# **Stylization** 2018~2020 loss function 정리

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$$L(G, F, D_{\mathcal{D}}, D_{\mathcal{P}}):$$

$$\min_{G,F} \max_{D_{\mathcal{D}}, D_{\mathcal{P}}} L(G, F, D_{\mathcal{D}}, D_{\mathcal{P}})$$

$$= (L_{adv}(G, D_{\mathcal{D}}) + L_{adv}(F, D_{\mathcal{P}})) + \lambda_1 L_{relaxed-cyc}(G, F)$$

$$+ \lambda_2 L_{strict-cyc}(G, F) + \lambda_3 L_{trunc}(G, F) + \lambda_4 L_{style}(G, D_{\mathcal{D}})$$

#### 2. Adversarial loss

$$L_{adv}(G, D_{\mathcal{D}}) = \sum_{D \in D_{\mathcal{D}}} \mathbb{E}_{d \in S(d)}[\log D(d)]$$
$$+ \sum_{D \in D_{\mathcal{D}}} \mathbb{E}_{p \in S(p)}[\log(1 - D(G(p, s)))]$$

$$L_{adv}(F, D_{\mathcal{P}}) = \mathbb{E}_{p \in S(p)}[\log D_{\mathcal{P}}(p)] + \mathbb{E}_{d \in S(d)}[\log(1 - D_{\mathcal{P}}(F(d)))]$$

3. Relaxed forward cycle-consistency loss

$$L_{relaxed-cyc}(G,F) = \mathbb{E}_{p \in S(p)}[L_{lpips}(H(p),H(F(G(p,s))))]$$

4. Strict backward cycle-consistency loss

$$L_{strict-cyc}(G,F) = \mathbb{E}_{d \in S(d)}[||d - G(F(d),s(d))||_1]$$

#### 5. Truncation loss

$$L_{trunc}(G, F) = \mathbb{E}_{p \in S(p)}[L_{lpips}(H(p), H(F(T[G(p, s)])))$$

## 6. Style loss

$$L_{cls}(G, D_{\mathcal{D}}) = \mathbb{E}_{d \in S(d)} \left[ -\sum_{c} p(c) \log D_{cls}(c|d) \right]$$
$$+ \mathbb{E}_{p \in S(p)} \left[ -\sum_{c} p'(c) \log D_{cls}(c|G(p,s)) \right]$$

**Truncation loss.** The truncation loss is designed to prevent the generated drawing from hiding information in small values. It is in the same format as the relaxed cycleconsistency loss, except that the generated drawing G(p,s) is first truncated to 6 bits (a general digital image stores intensity in 8 bits) to ensure encoded information is clearly visible, and then fed into F to reconstruct the photo. Denote the truncation operation as  $T[\cdot]$ , the truncation loss is formulated as:

$$L_{trunc}(G, F) = \mathbb{E}_{p \in S(p)}[L_{lpips}(H(p), H(F(T[G(p, s)])))]$$
(6)

In the first period of training, the weight for the truncation loss is kept low, otherwise it would be too hard for the model to optimize. The weight gradually increases as the training progresses.

$$\min_{\theta} \left( \mathcal{L}_c(T(\mathbf{c})) + \mathcal{L}_s(T(\mathbf{c})) \right)$$

### 2. Content loss & Style loss

$$\mathcal{L}_{c}(\mathbf{p}) = \sum_{l \in C} \alpha_{c}^{l} \mathcal{L}_{c}^{l}(\mathbf{p}) \text{ and } \mathcal{L}_{s}(\mathbf{p}) = \sum_{l \in S} \alpha_{s}^{l} \mathcal{L}_{s}^{l}(\mathbf{p})$$

$$\mathcal{L}_{c}^{l}(\mathbf{p}) = \left| \left| \phi^{l}(\mathbf{p}) - \phi^{l}(\mathbf{s}) \right| \right|_{2}^{2}$$

$$\mathcal{L}_{s}^{l}(\mathbf{p}) = \left| \left| G(\phi^{l}(\mathbf{p})) - G(\phi^{l}(\mathbf{s})) \right| \right|_{F}^{2}$$

$$\mathbf{p} = \Psi(\mathbf{c}, \mathbf{s}, \boldsymbol{\alpha}_{c}, \boldsymbol{\alpha}_{s}) \rightarrow \text{Stylized image}$$

$$L(X, \theta, I_c, I_s, P, P') = \alpha L_{\text{content}}(I_c, X)$$

$$+ L_{\text{style}}(I_s, X) + L_{\text{style}}(I_s, W(X, \theta))$$

$$+ \beta L_{\text{warp}}(P, P', \theta)$$

$$+ \gamma R_{\text{TV}}(f_{\theta}),$$

### 2. Style loss

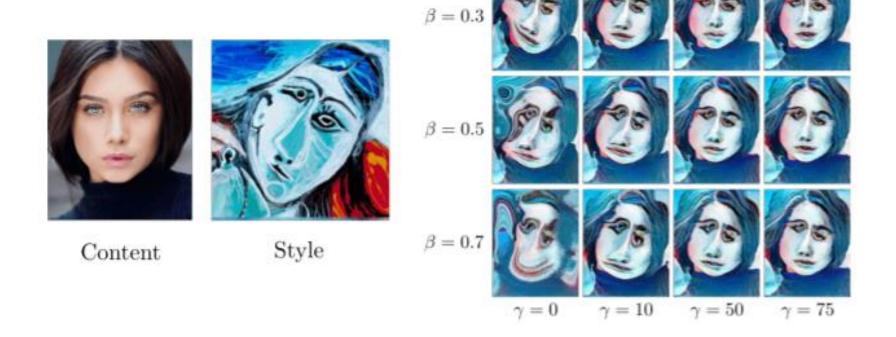
$$L_{\text{style}}(I_s, X) + L_{\text{style}}(I_s, W(X, \theta)).$$

#### 3. Deformation loss

$$L_{\text{warp}}(P, P', \theta) = \frac{1}{k} \sum_{i=1}^{k} ||p'_i - (p_i + \theta_i)||_2,$$

+) Regularization term

$$R_{\text{TV}}(f) = \frac{1}{W \times H} \sum_{i=1}^{W} \sum_{j=1}^{H} ||f_{i+1,j} - f_{i,j}||_1 + ||f_{i,j+1} - f_{i,j}||_1.$$



## Learning to Cartoonize Using White-Box Cartoon Representations

#### 1. Surface loss

$$\mathcal{L}_{surface}(G, D_s) = log D_s(\mathcal{F}_{dgf}(\mathbf{I}_c, \mathbf{I}_c)) + log(1 - D_s(\mathcal{F}_{dgf}(G(\mathbf{I}_p), G(\mathbf{I}_p))))$$

#### 2. Structure loss

$$\mathcal{L}_{structure} = \|VGG_n(G(\mathbf{I}_p)) - VGG_n(\mathcal{F}_{st}(G(\mathbf{I}_p)))\|$$

#### 3. Texture loss

$$\mathcal{L}_{texture}(G, D_t) = log D_t(\mathcal{F}_{rcs}(\mathbf{I}_c))$$

$$+ log (1 - D_t(\mathcal{F}_{rcs}(G(\mathbf{I}_p))))$$

$$\mathcal{F}_{rcs}(\mathbf{I}_{rgb}) = (1 - \alpha)(\beta_1 * \mathbf{I}_r + \beta_2 * \mathbf{I}_g + \beta_3 * \mathbf{I}_b) + \alpha * \mathbf{Y}$$

#### 4. Content loss

$$\mathcal{L}_{content} = \|VGG_n(G(\mathbf{I}_p)) - VGG_n(\mathbf{I}_p)\|$$

## +) regularization

$$\mathcal{L}_{tv} = \frac{1}{H * W * C} \| \bigtriangledown_x (G(\mathbf{I}_p)) + \bigtriangledown_y (G(\mathbf{I}_p)) \|$$

$$\mathcal{L}_{total} = \lambda_1 * \mathcal{L}_{surface} + \lambda_2 * \mathcal{L}_{texture}$$

$$+ \lambda_3 * \mathcal{L}_{structure} + \lambda_4 * \mathcal{L}_{content} + \lambda_5 * \mathcal{L}_{tv}$$

## U-GAT-IT: Unsupervised generative attentional networks with adaptive layer-instance normalization for image-to-image translation

#### 1. Adversarial loss

$$L_{lsgan}^{s \to t} = (\mathbb{E}_{x \sim X_t}[(D_t(x))^2] + \mathbb{E}_{x \sim X_s}[(1 - D_t(G_{s \to t}(x)))^2]).$$

### 2. Cycle loss

$$L_{cycle}^{s \to t} = \mathbb{E}_{x \sim X_s}[|x - G_{t \to s}(G_{s \to t}(x)))|_1].$$

## 3. Identity loss

$$L_{identity}^{s \to t} = \mathbb{E}_{x \sim X_t}[|x - G_{s \to t}(x)|_1].$$

## U-GAT-IT: Unsupervised generative attentional networks with adaptive layer-instance normalization for image-to-image translation

#### 4. CAM loss

$$L_{cam}^{s \to t} = -(\mathbb{E}_{x \sim X_s}[log(\eta_s(x))] + \mathbb{E}_{x \sim X_t}[log(1 - \eta_s(x))]),$$

$$L_{cam}^{D_t} = \mathbb{E}_{x \sim X_t}[(\eta_{D_t}(x))^2] + \mathbb{E}_{x \sim X_s}[(1 - \eta_{D_t}(G_{s \to t}(x))^2].$$

$$\min_{G_{s \to t}, G_{t \to s}, \eta_s, \eta_t} \max_{D_s, D_t, \eta_{D_s}, \eta_{D_t}} \lambda_1 L_{lsgan} + \lambda_2 L_{cycle} + \lambda_3 L_{identity} + \lambda_4 L_{cam},$$

$$\min_{\theta} \sum_{I_c \in \mathcal{D}_c} \sum_{I_s \in \mathcal{D}_s} \mathbf{PLoss}(I_x | I_c, I_s),$$

$$w_{\theta} = Meta\mathcal{N}(I_c; w_{\theta})$$

$$\lambda_c ||\mathbf{CP}(I) - \mathbf{CP}(I_c)||_2^2 + \lambda_s ||\mathbf{SP}(I) - \mathbf{SP}(I_s)||_2^2$$
 | : transferred image

$$\mathcal{L}_{total} = \alpha \mathcal{L}_{cont} + (1 - \alpha) \mathcal{L}_{shuf}.$$

#### 2. Content loss

$$\mathcal{L}_{cont} = ||F_o - F_c||_{F}^2,$$

#### 3. Reshuffle loss

$$\mathcal{L}_{shuf} = \sum_{p} ||\Psi_{p}(F_{o}) - \Psi_{ ext{NNC}(p)}(F_{s})||_{ ext{F}}^{2}, \ ext{NNC}(p) = \mathop{rg \max}_{p'=1,2,...,\Theta} (rac{\Psi_{p}(F_{o}) \cdot \Psi_{p'}(F_{s})}{||\Psi_{p}(F_{o})||_{ ext{F}}^{2} \cdot ||\Psi_{p'}(F_{s})||_{ ext{F}}^{2}} - \lambda rac{\Gamma(\Psi_{p'}(F_{s}))}{P_{o} \cdot P_{o}}),$$

$$\ell_{\text{total}} = \|\mathbf{x} - \tilde{\mathbf{x}}\|_{2}^{2} +$$

$$\lambda_{1} \frac{1}{|\mathcal{I}|} \sum_{i \in \mathcal{I}} \|\mathbf{\Psi}_{\text{VGG}}^{i}(\mathbf{x}) - \mathbf{\Psi}_{\text{VGG}}^{i}(\tilde{\mathbf{x}})\|_{2}^{2} + \lambda_{2} \ell_{\text{TV}}(\mathbf{x}),$$

## Stroke Controllable Fast Style Transfer with Adaptive Receptive Fields

#### 1. Total loss

$$\mathcal{L}_{\mathcal{B}_{s_k}} = \alpha \mathcal{L}_c + \beta_k \mathcal{L}_{\mathcal{T}_k} + \gamma \mathcal{L}_{tv},$$

#### 2. Semantic loss

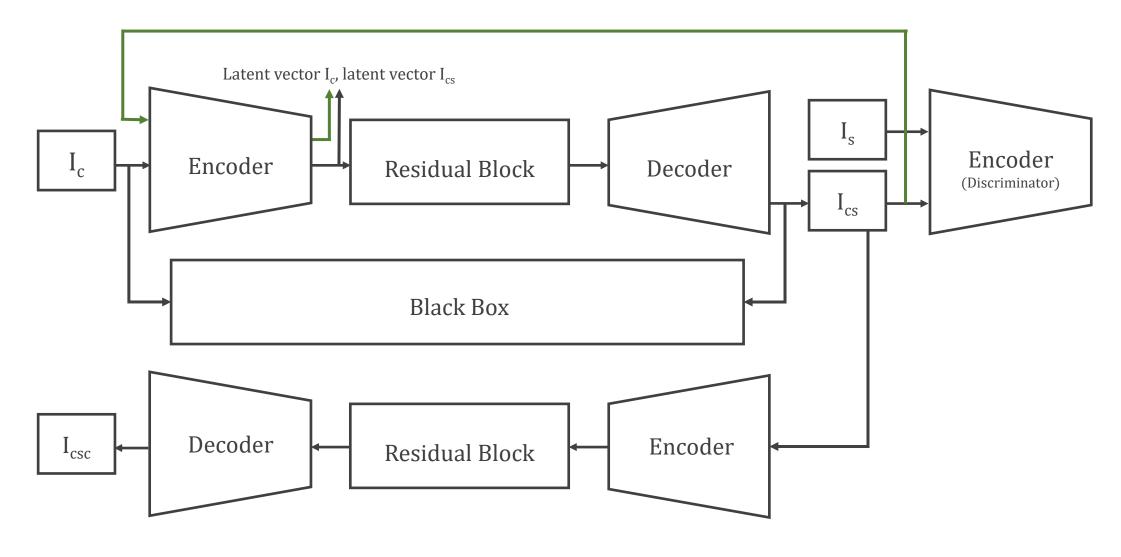
$$\mathcal{L}_c = \sum_{l \in \{l_c\}} \|\mathcal{F}^l(I_c) - \mathcal{F}^l(I_o)\|^2,$$

#### 3. Stroke loss

$$\mathcal{L}_{\mathcal{T}_k} = \sum_{l \in \{l_s\}} \|\mathcal{G}(\mathcal{F}^l(\mathcal{R}(I_s, \mathcal{T}_k))') - \mathcal{G}(\mathcal{F}^l(I_o^{\mathcal{B}_{s_k}})')\|^2,$$

$$\mathcal{G}(\mathcal{F}^l(I_s)') = [\mathcal{F}^l(I_s)'][\mathcal{F}^l(I_s)']^T$$

$$\mathcal{F}^l(I)' \in \mathbb{R}^{C \times (H \times W)}$$



#### 1. Optimization problem

$$\mathcal{L}(E,G,D) = \mathcal{L}_c(E,G) + \mathcal{L}_t(E,G) + \lambda \mathcal{L}_D(E,G,D)$$

$$E, G = \arg \min_{E,G} \max_{D} \mathcal{L}(E, G, D).$$

## A Style-Aware Content Loss for Real-time HD Style Transfer

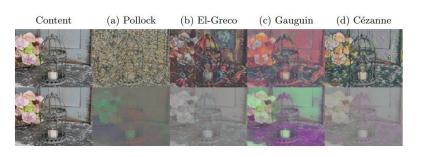
#### 3. Adversarial loss

$$\mathcal{L}_D(E, G, D) = \underset{y \sim p_Y(y)}{\mathbb{E}} \left[ \log D(y) \right] + \underset{x \sim p_X(x)}{\mathbb{E}} \left[ \log \left( 1 - D(G(E(x))) \right) \right]$$

#### 4. style-aware content loss

$$\mathcal{L}_c(E, G) = \underset{x \sim p_X(x)}{\mathbb{E}} \left[ \frac{1}{d} \left\| E(x) - E(G(E(x))) \right\|_2^2 \right]$$

5. Transformed image loss 
$$\mathcal{L}_{\mathbf{T}}(E,G) = \mathop{\mathbb{E}}_{x \sim p_X(x)} \left[ \frac{1}{CHW} ||\mathbf{T}(x) - \mathbf{T}(G(E(x))||_2^2 \right]$$



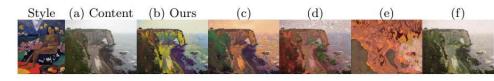
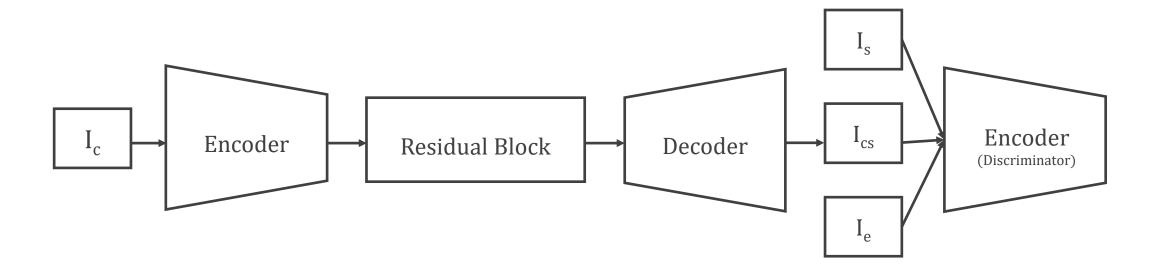


Fig. 10. Different variations of our method for Gauguin stylization. See Sect. 3.3 for details. (a) Content image; (b) full model ( $\mathcal{L}_c$ ,  $\mathcal{L}_{rab}$  and  $\mathcal{L}_D$ ); (c)  $\mathcal{L}_{rab}$  and  $\mathcal{L}_D$ ; (d) without transformer block; (e) only  $\mathcal{L}_D$ ; (f) trained with all of Gauguin's artworks as style images. Please zoom in to compare.



#### 1. Optimization problem

$$(G^*, D^*) = \arg\min_{G} \max_{D} \mathcal{L}(G, D)$$

#### 2. Total loss

$$\mathcal{L}(G, D) = \mathcal{L}_{adv}(G, D) + \omega \mathcal{L}_{con}(G, D),$$

#### 3. Adversarial loss

$$\mathcal{L}_{adv}(G, D) = \mathbb{E}_{c_i \sim S_{data}(c)}[\log D(c_i)] + \mathbb{E}_{e_j \sim S_{data}(e)}[\log(1 - D(e_j))] + \mathbb{E}_{p_k \sim S_{data}(p)}[\log(1 - D(G(p_k)))].$$

usually very small in the whole image. Therefore, an output image without clearly reproduced edges but with correct shading is likely to confuse the discriminator trained with a standard loss.

#### 4. Content loss

$$\mathcal{L}_{con}(G, D) = \mathbb{E}_{p_i \sim S_{data}(p)}[||VGG_l(G(p_i)) - VGG_l(p_i)||_1]$$

$$L(X, I_C, I_S) = \frac{\alpha \ell_C + \ell_m + \ell_r + \frac{1}{\alpha} \ell_p}{2 + \alpha + \frac{1}{\alpha}}$$

#### 2. Content loss

$$\mathcal{L}_{content}(X, C) = \frac{1}{n^2} \sum_{i,j} \left| \frac{D_{ij}^X}{\sum_{i} D_{ij}^X} - \frac{D_{ij}^{I_C}}{\sum_{i} D_{ij}^{I_C}} \right|$$

Stylization에 대한 content preserving의 상대적 중요성

$$C_{ij} = \begin{cases} \beta * D_{cos}(A_i, B_j), & \text{if } i \in X_{tk}, j \in S_{sk} \\ \infty, & \text{if } \exists k \text{ s.t. } i \in X_{tk}, j \notin S_{sk} \\ D_{cos}(A_i, B_j) & \text{otherwise,} \end{cases}$$

#### 3, REMD loss

$$\begin{split} \text{EMD}(A,B) = & \min_{T \geq 0} \sum_{ij} T_{ij} C_{ij} \\ s.t. \sum_{j} T_{ij} = 1/m \\ & \sum_{i} T_{ij} = 1/n \\ \ell_r = REMD(A,B) = & \max(R_A(A,B), R_B(A,B)) \\ & R_A(A,B) = & \min_{T \geq 0} \sum_{ij} T_{ij} C_{ij} \quad s.t. \quad \sum_{j} T_{ij} = 1/m \\ & R_B(A,B) = & \min_{T \geq 0} \sum_{ij} T_{ij} C_{ij} \quad s.t. \quad \sum_{i} T_{ij} = 1/n \\ \ell_r = & \max\left(\frac{1}{n} \sum_{i} \min_{j} C_{ij}, \frac{1}{m} \sum_{j} \min_{i} C_{ij}\right) \\ & C_{ij} = D_{\cos}(A_i,B_j) = 1 - \frac{A_i \cdot B_j}{\|A_i\| \|B_j\|} \end{split}$$

#### 4. Moment matching loss

$$\ell_m = \frac{1}{d} \|\mu_A - \mu_B\|_1 + \frac{1}{d^2} \|\Sigma_A - \Sigma_B\|_1$$

#### 5. Color matching loss

 $\ell_p$ 

- 생성된 image와 style image 사이의 pixel colors distance를 relaxed EMD로 사용하여 측정
- 팔레트의 이동과 content 보존은 서로 상충 → 따라서 1/α 가중

## Thank You