

PDE Seminar: Day 1

Sobolev Spaces and Distributions

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1 σ -Algebras and Measurable Sets

A σ -algebra provides the formal framework for defining sets that are "measurable" in the sense of measure theory.

Definition 1.1 (σ -algebra). Let X be a set. A σ -algebra on X is a non-empty collection Σ of subsets of X satisfying:

1. $\emptyset \in \Sigma$ and $X \in \Sigma$.
2. **Closed under complement:** If $E \in \Sigma$, then $E^c = X \setminus E \in \Sigma$.
3. **Closed under countable unions:** If $\{E_k\}_{k=1}^{\infty} \subseteq \Sigma$, then $\bigcup_{k=1}^{\infty} E_k \in \Sigma$.

By De Morgan's laws, these conditions imply Σ is also closed under countable intersections.

2 Set Functions and Measures

Definition 2.1 (Set Function). A set function is a function whose domain is a family of subsets (usually a σ -algebra) of a given set X , mapping to the extended real line $[-\infty, \infty]$.

Definition 2.2 (Measure). Let X be a set and Σ be a σ -algebra over X . A set function $\mu : \Sigma \rightarrow [0, \infty]$ is called a **positive measure** if:

1. $\mu(\emptyset) = 0$.
2. **Countable Additivity:** For any sequence $\{E_k\}_{k=1}^{\infty}$ of pairwise disjoint sets in Σ :

$$\mu\left(\bigcup_{k=1}^{\infty} E_k\right) = \sum_{k=1}^{\infty} \mu(E_k).$$

The triple (X, Σ, μ) is called a **measure space**.

3 Lebesgue Measure on \mathbb{R}^n

The Lebesgue measure extends the notions of length, area, and volume to Euclidean spaces \mathbb{R}^n .

Definition 3.1 (Lebesgue Outer Measure). For any subset $E \subset \mathbb{R}^n$, the Lebesgue outer measure $\lambda^*(E)$ is defined as:

$$\lambda^*(E) := \inf \left\{ \sum_{k=1}^{\infty} \text{vol}(C_k) \right\},$$

where the infimum is taken over all sequences of open rectangular cuboids $\{C_k\}$ such that $E \subset \bigcup_{k=1}^{\infty} C_k$.

- In 1D, $\text{vol}(C_k)$ is the length $l(I) = b - a$.
- In n -dimensions, for $C = I_1 \times \cdots \times I_n$, $\text{vol}(C) = \prod_{i=1}^n l(I_i)$.

Proposition 3.1 (Carathéodory Criterion). *A set $E \subset \mathbb{R}^n$ is **Lebesgue measurable** if for every test set $A \subset \mathbb{R}^n$:*

$$\lambda^*(A) = \lambda^*(A \cap E) + \lambda^*(A \cap E^c).$$

The collection \mathcal{L} of all such measurable sets forms a σ -algebra. Restricting λ^ to \mathcal{L} gives the Lebesgue measure m , i.e., $m(E) = \lambda^*(E)$ for $E \in \mathcal{L}$. The triple $(\mathbb{R}^n, \mathcal{L}, m)$ is the Lebesgue measure space.*

Exercise 3.1 (Properties of Lebesgue Measure). *For $n \geq 1$:*

1. *Verify that \mathcal{L} satisfies the axioms of a σ -algebra.*
2. *Show that the restriction $\lambda^*|_{\mathcal{L}}$ satisfies countable additivity, hence is a measure.*

Solution 3.1.

1. *We only show closure under countable unions. Let $\{E_k\} \subset \mathcal{L}$ be pairwise disjoint and set $E = \bigcup_k E_k$. For any A , iterating the Carathéodory condition gives*

$$\lambda^*(A) = \sum_{k=1}^N \lambda^*(A \cap E_k) + \lambda^*\left(A \cap \bigcap_{k=1}^N E_k^c\right).$$

Letting $N \rightarrow \infty$ yields

$$\lambda^*(A) = \lambda^*(A \cap E) + \lambda^*(A \cap E^c),$$

so $E \in \mathcal{L}$.

2. *For countable additivity, let $\{E_k\} \subset \mathcal{L}$ be disjoint and $E = \bigcup_k E_k$. Apply Carathéodory with $A = E$:*

$$\lambda^*(E) = \sum_{k=1}^N \lambda^*(E_k) + \lambda^*\left(E \cap \bigcap_{k=1}^N E_k^c\right).$$

The last term decreases to 0 as $N \rightarrow \infty$, hence

$$\lambda^*(E) = \sum_{k=1}^{\infty} \lambda^*(E_k).$$

Thus $\lambda^|_{\mathcal{L}}$ is a measure.*

Example 3.1 (Dirichlet Function in 1D). Define $f : \mathbb{R} \rightarrow \mathbb{R}$ as the indicator of the rationals:

$$f(x) = \mathbf{1}_{\mathbb{Q}}(x) = \begin{cases} 1 & \text{if } x \in \mathbb{Q}, \\ 0 & \text{if } x \in \mathbb{R} \setminus \mathbb{Q}. \end{cases}$$

On $[0, 1]$:

- $\mathbb{Q} \cap [0, 1]$ is countable, so $m(\mathbb{Q} \cap [0, 1]) = 0$.
- $m([0, 1] \setminus \mathbb{Q}) = 1$.

The Lebesgue integral is

$$\int_{[0,1]} f \, dm = 1 \cdot m(\mathbb{Q}) + 0 \cdot m(\mathbb{R} \setminus \mathbb{Q}) = 0.$$

4 Lebesgue Spaces L^p

Let (X, Σ, μ) be a measure space and f a measurable function.

4.1 L^p spaces for $0 < p < \infty$

Define the L^p (semi-)norm by

$$\|f\|_p := \left(\int_X |f|^p d\mu \right)^{1/p}.$$

The space $L^p(X, \mu)$ consists of all measurable f with $\|f\|_p < \infty$ (identifying functions equal a.e.).

4.2 L^∞ space

For a measurable $g : X \rightarrow [0, \infty]$, define the set of essential bounds

$$S = \{\alpha \in [0, \infty] \mid \mu(\{x : g(x) > \alpha\}) = 0\}.$$

If $S = \emptyset$, set $\|g\|_\infty = \infty$; otherwise, the **essential supremum** is

$$\|g\|_\infty := \inf S.$$

Functions in $L^\infty(X, \mu)$ are essentially bounded.

5 Key Inequalities and Convexity

5.1 Conjugate Exponents

Definition 5.1 (Conjugate Exponents). Two positive real numbers p and q are called **conjugate exponents** if

$$\frac{1}{p} + \frac{1}{q} = 1.$$

Common pairs: $p = q = 2$ (self-conjugate, Hilbert space case) and $p = 1, q = \infty$ (limiting case).

5.2 Hölder's Inequality

Proposition 5.1 (Basic Hölder Inequality). *Let p, q be conjugate exponents with $1 < p < \infty$, and let f, g be non-negative measurable functions on (X, μ) . Then*

$$\int_X fg d\mu \leq \left(\int_X f^p d\mu \right)^{1/p} \left(\int_X g^q d\mu \right)^{1/q}.$$

Proof. Set $A = \|f\|_p$, $B = \|g\|_q$.

1. If $A = 0$, then $f = 0$ a.e., so $fg = 0$ a.e., and the inequality holds.
2. If $A > 0$ and $B = \infty$, the inequality is trivial.
3. Assume $0 < A, B < \infty$. Define normalized functions $F = f/A$, $G = g/B$, so that $\|F\|_p = \|G\|_q = 1$.

For any x with $0 < F(x), G(x) < \infty$, write $F(x) = e^{s/p}$, $G(x) = e^{t/q}$. By convexity of the exponential,

$$e^{\frac{s}{p} + \frac{t}{q}} \leq \frac{1}{p} e^s + \frac{1}{q} e^t,$$

which gives the pointwise Young inequality

$$F(x)G(x) \leq \frac{F(x)^p}{p} + \frac{G(x)^q}{q} \quad \text{for a.e. } x. \quad (*)$$

Integrating (*) over X yields

$$\int_X FG \, d\mu \leq \frac{1}{p} \int_X F^p \, d\mu + \frac{1}{q} \int_X G^q \, d\mu = \frac{1}{p} + \frac{1}{q} = 1.$$

Substituting back $F = f/A$, $G = g/B$ gives $\frac{1}{AB} \int_X fg \, d\mu \leq 1$, i.e., $\int_X fg \, d\mu \leq AB$. □

5.3 Convex Functions

Definition 5.2 (Convex Function). A function $\phi : (a, b) \rightarrow \mathbb{R}$ (with $-\infty \leq a < b \leq \infty$) is **convex** if

$$\phi((1 - \lambda)x + \lambda y) \leq (1 - \lambda)\phi(x) + \lambda\phi(y)$$

for all $x, y \in (a, b)$ and all $\lambda \in [0, 1]$.

5.4 General Hölder Inequality

Proposition 5.2 (Hölder in L^p). Let $1 \leq p \leq \infty$ and q be its conjugate exponent. If $f \in L^p(\mu)$ and $g \in L^q(\mu)$, then $fg \in L^1(\mu)$ and

$$\|fg\|_1 \leq \|f\|_p \|g\|_q.$$

Proof. The case $1 < p < \infty$ follows from the basic Hölder inequality applied to $|f|$ and $|g|$.

For $p = \infty$ (so $q = 1$), the definition of $\|\cdot\|_\infty$ gives $|f(x)g(x)| \leq \|f\|_\infty |g(x)|$ a.e. Integrating yields the result. The case $p = 1, q = \infty$ is symmetric. □

6 Weak Derivatives

6.1 Motivation and Definition

We begin by substantially weakening the notion of partial derivatives.

Notation. Let $C_c^\infty(U)$ denote the space of infinitely differentiable functions $\phi : U \rightarrow \mathbb{R}$ with compact support in U . Functions $\phi \in C_c^\infty(U)$ are called *test functions*.

Motivation. Assume $u \in C^1(U)$. For any $\phi \in C_c^\infty(U)$, integration by parts gives

$$\int_U u \phi_{x_i} \, dx = - \int_U u_{x_i} \phi \, dx \quad (i = 1, \dots, n). \quad (1)$$

There are no boundary terms because ϕ has compact support. More generally, if $u \in C^k(U)$ and $\alpha = (\alpha_1, \dots, \alpha_n)$ is a multi-index of order $|\alpha| = k$, then

$$\int_U u D^\alpha \phi \, dx = (-1)^{|\alpha|} \int_U D^\alpha u \phi \, dx. \quad (2)$$

This follows by applying (1) repeatedly.

Observing that the left-hand side of (2) makes sense for any locally integrable u , we are led to the following definition.

Definition 6.1 (Weak Derivative). Let $u, v \in L^1_{\text{loc}}(U)$ and let α be a multi-index. We say that v is the α^{th} **weak partial derivative** of u , written

$$D^\alpha u = v,$$

provided

$$\int_U u D^\alpha \phi \, dx = (-1)^{|\alpha|} \int_U v \phi \, dx \quad \text{for all } \phi \in C_c^\infty(U). \quad (3)$$

Lemma 6.1 (Uniqueness). *A weak α^{th} -partial derivative of u , if it exists, is unique up to sets of measure zero.*

Proof. Assume $v, \tilde{v} \in L^1_{\text{loc}}(U)$ both satisfy (3) for all test functions ϕ . Then

$$\int_U (v - \tilde{v}) \phi \, dx = 0 \quad \forall \phi \in C_c^\infty(U),$$

which implies $v = \tilde{v}$ almost everywhere. □

6.2 Example

Example 6.1. Let $n = 1$, $U = (0, 2)$, and

$$u(x) = \begin{cases} x, & 0 < x \leq 1, \\ 1, & 1 \leq x < 2. \end{cases}$$

Define

$$v(x) = \begin{cases} 1, & 0 < x \leq 1, \\ 0, & 1 < x < 2. \end{cases}$$

We claim $u' = v$ in the weak sense. Indeed, for any $\phi \in C_c^\infty(U)$,

$$\begin{aligned} \int_0^2 u \phi' \, dx &= \int_0^1 x \phi' \, dx + \int_1^2 \phi' \, dx \\ &= [x \phi(x)]_0^1 - \int_0^1 \phi \, dx + \phi(2) - \phi(1) \\ &= - \int_0^1 \phi \, dx = - \int_0^2 v \phi \, dx, \end{aligned}$$

which is exactly condition (3) with $\alpha = 1$.

7 Compact Sets in \mathbb{R}^n : A Brief Review

- Typical examples of compact sets in \mathbb{R}^n (by Heine–Borel theorem):
 - Finite sets.
 - Closed hypercubes: $[a_1, b_1] \times \cdots \times [a_n, b_n]$.
 - Closed balls: $\overline{B}(x_0, r)$.
 - n -spheres: $\{x \in \mathbb{R}^{n+1} \mid |x| = 1\}$.

8 Sobolev Spaces

Fix $1 \leq p \leq \infty$ and let k be a nonnegative integer. Sobolev spaces are function spaces whose members have weak derivatives up to order k lying in L^p .

8.1 Definition and Basic Properties

Definition 8.1 (Sobolev Space $W^{k,p}(U)$). The Sobolev space $W^{k,p}(U)$ consists of all locally summable functions $u : U \rightarrow \mathbb{R}$ such that for each multi-index α with $|\alpha| \leq k$, the weak derivative $D^\alpha u$ exists and belongs to $L^p(U)$.

Remark 8.1.

(i) When $p = 2$, we denote $H^k(U) = W^{k,2}(U)$ for $k = 0, 1, \dots$. The letter H is used because $H^k(U)$ is a Hilbert space. Note that $H^0(U) = L^2(U)$.

(ii) We identify functions in $W^{k,p}(U)$ that agree almost everywhere.

Definition 8.2 (Sobolev Norm). For $u \in W^{k,p}(U)$, define its Sobolev norm by

$$\|u\|_{W^{k,p}(U)} := \begin{cases} \left(\sum_{|\alpha| \leq k} \int_U |D^\alpha u|^p dx \right)^{1/p} & (1 \leq p < \infty), \\ \sum_{|\alpha| \leq k} \operatorname{ess\,sup}_U |D^\alpha u| & (p = \infty). \end{cases}$$

8.2 Convergence and Local Spaces

Definition 8.3 (Convergence in Sobolev Spaces).

1. Let $\{u_m\}_{m=1}^\infty, u \in W^{k,p}(U)$. We say u_m **converges to u in $W^{k,p}(U)$** , written

$$u_m \rightarrow u \quad \text{in } W^{k,p}(U),$$

provided $\lim_{m \rightarrow \infty} \|u_m - u\|_{W^{k,p}(U)} = 0$.

2. We say $u_m \rightarrow u$ **in $W_{\text{loc}}^{k,p}(U)$** if $u_m \rightarrow u$ in $W^{k,p}(V)$ for every $V \subset\subset U$ (i.e., V is compactly contained in U).

8.3 Space $W_0^{k,p}(U)$: Functions with Zero Boundary Values

Definition 8.4 ($W_0^{k,p}(U)$). We denote by $W_0^{k,p}(U)$ the closure of $C_c^\infty(U)$ in $W^{k,p}(U)$.

Thus $u \in W_0^{k,p}(U)$ if and only if there exist functions $u_m \in C_c^\infty(U)$ such that $u_m \rightarrow u$ in $W^{k,p}(U)$. Intuitively, $W_0^{k,p}(U)$ consists of functions $u \in W^{k,p}(U)$ that satisfy

$$“D^\alpha u = 0 \text{ on } \partial U” \quad \text{for all } |\alpha| \leq k-1,$$

in a weak sense. This interpretation will be made precise by the theory of traces.

9 Poincaré Inequality

The Poincaré inequality shows that for functions vanishing on the boundary, the L^p norm can be controlled by the norm of the gradient.

Theorem 9.1 (Poincaré Inequality for $W_0^{1,p}(\Omega)$). Let Ω be a bounded domain. If $u \in W_0^{1,p}(\Omega)$, there exists a constant $C = C(\Omega, p)$ such that

$$\|u\|_{L^p(\Omega)} \leq C \|\nabla u\|_{L^p(\Omega)}.$$

Proof. We present the proof for $n = 1$; the generalization to $n \geq 2$ is straightforward.

First, prove the inequality for $u \in C_0^\infty(\Omega)$. Since Ω is bounded, enclose it in a cube $Q = [0, a]^n$. Extend u by zero to Q , so $u \in C_0^\infty(Q)$.

For $x = (x_1, \dots, x_n) \in Q$, we have

$$u(x) = \int_0^{x_1} \partial_1 u(t, x_2, \dots, x_n) dt,$$

because $u(0, x_2, \dots, x_n) = 0$. By Hölder's inequality,

$$|u(x)|^p \leq \left(\int_0^{x_1} |\partial_1 u(t, x_2, \dots, x_n)| dt \right)^p \leq x_1^{p-1} \int_0^{x_1} |\partial_1 u(t, x_2, \dots, x_n)|^p dt.$$

Integrate over Q :

$$\begin{aligned} \int_Q |u(x)|^p dx &\leq \int_Q x_1^{p-1} \left(\int_0^{x_1} |\partial_1 u(t, x')|^p dt \right) dx \\ &= \int_{[0, a]^{n-1}} \int_0^a x_1^{p-1} \left(\int_0^{x_1} |\partial_1 u(t, x')|^p dt \right) dx_1 dx', \end{aligned}$$

where $x' = (x_2, \dots, x_n)$. Changing the order of integration,

$$\begin{aligned} &\int_0^a x_1^{p-1} \left(\int_0^{x_1} |\partial_1 u(t, x')|^p dt \right) dx_1 \\ &= \int_0^a |\partial_1 u(t, x')|^p \left(\int_t^a x_1^{p-1} dx_1 \right) dt \\ &= \int_0^a |\partial_1 u(t, x')|^p \cdot \frac{a^p - t^p}{p} dt \\ &\leq \frac{a^p}{p} \int_0^a |\partial_1 u(t, x')|^p dt. \end{aligned}$$

Therefore,

$$\int_Q |u|^p dx \leq \frac{a^p}{p} \int_Q |\partial_1 u|^p dx \leq \frac{a^p}{p} \int_Q |\nabla u|^p dx.$$

Hence,

$$\|u\|_{L^p(\Omega)} = \|u\|_{L^p(Q)} \leq \frac{a}{p^{1/p}} \|\nabla u\|_{L^p(\Omega)}.$$

Now for general $u \in W_0^{1,p}$, take a sequence $\{u_k\} \subset C_0^\infty(\Omega)$ with $u_k \rightarrow u$ in $W^{1,p}(\Omega)$. Applying the inequality to each u_k and passing to the limit yields the result. \square

Remark 9.1 (General Poincaré Inequality). *For $u \in W_0^{n,p}(\Omega)$ with Ω bounded, there exists $C = C(\Omega, n, p)$ such that*

$$\|u\|_{L^p(\Omega)} \leq C \sum_{|\alpha|=n} \|D^\alpha u\|_{L^p(\Omega)}.$$

10 Boundary Values and Trace Operator

Remark 10.1. *Boundary values of Sobolev functions are defined via a **trace operator**. For $u \in W_0^{1,p}(\Omega)$, the trace Tu is a well-defined element of $L^p(\partial\Omega)$ (for sufficiently smooth $\partial\Omega$). This is not a pointwise restriction but a continuous linear operator*

$$T : W^{1,p}(\Omega) \rightarrow L^p(\partial\Omega).$$

The space $W^{1,p}(\Omega)$ precisely consists of functions whose trace is zero.

11 Distributions and Weak Solutions

11.1 Distributions: Basic Idea

A **distribution** generalizes the concept of a function. Formally, a distribution T is a continuous linear functional

$$T : C_0^\infty(\Omega) \rightarrow \mathbb{R}.$$

Example 11.1 (Regular Distributions). If $g \in L_{\text{loc}}^1(\Omega)$, then

$$T_g(\varphi) := \int_{\Omega} g(x)\varphi(x)dx$$

defines a distribution.

Example 11.2 (Dirac Delta). The Dirac delta δ_{x_0} is defined by $\delta_{x_0}(\varphi) = \varphi(x_0)$.

Test functions $\varphi \in C_0^\infty(\Omega)$ are ideal because they are smooth and vanish near the boundary, so integration by parts produces no boundary terms.

11.2 Weak Formulation of Poisson's Equation

Consider the Dirichlet problem

$$-\Delta u = f \quad \text{in } \Omega, \quad u = 0 \quad \text{on } \partial\Omega.$$

If u were smooth, multiplying by a test function $\varphi \in C_0^\infty(\Omega)$ and integrating by parts gives

$$\int_{\Omega} \nabla u \cdot \nabla \varphi dx = \int_{\Omega} f \varphi dx.$$

This identity makes sense even when u is not twice differentiable.

Definition 11.1 (Weak Solution). A function $u \in H_0^1(\Omega)$ is a **weak solution** of $-\Delta u = f$ with $u = 0$ on $\partial\Omega$ if

$$\int_{\Omega} \nabla u \cdot \nabla \varphi dx = \int_{\Omega} f \varphi dx \quad \forall \varphi \in C_0^\infty(\Omega).$$

Key idea: Derivatives are transferred from u to the test function φ . This allows solutions when u lacks classical second derivatives and when f is only in $L^2(\Omega)$ or even $H^{-1}(\Omega)$.

11.3 The Dual Space $H^{-1}(\Omega)$

Definition 11.2. The space $H^{-1}(\Omega)$ is the dual space of $H_0^1(\Omega)$:

$$H^{-1}(\Omega) = (H_0^1(\Omega))^*.$$

Its elements are continuous linear functionals on $H_0^1(\Omega)$.

Remark 11.1 (Interpretation).

- Elements of $H^{-1}(\Omega)$ are distributions that act continuously on $H_0^1(\Omega)$.
- The negative index indicates that H^{-1} functions are “one derivative less regular” than L^2 .
- $-\Delta : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$ is the natural mapping of the Laplacian.
- In the weak formulation, it is natural to allow $f \in H^{-1}(\Omega)$.

Key takeaway: $H^{-1}(\Omega)$ is the natural space for the right-hand side f in the weak formulation of second-order elliptic equations, ensuring the formulation remains well-defined even for irregular data.