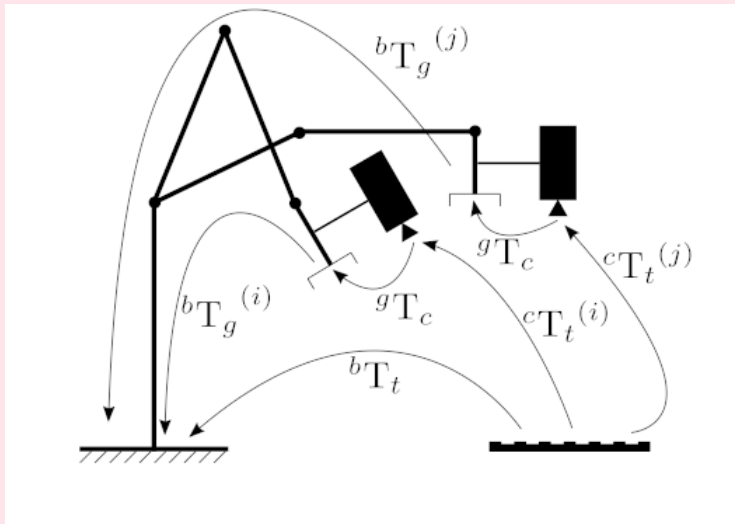
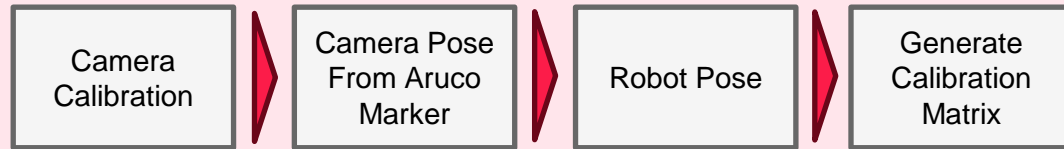


미니 프로젝트 3. 2D 비전을 활용한 로봇 작업 구현



Hand-eye Calibration



Vision Guided Pick and place

