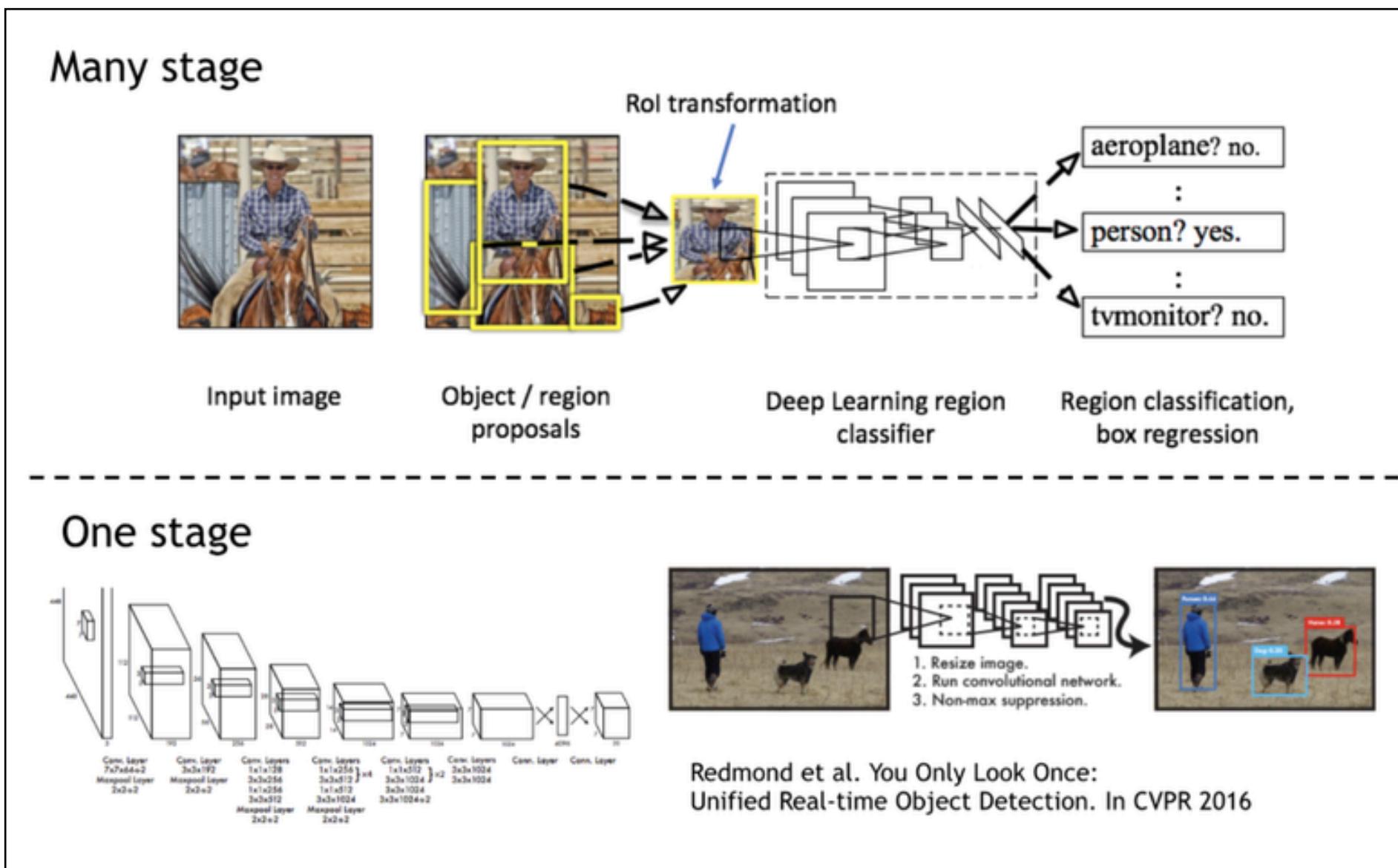


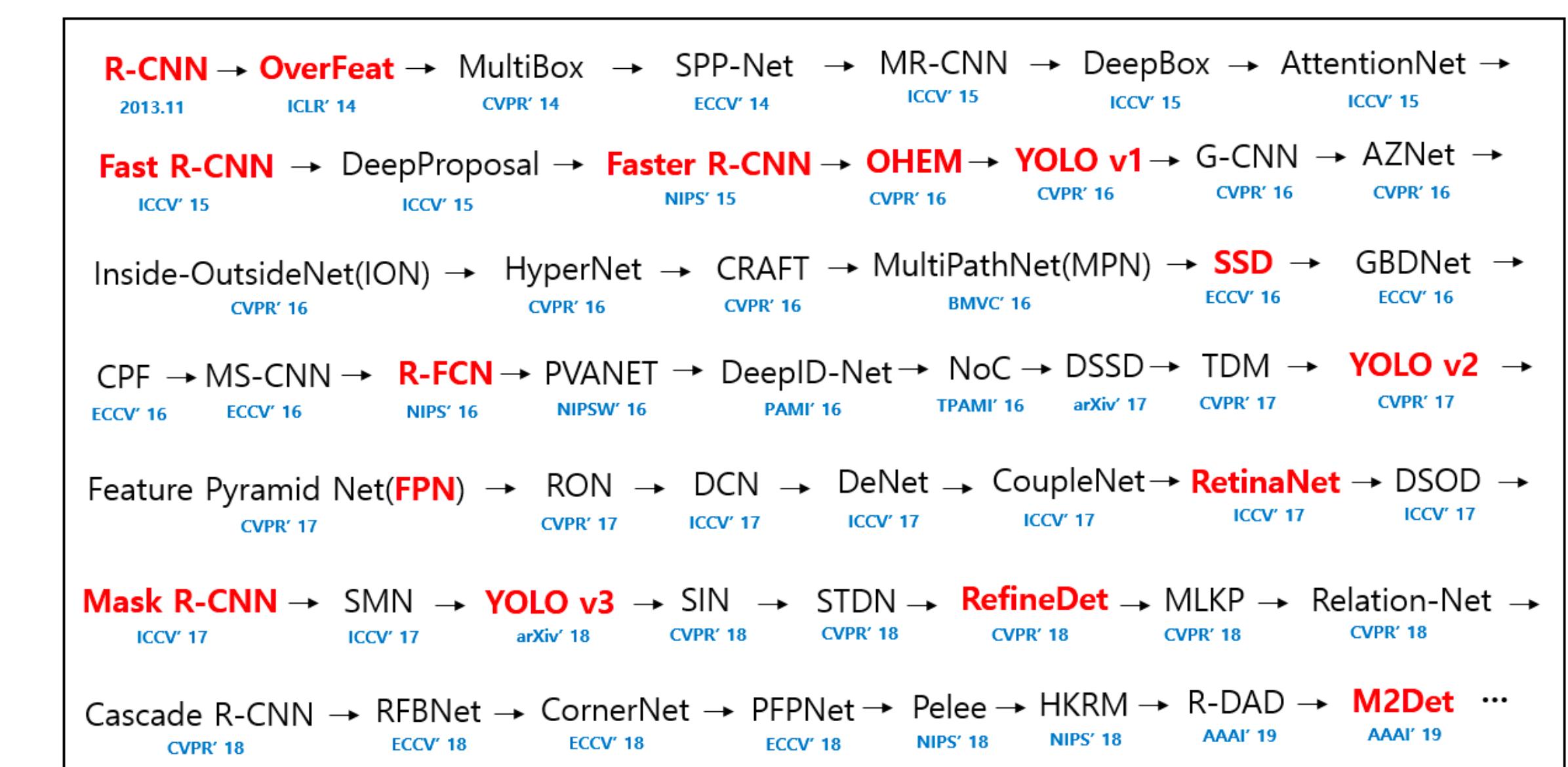
Yolo v3

object detection

- one-stage detector (vs 2-stage)



- object detection 연대기



- Yolo 목적: real-time application
(speed > accuracy)
- Yolo v3: v2보다 속도 ↓, 정확도 ↑

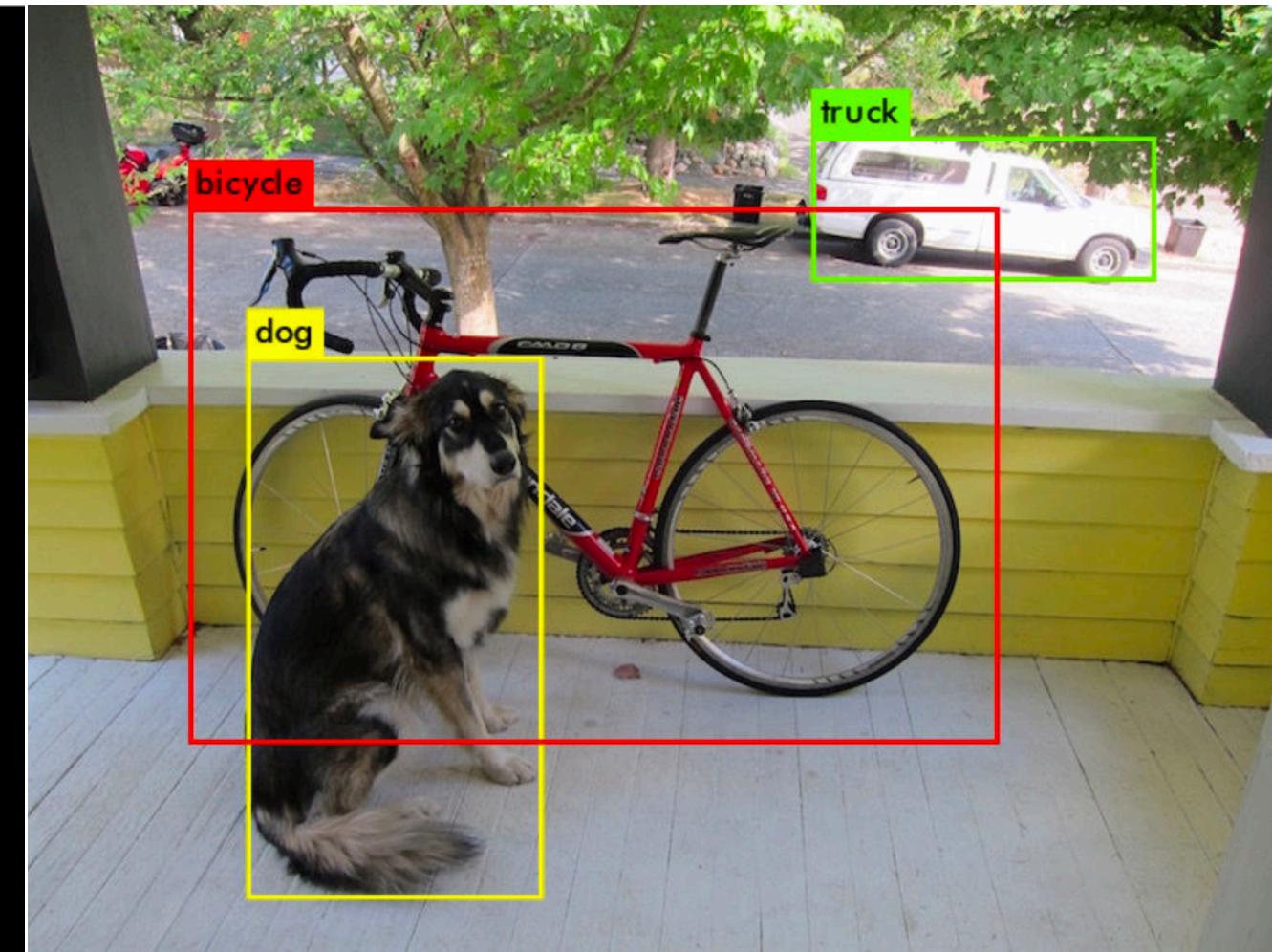
- Yolo 단점: 그리드 영역 단위로 bbox prediction 진행 → 그리드보다 작은 크기의 물체의 detection 정확도 떨어짐
- Yolo v3에서 작은 object에 대한 성능 개선

Yolo v3 - 서버컴에서 실행

```
./darknet detect cfg/yolov3.cfg yolov3.weights data/dog.jpg
```

```
user ~/Desktop/yolov3 master ./darknet detect cfg/yolov3.cfg yolov3.weights data/dog.jpg
layer   filters    size      input           output
0 conv    32 3 x 3 / 1 608 x 608 x 3 -> 608 x 608 x 32 0.639 BFLOPs
1 conv    64 3 x 3 / 2 608 x 608 x 32 -> 304 x 304 x 64 3.407 BFLOPs
2 conv    32 1 x 1 / 1 304 x 304 x 64 -> 304 x 304 x 32 0.379 BFLOPs
3 conv    64 3 x 3 / 1 304 x 304 x 32 -> 304 x 304 x 64 3.407 BFLOPs
4 res     1          304 x 304 x 64 -> 304 x 304 x 64
5 conv    128 3 x 3 / 2 304 x 304 x 64 -> 152 x 152 x 128 3.407 BFLOPs
6 conv    64 1 x 1 / 1 152 x 152 x 128 -> 152 x 152 x 64 0.379 BFLOPs
7 conv    128 3 x 3 / 1 152 x 152 x 64 -> 152 x 152 x 128 3.407 BFLOPs
8 res     5          152 x 152 x 128 -> 152 x 152 x 128
9 conv    64 1 x 1 / 1 152 x 152 x 128 -> 152 x 152 x 64 0.379 BFLOPs
10 conv   128 3 x 3 / 1 152 x 152 x 64 -> 152 x 152 x 128 3.407 BFLOPs
11 res    8          152 x 152 x 128 -> 152 x 152 x 128
12 conv   256 3 x 3 / 2 152 x 152 x 128 -> 76 x 76 x 256 3.407 BFLOPs
13 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
14 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
15 res    12         76 x 76 x 256 -> 76 x 76 x 256
16 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
17 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
18 res    15         76 x 76 x 256 -> 76 x 76 x 256
19 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
20 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
21 res    18         76 x 76 x 256 -> 76 x 76 x 256
22 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
23 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
24 res    21         76 x 76 x 256 -> 76 x 76 x 256
25 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
26 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
27 res    24         76 x 76 x 256 -> 76 x 76 x 256
28 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
29 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
30 res    27         76 x 76 x 256 -> 76 x 76 x 256
31 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
32 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
33 res    30         76 x 76 x 256 -> 76 x 76 x 256
34 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
35 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
36 res    33         76 x 76 x 256 -> 76 x 76 x 256
37 conv   512 3 x 3 / 2 76 x 76 x 256 -> 38 x 38 x 512 3.407 BFLOPs
38 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
39 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
40 res    37         38 x 38 x 512 -> 38 x 38 x 512
41 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
42 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
43 res    40         38 x 38 x 512 -> 38 x 38 x 512
44 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
45 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
46 res    43         38 x 38 x 512 -> 38 x 38 x 512
47 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
48 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
49 res    46         38 x 38 x 512 -> 38 x 38 x 512
50 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
51 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
52 res    49         38 x 38 x 512 -> 38 x 38 x 512
53 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
54 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
55 res    52         38 x 38 x 512 -> 38 x 38 x 512
56 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
57 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
58 res    55         38 x 38 x 512 -> 38 x 38 x 512
59 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
60 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
61 res    58         38 x 38 x 512 -> 38 x 38 x 512
62 conv   1024 3 x 3 / 2 38 x 38 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
63 conv   512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
64 conv   1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
```

```
65 res    62          19 x 19 x 1024 -> 19 x 19 x 1024
66 conv   512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
67 conv   1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
68 res    65          19 x 19 x 1024 -> 19 x 19 x 1024
69 conv   512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
70 conv   1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
71 res    68          19 x 19 x 1024 -> 19 x 19 x 1024
72 conv   512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
73 conv   1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
74 res    71          19 x 19 x 1024 -> 19 x 19 x 1024
75 conv   512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
76 conv   1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
77 conv   512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
78 conv   1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
79 conv   512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
80 conv   1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
81 conv   255 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 255 0.189 BFLOPs
82 yolo
83 route  79
84 conv   256 1 x 1 / 1 19 x 19 x 512 -> 19 x 19 x 256 0.095 BFLOPs
85 upsample 2x 19 x 19 x 256 -> 38 x 38 x 256
86 route  85 61
87 conv   256 1 x 1 / 1 38 x 38 x 768 -> 38 x 38 x 256 0.568 BFLOPs
88 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
89 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
90 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
91 conv   256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
92 conv   512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
93 conv   255 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 255 0.377 BFLOPs
94 yolo
95 route  91
96 conv   128 1 x 1 / 1 38 x 38 x 256 -> 38 x 38 x 128 0.095 BFLOPs
```



```
97 upsample          2x 38 x 38 x 128 -> 76 x 76 x 128
98 route  97 36
99 conv    128 1 x 1 / 1 76 x 76 x 384 -> 76 x 76 x 128 0.568 BFLOPs
100 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
101 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
102 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
103 conv   128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
104 conv   256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
105 conv   255 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 255 0.754 BFLOPs
106 yolo
```

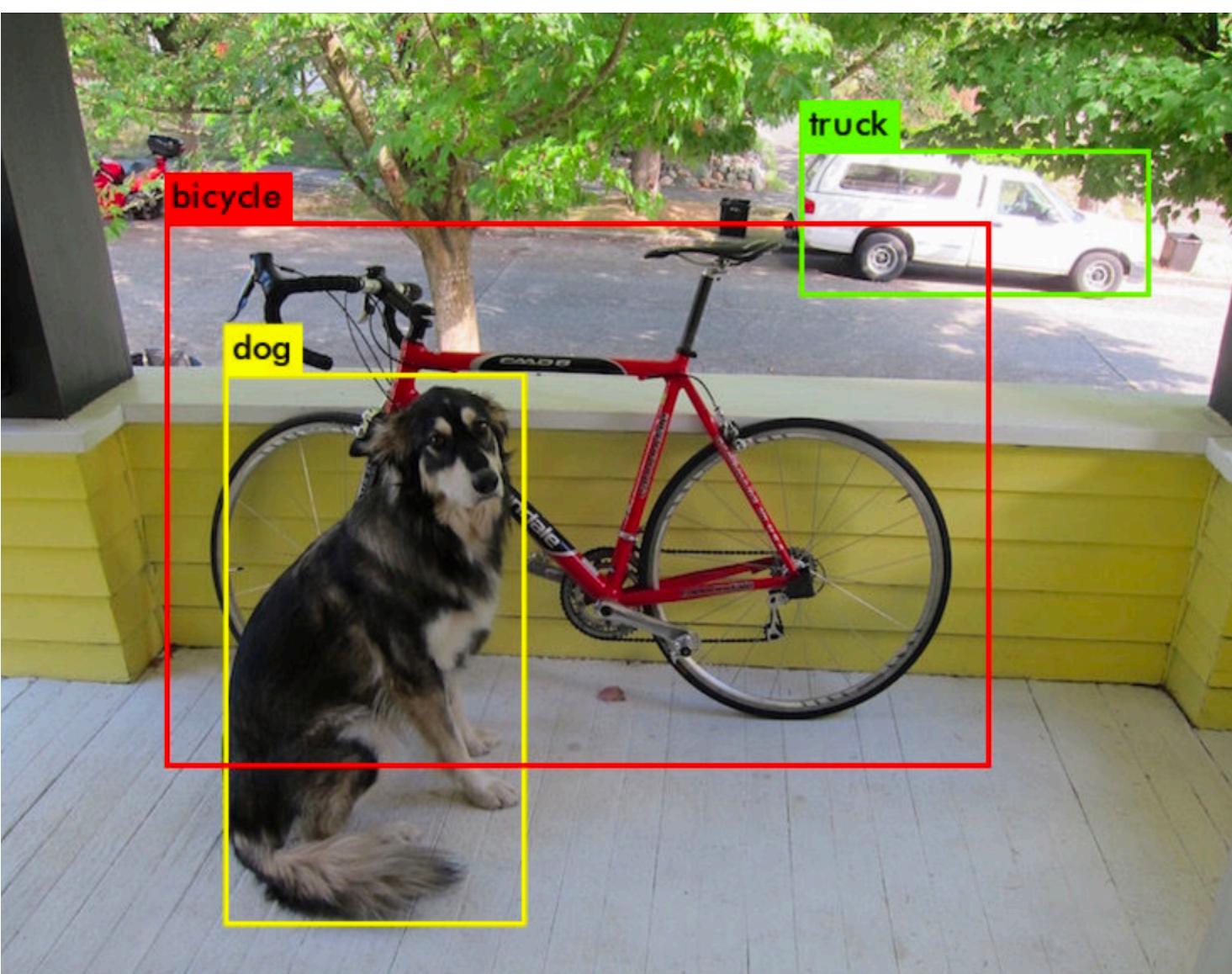
Loading weights from yolov3.weights...Done!
data/dog.jpg: Predicted in 22.869935 seconds.
dog: 100%
truck: 92%
bicycle: 99%

user ~/Desktop/yolov3 master

Yolo v3 - test

```
./darknet detector test cfg/coco.data cfg/yolov3.cfg yolov3.weights data/dog.jpg
```

- The detect command is shorthand for a more general version of the command
- 두 명령어 동일: detect = detector test



```
70 conv 1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
71 res 68 19 x 19 x 1024 -> 19 x 19 x 1024
72 conv 512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
73 conv 1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
74 res 71 19 x 19 x 1024 -> 19 x 19 x 1024
75 conv 512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
76 conv 1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
77 conv 512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
78 conv 1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
79 conv 512 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 512 0.379 BFLOPs
80 conv 1024 3 x 3 / 1 19 x 19 x 512 -> 19 x 19 x 1024 3.407 BFLOPs
81 conv 255 1 x 1 / 1 19 x 19 x 1024 -> 19 x 19 x 255 0.189 BFLOPs
82 yolo
83 route 79
84 conv 256 1 x 1 / 1 19 x 19 x 512 -> 19 x 19 x 256 0.095 BFLOPs
85 upsample 2x 19 x 19 x 256 -> 38 x 38 x 256
86 route 85 61
87 conv 256 1 x 1 / 1 38 x 38 x 768 -> 38 x 38 x 256 0.568 BFLOPs
88 conv 512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
89 conv 256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
90 conv 512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
91 conv 256 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 256 0.379 BFLOPs
92 conv 512 3 x 3 / 1 38 x 38 x 256 -> 38 x 38 x 512 3.407 BFLOPs
93 conv 255 1 x 1 / 1 38 x 38 x 512 -> 38 x 38 x 255 0.377 BFLOPs
94 yolo
95 route 91
96 conv 128 1 x 1 / 1 38 x 38 x 256 -> 38 x 38 x 128 0.095 BFLOPs
97 upsample 2x 38 x 38 x 128 -> 76 x 76 x 128
98 route 97 36
99 conv 128 1 x 1 / 1 76 x 76 x 384 -> 76 x 76 x 128 0.568 BFLOPs
100 conv 256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
101 conv 128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
102 conv 256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
103 conv 128 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 128 0.379 BFLOPs
104 conv 256 3 x 3 / 1 76 x 76 x 128 -> 76 x 76 x 256 3.407 BFLOPs
105 conv 255 1 x 1 / 1 76 x 76 x 256 -> 76 x 76 x 255 0.754 BFLOPs
106 yolo
Loading weights from yolov3.weights...Done!
data/dog.jpg: Predicted in 24.620853 seconds.
dog: 100%
truck: 92%
bicycle: 99%
```

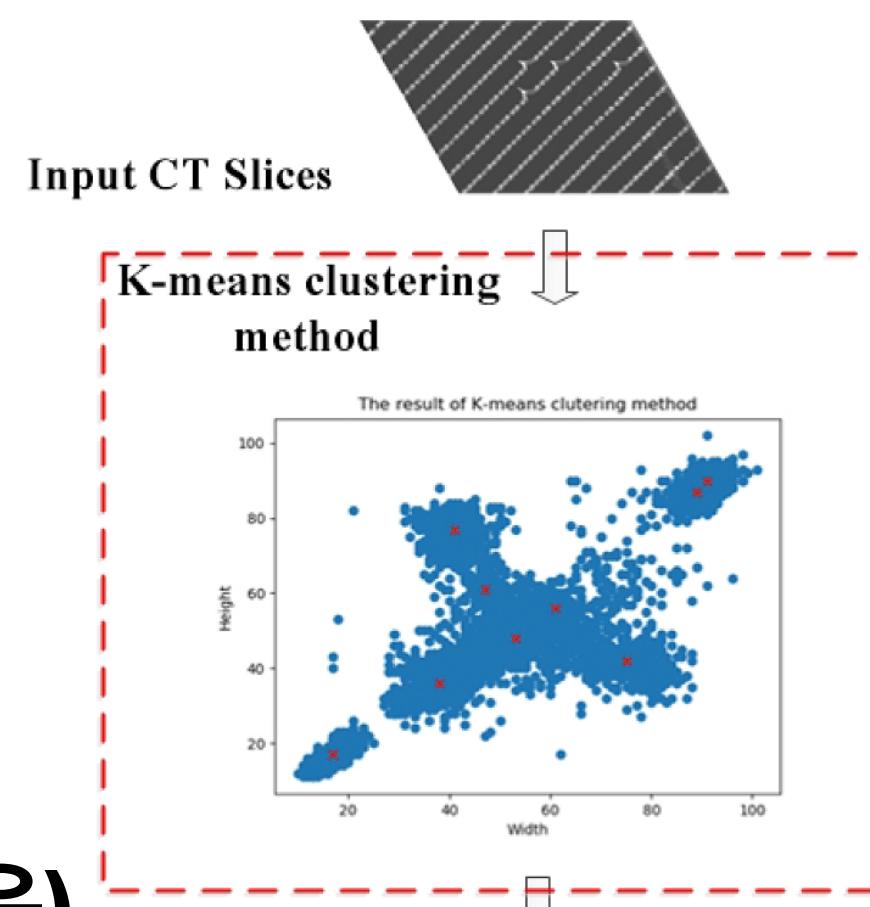
Yolo v3 - train

```
./darknet detector train cfg/voc.data cfg/yolov3-voc.cfg darknet53.conv.74
```

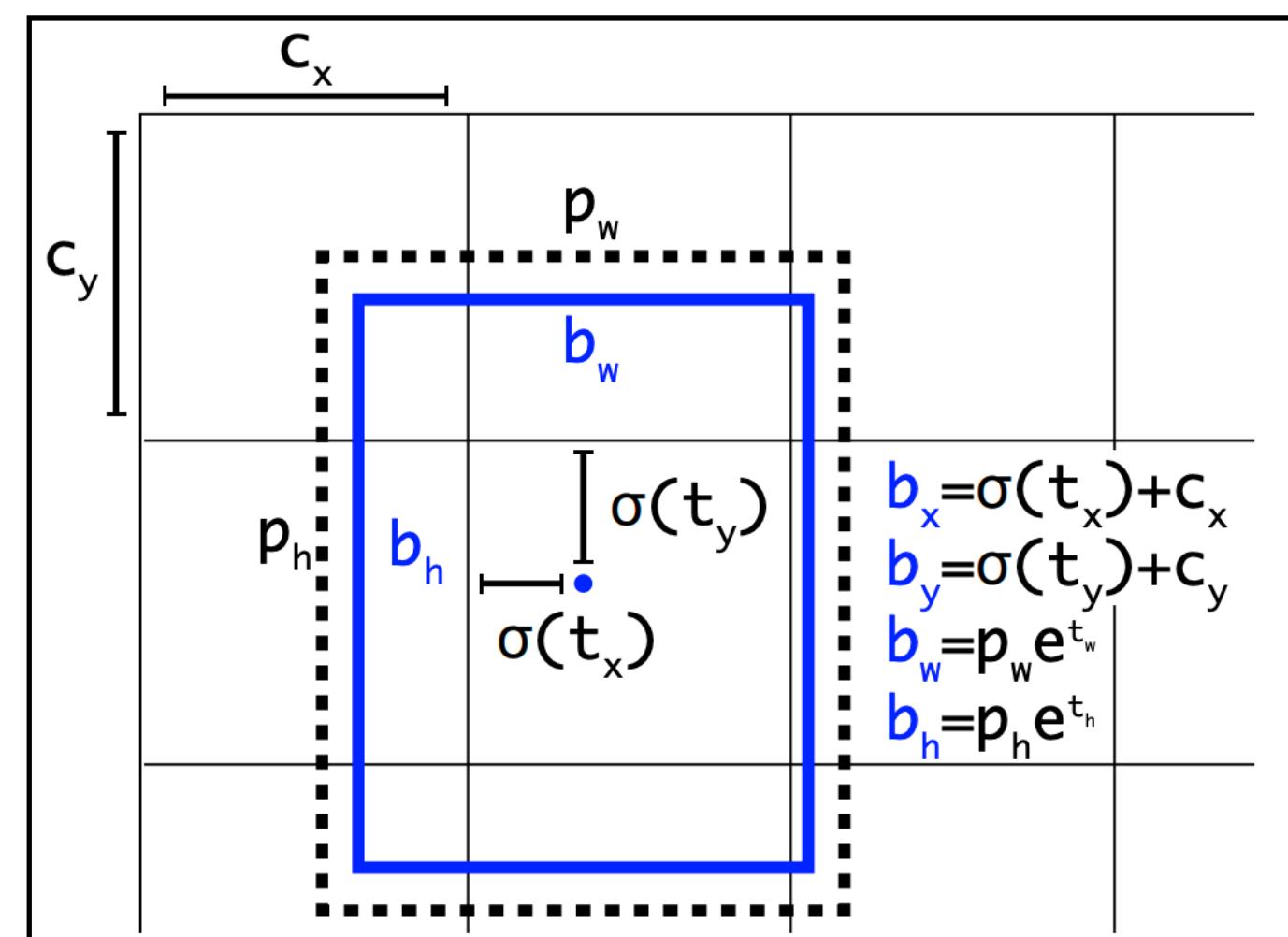
```
833: 3.052898, 7.765930 avg, 0.000481 rate, 80.197244 seconds, 833 images
Loaded: 0.000088 seconds
Region 82 Avg IOU: 0.631598, Class: 0.057110, Obj: 0.001416, No Obj: 0.001518, .5R: 1.000000, .75R: 0.000000, count: 1
Region 94 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000085, .5R: -nan, .75R: -nan, count: 0
Region 106 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000026, .5R: -nan, .75R: -nan, count: 0
834: 0.798131, 7.069150 avg, 0.000484 rate, 80.049766 seconds, 834 images
Loaded: 0.000070 seconds
Region 82 Avg IOU: 0.846931, Class: 0.064752, Obj: 0.000796, No Obj: 0.001429, .5R: 1.000000, .75R: 1.000000, count: 1
Region 94 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000093, .5R: -nan, .75R: -nan, count: 0
Region 106 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000025, .5R: -nan, .75R: -nan, count: 0
835: 1.097970, 6.472033 avg, 0.000486 rate, 80.260722 seconds, 835 images
Loaded: 0.000077 seconds
Region 82 Avg IOU: 0.533565, Class: 0.123666, Obj: 0.001857, No Obj: 0.001450, .5R: 1.000000, .75R: 0.000000, count: 2
Region 94 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000127, .5R: -nan, .75R: -nan, count: 0
Region 106 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000013, .5R: -nan, .75R: -nan, count: 0
836: 2.047835, 6.029613 avg, 0.000488 rate, 79.784090 seconds, 836 images
Loaded: 0.000071 seconds
Region 82 Avg IOU: 0.248816, Class: 0.034317, Obj: 0.001530, No Obj: 0.000663, .5R: 0.000000, .75R: 0.000000, count: 1
Region 94 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000182, .5R: -nan, .75R: -nan, count: 0
Region 106 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000109, .5R: -nan, .75R: -nan, count: 0
837: 2.806063, 5.707258 avg, 0.000491 rate, 80.220300 seconds, 837 images
Loaded: 0.000092 seconds
Region 82 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.004298, .5R: -nan, .75R: -nan, count: 0
Region 94 Avg IOU: 0.548553, Class: 0.484042, Obj: 0.000622, No Obj: 0.000170, .5R: 0.500000, .75R: 0.000000, count: 2
Region 106 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000025, .5R: -nan, .75R: -nan, count: 0
838: 2.337715, 5.370304 avg, 0.000493 rate, 79.821647 seconds, 838 images
Loaded: 0.000088 seconds
Region 82 Avg IOU: 0.365163, Class: 0.027143, Obj: 0.001777, No Obj: 0.000900, .5R: 0.000000, .75R: 0.000000, count: 1
Region 94 Avg IOU: 0.455324, Class: 0.114283, Obj: 0.000251, No Obj: 0.000089, .5R: 0.666667, .75R: 0.000000, count: 3
Region 106 Avg IOU: -nan, Class: -nan, Obj: -nan, No Obj: 0.000011, .5R: -nan, .75R: -nan, count: 0
839: 15.034252, 6.336699 avg, 0.000496 rate, 79.508525 seconds, 839 images
Loaded: 0.000099 seconds
```

Bounding box 예측

변경사항 1



- k-means clustering을 이용해 Anchor Box(p_* 정해짐)를 생성 (예측 전 이미 정해져 있음)
 - 총 9개 (3 bbox x 3 feature map)의 anchor box 결정
 - Anchor Box 생성 후 예측 시작 (효율적으로 예측하기 위함)
- t_* : 예측하는 대상
- b_* : 예측 후, bbox의 중심점 위치 & 크기 (예측한 t_* 에서 적절한 계산을 통해 구함)
 - 기준에는 그리드 중심점을 기준으로 예측했지만, 좌상단 기준에서의 offset (c_*) & Anchor box (p_*) 의 비율을 조절하여 예측
 - Loss는 b_* 로 변형한 후 구함
- b_x, b_y : 예측한 bbox의 중심점 위치
 - $\sigma(t_x, t_y)$ (0~1), c_x, c_y (좌상단 기준에서의 offset)
 - center 좌표가 cell 중심을 너무 벗어나지 않도록 시그모이드 값(0~1)으로 조절
- b_w, b_h : 예측한 bbox의 비율 크기
 - p_x, p_y : 사전에 정의된 Anchor box 크기 비율에 지수승을 곱함



Bounding box 예측 - CODE

t_x 와 직접 L1 loss를 통해 학습시키는 방식

```
box get_yolo_box(float *x, float *biases, int n, int index, int i, int j, int lw, int lh, int w, int h, int stride)
{
    box b;
    b.x = (i + x[index + 0*stride]) / lw;
    b.y = (j + x[index + 1*stride]) / lh;
    b.w = exp(x[index + 2*stride]) * biases[2*n] / w;
    b.h = exp(x[index + 3*stride]) * biases[2*n+1] / h;
    return b;
}

float delta_yolo_box(box truth, float *x, float *biases, int n, int index, int i, int j, int lw, int lh, int w, int h, float *delta,
                     float scale, int stride)
{
    box pred = get_yolo_box(x, biases, n, index, i, j, lw, lh, w, h, stride);
    float iou = box_iou(pred, truth);

    float tx = (truth.x*lw - i);
    float ty = (truth.y*lh - j);
    float tw = log(truth.w*w / biases[2*n]);
    float th = log(truth.h*h / biases[2*n + 1]);

    delta[index + 0*stride] = scale * (tx - x[index + 0*stride]);
    delta[index + 1*stride] = scale * (ty - x[index + 1*stride]);
    delta[index + 2*stride] = scale * (tw - x[index + 2*stride]);
    delta[index + 3*stride] = scale * (th - x[index + 3*stride]);
    return iou;
}
```

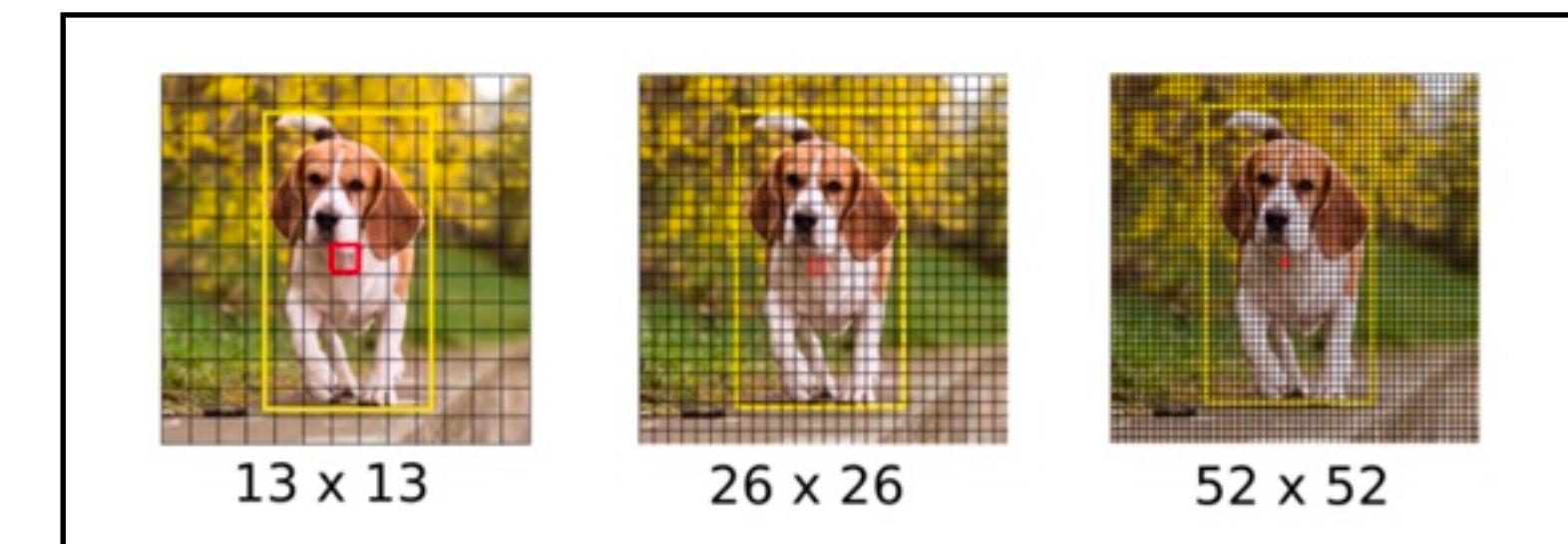
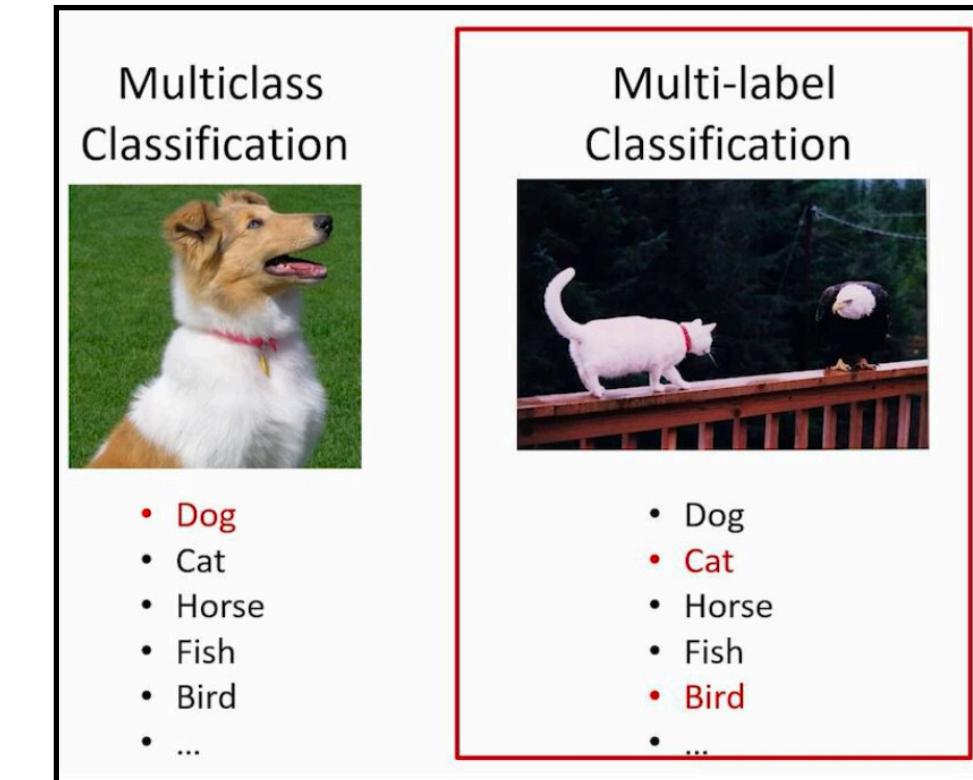
$$\begin{aligned}b_* &= \sigma(t_*) + c_x \\ \sigma(t_*) &= b_* - c_* \\ t_* &= \log(b_* - c_*)\end{aligned}$$

class 예측

변경사항 2

<https://herbwood.tistory.com/21>

- **classification**
 - softmax 분류기 -> logistic 분류기
 - softmax: n개의 클래스 중 하나를 결정
 - logistic: 각 class마다 binary cross-entropy 수행
 - n개의 클래스에 대한 각각 확률값 (0~1)
- **BackBone: Darknet 53**
 - Google Net -> Darknet 19 -> Darknet 53 (53 conv)
 - ResNet 추가
- **Network (추가)**
 - output feature map 3개: 각각 size가 다름
 - 네트워크 모양 추가 공부 필요



Yolo Loss

Bounding box 예측

$$\lambda_{\text{coord}} \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{obj}} \left[(x_i - \hat{x}_i)^2 + (y_i - \hat{y}_i)^2 \right]$$

$$+ \lambda_{\text{coord}} \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{obj}} \left[(\sqrt{w_i} - \sqrt{\hat{w}_i})^2 + (\sqrt{h_i} - \sqrt{\hat{h}_i})^2 \right]$$

$$+ \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{obj}} \left(C_i - \hat{C}_i \right)^2$$

$$+ \lambda_{\text{noobj}} \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{noobj}} \left(C_i - \hat{C}_i \right)^2$$

$$+ \sum_{i=0}^{S^2} \mathbb{1}_i^{\text{obj}} \sum_{c \in \text{classes}} (p_i(c) - \hat{p}_i(c))^2 \quad (3)$$

- **B-box regression Loss**
- **Object Confidence Loss**
- **Classification Loss**

```
void correct_yolo_boxes(detection *dets, int n, int w, int h, int netw, int neth, int relative)
{
    int i;
    int new_w=0;
    int new_h=0;
    if (((float)netw/w) < ((float)neth/h)) {
        new_w = netw;
        new_h = (h * netw)/w;
    } else {
        new_h = neth;
        new_w = (w * neth)/h;
    }
    for (i = 0; i < n; ++i){
        box b = dets[i].bbox;
        b.x = (b.x - (netw - new_w)/2./netw) / ((float)new_w/netw);
        b.y = (b.y - (neth - new_h)/2./neth) / ((float)new_h/neth);
        b.w *= (float)netw/new_w;
        b.h *= (float)neth/new_h;
        if(!relative){
            b.x *= w;
            b.w *= w;
            b.y *= h;
            b.h *= h;
        }
        dets[i].bbox = b;
    }
}
```

- **Yolo v1 - Loss function**
- **total Loss: 3개의 Loss를 합산**

Herbarium 2022 - FGVC9

식물 Dataset

- The categories in the `training_metadata.json` contain three levels of hierarchical structure, family - genus - species
- Plant Dataset - object detection 가능한 것인지 확인 못 함



The Herbarium 2022: Flora of North America is a part of a project of the [New York Botanical Garden](#) funded by the [National Science Foundation](#) to build tools to identify novel plant species around the world. The dataset strives to represent all known vascular plant taxa in North America, using images gathered from 60 different botanical institutions around the world.