



Probabilistic Reasoning

Russell Chap 13, 14, 15

Luger Chap. 5, 9



Managing Uncertainty

- Abduction

- If $P \Rightarrow Q$, Q then $P \rightarrow$ Not sound

- Most diagnostic rules are abduction

- True implication (causal relation):
 - *Problem \Rightarrow Symptom*
Ex> Problem in battery \Rightarrow Light gone
- Expert system rule:
 - *Symptom \Rightarrow Problem*
Ex> Light gone \Rightarrow Problem in battery
 \rightarrow Not 100% true
 \rightarrow Need measure of uncertainty



Certainty Factor

■ Certainty Theory


- Confidence measure (expert heuristic) + combining rules

E(evidence) → H(hypothesis) : Confidence?

- Certainty Factor(CF) of H(hypothesis) given E(evidence)

- $CF(H | E) = MB(H | E) - MD(H | E)$
- MB: Measure of belief of H given E
- MD: Measure of disbelief of H given E

- Inference with CF

- Rule: if P then Q (CF = 0.9)
- Fact: P (CF = 0.9)  Q (CF = $0.9 * 0.9 = 0.81$)

- Combining CF

- $CF(P1 \text{ and } P2) = \min (CF(P1), CF(P2))$
- $CF(P1 \text{ or } P2) = \max (CF(P1), CF(P2))$



Certainty Factor

■ Example

- Rule: $(P1 \text{ and } P2) \text{ or } P3 \rightarrow R1(0.7) \text{ and } R2(0.3)$
- During production cycle, it is found that

$$CF(P1) = 0.6$$

$$CF(P2) = 0.4$$

$$CF(P3) = 0.2$$

- Then

$$\begin{aligned} CF((P1 \text{ and } P2) \text{ or } P3) &= \max(\min(0.6, 0.4), 0.2) \\ &= 0.4 \end{aligned}$$

$$\therefore CF(R1) = 0.4 * 0.7 = 0.28$$

$$CF(R2) = 0.4 * 0.3 = 0.12$$

- Purpose

- ## ■ Inference

- Example rule

- 5

Fuzzy Logic

- Fuzzy set

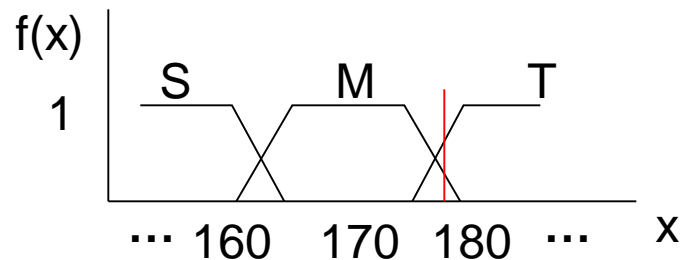
- Set membership is a function to $[0, 1]$

Ex> S = set of small integer

$$fs(1) = 1.0, fs(5) = 0.7, fs(100) = 0.001$$

- Membership function

- Sets: S, M, T



→ $f_T(178) = 0.7, f_M(178) = 0.3$



Fuzzy Logic

- Fuzzy logic

- If $f_A(x) = a$, $f_B(x) = b$ then

$$f_{A \cap B}(x) = \min(a, b)$$

$$f_{A \cup B}(x) = \max(a, b)$$

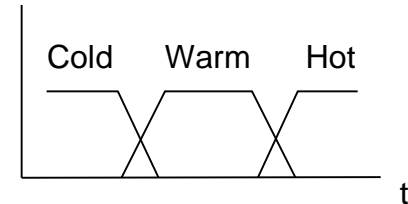
- Fuzzy rules

- If (speed = high) and (no. of cars = many) then (push brake)
 - If (temp = hot) then (fan speed = high)

Reasoning with Fuzzy Logic

1. Define fuzzy sets

- Temperature Hot, Warm, Cold, ...



2. Build logical rules with the fuzzy sets

- If (temp is Hot) then (fan_speed is High)

3. Perform inference

1. Fuzzification : real value (30° C) \rightarrow fuzzy set (Hot)
2. Apply rules : use fuzzy logic
3. Defuzzification : fuzzy set (High) \rightarrow real_value (4500 RPM)

Reasoning with Fuzzy Logic

- Example: Inverted Pendulum

- Input: $x_1 = \theta$, $x_2 = d\theta/dt$
- Output: $u = \text{movement } M$

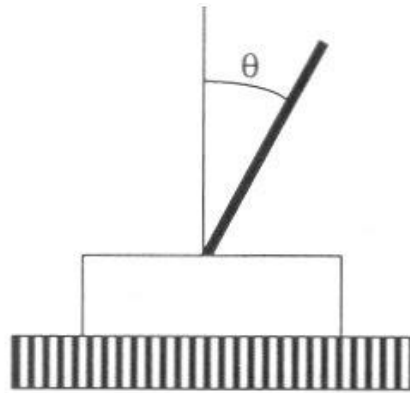


Figure 7.15 The inverted pendulum and the angle θ and $d\theta/dt$ input values.



Reasoning with Fuzzy Sets

- Fuzzy set

- x_1, x_2 : Z(zero), P(positive), N(negative)
- u : Z, P, PB(positive big), N, NB(negative big)

- Rules

1. If ($x_1 = P$ and $x_2 = Z$) then $u = P$
2. If ($x_1 = P$ and $x_2 = N$) then $u = Z$
3. If ($x_1 = Z$ and $x_2 = Z$) then $u = Z$
4. If ($x_1 = Z$ and $x_2 = N$) then $u = N$
5. . . .

Reasoning with Fuzzy Sets

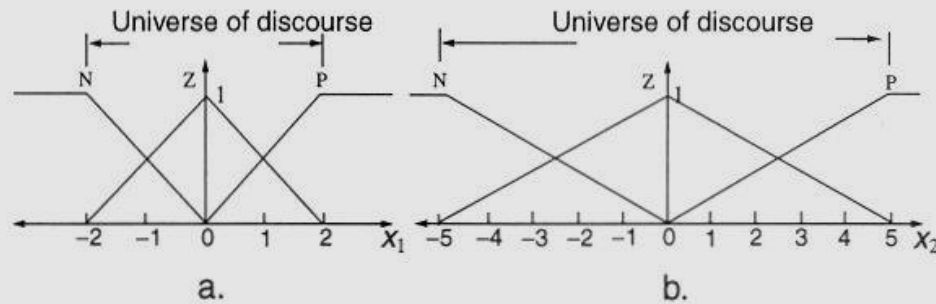


Figure 7.16 The fuzzy regions for the input values θ a. and $d\theta/dt$ b.

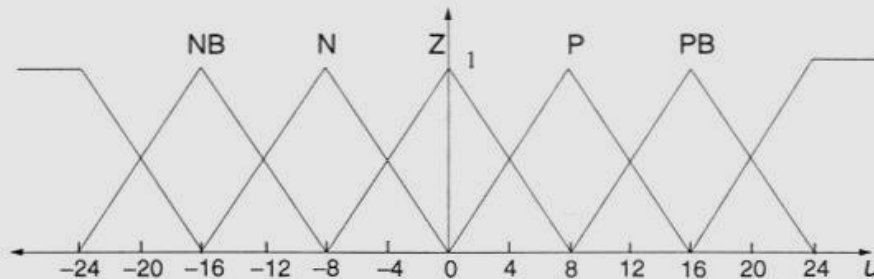
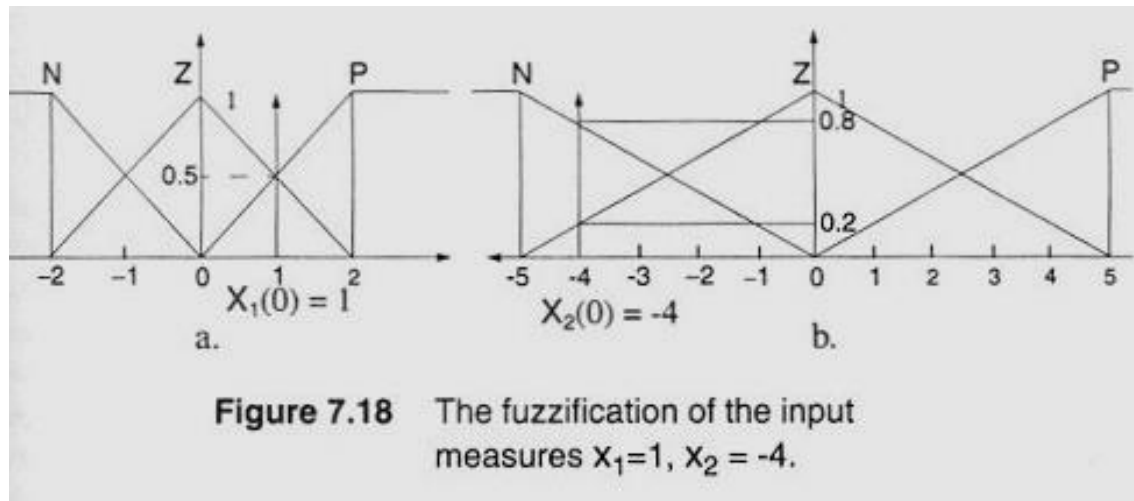


Figure 7.17 The fuzzy regions of the output value u , indicating the movement of the pendulum base.

Reasoning with Fuzzy Sets

- When $x_1 = \theta = 1$, $x_2 = d\theta/dt = -4$
 1. from fuzzy set membership
 - x_1 : 0.5P, 0.5Z
 - x_2 : 0.8N, 0.2Z



Reasoning with Fuzzy Sets

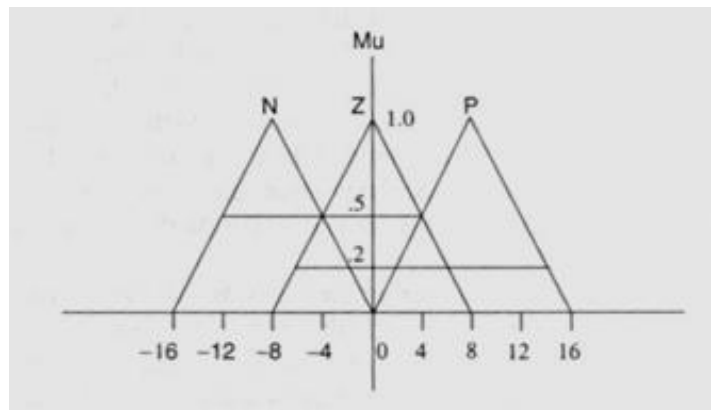
2. From fuzzy rules

$u = 0.2P$ (1. If $x_1 = P(0.5)$ and $x_2 = Z(0.2)$ then $u = P(\min(0.5, 0.2))$)

$u = 0.5Z$ (2. If $x_1 = P(0.5)$ and $x_2 = N(0.8)$ then $u = Z(\min(0.5, 0.8))$)

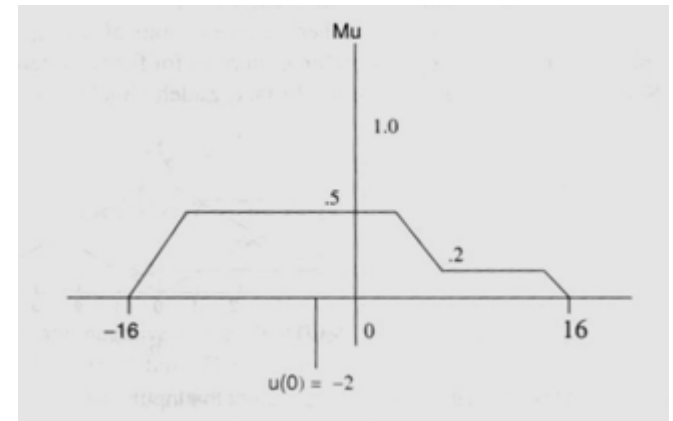
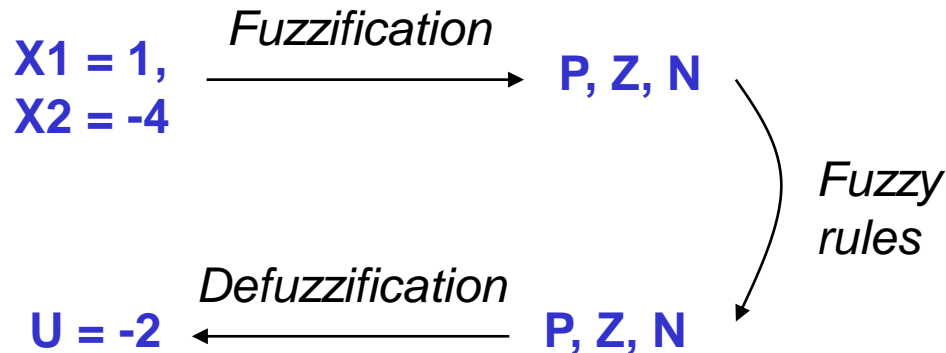
$u = 0.2Z$ (3. If $x_1 = Z(0.5)$ and $x_2 = Z(0.2)$ then $u = Z(\min(0.5, 0.2))$)

$u = 0.5N$ (4. If $x_1 = Z(0.5)$ and $x_2 = N(0.8)$ then $u = N(\min(0.5, 0.8))$)



Reasoning with Fuzzy Sets

3. From fuzzy set membership,
computing centroid of the union
 $\rightarrow u = -2$





Probability

- For an experiment that produces outcomes
 - Sample space S : set of all outcomes
 - Event E : a subset of S
 - Probability $P(E) = |E|/|S|$ (if outcomes are equally likely)
- Probability distribution
 - Function $P: x \rightarrow [0, 1]$ (x : random variable)

S	x	P(x)	y(odd)	P(y)
1	1	1/6	1	1/2
2	2	1/6	0	1/2
...	
6	6	1/6	0	

S	x(# of H)	P(x)
HH	2	1/4
HT	1	1/2
TH	1	
TT	0	1/4



Probability

- Joint probability distribution

- $P(x,y)$: represents joint probability distribution of x and y
- Example
 - Gas{true,false}, Meter{empty, full}, Start{yes, no}
 - $P(G,M,S)$:

Gas	Meter	Start	$P(G,M,S)$
false	empty	no	0.1386
false	empty	yes	0.0014
false	full	no	0.0594
false	full	yes	0.0006
true	empty	no	0.0240
true	empty	yes	0.0560
true	full	no	0.2160
true	full	yes	0.5040



Probability

Gas	Meter	Start	P(G,M,S)
false	empty	no	0.1386
false	empty	yes	0.0014
false	full	no	0.0594
false	full	yes	0.0006
true	empty	no	0.0240
true	empty	yes	0.0560
true	full	no	0.2160
true	full	yes	0.5040

- $P(\text{Gas}=\text{false}, \text{Meter}=\text{empty}, \text{Start}=\text{no}) = 0.1386$

- $P(\text{Start}=\text{yes}) = 0.5620$

➡ *Prior probability*

- $P(\text{Start}=\text{yes}), \text{ given that Meter}=\text{empty} ?$

➡ *Posterior probability (conditional probability)*

Conditional Probability

- Conditional probability

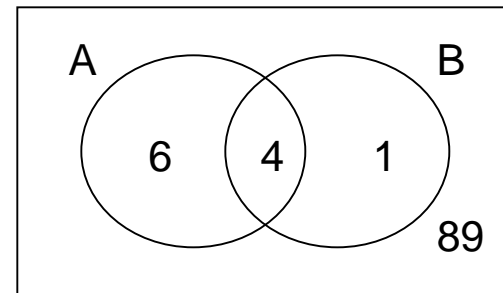
- $P(A|B) = P(A \cap B) / P(B)$

- Example

- $P(A \cap B) = 4 / 100 = 0.04$

- $P(B) = 5 / 100 = 0.05$

- $P(A | B) = 4 / 5 = 0.80$



- Independence

- $P(A|B) = P(A)$

- $P(A \cap B) = P(A|B) P(B)$

$$= P(A) P(B) \text{ if } A, B \text{ are independent}$$



Bayesian Reasoning

- Let H: Hypothesis (Problem)
E: Evidence (Symptom)
- Then the probability of $E \rightarrow H$ is $P(H | E)$

$$\begin{aligned}P(H \cap E) &= P(H | E) * P(E) \\ &= P(E | H) * P(H)\end{aligned}$$

\therefore

$$P(H | E) = \frac{P(E | H) * P(H)}{P(E)}$$



Bayesian Reasoning

- If we want to compare $P(H1 | E)$, $P(H2 | E)$, ...

$$P(H1 | E) = \frac{P(E | H1) * P(H1)}{P(E)}$$

$$P(H2 | E) = \frac{P(E | H2) * P(H2)}{P(E)}$$

same

∴

$$P(Hi | E) = \alpha P(E | Hi) P(Hi)$$



Bayesian Reasoning

- For multiple, conditionally independent evidences

$$P(E1, E2, \dots E_n | H_i) = P(E1 | H_i)P(E2 | H_i) \dots P(E_n | H_i)$$

$$\therefore P(H_i | E1, E2, \dots E_n)$$

$$= \alpha P(E1, E2, \dots E_n | H_i) P(H_i)$$

$$= \alpha P(E1 | H_i) P(E2 | H_i) \dots P(E_n | H_i) P(H_i)$$

$$= \alpha P(H_i) \prod_{i=1..n} P(E_i | H_i)$$

*These probabilities are obtained
from sample data*



Bayesian Classifier Example

No.	age	income	student	credit_rating	buys_computer
1	<=30	high	no	fair	no
2	<=30	high	no	excellent	no
3	31...40	high	no	fair	yes
4	>40	medium	no	fair	yes
5	>40	low	yes	fair	yes
6	>40	low	yes	excellent	no
7	31...40	low	yes	excellent	yes
8	<=30	medium	no	fair	no
9	<=30	low	yes	fair	yes
10	>40	medium	yes	fair	yes
11	<=30	medium	yes	excellent	yes
12	31...40	medium	no	excellent	yes
13	31...40	high	yes	fair	yes
14	>40	medium	no	excellent	no

Bayesian Classifier Example

E

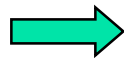
X: (age="<30", income="medium",
student="yes", credit="fair")



yes / no ?

H

- $P(\text{Yes} \mid X) = \alpha P(\text{Yes}) P(X \mid \text{Yes})$
 $= \alpha P(\text{Yes}) P(<30 \mid \text{Yes}) P(m \mid \text{Yes}) P(y \mid \text{Yes}) P(f \mid \text{Yes})$
 $= \alpha \times 9/14 \times 2/9 \times 4/9 \times 6/9 \times 6/9 = 0.028 \alpha$
- $P(\text{No} \mid X) = \alpha P(\text{No}) P(X \mid \text{No})$
 $= \alpha P(\text{No}) P(<30 \mid \text{No}) P(m \mid \text{No}) P(y \mid \text{No}) P(f \mid \text{No})$
 $= \alpha \times 5/14 \times 3/5 \times 2/5 \times 1/5 \times 2/5 = 0.007 \alpha$



X is classified to **yes**



Bayesian Classifier Example

- Category C1 : # of sample documents – 60
Keywords - information (2), network (12), algorithm (6), system (10)
- Category C2 : # of sample documents – 40
Keywords - information (10), database (8), algorithm (4), system (8)
- New document **D**: has keywords - **information, system**

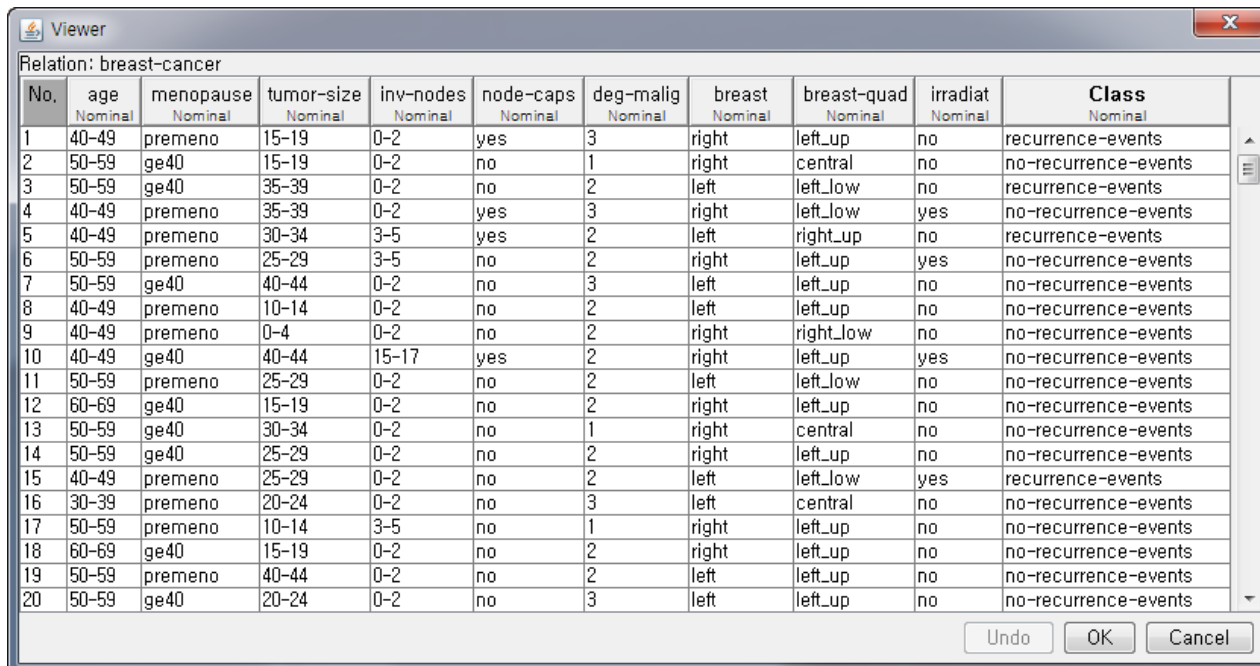
$$\begin{aligned} P(C1 \mid \text{information, system}) \\ &= k * P(\text{information} \mid C1) * P(\text{system} \mid C1) * P(C1) \\ &= k * 2/30 * 10/30 * 60/100 = 0.013 k \end{aligned}$$

$$\begin{aligned} P(C2 \mid \text{information, system}) \\ &= k * P(\text{information} \mid C2) * P(\text{system} \mid C2) * P(C2) \\ &= k * 10/30 * 8/30 * 40/100 = 0.036 k \end{aligned}$$

 D is classified to C2

Bayesian Classifier Example

- Breast cancer classification
 - Compute $P(\text{recur} \mid \text{age}=40-49, \text{menop}=\text{ge40}, \dots)$
 - Based on $P(\text{recur})$, $P(\text{age}=40-49 \mid \text{recur})$, $P(\text{menop}=\text{ge40} \mid \text{recur})$, ...



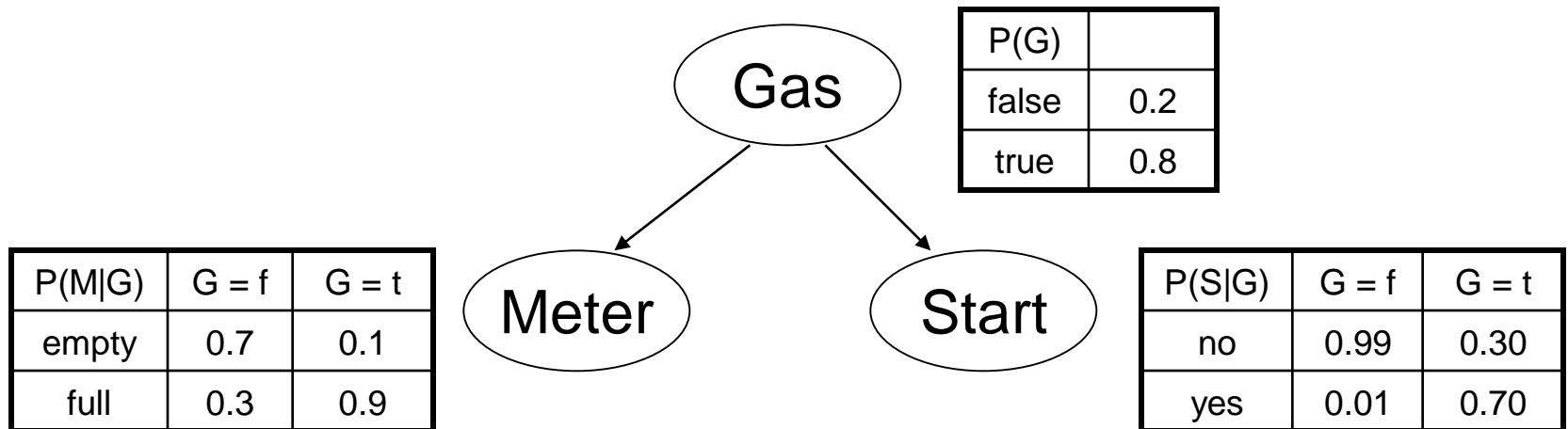
Relation: breast-cancer

No.	age Nominal	menopause Nominal	tumor-size Nominal	inv-nodes Nominal	node-caps Nominal	deg-malig Nominal	breast Nominal	breast-quad Nominal	irradiat Nominal	Class Nominal
1	40-49	premeno	15-19	0-2	yes	3	right	left_up	no	recurrence-events
2	50-59	ge40	15-19	0-2	no	1	right	central	no	no-recurrence-events
3	50-59	ge40	35-39	0-2	no	2	left	left_low	no	recurrence-events
4	40-49	premeno	35-39	0-2	yes	3	right	left_low	yes	no-recurrence-events
5	40-49	premeno	30-34	3-5	yes	2	left	right_up	no	recurrence-events
6	50-59	premeno	25-29	3-5	no	2	right	left_up	yes	no-recurrence-events
7	50-59	ge40	40-44	0-2	no	3	left	left_up	no	no-recurrence-events
8	40-49	premeno	10-14	0-2	no	2	left	left_up	no	no-recurrence-events
9	40-49	premeno	0-4	0-2	no	2	right	right_low	no	no-recurrence-events
10	40-49	ge40	40-44	15-17	yes	2	right	left_up	yes	no-recurrence-events
11	50-59	premeno	25-29	0-2	no	2	left	left_low	no	no-recurrence-events
12	60-69	ge40	15-19	0-2	no	2	right	left_up	no	no-recurrence-events
13	50-59	ge40	30-34	0-2	no	1	right	central	no	no-recurrence-events
14	50-59	ge40	25-29	0-2	no	2	right	left_up	no	no-recurrence-events
15	40-49	premeno	25-29	0-2	no	2	left	left_low	yes	recurrence-events
16	30-39	premeno	20-24	0-2	no	3	left	central	no	no-recurrence-events
17	50-59	premeno	10-14	3-5	no	1	right	left_up	no	no-recurrence-events
18	60-69	ge40	15-19	0-2	no	2	right	left_up	no	no-recurrence-events
19	50-59	premeno	40-44	0-2	no	2	left	left_up	no	no-recurrence-events
20	50-59	ge40	20-24	0-2	no	3	left	left_up	no	no-recurrence-events

Undo OK Cancel

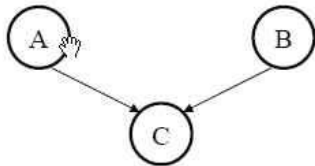
Bayesian Belief Network

- Nodes: Random variables
- Edges: Direct influence
- Each node x stores $P(x \mid \text{parents}(x))$

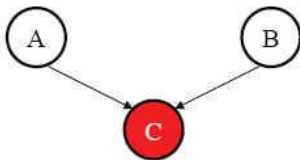


$$P(G, M, S) = P(G) P(M \mid G) P(S \mid G)$$

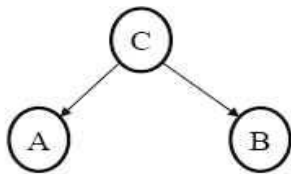
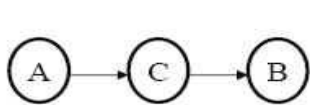
Dependency



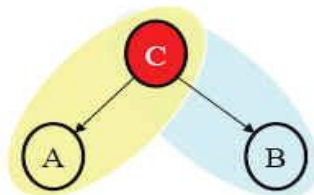
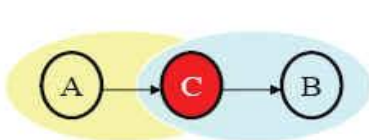
- A, B are independent
 - $P(B|A) = P(B)$



- A, B are *conditionally* dependent
 - $P(B|A,C) \neq P(B|C)$



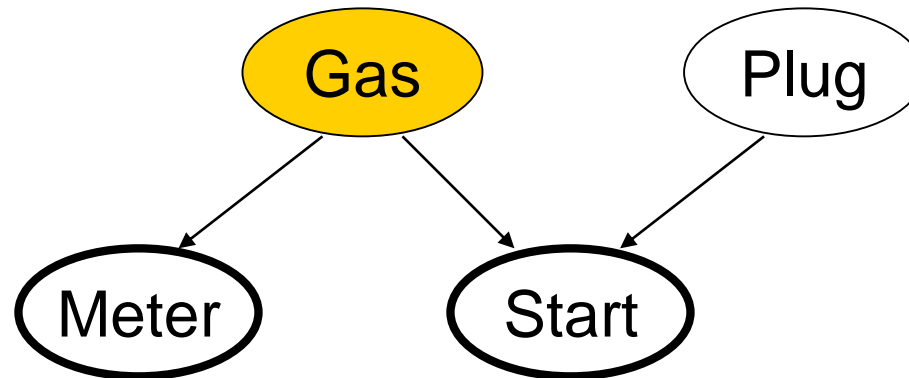
- A, B are dependent
 - $P(B|A) \neq P(B)$



- A, B are *conditionally* independent
 - $P(B|A,C) = P(B|C)$

Dependency

- Gas and Start are dependent
- Gas and Plug are independent
- Gas and Plug are conditionally dependent given Start
- Meter and Start are conditionally independent given Gas
 - $P(S | M, G) = P(S | G)$





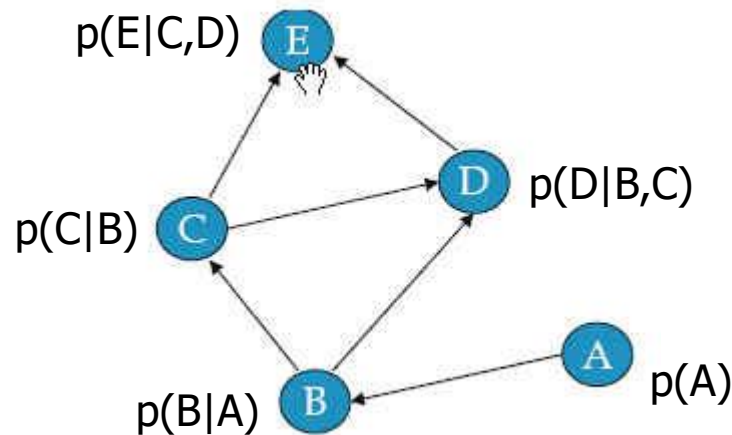
Chain Rule and Independence

- $P(A,B) = \frac{P(A,B)}{P(A)} P(A) = P(B|A) P(A)$
- $P(A,B,C) = \frac{P(A,B,C)}{P(A,B)} \frac{P(A,B)}{P(A)} P(A) = P(C|B,A) P(B|A) P(A)$
- $P(A,B,C,D) = P(D|C,B,A) P(C|B,A) P(B|A) P(A)$

- $P(G,M,S) = P(S | G,M) P(M | G) P(G) \quad (\text{Chain rule})$
 $= P(S | G) P(M | G) P(G)$
(If S, M are conditionally independent given G)
 $= P(S) P(M) P(G)$
(If S, M, G are all independent)

Computing Joint Distribution from Bayesian Network

- In general,
Joint probability \leftarrow *product of conditional probabilities*
- Ex>



$$\begin{aligned} P(A,B,C,D,E) &= P(A)P(B|A)P(C|A,B)P(D|A,B,C)P(E|A,B,C,D) \\ &= P(A)P(B|A)P(C|B) \quad P(D|B,C) \quad P(E|C,D) \end{aligned}$$

Bayesian Reasoning with Full Probability Distribution

Gas	Meter	Start	P(G,M,S)
false	empty	no	0.1386
false	empty	yes	0.0014
false	full	no	0.0594
false	full	yes	0.0006
true	empty	no	0.0240
true	empty	yes	0.0560
true	full	no	0.2160
true	full	yes	0.5040

- $P(\text{Gas=false, Meter=empty, Start=no}) = 0.1386$
- $P(\text{Gas=false}) = 0.2$
- $P(\text{Start=yes} \mid \text{Meter=full}) = P(S=\text{yes}, M=\text{full}) / P(M=\text{full})$
 $= (0.5040 + 0.0006) / (0.5040 + 0.0006 + 0.2160 + 0.0594)$
 $= 0.6469$



Bayesian Reasoning with Full Probability Distribution

- $P(\text{Start}=\text{yes} \mid \text{Meter}=\text{full})$

Gas	Meter	Start	$P(G,M,S)$
false	full	no	0.0594
false	full	yes	0.0006
true	full	no	0.2160
true	full	yes	0.5040

Select M=full

Gas	Start	$P(G,M,S)$
ALL	no	0.2754
ALL	yes	0.5046

Sum G

Start	$P(G,M,S)$
no	0.3531
yes	0.6469

Normalize



Reasoning with Bayesian Belief Network

- Inference for $P(H \mid E)$
 - From the product of probability table,
 1. Remove all rows except E
 2. Compute product
 3. Sum over irrelevant variables
 4. Normalize
- Example
 - $P(S=\text{yes} \mid M=\text{full})$

Reasoning with Bayesian Belief Network

$p(S, G, M)$

P(G)	
false	0.2
true	0.8

P(M G)	G = f	G = t
empty	0.7	0.1
full	0.3	0.9

P(S G)	G = f	G = t
no	0.99	0.30
yes	0.01	0.70

$p(S, G \mid M=f)$

S	G = f	G = t
no	0.0594	0.2160
yes	0.0006	0.5040

Remove M=empty

Product

$p(S \mid M=f)$

S	
no	0.2754
yes	0.5046

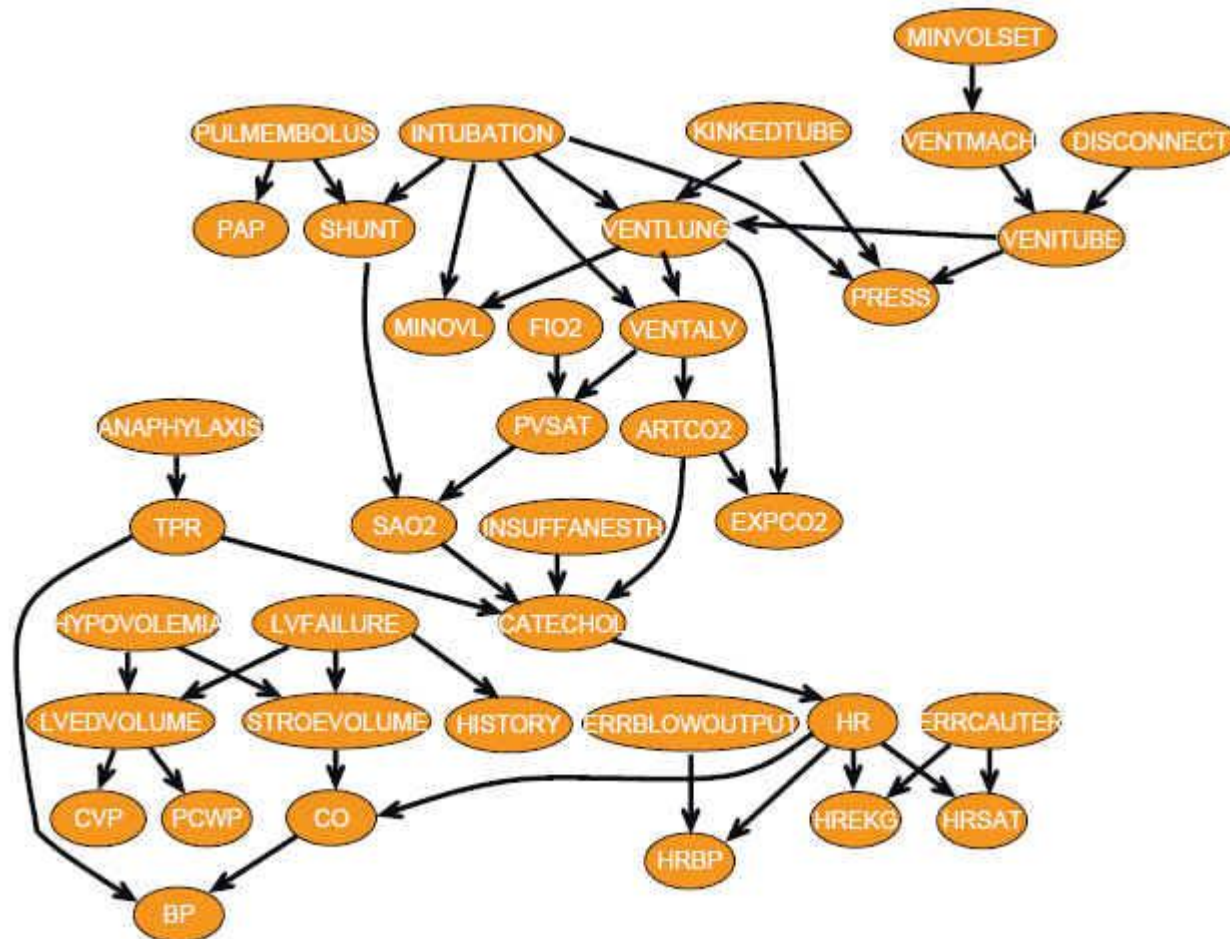
Sum over G

$p(S \mid M=f)$

S	
no	0.3531
yes	0.6469

Normalize

Advantage of Reasoning with Bayesian Belief Network



Advantage of Reasoning with Bayesian Belief Network

- Assume 20 boolean variables: 19 E \rightarrow 1 H
- Compute $P(H \mid E_1, E_2, \dots, E_{19})$
$$= \frac{P(E_1, E_2, \dots, E_{19} \mid H) P(H)}{P(E_1, E_2, \dots, E_{19})}$$

1) From full joint distribution

$P(H, E_1, E_2, \dots, E_{19})$

\rightarrow We need to know $2^{20} = 1,048,576$ prob.

 Almost impossible

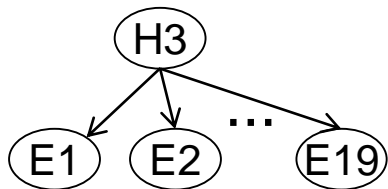
H	E1	E2	...	$P(H, E_1, E_2, \dots)$
T	T	T	...	0.xxxx
		
F	F	F	...	0.xxxx

Advantage of Reasoning with Bayesian Belief Network

2) Assume complete independences (Naïve Bayesian)

$$P(E1 | H) P(E2 | H) \dots P(E19 | H) P(H)$$

$$\rightarrow 4 \cdot 19 + 2 = 78 \text{ prob.}$$



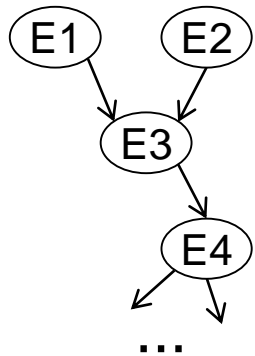
➡ But the evidences are not actually independent

2) Consider actual dependences (Bayesian Network)

$$P(E1) P(E2) P(E3 | E1, E2) \dots$$

(assume less than 2 parents in Bayesian Network)

$$\rightarrow \text{less than } 8 \cdot 20 = 160 \text{ prob.}$$

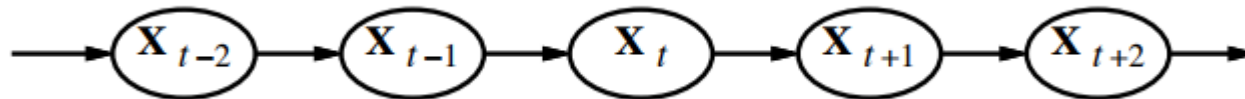


➡ Actual dependences are considered, yet need small # of probabilities.



Markov Model

- Markov process (Markov chain)
 - Probability of a state at time t depends on its previous n states
$$P(X_t | X_{t-1}, X_{t-2}, X_{t-3}, \dots, X_{t-n})$$
- First-order Markov process
 - Probability of a state at time t depends on its previous 1 state
$$P(X_t | X_{t-1})$$

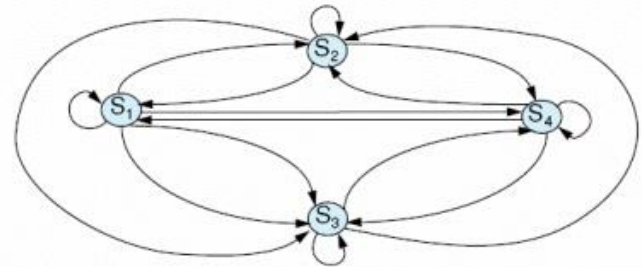


Markov Model

■ Example

- 4 states: S1(sunny), S2(cloudy), S3(Foggy), S4(Rainy)

	S ₁	S ₂	S ₃	S ₄
S ₁	0.4	0.3	0.2	0.1
S ₂	0.2	0.3	0.2	0.3
S ₃	0.1	0.3	0.3	0.3
S ₄	0.2	0.3	0.3	0.2



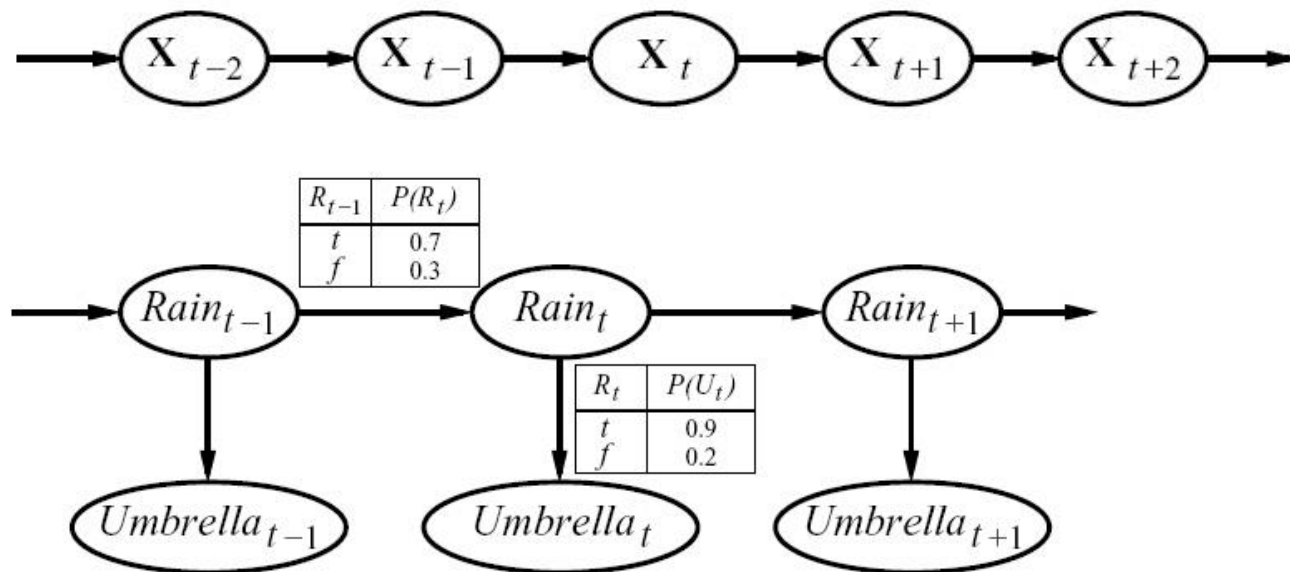
- Today is sunny. Prob. of next 2 days are rainy?

$$\begin{aligned} P(S_1, S_4, S_4) &= P(S_1) P(S_4 | S_1) P(S_4 | S_1, S_4) \\ &= P(S_1) P(S_4 | S_1) P(S_4 | S_4) \\ &= 1 * 0.1 * 0.2 = 0.02 \end{aligned}$$

Hidden Markov Model (HMM)

■ HMM

- States are “hidden”
- Probability of observation is given. $P(O_j | S_i)$





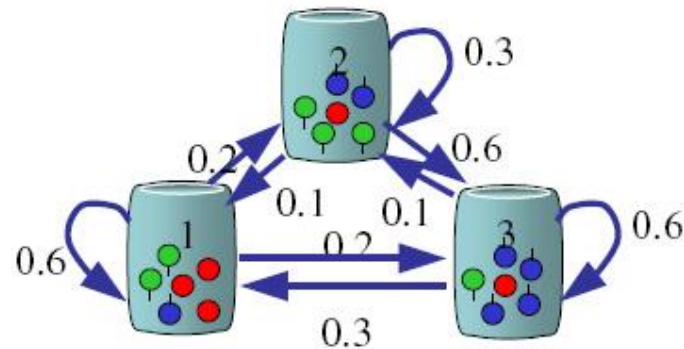
Hidden Markov Model (HMM)

$$\begin{aligned} &P(s1 \dots sn \mid o1 \dots on) \\ &= \frac{P(o1 \dots on \mid s1 \dots sn) P(s1 \dots sn)}{P(o1 \dots on)} \\ &= \alpha P(o1 \dots on \mid s1 \dots sn) P(s1 \dots sn) \\ &= \alpha P(o1 \mid s1)P(o2 \mid s2)...P(on \mid sn) P(s1 \dots sn) \\ &= \alpha P(o1 \mid s1)P(o2 \mid s2)...P(on \mid sn) P(s1)P(s2 \mid s1)...P(sn \mid sn-1) \\ &= \prod_{i=1..n} P(o_i \mid s_i) P(s_i \mid s_{i-1}) \end{aligned}$$

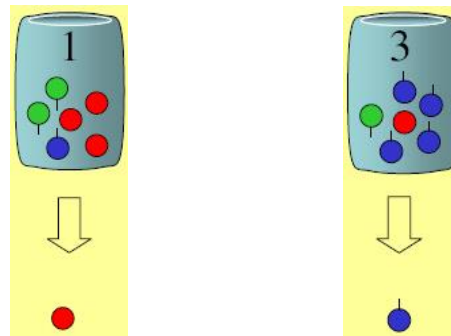
Hidden Markov Model (HMM)

- Example

- Markov process

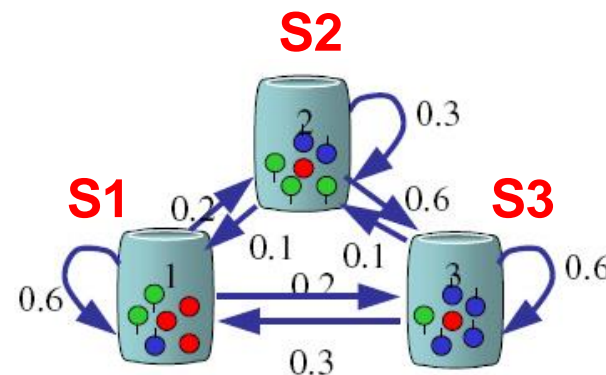
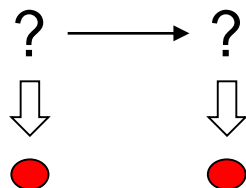


- Output process



Hidden Markov Model (HMM)

- Which cup is selected? → hidden
- Only output sequence is observed



- Most likely sequence

$$= \operatorname{argmax}_X P(X_0, X_1, \dots, X_t \mid E_1, E_2, \dots, E_t)$$

$$= \operatorname{argmax}_{x_1, x_2} (1/3 * (\mathbf{S1}) * 3/6 * 0.6(\mathbf{S1}) * 3/6,$$

$$1/3 * (\mathbf{S1}) * 3/6 * 0.2(\mathbf{S2}) * 1/6,$$

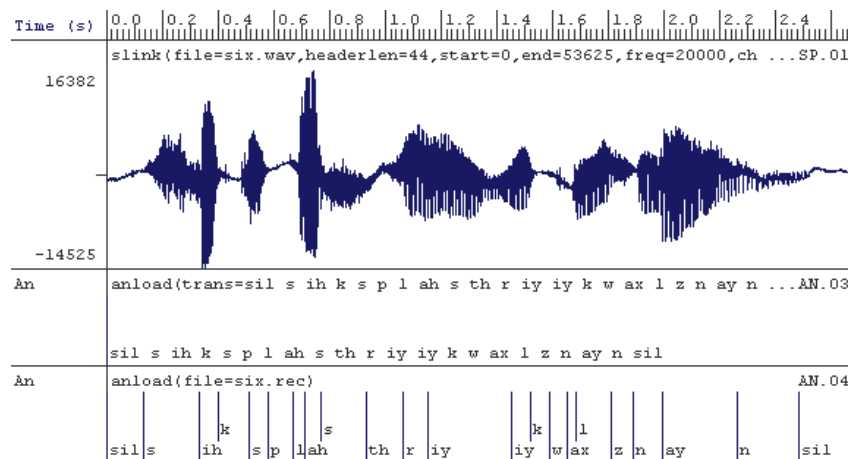
$$1/3 * (\mathbf{S1}) * 3/6 * 0.2(\mathbf{S3}) * 1/6,$$

$$1/3 * (\mathbf{S2}) * 1/6 * 0.1(\mathbf{S1}) * 3/6, \dots) = \mathbf{S1}, \mathbf{S1}$$

Speech Recognition

- The problem

- Observed: sequence of acoustic signals
- Determine: which phoneme? → which word?



➡ Compute $P(\text{phoneme} \mid \text{signal})$ by using HMM

$$\begin{aligned} &\text{Find } \operatorname{argmax} P(p_1, p_2, p_3, \dots \mid o_1, o_2, o_3, \dots) \\ &= \operatorname{argmax} \prod_{i=1..n} P(o_i \mid p_i) P(p_i \mid p_{i-1}) \end{aligned}$$

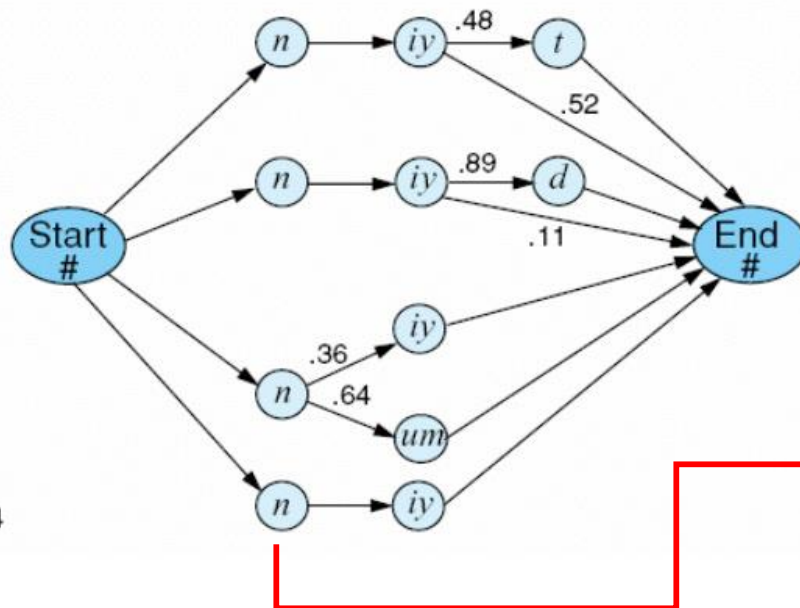
Speech Recognition

neat
.00013

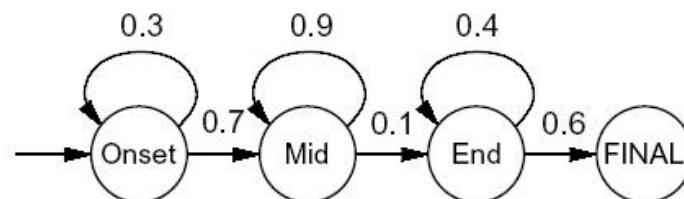
need
.00056

new
.001

knee
.000024



Phone HMM for [m]:



Output probabilities for the phone HMM:

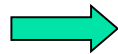
Onset:	Mid:	End:
C1: 0.5	C3: 0.2	C4: 0.1
C2: 0.2	C4: 0.7	C6: 0.5
C3: 0.3	C5: 0.1	C7: 0.4

*state
(hidden)*

observation

Handwriting Recognition

- Hand-written character recognition



a or 6?



5 or S?



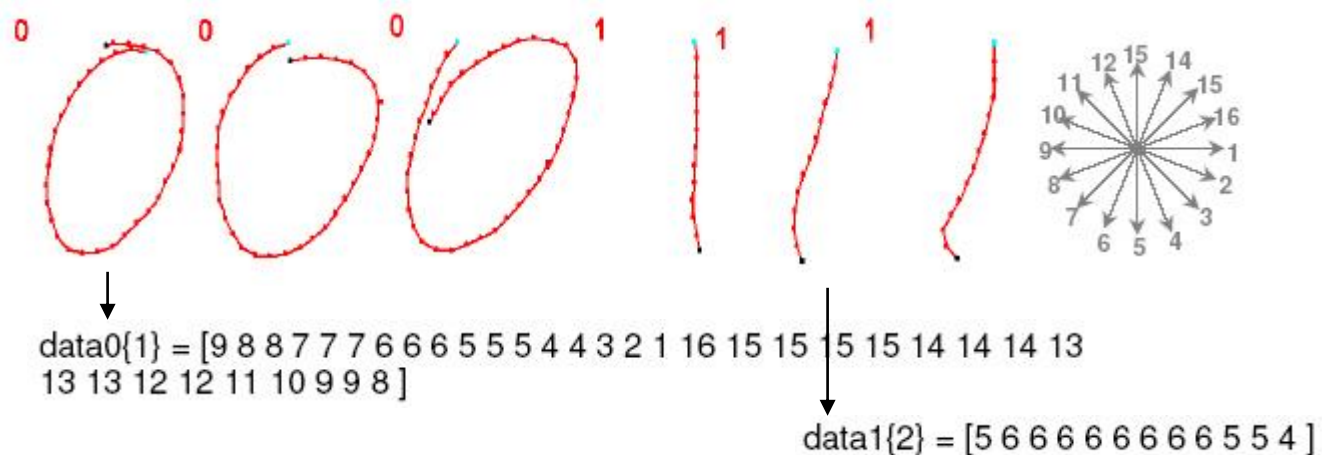
Handwriting Recognition

■ The problem

- Observed: sequence of moving directions ($d_1 \dots d_n$)
- Determine: which character? - states ($s_1 \dots s_n$)

Find $\text{argmax } P(s_1 \dots s_n \mid d_1 \dots d_n)$

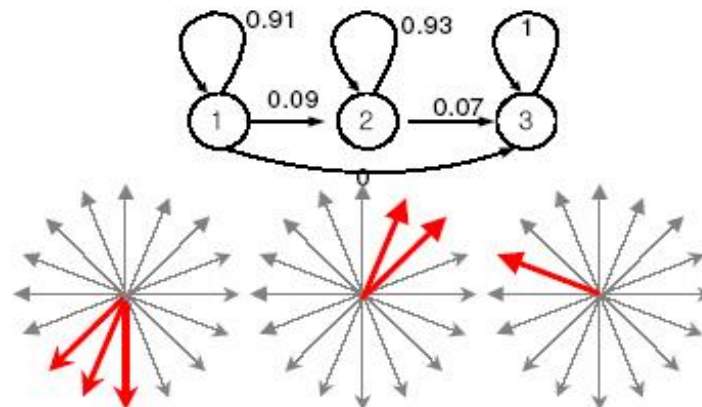
$$= \text{argmax } \prod_{i=1..n} P(d_i \mid s_i) P(s_i \mid s_{i-1})$$



Handwriting Recognition

■ Example

- Writing: [8, 8, 7, 7, 7, 6, 6, 5, 5, ...]
- $P(\text{States of 'zero' } | 8, 8, 7, 7, 7, 6, 6, 5, 5, \dots) \gg P(\text{States of 'one' } | 8, 8, 7, 7, 7, 6, 6, 5, 5, \dots)$
- Markov process for '0':



- Output process:

```
0.00 0.00 0.00 0.00 0.30 0.33 0.21 0.12 0.03 0.00 0.00 0.00 0.00 0.00 0.00 0.00
0.09 0.07 0.07 0.11 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.28 0.28 0.11
0.00 0.00 0.00 0.00 0.00 0.06 0.06 0.16 0.23 0.13 0.10 0.10 0.16 0.00 0.00 0.00
```