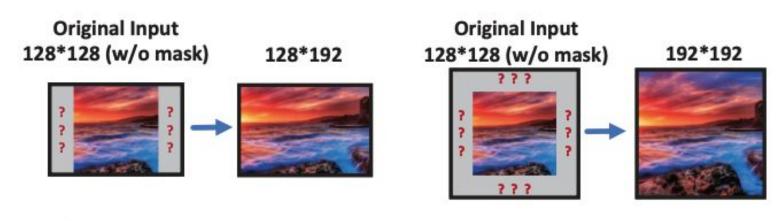




### Outpainting: Can we extrapolate beyond the borders of the image?

#### Challenges:

- Extends into unknown regions with less context
- Unknown regions must attend to inputs near the edges and far from the edges
- Unknown regions should be similar but different from inputs



(a) Horizontal extrapolation.

(b) Generalised image outpainting.



# **Our Challenge**

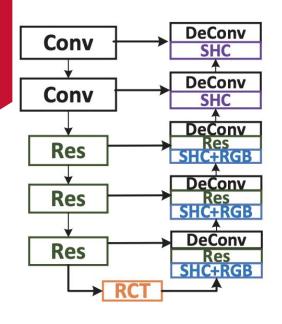
If we provide two images, can we outpaint towards each other so that the images blend together? (Similar to Lu et al. 2021)



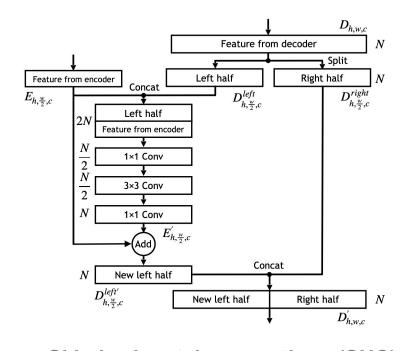
-

### **Prior Approaches: Unets**

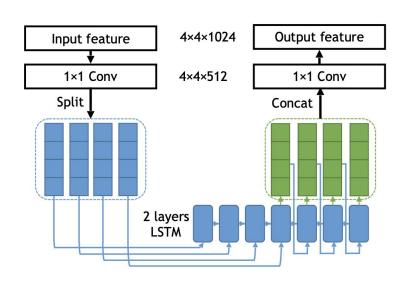




Adjusted Unet for outpainting



Skip horizontal connections (SHC):
Allows for the spatial size of the
encoder feature to be different than
the decoder feature



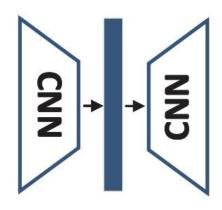
Recurrent Content Transfer (RCT): An LSTM based sequence prediction

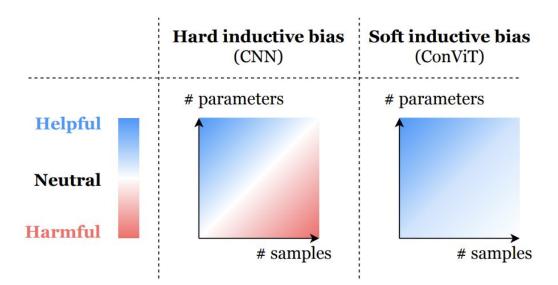


### **Prior Approaches: Convolutional & Transformer**

CNN, Vision Transformers & ConVit:

- CNNs have hard inductive biases, meaning that when data is easily available at scale the structure of CNNs learning spatial relationships is overly restrictive
- Vision Transformers use self attention and don't have this same inductive bias but requires pre-training on large amounts of data
- ConVit introduces a soft inductive bias to bridge the between CNNs and Vision transformers
- Despite this, these methods are still limited by locality and have difficulty capturing global features and long-range semantic information







#### **Prior Approaches: GANs**

UNets combined with GAN architecture and attention lead to increased performance!

Lu et al (2021), attempted to outpaint images towards each other and that they blend together to create an entire panorama:



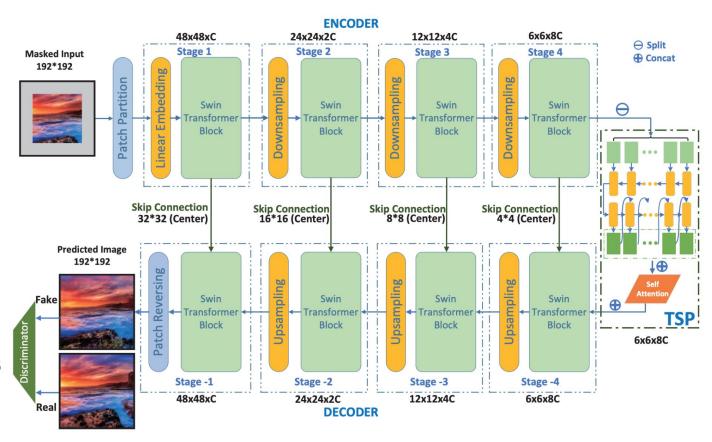
First Input Photo Second Input Photo

Resultant Panorama-1

Resultant Panorama-2

#### **Prior Approaches: UTransformer**

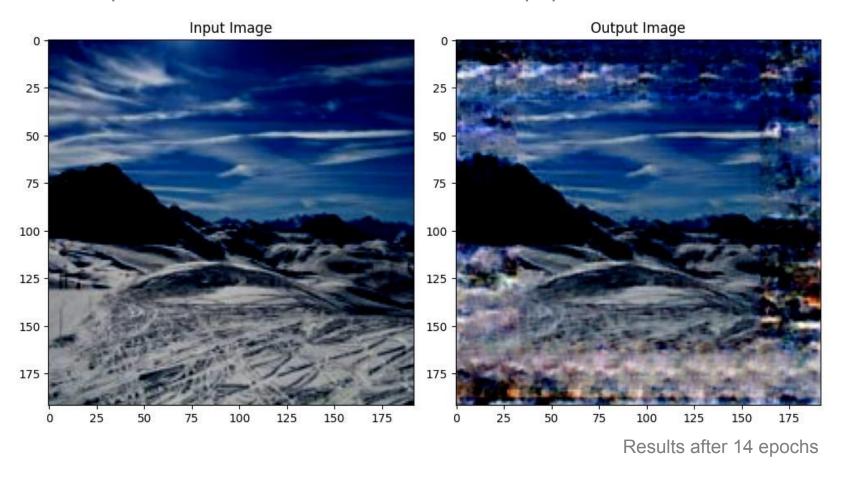
- Uses Unet & GAN architecture with Swin Transformer.
- Swin (Shifted Windows) an adaption of the transformer specifically for computer vision which leverages hierarchical feature extraction to handle spatial tasks in an efficient way by applying attention in windows
- Introduces a Temporal Spatial Predictor (TSP) as a bottleneck to ensure that spatial and temporal relationships are propagated
- TSP splits encoded features into bars and a 2-layer LSTM is used to process the sequence for each bar and then is passed to a self attention layer.





#### **UTransformer**

We were able to replicate the results of the UTransformer paper.





### **Drawbacks to U-Transformer Model**

- 1. Very slow and compute-intensive to train
  - o 1 hour to run 14 epochs on a NVIDIA A100
  - o 3 hours to train 1 epoch on RTX 2070.
- 2. Fixed size for center-expansion
  - o 128 \* 128 -> 192 \* 192
  - Hard code in model



## **Our Models**

- 1. GAN Model: Inspired by <u>Image-to-Image Translation with Conditional Adversarial Networks</u>
- 2. Diffusion Model: Inspired by <u>"Repaint: Inpainting using Denoising Diffusion Probabilistic Models"</u>, Lugmayr et al. (2022)



# **Our Dataset: NS-Outpainting**

6,000 very wide images of scenery





Original Image and Mask

## **Diffusion Model Architecture**

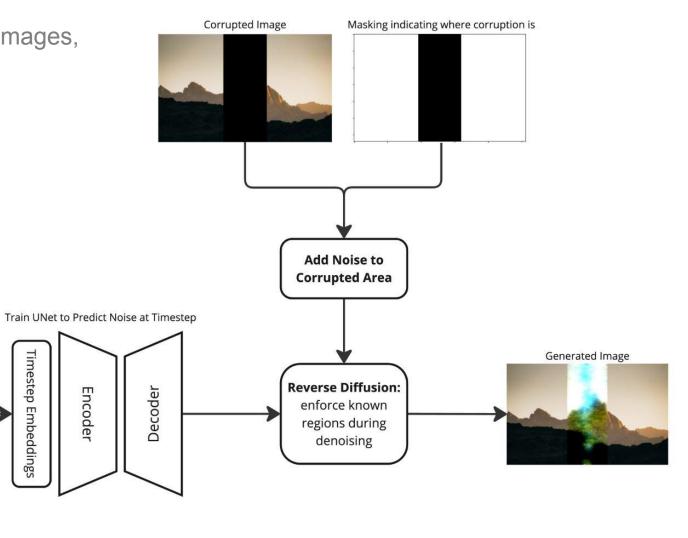
**Forward Diffusion:** 

add noise to images

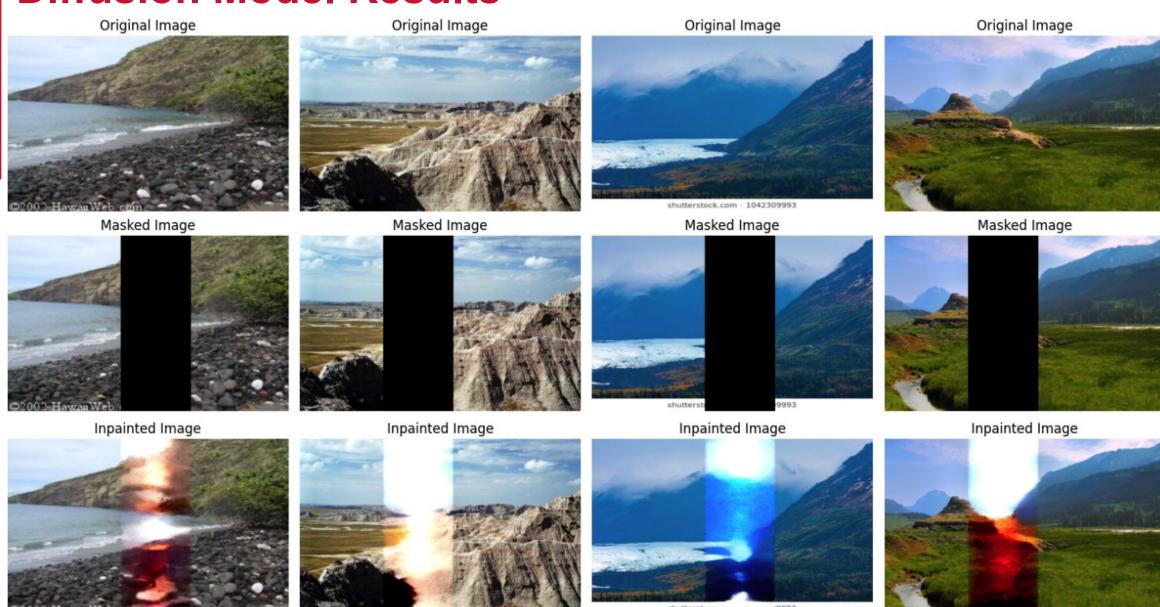
in masked regions

Timestep Embeddings

Conditioning a DDPM model on given images, yields decent results.



## **Diffusion Model Results**





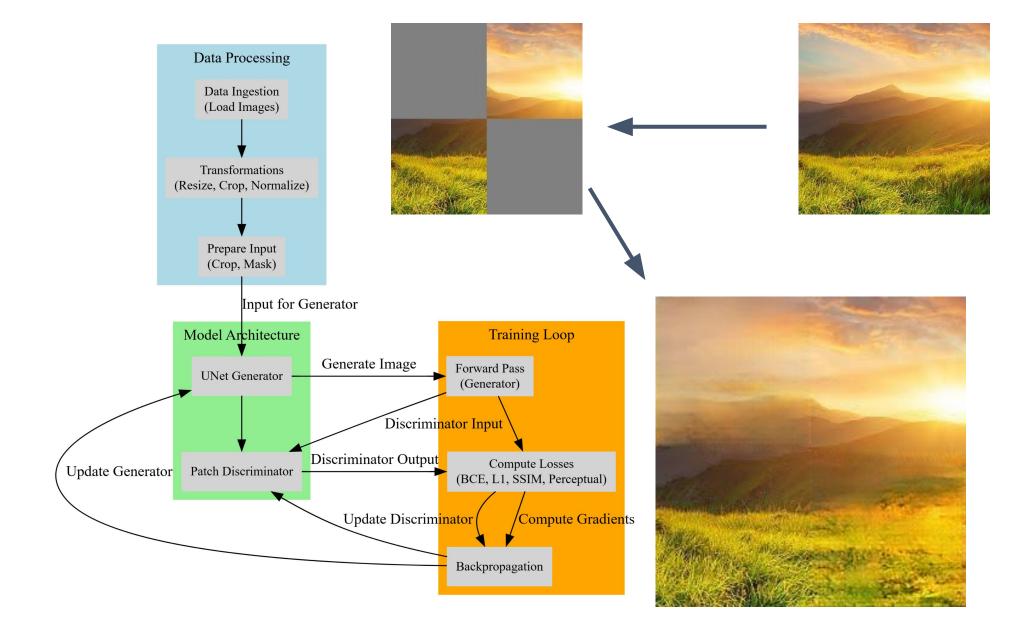
## **Diffusion Model Evaluation**

#### Challenges & findings:

- Difficulty blurring the edges of given images and generated fill (attempted to fix with gaussian blur)
- Center of the fill image was usually quite blurry
- Initially only used one mask, which lead to poorer quality results. Specifically, desert and ocean scenes could take on a forest like texture
- Color tones in early epoch were good, but in later epoch could turn reddish

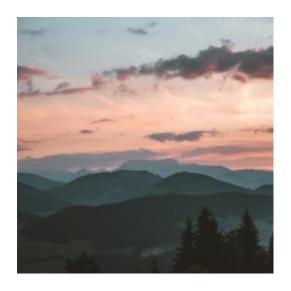
Metric	Value
Peak Signal-to-Noise Ratio (PSNR)	19.381
Structural Similarity Index Measure (SSIM)	0.762
Fréchet inception distance (FID)	505.608

## **GAN Model**





# **GAN Results**

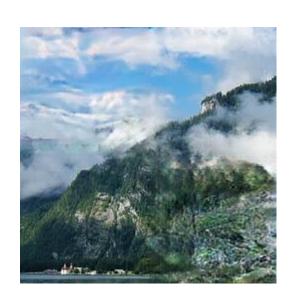














# **GAN Results-Two images**



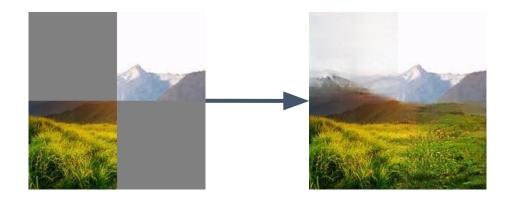


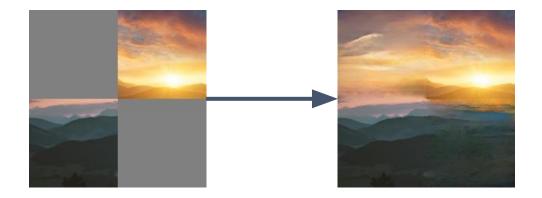




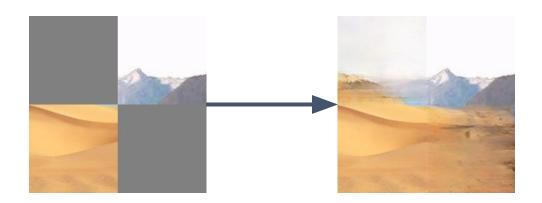


# **GAN Results - Two images**











# **GAN Model Metrics**





Metric	Value
Peak Signal-to-Noise Ratio (PSNR)	18.8690
Structural Similarity Index Measure (SSIM)	0.7305
Fréchet inception distance (FID)	69.5485

# **GAN Results-Larger Mask**





## **Our Model VS U-Transformer**

- 1. Training Costs
  - U-Transformer
    - i. 3 hours to train 1 epoch on RTX 2070.
    - ii. 500 epochs needed/
  - Our model
    - i. 1 hour to train 10 epochs on RTX 2070
    - ii. 20 epochs needed for 0.5 mask
    - iii. 50 epochs for 0.6 mask.
- 2. Image Size
  - U-Transformer
    - i. 128 \* 128 -> 192 \* 192
    - ii. Only for center-expansion, hard to change for other mask
  - Our model
    - i. 256 \* 256 base image
    - ii. The mask can be set anywhere with configuration



## **Future Potential**



Bigger image size



Reduce the blur



# **Thank You!**



## **Appendix: GAN Model Next Steps**

- Update Model Structure to optimize loss.
- Bigger image size
- Generate only the missing part, instead of using mask (hard based on GAN)
- Random crop region (hard based on GAN)



# **Appendix: Diffusion Model Next Steps**

- Try switching to a DDIM architecture
- Use Repaint's resampling strategy that jumps back and forth between timesteps
- Try using pre-trained embeddings
- Add more crops to training
- Revisit gaussian blur implementation



# **Appendix: GAN Model Architecture**

