_i: f_j^{-1}: f_i(U_i \cap U_j) \rightarrow f_i(U_i \cap U_j)$ are biholomorphic.

Remark 1.1. A function $f: \mathbb{C} \rightarrow \mathbb{C}$ is holomorphic at p if $f'(p) = \lim_{z \rightarrow p} \frac{f(z) - f(p)}{z - p}$ exists.

Definition 1.3 (Biholomorphism). A function $f: \mathbb{C} \rightarrow \mathbb{C}$ is called biholomorphic if it has an inverse and both f and f' are holomorphic.

Definition 1.4 (Atlas). The $\{(U_i, f_i)\}_{i \in I}$ are called an atlas of the Riemann surface.

Definition 1.5 (Chart). Each individual (U_i, f_i) is called a chart of the Riemann surface.

Example 1.1. Let $U \subset \mathbb{C}$. Then U can take an atlas with one chart which is the identity map.

Example 1.2 (Riemann sphere). Let $X = \{(z, t) \in \mathbb{C} \times \mathbb{R} : |z|^2 + t^2 = 1\}$. We identify \mathbb{C} with the equator of a sphere. Denote N and S the north and south poles of the sphere accordingly. We define $\pi_N: \mathbb{C} \rightarrow S$ such that π_N is the point on the sphere ... We can similarly define π_S and verify and their images are $X \setminus \{N\}$ and $X \setminus \{S\}$ accordingly.

X is a Riemann surface with an atlas consisting of $\pi_S: X \setminus \{S\} \rightarrow \mathbb{C}$ and $\pi_N: X \setminus \{N\} \rightarrow \mathbb{C}$. We denote the Riemann sphere as $\hat{\mathbb{C}}$.

Definition 1.6 (Biholomorphism of Riemann surfaces). Let $(X, (U_i, f_i))$, $(Y, (W_i, g_i))$ be two Riemann surfaces. A biholomorphism between them is a homeomorphism $X \xrightarrow{\phi} Y$ such that $g_i \circ \phi \circ f_i^{-1}$ are biholomorphisms on their domains of definition.

A main problem in Riemann surfaces was classifying certain types of Riemann surfaces up to biholomorphisms.

Theorem 1.1. (Riemann mapping theorem). *Any two proper open simply connected subsets of \mathbb{C} are biholomorphic.*

A generalization of the Riemann mapping theorem is the uniformization theorem proved by Kobe in 1907.

Theorem 1.2. (Uniformization theorem). *Any simply connected Riemann surface is biholomorphic to one of the following:*

- (1) \mathbb{C}
- (2) $\hat{\mathbb{C}}$
- (3) $\mathbb{H} = \{z \in \mathbb{C} : \text{Im}(z) > 0\}$

We will give a proof for this theorem in the end of the class.

A natural question that arises is what about non simply connected Riemann surfaces.

Theorem 1.3. (Uniformization theorem, part II). *Any connected Riemann surface is biholomorphic either to $\hat{\mathbb{C}}$ or to a quotient of \mathbb{C} or \mathbb{H} by a properly discontinuous torsion free subgroup of biholomorphisms.*

Remark 1.2. Biholomorphisms of $U = \mathbb{C}$ or \mathbb{H} (or any subset of \mathbb{C}) forms a group under composition. We denote that group by $Bih(U)$.

Definition 1.7 (Properly discontinuity). A countable subgroup of $Bih(U)$ is said to be properly discontinuous if for all compact $K \subseteq U$, the set $\{g \in G: gK \cap K \neq \emptyset\}$ is finite.

Definition 1.8 (Torsion free group). $G \subseteq Bih(U)$ is torsion free if $gp = p$ for some $p \in U$ implies g is the identity.

We can now define the quotient space U/G where $p \sim q$ if there exists $g \in G$ such that $gp = q$.

Introduce a topology on U/G which is the coarsest topology such that the canonical projections $U \rightarrow U/G$ are continuous.

Under the assumptions that G is properly discontinuous and torsion-free, U/G is a Riemann surface with the following charts. By assumptions on G , we can find for any $p \in U$ a neighbourhood W of $p \in U$ such that $\pi: U \rightarrow U/G$ is a homeomorphism onto its image when restricted to W .

So, restrictions of π to these neighbourhoods W give you an atlas.