

# YEON-JI SONG

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## EDUCATION

<b>Seoul National University (SNU)</b> <i>Ph.D in Interdisciplinary Program in Neuroscience</i> <ul style="list-style-type: none"><li>Advisor: Byoung-Tak Zhang</li><li>Computer Vision, Unsupervised Representation Learning, Video Understanding</li></ul>	2021.09 – Present Seoul, South Korea
<b>Hong Kong University of Science and Technology (HKUST)</b> <i>B.Eng. in Electronic and Computer Engineering</i>	2017.09 – 2021.05 Clear Water Bay, Hong Kong

## PUBLICATIONS

<b>Unsupervised Dynamics Prediction with Object-Centric Kinematics</b> Yeon-Ji Song, Suhyung Choi, Jaein Kim, Jin-Hwa Kim*, Byoung-Tak Zhang* <i>Under review</i>
<b>Continuous SO(3) Equivariant Convolution for 3D Point Cloud Analysis</b> Jaein Kim, Heebin Yoo, Dong-Sig Han, <u>Yeon-Ji Song</u> , Byoung-Tak Zhang <i>Under review</i>
<b>Learning Object Appearance and Motion Dynamics with Object-Centric Representations</b> Yeon-Ji Song, Hyunseo Kim, Suhyung Choi, Jin-Hwa Kim*, Byoung-Tak Zhang* <i>NeurIPS 2023 workshop on Causal Representation Learning</i>
<b>On Discovery of Local Independence over Continuous Variables via Neural Contextual Decomposition</b> Inwoo Hwang, Yunhyeok Kwak, <u>Yeon-Ji Song</u> , Byoung-Tak Zhang*, Sanghack Lee* <i>In Proceedings of CLeaR 2023</i>

## WORK EXPERIENCE

<b>PitchDaily</b> <i>Part-time Artificial Intelligence Intern</i> <ul style="list-style-type: none"><li>Created text summarization module using KoAlpaca.</li></ul>	2023.03 – 2023.11 Seoul, South Korea
<b>Biointelligence Lab (SNU)</b> <i>Undergraduate Research Intern</i> <ul style="list-style-type: none"><li>Designed and conducted research on Robotics and Reinforcement Learning.</li></ul>	2020.12 – 2021.04 Seoul, South Korea
<b>Surromind (SNU)</b> <i>Artificial Intelligence Research Engineer</i> <ul style="list-style-type: none"><li>Designed and implemented a Deep Learning model for Pose Estimation based on Detectron2.</li></ul>	2020.07 – 2020.10 Seoul, South Korea
<b>Robocore AI</b> <i>Robotics Software Engineer</i> <ul style="list-style-type: none"><li>Created new solutions for temi robots, combining IOT products and the mobility of temi.</li><li>Performed GUI design, system design and solved real-life customer request with AI solution.</li></ul>	2020.06 – 2020.07 Science Park, HongKong
<b>Codecrain Inc.</b> <i>Full-stack Web Developer</i> <ul style="list-style-type: none"><li>Developed frontend web application along with a senior developer using React.js.</li><li>Implemented React.js and Node.js to enhance functionality and user experience.</li></ul>	2019.06 – 2019.09 Seoul, South Korea

## PROJECTS

<b>Robot Navigation based on Reinforcement Learning</b> <i>Final Year Project</i> <ul style="list-style-type: none"><li>Title: Map-based Robot Navigation and Path planning with Deep Reinforcement Learning</li><li>Proposed ML and RL based algorithm for autonomous navigation in a cluttered environment.</li></ul>	2020.05 – 2021.05 HKUST
<b>Bundleport</b> <i>CTO &amp; Logistics Manager</i> <ul style="list-style-type: none"><li>Created a full-stack web application using Node.js, MySQL, HTML5/CSS3, and JavaScript.</li><li>Developed on cloud server using AWS S3, EC2, Elastic Beanstalk and Cloudfront.</li></ul>	2018.05 – 2020.05 HKUST

**HKUST Robotics Team**  
*Robotics Software Engineer*

2018.09 – 2018.12  
*HKUST*

- Designed and implemented algorithms for processing data from Camera and LiDAR sensors.

**HKUST ROV Community Project**  
*Activity Assistant*

2019.02 – 2019.05  
*HKUST*

- HKUST course code: ENGG2900D

## TEACHING EXPERIENCE

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POSCO DX 2024 AI Youth Challenge

2024.06 – 2024.08

POSCO DX 2023 AI Youth Challenge

2023.06 – 2023.08

Artificial Intelligence

2022.05 – 2022.06

New Computer Technology (SNU x HKUST)

2022.05 – 2022.06

Electronics and Circuits

2020.02 – 2020.05

## AWARDS AND CERTIFICATES

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RoboCup@Home DSPL 2nd Place

2022

HKUST Admission Scholarship

2017