# YEON-JI SONG

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#### **EDUCATION**

# Seoul National University (SNU)

Ph.D in Interdisciplinary Program in Neuroscience

2021.09 – Present Seoul, South Korea

- Advisor: Byoung-Tak Zhang
- · Computer Vision, Unsupervised Representation Learning, Video Understanding

## Hong Kong University of Science and Technology (HKUST)

B.Eng. in Electronic and Computer Engineering

2017.09 – 2021.05 Clear Water Bay, Hong Kong

#### **PUBLICATIONS**

## **Sparse-Controlled Gaussian Splatting from Blurry Images**

Yeon-Ji Song, Byoung-Tak Zhang\*

In progress, to be submitted

#### **Unsupervised Dynamic Video Prediction with Object-Centric Kinematics**

Yeon-Ji Song, Suhyung Choi, Jaein Kim, Jin-Hwa Kim\*, Byoung-Tak Zhang\* *Under review* 

#### Continuous SO(3) Equivariant Convolution for 3D Point Cloud Analysis

Jaein Kim, Heebin Yoo, Dong-Sig Han, Yeon-Ji Song, Byoung-Tak Zhang\*

The 18th European Conference on Computer Vision (ECCV) 2024

### Learning Object Appearance and Motion Dynamics with Object-Centric Representations

Yeon-Ji Song, Hyunseo Kim, Suhyung Choi, Jin-Hwa Kim\*, Byoung-Tak Zhang\*

NeurIPS 2023 workshop on Causal Representation Learning

# On Discovery of Local Independence over Continuous Variables via Neural Contextual Decomposition

Inwoo Hwang, Yunhyeok Kwak, <u>Yeon-Ji Song</u>, Byoung-Tak Zhang\*, Sanghack Lee\* *In Proceedings of CLeaR 2023* 

• Implemented React.js and Node.js to enhance functionality and user experience.

#### **WORK EXPERIENCE**

PitchDaily	2023.03 - 2023.11
Part-time Artificial Intelligence Intern	Seoul, South Korea
<ul> <li>Created text summarization module using KoAlpaca.</li> </ul>	
Biointelligence Lab	2020.12 - 2021.04
Undergraduate Research Intern	SNU
<ul> <li>Designed and conducted research on Robotics and Reinforcement Learning.</li> </ul>	
Surromind (SNU)	2020.07 - 2020.10
Artificial Intelligence Research Engineer	Seoul, South Korea
• Designed and implemented a Deep Learning model for Pose Estimation based on Detectron2.	
Robocore AI	2020.06 - 2020.07
Robotics Software Engineer	Science Park, HongKong
<ul> <li>Created new solutions for temi robots, combining IOT products and the mobility of temi.</li> </ul>	
• Performed GUI design, system design and solved real-life customer request with AI solution.	
Codecrain Inc.	2019.06 - 2019.09
Full-stack Web Developer	Seoul, South Korea
<ul> <li>Developed frontend web application along with a senior developer using React.js.</li> </ul>	

# **PROJECTS**

Robot Navigation based on Reinforcement Learning  Final Year Project  Title: Map-based Robot Navigation and Path planning with Deep Reinforcement Learning  Proposed ML and RL based algorithm for autonomous navigation in a cluttered environment.	2020.05 – 2021.05 HKUST
Bundleport  CTO & Logistics Manager  Created a full-stack web application using Node.js, MySQL, HTML5/CSS3, and JavaScript.  Developed on cloud server using AWS S3, EC2, Elastic Beanstalk and Cloudfront.	2018.05 – 2020.05 HKUST
<ul><li>HKUST Robotics Team</li><li>Robotics Software Engineer</li><li>Designed and implemented algorithms for processing data from Camera and LiDAR sensors.</li></ul>	2018.09 – 2018.12 HKUST
HKUST ROV Community Project  Activity Assistant  HKUST course code: ENGG2900D  TEACHING EXPERIENCE	2019.02 – 2019.05 HKUST
Multimodal Deep Learning Theories and Applications POSCO DX 2024 AI Youth Challenge POSCO DX 2023 AI Youth Challenge Artificial Intelligence New Computer Technology (SNU x HKUST)	2024.09 - 2024.12 2024.06 - 2024.08 2023.06 - 2023.08 2022.03 - 2022.06 2022.03 - 2022.06
AWARDS AND CERTIFICATES	
Best Presentation Paper Award @KCC2024 RoboCup@Home DSPL 2nd Place HKUST Admission Scholarship	2024 2022 2017