# PSEUDOCODE ALGORITHMS FOR REPRODUCIBILITY

### Algorithm 1: Feature Extraction from Video Data

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ALGORITHM 1: Behavioral Biomarker Feature Extraction
INPUT: Video frames V = \{v_1, v_2, \ldots, v_n\}
OUTPUT: Feature matrix F \in \mathbb{R}^{T \times d} where T=sequence_length, d=feature_dimensions
1. INITIALIZE MediaPipe Pose model
2. FOR each frame v_i in V:
   3. landmarks \leftarrow EXTRACT_POSE_LANDMARKS(v_i)
   4. IF landmarks is None:
      5. landmarks ← INTERPOLATE_MISSING_LANDMARKS()
   6. STORE landmarks[i] ← landmarks
7. END FOR
8. // Calculate movement parameters
9. FOR each landmark point j:

 movement[j] ← CALCULATE_EUCLIDEAN_DISTANCE(landmarks[i][j],

landmarks[i-1][j])
   11. velocity[j] \leftarrow (movement[j] - movement[j-1]) / \Delta t
   12. acceleration[j] \leftarrow (velocity[j] - velocity[j-1]) / \Deltat
   13. jerk[j] \leftarrow (acceleration[j] - acceleration[j-1]) / \Delta t
14. END FOR
15. // Statistical features
16. FOR each movement sequence s:
   17. mean[s] ← MEAN(movement[s])
   18. std[s] ← STANDARD_DEVIATION(movement[s])
   19. skewness[s] ← SKEWNESS(movement[s])
   20. kurtosis[s] ← KURTOSIS(movement[s])
21. END FOR
22. // Frequency domain features
23. FOR each movement sequence s:
   24. X[s] \leftarrow FFT(movement[s])
   25. dominant_freq[s] \leftarrow ARGMAX(|X[s]|) \times fs/N
   26. spectral_centroid[s] \leftarrow \Sigma(f[k] \times |X[s][k]|) / \Sigma|X[s][k]|
   27. bandwidth[s] \leftarrow SQRT(\Sigma((f[k] - spectral\_centroid[s])^2 \times |X[s][k]|) /
\Sigma |X[s][k]|
28. END FOR
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29. // Coordination indices
30. left_movement ← EXTRACT_LEFT_LIMB_MOVEMENTS()
31. right_movement ← EXTRACT_RIGHT_LIMB_MOVEMENTS()
32. correlation_coeff ← PEARSON_CORRELATION(left_movement, right_movement)
33. synchronization_score \leftarrow 1 - MIN(1, |\sigma| left - \sigma_right| / MAX(\sigma_left,
\sigma_{right}
34. // Repetitiveness measurement
35. direction_changes ← COUNT_DIRECTION_CHANGES(movement)
36. intervals ← CALCULATE_INTERVALS_BETWEEN_CHANGES()
37. repetitiveness_score \leftarrow direction_changes \times (1 - MIN(\sigma_intervals/
\mu_intervals, 1))
38. // Combine all features
39. F ← CONCATENATE([movement, velocity, acceleration, jerk,
                     statistical_features, frequency_features,
                     coordination_features, repetitiveness_features])
40. F ← NORMALIZE_TO_SEQUENCE_LENGTH(F, T=100)
41. RETURN F
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# Algorithm 2: Hybrid BiLSTM+CNN+Attention Model Architecture

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ALGORITHM 2: Hybrid Deep Learning Model Construction
INPUT: Feature sequences X \in \mathbb{R}^{N \times T \times d}, Labels y \in \{0,1\}^N
OUTPUT: Trained hybrid model M
1. // Model architecture definition
2. input_layer \( \text{INPUT(shape=(T, d))} \)
3. // CNN pathway for spatial feature extraction
4. conv1 ← CONV1D(filters=64, kernel_size=3, activation='relu')(input_layer)
5. conv2 ← CONV1D(filters=64, kernel_size=5, activation='relu')(input_layer)
6. conv3 ← CONV1D(filters=64, kernel_size=7, activation='relu')(input_layer)
7. conv_concat ← CONCATENATE([conv1, conv2, conv3])
8. conv_pool ← MAX_POOLING1D(pool_size=1)(conv_concat)
9. conv_dropout \( DROPOUT(rate=0.3)(conv_pool) \)
10. // BiLSTM pathway for temporal modeling
11. bilstm1 ← BIDIRECTIONAL_LSTM(units=64, return_sequences=True)
(input_layer)
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12. bilstm_dropout1 ← DROPOUT(rate=0.3)(bilstm1)
13. bilstm2 ← BIDIRECTIONAL_LSTM(units=32, return_sequences=True)
(bilstm_dropout1)
14. bilstm_dropout2 ← DROPOUT(rate=0.3)(bilstm2)
15. // Multi-head attention mechanism
16. attention ← MULTI_HEAD_ATTENTION(num_heads=4, key_dim=16)
(bilstm_dropout2, bilstm_dropout2)
17. attention_add ← ADD([attention, bilstm_dropout2])
18. attention_norm ← LAYER_NORMALIZATION()(attention_add)
19. // Feature fusion
20. concat_features ← CONCATENATE([conv_dropout, attention_norm])
21. flatten ← TIME_DISTRIBUTED(FLATTEN())(concat_features)
22. // Global feature extraction
23. global_max ← GLOBAL_MAX_POOLING1D()(flatten)
24. global_avg ← GLOBAL_AVERAGE_POOLING1D()(flatten)
25. global_concat ← CONCATENATE([global_max, global_avg])
26. // Classification layers
27. dense1 ← DENSE(units=64, activation='relu')(global_concat)
28. dropout1 ← DROPOUT(rate=0.4)(dense1)
29. dense2 ← DENSE(units=32, activation='relu')(dropout1)
30. dropout2 ← DROPOUT(rate=0.3)(dense2)
31. output ← DENSE(units=1, activation='sigmoid')(dropout2)
32. // Model compilation
33. model ← MODEL(inputs=input_layer, outputs=output)
34. COMPILE(model, optimizer=Adam(lr=0.001), loss='binary_crossentropy',
           metrics=['accuracy', 'precision', 'recall', 'auc'])
35. RETURN model
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#### Algorithm 3: Ensemble Learning Strategy

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ALGORITHM 3: Weighted Ensemble Model Training and Prediction
INPUT: Training data (X_train, y_train), Test data (X_test, y_test)
OUTPUT: Ensemble predictions P_ensemble

1. // Individual model creation
2. model_bilstm_cnn_attention ← CREATE_HYBRID_MODEL()
3. model_gru ← CREATE_GRU_MODEL()
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4. model_cnn ← CREATE_CNN_MODEL()
5. // Training configuration

 callbacks ← [EARLY_STOPPING(patience=15),

                REDUCE_LR_ON_PLATEAU(patience=5, factor=0.5),
               MODEL_CHECKPOINT(save_best_only=True)]
7. // Individual model training
8. FOR each model in [model_bilstm_cnn_attention, model_gru, model_cnn]:
   9. TRAIN(model, X_train, y_train, epochs=50, batch_size=32,
            validation_split=0.2, callbacks=callbacks)
10. END FOR
11. // Validation performance evaluation
12. P_bilstm_cnn_attention ← PREDICT(model_bilstm_cnn_attention,
X_validation)
13. P_gru ← PREDICT(model_gru, X_validation)
14. P_cnn ← PREDICT(model_cnn, X_validation)
15. // Weight optimization based on validation performance
16. weights ← OPTIMIZE_WEIGHTS([P_bilstm_cnn_attention, P_gru, P_cnn],
y_validation)
17. // Empirically determined optimal weights: w_1=0.5, w_2=0.3, w_3=0.2
18. // Ensemble prediction
19. P_test_bilstm_cnn_attention ← PREDICT(model_bilstm_cnn_attention, X_test)
20. P_test_gru ← PREDICT(model_gru, X_test)
21. P_test_cnn ← PREDICT(model_cnn, X_test)
22. P_ensemble \leftarrow W<sub>1</sub> \times P_test_bilstm_cnn_attention +
                 W_2 \times P_test_gru +
                 w₃ × P_test_cnn
23. P_ensemble_binary \leftarrow (P_ensemble > 0.5) ? 1 : 0
24. RETURN P_ensemble, P_ensemble_binary
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## Algorithm 4: Cross-Validation and Statistical Analysis

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Plain Text  ALGORITHM \ 4: \ 5-Fold \ Cross-Validation \ with \ Statistical \ Testing \\ INPUT: \ Dataset \ D = (X, y), \ Models \ M = \{M_1, M_2, \ldots, M_k\} \\ OUTPUT: \ Performance \ metrics \ with \ statistical \ significance
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1. // 5-fold stratified cross-validation
2. folds ← STRATIFIED_K_FOLD(D, k=5, random_state=42)
INITIALIZE performance_matrix[k_models][k_folds][n_metrics]
4. FOR fold_i in range(5):
   5. (X_train_fold, y_train_fold), (X_val_fold, y_val_fold) ← folds[fold_i]
   6. FOR model_j in M:
      7. model_j ← TRAIN(model_j, X_train_fold, y_train_fold)
      8. predictions ← PREDICT(model_j, X_val_fold)
      9. // Calculate performance metrics
      10. accuracy ← ACCURACY_SCORE(y_val_fold, predictions)
      11. precision ← PRECISION_SCORE(y_val_fold, predictions)
      12. recall ← RECALL_SCORE(y_val_fold, predictions)
      13. f1_score ← F1_SCORE(y_val_fold, predictions)
      14. roc_auc ← ROC_AUC_SCORE(y_val_fold, predictions)
      15. performance_matrix[model_j][fold_i] ← [accuracy, precision, recall,
f1_score, roc_auc]
   16. END FOR
17. END FOR
18. // Statistical significance testing
19. FOR each pair (model_i, model_j) in M:
   20. performance_i ← MEAN(performance_matrix[model_i], axis=folds)
   21. performance_j ← MEAN(performance_matrix[model_j], axis=folds)
   22. // Paired t-test
   23. t_statistic, p_value ← PAIRED_T_TEST(performance_i, performance_j)
   24. // Effect size (Cohen's d)
   25. pooled_std \leftarrow SQRT((STD(performance_i)<sup>2</sup> + STD(performance_j)<sup>2</sup>) / 2)
   26. cohens_d ← ABS(MEAN(performance_i) - MEAN(performance_j)) / pooled_std
   27. // Significance level
   28. IF p_value < 0.001: significance \leftarrow "***"
   29. ELIF p_value < 0.01: significance ← "**"
   30. ELIF p_value < 0.05: significance ← "*"
   31. ELSE: significance ← "ns"
   32. STORE statistical_results[model_i][model_j] \leftarrow {p_value, cohens_d,
significance}
33. END FOR
34. RETURN performance_matrix, statistical_results
```

#### Algorithm 5: Data Preprocessing and Augmentation

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ALGORITHM 5: Data Preprocessing Pipeline
INPUT: Raw feature sequences F_raw, Labels y_raw
OUTPUT: Preprocessed training and test sets
1. // Handle missing values
2. FOR each sequence s in F_raw:
   3. missing_indices ← FIND_MISSING_VALUES(s)
   4. IF missing_indices is not empty:
      5. s[missing_indices] ← INTERPOLATE_LINEAR(s, missing_indices)
   6. END IF
7. END FOR
8. // Sequence length normalization
9. TARGET_LENGTH ← 100
10. FOR each sequence s in F_raw:
    11. IF LENGTH(s) > TARGET_LENGTH:
        12. S ← DOWNSAMPLE(S, TARGET_LENGTH)
    13. ELIF LENGTH(s) < TARGET_LENGTH:</pre>
        14. s ← PAD_SEQUENCE(s, TARGET_LENGTH, method='zero')
    15. END IF
16. END FOR
17. // Feature standardization
18. scaler \( \text{STANDARD_SCALER()} \)
19. F_scaled ← FIT_TRANSFORM(scaler, F_raw)
20. // Train-test split
21. X_train, X_test, y_train, y_test ← TRAIN_TEST_SPLIT(F_scaled, y_raw,
                                                          test_size=0.2,
                                                          stratify=y_raw,
                                                          random_state=42)
22. // Handle class imbalance with SMOTE
23. smote ← SMOTE(random_state=42, k_neighbors=5)
24. X_train_balanced, y_train_balanced 
FIT_RESAMPLE(smote, X_train,
y_train)
25. // Data validation
26. ASSERT SHAPE(X_train_balanced)[1] == TARGET_LENGTH
27. ASSERT SHAPE(X_train_balanced)[2] == FEATURE_DIMENSIONS
28. ASSERT UNIQUE(y_train_balanced) == [0, 1]
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#### **Implementation Notes:**

#### **Hyperparameters:**

• Sequence Length: 100 frames

• **Feature Dimensions**: 21 (7 landmarks × 3 features each)

• Learning Rate: 0.001 with ReduceLROnPlateau

• Batch Size: 32

Dropout Rates: 0.3-0.4 for regularization

• Early Stopping: Patience of 15 epochs

• **Ensemble Weights**: [0.5, 0.3, 0.2] for [BiLSTM+CNN+Attention, GRU, CNN]

#### **Key Functions:**

MediaPipe Pose: For pose landmark extraction

• SMOTE: For handling class imbalance

StratifiedKFold: For cross-validation

Adam Optimizer: For model training

Multi-Head Attention: With 4 heads and key dimension 16

#### Reproducibility Requirements:

Set random seeds: random\_state=42 for all stochastic operations

• Use fixed train-test split with stratification

Apply consistent preprocessing pipeline

- Save model checkpoints and training histories
- Document all hyperparameter choices and architectural decisions