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$$K_0 = K_1 = A K_2 \quad K_2 = A K_3$$

$$A [K_0, K_1, K_2]$$

$$= [AK_0, AK_1, AK_2]$$

$$= [K_1, K_2, K_3]$$

$$= [K_0, K_1, K_2] \begin{bmatrix} 0 & 0 & d_0 \\ 1 & 0 & d_1 \\ 0 & 1 & d_2 \end{bmatrix}$$

$$+ \begin{bmatrix} 0 & 0 & K_3 - d_0 K_0 - d_1 K_1 \\ & & - d_2 K_2 \end{bmatrix}$$

$$A K_3 = K_3 Z + \hat{K}_3 L_2^T$$

$$Z = \begin{bmatrix} 0 & 0 & d_0 \\ 1 & 0 & d_1 \\ 0 & 1 & d_2 \end{bmatrix}$$

$$\hat{K}_3 = K_3 - \underline{d_0} K_0 - \underline{d_1} K_1 - \underline{d_2} K_2$$

$$A K_3 = K_3 Z + \hat{K}_3 L_2^T$$

$$K_3 = Q_3 R_3$$

$$A Q_3 R_3 = Q_3 \overset{\hat{K}_3}{A_3} Z + \overset{\hat{K}_3}{K_3} L_2^T$$

$$A Q_3 = Q_3 \left(R_3 Z R_3^{-1} + \hat{K}_3 (L_2^T R_3^{-1}) \right)$$

$$H_3 = R_3 Z \overline{R_3^{-1}}$$

$$H_3 = \begin{bmatrix} * & * & * \\ * & * & * \\ 0 & * & * \end{bmatrix}$$

H - upper
Hessenberg

$$H = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix}$$

$$e_2^T R_3^{-1}$$

$$R_3 = \begin{bmatrix} * & * & * \\ & * & * \\ & & * \end{bmatrix}$$

$$e_2^T R_3^{-1} = \begin{bmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & * \end{bmatrix} = \gamma e_2^T$$

$$e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$AQ_k = Q_k H_k + \gamma_{k+1} e_k^T$$

columns of Q
and not in row.

we will assume
 q_{k+1} belong to the
 next Krylov subspace.
 We can select q_k

To make q_{k+1} 1
 columns of Q

$$A Q_k = Q_k H_k + h_{k,k+1} q_{k+1}$$

$$Q_k^* q_{k+1} = 0$$

$$\|q_{k+1}\| = 1$$

$$Q_k^* Q_k = I$$

H_k - upper Hessenberg
 Arnoldi relation

$$\begin{matrix} \nearrow \\ Q_k^* \end{matrix} A \begin{matrix} \nearrow \\ Q_k \end{matrix} = \begin{matrix} \nearrow \\ Q_k \end{matrix} H_k + \underbrace{h_{k,k+1} q_{k+1}}_{\begin{matrix} \nearrow \\ Q_k^* \end{matrix}}$$

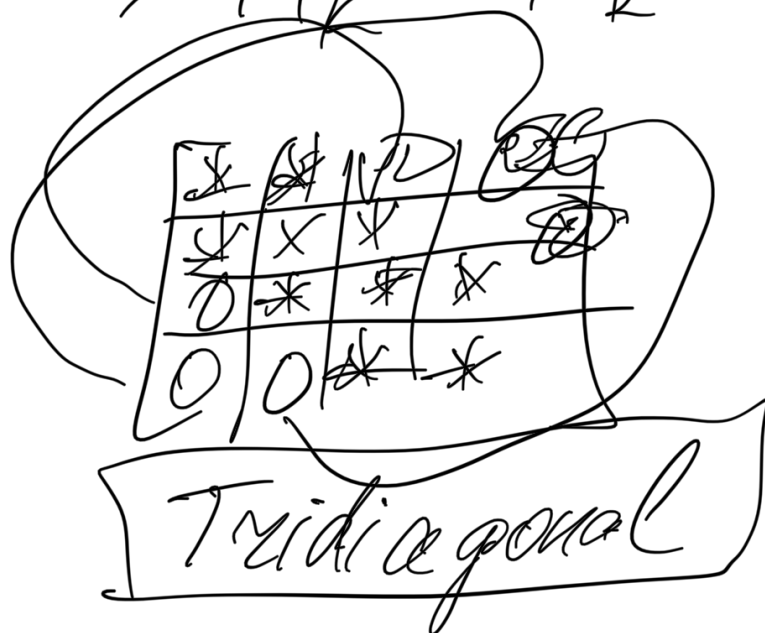
$$\underbrace{Q_k^* A Q_k}_{H} = \underbrace{H_k}_{H} + 0$$

$$H = Q^* A Q$$

$$\left[\begin{array}{cccc} 1 & 1 & 2 & \dots & x_k & 1 & 1 & x_k \end{array} \right]$$

$$A = A^*$$

$$\Rightarrow H_k = H_k^*$$



$$A Q_k = Q_k T_k + \sqrt{h_{k+1,k}} q_{k+1} e_k^T$$

$$x = x_0 + Q_j c_j$$

$$c_j^T Q_j^* A Q_j c_j = Q_j^* (A - \frac{A Q_j c_j c_j^T A}{c_j^T A c_j}) c_j$$

$$x_j = Q_j^* x_0 = x_0^v$$

$$Q_j = \begin{bmatrix} x_0 \\ \sqrt{x_0} \end{bmatrix} \dots$$

$$A = A^* > 0$$

$$\Rightarrow T = Q_j^* A Q_j > 0$$

$$x_j = P_j \cdot z_j$$

$$P_j = [P_{j-1} \quad P_j]$$

$$z_j = \begin{bmatrix} z_{j-1} \\ \delta_j \end{bmatrix}$$

$$P_j z_j = [P_{j-1} \quad P_j] \begin{bmatrix} z_{j-1} \\ \delta_j \end{bmatrix}$$

$$= (P_{j-1} z_{j-1}) + P_j \delta_j$$

$\sqrt{\quad} \quad 19-9$

$$(Ax, x) = \mathcal{L}(f, x)$$

$$Ax_* = f \quad \nearrow$$

$$(Ax, x) = \mathcal{L}(Ax_*, x)$$

$$(A(x-x_*), (x-x_*))$$

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$$(A(x-x_*), x-x_*)$$

Problem: Too many vectors to store

↳ Anticipation of DIRECT1 DT

Iterations / position

x_j - current approximation
Look for correction:

$$A(x_j + e_j) = f$$

$$Ae_j = f - Ax_j = r_j$$

Generate Krylov subspace
from scratch

$$q = \frac{\sqrt{\text{cond}(A^*A)} - 1}{\sqrt{\text{cond}(A^*A)} + 1}$$

$\text{cond}(A)$

$$q = \frac{\text{cond}(A) - 1}{\text{cond}(A) + 1}$$

$$Ax = f$$

$$x = VC$$

$$AVC = f$$

N equations
for m unknowns

$$W^* AVC = W^* f$$

$m < N$

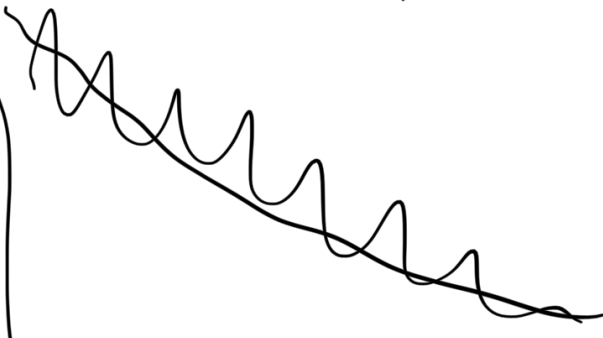
square

"sketching"

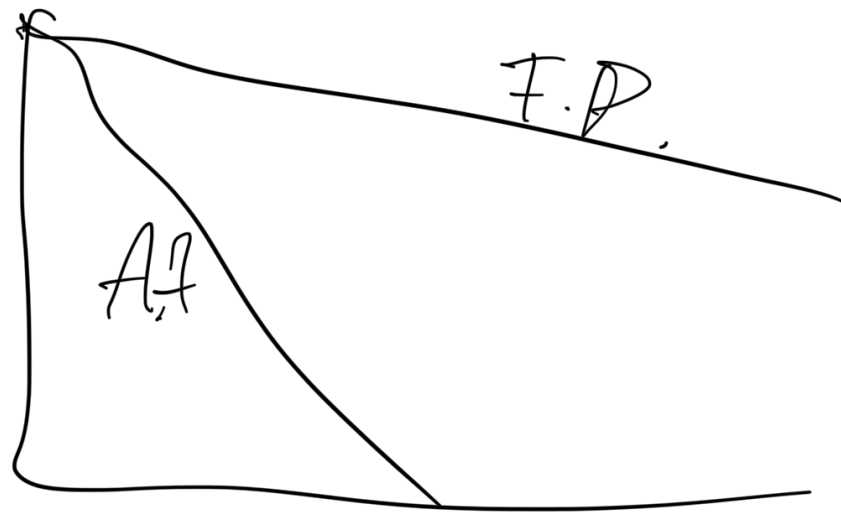
row sampling

W basis for A^*

residual



it.
 1 iteration of BFG
 + 1 iteration of GMRES



$$Ax = f$$

$$\text{cond}(A) \gg 1$$

p_{left}^a

n

$$PAx = P\mathbb{1}$$

$$\text{cond}(PA) \leq \text{cond}(A)$$

P, Z is cheap

$$P = A^{-1} - \text{ideal}$$

$$\textcircled{AP^{-1}} y = \left(\text{cond}(AP^{-1}) \right) \leq \text{cond}(A)$$

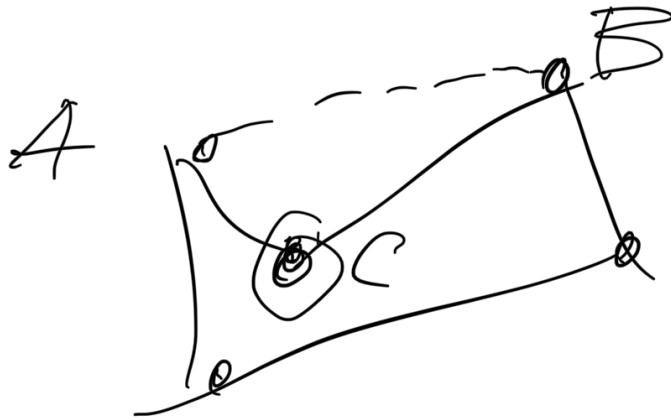
$$x = P^{-1}y \text{ is cheap}$$

✓

□

Lower matrix

\Rightarrow graph
Elimination



$\textcircled{U_2} U_2^T \rightarrow$
 Spars $(U_2 + R_2)(U_2 + R_2)^T$
 $\approx U_2 U_2^T + U_2 R_2^T$
 $+ R_2 U_2^T + \cancel{R_2 R_2^T}$

