

view_frames Result
Recorded at time: 41.624

dp3_0/map

dp3_2/map

dp3_1/map

dp3_0/odom

dp3_2/odom

dp3_1/odom

dp3_0/base_footprint

dp3_2/base_footprint

dp3_1/base_footprint

dp3_0/base_link

dp3_2/base_link

dp3_1/base_link

dp3_0/camera_link

dp3_0/caster_back_left_link

dp3_0/caster_back_right_link

dp3_0/imu_link

dp3_0/wheel_left_link

dp3_0/wheel_right_link

dp3_2/camera_link

dp3_2/caster_back_left_link

dp3_2/caster_back_right_link

dp3_2/imu_link

dp3_2/wheel_left_link

dp3_2/wheel_right_link

dp3_1/camera_link

dp3_1/caster_back_left_link

dp3_1/caster_back_right_link

dp3_1/imu_link

dp3_1/wheel_left_link

dp3_1/wheel_right_link

dp3_0/camera_rgb_frame

dp3_2/camera_rgb_frame

dp3_1/camera_rgb_frame

dp3_0/camera_rgb_optical_frame

dp3_2/camera_rgb_optical_frame

dp3_1/camera_rgb_optical_frame

Broadcaster: /dp3_0/gmapping
Average rate: 20.308 Hz
Most recent transform: 41.672 (-0.048 sec old)
Buffer length: 3.250 sec

Broadcaster: /dp3_2/gmapping
Average rate: 20.319 Hz
Most recent transform: 41.647 (-0.023 sec old)
Buffer length: 3.199 sec

Broadcaster: /dp3_1/gmapping
Average rate: 20.319 Hz
Most recent transform: 41.638 (-0.014 sec old)
Buffer length: 3.199 sec

Broadcaster: /gazebo
Average rate: 30.322 Hz
Most recent transform: 41.599 (0.025 sec old)
Buffer length: 3.232 sec

Broadcaster: /gazebo
Average rate: 30.312 Hz
Most recent transform: 41.604 (0.020 sec old)
Buffer length: 3.233 sec

Broadcaster: /gazebo
Average rate: 30.284 Hz
Most recent transform: 41.596 (0.028 sec old)
Buffer length: 3.203 sec

Broadcaster: /dp3_0/robot_state_publisher1
Average rate: 10000.000 Hz
Most recent transform: 0.000 (41.624 sec old)
Buffer length: 0.000 sec

Broadcaster: /dp3_2/robot_state_publisher3
Average rate: 10000.000 Hz
Most recent transform: 0.000 (41.624 sec old)
Buffer length: 0.000 sec

Broadcaster: /dp3_1/robot_state_publisher2
Average rate: 10000.000 Hz
Most recent transform: 0.000 (41.624 sec old)
Buffer length: 0.000 sec

Broadcaster: /dp3_0/robot_state_publisher1
Average rate: 10000.000 Hz
Most recent transform: 0.000 (41.624 sec old)
Buffer length: 0.000 sec

Broadcaster: /dp3_0/robot_state_publisher1
Average rate: 10000.000 Hz
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Broadcaster: /dp3_0/robot_state_publisher1
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Broadcaster: /dp3_2/robot_state_publisher3
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Average rate: 10000.000 Hz
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Broadcaster: /dp3_0/robot_state_publisher1
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Buffer length: 0.000 sec

Broadcaster: /dp3_0/robot_state_publisher1
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Most recent transform: 0.000 (41.624 sec old)
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Broadcaster: /dp3_0/robot_state_publisher1
Average rate: 10000.000 Hz
Most recent transform: 0.000 (41.624 sec old)
Buffer length: 0.000 sec

Broadcaster: /dp3_2/robot_state_publisher3
Average rate: 10000.000 Hz
Most recent transform: 0.000 (41.624 sec old)
Buffer length: 0.000 sec

Broadcaster: /dp3_1/robot_state_publisher2
Average rate: 10000.000 Hz
Most recent transform: 0.000 (41.624 sec old)
Buffer length: 0.000 sec