YEON-JI SONG

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EDUCATION

Seoul National University (SNU)

Ph.D in Interdisciplinary Program in Neuroscience

2021.09 – Present Seoul, South Korea

- · Advisor: Byoung-Tak Zhang
- Video Understanding, Generative AI, Unsupervised Representation Learning

Hong Kong University of Science and Technology (HKUST)

B.Eng. in Electronic and Computer Engineering

2017.09 – 2021.05 Clear Water Bay, Hong Kong

PUBLICATIONS

Motion-Aware Dynamic View Synthesis from Blurry Monocular Video via Sparse-Controlled Gaussian Splatting

To be submitted

Unsupervised Dynamic Video Prediction with Object-Centric Kinematics

Yeon-Ji Song, Suhyung Choi, Jaein Kim, Jin-Hwa Kim*, Byoung-Tak Zhang* *Under review*

Continuous SO(3) Equivariant Convolution for 3D Point Cloud Analysis

Jaein Kim, Heebin Yoo, Dong-Sig Han, Yeon-Ji Song, Byoung-Tak Zhang* The 18th European Conference on Computer Vision (ECCV) 2024

Learning Object Appearance and Motion Dynamics with Object-Centric Representations

Yeon-Ji Song, Hyunseo Kim, Suhyung Choi, Jin-Hwa Kim*, Byoung-Tak Zhang*

NeurIPS 2023 workshop on Causal Representation Learning

On Discovery of Local Independence over Continuous Variables via Neural Contextual Decomposition

Inwoo Hwang, Yunhyeok Kwak, <u>Yeon-Ji Song</u>, Byoung-Tak Zhang*, Sanghack Lee* *In Proceedings of CLeaR 2023*

• Implemented React.js and Node.js to enhance functionality and user experience.

WORK EXPERIENCE

PitchDaily	2023.03 - 2023.11
Part-time Artificial Intelligence Intern	Seoul, South Korea
 Created text summarization module using KoAlpaca. 	
Biointelligence Lab	2020.12 - 2021.04
Undergraduate Research Intern	SNU
Designed and conducted research on Robotics and Reinforcement Learning.	
Surromind (SNU)	2020.07 - 2020.10
Artificial Intelligence Research Engineer	Seoul, South Korea
• Designed and implemented a Deep Learning model for Pose Estimation based on Detectron2.	
Robocore AI	2020.06 - 2020.07
Robotics Software Engineer	Science Park, HongKong
Created new solutions for temi robots, combining IOT products and the mobility of temi.	
• Performed GUI design, system design and solved real-life customer request with AI solution.	
Codecrain Inc.	2019.06 - 2019.09
Full-stack Web Developer	Seoul, South Korea
 Developed frontend web application along with a senior developer using React.js. 	

PROJECTS

Robot Navigation based on Reinforcement Learning Final Year Project Advisor: Ming Liu (Robotics and Multi-Perception Lab, Robotics Institute) Title: Map-based Robot Navigation and Path planning with Deep Reinforcement Learning Proposed ML and RL based algorithm for autonomous navigation in a cluttered environment.	2020.05 – 2021.05 HKUST
 Bundleport CTO & Logistics Manager Created a full-stack web application using Node.js, MySQL, HTML5/CSS3, and JavaScript. Developed on cloud server using AWS S3, EC2, Elastic Beanstalk and Cloudfront. 	2018.05 – 2020.05 HKUST
 HKUST Robotics Team Robotics Software Engineer Designed and implemented algorithms for processing data from Camera and LiDAR sensors. 	2018.09 – 2018.12 HKUST
HKUST ROV Community Project Activity Assistant HKUST course code: ENGG2900D	2019.02 – 2019.05 HKUST
TEACHING EXPERIENCE	
Multimodal Deep Learning Theories and Applications POSCO DX 2024 AI Youth Challenge POSCO DX 2023 AI Youth Challenge Artificial Intelligence New Computer Technology (SNU x HKUST)	2024.09 - 2024.12 2024.06 - 2024.08 2023.06 - 2023.08 2022.03 - 2022.06 2022.03 - 2022.06
Awards and Certificates	
Best Presentation Paper Award @KCC2024 RoboCup@Home DSPL 2nd Place HKUST Admission Scholarship	2024 2022 2017