

Unified M-estimation of Matrix Exponential Spatial Dynamic Panel Specification

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January 27th, 2022

Abstract

In this paper, a unified M-estimation method in Yang (2018) is extended to the matrix exponential spatial dynamic panel specification (MESDPS) with fixed effects in short panels. Similar to the STLE model which includes the spatial lag effect, the space-time effect and the spatial error effect in Yang (2018), the quasi-maximum likelihood (QML) estimation for MESDPS also has the initial condition specification problem. The initial-condition free M-estimator in this paper solves this problem and is proved to be consistent and asymptotically normal. An outer product of martingale difference (OPMD) estimator for the variance-covariance (VC) matrix of the M-estimator is also derived and proved to be consistent. The finite sample property of the M-estimator is studied through an extensive Monte Carlo study. The method is applied to US outward FDI data to show its validity.

JEL-Classification: C10, C13, C15, C21, C23.

Keywords: Matrix exponential; dynamic panels; martingale difference; OPMD; initial-condition free estimator.

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1 Introduction

Dynamic panel data (DPD) models are important elements in Economics literature. Spatial dependence can be incorporated into DPD models to discuss topics in applied economics like regional markets (Keller and Shiue 2007), labor economics (Foote 2007) and technological interdependence (Ertur and Koch 2007). The resulting spatial dynamic panel data (SDPD) models have gained much attention. Some papers (Lee and Yu 2010c, 2013; Xu and Lee 2019) provide excellent surveys on these models.

Depending on the type of dynamic features allowed in the SDPD model, four categories can be generated (Anselin et al. 2008; Lee and Yu 2010c): “pure space recursive” with only a spatial time lag, “time-space recursive” with an individual time lag and a spatial time lag, “time-space simultaneous” with an individual time lag and a contemporaneous spatial lag and “time-space dynamic” with all forms of lags. Recent studies have also used the terminology, *weak* and *strong* spatial dependence, to refer to the regression models that have spatial lag terms and interactive fixed effects respectively (Chudik et al. 2011; Kuersteiner and Prucha 2020; Shi and Lee 2017). While most of the literature in the SDPD models focus on the long panel setting with a large time period T (Anselin 2001; Lee and Yu 2010a; Yu and Lee 2010; Yu et al. 2008), the setup with a large cross-sectional unit n and a small time period T , named short panels, has also gained more interest recently. Some papers discuss the likelihood based estimators for short panels (Elhorst 2010; Su and Yang 2015; Yang 2018).

However there is one difficulty with the quasi-maximum likelihood (QML) estimation for the short panel SDPD model: the “initial condition” problem (Hsiao et al. 2002). The first observation for the first differenced data is endogenous in models with fixed effects, no matter whether the initial observation is endogenous or exogenous. To solve this problem, the traditional way is to use the predicted value obtained from the values of regressors (Elhorst 2010; Hsiao et al. 2002; Su and Yang 2015). But this method has its disadvantages. First process starting time is unknown and the time-varying regressors need to be trend or first-difference stationary. Second, the method cannot be applied to the SDPD models with spatial lags (SL) because the initial difference contains spatial effect in the exogenous part when expanded using backward substitutions. To deal with this problem, Yang (2018) proposes an initial-condition free M-estimator for the STLE model that includes a dynamic effect, a spatial lag (SL), a space-time effect (STL) and a spatial error (SE). The estimator is derived from a set of estimating equations based on the unbiased adjusted quasi score (AQS) functions and is consistent and asymptotically normal. He also proposes an outer product of martingale difference (OPMD) estimator for the variance-covariance (VC) matrix of the M-estimator and proves that it is consistent.

The matrix exponential spatial specification (MESS) is first proposed by LeSage and Pace (2007). They introduce the cross-sectional MESS and show that it has advantages over the traditional spatial autoregressive (SAR) models: a simpler log-likelihood function without the Jacobian matrix and an unrestricted parameter space for its spatial coefficients. Debarsy et al. (2015) derive the QML estimator and the GMM estimator of the MESS in cross-sectional setting and explore

their large sample properties. Similar to the SPD models, MESS can be extended to the panel data models (Figueiredo and Da Silva 2015; LeSage and Chih 2018; Zhang et al. 2019). There has been a growing interest in recent literature in using MESS to explore various topics such as technological spillover (LeSage and Pace 2000), housing price (LeSage and Pace 2004), third-country effect on FDI (Debary et al. 2015), cigarette demands (Figueiredo and Da Silva 2015), wage rates (LeSage and Chih 2018) and geographical spillover (Zhang et al. 2019).

In this paper, the M-estimation method in Yang (2018) is extended to the matrix exponential spatial dynamic panel specification (MESDPS) with fixed effect in short panels, which assumes large n and small T and is typical for most real world datasets. Similar to the STLE model, the MESDPS also suffers from the “initial condition” problem. As discussed above, the traditional way of solving this problem, which is to use the predicted value derived from the values of the regressors, does not provide a satisfactory solution. A consistent way to estimate the coefficients and its VC matrix is needed. We first derive a set of conditional quasi score (CQS) functions treating the initial differences as exogenous, even if they are not. Then we modify these score functions to get the adjusted quasi score (AQS) functions which are unbiased. The M-estimator thus is derived by setting the AQS functions equaling to zero. To get a consistent estimate for the VC matrix of the M-estimator, a martingale difference (M.D.) of the AQS functions at the true value is established. The average of the outer product of M.D. (OPMD) is shown to generate a consistent estimate of the VC matrix when being substituted into the “sandwich” estimate of it, which is referred to as the OPMD estimator. In Monte Carlo simulations six types of submodels, MESDPS(1,1,1), MESDPS(1,1,0), MESDPS(1,0,1), MESDPS(0,1,1), MESDPS(1,0,0) and MESDPS(0,1,0) are estimated, where 1’s denote the MESS in the dependent variable, the lagged dependent variable and the disturbances respectively. The results show that the M-estimator has good finite sample properties and is robust to the way the initial observation is generated, which implies that it solves the “initial condition” problem. The OPMD estimator of the VC matrix generates asymptotic standard errors that’s much closer to the true standard deviation than the other candidates, especially when the disturbance is non-normal, emphasizing its importance in research when the normality of disturbances is in doubt. MESDPS(1,1,1) is applied to US outward FDI data to examine the validity of the model. The estimation results for the STLE model that includes the spatial lag, the space-time effect and the spatial error from Yang (2018) are also reported to emphasize the relation for the spatial coefficients of these two models.

The contribution of this paper is two-fold. First the unified M-estimation method is extended to MESDPS. The unified M-estimation is designed for the STLE model in Yang (2018). The MESDPS and the STLE model are non-nested. So it remains to be explored whether the M-estimation method designed for the STLE model can be extended to the MESDPS. Second, to our best knowledge, this is the first paper to consider MESS in a dynamic panel setting. Previous literature (Figueiredo and Da Silva 2015; LeSage and Chih 2018; Zhang et al. 2019) study the MESS in a panel data model. As mentioned previously, the “initial condition” problem remains when the spatial effects in the dynamic panel data model are in forms of the MESS, so consistent estimators for the coefficients

and corresponding standard errors need to be designed, which is accomplished in this paper.

The rest of the paper is organized as follows. Section 2 introduces the M-estimation method. Section 3 presents the asymptotic distribution of the M-estimator and introduces the OPMD estimator of its VC matrix. Section 4 presents Monte Carlo simulation results. Section 5 applies the model to US outward FDI. Section 6 concludes. All technical parts and proofs are provided in a web appendix which is available through the journal webpage.

2 M-estimation of Matrix Exponential Spatial Dynamic Panel Specification

In this section we first discuss the literature that incorporate the MESS in the panel data setting. Although these papers discuss the panel data instead of the dynamic panel data, we include them in the review to underline the importance of our study, i.e., MESDPS has not been explored in the previous literature. The M-estimator and the OPMD estimator thus provide researchers who want to work with the MESDPS a reliable method to estimate the parameters and conduct inference. In the second subsection we present the M-estimation in MESDPS(1,1,1) in short panel. Short panel assumes large n and small T , which is typical for most real world datasets. M-estimation first formulates a set of conditional quasi score (CQS) functions assuming that the initial difference is exogenous, and then modifies it to get a set of adjusted quasi score (AQS) functions which result in consistent parameter estimates.

2.1 Matrix Exponential Spatial Dynamic Panel Specification

The matrix exponential spatial dynamic panel specification with fixed effects is given by

$$e^{\alpha_1 W_1} y_t = \tau y_{t-1} + e^{\alpha_2 W_2} y_{t-1} + X_t \beta + Z \gamma + \mu + \lambda_t l_n + u_t, \quad e^{\alpha_3 W_3} u_t = \epsilon_t, \quad t = 1, 2, \dots, T, \quad (2.1)$$

where y_t is an $n \times 1$ vector of observations on the dependent variable; W_r for $r = 1, 2, 3$ are three $n \times n$ spatial weight matrices, with corresponding spatial coefficients α_r capturing the MESS in the dependent variable, the lagged dependent variable and the disturbances respectively; y_{t-1} is the lagged vector of y_t with coefficient τ capturing the dynamic effect; X_t is an $n \times k$ matrix of time-varying exogenous variables with corresponding coefficient vector β ; Z is an $n \times p$ matrix of time-invariant exogenous variables, which might include the intercept, with corresponding coefficient vector γ ¹; μ is an $n \times 1$ vector of unobserved individual fixed effects; λ_t is the time fixed effects; l_n is an $n \times 1$ vector of 1; and ϵ_t is a vector of disturbances independent and identically distributed across i and t with mean zero and variance σ_ϵ^2 . The matrix exponential $e^{\alpha_r W_r}$ is defined as $\sum_{j=0}^{\infty} \frac{\alpha_r^j W_r^j}{j!}$ for $r = 1, 2$ and 3 and is always invertible with inverse $e^{-\alpha_r W_r}$ (Chiu et al. 1996). The reduced form of the model is given by $y_t = e^{-\alpha_1 W_1} (\tau I_n + e^{\alpha_2 W_2}) y_{t-1} + e^{-\alpha_1 W_1} (X_t \beta + Z \gamma + \mu + \lambda_t l_n + e^{-\alpha_3 W_3} \epsilon_t)$. The

¹As kindly pointed out by a referee, since the estimation approach is based on the first difference of the model, we cannot estimate the parameters of time-invariant variables.

model is stationary if all eigenvalues of $e^{-\alpha_1 W_1}(\tau I_n + e^{\alpha_2 W_2})$ lie inside the unit circle. (Proposition 10.1, Hamilton (1994)).

The specification in (2.1) is comprehensive. It incorporates different submodels by setting the spatial coefficients $\alpha_r = 0$ for $r = 1, 2$ or 3 . By setting $\alpha_2 = 0$, we have MESDPS(1,0,1) with MESS in the dependent variable and the disturbances:

$$e^{\alpha_1 W_1} y_t = (\tau + 1)y_{t-1} + X_t \beta + Z \gamma + \mu + \lambda_t l_n + u_t, \quad e^{\alpha_3 W_3} u_t = \epsilon_t, \quad t = 1, 2, \dots, T. \quad (2.2)$$

Without $(\tau + 1)y_{t-1}$, $Z \gamma$ and merging $\lambda_t l_n$ into $X_t \beta$, Zhang et al. (2019) study the QML estimation of (2.2) in panel data setting. They allow large n and small or large T and establish the consistency and asymptotic normality under unknown heteroskedasticity when the spatial weight matrices in MESS for y_t and u_t are commutable, i.e., $W_1 W_3 = W_3 W_1$ ².

By setting $\alpha_2 = 0$ and $\alpha_3 = 0$, we get MESDPS(1,0,0):

$$e^{\alpha_1 W_1} y_t = (\tau + 1)y_{t-1} + X_t \beta + Z \gamma + \mu + \lambda_t l_n + \epsilon_t, \quad t = 1, 2, \dots, T. \quad (2.3)$$

Figueiredo and Da Silva (2015) discuss (2.3) without $(\tau + 1)y_{t-1}$ and $Z \gamma$. They use the deviation from mean operator to get rid of the individual and time fixed effects and present the ML estimation of the transformed model. This approach, however, results in linearly dependent disturbance terms after transformation. Instead, we can pre- and post-multiply the model by the orthonormal eigenvector matrix of the individual and time mean deviation operators respectively (Lee and Yu 2010b).

The literature above incorporate MESS into a panel data model. To the best of our knowledge, MESS in a dynamic panel setting has not been studied in the previous literature. The M-estimation proposed in this paper provides consistent and asymptotically normal estimates. The OPMD estimator for the VC matrix is also consistent and provides good finite sample properties. The method is useful for those who want to utilize the MESDPS in empirical research.

2.2 The M-estimation of MESDPS

Different from the geometrical decay in the STLE model, (2.1) has an exponential decay. It also has a simpler quasi log-likelihood function without the Jacobian of the transformation. However, they suffer from the “initial condition” problem discussed below.

Denote the true value of the parameter vector by $\theta_0 = (\beta'_0, \sigma_{\epsilon 0}^2, \tau_0, \alpha'_0)'$, where $\alpha_0 = (\alpha_{10}, \alpha_{20}, \alpha_{30})'$. Let $A_{20} = \tau_0 I_n + e^{\alpha_{20} W_2}$. Taking first difference for (2.1), we get:

$$e^{\alpha_{10} W_1} \Delta y_t = A_{20} \Delta y_{t-1} + \Delta X_t \beta_0 + \Delta u_t, \quad e^{\alpha_{30} W_3} \Delta u_t = \Delta \epsilon_t, \quad t = 2, 3, \dots, T. \quad (2.4)$$

where $\Delta \lambda_t l_n$ is merged into $\Delta X_t \beta_0$. Here we abuse the notation and let $\Delta X_t \beta_0$ in (2.4) denote

²In this paper the commutability is not required since it is a dynamic panel data setting instead of panel data setting.

the merged variable of first differenced $\Delta X_t \beta_0$ and $\Delta \lambda_t l_n$ from (2.1). Note (2.4) is not defined for $t = 1$ because Δy_1 depends on Δy_0 and the latter is unobserved. So even if y_0 and Δy_0 is exogenous, the likelihood function which conditions on Δy_0 cannot be formulated. Also y_1 and thus Δy_1 are not exogenous. This “initial condition” problem prevents us from deriving consistent estimates for the MESDPS. The traditional way is to use the predicted values based on the observed values of regressors (Elhorst 2010; Hsiao et al. 2002; Su and Yang 2015). However, it requires that the time-varying regressors be trend or first-difference stationary. Besides, for the MESDPS with MESS in the dependent variable, for example MESDPS(1,0,0), the first differenced equation is given by $e^{\alpha_{10} W_1} \Delta y_t = (\tau_0 + 1) \Delta y_{t-1} + \Delta X_t \beta_0 + \Delta \epsilon_t$. By backward substitution, we get $\Delta y_1 = (\tau_0 + 1)^m (e^{-\alpha_{10} W_1})^m \Delta y_{-m+1} + \sum_{i=0}^{m-1} (\tau_0 + 1)^i (e^{-\alpha_{10} W_1})^{i+1} \Delta X_{-i+1} \beta_0 + \sum_{i=0}^{m-1} (\tau_0 + 1)^i (e^{-\alpha_{10} W_1})^{i+1} \Delta \epsilon_{-i+1}$, where $-m$ is the process starting time. Note the exogenous part contains the MESS $e^{-\alpha_{10} W_1}$. The linear structure no longer exists due to the existence of the MESS and the linear projection method fails. Thus we need a unified way to estimate the model.

To express the model in vector form, we define the following: $\Delta Y = (\Delta y_2', \dots, \Delta y_T')'$, $\Delta Y_{-1} = (\Delta y_1', \dots, \Delta y_{T-1}')'$, $\Delta X = (\Delta X_2', \dots, \Delta X_T')'$, $\Delta u = (\Delta u_2', \dots, \Delta u_T')'$, $\Delta \epsilon = (\Delta \epsilon_2', \dots, \Delta \epsilon_T')'$, $\mathbf{A}_{20} = I_{T-1} \otimes A_{20}$, $\mathbf{W}_r = I_{T-1} \otimes W_r$ and $\mathbf{e}^{\alpha_{r0} \mathbf{W}_r} = I_{T-1} \otimes e^{\alpha_{r0} W_r}$ for $r = 1, 2$ and 3 . Stacking the observations vertically, the model can be expressed as:

$$\mathbf{e}^{\alpha_{10} \mathbf{W}_1} Y = \mathbf{A}_{20} \Delta Y_{-1} + \Delta X \beta_0 + \Delta u, \quad \mathbf{e}^{\alpha_{30} \mathbf{W}_3} \Delta u = \Delta \epsilon. \quad (2.5)$$

So $\text{Var}(\Delta u) = \text{Var}(\mathbf{e}^{-\alpha_{30} \mathbf{W}_3} \Delta \epsilon) = \sigma_{\epsilon 0}^2 (B \otimes e^{-\alpha_{30} W_3} e^{-\alpha_{30} W_3'}) = \sigma_{\epsilon 0}^2 \Sigma(\alpha_{30})$, where

$$B = \begin{pmatrix} 2 & -1 & 0 & \cdots & 0 & 0 & 0 \\ -1 & 2 & -1 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -1 & 2 & -1 \\ 0 & 0 & 0 & \cdots & 0 & -1 & 2 \end{pmatrix}$$

Under normally distributed ϵ_t , the joint distribution of Δu_t can be used to derive the log-likelihood function of parameters θ :

$$\ell(\theta) = -\frac{n(T-1)}{2} \log(2\pi\sigma_\epsilon^2) - \frac{1}{2} \log|\Sigma(\alpha_3)| + \log|\mathbf{e}^{\alpha_1 \mathbf{W}_1}| - \frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \quad (2.6)$$

with $\theta = (\beta', \sigma_\epsilon^2, \tau, \alpha')'$ and $\phi = (\beta', \tau, \alpha_1, \alpha_2)'$ where ϕ are the parameters in $\Delta u(\phi) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1} - \Delta X \beta$. Note $\log|\Sigma(\alpha_3)| = n \log|B| + 2(T-1) \log(e^{-\alpha_3 \text{tr}(W_3)}) = n \log|B|$ which is a constant and $\log(|\mathbf{e}^{\alpha_1 \mathbf{W}_1}|) = (T-1) \log(e^{\alpha_1 \text{tr}(W_1)}) = 0$ because the spatial weight matrices have zero diagonals. So we can ignore the constants and simplify the log-likelihood function to:

$$\ell(\theta) = -\frac{n(T-1)}{2} \log(\sigma_\epsilon^2) - \frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi). \quad (2.7)$$

Given $\zeta = (\tau, \alpha')'$ with $\alpha = (\alpha_1, \alpha_2, \alpha_3)'$, we can derive the estimators of β and σ_ϵ^2 as following:

$$\tilde{\beta}(\zeta) = (\Delta X' \Sigma(\alpha_3)^{-1} \Delta X)^{-1} \Delta X' \Sigma(\alpha_3)^{-1} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1}), \quad (2.8)$$

$$\tilde{\sigma}_\epsilon^2(\zeta) = \frac{1}{n(T-1)} \Delta \tilde{u}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta \tilde{u}(\zeta), \quad (2.9)$$

where $\Delta \tilde{u}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1} - \Delta X \tilde{\beta}(\zeta)$. Substituting them back into (2.7), ignoring constants, we get the concentrated log-likelihood function:

$$l^c(\zeta) = -\frac{n(T-1)}{2} \log[\Delta \tilde{u}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta \tilde{u}(\zeta)]. \quad (2.10)$$

The conditional QML (CQML) estimators $\tilde{\zeta} = (\tilde{\tau}, \tilde{\alpha}')'$ are then derived by maximizing (2.10). The CQML estimators $\tilde{\beta} = \tilde{\beta}(\tilde{\zeta})$ and $\tilde{\sigma}_\epsilon^2 = \tilde{\sigma}_\epsilon^2(\tilde{\zeta})$ are subsequently derived by substituting $\tilde{\zeta}$ into (2.8) and (2.9).

The comprehensive model in Yang (2018) that includes the spatial lag (SL), the space-time lag (STL) and the spatial error (SE) is denoted as the STLE model. Consider the STLE model given by $y_t = \rho y_{t-1} + \lambda_1 W_1 y_t + \lambda_2 W_2 y_{t-1} + X_t \beta + Z_t \gamma + \mu + \alpha_t l_n + u_t$, $u_t = \lambda_3 W_3 u_t + \epsilon_t$. The log-likelihood function (2.7) and the concentrated log-likelihood function (2.10) are simpler without the Jacobian $\log|\mathbf{B}_1(\lambda_1)|$ where $\mathbf{B}_1(\lambda_1) = I_{T-1} \otimes B_1(\lambda_1)$ and $B_1(\lambda_1) = I_n - \lambda_1 W_1$. It makes the MESDPS computationally easier, especially for large sample sizes. A correspondence of relation for the parameters also exists for the MESDPS and the STLE model. Consider (2.1), assume the spatial weight matrix is row-normalized and a shock ∂x_{tk} is applied to all spatial units on the k th independent variable X_{tk} , so that the new variable becomes $X_{tk} + l_n \partial x_{tk}$. Then the contemporaneous total impact for the MESDPS is given by $\partial y_t = e^{-\alpha_1 W_1} l_n \partial x_{tk} \beta_k$, so the average contemporaneous total impact is $\frac{1}{n} l_n' \partial y_t = e^{-\alpha_1} \partial x_{tk} \beta_k$. Similarly for the STLE model, the average contemporaneous total impact is given by $\frac{1}{1-\lambda_1} \partial x_{tk} \beta_k$. Equating them gives us the relation $\lambda_1 = 1 - e^{\alpha_1}$. For y_{t-1} , a shock $\partial \nu_{t-1}$ leads to the average total impact $e^{-\alpha_1} (\tau + e^{\alpha_2}) \partial \nu_{t-1}$ for the MESDPS and $\frac{\rho + \lambda_2}{1-\lambda_1} \partial \nu_{t-1}$ for the STLE model. So $\tau + e^{\alpha_2} = \rho + \lambda_2$. Setting $\alpha_2 = 0$ and $\lambda_2 = 0$ gives us $\rho = \tau + 1$, which implies $\lambda_2 = e^{\alpha_2} - 1$. On contrary to the negative relation between α_1 and λ_1 , the relation between α_2 and λ_2 is positive. When $-1 < \lambda_2 < 0$, α_2 also takes negative values and vice versa.

The CQML estimator $\tilde{\theta} = (\tilde{\beta}', \tilde{\sigma}_\epsilon^2, \tilde{\tau}, \tilde{\alpha}')'$ derived above encounters a bias when T is small as shown below. We simplify the notation by denoting $\Sigma = \Sigma(\alpha_3)$ and $\Sigma_0 = \Sigma(\alpha_{30})$. Using the simplified log-likelihood function in (2.7), the conditional quasi score (CQS) function $S(\theta) = \frac{\partial \ell(\theta)}{\partial \theta}$

is derived as

$$S(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma^{-1} \Delta u(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta u(\phi)' \Sigma^{-1} \Delta u(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1}, \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y, \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}, \\ \alpha_3 : & -\frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi), \end{cases} \quad (2.11)$$

where $E_3 = e^{\alpha_3 \mathbf{W}_3'} (W_3 + W_3') e^{\alpha_3 \mathbf{W}_3}$. We will show that the τ , α_1 and α_2 elements of the CQS function (2.11) are biased, meaning their expected values are nonzeros at the true parameter values, leading to the inconsistency of the CQML estimator. First let's make Assumption 1 below.

Assumption 1. For model (2.1), (i) the processes started m periods before the start of data collection, the 0th period, (ii) if $m \geq 1$, Δy_0 is independent of future disturbances $\{\epsilon_t, t \geq 1\}$; if $m = 0$, y_0 is independent of future disturbances $\{\epsilon_t, t \geq 1\}$.

Assumption 1 is the same as the Assumption A in Yang (2018). Compared with the assumptions in previous literature (Elhorst 2010; Hsiao et al. 2002; Su and Yang 2015), Assumption 1 requires minimum information about the past processes. It does not require the time-varying regressors to be trend or first-difference stationary. This is one of the advantages of M-estimation, i.e., some restrictive assumptions on the initial values and initial differences are removed. Denote $A_{21,0} = A_{20} e^{-\alpha_{10} \mathbf{W}_1}$. The following lemma is necessary to compute the bias of the CQS function.

Lemma 2.1. Under Assumption 1, $E(\Delta Y \Delta \epsilon') = -\sigma_{\epsilon 0}^2 e^{-\alpha_{10} \mathbf{W}_1} \mathbf{D}_0 e^{-\alpha_{30} \mathbf{W}_3}$ and $E(\Delta Y_{-1} \Delta \epsilon') = -\sigma_{\epsilon 0}^2 e^{-\alpha_{10} \mathbf{W}_1} \mathbf{D}_{-1,0} e^{-\alpha_{30} \mathbf{W}_3}$, where

$$\mathbf{D}_{-1,0} = \begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_{21,0} - 2I_n & I_n & \ddots & \dots & \vdots \\ (A_{21,0} - I_n)^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ A_{21,0}^{T-4} (A_{21,0} - I_n)^2 & \dots & (A_{21,0} - I_n)^2 & A_{21,0} - 2I_n & I_n \end{pmatrix}$$

$$\text{and } \mathbf{D}_0 = \begin{pmatrix} A_{21,0} - 2I_n & I_n & \dots & \dots & 0 \\ (A_{21,0} - I_n)^2 & A_{21,0} - 2I_n & \ddots & \dots & \vdots \\ \vdots & \vdots & \ddots & \ddots & I_n \\ A_{21,0}^{T-3} (A_{21,0} - I_n)^2 & \dots & \dots & (A_{21,0} - I_n)^2 & A_{21,0} - 2I_n \end{pmatrix}.$$

Here we used the fact that ϵ_{it} is i.i.d. across i and t , and that $e^{\alpha_{r0} \mathbf{W}_r}$ is always invertible for

$r = 1$ and 3. Using Lemma 2.1, we have

$$E(\Delta u' \Sigma_0^{-1} \Delta Y_{-1}) = -\sigma_{\epsilon 0}^2 \text{tr}(\mathbf{D}_{-1,0} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_{10} \mathbf{W}_1}), \quad (2.12)$$

$$E(\Delta u' \Sigma_0^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_{10} \mathbf{W}_1} \Delta Y) = -\sigma_{\epsilon 0}^2 \text{tr}(\mathbf{D}_0 \mathbf{B}^{-1} \mathbf{W}_1), \quad (2.13)$$

$$E(\Delta u' \Sigma_0^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_{20} \mathbf{W}_2} \Delta Y_{-1}) = -\sigma_{\epsilon 0}^2 \text{tr}(\mathbf{D}_{-1,0} \mathbf{B}^{-1} \mathbf{W}_{21,0}), \quad (2.14)$$

where $\mathbf{W}_{21,0} = \mathbf{W}_2 \mathbf{e}^{\alpha_{20} \mathbf{W}_2} \mathbf{e}^{-\alpha_{10} \mathbf{W}_1}$ and $\mathbf{B} = B \otimes I_n$. These equations imply that $E(\frac{\partial \ell(\theta)}{\partial \tau})$, $E(\frac{\partial \ell(\theta)}{\partial \alpha_1})$ and $E(\frac{\partial \ell(\theta)}{\partial \alpha_2})$ are nonzero, making τ , α_1 and α_2 elements of the CQS function (2.11) biased. The set of CQS functions are estimating functions for the CQML estimator. The consistency of an M-estimator requires that the estimating functions need to have a probability limit of zero at the true parameter values, i.e., $\text{plim}_{n \rightarrow \infty} \frac{1}{nT} S(\theta_0) = 0$ (Vaart 2000). However Lemma 2.1 implies that it does not hold for the CQML estimator. Typically $E(\frac{\partial \ell(\theta)}{\partial \tau})$, $E(\frac{\partial \ell(\theta)}{\partial \alpha_1})$ and $E(\frac{\partial \ell(\theta)}{\partial \alpha_2})$ are of order n , which implies $E[\sqrt{nT}(\tilde{\theta} - \theta_0)] = O(\sqrt{\frac{n}{T}})$. The bias thus does not vanish in short panels when T is fixed. The bias vanishes when $\frac{n}{T} \rightarrow 0$, which refers to a long panel and is not of interest in our study. So the CQML estimation fails to produce consistent estimates.

To have a set of unbiased estimating functions, we modify the CQS functions in (2.11) to get the adjusted quasi score (AQS) functions:

$$S^*(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_{\epsilon}^2} \Delta X' \Sigma^{-1} \Delta u(\phi), \\ \sigma_{\epsilon}^2 : & -\frac{n(T-1)}{2\sigma_{\epsilon}^2} + \frac{1}{2\sigma_{\epsilon}^2} \Delta u(\phi)' \Sigma^{-1} \Delta u(\phi), \\ \tau : & \frac{1}{\sigma_{\epsilon}^2} \Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_1 : & -\frac{1}{\sigma_{\epsilon}^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \alpha_2 : & \frac{1}{\sigma_{\epsilon}^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \\ \alpha_3 : & -\frac{1}{2\sigma_{\epsilon}^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi). \end{cases} \quad (2.15)$$

The M-estimator derived from the AQS functions is consistent and asymptotically normal, which will be shown in the next section. It is interesting to compare the AQS functions with those for the STLE model in Yang (2018). First the bias term $\text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1})$ in the τ element has similar format with that for the ρ element³ in the STLE model (with SAR process being replaced by MESS). This means that while the inherent spatial processes are different, the format of the bias that comes from the dynamic effect is not affected by the nature of the spatial structure. Second thing to note is that, similar to the STLE model, the adjustments in the AQS functions are free from MESS in the disturbance term, i.e., $e^{\alpha_3 \mathbf{W}_3}$ does not appear in the trace terms. This implies that the AQS adjustments will not change if MESS in the disturbance term changes to other forms of spatial relationship, e.g., higher order MESS, autoregressive, moving average, etc. Third the adjustments modify the estimation of τ , α_1 and α_2 so that they become nonlinear.

To derive the M-estimator, we first solve for the constrained M-estimators of β and σ_{ϵ}^2 , given

³Note the differences in the definition of matrix \mathbf{D} and \mathbf{D}_{-1} with those in Yang (2018).

$\zeta = (\tau, \alpha')'$, as

$$\hat{\beta}_M(\zeta) = (\Delta X' \Sigma^{-1} \Delta X)^{-1} \Delta X' \Sigma^{-1} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1}), \quad (2.16)$$

$$\hat{\sigma}_{\epsilon, M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \Delta \hat{u}(\zeta), \quad (2.17)$$

where $\Delta \hat{u}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1} - \Delta X \hat{\beta}_M(\zeta)$. Then $\hat{\beta}_M(\zeta)$ and $\hat{\sigma}_{\epsilon, M}^2(\zeta)$ are substituted back into the other four elements of the AQS function $S^*(\theta)$ to get the concentrated AQS function:

$$S^{*c}(\zeta) = \begin{cases} \tau : & \frac{1}{\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_1 : & -\frac{1}{\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \alpha_2 : & \frac{1}{\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \\ \alpha_3 : & -\frac{1}{2\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' (\mathbf{B}^{-1} \otimes \mathbf{E}_3) \Delta \hat{u}(\zeta). \end{cases} \quad (2.18)$$

The unconstrained M-estimator $\hat{\zeta}_M = (\hat{\tau}_M, \hat{\alpha}'_M)'$ can be solved by letting $S^{*c}(\zeta) = 0$. The unconstrained M-estimators $\hat{\beta}_M$ and $\hat{\sigma}_{\epsilon, M}^2$ are then derived by substituting $\hat{\zeta}_M$ into $\hat{\beta}_M(\zeta)$ and $\hat{\sigma}_{\epsilon, M}^2(\zeta)$. Note the CQML estimator (CQMLE) and the M-estimator use the same set of estimators of β and σ_ϵ^2 to derive unconstrained ones, i.e., $\tilde{\beta}(\zeta) = \hat{\beta}_M(\zeta)$ and $\tilde{\sigma}_\epsilon^2(\zeta) = \hat{\sigma}_{\epsilon, M}^2(\zeta)$, which are from (2.8), (2.16), (2.9) and (2.17) respectively. The advantage of M-estimation comes from the AQS function (2.15). It adjusts the estimation functions so that they become unbiased. For the CQML estimation, the estimators $\tilde{\beta}(\tilde{\zeta})$ and $\tilde{\sigma}^2(\tilde{\zeta})$ are biased because of the spillover from the bias of the estimator $\tilde{\zeta}$ when being substituted into (2.8) and (2.9).

3 Asymptotic Properties of the M-estimator

In this section we explore the asymptotic properties of the M-estimator. We first prove it is consistent and then derive its asymptotic distribution. To facilitate valid inference, an OPMD estimator of the VC matrix is also proposed. Valid inference can thus be based on the standard errors implied by the OPMD estimator of the VC matrix.

3.1 Consistency of the M-estimator

To prove the consistency and to later derive the asymptotic distribution of the M-estimator, we first make some regularity assumptions. Let C_n be an $n \times n$ matrix. Then C'_n , $\text{tr}(C_n)$, $|C_n|$, $\|C_n\|$, $\gamma_{\min}(C_n)$ and $\gamma_{\max}(C_n)$ denote the transpose, trace, determinant, Euclidean norm, the smallest and largest eigenvalues of C_n respectively.

Assumption 2. *Matrices $\{W_1\}$, $\{W_2\}$ and $\{W_3\}$ are bounded in both row and column sum norms. The diagonal elements of W_1 , W_2 and W_3 are zeroes.*

Assumption 3. The time-varying regressors $\{X_t, t = 1, \dots, T\}$ are exogenous with uniformly bounded elements and have full column rank. Also $\lim_{n \rightarrow \infty} \frac{1}{nT} \Delta X' \Delta X$ exists and is nonsingular.

Assumption 4. There exists a constant $\delta > 0$ such that $|\alpha_r| \leq \delta$ for $r = 1, 2$ and 3, and the true ζ_0 is in the interior of the parameter space \mathcal{Z} . Also there exist a lower bound \underline{c}_{α_r} and an upper bound \bar{c}_{α_r} such that $0 < \underline{c}_{\alpha_r} \leq \inf_{\alpha_r \in \mathcal{Z}_r} \gamma_{\min}(e^{\alpha_r W_r'} e^{\alpha_r W_r}) \leq \sup_{\alpha_r \in \mathcal{Z}_r} \gamma_{\max}(e^{\alpha_r W_r'} e^{\alpha_r W_r}) \leq \bar{c}_{\alpha_r} < \infty$ for $r = 1, 2$ and 3.

Assumption 5. The $\{\epsilon_{it}\}$ are i.i.d. with mean zero and variance σ_ϵ^2 , and $E|\epsilon_{it}|^{4+a}$ exists for some $a > 0$.

Assumption 6. For an $n \times n$ matrix C_n uniformly bounded in row and column sums with elements of uniform order g_n^{-1} , and an $n \times 1$ vector c_n with elements of uniform order $g_n^{-1/2}$, (i) $\frac{g_n}{n} \Delta y_1' C_n \Delta y_1 = O_p(1)$ and $\frac{g_n}{n} \Delta y_1' C_n \Delta \epsilon_2 = O_p(1)$; (ii) $\frac{g_n}{n} [\Delta y_1 - E(\Delta y_1)]' c_n = o_p(1)$; (iii) $\frac{g_n}{n} [\Delta y_1' C_n \Delta y_1 - E(\Delta y_1' C_n \Delta y_1)] = o_p(1)$; (iv) $\frac{g_n}{n} [\Delta y_1' C_n \Delta \epsilon_2 - E(\Delta y_1' C_n \Delta \epsilon_2)] = o_p(1)$.

Assumptions 2-5 are standard in the literature (see, e.g., Lee (2004), Debarsy et al. (2015)). Assumption 6 is the same as Assumption F in Yang (2018). It imposes some mild conditions on the initial difference Δy_1 which will be used in the later proofs.

First note that the consistency of $\hat{\theta}_M = (\hat{\beta}_M', \hat{\sigma}_{\epsilon, M}^2, \hat{\tau}_M, \hat{\alpha}_M')'$ follows from the consistency of $\hat{\zeta}_M = (\hat{\tau}_M, \hat{\alpha}_M')'$ since $\hat{\beta}_M = \hat{\beta}_M(\hat{\zeta}_M)$ and $\hat{\sigma}_{\epsilon, M}^2 = \hat{\sigma}_{\epsilon, M}^2(\hat{\zeta}_M)$. To prove the consistency of $\hat{\zeta}_M$, we first define the population counterpart of the AQS function as:

$$\bar{S}^*(\theta) = E[S^*(\theta)] = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} E[\Delta X' \Sigma^{-1} \Delta u(\phi)], \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} E[\Delta u(\phi)' \Sigma^{-1} \Delta u(\phi)], \\ \tau : & \frac{1}{\sigma_\epsilon^2} E[\Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1}] + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2} E[\Delta u(\phi)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y] - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} E[\Delta u(\phi)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}] + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \\ \alpha_3 : & -\frac{1}{2\sigma_\epsilon^2} E[\Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi)]. \end{cases} \quad (3.1)$$

Similar to the process of deriving the M-estimator, we can first solve for $\bar{\beta}_M(\zeta)$ and $\bar{\sigma}_{\epsilon, M}^2(\zeta)$ as:

$$\bar{\beta}_M(\zeta) = (\Delta X' \Sigma^{-1} \Delta X)^{-1} \Delta X' \Sigma^{-1} [\mathbf{e}^{\alpha_1 \mathbf{W}_1} E(\Delta Y) - \mathbf{A}_2 E(\Delta Y_{-1})], \quad (3.2)$$

$$\bar{\sigma}_{\epsilon, M}^2(\zeta) = \frac{1}{n(T-1)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \Delta \bar{u}(\zeta)], \quad (3.3)$$

where $\Delta \bar{u}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1} - \Delta X \bar{\beta}_M(\zeta)$. By substituting them into the last four elements

of $\bar{S}^*(\theta)$, we get the population counterpart of the concentrated AQS function (2.18) as

$$\bar{S}^{*c}(\zeta) = \begin{cases} \tau : & \frac{1}{\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1}] + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1} \mathbf{W}_1), \\ \alpha_1 : & -\frac{1}{\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1 \Delta Y] - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \alpha_2 : & \frac{1}{\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2 \Delta Y_{-1}] + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \\ \alpha_3 : & -\frac{1}{2\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' (B^{-1} \otimes E_3) \Delta \bar{u}(\zeta)]. \end{cases} \quad (3.4)$$

Note ζ_0 is a zero of $\bar{S}^{*c}(\zeta)$. According to Theorem 5.9 of Vaart (2000), if $\hat{\zeta}_M$ is a zero of $S^{*c}(\zeta)$ and ζ_0 is a zero of $\bar{S}^{*c}(\zeta)$, then $\hat{\zeta}_M$ is a consistent estimator of ζ_0 if $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} \|S^{*c}(\zeta) - \bar{S}^{*c}(\zeta)\| \xrightarrow{p} 0$ and the following assumption holds.

Assumption 7. $\inf_{\zeta: d(\zeta, \zeta_0) \geq \nu} \|\bar{S}^{*c}(\zeta)\| > 0$ for every $\nu > 0$, where $d(\zeta, \zeta_0)$ is a measure of distance between ζ and ζ_0 .

Before we show $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} \|S^{*c}(\zeta) - \bar{S}^{*c}(\zeta)\| \xrightarrow{p} 0$, let's first define some convenient expressions. Let $\Delta \bar{u}^*(\zeta) = \Sigma^{-\frac{1}{2}} \Delta \bar{u}(\zeta)$, $\mathbf{e}^{\alpha_1} \mathbf{W}_1^* = \Sigma^{-\frac{1}{2}} \mathbf{e}^{\alpha_1} \mathbf{W}_1$, $\mathbf{A}_2^* = \Sigma^{-\frac{1}{2}} \mathbf{A}_2$, $\Delta Y^\dagger = \Delta Y - E(\Delta Y)$, $\Delta Y_{-1}^\dagger = \Delta Y_{-1} - E(\Delta Y_{-1})$, $P = \Sigma^{-\frac{1}{2}} \Delta X (\Delta X' \Sigma^{-1} \Delta X)^{-1} \Delta X' \Sigma^{-\frac{1}{2}}$ and $M = I_{n(T-1)} - P$. Then we have

$$\Delta \bar{u}^*(\zeta) = P(\mathbf{e}^{\alpha_1} \mathbf{W}_1^* \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger) + M(\mathbf{e}^{\alpha_1} \mathbf{W}_1^* \Delta Y - \mathbf{A}_2^* \Delta Y_{-1}). \quad (3.5)$$

The expression will be useful in deriving $\bar{\sigma}_{\epsilon, M}^2(\zeta)$ in (3.3) in the proof for Theorem 3.1 below.

Theorem 3.1. Suppose Assumptions 1-7 hold and further the following condition $0 < \underline{c}_{\Delta Y} \leq \inf_{\zeta \in \mathcal{Z}} \gamma_{\min}[\text{Var}(\mathbf{e}^{\alpha_1} \mathbf{W}_1^* \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})] \leq \sup_{\zeta \in \mathcal{Z}} \gamma_{\max}[\text{Var}(\mathbf{e}^{\alpha_1} \mathbf{W}_1^* \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})] \leq \bar{c}_{\Delta Y} < \infty$, we have $\hat{\theta}_M \xrightarrow{p} \theta_0$ as $n \rightarrow \infty$.

3.2 Asymptotic Distribution of the M-estimator

To derive the asymptotic distribution of $\hat{\theta}_M$, we apply the mean value theorem (MVT) to $S^*(\hat{\theta}_M) = 0$ at the true θ_0 to get $\sqrt{n(T-1)}(\hat{\theta}_M - \theta_0) = -(\frac{1}{n(T-1)} \frac{\partial S^*(\bar{\theta})}{\partial \theta'})^{-1} \frac{1}{\sqrt{n(T-1)}} S^*(\theta_0)$ for some $\bar{\theta}$ between θ_0 and $\hat{\theta}_M$ elementwise. Then we show that $\frac{1}{n(T-1)} \frac{\partial S^*(\bar{\theta})}{\partial \theta'}$ carries appropriate asymptotic properties and that $\frac{1}{\sqrt{n(T-1)}} S^*(\theta_0)$ is asymptotically normal. One thing to note here is that Δy_1 might not be exogenous and is unspecified, so the regular law of large numbers (LLN) and central limit theorem (CLT) for linear-quadratic forms from Kelejian and Prucha (2001) is not sufficient. Instead we use the extended LLN and CLT for bilinear-quadratic forms from Yang (2018) and Su and Yang (2015), which are listed in Lemmas A.3 and A.4 in the web appendix. The following lemma that expresses ΔY and ΔY_{-1} in a convenient format will be crucial in deriving the asymptotic distribution and later a consistent estimate of the VC matrix. Let $\text{blkdiag}(C_1, \dots, C_n)$ be the block diagonal matrix with diagonal $n \times n$ matrices C_1, \dots, C_n . Denote $A_{12,0} = e^{-\alpha_{10}} W_1 A_{20}$.

Lemma 3.1. *Under Assumptions 1, 3 and 5,*

$$\Delta Y = G\Delta \mathbf{y}_1 + \boldsymbol{\delta} + K\Delta \epsilon, \quad (3.6)$$

$$\Delta Y_{-1} = G_{-1}\Delta \mathbf{y}_1 + \boldsymbol{\delta}_{-1} + K_{-1}\Delta \epsilon, \quad (3.7)$$

where $\Delta \mathbf{y}_1 = I_{T-1} \otimes \Delta y_1$, $G = \text{blkdiag}[A_{12,0}, (A_{12,0})^2, \dots, (A_{12,0})^{T-1}]$, $G_{-1} = \text{blkdiag}[I_n, A_{12,0}, \dots, (A_{12,0})^{T-2}]$, $\boldsymbol{\delta} = J\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\Delta X\beta_0$, $\boldsymbol{\delta}_{-1} = J_{-1}\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\Delta X\beta_0$, $K = J\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\mathbf{e}^{-\alpha_{30}\mathbf{W}_3}$, $K_{-1} = J_{-1}\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\mathbf{e}^{-\alpha_{30}\mathbf{W}_3}$,

$$J = \begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_{12,0} & \ddots & \ddots & \ddots & \vdots \\ A_{12,0}^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ A_{12,0}^{T-2} & \dots & A_{12,0}^2 & A_{12,0} & I_n \end{pmatrix} \text{ and } J_{-1} = \begin{pmatrix} 0 & 0 & \dots & \dots & 0 \\ I_n & \ddots & \ddots & \ddots & \vdots \\ A_{12,0} & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ A_{12,0}^{T-3} & \dots & A_{12,0} & I_n & 0 \end{pmatrix}.$$

By substituting (3.6) and (3.7) into τ , α_1 and α_2 elements and substituting $\Delta u = \mathbf{e}^{-\alpha_{30}\mathbf{W}_3}\Delta \epsilon$ into the β , σ_ϵ^2 and α_3 elements of the AQS function (2.15) at the true value θ_0 , we get

$$S^*(\theta_0) = \begin{cases} \beta : & R'_1\Delta \epsilon, \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_{\epsilon_0}^2} + \Delta \epsilon' O_1 \Delta \epsilon, \\ \tau : & \Delta \epsilon' F_1 \Delta \mathbf{y}_1 + R'_2\Delta \epsilon + \Delta \epsilon' O_2 \Delta \epsilon + \text{tr}(\mathbf{D}_{-1,0}\mathbf{B}^{-1}\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}), \\ \alpha_1 : & -\Delta \epsilon' F_2 \Delta \mathbf{y}_1 - R'_3\Delta \epsilon - \Delta \epsilon' O_3 \Delta \epsilon - \text{tr}(\mathbf{D}_0\mathbf{B}^{-1}\mathbf{W}_1), \\ \alpha_2 : & \Delta \epsilon' F_3 \Delta \mathbf{y}_1 + R'_4\Delta \epsilon + \Delta \epsilon' O_4 \Delta \epsilon + \text{tr}(\mathbf{D}_{-1,0}\mathbf{B}^{-1}\mathbf{W}_{21,0}), \\ \alpha_3 : & \Delta \epsilon' O_5 \Delta \epsilon, \end{cases} \quad (3.8)$$

where $R_1 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\Delta X$, $R_2 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\boldsymbol{\delta}_{-1}$, $R_3 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\mathbf{W}_1\mathbf{e}^{\alpha_1\mathbf{W}_1}\boldsymbol{\delta}$, $R_4 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\mathbf{W}_2\mathbf{e}^{\alpha_2\mathbf{W}_2}\boldsymbol{\delta}_{-1}$, $O_1 = \frac{1}{2\sigma_{\epsilon_0}^4}(B^{-1} \otimes I_n)$, $O_2 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})K_{-1}$, $O_3 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\mathbf{W}_1\mathbf{e}^{\alpha_1\mathbf{W}_1}K$, $O_4 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\mathbf{W}_2\mathbf{e}^{\alpha_2\mathbf{W}_2}K_{-1}$, $O_5 = -\frac{1}{2\sigma_{\epsilon_0}^2}[B^{-1} \otimes (W_3 + W'_3)]$, $F_1 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})G_{-1}$, $F_2 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\mathbf{W}_1\mathbf{e}^{\alpha_1\mathbf{W}_1}G$ and $F_3 = \frac{1}{\sigma_{\epsilon_0}^2}(B^{-1} \otimes e^{\alpha_{30}W_3})\mathbf{W}_2\mathbf{e}^{\alpha_2\mathbf{W}_2}G_{-1}$.

Using $S^*(\theta_0)$ in (3.8), we can derive the expected score and the variance of the AQS function at the true value to get the asymptotic distribution of the M-estimator.

Theorem 3.2. *Suppose assumptions of Theorem 3.1 hold, we have, as $n \rightarrow \infty$,*

$$\sqrt{n(T-1)}(\hat{\theta}_M - \theta_0) \xrightarrow{d} N[0, \lim_{n \rightarrow \infty} \Psi^{*-1}(\theta_0)\Omega^*(\theta_0)\Psi^{*-1}(\theta_0)], \quad (3.9)$$

where $\Psi^*(\theta_0) = -\frac{1}{n(T-1)}\mathbf{E}\left[\frac{\partial S^*(\theta_0)}{\partial \theta'}\right]$ and $\Omega^*(\theta_0) = \frac{1}{n(T-1)}\text{Var}[S^*(\theta_0)]$ are assumed to exist and $\Psi^*(\theta_0)$ is assumed to be positive definite for sufficiently large n .

3.3 The OPMD Estimator of VC Matrix

In this section we derive a feasible estimator for the VC matrix $\Psi^{*-1}(\theta_0)\Omega^*(\theta_0)\Psi^{*-1}(\theta_0)$. Denote the Hessian matrix by $H^*(\theta) = \frac{\partial S^*(\theta)}{\partial \theta'}$. Then a consistent estimate of $\Psi^*(\theta_0)$ is easily derived by substituting the consistent M-estimates in, i.e., $\Psi^*(\hat{\theta}_M) = -\frac{1}{n(T-1)}H^*(\hat{\theta}_M)$. The detailed expression of $\Psi^*(\hat{\theta}_M)$ and the proof for the consistency of it are provided in the proof of Theorem 3.2 in the web appendix.

For $\Omega^*(\theta_0)$, however, this method does not work. This is because from (3.8) we know that τ , α_1 and α_2 elements of $S^*(\theta_0)$ contain the initial difference Δy_1 , which is unspecified. So we need to design a method that is free from the initial condition. Following Yang (2018), we propose an outer product of martingale difference (OPMD) method to consistently estimate $\Omega^*(\theta_0)$. The OPMD method first transforms $S^*(\theta_0)$ in (3.8) into a sum of vector martingale difference sequence (MDS). Specifically, we will write $R_r'\Delta\epsilon$, $\Delta\epsilon' O_r \Delta\epsilon - E(\Delta\epsilon' O_r \Delta\epsilon)$ and $\Delta\epsilon' F_r \Delta y_1 - E(\Delta\epsilon' F_r \Delta y_1)$ for suitable r as sums of MDS. The transformation enables us to write $\Omega^*(\theta_0)$, which is the variance of the outer product of the sum of elements of a vector MDS, as the expected outer product of the elements of MDS because MDS has mean zero and the terms in the sum are independent (See 3.14 below). Then the averaged sum of the outer product of elements of the estimated vector MDS can be computed to be a consistent estimate of $\Omega^*(\theta_0)$.

For a square matrix $A = A^u + A^l + A^d$, let A^u , A^l and A^d be the upper-triangular, lower-triangular and diagonal matrix of A respectively. In the following we suppress the subscripts in R_r , O_r and F_r for suitable r to simplify notations. Let R_t be the $n \times k$ submatrix or $n \times 1$ subvector of R , where R could be a $n(T-1) \times K$ matrix (R_1) or $n(T-1) \times 1$ vector (R_2 , R_3 and R_4). Let O_{ts} and F_{ts} be the $n \times n$ submatrix of $n(T-1) \times n(T-1)$ matrix O and F respectively. Note R_t , O_{ts} and F_{ts} are partitioned by $t, s = 2, \dots, T$. Define $F_t^+ = \sum_{s=2}^T F_{ts}$, for $t = 2, \dots, T$, $F_2^{++} = F_2^+ e^{-\alpha_{10}W_1} e^{\alpha_{30}W_3}$, $\Delta y_1^\diamond = e^{\alpha_3 W_3} e^{\alpha_{10}W_1} \Delta y_1$, $\Delta \xi = (F_2^{++u} + F_2^{++l}) \Delta y_1^\diamond$, $\Delta \eta_t = \sum_{s=2}^T (O_{st}^u + O_{st}^l) \Delta \epsilon_s$, $\Delta \epsilon_t^* = \sum_{t=2}^T O_{ts}^d \Delta \epsilon_s$ and $\Delta y_{1t}^* = F_t^+ \Delta y_1$. Let d_{it} be the it th diagonal element of $\mathbf{B}O$, where $\mathbf{B} = B \otimes I_n$ is defined after (2.14) in section 2.2. Let $\{\Pi_{n,i}\}$ be the increasing sequence of σ -fields generated by $\{\epsilon_{j1}, \dots, \epsilon_{jT}, j = 1, \dots, i\}, i = 1, \dots, n, n \geq 1$. Let $\Phi_{n,0}$ be the σ -field generated by $\{\epsilon_0, \Delta y_0\}$. Define $\Phi_{n,i} = \Phi_{n,0} \otimes \Pi_{n,i}$ as the σ -field on the Cartesian product generated by subset of the form $\phi_{n,0} \times \pi_{n,i}$, where $\phi_{n,0} \in \Phi_{n,0}$ and $\pi_{n,i} \in \Pi_{n,i}$. We show in the following lemma that $S^*(\theta_0)$ can be written as sums of vector MDS.

Lemma 3.2. *Suppose the assumptions of Lemma 3.1 hold, define $a_{1i} = \sum_{t=2}^T R_{it}' \Delta \epsilon_{it}$, $a_{2i} = \sum_{t=2}^T (\Delta \epsilon_{it} \Delta \eta_{it} + \Delta \epsilon_{it} \Delta \epsilon_{it}^* - \sigma_{\epsilon_0}^2 d_{it})$ and $a_{3i} = \Delta \epsilon_{2i} \Delta \xi_i + F_{2,ii}^{++} (\Delta \epsilon_{2i} \Delta y_{1i}^\diamond + \sigma_{\epsilon_0}^2) + \sum_{t=3}^T \Delta \epsilon_{it} \Delta y_{1it}^*$.*

Then

$$R' \Delta \epsilon = \sum_{i=1}^n a_{1i}, \quad (3.10)$$

$$\Delta \epsilon' O \Delta \epsilon - E(\Delta \epsilon' O \Delta \epsilon) = \sum_{i=1}^n a_{2i}, \quad (3.11)$$

$$\Delta \epsilon' F \Delta \mathbf{y}_1 - E(\Delta \epsilon' F \Delta \mathbf{y}_1) = \sum_{i=1}^n a_{3i}, \quad (3.12)$$

and $\{(a'_{1i}, a_{2i}, a_{3i})', \Phi_{n,i}\}_{i=1}^n$ forms a vector MDS.

Now using Lemma 3.2, for each R_r , define $a_{1ri} = \sum_{t=2}^T R'_{rit} \Delta \epsilon_{it}$ for $r = 1, 2, 3$ and 4; for each O_r , define $a_{2ri} = \sum_{t=2}^T (\Delta \epsilon_{it} \Delta \eta_{rit} + \Delta \epsilon_{it} \Delta \epsilon_{rit}^* - \sigma_{\epsilon 0}^2 d_{rit})$ for $r = 1, 2, 3, 4$ and 5; for each F_r , define $a_{3ri} = \sum_{t=2}^T [\Delta \epsilon_{2i} \Delta \xi_{ri} + F_{2,ri}^{++} (\Delta \epsilon_{2i} \Delta y_{1i}^\circ + \sigma_{\epsilon 0}^2) + \sum_{t=3}^T \Delta \epsilon_{it} \Delta y_{r1it}^*]$ for $r = 1, 2$ and 3. Then we can construct a vector $a_i = (a'_{11i}, a_{21i}, a_{31i} + a_{12i} + a_{22i}, -a_{32i} - a_{13i} - a_{23i}, a_{33i} + a_{14i} + a_{24i}, a_{25i})'$. Here for the first element $E(R'_1 \Delta \epsilon) = 0$. For the second element $E(\Delta \epsilon' O_1 \Delta \epsilon) = \frac{n(T-1)}{2\sigma_{\epsilon 0}^2}$. For the third element $E(\Delta \epsilon' F_1 \mathbf{y}_1 + R'_2 \Delta \epsilon + \Delta \epsilon' O_2 \Delta \epsilon) = -tr(\mathbf{D}_{-1,0} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_{10} \mathbf{W}_1})$. For the fourth element $E(\Delta \epsilon' F_2 \mathbf{y}_1 + R'_3 \Delta \epsilon + \Delta \epsilon' O_3 \Delta \epsilon) = -tr(\mathbf{D}_0 \mathbf{B}^{-1} \mathbf{W}_1)$. For the fifth element $E(\Delta \epsilon' F_3 \Delta \mathbf{y}_1 + R'_4 \Delta \epsilon + \Delta \epsilon' O_4 \Delta \epsilon) = -tr(\mathbf{D}_{-1,0} \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{-\alpha_{10} \mathbf{W}_1})$. For the sixth element $E(\Delta \epsilon' O_5 \Delta \epsilon) = 0$. So

$$S^*(\theta_0) = \sum_{i=1}^n a_i. \quad (3.13)$$

Since $E(a_i | \Phi_{n,i-1}) = 0$, $\{a_i, \Phi_{n,i}\}$ form a vector MDS. Together with (3.13), we thus have

$$\text{Var}[S^*(\theta_0)] = E \left[\left(\sum_{i=1}^n a_i \right) \left(\sum_{i=1}^n a_i \right)' \right] - \left[E \left(\sum_{i=1}^n a_i \right) \right] \left[E \left(\sum_{i=1}^n a_i \right) \right]' = \sum_{i=1}^n E(a_i a_i'). \quad (3.14)$$

A consistent estimator of $\Omega^*(\theta_0)$ is then given by $\hat{\Omega}^* = \frac{1}{n(T-1)} \sum_{i=1}^n \hat{a}_i \hat{a}_i'$, where \hat{a}_i is derived by replacing θ_0 in a_i by the M-estimator $\hat{\theta}_M$. The consistency of $\hat{\Omega}^*$ and thus of the VC matrix $\Psi^{*-1}(\hat{\theta}_M) \hat{\Omega}^* \Psi^{*-1}(\hat{\theta}_M)$ follow in the theorem below.

Theorem 3.3. *Under the assumptions of Theorem 3.1, as $n \rightarrow \infty$,*

$$\hat{\Omega}^* - \Omega^*(\theta_0) = \frac{1}{n(T-1)} \left[\sum_{i=1}^n \hat{a}_i \hat{a}_i' - \sum_{i=1}^n a_i a_i' \right] \xrightarrow{p} 0, \quad (3.15)$$

and thus

$$\Psi^{*-1}(\hat{\theta}_M) \hat{\Omega}^* \Psi^{*-1}(\hat{\theta}_M) - \Psi^{*-1}(\theta_0) \Omega^*(\theta_0) \Psi^{*-1}(\theta_0) \xrightarrow{p} 0. \quad (3.16)$$

The M-estimator and the OPMD estimator of the VC matrix subsume submodels that contain MESS in the dependent variable, the lagged dependent variable and/or the disturbances. Their

formats are derived in the web appendix. Different submodels are also explored in the Monte Carlo simulations in the next section.

4 Monte Carlo Simulation

To fully investigate the performance of the M-estimator and the OPMD-based standard error, we establish the following models in the Monte Carlo simulation.

$$\begin{aligned}
\text{MESDPS}(1,1,1): \quad & e^{\alpha_1 W_1} y_t = \tau y_{t-1} + e^{\alpha_2 W_2} y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z\gamma + \mu + u_t, \quad e^{\alpha_3 W_3} u_t = \epsilon_t, \\
\text{MESDPS}(1,1,0): \quad & e^{\alpha_1 W_1} y_t = \tau y_{t-1} + e^{\alpha_2 W_2} y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z\gamma + \mu + \epsilon_t, \\
\text{MESDPS}(1,0,1): \quad & e^{\alpha_1 W_1} y_t = (\tau + 1) y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z\gamma + \mu + u_t, \quad e^{\alpha_3 W_3} u_t = \epsilon_t, \\
\text{MESDPS}(0,1,1): \quad & y_t = \tau y_{t-1} + e^{\alpha_2 W_2} y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z\gamma + \mu + u_t, \quad e^{\alpha_3 W_3} u_t = \epsilon_t, \\
\text{MESDPS}(1,0,0): \quad & e^{\alpha_1 W_1} y_t = (\tau + 1) y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z\gamma + \mu + \epsilon_t, \\
\text{MESDPS}(0,1,0): \quad & y_t = \tau y_{t-1} + e^{\alpha_2 W_2} y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z\gamma + \mu + \epsilon_t.
\end{aligned}$$

The elements of X_t is drawn from $N(0, 4)$. Elements of Z and μ are drawn from $U(0, 1)$ and $N(0, 1)$ respectively. The spatial weight matrices are based on rook and queen contiguity. To this end, n spatial units are randomly allocated into $\sqrt{n} \times \sqrt{n}$ square lattice graph. In the rook contiguity case, $w_{ij} = 1$ if the j 'th observation is adjacent (left/right/above or below) to the i 'th observation on the graph. In the queen contiguity case, $w_{ij} = 1$ if the j 'th observation is adjacent to, or shares a border with the i 'th observation. The weights matrices are then row normalized. Three specifications of the disturbances ϵ_t are generated: (i) normal, (ii) normal mixture (10% $N(0, 5^2)$ and 90% $N(0, 1)$), (iii) standardized gamma (2, 1). Both (ii) and (iii) are standardized to have the same mean and variance with (i). Four sample sizes are considered, corresponding to $n = (49, 100)$ and $T = (3, 7)$.

The values of parameters are $\beta_0 = 10$, $\beta_1 = 1$, $\gamma = 1$ and $\sigma_\epsilon^2 = 1$. For ρ and α_r , $r = 1, 2, 3$, we select from a set of values $(-1.5, -1.1, -0.5, -0.1, 0, 0.5, 1.1, 1.5)$ in different submodels. Each experiment is replicated 1000 times. To compare the performance of the OPMD estimator, we report the empirical standard deviations (*sd*), OPMD-based standard errors (*se*), standard errors based on $\hat{\Omega}^{*-1}(\tilde{s}e)$ and standard errors based on $\Psi^{*-1}(\hat{\theta}_M)(\hat{s}e)$. Better performance is represented by closer approximation to *sd*. We only show the results from the full model MESDPS(1,1,1) in the main paper and put the rest of estimated results in the web appendix.

Table 4.1 presents results for the empirical means of the CQMLE and the M-estimator and Table 4.2 presents the empirical standard deviations and the standard errors for MESDPS(1,1,1). For the empirical means in Table 4.1, the M-estimator provides closer results to the true values of parameters than the CQMLE in most cases. It gives nearly unbiased results in many cases. For example, when $n = 49$, $T = 3$ and $(\beta_0, \sigma_{\epsilon_0}^2, \tau_0, \alpha_{10}, \alpha_{20}, \alpha_{30}) = (1, 1, 0.5, 1.1, 1.1, 1.1)$, the CQMLE are (0.9606, 0.8833, 0.4102, 1.0856, 1.1123, 1.1516) respectively, leading to the biases of $(-0.0394, -0.1167, -0.0898, -0.0144, 0.0123, 0.0516)$. On the other hand, the M-estimators are (1.0016, 0.9446, 0.5024, 1.1060, 1.1053, 1.1726) respectively, with the biases

(0.0016, -0.0554, 0.0024, 0.0060, 0.0053, 0.0726). The M-estimator thus provides better results than the CQMLE except for α_3 . For β, τ, α_1 and α_2 , the M-estimates are nearly unbiased. For α_3 , the bias of the M-estimator is relatively larger than that of the CQMLE. When n increases to 100, the biases of the CQMLE does not vanish for β, τ, α_1 . But when T grows bigger, the biases of the CQMLE are getting smaller. On the other hand, the M-estimators remain unbiased for all n and T , while the bias of α_3 also vanishes as n and T grows bigger. For example, when $n = 49$ and $T = 7$, the biases of the CQMLE reduce to (0.0002, -0.0176, -0.0034, 0.0034, 0.0051, 0.0125) and the biases of the M-estimator remains small at (0.0009, -0.0128, 0.0000, 0.0004, 0.0005, 0.0208). The rational choice of n and T means that the M-estimator is useful in many real-world applications. It brings nearly unbiased results for studies with short panels. For the standard errors in Table 4.2, the OPMD estimator has good performance, exhibiting much closer approximation to the empirical sd than the other two candidates in most cases. The OPMD estimator stays close to the empirical sd for most parameters under all n and T . Paying specific attention to τ under disturbance that follows gamma distribution, we find that the OPMD estimator gives especially better performance than the other two candidates of se . For example, when $(\beta, \sigma_\epsilon^2, \tau, \alpha_1, \alpha_2, \alpha_3) = (1, 1, 0.5, 1.1, 1.1, 1.1)$ and $n = 49, T = 3$, under the gamma disturbances, sd for σ_ϵ^2 is 0.218. The OPMD based $se = 0.196$. The other two candidates have estimates $\tilde{se} = 0.139$ and $\hat{se} = 0.149$. We can see that se is much closer to sd than the other two candidates. This highlights the importance of conducting inference using the OPMD estimator when the normality of the disturbance is in doubt. Overall the M-estimator and the OPMD-based estimator for the standard error provide unbiased estimates and exhibit good finite sample properties.

The estimation results for other submodels are provided in the web appendix. The main conclusion does not change. The CQMLE is biased while the M-estimator provides nearly unbiased estimates in most cases, regardless of n and T . The OPMD estimator for the VC matrix provides closer approximation to sd in most cases than the other two candidates, especially when the disturbance is non-normal.

Table 4.1: Empirical mean of CQMLE and M-estimator, MESDPS(1,1,1)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9606	1.0016	0.9629	1.0013	1.0002	1.0009	0.9993	1.0001
	1	0.8833	0.9446	0.9214	0.9812	0.9824	0.9872	0.9858	0.9903
	0.5	0.4102	0.5024	0.4136	0.5028	0.4966	0.5000	0.4967	0.5000
	1.1	1.0856	1.1060	1.0828	1.1013	1.1034	1.1004	1.1032	1.1001
	1.1	1.1123	1.1053	1.1085	1.1001	1.1051	1.1005	1.1048	1.1002
	1.1	1.1516	1.1726	1.1069	1.1301	1.1125	1.1208	1.1084	1.1168
2	1	0.9602	1.0030	0.9625	1.0015	1.0000	1.0009	0.9994	1.0002
	1	0.8958	0.9605	0.9165	0.9754	0.9778	0.9826	0.9856	0.9900
	0.5	0.4124	0.5069	0.4133	0.5013	0.4968	0.5001	0.4968	0.5000
	1.1	1.0839	1.1075	1.0838	1.1039	1.1031	1.1001	1.1032	1.1001
	1.1	1.1095	1.1054	1.1098	1.1037	1.1046	1.1001	1.1047	1.1002
	1.1	1.1531	1.1749	1.1062	1.1254	1.1129	1.1210	1.1018	1.1099
3	1	0.9629	1.0047	0.9628	1.0009	0.9976	0.9984	1.0002	1.0010
	1	0.8934	0.9593	0.9131	0.9720	0.9783	0.9831	0.9840	0.9884
	0.5	0.4132	0.5075	0.4137	0.5015	0.4967	0.5001	0.4967	0.5000
	1.1	1.0855	1.1066	1.0841	1.1023	1.1033	1.1003	1.1033	1.1001
	1.1	1.1112	1.1044	1.1100	1.1017	1.1049	1.1004	1.1049	1.1002
	1.1	1.1514	1.1752	1.1047	1.1255	1.1149	1.1230	1.1054	1.1135
1	1	0.9383	1.0016	0.9379	1.0005	1.0006	1.0004	1.0018	1.0012
	1	0.8768	0.9537	0.9039	0.9779	0.9725	0.9856	0.9821	0.9943
	0	-0.1288	0.0062	-0.1289	0.0022	-0.0203	0.0017	-0.0207	0.0005
	1.1	1.0445	1.1037	1.0424	1.1013	1.1155	1.0999	1.1176	1.1011
	1.1	1.0890	1.1017	1.0869	1.1007	1.1220	1.0992	1.1243	1.1009
	1.1	1.1804	1.1768	1.1490	1.1408	1.0971	1.1238	1.0824	1.1095
2	1	0.9378	1.0008	0.9398	1.0016	0.9998	0.9998	1.0015	1.0009
	1	0.8801	0.9566	0.9084	0.9822	0.9710	0.9838	0.9785	0.9907
	0	-0.1286	0.0058	-0.1295	0.0005	-0.0211	0.0006	-0.0209	0.0004
	1.1	1.0398	1.0979	1.0473	1.1049	1.1171	1.1017	1.1178	1.1010
	1.1	1.0844	1.0960	1.0918	1.1047	1.1238	1.1014	1.1245	1.1008
	1.1	1.1786	1.1742	1.1351	1.1284	1.0965	1.1218	1.0818	1.1089
3	1	0.9396	1.0039	0.9377	0.9994	1.0013	1.0014	1.0001	0.9996
	1	0.8749	0.9531	0.9052	0.9798	0.9672	0.9799	0.9760	0.9884
	0	-0.1299	0.0054	-0.1270	0.0035	-0.0209	0.0006	-0.0204	0.0011
	1.1	1.0446	1.1050	1.0433	1.1007	1.1167	1.1014	1.1170	1.1004
	1.1	1.0895	1.1034	1.0872	1.0996	1.1234	1.1011	1.1236	1.1000
	1.1	1.1750	1.1704	1.1442	1.1373	1.0906	1.1158	1.0807	1.1079
1	1	0.9360	0.9979	0.9392	1.0001	0.9839	1.0003	0.9840	1.0004
	1	0.8965	0.9568	0.9269	0.9868	0.9702	0.9845	0.9767	0.9909
	-0.5	-0.6370	-0.4984	-0.6328	-0.4961	-0.5502	-0.4997	-0.5506	-0.5002
	1.1	1.0286	1.1000	1.0337	1.1031	1.0815	1.1013	1.0805	1.1000
	1.1	1.0893	1.1006	1.0913	1.1019	1.1016	1.1012	1.1009	1.1002
	1.1	1.1984	1.1643	1.1591	1.1287	1.1277	1.1169	1.1235	1.1131
2	1	0.9392	1.0009	0.9409	1.0013	0.9826	0.9994	0.9831	0.9994
	1	0.8995	0.9604	0.9209	0.9798	0.9666	0.9808	0.9778	0.9919
	-0.5	-0.6339	-0.4945	-0.6354	-0.4998	-0.5509	-0.5004	-0.5510	-0.5007
	1.1	1.0290	1.1001	1.0333	1.1024	1.0796	1.0996	1.0802	1.0997
	1.1	1.0882	1.0990	1.0916	1.1022	1.1002	1.0998	1.1007	1.1001
	1.1	1.2135	1.1844	1.1568	1.1275	1.1332	1.1226	1.1175	1.1074
3	1	0.9357	0.9969	0.9400	1.0001	0.9841	1.0010	0.9851	1.0013
	1	0.8995	0.9607	0.9172	0.9759	0.9717	0.9862	0.9764	0.9905
	-0.5	-0.6364	-0.4982	-0.6329	-0.4985	-0.5509	-0.5001	-0.5489	-0.4988
	1.1	1.0241	1.0944	1.0302	1.0985	1.0807	1.1009	1.0815	1.1007
	1.1	1.0856	1.0957	1.0883	1.0986	1.1012	1.1010	1.1010	1.1003
	1.1	1.2181	1.1889	1.1647	1.1360	1.1320	1.1209	1.1202	1.1102

Note: Disturbance 1=normal, 2=normal-mixture and 3=gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_1, \alpha_2, \alpha_3)'$. W_1 , W_2 and W_3 are generated by queen, rook and queen contiguity respectively.

Table 4.2: Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,1,1)

dis	par	<i>sd</i>	se	\tilde{se}	\hat{se}	<i>sd</i>	se	\tilde{se}	\hat{se}	<i>sd</i>	se	\tilde{se}	\hat{se}	<i>sd</i>	se	\tilde{se}	\hat{se}
n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7					
1	1	.054	.054	.057	.052	.037	.037	.038	.037	.024	.023	.026	.024	.017	.017	.017	.017
	1	.152	.148	.163	.146	.105	.107	.112	.106	.081	.089	.090	.085	.058	.062	.060	.059
	0.5	.049	.049	.047	.045	.032	.034	.030	.031	.004	.004	.004	.004	.003	.003	.002	.003
	1.1	.072	.082	.074	.073	.050	.057	.050	.052	.006	.006	.005	.005	.004	.004	.004	.004
	1.1	.088	.104	.092	.092	.062	.072	.061	.065	.008	.009	.007	.007	.005	.006	.005	.005
	1.1	.224	.226	.231	.214	.149	.154	.153	.149	.116	.113	.120	.111	.080	.080	.082	.079
2	1	.057	.054	.058	.053	.037	.037	.038	.037	.025	.024	.026	.024	.017	.017	.017	.017
	1	.154	.150	.168	.149	.109	.107	.111	.105	.083	.087	.090	.084	.057	.062	.060	.059
	0.5	.049	.049	.047	.045	.032	.033	.030	.031	.004	.004	.004	.004	.003	.003	.002	.002
	1.1	.077	.083	.074	.074	.049	.057	.049	.051	.005	.006	.005	.005	.004	.004	.004	.004
	1.1	.094	.104	.092	.092	.061	.072	.061	.064	.007	.008	.007	.007	.005	.006	.005	.005
	1.1	.228	.227	.229	.214	.151	.153	.153	.148	.112	.111	.121	.111	.080	.079	.082	.079
3	1	.057	.054	.060	.053	.038	.038	.039	.036	.024	.023	.027	.024	.017	.017	.018	.017
	1	.218	.196	.139	.149	.144	.141	.088	.105	.123	.126	.065	.084	.085	.090	.042	.059
	0.5	.053	.052	.049	.046	.034	.034	.031	.031	.004	.004	.004	.004	.003	.003	.002	.003
	1.1	.074	.085	.077	.074	.051	.057	.051	.051	.005	.006	.006	.005	.004	.004	.004	.004
	1.1	.089	.107	.096	.093	.064	.072	.063	.064	.007	.008	.008	.007	.005	.006	.005	.005
	1.1	.225	.227	.240	.215	.149	.153	.157	.148	.111	.111	.124	.111	.078	.078	.084	.079
1	1	.062	.060	.064	.059	.042	.042	.042	.041	.026	.026	.028	.026	.019	.019	.019	.018
	1	.162	.148	.168	.149	.109	.106	.113	.106	.083	.084	.091	.083	.059	.059	.061	.059
	0	.067	.059	.059	.056	.045	.040	.038	.038	.014	.016	.014	.014	.010	.011	.009	.010
	1.1	.091	.093	.090	.087	.058	.065	.059	.061	.028	.032	.026	.027	.020	.023	.018	.019
	1.1	.090	.096	.092	.089	.057	.066	.060	.062	.031	.037	.030	.031	.022	.026	.020	.022
	1.1	.238	.229	.235	.218	.153	.155	.156	.151	.117	.118	.124	.115	.081	.084	.084	.082
2	1	.061	.060	.064	.059	.043	.042	.042	.041	.026	.027	.028	.026	.018	.019	.018	.018
	1	.159	.147	.170	.149	.114	.106	.113	.106	.083	.083	.091	.083	.058	.059	.061	.059
	0	.066	.058	.059	.055	.044	.040	.038	.038	.014	.016	.014	.014	.010	.011	.009	.010
	1.1	.088	.093	.090	.087	.060	.066	.060	.061	.027	.032	.026	.028	.019	.023	.018	.019
	1.1	.087	.096	.092	.089	.060	.067	.061	.062	.031	.037	.030	.031	.021	.026	.020	.022
	1.1	.233	.227	.236	.218	.155	.156	.155	.151	.118	.119	.123	.115	.081	.083	.084	.082
3	1	.064	.060	.067	.059	.044	.042	.043	.041	.027	.027	.028	.026	.018	.019	.019	.018
	1	.203	.188	.143	.149	.152	.140	.091	.106	.116	.118	.066	.083	.085	.087	.043	.058
	0	.068	.060	.061	.056	.046	.042	.039	.038	.014	.016	.014	.014	.010	.011	.009	.010
	1.1	.088	.094	.094	.087	.063	.065	.062	.061	.026	.033	.027	.028	.019	.023	.018	.019
	1.1	.088	.097	.096	.089	.063	.067	.062	.062	.029	.037	.031	.031	.022	.026	.021	.022
	1.1	.227	.226	.248	.219	.163	.153	.162	.151	.120	.117	.128	.115	.083	.083	.085	.082
1	1	.064	.063	.067	.062	.045	.044	.044	.043	.033	.032	.034	.032	.022	.022	.023	.022
	1	.152	.147	.167	.148	.106	.107	.113	.107	.085	.082	.091	.083	.056	.058	.061	.058
	-0.5	.070	.062	.068	.061	.048	.043	.045	.043	.027	.026	.028	.026	.019	.018	.019	.018
	1.1	.095	.100	.099	.094	.066	.069	.065	.065	.048	.048	.049	.046	.033	.034	.033	.033
	1.1	.075	.080	.080	.076	.053	.056	.053	.053	.041	.041	.042	.040	.028	.029	.028	.028
	1.1	.231	.229	.240	.221	.161	.158	.158	.153	.121	.121	.130	.120	.084	.086	.088	.085
2	1	.063	.063	.067	.061	.043	.044	.044	.043	.033	.032	.034	.032	.022	.022	.023	.022
	1	.153	.147	.168	.149	.108	.106	.112	.106	.082	.082	.091	.083	.057	.059	.061	.058
	-0.5	.070	.062	.068	.061	.047	.043	.044	.042	.028	.025	.029	.026	.019	.018	.019	.018
	1.1	.093	.100	.099	.094	.063	.068	.065	.065	.048	.048	.049	.046	.033	.034	.033	.033
	1.1	.075	.081	.080	.076	.051	.055	.052	.052	.041	.041	.042	.040	.028	.029	.028	.028
	1.1	.235	.228	.239	.220	.156	.157	.158	.153	.125	.121	.130	.120	.085	.086	.088	.085
3	1	.064	.062	.070	.061	.044	.044	.045	.043	.032	.032	.035	.032	.023	.022	.023	.022
	1	.209	.192	.141	.149	.151	.140	.090	.105	.129	.118	.067	.083	.086	.086	.043	.058
	-0.5	.072	.063	.070	.061	.049	.043	.045	.042	.029	.025	.029	.026	.019	.018	.019	.018
	1.1	.097	.100	.104	.095	.063	.068	.067	.065	.047	.048	.050	.046	.032	.034	.033	.033
	1.1	.078	.081	.084	.076	.050	.055	.054	.052	.040	.041	.043	.040	.027	.029	.029	.028
	1.1	.236	.227	.252	.221	.151	.155	.163	.153	.121	.119	.134	.120	.085	.085	.090	.085

Note: Same configuration as Table 4.1. Here *sd* is empirical standard deviation, **se** is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

5 Empirical Application to US Outward FDI

In this section we apply the M-estimation method to US foreign direct investment to explore its usefulness. Recent literature explore third market as a determinant of bilateral FDI. Coughlin and Segev (1999) is the first paper to study FDI using spatial econometrics. They find a positive spatial lag (SL) and spatial error (SE) effect for China’s inward FDI for neighboring regions. Baltagi et al. (2007) use the industries and countries FDI data to explore the knowledge-capital model of US outbound FDI using generalized moments (GM) estimators. They find that the spatial coefficients are significant while evidence of various modes of FDI emerges. Blonigen et al. (2007) study the US outward FDI by including spatial lag in the model and find that the estimates of the traditional determinants of FDI are robust to the inclusion of spatial lag. They find a positive and significant spatial lag using the whole sample which suggests complex-vertical motivations for MNE activity. Garretsen and Peeters (2009) apply a spatial lag model (SLM) and spatial error model (SEM) for Dutch FDI and find positive and significant spatial effects in both. Debarsy et al. (2015) utilize a cross-sectional MESS model on Belgium’s outward FDI and find evidence of pure vertical FDI. They argue that this is because Belgium has high production costs such as labor. In our study, the focus will be placed on the spatial coefficients since the dynamic nature of the model changes the situation in a significant way.

We explore the US outward FDI using the MESDPS. Our balanced data contains 40 countries from both developed and developing world over 7 years (2011-2017). The list of countries are listed in Table 5.1.

Table 5.1: List of Countries

Argentina	Australia	Belgium	Brazil	Canada	Chile
China	Cyprus	Czech	Denmark	Estonia	Finland
France	Germany	Hungary	India	Ireland	Italy
Japan	South Korea	Luxembourg	Malaysia	Mexico	Netherland
New Zealand	Norway	Poland	Portugal	Romania	Russia
Singapore	South Africa	Spain	Sweden	Switzerland	Thailand
Turkey	Ukraine	United Kingdom	Vietnam		

The model to be estimated is a dynamic panel framework,

$$e^{\alpha_1 W_1} LFDI_t = \tau LFDI_{t-1} + e^{\alpha_2 W_2} LFDI_{t-1} + \beta_1 LGDP_t + \beta_2 LPOP_t + \beta_3 LRISK_t + \beta_4 MP_t + \phi t_l_n + u_{it}, \quad e^{\alpha_3 W_3} u_t = \epsilon_t. \quad (5.1)$$

Here $LFDI_t$ is the log of stock of outward FDI from US to host countries in year t . FDI are US outward positions (stocks) from International Direct Investment Statistics. The independent variables are a set of host country variables which includes log of GDP ($LGDP$), log of population ($LPOP$), log of an investment risk variable ($LRISK$), which is found to be important in the International Finance literature, and a surrounding-market potential variable (MP). We follow

Garretsen and Peeters (2009) and compute it as the distance-weighted sums of other countries' GDP in the sample where the distance is the bilateral distance between capitals from Mayer and Zignago (2011). GDP and population data are extracted from the World Bank's World Development Indicators (WDI). Risk is the inverse of an investment profile index from International Country Risk Guide. We also add a time trend $\phi t l_n$ to capture the time-series variation. Table 5.2 contains the summary statistics of these variables. The spatial weight matrix is an inverse arc-distance between capitals of host countries. Similar to Blonigen et al. (2007), we multiply the weights by the shortest distance between capitals (80.98 km between capitals of Estonia and Finland). The same spatial weight matrix will be applied to all spatial processes.

Table 5.2: Descriptive Statistics

Variable	Mean	Std	Min	Max
Log of FDI (\$millions)	10.09	1.97	4.09	13.75
Log of host country GDP (2010 constant dollars)	27.02	1.34	23.77	29.95
Log of host country population	17.05	1.64	13.16	21.05
Log of investment risk	-2.22	0.2	-2.48	-1.73
Surrounding market potential	25.66	2.07	22.5	27.16

As discussed in section 2.2, there exists a relation between the spatial coefficients in STLE model and MESDPS⁴, i.e., $\lambda_1 = 1 - e^{\alpha_1}$, $\rho = \tau + 1$ and $\lambda_2 = e^{\alpha_2} - 1$. The M-estimation results of corresponding models in Yang (2018) are thus also reported to highlight the relation in interpretations of the two methods.

Table 5.3 summarizes the estimation results. We run two specifications: the STLE model and MESDPS(1,1,1). The STLE models is based on Yang (2018). Both specifications contain the CQMLE and the M-estimator.

We make three important observations. First we would like to emphasize the fact that the results capture the expected relation between spatial coefficients. In Table 5.3, the coefficient estimate for dynamic effects of the CQMLE for the STLE model is 0.4756 and for MESDPS(1,1,1) is -0.5619. For the M-estimator they are 0.7038 and -0.2911 respectively. They satisfy the relation $\rho = \tau + 1$. For W_1 , which represents the spatial lag in the STLE model and MESS in MESDPS(1,1,1) for the dependent variables, we find that the signs of the CQMLE of coefficients are positive and negative respectively. For the CQMLE, the STLE model has a coefficient of 0.3887 and MESDPS(1,1,1) has a coefficient of -0.4772. On the other hand, for the M-estimators the coefficient estimates are -0.1818 and 0.2569 respectively. These are in line with the relation $\lambda_1 = 1 - e^{\alpha_1}$. For W_2 , we find that the coefficient estimates have the same signs. The CQMLE are -0.2388 for the STLE model and -0.2116 for MESDPS(1,1,1). The M-estimator has estimates 0.0574 for the STLE model and 0.1489 for the MESDPS(1,1,1). Combined with their magnitudes, the expected relation $\lambda_2 = e^{\alpha_2} - 1$

⁴STLE specification is the comprehensive model which contains the spatial lag effect, dynamic effect, space-time effect and spatial error effect. It corresponds to our MESDPS(1,1,1). See section 2.2 for the detailed model specification.

holds. For W_3 , the CQMLE for the STLE model is -0.7770 and for MESDPS(1,1,1) is 0.7255^5 . For the M-estimator they are -0.1237 and -0.0191 respectively. Thus the results confirm our proposed relation between the coefficient estimates in the theory.

Table 5.3: Estimation results of US outbound log(FDI) for STLE and MESDPS(1,1,1)

	STLE		MESDPS(1,1,1)	
	CQMLE	M-Estimator	CQMLE	M-Estimator
<i>LGDP</i>	0.6958	0.2545 (0.328)	0.6253	0.2220 (0.265)
<i>LPOP</i>	1.5881	1.3188 (0.987)	1.9200	1.2389 (0.965)
<i>RISK</i>	-0.0720	-0.1083 (0.113)	-0.0516	-0.0933 (0.110)
<i>MP</i>	0.5506	-0.7573 (2.485)	0.3350	-0.9495 (2.769)
<i>TREND</i>	-0.0310	0.0045 (0.054)	-0.0262	0.009 (0.059)
<i>LFDI_{t-1}</i>	0.4756	0.7038*** (0.139)	-0.5619	-0.2911*** (0.076)
W_1	0.3887	-0.1818*** (0.071)	-0.4772	0.2569** (0.131)
W_2	-0.2388	0.0574 (0.047)	-0.2116	0.1489 (0.099)
W_3	-0.7770	-0.1237*** (0.044)	0.7255	-0.0191 (0.120)

Note: OPMD standard errors are in parenthesis. W_1 , W_2 and W_3 are spatial weight matrices in terms of SAR in the STLE model and MESS in MESDPS(1,1,1).

* Correspond to significance at 10%.

** Correspond to significance at 5%.

*** Correspond to significance at 1%.

The second observation is that the inclusion of dynamic effects makes the coefficients of host country variables insignificant compared with the panel data case. In Blonigen et al. (2007) where the data from 1983 to 1998 are used, the signs for *LGDP* is positive and for *LPOP* and *RISK* are negative (see table 3 on p1315). The estimates are mostly significant in their study except MP variable. In our study, however, adding in a lagged dependent variable changes the model estimates extensively. Although the estimates (except *LPOP*) have the same signs with those in Blonigen et al. (2007), they are no longer significant. The sign for spatial lag of *LFDI* stays significant but becomes negative. The significance of coefficient estimate for *LFDI_{t-1}* tells us that the dynamic effect is a relatively important variable in explaining the variation in *LFDI*. The spatial terms are

⁵As kindly pointed out by a referee, note here $0.7255 > \ln 2$, which implies the corresponding STLE coefficient is $1 - e^{0.7255} = -1.0658$. This is one of the advantages of the MESDPS compared with the STLE model: the parameter space of the MESS coefficient for the disturbance term is unrestricted.

also significant in most cases.

The third observation is the difference between of the CQMLE and the M-estimator. While in most cases they have same signs in respective groups, their magnitudes differ. For example, the estimate for *LGDP* is 0.6958 for the CQMLE and 0.2545 for the M-estimator in the STLE model. This tells us that the M-estimator might correctly captures the impact of *LGDP* on *LFDI*. Although we do not have a reference in this field to examine its validity, the difference do tell us that we need to be careful in using the CQMLE which provide biased results.

To investigate the impact measures, we compute the average direct impacts for the STLE model and MESDPS(1,1,1) and summarize them in Table 5.4. We can see that the CQMLE has similar average direct impacts for the STLE model and MESDPS(1,1,1) model for the 4 independent variables. This is also the case for the M-estimator. Their OPMD ses are also similar, which shows that the M-estimation method works for both MESDPS and the STLE model and provides similar impact measures.

Table 5.4: Average direct impacts for STLE and MESDPS(1,1,1)

	STLE			MESDPS(1,1,1)		
	CQMLE	M-Est	OPMD se	CQMLE	M-Est	OPMD se
LGDP	1.0296	0.2371	0.3062	1.0043	0.2010	0.2321
LPOP	2.4084	1.1965	0.7572	2.5437	1.0629	0.7819
RISK	-0.0378	-0.0989	0.0965	-0.0723	-0.0806	0.0901
MP	-1.5727	-0.4808	0.4980	-1.4253	-0.4112	0.4302

6 Conclusion

In this paper we propose a consistent M-estimator to estimate the matrix exponential spatial dynamic panel specification (MESDPS) with fixed effects in short panels. To the best of our knowledge, this is the first paper to tackle this problem. The comprehensive model includes matrix exponential in the dependent variable, the lagged dependent variable and the disturbances. We also propose an OPMD estimator for the VC matrix. Valid inference can be based on the standard error derived from the OPMD estimator, especially when the normality of the disturbance is in doubt. The method can be applied to submodels and works well. The method is free from the initial condition specification and simple to use. It provides scholars a reliable way to conduct empirical research. Future research might focus on modifying the type of disturbance in the model to heteroskedastic.

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Web Appendix for Unified M-estimation of Matrix Exponential Spatial Dynamic Panel Specification

Ye Yang*

This web appendix provides the following: (A) some useful lemmas that will be used in the proofs of theorems below, (B) proofs of Lemmas 2.1, 3.1 and 3.2 in the main paper, (C) proofs of Theorems 3.1-3.3 in the main paper, (D) estimation of submodels MESDPS(1,0,0), MESDPS(0,1,0), MESDPS(1,1,0), MESDPS(1,0,1) and MESDPS(0,1,1), and (E) some more comprehensive Monte Carlo simulation results.

A Some Useful Lemmas

In the following, Lemma A.1 can be found in Kelejian and Prucha (1999). Lemma A.2 can be found in, e.g., Debarsy et al. (2015) and Lee (2004). Lemma A.3 can be found in, e.g., Yang (2015) and Yang (2018). Lemma A.4, a central limit theorem for bilinear quadratic forms, can be found in Yang (2018). Lemma A.5 can be found in Debarsy et al. (2015). The proofs are contained in these papers and thus are omitted. Let UB stand for “bounded in both row and column sum norms”.

Lemma A.1. *Suppose that $n \times n$ matrices $\{A_n\}$ and $\{B_n\}$ are UB and C_n is a sequence of conformable matrices whose elements are uniformly $O(g_n^{-1})$. Then*

- (i) *the sequence $\{A_n B_n\}$ are UB,*
- (ii) *the elements of A_n are uniformly bounded and $\text{tr}(A_n) = O(n)$, and*
- (iii) *the elements of $A_n C_n$ and $C_n A_n$ are uniformly $O(g_n^{-1})$.*

Lemma A.2. *Suppose that elements of $n \times k$ matrix X_n are uniformly bounded and $\lim_{n \rightarrow \infty} n^{-1} X_n' X_n$ exists and is nonsingular, then $P_n = X_n (X_n' X_n)^{-1} X_n'$ and $M_n = I_n - P_n$ are UB.*

Lemma A.3. *Suppose that $n \times n$ matrices $\{A_n\}$ are uniformly bounded in either row or column sum norm and the elements $a_{n,ij}$ of A_n are $O(g_n^{-1})$ uniformly in all i and j . Also suppose that ϵ_n is an $n \times 1$ random vector of i.i.d. elements with mean zero, variance σ^2 and finite 4th moment and b_n is an $n \times 1$ vector with constant elements of uniform order $O(g_n^{-1/2})$. Then (i) $E(\epsilon_n' A_n \epsilon_n) =$*

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$O(\frac{n}{g_n})$; (ii) $\text{Var}(\epsilon'_n A_n \epsilon_n) = O(\frac{n}{g_n})$; (iii) $\text{Var}(\epsilon'_n A_n \epsilon_n + b'_n \epsilon_n) = O(\frac{n}{g_n})$; (iv) $\epsilon'_n A_n \epsilon_n = O_p(\frac{n}{g_n})$; (v) $\epsilon'_n A_n \epsilon_n - \mathbb{E}(\epsilon'_n A_n \epsilon_n) = O_p[(\frac{n}{g_n})^{1/2}]$; (vi) $\epsilon'_n A_n b_n = O_p[(\frac{n}{g_n})^{1/2}]$; (vii) The results in (iii) and (vi) remain valid if b_n is an $n \times 1$ random vector independent of ϵ_n such that $\{\mathbb{E}(b_n^2)\}$ are of uniform order $O(g_n^{-1})$.

Lemma A.4. Suppose that $n \times n$ matrices $\{A_n\}$ is UB with elements of uniform order $O(g_n^{-1})$. Suppose $\{\epsilon_n\}$ is a $n \times 1$ random vector of i.i.d. elements with mean zero, variance σ_ϵ^2 and finite $(4+2\nu_0)$ th moment for some $\nu_0 > 0$. Suppose an $n \times 1$ random vector $b_n = \{b_{ni}\}$ is independent of ϵ_n and satisfies the following conditions (i) $\{\mathbb{E}(b_{ni}^2)\}$ are of uniform order $O(g_n^{-1})$, (ii) $\sup_i \mathbb{E}|b_{ni}|^{2+\nu_0} < \infty$, (iii) $\frac{g_n}{n} \sum_{i=1}^n [A_{n,ii}(b_{ni} - \mathbb{E}(b_{ni}))] = o_p(1)$ where $\{A_{n,ii}\}$ are the diagonal elements of A_n , (iv) $\frac{g_n}{n} \sum_{i=1}^n [b_{ni}^2 - \mathbb{E}(b_{ni}^2)] = o_p(1)$. Define the bilinear-quadratic form as $C_n = b'_n \epsilon_n + \epsilon'_n A_n \epsilon_n - \sigma_\epsilon^2 \text{tr}(A_n)$ with variance $\sigma_{C_n}^2$. If $\lim_{n \rightarrow \infty} g_n^{1+2/\nu_0}/n = 0$ and $\{\frac{g_n}{n} \sigma_{C_n}^2\}$ are bounded away from zero, then $C_n/\sigma_{C_n} \xrightarrow{d} N(0, 1)$.

Lemma A.5. Let A be any $n(T-1) \times n(T-1)$ matrix that is UB and $a = o_p(1)$. Then $\|e^{aA} - I_n\|_\infty = o_p(1)$ and $\|e^{aA} - I_n\|_1 = o_p(1)$.

Lemma A.6. Let A_n and B_n be any two $n \times n$ matrices that are UB. Also $a_n = o_p(1)$ and $b_n = o_p(1)$. Then $\|e^{a_n A'_n} e^{b_n B_n} - I_n\|_\infty = o_p(1)$ and $\|e^{a_n A'_n} e^{b_n B_n} - I_n\|_1 = o_p(1)$.

B Proofs of Lemmas A.6, 2.1, 3.1 and 3.2

Proof of Lemma A.6. We have

$$\begin{aligned} \|e^{a_n A'_n} e^{b_n B_n} - I_n\|_\infty &= \left\| \sum_{i=1}^{\infty} \frac{a_n^i A_n'^i}{i!} + \sum_{j=1}^{\infty} \frac{b_n^j B_n^j}{j!} + \left(\sum_{i=1}^{\infty} \frac{a_n^i A_n'^i}{i!} \right) \left(\sum_{j=1}^{\infty} \frac{b_n^j B_n^j}{j!} \right) \right\|_\infty \\ &\leq \sum_{i=1}^{\infty} \frac{|a_n|^i \|A_n'\|_\infty}{i!} + \sum_{j=1}^{\infty} \frac{|b_n|^j \|B_n\|_\infty}{j!} + \sum_{i=1}^{\infty} \frac{|a_n|^i \|A_n'\|_\infty}{i!} \sum_{j=1}^{\infty} \frac{|b_n|^j \|B_n\|_\infty}{j!} \\ &\leq e^{|a_n| \|A_n'\|_\infty} - 1 + e^{|b_n| \|B_n\|_\infty} - 1 + (e^{|a_n| \|A_n'\|_\infty} - 1)(e^{|b_n| \|B_n\|_\infty} - 1) \\ &= o_p(1). \end{aligned}$$

Similarly $\|e^{a_n A'_n} e^{b_n B_n} - I_n\|_1 = o_p(1)$.

Proof of Lemma 2.1. First note the reduced form of ΔY is given by $\Delta Y = \mathbf{e}^{-\alpha_{10} \mathbf{W}_1} \mathbf{A}_{20} \Delta Y_{-1}$

$+ \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \Delta X \beta_0 + \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \mathbf{e}^{-\alpha_{30}\mathbf{W}_3} \Delta \epsilon$. For each element of ΔY , we have:

- (1) $E(\Delta y_{t-1} \Delta \epsilon'_t)$
 $= E[(e^{-\alpha_{10}W_1} A_{20} \Delta y_{t-2} + e^{-\alpha_{10}W_1} \Delta X_{t-1} \beta_0 + e^{-\alpha_{10}W_1} e^{-\alpha_{30}W_3} \Delta \epsilon_{t-1}) \Delta \epsilon'_t]$
 $= -\sigma_{\epsilon_0}^2 e^{-\alpha_{10}W_1} e^{-\alpha_{30}W_3};$
- (2) $E(\Delta y_t \Delta \epsilon'_t)$
 $= E[(e^{-\alpha_{10}W_1} A_{20} \Delta y_{t-1} + e^{-\alpha_{10}W_1} \Delta X_t \beta_0 + e^{-\alpha_{10}W_1} e^{-\alpha_{30}W_3} \Delta \epsilon_t) \Delta \epsilon'_t]$
 $= -\sigma_{\epsilon_0}^2 e^{-\alpha_{10}W_1} (A_{20} e^{-\alpha_{10}W_1} - 2I_n) e^{-\alpha_{30}W_3};$
- (3) $E(\Delta y_{t+1} \Delta \epsilon'_t)$
 $= E[(e^{-\alpha_{10}W_1} A_{20} \Delta y_t + e^{-\alpha_{10}W_1} \Delta X_{t+1} \beta_0 + e^{-\alpha_{10}W_1} e^{-\alpha_{30}W_3} \Delta \epsilon_{t+1}) \Delta \epsilon'_t]$
 $= -\sigma_{\epsilon_0}^2 e^{-\alpha_{10}W_1} (A_{20} e^{-\alpha_{10}W_1} - I_n)^2 e^{-\alpha_{30}W_3};$
- (4) For $t \geq s+1$ and $s \geq 2$,
 $E(\Delta y_t \Delta \epsilon'_s) = -\sigma_{\epsilon_0}^2 e^{-\alpha_{10}W_1} (A_{20} e^{-\alpha_{10}W_1})^{t-(s+1)} (A_{20} e^{-\alpha_{10}W_1} - I_n)^2 e^{-\alpha_{30}W_3};$
- (5) All the remaining terms $E(\Delta y_t \Delta \epsilon'_{t+2}) = 0$ for $t \geq 1$.

Combining all elements, we have

$$E(\Delta Y_{-1} \Delta \epsilon') = E \left[\begin{pmatrix} \Delta y_1 \\ \vdots \\ \Delta y_{T-1} \end{pmatrix} \times \begin{pmatrix} \Delta \epsilon_2 & \dots & \Delta \epsilon_T \end{pmatrix} \right] = -\sigma_{\epsilon_0}^2 \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \mathbf{D}_{-1,0} \mathbf{e}^{-\alpha_{30}\mathbf{W}_3}$$

$$\text{and } E(\Delta Y \Delta \epsilon') = E \left[\begin{pmatrix} \Delta y_2 \\ \vdots \\ \Delta y_T \end{pmatrix} \times \begin{pmatrix} \Delta \epsilon_2 & \dots & \Delta \epsilon_T \end{pmatrix} \right] = -\sigma_{\epsilon_0}^2 \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \mathbf{D}_0 \mathbf{e}^{-\alpha_{30}\mathbf{W}_3}.$$

Proof of Lemma 3.1. Recall $A_{12,0} = e^{-\alpha_{10}W_1} A_{20}$. By the reduced form of Δy_t and continuous substitution, we have:

$$\begin{aligned} \Delta y_t &= A_{12,0} \Delta y_{t-1} + e^{-\alpha_{10}W_1} \Delta X_t \beta_0 + e^{-\alpha_{10}W_1} e^{-\alpha_{30}W_3} \Delta \epsilon_t \\ &= A_{12,0}^{t-1} \Delta y_1 + \sum_{i=0}^{t-2} A_{12,0}^i e^{-\alpha_{10}W_1} \Delta X_{t-i} \beta_0 + \sum_{i=0}^{t-2} A_{12,0}^i e^{-\alpha_{10}W_1} e^{-\alpha_{30}W_3} \Delta \epsilon_{t-i} \\ &= A_{12,0}^{t-1} \Delta y_1 + [A_{12,0}^{t-2} \ A_{12,0}^{t-3} \ \dots \ I_n \ 0 \ \dots \ 0] \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \Delta X \beta_0 + [A_{12,0}^{t-2} \ A_{12,0}^{t-3} \ \dots \ I_n \ 0 \\ &\quad \dots \ 0] \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \mathbf{e}^{-\alpha_{30}\mathbf{W}_3} \Delta \epsilon. \end{aligned}$$

Stacking them in one column we have:

$$\Delta Y = G \Delta y_1 + J \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \Delta X \beta_0 + J \mathbf{e}^{-\alpha_{10}\mathbf{W}_1} \mathbf{e}^{-\alpha_{30}\mathbf{W}_3} \Delta \epsilon = G \Delta y_1 + \delta + K \Delta \epsilon.$$

Similarly for ΔY_{-1} we have:

$$\Delta Y_{-1} = G_{-1} \Delta \mathbf{y}_1 + J_{-1} \mathbf{e}^{-\alpha_{10} \mathbf{W}_1} \Delta X \beta_0 + J_{-1} \mathbf{e}^{-\alpha_{10} \mathbf{W}_1} \mathbf{e}^{-\alpha_{30} \mathbf{W}_3} \Delta \epsilon = G_{-1} \Delta \mathbf{y}_1 + \boldsymbol{\delta}_{-1} + K_{-1} \Delta \epsilon.$$

Proof of Lemma 3.2. First note $R' \Delta \epsilon = \sum_{i=1}^T R'_t \Delta \epsilon_t = \sum_{i=1}^n \sum_{t=2}^T R'_{it} \Delta \epsilon_{it} = \sum_{i=1}^n a_{1i}$. Here we partition $R' \Delta \epsilon$ by time periods in the first equality and then by time periods and individuals in the second equality.

Second $E(\Delta \epsilon' O \Delta \epsilon) = E[\text{tr}(\Delta \epsilon' O \Delta \epsilon)] = \text{tr}[E(\Delta \epsilon' \Delta \epsilon) O] = \sigma_{\epsilon_0}^2 \text{tr}(\mathbf{B} O) = \sigma_{\epsilon_0}^2 \sum_{i=1}^n \sum_{t=2}^T d_{it}$, where d_{it} is the it th diagonal element of $\mathbf{B} O$. So we have:

$$\begin{aligned} \Delta \epsilon' O \Delta \epsilon - E(\Delta \epsilon' O \Delta \epsilon) &= \sum_{t=2}^T \sum_{s=2}^T \Delta \epsilon'_t (O_{ts}^u + O_{ts}^l + O_{ts}^d) \Delta \epsilon_s - \sigma_{\epsilon_0}^2 \sum_{i=1}^n \sum_{t=2}^T d_{it} \\ &= \sum_{t=2}^T \sum_{s=2}^T [\Delta \epsilon'_s O_{ts}^u \Delta \epsilon_t + \Delta \epsilon'_t (O_{ts}^l + O_{ts}^d) \Delta \epsilon_s] - \sigma_{\epsilon_0}^2 \sum_{t=2}^T \sum_{s=2}^T d_{it} \\ &= \sum_{i=1}^n \sum_{t=2}^T (\Delta \epsilon_{it} \Delta \eta_{it} + \Delta \epsilon_{it} \Delta \epsilon_{it}^* - \sigma_{\epsilon_0}^2 d_{it}) \\ &= \sum_{i=1}^n a_{2i}, \end{aligned}$$

where $\Delta \eta_t = \sum_{s=2}^T (O_{st}^u + O_{ts}^l) \Delta \epsilon_s$ and $\Delta \epsilon_t^* = \sum_{s=2}^T O_{ts}^d \Delta \epsilon_s$. Here we change the way $\Delta \epsilon' O \Delta \epsilon$ is partitioned from by time periods to by individuals and time periods.

Third we first write $\Delta \epsilon' F \Delta \mathbf{y}_1$ as following:

$$\begin{aligned} \Delta \epsilon' F \Delta \mathbf{y}_1 &= \sum_{t=2}^T \Delta \epsilon'_t F_t^+ \Delta \mathbf{y}_1 = \Delta \epsilon'_2 F_2^+ \Delta \mathbf{y}_1 + \sum_{t=3}^T \Delta \epsilon'_t F_t^+ \Delta \mathbf{y}_1 \\ &= \Delta \epsilon'_2 F_2^+ e^{-\alpha_{10} W_1} e^{-\alpha_{30} W_3} e^{\alpha_{30} W_3} e^{\alpha_{10} W_1} \Delta \mathbf{y}_1 + \sum_{t=3}^T \Delta \epsilon'_t F_t^+ \Delta \mathbf{y}_1 \\ &= \Delta \epsilon'_2 F_2^{++} \Delta \mathbf{y}_1^\diamond + \sum_{t=3}^T \Delta \epsilon'_t \Delta \mathbf{y}_{1t}^*, \end{aligned}$$

where $F_2^{++} = F_2^+ e^{-\alpha_{10} W_1} e^{-\alpha_{30} W_3}$, $\Delta \mathbf{y}_1^\diamond = e^{\alpha_{30} W_3} e^{\alpha_{10} W_1} \Delta \mathbf{y}_1$ and $\Delta \mathbf{y}_{1t}^* = F_t^+ \Delta \mathbf{y}_1$. Also note $\Delta \mathbf{y}_1^\diamond = e^{\alpha_{30} W_3} A_{20} \Delta \mathbf{y}_0 + e^{\alpha_{30} W_3} \Delta X_1 \beta_0 + \Delta \epsilon_1$, where $A_{20} = \tau_0 I_n + e^{\alpha_{20} W_2}$. By Assumption 1, $\Delta \mathbf{y}_0$ is independent of ϵ_t for $t \geq 1$. So $E(\Delta \epsilon'_2 F_2^{++} \Delta \mathbf{y}_1^\diamond) = E(\epsilon'_2 F_2^{++} \Delta \epsilon_1) = -\sigma_{\epsilon_0}^2 \text{tr}(F_2^{++})$, which leads to the following:

$$\begin{aligned} \Delta \epsilon'_2 F_2^{++} \Delta \mathbf{y}_1^\diamond - E(\Delta \epsilon'_2 F_2^{++} \Delta \mathbf{y}_1^\diamond) &= \Delta \epsilon'_2 (F_2^{++u} + F_2^{++l}) \Delta \mathbf{y}_1^\diamond + \Delta \epsilon'_2 F_2^{++d} \Delta \mathbf{y}_1^\diamond + \sigma_{\epsilon_0}^2 \text{tr}(F_2^{++}) \\ &= \sum_{i=1}^n \Delta \epsilon_{2i} \Delta \xi_i + \sum_{i=1}^n F_{2,ii}^{++} (\Delta \epsilon_{2i} \Delta \mathbf{y}_{1i}^\diamond + \sigma_{\epsilon_0}^2), \end{aligned}$$

where $\Delta\xi = (F_2^{++u} + F_2^{++l})\Delta y_1^\diamond$. Combining the equations above, we get the following:

$$\begin{aligned}
& \Delta\epsilon' F \Delta \mathbf{y}_1 - \mathbb{E}(\Delta\epsilon' F \Delta \mathbf{y}_1) \\
&= \Delta\epsilon_2' F_2^{++} \Delta y_1^\diamond - \mathbb{E}(\Delta\epsilon_2' F_2^{++} \Delta y_1^\diamond) + \sum_{t=3}^T \Delta\epsilon_t' \Delta y_{1t}^* - \mathbb{E}(\sum_{t=3}^T \Delta\epsilon_t' \Delta y_{1t}^*) \\
&= \sum_{i=1}^n \Delta\epsilon_{2i} \Delta\xi_i + \sum_{i=1}^n F_{2,ii}^{++} (\Delta\epsilon_{2i} \Delta y_{1i}^\diamond + \sigma_{\epsilon 0}^2) + \sum_{t=3}^T \Delta\epsilon_t' \Delta y_{1t}^* \\
&= \sum_{i=1}^n a_{3i},
\end{aligned}$$

where $a_{3i} = \Delta\epsilon_{2i} \Delta\xi_i + F_{2,ii}^{++} (\Delta\epsilon_{2i} \Delta y_{1i}^\diamond + \sigma_{\epsilon 0}^2) + \sum_{t=3}^T \Delta\epsilon_{it}' \Delta y_{1t}^*$. Here $\mathbb{E}(\sum_{t=3}^T \Delta\epsilon_t' \Delta y_{1t}^*) = 0$ according to Assumption 1.

Because $\mathbb{E}[(a_{1i}', a_{2i}, a_{3i}) | \Phi_{n,i-1}] = 0$, where $\Phi_{n,i-1} = \Phi_{n,0} \otimes \Pi_{n,i-1}$ is the Cartesian product generated by subsets of $X_1 \times X_2$, with $X_1 \in \Phi_{n,0}$ and $X_2 \in \Pi_{n,i-1}$, $\{(a_{1i}', a_{2i}, a_{3i}), \Phi_{n,i}\}$ form a vector MDS.

C Proofs of Theorems 3.1-3.3

Proof of Theorem 3.1. Given Assumption 7, we need to prove $\sup_{\zeta \in \mathcal{Z}} \|S^{*c}(\zeta) - \bar{S}^{*c}(\zeta)\| \xrightarrow{p} 0$. Note $S^{*c}(\zeta)$ has four elements by (2.18). So

$$\begin{aligned}
& S^{*c}(\zeta) - \bar{S}^{*c}(\zeta) = \\
& \begin{cases} \frac{1}{\bar{\sigma}_{\epsilon,M}^2(\zeta)} \Delta\hat{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1} - \frac{1}{\bar{\sigma}_{\epsilon,M}^2(\zeta)} \mathbb{E}[\Delta\bar{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1}], \\ -\frac{1}{\bar{\sigma}_{\epsilon,M}^2(\zeta)} \Delta\hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1 \Delta Y + \frac{1}{\bar{\sigma}_{\epsilon,M}^2(\zeta)} \mathbb{E}[\Delta\bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1 \Delta Y], \\ \frac{1}{\bar{\sigma}_{\epsilon,M}^2(\zeta)} \Delta\hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2 \Delta Y_{-1} - \frac{1}{\bar{\sigma}_{\epsilon,M}^2(\zeta)} \mathbb{E}[\Delta\bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2 \Delta Y_{-1}], \\ -\frac{1}{2\bar{\sigma}_{\epsilon,M}^2(\zeta)} \Delta\hat{u}(\zeta)' (B^{-1} \otimes E_3) \Delta\hat{u}(\zeta) + \frac{1}{2\bar{\sigma}_{\epsilon,M}^2(\zeta)} \mathbb{E}[\Delta\bar{u}(\zeta)' (B^{-1} \otimes E_3) \Delta\bar{u}(\zeta)]. \end{cases}
\end{aligned}$$

Now each function can be written as, while neglecting $\frac{1}{2}$, positive or negative $\frac{\bar{\sigma}_{\epsilon,M}^2(\zeta) - \hat{\sigma}_{\epsilon,M}^2(\zeta)}{\bar{\sigma}_{\epsilon,M}^2(\zeta) \hat{\sigma}_{\epsilon,M}^2(\zeta)} f[\Delta\hat{u}(\zeta)] + \frac{1}{\bar{\sigma}_{\epsilon,M}^2(\zeta)} [f[\Delta\hat{u}(\zeta)] - \mathbb{E}f[\Delta\bar{u}(\zeta)]]$, where $f[\Delta\hat{u}(\zeta)]$ and $f[\Delta\bar{u}(\zeta)]$ are functions of $\Delta\hat{u}(\zeta)$ and $\Delta\bar{u}(\zeta)$ respectively. To show that these functions are $o_p(1)$, we need to prove the following:

- (i) $\inf_{\zeta \in \mathcal{Z}} \bar{\sigma}_{\epsilon,M}^2(\zeta) > c > 0$ for some positive number c ,
- (ii) $\sup_{\zeta \in \mathcal{Z}} |\hat{\sigma}_{\epsilon,M}^2(\zeta) - \bar{\sigma}_{\epsilon,M}^2(\zeta)| = o_p(1)$,
- (iii) $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} |\Delta\hat{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1} - \mathbb{E}[\Delta\bar{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1}]| = o_p(1)$,
- (iv) $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} |\Delta\hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1 \Delta Y - \mathbb{E}[\Delta\bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1 \Delta Y]| = o_p(1)$,

- (v) $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} \left| \Delta \hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} - \mathbb{E}[\Delta \bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}] \right| = o_p(1),$
- (vi) $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} \left| \Delta \hat{u}(\zeta)' (B^{-1} \otimes E_3) \Delta \hat{u}(\zeta) - \mathbb{E}[\Delta \bar{u}(\zeta)' (B^{-1} \otimes E_3) \Delta \bar{u}(\zeta)] \right| = o_p(1).$

Proof of (i): Utilizing (3.5), $\bar{\sigma}_{\epsilon, M}^2(\zeta)$ can be expressed as:

$$\begin{aligned}
\bar{\sigma}_{\epsilon, M}^2(\zeta) &= \frac{1}{n(T-1)} \mathbb{E}[\Delta \bar{u}(\zeta)' \Sigma^{-1} \Delta \bar{u}(\zeta)] = \frac{1}{n(T-1)} \mathbb{E}[\Delta \bar{u}^*(\zeta)' \Delta \bar{u}^*(\zeta)] \\
&= \frac{1}{n(T-1)} \mathbb{E}[(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger)' P(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger) \\
&\quad + (\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})] \\
&= \frac{1}{n(T-1)} \mathbb{E}[\text{tr}[(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger)' (\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger)]] \\
&\quad + \frac{1}{n(T-1)} \mathbb{E}[(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \mathbb{E} \Delta Y - \mathbf{A}_2^* \mathbb{E} \Delta Y_{-1})' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})] \\
&\quad + \frac{1}{n(T-1)} \mathbb{E}[(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger)' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \mathbb{E} \Delta Y^\dagger - \mathbf{A}_2^* \mathbb{E} \Delta Y_{-1}^\dagger)] \\
&= \frac{1}{n(T-1)} \text{tr}[\text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})] \\
&\quad + \frac{1}{n(T-1)} (\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \mathbb{E} \Delta Y - \mathbf{A}_2^* \mathbb{E} \Delta Y_{-1})' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \mathbb{E} \Delta Y - \mathbf{A}_2^* \mathbb{E} \Delta Y_{-1})
\end{aligned}$$

where we used $\mathbb{E}(\Delta Y^\dagger) = \mathbb{E}(\Delta Y_{-1}^\dagger) = 0$ in the last equality.

For the first term, note

$$\begin{aligned}
&\frac{1}{n(T-1)} \text{tr}[\text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})] = \frac{1}{n(T-1)} \text{tr}[\Sigma_3^{-1} \text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})] \\
&= \frac{1}{n(T-1)} \text{tr}[(B^{-1} \otimes e^{\alpha_3 W_3'} e^{\alpha_3 W_3}) \text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})] \\
&\geq \frac{1}{n(T-1)} \gamma_{\min}(B^{-1}) \gamma_{\min}(e^{\alpha_3 W_3'} e^{\alpha_3 W_3}) \text{tr}[\text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})],
\end{aligned}$$

where $\gamma_{\min}(B^{-1}) > 0$ given the structure of B , $\gamma_{\min}(e^{\alpha_3 W_3'} e^{\alpha_3 W_3}) > 0$ by Assumption 4 and $\text{tr}[\text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})] > 0$ by the assumption of the theorem. So $\frac{1}{n(T-1)} \text{tr}[\text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})] > 0$.

For the second term, since M is positive semi-definite, we have $\frac{1}{n(T-1)} (\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \mathbb{E} \Delta Y - \mathbf{A}_2^* \mathbb{E} \Delta Y_{-1})' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \mathbb{E} \Delta Y - \mathbf{A}_2^* \mathbb{E} \Delta Y_{-1}) \geq 0$ uniformly in $\zeta \in \mathcal{Z}$. So (i) holds.

Proof of (ii): We first express $\Delta \hat{u}^*(\zeta)$ as $\Delta \hat{u}^*(\zeta) = \Sigma^{-\frac{1}{2}} \Delta \hat{u}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1} - P(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1}) = M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})$. So $\hat{\sigma}_{\epsilon, M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \hat{u}^*(\zeta)' \Delta \hat{u}^*(\zeta) = \frac{1}{n(T-1)} (\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})$. Utilizing the function in the third equal-

ity in the expression in the proof of (i) for $\bar{\sigma}_{\epsilon,M}^2(\zeta)$, we have the following:

$$\begin{aligned}\hat{\sigma}_{\epsilon,M}^2(\zeta) - \bar{\sigma}_{\epsilon,M}^2(\zeta) &= \frac{1}{n(T-1)}(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1}) \\ &\quad - \frac{1}{n(T-1)} \mathbb{E}[(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger)' P(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger) \\ &\quad + (\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})' M(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1})] \\ &= \frac{1}{n(T-1)}[N_1 - \mathbb{E}(N_1)] - \frac{2}{n(T-1)}[N_2 - \mathbb{E}(N_2)] + \frac{1}{n(T-1)}[N_3 - \\ &\quad \mathbb{E}(N_3)] - \frac{1}{n(T-1)}\mathbb{E}(N_4),\end{aligned}$$

where $N_1 = \Delta Y' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y$, $N_2 = \Delta Y' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* \Delta Y_{-1}$, $N_3 = \Delta Y_{-1}' \mathbf{A}_2^* M \mathbf{A}_2^* \Delta Y_{-1}$ and $N_4 = (\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger)' P(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger)$. We need to prove $\frac{1}{n(T-1)}[N_r - \mathbb{E}(N_r)] \xrightarrow{p} 0$ uniformly in $\zeta \in \mathcal{Z}$ for $r = 1, 2, 3$ and $\frac{1}{n(T-1)}\mathbb{E}(N_4) \rightarrow 0$ uniformly in $\zeta \in \mathcal{Z}$.

To prove $\frac{1}{n(T-1)}[N_r - \mathbb{E}(N_r)] \xrightarrow{p} 0$ uniformly in $\zeta \in \mathcal{Z}$ for $r = 1, 2$ and 3 , we need to prove the pointwise convergence of $\frac{1}{n(T-1)}[N_r - \mathbb{E}(N_r)]$ in each $\zeta \in \mathcal{Z}$ and the stochastic equicontinuity of $\frac{1}{n(T-1)}N_r$.

Proof of pointwise convergence: By Lemma 3.1, we can express N_r 's for $r = 1, 2$ and 3 as a function of $\Delta \mathbf{y}_1$, $\boldsymbol{\delta}$ and $\Delta \epsilon$ as follows:

$$\begin{aligned}N_1 &= \Delta \mathbf{y}_1' G' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} G \Delta \mathbf{y}_1 + \boldsymbol{\delta}' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \boldsymbol{\delta} + \Delta \epsilon' K' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} K \Delta \epsilon \\ &\quad + 2\Delta \mathbf{y}_1' G' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \boldsymbol{\delta} + 2\boldsymbol{\delta}' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} K \Delta \epsilon + 2\Delta \mathbf{y}_1' G' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} K \Delta \epsilon \\ N_2 &= \Delta \mathbf{y}_1' G' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* G_{-1} \Delta \mathbf{y}_1 + \Delta \mathbf{y}_1' G' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* \boldsymbol{\delta}_{-1} + \Delta \mathbf{y}_1' G' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* K_{-1} \Delta \epsilon \\ &\quad + \boldsymbol{\delta}' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* G_{-1} \Delta \mathbf{y}_1 + \boldsymbol{\delta}' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* \boldsymbol{\delta}_{-1} + \boldsymbol{\delta}' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* K_{-1} \Delta \epsilon \\ &\quad + \Delta \epsilon' K' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* G_{-1} \Delta \mathbf{y}_1 + \Delta \epsilon' K' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* \boldsymbol{\delta}_{-1} + \Delta \epsilon' K' \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} M \mathbf{A}_2^* K_{-1} \Delta \epsilon \\ N_3 &= \Delta \mathbf{y}_1' G_{-1}' \mathbf{A}_2^* M \mathbf{A}_2^* G_{-1} \Delta \mathbf{y}_1 + \boldsymbol{\delta}_{-1}' \mathbf{A}_2^* M \mathbf{A}_2^* \boldsymbol{\delta}_{-1} + \Delta \epsilon' K_{-1}' \mathbf{A}_2^* M \mathbf{A}_2^* K_{-1} \Delta \epsilon \\ &\quad + 2\Delta \mathbf{y}_1' G_{-1}' \mathbf{A}_2^* M \mathbf{A}_2^* \boldsymbol{\delta}_{-1} + 2\Delta \mathbf{y}_1' G_{-1}' \mathbf{A}_2^* M \mathbf{A}_2^* K_{-1} \Delta \epsilon + 2\boldsymbol{\delta}_{-1}' \mathbf{A}_2^* M \mathbf{A}_2^* K_{-1} \Delta \epsilon\end{aligned}$$

Denote $N_1 = \sum_{q=1}^6 N_{1,q}$, $N_2 = \sum_{q=1}^9 N_{2,q}$ and $N_3 = \sum_{q=1}^6 N_{3,q}$, where each q denotes the corresponding term in N_1 , N_2 and N_3 . We can prove that each element satisfies $N_{r,q} - \mathbb{E}(N_{r,q}) = o_p(1)$ for all r and q . First note that $N_{1,2} - \mathbb{E}(N_{1,2}) = 0$, $N_{2,5} - \mathbb{E}(N_{2,5}) = 0$ and $N_{3,2} - \mathbb{E}(N_{3,2}) = 0$ because they are nonstochastic. For the rest of the terms, we group them into five categories:

- (A) $\Delta \mathbf{y}_1' C_1 \Delta \mathbf{y}_1 : N_{1,1}, N_{2,1}$ and $N_{3,1}$;
- (B) $\Delta \epsilon' C_2 \Delta \epsilon : N_{1,3}, N_{2,9}$ and $N_{3,3}$;
- (C) $\Delta \mathbf{y}_1' c_3 : N_{1,4}, N_{2,2}, N_{2,4}$ and $N_{3,4}$;
- (D) $\Delta \mathbf{y}_1' C_4 \Delta \epsilon : N_{1,6}, N_{2,3}, N_{2,7}$ and $N_{3,5}$;

(E) $\Delta \epsilon' c_5 : N_{1,5}, N_{2,6}, N_{2,8}$ and $N_{3,6}$,

where C_1, C_2 and C_4 are $n(T-1) \times n(T-1)$ nonstochastic matrices and c_3 and c_5 are $n(T-1) \times 1$ nonstochastic vectors comprised of $G, G_{-1}, K, K_{-1}, \delta, \delta_{-1}, \mathbf{e}^{\alpha_1 \mathbf{W}_1^*}, \mathbf{A}_2^*$ and M . Note $G, G_{-1}, K, K_{-1}, \delta$ and δ_{-1} are functions of the true parameters, $\mathbf{e}^{\alpha_1 \mathbf{W}_1^*}$ is a function of α_1 and α_3 , \mathbf{A}_2^* is a function of τ, α_2 and α_3 and M is a function α_3 .

For (A), we can write $\frac{1}{n(T-1)} \Delta \mathbf{y}_1' C_1 \Delta \mathbf{y}_1 = \frac{1}{n} \Delta \mathbf{y}_1' C_1^* \Delta \mathbf{y}_1$, where $C_1^* = \frac{1}{T-1} \sum_s \sum_t C_{1,st}$. By Lemma A.1 and Lemma A.2, it is uniformly bounded in row or column sums. Hence $\frac{1}{n(T-1)} [\Delta \mathbf{y}_1' C_1 \Delta \mathbf{y}_1 - E(\Delta \mathbf{y}_1' C_1 \Delta \mathbf{y}_1)] = \frac{1}{n} [\Delta \mathbf{y}_1' C_1^* \Delta \mathbf{y}_1 - E(\Delta \mathbf{y}_1' C_1^* \Delta \mathbf{y}_1)]$ is pointwise convergent by Assumption 6(iii).

For (B), we can write $\frac{1}{n(T-1)} \Delta \epsilon' C_2 \Delta \epsilon = \frac{1}{T-1} \sum_s \sum_t \frac{1}{n} \epsilon' C_{2,st} \epsilon$. By Lemma A.3(v), $\frac{1}{n} [\epsilon' C_{2,st} \epsilon - E(\epsilon' C_{2,st} \epsilon)]$ is pointwise convergent for each s and t .

For (C), the pointwise convergence of $\frac{1}{n(T-1)} [\Delta \mathbf{y}_1' c_3 - E(\Delta \mathbf{y}_1' c_3)]$ follows from Assumption 6(ii).

For (D), we can write $\Delta \mathbf{y}_1' C_4 \Delta \epsilon = \sum_s \Delta \mathbf{y}_1' C_{4,s}^* \Delta \epsilon_s$ and the pointwise convergence follows from Lemma A.3(vii) and Assumption 6(iv).

For (E), we can write $\Delta \epsilon' c_5 = \sum_s \Delta \epsilon_s c_{5,s}$. Note $E(\Delta \epsilon_s c_{5,s}) = 0$. By Chebyshev's inequality, $\Delta \epsilon_s c_{5,s}$ is pointwise convergent for each s .

Proof of stochastic equicontinuity: Denote each $N_{r,q}$ for $r = 1, 2$ and 3 by $N_{r,q}(\zeta)$. Then for any two parameter vectors $\zeta_1 \in \mathcal{Z}$ and $\zeta_2 \in \mathcal{Z}$, we have by mean value theorem: $N_{r,q}(\zeta_1) - N_{r,q}(\zeta_2) = \frac{\partial N_{r,q}(\bar{\zeta})}{\partial \zeta'} (\zeta_1 - \zeta_2)$, where $\bar{\zeta}$ is between ζ_1 and ζ_2 elementwise. We can prove each of $\sup_{\zeta \in \mathcal{Z}} \left| \frac{1}{n(T-1)} \frac{\partial N_{r,q}(\zeta)}{\partial \zeta'} \right|$ is $O_p(1)$ for the five categories above. For example for $N_{1,1}(\zeta)$ we have:

$$\begin{aligned} \sup_{\zeta \in \mathcal{Z}} \left| \frac{1}{n(T-1)} \frac{\partial N_{1,1}(\zeta)}{\partial \alpha_1} \right| &= \sup_{\zeta \in \mathcal{Z}} \left| \frac{2}{n(T-1)} \Delta \mathbf{y}_1' G' \mathbf{e}^{\alpha_1 \mathbf{W}_1'} \mathbf{W}_1' \Sigma^{-\frac{1}{2}} M \Sigma^{-\frac{1}{2}} \mathbf{e}^{\alpha_1 \mathbf{W}_1} G \Delta \mathbf{y}_1 \right| \\ &\leq \gamma_{\max}(\mathbf{W}_1 \Sigma^{-1}) \gamma_{\max}(\mathbf{e}^{\alpha_1 \mathbf{W}_1'} \mathbf{e}^{\alpha_1 \mathbf{W}_1}) \frac{2}{n(T-1)} \left| \Delta \mathbf{y}_1' G' G \Delta \mathbf{y}_1 \right| \\ &= O_p(1) \end{aligned}$$

where we used $\gamma_{\max}(M) = 1$ and Assumption 6(i). So $\sup_{\zeta \in \mathcal{Z}} \left| \frac{1}{n(T-1)} \frac{\partial N_{1,1}(\zeta)}{\partial \zeta'} \right| = O_p(1)$ and $\frac{1}{n(T-1)} N_{1,1}(\zeta)$ is stochastic equicontinuous. The proofs for stochastic equicontinuity of each of the remaining $N_{r,q}(\zeta)$ follow similarly. By Corollary 2.2 in Newey (1991), $\frac{1}{n(T-1)} [N_{r,q}(\zeta) - E(N_{r,q}(\zeta))] \xrightarrow{p} 0$ uniformly in $\zeta \in \mathcal{Z}$ for all r and q . Hence $\frac{1}{n(T-1)} [N_r(\zeta) - E(N_r(\zeta))] \xrightarrow{p} 0$ uniformly in $\zeta \in \mathcal{Z}$ for $r = 1, 2$ and 3 .

To prove $\frac{1}{n(T-1)}\mathbb{E}[N_4(\zeta)] \rightarrow 0$ uniformly in $\zeta \in \mathcal{Z}$, first note that

$$\begin{aligned}
\frac{1}{n(T-1)}\mathbb{E}[N_4(\zeta)] &= \frac{1}{n(T-1)}\mathbb{E}[(Y^\dagger \mathbf{e}^{\alpha_1 \mathbf{W}_1^*} - Y_{-1}^\dagger \mathbf{A}_2^*) \Sigma^{-\frac{1}{2}} P \Sigma^{-\frac{1}{2}} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} Y^\dagger - \mathbf{A}_2^* Y_{-1}^\dagger)] \\
&= \frac{1}{n(T-1)} \text{tr}[\Sigma^{-1} \Delta X (\Delta X' \Sigma^{-1} \Delta X)^{-1} \Delta X' \Sigma^{-1} \text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})] \\
&\leq \frac{\gamma_{\max}(\Sigma^{-2})}{n(T-1)} \gamma_{\min}^{-1}(\Delta X' \Sigma^{-1} \Delta X) \text{tr}[\Delta X' \text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1}) \Delta X] \\
&\leq \frac{\gamma_{\max}(\Sigma^{-2})}{n(T-1)} \gamma_{\min}^{-1} \left[\frac{\Delta X' \Sigma^{-1} \Delta X}{n(T-1)} \right] \frac{1}{n(T-1)} \text{tr}[\Delta X' \text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1}) \Delta X].
\end{aligned}$$

By Assumption 4, there exists two positive constants \underline{c}_{α_3} and \bar{c}_{α_3} such that $0 < \underline{c}_{\alpha_3} \leq \inf_{\alpha_3 \in \mathcal{Z}_3} \gamma_{\min}(\Sigma^{-1}) \leq \sup_{\alpha_3 \in \mathcal{Z}_3} \gamma_{\max}(\Sigma^{-1}) \leq \bar{c}_{\alpha_3} < \infty$. So there exists two other constants $\underline{c}_{\Delta X}$ and $\bar{c}_{\Delta X}$ such that $0 < \underline{c}_{\Delta X} \leq \inf_{\alpha_3 \in \mathcal{Z}_3} \gamma_{\min}(\Sigma^{-1}) \gamma_{\min}[\frac{\Delta X' \Delta X}{n(T-1)}] \leq \gamma_{\min}[\frac{\Delta X' \Sigma^{-1} \Delta X}{n(T-1)}] \leq \gamma_{\max}[\frac{\Delta X' \Sigma^{-1} \Delta X}{n(T-1)}] \leq \sup_{\alpha_3 \in \mathcal{Z}_3} \gamma_{\max}(\Sigma^{-1}) \gamma_{\max}[\frac{\Delta X' \Delta X}{n(T-1)}] \leq \bar{c}_{\Delta X} < \infty$, which can be used in the inequality above and leads to

$$\begin{aligned}
\frac{1}{n(T-1)}\mathbb{E}[N_4(\zeta)] &\leq \frac{1}{n(T-1)} \bar{c}_{\alpha_3}^2 \underline{c}_{\Delta X} \frac{1}{n(T-1)} \text{tr}[\Delta X' \text{Var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1}) \Delta X] \\
&\leq \frac{1}{n(T-1)} \bar{c}_{\alpha_3}^2 \underline{c}_{\Delta X} \bar{c}_{\Delta Y} \frac{1}{n(T-1)} \text{tr}(\Delta X' \Delta X) \\
&= O\left(\frac{1}{n}\right)
\end{aligned}$$

by assumption of the theorem and bounds on Rayleigh quotient. Hence $\hat{\sigma}_{\epsilon, M}^2(\zeta) - \bar{\sigma}_{\epsilon, M}^2(\zeta) = o_p(1)$ uniformly in $\zeta \in \mathcal{Z}$ and (ii) holds.

Proof of (iii)-(vi): Using the similar transformations in the proof of (ii), by letting $\widetilde{\mathbf{W}}_r = \Sigma^{-\frac{1}{2}} \mathbf{W}_r \Sigma^{\frac{1}{2}}$ for $r = 1$ and 2, we can express the functions in (iii)-(vi) as follows:

$$\begin{aligned}
& \Delta \hat{u}(\alpha)' \Sigma^{-1} \Delta Y_{-1} - E[\Delta \bar{u}(\alpha)' \Sigma^{-1} \Delta Y_{-1}] \\
&= \Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M \Sigma^{-\frac{1}{2}} \Delta Y_{-1} - E(\Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M \Sigma^{-\frac{1}{2}} \Delta Y_{-1}) \\
&\quad - \Delta Y_{-1}' \mathbf{A}_2^{*'} M \Sigma^{-\frac{1}{2}} \Delta Y_{-1} + E(\Delta Y_{-1}' \mathbf{A}_2^{*'} M \Sigma^{-\frac{1}{2}} \Delta Y_{-1}) \\
&\quad - E(\Delta Y^\dagger' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} P \Sigma^{-\frac{1}{2}} \Delta Y_{-1}) + E(\Delta Y_{-1}^\dagger' \mathbf{A}_2^{*'} P \Sigma^{-\frac{1}{2}} \Delta Y_{-1}) \\
& \Delta \hat{u}(\alpha)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1 \Delta Y - E[\Delta \bar{u}(\alpha)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1 \Delta Y] \\
&= \Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M \widetilde{\mathbf{W}}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y - E(\Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M \widetilde{\mathbf{W}}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y) \\
&\quad - \Delta Y_{-1}' \mathbf{A}_2^{*'} M \widetilde{\mathbf{W}}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y + E(\Delta Y_{-1}' \mathbf{A}_2^{*'} M \widetilde{\mathbf{W}}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y) \\
&\quad - E(\Delta Y^\dagger' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} P \widetilde{\mathbf{W}}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y) + E(\Delta Y_{-1}^\dagger' \mathbf{A}_2^{*'} P \widetilde{\mathbf{W}}_1 \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y) \\
& \Delta \hat{u}(\alpha)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2 \Delta Y_{-1} - E[\Delta \bar{u}(\alpha)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2 \Delta Y_{-1}] \\
&= \Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M \widetilde{\mathbf{W}}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2^{*'} \Delta Y_{-1} - E(\Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M \widetilde{\mathbf{W}}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2^{*'} \Delta Y_{-1}) \\
&\quad - \Delta Y_{-1}' \mathbf{A}_2^{*'} M \widetilde{\mathbf{W}}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2^{*'} \Delta Y_{-1} + E(\Delta Y_{-1}' \mathbf{A}_2^{*'} M \widetilde{\mathbf{W}}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2^{*'} \Delta Y_{-1}) \\
&\quad - E(\Delta Y^\dagger' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} P \widetilde{\mathbf{W}}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2^{*'} \Delta Y_{-1}) + E(\Delta Y_{-1}^\dagger' \mathbf{A}_2^{*'} P \widetilde{\mathbf{W}}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2^{*'} \Delta Y_{-1}) \\
& \Delta \hat{u}(\alpha)' (B^{-1} \otimes E_3) \Delta \hat{u}(\alpha) - \frac{1}{\bar{\sigma}_{\epsilon, M}^2(\alpha)} E[\Delta \bar{u}(\alpha)' (B^{-1} \otimes E_3) \Delta \bar{u}(\alpha)] \\
&= \Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M (B^{-1} \otimes E_3) M \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y - E[\Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M (B^{-1} \otimes E_3) M \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y] \\
&\quad + \Delta Y_{-1}' \mathbf{A}_2^{*'} M (B^{-1} \otimes E_3) M \mathbf{A}_2^{*'} \Delta Y_{-1} - E[\Delta Y_{-1}' \mathbf{A}_2^{*'} M (B^{-1} \otimes E_3) M \mathbf{A}_2^{*'} \Delta Y_{-1}] \\
&\quad - 2 \Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M (B^{-1} \otimes E_3) M \mathbf{A}_2^{*'} \Delta Y_{-1} - 2 E[\Delta Y' \mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} M (B^{-1} \otimes E_3) M \mathbf{A}_2^{*'} \Delta Y_{-1}] \\
&\quad - 2 E[(\mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y^\dagger - \mathbf{A}_2^{*'} \Delta Y_{-1}^\dagger)' P (B^{-1} \otimes E_3) P (\mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y^\dagger - \mathbf{A}_2^{*'} \Delta Y_{-1}^\dagger)] \\
&\quad - 2 E[(\mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y^\dagger - \mathbf{A}_2^{*'} \Delta Y_{-1}^\dagger)' P (B^{-1} \otimes E_3) M (\mathbf{e}^{\alpha_1} \mathbf{W}_1^{*'} \Delta Y^\dagger - \mathbf{A}_2^{*'} \Delta Y_{-1}^\dagger)]
\end{aligned}$$

Using Lemma 3.1, we can express these terms as functions of $\Delta \mathbf{y}_1, \delta$ and $\Delta \epsilon$. Similar proofs follow from those for (ii) and thus are omitted.

Proof of Theorem 3.2. By the mean value theorem, we have $\sqrt{n(T-1)}(\hat{\theta}_M - \theta_0) = -[\frac{1}{n(T-1)} H^*(\bar{\theta})]^{-1} \frac{1}{\sqrt{n(T-1)}} S^*(\theta_0)$, where $H^*(\bar{\theta}) = \frac{\partial S^*(\bar{\theta})}{\partial \theta'}$ and $\bar{\theta}$ is between $\hat{\theta}_M$ and θ_0 element-wise. To obtain the asymptotic distribution of $\sqrt{n(T-1)}(\hat{\theta}_M - \theta_0)$, we will thus first prove that $\frac{1}{n(T-1)} H^*(\bar{\theta}) = \frac{1}{n(T-1)} H^*(\theta_0) + o_p(1) = \frac{1}{n(T-1)} E[H^*(\theta_0)] + o_p(1)$ and then $\frac{1}{\sqrt{n(T-1)}} S^*(\theta_0) \xrightarrow{d} N[0, \lim_{n \rightarrow \infty} \Omega^*(\theta_0)]$.

The generic form $H^*(\theta) = \frac{\partial S^*(\theta)}{\partial \theta'}$ is comprised of the following elements:

$$\begin{aligned}
H_{\beta\beta}^*(\theta) &= -\frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma^{-1} \Delta X, \\
H_{\beta\sigma_\epsilon^2}^*(\theta) &= H_{\sigma_\epsilon^2\beta}^{*'}(\theta) = -\frac{1}{\sigma_\epsilon^4} \Delta X' \Sigma^{-1} \Delta u(\phi), \\
H_{\beta\tau}^*(\theta) &= H_{\tau\beta}^{*'}(\theta) = -\frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma^{-1} \Delta Y_{-1}, \\
H_{\beta\alpha_1}^*(\theta) &= H_{\alpha_1\beta}^{*'}(\theta) = \frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y, \\
H_{\beta\alpha_2}^*(\theta) &= H_{\alpha_2\beta}^{*'}(\theta) = -\frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}, \\
H_{\beta\alpha_3}^*(\theta) &= H_{\alpha_3\beta}^{*'}(\theta) = \frac{1}{\sigma_\epsilon^2} \Delta X' (B^{-1} \otimes E_3) \Delta u(\phi), \\
H_{\sigma_\epsilon^2\sigma_\epsilon^2}^*(\theta) &= \frac{n(T-1)}{2\sigma_\epsilon^4} - \frac{1}{\sigma_\epsilon^6} \Delta u(\phi)' \Sigma^{-1} \Delta u(\phi), \\
H_{\sigma_\epsilon^2\tau}^*(\theta) &= H_{\tau\sigma_\epsilon^2}^*(\theta) = -\frac{1}{\sigma_\epsilon^4} \Delta Y_{-1}' \Sigma^{-1} \Delta u(\phi), \\
H_{\sigma_\epsilon^2\alpha_1}^*(\theta) &= H_{\alpha_1\sigma_\epsilon^2}^*(\theta) = \frac{1}{\sigma_\epsilon^4} \Delta Y_{-1}' \mathbf{e}^{\alpha_1 \mathbf{W}_1} \mathbf{W}_1' \Sigma^{-1} \Delta u(\phi), \\
H_{\sigma_\epsilon^2\alpha_2}^*(\theta) &= H_{\alpha_2\sigma_\epsilon^2}^*(\theta) = -\frac{1}{\sigma_\epsilon^4} \Delta Y_{-1}' \mathbf{e}^{\alpha_2 \mathbf{W}_2} \mathbf{W}_2' \Sigma^{-1} \Delta u(\phi), \\
H_{\sigma_\epsilon^2\alpha_3}^*(\theta) &= H_{\alpha_3\sigma_\epsilon^2}^*(\theta) = \frac{1}{2\sigma_\epsilon^4} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi), \\
H_{\tau\tau}^*(\theta) &= -\frac{1}{\sigma_\epsilon^2} \Delta Y_{-1}' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1,\tau} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\
H_{\tau\alpha_1}^*(\theta) &= \frac{1}{\sigma_\epsilon^2} \Delta Y_{-1}' \mathbf{e}^{\alpha_1 \mathbf{W}_1} \mathbf{W}_1' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1,\alpha_1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1} - \mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_1 \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\
H_{\tau\alpha_2}^*(\theta) &= -\frac{1}{\sigma_\epsilon^2} \Delta Y_{-1}' \mathbf{e}^{\alpha_2 \mathbf{W}_2} \mathbf{W}_2' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1,\alpha_2} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\
H_{\tau\alpha_3}^*(\theta) &= \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta Y_{-1}, \\
H_{\alpha_1\tau}^*(\theta) &= \frac{1}{\sigma_\epsilon^2} \Delta Y_{-1}' \mathbf{e}^{\alpha_1 \mathbf{W}_1} \mathbf{W}_1' \Sigma^{-1} \Delta Y_{-1} - \text{tr}(\mathbf{D}_\tau \mathbf{B}^{-1} \mathbf{W}_1), \\
H_{\alpha_1\alpha_1}^*(\theta) &= -\frac{1}{\sigma_\epsilon^2} [\Delta Y_{-1}' \mathbf{e}^{\alpha_1 \mathbf{W}_1} \mathbf{W}_1' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y + \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_1^2 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y] \\
&\quad - \text{tr}(\mathbf{D}_{\alpha_1} \mathbf{B}^{-1} \mathbf{W}_1), \\
H_{\alpha_1\alpha_2}^*(\theta) &= \frac{1}{\sigma_\epsilon^2} \Delta Y_{-1}' \mathbf{e}^{\alpha_2 \mathbf{W}_2} \mathbf{W}_2' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D}_{\alpha_2} \mathbf{B}^{-1} \mathbf{W}_1), \\
H_{\alpha_1\alpha_3}^*(\theta) &= -\frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y, \\
H_{\alpha_2\tau}^*(\theta) &= -\frac{1}{\sigma_\epsilon^2} \Delta Y_{-1}' \mathbf{e}^{\alpha_2 \mathbf{W}_2} \mathbf{W}_2' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1,\tau} \mathbf{B}^{-1} \mathbf{W}_{21}), \\
H_{\alpha_2\alpha_1}^*(\theta) &= \frac{1}{\sigma_\epsilon^2} \Delta Y_{-1}' \mathbf{e}^{\alpha_2 \mathbf{W}_2} \mathbf{W}_2' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y + \text{tr}(\mathbf{D}_{-1,\alpha_1} \mathbf{B}^{-1} \mathbf{W}_{21} + \mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21,\alpha_1}),
\end{aligned}$$

$$\begin{aligned}
H_{\alpha_2\alpha_2}^*(\theta) &= \frac{1}{\sigma_\epsilon^2} [-\Delta Y_{-1}' \mathbf{e}^{\alpha_2 \mathbf{W}_2'} \mathbf{W}_2' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \Delta u(\phi)' \Sigma_3^{-1} \mathbf{W}_2^2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}] \\
&\quad + \text{tr}(\mathbf{D}_{-1,\alpha_2} \mathbf{B}^{-1} \mathbf{W}_{21} + \mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21,\alpha_2}), \\
H_{\alpha_2\alpha_3}^*(\theta) &= \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}, \\
H_{\alpha_3\alpha_3}^*(\theta) &= -\frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_{33}) \Delta u(\phi),
\end{aligned}$$

where $\mathbf{D}_\omega = \frac{\partial \mathbf{D}}{\partial \omega}$, $\mathbf{D}_{-1,\omega} = \frac{\partial \mathbf{D}_{-1}}{\partial \omega}$, $\mathbf{W}_{21,\omega} = \frac{\partial \mathbf{W}_{21}}{\partial \omega}$ for $\omega = \tau, \alpha_1, \alpha_2$ and $E_{33} = \frac{\partial E_3}{\partial \alpha_3} = \mathbf{e}^{\alpha_3 \mathbf{W}_3'} (\mathbf{W}_3' + \mathbf{W}_3)^2 \mathbf{e}^{\alpha_3 \mathbf{W}_3}$.

We will first prove $\frac{1}{n(T-1)}[H^*(\bar{\theta}) - H^*(\theta_0)] = o_p(1)$. Note there are stochastic and nonstochastic elements in $H^*(\theta)$. The stochastic elements are comprised of all the terms other than the trace terms and the nonstochastic elements are the trace terms. By the model assumptions and Lemma A.1, all elements in $H^*(\theta_0)$ are uniformly bounded in both row and column sums and thus $\frac{1}{n(T-1)}H^*(\theta_0) = O_p(1)$. Note $\hat{\theta}_M \xrightarrow{p} \theta_0$ by Theorem 3.1. So $\bar{\theta} \xrightarrow{p} \theta_0$ as well because $\bar{\theta}$ is between $\hat{\theta}_M$ and θ_0 . It follows that $\frac{1}{n(T-1)}H^*(\bar{\theta}) = O_p(1)$. For $\bar{\sigma}_\epsilon^{-2}$, $\bar{\sigma}_\epsilon^{-4}$ and $\bar{\sigma}_\epsilon^{-6}$ in $H^*(\bar{\theta})$, note $\bar{\sigma}_\epsilon^{-2} \xrightarrow{p} \sigma_{\epsilon 0}^{-2}$, $\bar{\sigma}_\epsilon^{-4} \xrightarrow{p} \sigma_{\epsilon 0}^{-4}$ and $\bar{\sigma}_\epsilon^{-6} \xrightarrow{p} \sigma_{\epsilon 0}^{-6}$ which is implied by $\bar{\theta} \xrightarrow{p} \theta_0$. So they can be replaced by $\sigma_{\epsilon 0}^{-2}$, $\sigma_{\epsilon 0}^{-4}$ and $\sigma_{\epsilon 0}^{-6}$ respectively during the proof, i.e., we need to show $\frac{1}{n(T-1)}[H^*(\bar{\beta}, \sigma_{\epsilon 0}^2, \bar{\tau}, \bar{\alpha}) - H^*(\beta_0, \sigma_{\epsilon 0}^2, \tau_0, \alpha_0)] = o_p(1)$. Note that $\Delta u(\phi) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1} - \Delta X \beta$ and $\Delta u = \mathbf{e}^{\alpha_{10} \mathbf{W}_1} \Delta Y - \mathbf{A}_{20} \Delta Y_{-1} - \Delta X \beta_0$, which leads to the expression

$$\Delta u(\phi) = \Delta u + (\mathbf{e}^{\alpha_1 \mathbf{W}_1} - \mathbf{e}^{\alpha_{10} \mathbf{W}_1}) \Delta Y - (\mathbf{A}_2 - \mathbf{A}_{20}) \Delta Y_{-1} - \Delta X (\beta - \beta_0). \quad (\text{C.1})$$

By Lemma A.5 we have

$$\begin{aligned}
\|\mathbf{e}^{\bar{\alpha}_r \mathbf{W}_r} - \mathbf{e}^{\alpha_{r0} \mathbf{W}_r}\|_\infty &= \left\| (\mathbf{e}^{(\bar{\alpha}_r - \alpha_{r0}) \mathbf{W}_r} - I_{n(T-1)}) \mathbf{e}^{\alpha_{r0} \mathbf{W}_r} \right\|_\infty \\
&\leq \left\| \mathbf{e}^{(\bar{\alpha}_r - \alpha_{r0}) \mathbf{W}_r} - I_{n(T-1)} \right\|_\infty \left\| \mathbf{e}^{\alpha_{r0} \mathbf{W}_r} \right\|_\infty \\
&= o_p(1)
\end{aligned} \quad (\text{C.2})$$

for $r = 1, 2, 3$ by Lemma A.5¹. Similarly

$$\Sigma^{-1} = \Sigma_0^{-1} + B^{-1} \otimes (e^{\alpha_3 W_3'} e^{\alpha_3 W_3} - e^{\alpha_{30} W_3'} e^{\alpha_{30} W_3}). \quad (\text{C.3})$$

By lemma A.6 we have

$$\begin{aligned}
\left\| e^{\alpha_3 W_3'} e^{\alpha_3 W_3} - e^{\alpha_{30} W_3'} e^{\alpha_{30} W_3} \right\|_\infty &= \left\| e^{\alpha_{30} W_3'} [e^{(\alpha_3 - \alpha_{30}) W_3'} e^{(\alpha_3 - \alpha_{30}) W_3} - I_{n(T-1)}] e^{\alpha_{30} W_3} \right\|_\infty \\
&\leq \left\| e^{\alpha_{30} W_3'} \right\|_\infty \left\| e^{(\alpha_3 - \alpha_{30}) W_3'} e^{(\alpha_3 - \alpha_{30}) W_3} - I_{n(T-1)} \right\|_\infty \left\| e^{\alpha_{30} W_3} \right\|_\infty \\
&= o_p(1).
\end{aligned} \quad (\text{C.4})$$

¹Note that in general $e^{A+B} \neq e^A e^B$ for two matrices A and B . It is only true when A and B commute, i.e., $AB = BA$ (Chiu et al., 1996). Here \mathbf{W} commutes with itself so the equation holds.

We can first write $\frac{1}{n(T-1)}[H^*(\bar{\beta}, \sigma_{\epsilon 0}^2, \bar{\tau}, \bar{\alpha}) - H^*(\beta_0, \sigma_{\epsilon 0}^2, \tau_0, \alpha_0)]$ as functions that contain $\mathbf{e}^{\bar{\alpha}_r \mathbf{W}_r} - \mathbf{e}^{\alpha_{r0} \mathbf{W}_r}$ and $\Sigma^{-1} - \Sigma_0^{-1}$. For example, for $H_{\sigma_{\epsilon}^2 \alpha_1}^*(\theta)$, we have

$$\begin{aligned} & \frac{1}{n(T-1)}[H_{\sigma_{\epsilon}^2 \alpha_1}^*(\bar{\beta}, \sigma_{\epsilon 0}^2, \bar{\tau}, \bar{\alpha}) - H_{\sigma_{\epsilon}^2 \alpha_1}^*(\beta_0, \sigma_{\epsilon 0}^2, \tau_0, \alpha_0)] \\ &= \frac{1}{n(T-1)\sigma_{\epsilon 0}^4}[\Delta Y'(\mathbf{e}^{\alpha_1 \mathbf{W}_1'} - \mathbf{e}^{\alpha_{10} \mathbf{W}_1'})\mathbf{W}_1' \Sigma^{-1} \Delta u(\phi) + \Delta Y' \mathbf{e}^{\alpha_{10} \mathbf{W}_1'} \mathbf{W}_1' (\Sigma^{-1} - \Sigma_0^{-1}) \Delta u(\phi) \\ &+ \Delta Y' \mathbf{e}^{\alpha_{10} \mathbf{W}_1'} \mathbf{W}_1' \Sigma_0^{-1} (\Delta u(\phi) - \Delta u)]. \end{aligned}$$

Then by substituting (C.1) and (C.3) into $H^*(\theta)$, we know that the stochastic elements in $\frac{1}{n(T-1)}[H^*(\bar{\beta}, \sigma_{\epsilon 0}^2, \bar{\tau}, \bar{\alpha}) - H^*(\beta_0, \sigma_{\epsilon 0}^2, \tau_0, \alpha_0)]$ are linear, bilinear or quadratic in ΔY , ΔY_{-1} or Δu . By Lemma 2, we can express these elements in terms of $\Delta \mathbf{y}_1$ and $\Delta \epsilon$. Using (C.2) and (C.4) and the fact that $\bar{\theta} \xrightarrow{p} \theta_0$, we can prove all the stochastic elements are $o_p(1)$ using the similar proof to Theorem 3.1.

For the nonstochastic elements, we will prove that all the trace terms are $o_p(1)$. There are two types of trace terms, the first being $\text{tr}(\mathbf{D}_{\omega} \mathbf{B}^{-1} \mathbf{W}_1)$, $\text{tr}(\mathbf{D}_{-1, \omega} \mathbf{B}^{-1} \mathbf{W}_{21})$, $\text{tr}(\mathbf{D}_{\omega} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_r \mathbf{W}_r})$ and $\text{tr}(\mathbf{D}_{-1, \omega} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_r \mathbf{W}_r})$ and the second being $\text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21, \omega})$ for $\omega = \tau, \alpha_1, \alpha_2$ and $r = 1, 2$. For the first type, for example, $\text{tr}(\mathbf{D}_{\alpha_1} \mathbf{B}^{-1} \mathbf{W}_1)$, assume $(\check{\alpha}_1, \check{\alpha}_2)$ is between $(\bar{\alpha}_1, \bar{\alpha}_2)$ and $(\alpha_{10}, \alpha_{20})$ elementwise. By the mean value theorem:

$$\begin{aligned} & \frac{1}{n(T-1)}[\text{tr}(\mathbf{D}_{\alpha_1}(\bar{\alpha}_1, \bar{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_1) - \text{tr}(\mathbf{D}_{\alpha_1}(\alpha_{10}, \alpha_{20}) \mathbf{B}^{-1} \mathbf{W}_1)] \\ &= \frac{1}{n(T-1)}[(\bar{\alpha}_1 - \alpha_{10})[\text{tr}(\mathbf{D}_{\alpha_1 \alpha_1}(\check{\alpha}_1, \check{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_1)] + (\bar{\alpha}_2 - \alpha_{20})[\text{tr}(\mathbf{D}_{\alpha_1 \alpha_2}(\check{\alpha}_1, \check{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_1)]] \end{aligned}$$

where $\mathbf{D}_{\alpha_1 \alpha_1}(\check{\alpha}_1, \check{\alpha}_2)$ and $\mathbf{D}_{\alpha_1 \alpha_2}(\check{\alpha}_1, \check{\alpha}_2)$ are the derivatives of \mathbf{D}_{α_1} with respect to α_1 and α_2 respectively evaluated at $(\check{\alpha}_1, \check{\alpha}_2)$. WLOG we assume $T = 3$, then

$$\begin{aligned} \mathbf{D}_{\alpha_1 \alpha_1} &= \begin{pmatrix} A_2 W_1^2 e^{-\alpha_1 W_1} & 0_{n \times n} \\ 2[A_2 W_1 e^{-\alpha_1 W_1} A_2 W_1 e^{-\alpha_1 W_1} + (A_2 e^{-\alpha_1 W_1} - I_n) A_2 W_1^2 e^{-\alpha_1 W_1}] & A_2 W_1^2 e^{-\alpha_1 W_1} \end{pmatrix} \\ \mathbf{D}_{\alpha_1 \alpha_2} &= \begin{pmatrix} -W_2 A_2 W_1 e^{-\alpha_1 W_1} & 0_{n \times n} \\ -2[W_2 A_2 e^{-\alpha_1 W_1} A_2 W_1 e^{-\alpha_1 W_1} + (A_2 e^{-\alpha_1 W_1} - I_n) W_2 A_2 W_1 e^{-\alpha_1 W_1}] & -W_2 A_2 W_1 e^{-\alpha_1 W_1} \end{pmatrix}, \end{aligned}$$

By Lemma A.1, $\mathbf{D}_{\alpha_1 \alpha_1}$ and $\mathbf{D}_{\alpha_1 \alpha_2}$ are uniformly bounded in a matrix norm in the neighborhood of $(\alpha_{10}, \alpha_{20})$, leading to $\frac{1}{n(T-1)}[\text{tr}(\mathbf{D}_{\alpha_1}(\bar{\alpha}_1, \bar{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_1) - \text{tr}(\mathbf{D}_{\alpha_1}(\alpha_{10}, \alpha_{20}) \mathbf{B}^{-1} \mathbf{W}_1)] = o_p(1)$. The rest of the first type are proved similarly. For the second type, for example $\text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21, \alpha_2})$, we similarly apply the mean value theorem and get the following:

$$\begin{aligned} & \frac{1}{n(T-1)}[\text{tr}(\mathbf{D}_{-1}(\bar{\alpha}_1, \bar{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_{21, \alpha_2}(\bar{\alpha}_1, \bar{\alpha}_2)) - \text{tr}(\mathbf{D}_{-1}(\alpha_{10}, \alpha_{20}) \mathbf{B}^{-1} \mathbf{W}_{21, \alpha_2}(\alpha_{10}, \alpha_{20}))] \\ &= \frac{1}{n(T-1)}[(\bar{\alpha}_1 - \alpha_{10})[\text{tr}(\mathbf{D}_{-1, \alpha_1}(\check{\alpha}_1, \check{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_{21, \alpha_2}(\check{\alpha}_1, \check{\alpha}_2)) + \text{tr}(\mathbf{D}(\check{\alpha}_1, \check{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_{21, \alpha_2 \alpha_1}(\check{\alpha}_1, \check{\alpha}_2))] \\ &+ (\bar{\alpha}_2 - \alpha_{20})[\text{tr}(\mathbf{D}_{-1, \alpha_2}(\check{\alpha}_1, \check{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_{21, \alpha_2}(\check{\alpha}_1, \check{\alpha}_2)) + \text{tr}(\mathbf{D}(\check{\alpha}_1, \check{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_{21, \alpha_2 \alpha_2}(\check{\alpha}_1, \check{\alpha}_2))]] \end{aligned}$$

where $\mathbf{D}_{-1,\alpha_1}(\check{\alpha}_1, \check{\alpha}_2)$ and $\mathbf{D}_{-1,\alpha_2}(\check{\alpha}_1, \check{\alpha}_2)$ are the derivatives of \mathbf{D}_{-1} with respect to α_1 and α_2 respectively and $\mathbf{W}_{21,\alpha_2\alpha_1}(\check{\alpha}_1, \check{\alpha}_2)$ and $\mathbf{W}_{21,\alpha_2\alpha_2}(\check{\alpha}_1, \check{\alpha}_2)$ are derivatives of \mathbf{W}_{21,α_2} with respect to α_1 and α_2 respectively, all evaluated at $(\check{\alpha}_1, \check{\alpha}_2)$. Again WLOG assuming $T=3$, we have

$$\begin{aligned}\mathbf{D}_{-1,\alpha_1} &= \begin{pmatrix} I_n & 0_{n \times n} \\ -e^{\alpha_2 W_2} W_1 e^{-\alpha_1 W_1} & I_n \end{pmatrix}, \quad \mathbf{D}_{-1,\alpha_2} = \begin{pmatrix} I_n & 0_{n \times n} \\ W_2 e^{\alpha_2 W_2} e^{-\alpha_1 W_1} & I_n \end{pmatrix}, \\ \mathbf{W}_{21,\alpha_2\alpha_1} &= \begin{pmatrix} -W_2^2 e^{\alpha_2 W_2} W_1 e^{-\alpha_1 W_1} & 0_{n \times n} \\ 0_{n \times n} & -W_2^2 e^{\alpha_2 W_2} W_1 e^{-\alpha_1 W_1} \end{pmatrix} \quad \text{and} \\ \mathbf{W}_{21,\alpha_2\alpha_2} &= \begin{pmatrix} W_2^3 e^{\alpha_2 W_2} e^{-\alpha_1 W_1} & 0_{n \times n} \\ 0_{n \times n} & W_2^3 e^{\alpha_2 W_2} e^{-\alpha_1 W_1} \end{pmatrix}.\end{aligned}$$

Here \mathbf{D}_{-1,α_1} , \mathbf{D}_{-1,α_2} , \mathbf{W}_{21,α_2} and $\mathbf{W}_{21,\alpha_2\alpha_1}$ are uniformly bounded in a matrix norm by Lemma A.1. So $\frac{1}{n(T-1)} [\text{tr}(\mathbf{D}_{-1}(\bar{\alpha}_1, \bar{\alpha}_2) \mathbf{B}^{-1} \mathbf{W}_{21,\alpha_2}(\bar{\alpha}_1, \bar{\alpha}_2)) - \text{tr}(\mathbf{D}_{-1}(\alpha_{10}, \alpha_{20}) \mathbf{B}^{-1} \mathbf{W}_{21,\alpha_2}(\alpha_{10}, \alpha_{20}))] = o_p(1)$. It follows that $\frac{1}{n(T-1)} [H^*(\bar{\theta}) - H^*(\theta_0)] = o_p(1)$.

Next let's prove $\frac{1}{n(T-1)} [H^*(\theta_0) - E(H^*(\theta_0))] = o_p(1)$. The term is comprised of differences of linear, bilinear or quadratic forms in ΔY , ΔY_{-1} or Δu and their expected values at the true values. For terms involving ΔY and ΔY_{-1} , using Lemma 3.1, they can be expressed as formulas of sums of terms linear in $\Delta \mathbf{y}_1$, quadratic in $\Delta \mathbf{y}_1$, bilinear in $\Delta \mathbf{y}_1$ and $\Delta \epsilon$ and quadratic in $\Delta \epsilon$. Using Lemma A.1, Lemma A.4 and Assumption 6, these terms are $o_p(1)$. For terms involving Δu , note $\Delta u = e^{-\alpha_{30} W_3} \Delta \epsilon = e^{-\alpha_{30} W_3} C \epsilon$, where C is an $n(T-1) \times nT$ matrix:

$$C = \begin{pmatrix} -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & -1 & 1 \end{pmatrix}. \quad (\text{C.5})$$

So we have, for example, $H_{\sigma_{\epsilon}^2 \alpha_3}^*(\theta_0) - E[H_{\sigma_{\epsilon}^2 \alpha_3}^*(\theta_0)] = \frac{1}{2\sigma_{\epsilon 0}^4} [\epsilon' C' \mathbf{e}^{\alpha_{30} \mathbf{W}_3} \mathbf{W}_3' (B^{-1} \otimes E_{30}) \mathbf{e}^{\alpha_{30} \mathbf{W}_3} C \epsilon - E(\epsilon' C' \mathbf{e}^{\alpha_{30} \mathbf{W}_3} \mathbf{W}_3' (B^{-1} \otimes E_{30}) \mathbf{e}^{\alpha_{30} \mathbf{W}_3} C \epsilon)]$. By Lemma A.3(v), $\frac{1}{n(T-1)} [H_{\sigma_{\epsilon}^2 \alpha_3}^*(\theta_0) - E(H_{\sigma_{\epsilon}^2 \alpha_3}^*(\theta_0))] = o_p(1)$. Similar proofs can be done for all other terms involving Δu . So $\frac{1}{n(T-1)} [H^*(\theta_0) - E(H^*(\theta_0))] = o_p(1)$.

Finally let's prove $\frac{1}{\sqrt{n(T-1)}} S^*(\theta_0) \xrightarrow{d} N[0, \lim_{n \rightarrow \infty} \Omega^*(\theta_0)]$. From (3.8) we know $S^*(\theta_0)$ consists of three types of components: $R' \Delta \epsilon$, $\Delta \epsilon' F \Delta \mathbf{y}_1$ and $\Delta \epsilon' O \Delta \epsilon$ where subscripts r for R_r , F_r and O_r are suppressed for simplicity. Partitioning them using matrix C in (C.5) above gives us the following: $R' \Delta \epsilon = \sum_{t=1}^T R_t' \epsilon_t$, $\Delta \epsilon' F \Delta \mathbf{y}_1 = \sum_{t=1}^T \epsilon_t' F_t^* \Delta \mathbf{y}_1$, $\Delta \epsilon' O \Delta \epsilon = \sum_{s=1}^T \sum_{t=1}^T \epsilon_t' O_t^* \epsilon_s$, where $R_t^* = R_t' C_t$, $F_t^* = C_t' F_t$ and $O_t^* = C_t' O_t C_t$ are $n \times k$, $n \times n$ and $n \times n$ partitioned matrices of $R' C$, $C' T$ and $C' O C$ respectively. By substituting $\Delta \mathbf{y}_1 = (e^{-\alpha_{10} W_1} A_2 - I_n) y_0 + c_1 + e^{-\alpha_{10} W_1} e^{\alpha_{30} W_3} \epsilon_1$ into $\epsilon_t' F_t^* \Delta \mathbf{y}_1$, where c_1 is a non-stochastic term, we get $\sum_{t=1}^T \epsilon_t' F_t^* \Delta \mathbf{y}_1 = \sum_{t=1}^T \epsilon_t' F_{t1}^* y_0 + \sum_{t=1}^T \epsilon_t' F_t^* c_1 + \sum_{t=1}^T \epsilon_t' F_{t2}^* \epsilon_1$. So for an $(k+5) \times 1$ vector of constants a , $a' S^*(\theta_0) = \sum_{s=1}^T \sum_{t=1}^T \epsilon_t' A_{ts} \epsilon_s + \sum_{t=1}^T \epsilon_t' B_t \epsilon_1 + \sum_{t=1}^T \epsilon_t' f(y_0) + a' d$ for nonstochastic matrices A_{ts} , B_t , vector d and $f(y_0)$ as a function

of y_0 . By Assumption 1, y_0 is independent of ϵ_t for $t = 1, \dots, T$. Also $\epsilon_1, \dots, \epsilon_T$ are independent of each other by Assumption 5. Hence $\frac{1}{n(T-1)} a' S^*(\theta_0)$ is asymptotically normal by Lemma A.4. Since every fixed linear combination of elements of $S^*(\theta_0)$ converges in distribution, by Cramer-Wold device, $\frac{1}{n(T-1)} S^*(\theta_0) \xrightarrow{d} N[0, \lim_{n \rightarrow \infty} \Omega^*(\theta_0)]$.

Proof of Theorem 3.3. To prove $\hat{\Omega}^* = \frac{1}{n(T-1)} \sum_{i=1}^n \hat{a}_i \hat{a}_i' \xrightarrow{p} \Omega^*(\theta_0) = \frac{1}{n(T-1)} \sum_{i=1}^n E(a_i a_i')$, we need to prove the following:

- (i) $\frac{1}{n(T-1)} \sum_{i=1}^n \hat{a}_i \hat{a}_i' \xrightarrow{p} \frac{1}{n(T-1)} \sum_{i=1}^n a_i a_i'$;
- (ii) $\frac{1}{n(T-1)} \sum_{i=1}^n a_i a_i' \xrightarrow{p} \frac{1}{n(T-1)} \sum_{i=1}^n E(a_i a_i')$.

Proof of (i): For $\bar{\theta}$ between $\hat{\theta}_M$ and θ_0 elementwise, we can utilize the mean value theorem to each of the elements in $\frac{1}{n(T-1)} \sum_{i=1}^n (\hat{a}_{li} \hat{a}_{mi}' - a_{li} a_{mi}')$ for $l, m = 1, 2, 3$ and prove each of them is $o_p(1)$. For example, for the first element when $l = m = 1$, $a_{11i} a_{11i}'$ is an $k \times k$ matrix where k is the number of regressors in ΔX , and $\frac{1}{n(T-1)} (\hat{a}_{11i} \hat{a}_{11i}' - a_{11i} a_{11i}') = -\frac{2}{n(T-1)} \bar{a}_{11i} \sum_{j=1}^k \sum_{t=2}^T \bar{R}_{it}' (\mathbf{e}^{\bar{\alpha}_3 \mathbf{W}_3} \Delta X_j)_{it} (\hat{\beta}_{jM} - \beta_{j0}) - \frac{2}{n(T-1)} \bar{a}_{11i} (\sum_{t=2}^T \frac{1}{\sigma_\epsilon^4} \bar{R}_{it}' \Delta \bar{\epsilon}_{it})' (\hat{\sigma}_{\epsilon, M}^2 - \sigma_{\epsilon 0}^2) - \frac{2}{n(T-1)} \bar{a}_{11i} [\sum_{t=2}^T \bar{R}_{it}' (\mathbf{e}^{\bar{\alpha}_3 \mathbf{W}_3} \Delta Y_{-1})_{it}]' (\hat{\tau}_M - \tau_0) + \frac{2}{n(T-1)} \bar{a}_{11i} [\sum_{t=2}^T \bar{R}_{it}' (\mathbf{e}^{\bar{\alpha}_3 \mathbf{W}_3} \mathbf{W}_1 \mathbf{e}^{\bar{\alpha}_3 \mathbf{W}_3} \Delta Y)_{it}]' (\hat{\alpha}_{1M} - \alpha_{10}) - \frac{2}{n(T-1)} \bar{a}_{11i} [\sum_{t=2}^T \bar{R}_{it}' (\mathbf{e}^{\bar{\alpha}_3 \mathbf{W}_3} \mathbf{W}_2 \mathbf{e}^{\bar{\alpha}_2 \mathbf{W}_2} \Delta Y_{-1})_{it}]' (\hat{\alpha}_{2M} - \alpha_{20}) + \frac{2}{n(T-1)} \bar{a}_{11i} [\sum_{t=2}^T [(\frac{1}{\sigma_\epsilon^2} (B^{-1} \otimes W_3 e^{\bar{\alpha}_3 \mathbf{W}_3}) \Delta X)_{it} \Delta \bar{\epsilon}_{it} + \bar{R}_{1it}' (\mathbf{W}_3 \Delta \bar{\epsilon})_{it}]]' (\hat{\alpha}_{3M} - \alpha_{30})$, where the terms with bars on top denote the values implied by $\bar{\theta}$ which is between θ_M and θ_0 . By model assumptions and Lemma A.1, all the multipliers before the differences of parameters $\hat{\theta}_M - \theta_0$ are $O_p(1)$. Since $\hat{\theta}_M - \theta_0 = o_p(1)$ by Theorem 3.1, $\frac{1}{n(T-1)} (\hat{a}_{11i} \hat{a}_{11i}' - a_{11i} a_{11i}') = o_p(1)$. The proofs for other terms follow similarly.

Proof of (ii): We need to prove $\frac{1}{n(T-1)} \sum_{i=1}^n [a_{li} a_{mi}' - E(a_{li} a_{mi}')] \xrightarrow{p} 0$ for $l, m = 1, 2, 3$. We will prove it for $l = m = 1$, $l = m = 2$ and $l = m = 3$ and the cross multiplied cases are done in a similar way. Before proceeding with the proof we define the following notations.

(1) For $n(T-1) \times 1$ vector $\Delta \epsilon$, we denote $\Delta \epsilon_{\cdot t}$ as the $n \times 1$ vector that selects all elements corresponding to period t and denote $\Delta \epsilon_{i \cdot}$ as the $(T-1) \times 1$ vector that selects all elements corresponding to individual i .

(2) For $n(T-1) \times n(T-1)$ matrix O , we denote $O_{t \cdot, s}$ as the $n \times n$ matrix that selects all elements corresponding to period (t, s) , denote $O_{i \cdot, j \cdot}$ as the $(T-1) \times (T-1)$ matrix that selects all elements corresponding to individual (i, j) and denote $O_{it, j \cdot}$ as the $(T-1) \times 1$ vector that is the t th column of $O_{i \cdot, j \cdot}$.

Then we can express a_{1i} , a_{2i} and a_{3i} as $a_{1i} = \sum_{t=2}^T R_{it}' \epsilon_{it} = R_{i \cdot} \Delta \epsilon_{i \cdot}$, $a_{2i} = \sum_{t=2}^T (\Delta \epsilon_{it} \Delta \eta_{it} + \Delta \epsilon_{it} \Delta \epsilon_{it}^* - \sigma_{\epsilon 0}^2 d_{it}) = \Delta \epsilon_{i \cdot}' \Delta \eta_{i \cdot} + \Delta \epsilon_{i \cdot}' \Delta \epsilon_{i \cdot}^* - \sigma_{\epsilon 0}^2 l_{T-1}' d_{i \cdot}$ and $a_{3i} = \Delta \epsilon_{2i} \Delta \xi_i + F_{2, ii}^{++} (\Delta \epsilon_{2i} \Delta y_{1i}^* + \sigma_{\epsilon 0}^2) + \sum_{t=3}^T \Delta \epsilon_{it} \Delta y_{1it}^* = \Delta \epsilon_{2i} \Delta \xi_i + F_{2, ii}^{++} (\Delta \epsilon_{2i} \Delta y_{1i}^* + \sigma_{\epsilon 0}^2) + \Delta \epsilon_{i \cdot}' \Delta y_{1i \cdot}^*$, where $-$ in $\Delta y_{1i \cdot}^*$ denotes the selection of all element from $t = 3$ to T . These expressions will be convenient to use in the proof below.

For a_{1i} , $\frac{1}{n(T-1)} \sum_{i=1}^n [a_{1i} a_{1i}' - E(a_{1i} a_{1i}')] = \frac{1}{n(T-1)} \sum_{i=1}^n R_{i \cdot}' (\Delta \epsilon_{i \cdot} \Delta \epsilon_{i \cdot}' - \sigma_{\epsilon 0}^2 B) R_{i \cdot} = \frac{1}{n(T-1)} \sum_{i=1}^n z_{n, i}$. Note $z_{n, i}$ is a MDS since $\{z_{n, i}\}$ are independent and $E(z_{n, i}) = 0$. Given Assumption 6, we know from Lemma A.1 that the elements of $R_{i \cdot}$ are uniformly bounded in row and

column sums. Then $E|z_{n,i}|^{1+\zeta}$ is bounded above by some constant for $\zeta > 0$ which implies $z_{n,i}$ is uniformly integrable. Also for the multiplying coefficient, $\limsup_{n \rightarrow \infty} \sum_{i=1}^n \frac{1}{n(T-1)} = \frac{1}{T-1} < \infty$ and $\lim_{n \rightarrow \infty} \sum_{i=1}^n [\frac{1}{n(T-1)}]^2 = \lim_{n \rightarrow \infty} \frac{1}{n(T-1)^2} = 0$. By Theorem 19.7 on Weak Law of Large Numbers for MD array (Davidson, 1994), $\frac{1}{n(T-1)} \sum_{i=1}^n z_{n,i} \xrightarrow{p} 0$.

For a_{2i} , first note $E(\Delta\epsilon'_i \Delta\eta_i) = 0$ for $i = 1, \dots, n$ because each multiplying group of elements in $\Delta\epsilon_i$ and $\Delta\eta_i$ are from different individuals. Then we have $\frac{1}{n(T-1)} \sum_{i=1}^n [a_{2i}^2 - E(a_{2i}^2)] = \frac{1}{n(T-1)} \sum_{i=1}^n [((\Delta\epsilon'_i \Delta\eta_i)^2 - E(\Delta\epsilon'_i \Delta\eta_i)^2) + ((\Delta\epsilon'_i \Delta\epsilon_i^*)^2 - E(\Delta\epsilon'_i \Delta\epsilon_i^*)^2) + 2(\Delta\epsilon'_i \Delta\eta_i)(\Delta\epsilon'_i \Delta\epsilon_i^*) - 2\sigma_{\epsilon_0}^2 l'_{T-1} d_i (\Delta\epsilon'_i \Delta\eta_i) - 2(\sigma_{\epsilon_0}^2 l'_{T-1} d_i (\Delta\epsilon'_i \Delta\epsilon_i^* - E(\Delta\epsilon'_i \Delta\epsilon_i^*)))]$. We can prove that each of the five terms is $o_p(1)$. For example, for the first term, subtracting and adding a same term and noticing $E(\Delta\epsilon_i \Delta\epsilon'_i) = \sigma_{\epsilon_0}^2 B$, it equals $\frac{1}{n(T-1)} \sum_{i=1}^n \Delta\eta'_i (\Delta\epsilon_i \Delta\epsilon'_i - \sigma_{\epsilon_0}^2 B) \Delta\eta_i + \frac{\sigma_{\epsilon_0}^2}{n(T-1)} \sum_{i=1}^n [\Delta\eta'_i B \Delta\eta_i - E(\Delta\eta'_i B \Delta\eta_i)]$. Let $N_{n,i} = \Delta\eta'_i (\Delta\epsilon_i \Delta\epsilon'_i - \sigma_{\epsilon_0}^2 B) \Delta\eta_i$. Since $\Delta\eta_i$ is $\Pi_{n,i-1}$ measurable, $E(N_{n,i} | \Pi_{n,i-1}) = 0$. To be a MD array, it is also necessary that $E(N_{n,i}) < \infty$ (e.g. Davidson (1994) p232), which is obviously satisfied. Thus $\{N_{n,i}, \Pi_{n,i-1}\}$ is a MD array. Also $E|N_{n,i}^{1+\zeta}|$ is bounded above by some positive constant for some $\zeta > 0$. So $\{N_{n,i}\}$ is uniformly integrable. The multiplier $\frac{1}{n(T-1)}$ is shown in proof of a_{1i} to satisfy the other two conditions of Theorem 19.7 in Davidson (1994). So $\frac{1}{n(T-1)} \sum_{i=1}^n N_{n,i} = o_p(1)$.

For the second term, we can express $\Delta\eta'_i B \Delta\eta_i = \sum_{t=1}^{T-1} \sum_{s=1}^{T-1} \Delta\eta_{it} B_{ts} \Delta\eta_{it}$, where $\Delta\eta_{it}$ is the i th element of the $n \times 1$ vector $\Delta\eta_t = \sum_{s=2}^T (O_{st}^u + O_{ts}^l) \Delta\epsilon_s$. Here O is an $n(T-1) \times n(T-1)$ matrix and O_{st} is its st th $n \times n$ block matrix. So $\Delta\eta_{it} = \sum_{s=2}^T \sum_{j=1}^{i-1} (O_{js,it} + O_{it,j,s}) \Delta\epsilon_{js} = \sum_{j=1}^{i-1} \sum_{s=2}^T (O_{js,it} + O_{it,j,s}) \Delta\epsilon_{js} = \sum_{j=1}^{i-1} O'_{ijt} \Delta\epsilon_j$, where $O_{ijt} = O_{j,it} + O_{it,j}$. Then for $\Delta\eta_{is} = \Delta\eta_{it}$, we have $(\Delta\eta_{it})^2 - E[(\Delta\eta_{it})^2] = \sum_{j=1}^{i-1} O'_{ijt} (\Delta\epsilon_j \Delta\epsilon'_j - \sigma_{\epsilon_0}^2 B) O_{ijt} + 2 \sum_{j=1}^{i-1} \sum_{k=1}^{j-1} O'_{ijt} \Delta\epsilon'_j \Delta\epsilon'_k O_{ikt}$, which implies

$$\begin{aligned} & \frac{1}{n(T-1)} \sum_{i=1}^n [(\Delta\eta_{it})^2 - E((\Delta\eta_{it})^2)] \\ &= \frac{1}{n(T-1)} \sum_{i=1}^n \left[\sum_{j=1}^{i-1} O'_{ijt} (\Delta\epsilon_j \Delta\epsilon'_j - \sigma_{\epsilon_0}^2 B) O_{ijt} + 2 \sum_{j=1}^{i-1} \sum_{k=1}^{j-1} \Delta\epsilon'_j O_{ijt} O'_{ikt} \Delta\epsilon_k \right] \\ &= \frac{1}{n(T-1)} \sum_{j=1}^{n-1} \left[\sum_{i=j+1}^n [O'_{ijt} (\Delta\epsilon_j \Delta\epsilon'_j - \sigma_{\epsilon_0}^2 B) O_{ijt}] \right] + \frac{2}{n(T-1)} \sum_{j=1}^{n-1} \Delta\epsilon'_j \sum_{i=j+1}^n \sum_{k=1}^{j-1} O_{ijt} O'_{ikt} \Delta\epsilon_k. \end{aligned}$$

Now the terms in the summation in the first element are independent, and $\sum_{i=j+1}^n \sum_{k=1}^{j-1} O_{ijt} O'_{ikt} \Delta\epsilon_k$ is $\Pi_{n,j-1}$ -measurable. By Theorem 19.7 in Davidson (1994), $\frac{1}{n(T-1)} \sum_{i=1}^n [(\Delta\eta_{it})^2 - E((\Delta\eta_{it})^2)] = o_p(1)$. Similar proofs can be done for $\Delta\eta_{is} \neq \Delta\eta_{it}$. Thus $\frac{1}{n(T-1)} \sum_{i=1}^n [\Delta\eta'_i B \Delta\eta_i - E(\Delta\eta'_i B \Delta\eta_i)] = o_p(1)$. It follows that the first term in $\frac{1}{n(T-1)} \sum_{i=1}^n [a_{2i}^2 - E(a_{2i}^2)]$ is $o_p(1)$. The proofs for the second and the fifth term are similar to that of the first element of the first term, the proofs for the third and fourth terms are similar to that of the second element of the first term and thus they are omitted.

For a_{3i} , we have:

$$\begin{aligned}
& \frac{1}{n(T-1)} \sum_{i=1}^n [a_{3i}^2 - E(a_{3i}^2)] \\
&= \frac{1}{n(T-1)} \sum_{i=1}^n (\Delta \epsilon_{2i}^2 \Delta \xi_i^2 - 2\sigma_{\epsilon 0}^2 \Delta \xi_i^2) + \frac{2}{n(T-1)} \sum_{i=1}^n [\sigma_{\epsilon 0}^2 (\Delta \xi_i^2 - E(\Delta \xi_i^2))] \\
&+ \frac{1}{n(T-1)} \sum_{i=1}^n (F_{2,ii}^{++})^2 [\Delta \epsilon_{2i} \Delta y_{1i}^\diamond - E(\Delta \epsilon_{2i} \Delta y_{1i}^\diamond)^2] \\
&+ \frac{1}{n(T-1)} \sum_{i=1}^n [(\Delta \epsilon'_{i-} \Delta y_{1i-}^*)^2 - E(\Delta \epsilon'_{i-} \Delta y_{1i-}^*)^2] \\
&+ \frac{2}{n(T-1)} \sum_{i=1}^n [F_{2,ii}^{++} \Delta \epsilon_{2i}^2 \Delta \xi_i \Delta y_{1i}^\diamond - E(F_{2,ii}^{++} \Delta \epsilon_{2i}^2 \Delta \xi_i \Delta y_{1i}^\diamond)] \\
&+ \frac{2}{n(T-1)} \sum_{i=1}^n [\sigma_{\epsilon 0}^2 (F_{2,ii}^{++} \Delta \epsilon_{2i} \Delta \xi_i)] \\
&+ \frac{2}{n(T-1)} \sum_{i=1}^n [(\Delta \epsilon_{2i} \Delta \xi_i \Delta \epsilon'_{i-} \Delta y_{1i-}^*) - E(\Delta \epsilon_{2i} \Delta \xi_i \Delta \epsilon'_{i-} \Delta y_{1i-}^*)] \\
&+ \frac{2}{n(T-1)} \sum_{i=1}^n \{F_{2,ii}^{++} \sigma_{\epsilon 0}^2 [\Delta \epsilon_{2i} \Delta y_{1i}^\diamond - E(\Delta \epsilon_{2i} \Delta y_{1i}^\diamond)]\} \\
&+ \frac{2}{n(T-1)} \sum_{i=1}^n \{F_{2,ii}^{++} [\Delta \epsilon_{2i} \Delta y_{1i}^\diamond \Delta \epsilon'_{i-} \Delta y_{1i-}^* - E(\Delta \epsilon_{2i} \Delta y_{1i}^\diamond \Delta \epsilon'_{i-} \Delta y_{1i-}^*)]\} \\
&+ \frac{2}{n(T-1)} \sum_{i=1}^n [F_{2,ii}^{++} \sigma_{\epsilon 0}^2 (\Delta \epsilon'_{i-} \Delta y_{1i-}^* - E(\Delta \epsilon'_{i-} \Delta y_{1i-}^*))],
\end{aligned}$$

where we subtracted and added $\frac{2}{n(T-1)} \sum_{i=1}^n \sigma_{\epsilon 0}^2 \Delta \xi_i^2$ and used the fact that $F_{2,ii}^{++}$ is nonstochastic.

Note $\Delta \xi_i^2$ is $\Phi_{n,i-1}$ -measurable, which implies that the first term is the average of a MD array. By Theorem 19.7 in Davidson (1994), the first term is $o_p(1)$. The sixth term is thus also convergent. Note $\Delta \xi = (F_2^{++u} + F_2^{++l}) \Delta y_1^\diamond = (F_2^{++u} + F_2^{++l}) e^{\alpha_{30} W_3} e^{\alpha_{10} W_1} \Delta y_1$, so the second term equals $\frac{2}{n(T-1)} \sum_{i=1}^n [\sigma_{\epsilon 0}^2 (\Delta y_1' e^{\alpha_{10} W_1} e^{\alpha_{30} W_3} (F_2^{++u} + F_2^{++l})' (F_2^{++u} + F_2^{++l}) e^{\alpha_{30} W_3} e^{\alpha_{10} W_1} \Delta y_1 - E(\Delta y_1' e^{\alpha_{10} W_1} e^{\alpha_{30} W_3} (F_2^{++u} + F_2^{++l})' (F_2^{++u} + F_2^{++l}) e^{\alpha_{30} W_3} e^{\alpha_{10} W_1} \Delta y_1))]$. Since $e^{\alpha_{10} W_1} e^{\alpha_{30} W_3} (F_2^{++u} + F_2^{++l})' (F_2^{++u} + F_2^{++l}) e^{\alpha_{30} W_3} e^{\alpha_{10} W_1}$ is uniformly bounded in row and column sums by Lemma A.1, the convergence of the second term follows from Assumption 6. For the third, fifth and eighth term, we can substitute $\Delta y_1^\diamond = e^{\alpha_{30} W_3} e^{\alpha_{10} W_1} \Delta y_0 + e^{\alpha_{30} W_3} \Delta X_1 \beta_0 + \Delta \epsilon_1$ in them and prove they are convergent. For the fourth and tenth term, we can prove they are convergent using Assumption 6 since $\Delta \epsilon_{i-}$ are from $t = 3$ to T and Δy_{1i-}^* is constructed based on Δy_1 which implies they are independent. For the seventh and ninth term, note $\Delta y_{1t}^* = F_t^+ \Delta y_1 = F_t^+ \Delta y_0 + F_t^+ e^{-\alpha_{10} W_1} \Delta X_1 \beta_0 + F_t^+ e^{-\alpha_{10} W_1} e^{-\alpha_{30} W_3} \Delta \epsilon_1$. The convergence follows.

D Estimation of Submodels

The M-estimation proposed in the main paper can be modified to incorporate different submodels by getting rid of matrix exponential in dependent variable, lagged dependent variable and/or disturbance. In this part of the appendix we describe the estimation of submodels used in the Monte Carlo simulation.

MESDPS(1,0,0). By setting $\alpha_2 = 0$ and $\alpha_3 = 0$ we get MESDPS(1,0,0). Let $\mathbf{A}_0 = I_{t-1} \otimes A_0$ with $A_0 = \tau_0 + 1$. The first differenced model is given by

$$\mathbf{e}^{\alpha_{10}\mathbf{W}_1}\Delta Y = \mathbf{A}_0\Delta Y_{-1} + \Delta X\beta_0 + \Delta\epsilon, \quad (\text{D.1})$$

and the conditional quasi loglikelihood is thus given by

$$\ell_{(1,0,0)}(\theta) = -\frac{n(T-1)}{2}\log(\sigma_\epsilon^2) - \frac{1}{2\sigma_\epsilon^2}\Delta\epsilon(\phi)'\mathbf{B}^{-1}\Delta\epsilon(\phi), \quad (\text{D.2})$$

where $\theta = (\beta', \sigma_\epsilon^2, \tau, \alpha_1)'$, $\phi = (\beta', \tau, \alpha_1)'$, $\mathbf{B} = B \otimes I_n$ and $\Delta\epsilon(\phi) = \mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y - \mathbf{A}\Delta Y_{-1} - \Delta X\beta$. Given $\zeta = (\tau, \alpha_1)'$, the estimators of β and σ_ϵ^2 are given by

$$\tilde{\beta}(\zeta) = (\Delta X'\mathbf{B}^{-1}\Delta X)^{-1}\Delta X'\mathbf{B}^{-1}(\mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y - \mathbf{A}\Delta Y_{-1}), \quad (\text{D.3})$$

$$\tilde{\sigma}_\epsilon^2(\zeta) = \frac{1}{n(T-1)}\Delta\tilde{\epsilon}(\zeta)'\mathbf{B}^{-1}\Delta\tilde{\epsilon}(\zeta), \quad (\text{D.4})$$

where $\Delta\tilde{\epsilon}(\zeta) = \mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y - \mathbf{A}\Delta Y_{-1} - \Delta X\tilde{\beta}(\zeta)$. Substituting them back into (D.2), ignoring constants, the concentrated log-likelihood function is derived as:

$$l_{(1,0,0)}^c(\zeta) = -\log[\Delta\tilde{\epsilon}(\zeta)'\mathbf{B}^{-1}\Delta\tilde{\epsilon}(\zeta)], \quad (\text{D.5})$$

Maximizing (D.5) gives us CQMLE $\tilde{\zeta}$ and then CQMLEs $\tilde{\beta} = \tilde{\beta}(\tilde{\zeta})$ and $\tilde{\sigma}_\epsilon^2 = \tilde{\sigma}_\epsilon^2(\tilde{\zeta})$.

The conditional quasi score (CQS) function corresponding to (2.11) in the paper is given by

$$S_{(1,0,0)}(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2}\Delta X'\mathbf{B}^{-1}\Delta\epsilon(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4}\Delta\epsilon(\phi)'\mathbf{B}^{-1}\Delta\epsilon(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2}\Delta\epsilon(\phi)'\mathbf{B}^{-1}\Delta Y_{-1}, \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2}\Delta\epsilon(\phi)'\mathbf{B}^{-1}\mathbf{W}_1\mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y. \end{cases}$$

Note here the expectations in Lemma 2.1 reduce to $E(\Delta Y\Delta\epsilon') = -\sigma_{\epsilon 0}^2\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\mathbf{D}_0$ and $E(\Delta Y_{-1}\Delta\epsilon') = -\sigma_{\epsilon 0}^2\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\mathbf{D}_{-1,0}$, where $\mathbf{D}_0 =$

$$\begin{pmatrix} A_0e^{-\alpha_{10}W_1} - 2I_n & I_n & \dots & \dots & 0 \\ (A_0e^{-\alpha_{10}W_1} - I_n)^2 & A_0e^{-\alpha_{10}W_1} - 2I_n & \ddots & \dots & \vdots \\ \vdots & \vdots & \ddots & \ddots & I_n \\ (A_0e^{-\alpha_{10}W_1})^{T-3}(A_0e^{-\alpha_{10}W_1} - I_n)^2 & \dots & \dots & (A_0e^{-\alpha_{10}W_1} - I_n)^2 & A_0e^{-\alpha_{10}W_1} - 2I_n \end{pmatrix},$$

$$\text{and } \mathbf{D}_{-1,0} = \begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_0 e^{-\alpha_{10} W_1} - 2I_n & I_n & \ddots & \dots & \vdots \\ (A_0 e^{-\alpha_{10} W_1} - I_n)^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ (A_0 e^{-\alpha_{10} W_1})^{T-4} (A_0 e^{-\alpha_{10} W_1} - I_n)^2 & \dots & (A_0 e^{-\alpha_{10} W_1} - I_n)^2 & A_0 e^{-\alpha_{10} W_1} - 2I_n & I_n \end{pmatrix}.$$

The adjusted quasi score (AQS) corresponding to (2.15) in the paper is thus given by

$$S_{(1,0,0)}^*(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \end{cases}$$

Given $\zeta = (\tau, \alpha_1)'$, the constrained M-estimators of β and σ_ϵ^2 are first solved as

$$\hat{\beta}_M(\zeta) = (\Delta X' \mathbf{B}^{-1} \Delta X)^{-1} \Delta X' \mathbf{B}^{-1} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.6})$$

$$\hat{\sigma}_{\epsilon,M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \hat{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta \hat{\epsilon}(\zeta), \quad (\text{D.7})$$

where $\Delta \hat{\epsilon}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \hat{\beta}_M(\zeta)$. Then $\hat{\beta}_M(\zeta)$ and $\hat{\sigma}_{\epsilon,M}^2(\zeta)$ are substituted back into the third and fourth elements of the AQS function to get the concentrated AQS function:

$$S_{(1,0,0)}^*(\zeta) = \begin{cases} \tau : & \frac{1}{\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_1 : & -\frac{1}{\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{\epsilon}(\zeta)' \mathbf{B}^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1) \end{cases}$$

The unconstrained M-estimators $\hat{\tau}_M$ and $\hat{\alpha}_{1M}$ can be solved by letting $S_{(1,0,0)}^{*c}(\zeta) = 0$ and consequently the unconstrained M-estimators $\hat{\beta}_M = \hat{\beta}_M(\hat{\zeta}_M)$ and $\hat{\sigma}_{\epsilon,M}^2 = \hat{\sigma}_{\epsilon,M}^2(\hat{\zeta}_M)$.

MESDPS(0,1,0). By setting $\alpha_1 = 0$ and $\alpha_3 = 0$, MESDPS(0,1,0) appears. Let $\mathbf{A}_0 = I_{T-1} \otimes A_0$ with $A_0 = \tau_0 I_n + e^{\alpha_{20} W_2}$. The first differenced model is given by

$$\Delta Y = \mathbf{A}_0 \Delta Y_{-1} + \Delta X \beta_0 + \Delta \epsilon,$$

and the conditional quasi loglikelihood is subsequently given by

$$\ell_{(0,1,0)}(\theta) = -\frac{n(T-1)}{2} \log(\sigma_\epsilon^2) - \frac{1}{2\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta \epsilon(\phi), \quad (\text{D.8})$$

where $\theta = (\beta', \sigma_\epsilon^2, \tau, \alpha_2)'$, $\phi = (\beta', \tau, \alpha_2)'$, $\mathbf{B} = B \otimes I_n$ and $\Delta \epsilon(\phi) = \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \beta$. Given

$\zeta = (\tau, \alpha_2)'$, the estimators of β and σ_ϵ^2 are given by

$$\tilde{\beta}(\zeta) = (\Delta X' \mathbf{B}^{-1} \Delta X)^{-1} \Delta X' \mathbf{B}^{-1} (\Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.9})$$

$$\tilde{\sigma}_\epsilon^2(\zeta) = \frac{1}{n(T-1)} \Delta \tilde{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta \tilde{\epsilon}(\zeta), \quad (\text{D.10})$$

where $\Delta \tilde{\epsilon}(\zeta) = \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \tilde{\beta}(\zeta)$. Substituting them back into (D.8), ignoring constants, the concentrated log-likelihood function is:

$$l_{(0,1,0)}^c(\zeta) = -\log[\Delta \tilde{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta \tilde{\epsilon}(\zeta)], \quad (\text{D.11})$$

Maximizing (D.11) gives us CQMLE $\tilde{\zeta}$ and then CQMLEs $\tilde{\beta} = \tilde{\beta}(\tilde{\zeta})$ and $\tilde{\sigma}_\epsilon^2 = \tilde{\sigma}_\epsilon^2(\tilde{\zeta})$.

The conditional quasi score (CQS) function corresponding to (2.11) in the paper is given by

$$S_{(0,1,0)}(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta Y_{-1}, \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}. \end{cases}$$

In this case the expectation in Lemma 2.1 reduces to $E(\Delta Y_{-1} \Delta \epsilon') = -\sigma_{\epsilon 0}^2 \mathbf{D}_{-1,0}$, where

$$\mathbf{D}_{-1,0} = \begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_0 - 2I_n & I_n & \ddots & \dots & \vdots \\ (A_0 - I_n)^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ (A_0)^{T-4} (A_0 - I_n)^2 & \dots & (A_0 - I_n)^2 & A_0 - 2I_n & I_n \end{pmatrix}, \text{ and}$$

$$\mathbf{D}_0 = \begin{pmatrix} A_0 - 2I_n & I_n & \dots & \dots & 0 \\ (A_0 - I_n)^2 & A_0 - 2I_n & \ddots & \dots & \vdots \\ \vdots & \vdots & \ddots & \ddots & I_n \\ A_0^{T-3} (A_0 - I_n)^2 & \dots & \dots & (A_0 - I_n)^2 & A_0 - 2I_n \end{pmatrix}.$$

The adjusted quasi score (AQS) corresponding to (2.15) in the paper is then given by

$$S_{(0,1,0)}^*(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1}), \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2}). \end{cases}$$

To derive the M-estimator, the constrained M-estimators of β and σ_ϵ^2 are first solved as

$$\widehat{\beta}_M(\zeta) = (\Delta X' \mathbf{B}^{-1} \Delta X)^{-1} \Delta X' \mathbf{B}^{-1} (\Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.12})$$

$$\widehat{\sigma}_{\epsilon, M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \widehat{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta \widehat{\epsilon}(\zeta), \quad (\text{D.13})$$

where $\Delta \widehat{\epsilon}(\zeta) = \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \widehat{\beta}_M(\zeta)$. Then $\widehat{\beta}_M(\zeta)$ and $\widehat{\sigma}_{\epsilon, M}^2(\zeta)$ are substituted back into the third and fourth elements of the AQS function:

$$S_{(0,1,0)}^{*c}(\zeta) = \begin{cases} \tau : & \frac{1}{\widehat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \widehat{\epsilon}(\zeta)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1}), \\ \alpha_2 : & \frac{1}{\widehat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \widehat{\epsilon}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2}), \end{cases}$$

which is the concentrated AQS function. The unconstrained M-estimators $\widehat{\zeta}_M$ can be solved by letting $S_{(0,1,0)}^{*c}(\zeta) = 0$. The unconstrained M-estimators are then derived as $\widehat{\beta}_M = \widehat{\beta}_M(\widehat{\zeta}_M)$ and $\widehat{\sigma}_{\epsilon, M}^2 = \widehat{\sigma}_{\epsilon, M}^2(\widehat{\zeta}_M)$.

MESDPS(1,1,0). By setting $\alpha_3 = 0$, MESDPS(1,1,0) appears. Again let $\mathbf{A}_0 = I_{T-1} \otimes A_0$ with $A_0 = \tau_0 I_n + e^{\alpha_{20} \mathbf{W}_2}$. The first differenced model is given by

$$\mathbf{e}^{\alpha_{10} \mathbf{W}_1} \Delta Y = \mathbf{A}_0 \Delta Y_{-1} + \Delta X \beta_0 + \Delta \epsilon,$$

and the conditional quasi loglikelihood is thus given by

$$\ell_{(1,1,0)}(\theta) = -\frac{n(T-1)}{2} \log(\sigma_\epsilon^2) - \frac{1}{2\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta \epsilon(\phi), \quad (\text{D.14})$$

where $\theta = (\beta', \sigma_\epsilon^2, \tau, \alpha_1, \alpha_2)'$, $\phi = (\beta', \tau, \alpha_1, \alpha_2)'$, $\mathbf{B} = B \otimes I_n$ and $\Delta \epsilon(\phi) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \beta$. Given $\zeta = (\tau, \alpha_1, \alpha_2)'$, the estimators of β and σ_ϵ^2 are given by

$$\widetilde{\beta}(\zeta) = (\Delta X' \mathbf{B}^{-1} \Delta X)^{-1} \Delta X' \mathbf{B}^{-1} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.15})$$

$$\widetilde{\sigma}_\epsilon^2(\zeta) = \frac{1}{n(T-1)} \Delta \widetilde{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta \widetilde{\epsilon}(\zeta), \quad (\text{D.16})$$

where $\Delta \widetilde{\epsilon}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \widetilde{\beta}(\zeta)$. Substituting them back into (D.14), ignoring constants, the concentrated log-likelihood function is given by:

$$l_{(1,1,0)}^c(\zeta) = -\log[\Delta \widetilde{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta \widetilde{\epsilon}(\zeta)]. \quad (\text{D.17})$$

Maximizing (D.17) gives us CQMLE $\widetilde{\zeta}$, with the implied CQMLEs $\widetilde{\beta} = \widetilde{\beta}(\widetilde{\zeta})$ and $\widetilde{\sigma}_\epsilon^2 = \widetilde{\sigma}_\epsilon^2(\widetilde{\zeta})$.

Correspondingly, the conditional quasi score (CQS) function (2.11) in the paper becomes

$$S_{(1,1,0)}(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta Y_{-1}, \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y, \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}. \end{cases}$$

Here the expectations in Lemma 2.1 are simplified to $E(\Delta Y \Delta \epsilon') = -\sigma_{\epsilon_0}^2 \mathbf{e}^{-\alpha_1 \mathbf{W}_1} \mathbf{D}_0$ and $E(\Delta Y_{-1} \Delta \epsilon') = -\sigma_{\epsilon_0}^2 \mathbf{e}^{-\alpha_1 \mathbf{W}_1} \mathbf{D}_{-1,0}$, where \mathbf{D}_0 and $\mathbf{D}_{-1,0}$ have the same expression as those in Lemma 2.1.

The adjusted quasi score (AQS) in (2.15) in the main paper is then reduced to

$$S_{(1,1,0)}^*(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \Delta \epsilon(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} \Delta \epsilon(\phi)' \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \end{cases}$$

where $\mathbf{W}_{21} = \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}$. To derive the M-estimator, the constrained M-estimators of β and σ_ϵ^2 are first solved as

$$\hat{\beta}_M(\zeta) = (\Delta X' \mathbf{B}^{-1} \Delta X)^{-1} \Delta X' \mathbf{B}^{-1} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.18})$$

$$\hat{\sigma}_{\epsilon,M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \hat{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta \hat{\epsilon}(\zeta), \quad (\text{D.19})$$

where $\Delta \hat{\epsilon}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \hat{\beta}_M(\zeta)$. Then $\hat{\beta}_M(\zeta)$ and $\hat{\sigma}_{\epsilon,M}^2(\zeta)$ are substituted back into the rest of the AQS function to get the concentrated AQS function:

$$S_{(1,1,0)}^{*c}(\zeta) = \begin{cases} \tau : & \frac{1}{\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{\epsilon}(\zeta)' \mathbf{B}^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_1 : & -\frac{1}{\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{\epsilon}(\zeta) \mathbf{B}^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \alpha_2 : & \frac{1}{\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{\epsilon}(\zeta) \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}). \end{cases}$$

The unconstrained M-estimators $\hat{\zeta}_M$ can be solved by letting $S_{(1,1,0)}^{*c}(\zeta) = 0$ and then $\hat{\beta}_M = \hat{\beta}_M(\hat{\zeta}_M)$ and $\hat{\sigma}_{\epsilon,M}^2 = \hat{\sigma}_{\epsilon,M}^2(\hat{\zeta}_M)$.

MESDPS(1,0,1). By setting $\alpha_2 = 0$, we have MESDPS(1,0,1). Here let $\mathbf{A}_0 = I_{t-1} \otimes A_0$ with

$A_0 = \tau_0 + 1$. The first differenced model is given by

$$\mathbf{e}^{\alpha_{10}\mathbf{W}_1}\Delta Y = \mathbf{A}_0\Delta Y_{-1} + \Delta X\beta_0 + \Delta u, \quad \mathbf{e}^{\alpha_{30}\mathbf{W}_3}\Delta u = \Delta\epsilon,$$

and the conditional quasi loglikelihood is thus given by

$$\ell_{(1,0,1)}(\theta) = -\frac{n(T-1)}{2}\log(\sigma_\epsilon^2) - \frac{1}{2\sigma_\epsilon^2}\Delta u(\phi)'\Sigma(\alpha_3)^{-1}\Delta u(\phi), \quad (\text{D.20})$$

where $\theta = (\beta', \sigma_\epsilon^2, \tau, \alpha_1, \alpha_3)'$, $\phi = (\beta', \tau, \alpha_1)'$, $\Sigma(\alpha_3) = B \otimes e^{-\alpha_3\mathbf{W}_3}e^{-\alpha_3\mathbf{W}_3'}$, and $\Delta u(\phi) = \mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y - \mathbf{A}\Delta Y_{-1} - \Delta X\beta$. Given $\zeta = (\tau, \alpha_1, \alpha_3)'$, the estimators of β and σ_ϵ^2 are given by

$$\tilde{\beta}(\zeta) = (\Delta X'\Sigma(\alpha_3)^{-1}\Delta X)^{-1}\Delta X'\Sigma(\alpha_3)^{-1}(\mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y - \mathbf{A}\Delta Y_{-1}), \quad (\text{D.21})$$

$$\tilde{\sigma}_\epsilon^2(\zeta) = \frac{1}{n(T-1)}\Delta\tilde{\epsilon}(\zeta)'\Sigma(\alpha_3)^{-1}\Delta\tilde{\epsilon}(\zeta), \quad (\text{D.22})$$

where $\Delta\tilde{\epsilon}(\zeta) = \mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y - \mathbf{A}\Delta Y_{-1} - \Delta X\tilde{\beta}(\zeta)$. Substituting them back into (D.20), ignoring constants, the concentrated log-likelihood function is given by:

$$l_{(1,0,1)}^c(\zeta) = -\log[\Delta\tilde{u}(\zeta)'\Sigma(\alpha_3)^{-1}\Delta\tilde{u}(\zeta)], \quad (\text{D.23})$$

Maximizing (D.23) gives us CQMLE $\tilde{\zeta}$ and then the implied CQMLEs $\tilde{\beta} = \tilde{\beta}(\tilde{\zeta})$ and $\tilde{\sigma}_\epsilon^2 = \tilde{\sigma}_\epsilon^2(\tilde{\zeta})$.

Correspondingly, the conditional quasi score (CQS) function (2.11) in the paper becomes

$$S_{(1,0,1)}(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2}\Delta X'\Sigma(\alpha_3)^{-1}\Delta u(\phi), \\ \sigma_\epsilon^2 : & \frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4}\Delta u(\phi)'\Sigma(\alpha_3)^{-1}\Delta u(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2}\Delta u(\phi)'\Sigma^{-1}\Delta Y_{-1}, \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2}\Delta u(\phi)'\Sigma(\alpha_3)^{-1}\mathbf{W}_1\mathbf{e}^{\alpha_1\mathbf{W}_1}\Delta Y, \\ \alpha_3 : & -\frac{1}{2\sigma_\epsilon^2}\Delta u(\phi)'(B^{-1} \otimes E_3)\Delta u(\phi). \end{cases}$$

Now the expectations in Lemma 2.1 become $E(\Delta Y\Delta\epsilon') = -\sigma_{\epsilon 0}^2\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\mathbf{D}_0\mathbf{e}^{-\alpha_{30}\mathbf{W}_3}$ and $E(\Delta Y_{-1}\Delta\epsilon') = -\sigma_{\epsilon 0}^2\mathbf{e}^{-\alpha_{10}\mathbf{W}_1}\mathbf{D}_{-1,0}\mathbf{e}^{-\alpha_{30}\mathbf{W}_3}$, where $\mathbf{D}_0 =$

$$\begin{pmatrix} A_0e^{-\alpha_{10}\mathbf{W}_1} - 2I_n & I_n & \dots & \dots & 0 \\ (A_0e^{-\alpha_{10}\mathbf{W}_1} - I_n)^2 & A_0e^{-\alpha_{10}\mathbf{W}_1} - 2I_n & \ddots & \dots & \vdots \\ \vdots & \vdots & \ddots & \ddots & I_n \\ (A_0e^{-\alpha_{10}\mathbf{W}_1})^{T-3}(A_0e^{-\alpha_{10}\mathbf{W}_1} - I_n)^2 & \dots & \dots & (A_0e^{-\alpha_{10}\mathbf{W}_1} - I_n)^2 & A_0e^{-\alpha_{10}\mathbf{W}_1} - 2I_n \end{pmatrix},$$

and $\mathbf{D}_{-1,0} =$

$$\begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_0e^{-\alpha_{10}\mathbf{W}_1} - 2I_n & I_n & \ddots & \dots & \vdots \\ (A_0e^{-\alpha_{10}\mathbf{W}_1} - I_n)^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ (A_0e^{-\alpha_{10}\mathbf{W}_1})^{T-4}(A_0e^{-\alpha_{10}\mathbf{W}_1} - I_n)^2 & \dots & (A_0e^{-\alpha_{10}\mathbf{W}_1} - I_n)^2 & A_0e^{-\alpha_{10}\mathbf{W}_1} - 2I_n & I_n \end{pmatrix}.$$

The adjusted quasi score (AQS) in (2.15) in the main paper is then reduced to

$$S_{(1,0,1)}^*(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \\ \sigma_\epsilon^2 : & \frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1}), \\ \alpha_1 : & -\frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \alpha_3 : & -\frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi). \end{cases}$$

To derive the M-estimator, the constrained M-estimators of β and σ_ϵ^2 are first solved as

$$\hat{\beta}_M(\zeta) = (\Delta X' \Sigma(\alpha_3)^{-1} \Delta X)^{-1} \Delta X' \Sigma(\alpha_3)^{-1} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.24})$$

$$\hat{\sigma}_{\epsilon,M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \hat{\epsilon}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta \hat{\epsilon}(\zeta), \quad (\text{D.25})$$

where $\Delta \hat{\epsilon}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \hat{\beta}_M(\zeta)$. Then $\hat{\beta}_M(\zeta)$ and $\hat{\sigma}_{\epsilon,M}^2(\zeta)$ are substituted back into the rest of the AQS function to get the concentrated AQS function:

$$S_{(1,0,1)}^{*c}(\zeta) = \begin{cases} \frac{1}{\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ -\frac{1}{\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ -\frac{1}{2\hat{\sigma}_{\epsilon,M}^2(\zeta)} \Delta \hat{u}(\zeta)' (B^{-1} \otimes E_3) \Delta \hat{u}(\zeta). \end{cases}$$

The unconstrained M-estimators $\hat{\zeta}_M$ can be solved by letting $S_{(1,0,1)}^{*c}(\zeta) = 0$ and then $\hat{\beta}_M = \hat{\beta}_M(\hat{\zeta}_M)$ and $\hat{\sigma}_{\epsilon,M}^2 = \hat{\sigma}_{\epsilon,M}^2(\hat{\zeta}_M)$.

MESDPS(0,1,1). By setting $\alpha_1 = 0$, we have MESDPS(0,1,1). Let $\mathbf{A}_0 = I_{T-1} \otimes A_0$ with $A_0 = \tau_0 I_n + e^{\alpha_{20} W_2}$. The first differenced model is given by

$$\Delta Y = \mathbf{A}_0 \Delta Y_{-1} + \Delta X \beta_0 + \Delta u, \quad \mathbf{e}^{\alpha_{30} \mathbf{W}_3} \Delta u = \Delta \epsilon,$$

and the conditional quasi loglikelihood is thus given by

$$\ell_{(1,0,1)}(\theta) = -\frac{n(T-1)}{2} \log(\sigma_\epsilon^2) - \frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \quad (\text{D.26})$$

where $\theta = (\beta', \sigma_\epsilon^2, \tau, \alpha_2, \alpha_3)'$, $\phi = (\beta', \tau, \alpha_2)'$, $\Sigma(\alpha_3) = B \otimes e^{-\alpha_3 W_3} e^{-\alpha_3 W_3'}$, and $\Delta u(\phi) = \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \beta$. Given $\zeta = (\tau, \alpha_2, \alpha_3)'$, the estimators of β and σ_ϵ^2 are given by

$$\tilde{\beta}(\zeta) = (\Delta X' \Sigma(\alpha_3)^{-1} \Delta X)^{-1} \Delta X' \Sigma(\alpha_3)^{-1} (\Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.27})$$

$$\tilde{\sigma}_\epsilon^2(\zeta) = \frac{1}{n(T-1)} \Delta \tilde{u}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta \tilde{u}(\zeta), \quad (\text{D.28})$$

where $\Delta \tilde{u}(\zeta) = \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \tilde{\beta}(\zeta)$. Substituting them back into (D.26), ignoring constants,

the concentrated log-likelihood function is given by:

$$l_{(0,1,1)}^c(\zeta) = -\log[\Delta\tilde{u}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta\tilde{u}(\zeta)]. \quad (\text{D.29})$$

Maximizing (D.29) gives us CQMLE $\tilde{\zeta}$ and then the implied CQMLEs $\tilde{\beta} = \tilde{\beta}(\tilde{\zeta})$ and $\tilde{\sigma}_\epsilon^2 = \tilde{\sigma}_\epsilon^2(\tilde{\zeta})$.

Correspondingly, the conditional quasi score (CQS) function (2.11) in the paper becomes

$$S_{(0,1,1)}(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1}, \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}, \\ \alpha_3 : & -\frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi). \end{cases}$$

Now the expectations in Lemma 2.1 become $E(\Delta Y \Delta \epsilon') = -\sigma_{\epsilon 0}^2 \mathbf{D}_0 \mathbf{e}^{-\alpha_{30} \mathbf{W}_3}$ and $E(\Delta Y_{-1} \Delta \epsilon') = -\sigma_{\epsilon 0}^2 \mathbf{D}_{-1,0} \mathbf{e}^{-\alpha_{30} \mathbf{W}_3}$, where

$$\mathbf{D}_{-1,0} = \begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_0 - 2I_n & I_n & \ddots & \dots & \vdots \\ (A_0 - I_n)^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ (A_0)^{T-4} (A_0 - I_n)^2 & \dots & (A_0 - I_n)^2 & A_0 - 2I_n & I_n \end{pmatrix},$$

$$\mathbf{D}_0 = \begin{pmatrix} A_0 - 2I_n & I_n & \dots & \dots & 0 \\ (A_0 - I_n)^2 & A_0 - 2I_n & \ddots & \dots & \vdots \\ \vdots & \vdots & \ddots & \ddots & I_n \\ A_0^{T-3} (A_0 - I_n)^2 & \dots & \dots & (A_0 - I_n)^2 & A_0 - 2I_n \end{pmatrix}.$$

The adjusted quasi score (AQS) in (2.15) in the main paper is then reduced to

$$S_{(0,1,1)}^*(\theta) = \begin{cases} \beta : & \frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \\ \sigma_\epsilon^2 : & -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \\ \tau : & \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ \alpha_2 : & \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2}), \\ \alpha_3 : & -\frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi). \end{cases}$$

To derive the M-estimator, the constrained M-estimators of β and σ_ϵ^2 are first solved as

$$\widehat{\beta}_M(\zeta) = (\Delta X' \Sigma(\alpha_3)^{-1} \Delta X)^{-1} \Delta X' \Sigma(\alpha_3)^{-1} (\Delta Y - \mathbf{A} \Delta Y_{-1}), \quad (\text{D.30})$$

$$\widehat{\sigma}_{\epsilon, M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \widehat{u}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta \widehat{u}(\zeta), \quad (\text{D.31})$$

where $\Delta \widehat{u}(\zeta) = \Delta Y - \mathbf{A} \Delta Y_{-1} - \Delta X \widehat{\beta}_M(\zeta)$. Then $\widehat{\beta}_M(\zeta)$ and $\widehat{\sigma}_{\epsilon, M}^2(\zeta)$ are substituted back into the rest of the AQS function to get the concentrated AQS function:

$$S_{(0,1,1)}^{*c}(\zeta) = \begin{cases} \tau : & \frac{1}{\widehat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \widehat{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1}), \\ \alpha_2 : & \frac{1}{\widehat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \widehat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2 \Delta Y_{-1} + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2} \mathbf{W}_2), \\ \alpha_3 : & -\frac{1}{2\widehat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \widehat{u}(\zeta)' (B^{-1} \otimes E_3) \Delta \widehat{u}(\zeta). \end{cases}$$

The unconstrained M-estimators $\widehat{\rho}_M$, $\widehat{\alpha}_{2M}$ and $\widehat{\alpha}_{3M}$ can be solved by letting $S_{(0,1,1)}^{*c}(\zeta) = 0$ and consequently the unconstrained M-estimators $\widehat{\beta}_M = \widehat{\beta}_M(\widehat{\zeta}_M)$ and $\widehat{\sigma}_{\epsilon, M}^2 = \widehat{\sigma}_{\epsilon, M}^2(\widehat{\zeta}_M)$.

E Some more Monte Carlo results

Table E.1: Empirical mean of CQMLE and M-estimator, MESDPS(1,1,0)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9848	0.9990	0.9862	1.0003	0.9992	1.0000	0.9993	1.0001
	1	0.9363	0.9511	0.9679	0.9825	0.9898	0.9907	0.9910	0.9918
	1.5	1.4853	1.5002	1.4858	1.5006	1.4999	1.5000	1.4999	1.5000
	1.1	1.0986	1.1005	1.0982	1.1000	1.1001	1.1000	1.1001	1.1000
	-0.5	-0.4987	-0.5005	-0.4993	-0.5006	-0.5000	-0.5000	-0.5000	-0.5000
2	1	0.9832	0.9980	0.9862	1.0004	1.0001	1.0009	0.9997	1.0004
	1	0.9502	0.9654	0.9640	0.9783	0.9843	0.9852	0.9907	0.9915
	1.5	1.4854	1.5007	1.4856	1.5003	1.4999	1.5000	1.4999	1.5000
	1.1	1.0993	1.1014	1.0987	1.1003	1.1001	1.1000	1.1001	1.1000
	-0.5	-0.4986	-0.4998	-0.4984	-0.4998	-0.5000	-0.5000	-0.5000	-0.5000
3	1	0.9871	1.0015	0.9859	0.9998	0.9971	0.9978	1.0006	1.0013
	1	0.9452	0.9608	0.9617	0.9762	0.9848	0.9857	0.9890	0.9898
	1.5	1.4856	1.5008	1.4861	1.5008	1.4999	1.5000	1.4999	1.5000
	1.1	1.0987	1.1006	1.0983	1.1000	1.1001	1.1000	1.1001	1.1000
	-0.5	-0.4993	-0.5014	-0.4987	-0.5003	-0.5000	-0.5000	-0.5000	-0.5000
1	1	0.9593	1.0004	0.9583	0.9996	0.9933	0.9992	0.9945	1.0003
	1	0.9184	0.9623	0.9400	0.9822	0.9813	0.9879	0.9895	0.9957
	0	-0.0544	0.0022	-0.0549	0.0011	-0.0104	-0.0003	-0.0096	0.0000
	1.1	1.0513	1.1063	1.0486	1.1032	1.1135	1.1017	1.1120	1.1007
	-0.5	-0.4860	-0.5004	-0.4861	-0.4996	-0.5036	-0.5007	-0.5030	-0.5002
2	1	0.9601	1.0014	0.9596	1.0007	0.9932	0.9991	0.9946	1.0005
	1	0.9221	0.9662	0.9446	0.9870	0.9801	0.9865	0.9857	0.9918
	0	-0.0542	0.0025	-0.0546	0.0013	-0.0098	0.0002	-0.0097	-0.0002
	1.1	1.0479	1.1041	1.0484	1.1030	1.1121	1.1002	1.1120	1.1009
	-0.5	-0.4909	-0.5039	-0.4860	-0.4994	-0.5031	-0.5003	-0.5029	-0.5001
3	1	0.9610	1.0025	0.9575	0.9984	0.9950	1.0010	0.9932	0.9991
	1	0.9165	0.9608	0.9409	0.9838	0.9772	0.9837	0.9828	0.9890
	0	-0.0531	0.0035	-0.0542	0.0018	-0.0094	0.0005	-0.0095	0.0001
	1.1	1.0470	1.1029	1.0481	1.1029	1.1115	1.0998	1.1119	1.1007
	-0.5	-0.4883	-0.5013	-0.4870	-0.5005	-0.5031	-0.5003	-0.5029	-0.5000
1	1	0.9865	0.9977	0.9878	0.9991	0.9981	0.9995	0.9990	1.0005
	1	0.9544	0.9661	0.9784	0.9900	0.9860	0.9875	0.9913	0.9928
	-1.5	-1.5307	-1.5001	-1.5295	-1.4988	-1.5098	-1.4998	-1.5095	-1.4994
	1.1	1.1007	1.1031	1.1013	1.1027	1.0953	1.0986	1.0982	1.1017
	-0.5	-0.4636	-0.5023	-0.4662	-0.5038	-0.4863	-0.4982	-0.4879	-0.5002
2	1	0.9892	1.0003	0.9902	1.0013	0.9980	0.9995	0.9978	0.9993
	1	0.9568	0.9685	0.9728	0.9840	0.9830	0.9845	0.9923	0.9939
	-1.5	-1.5285	-1.4978	-1.5302	-1.5001	-1.5096	-1.4995	-1.5102	-1.5001
	1.1	1.1012	1.1027	1.0985	1.1002	1.0958	1.0992	1.0958	1.0991
	-0.5	-0.4664	-0.5038	-0.4613	-0.4981	-0.4870	-0.4989	-0.4869	-0.4990
3	1	0.9854	0.9964	0.9896	1.0006	0.9990	1.0006	0.9995	1.0010
	1	0.9597	0.9718	0.9694	0.9808	0.9878	0.9894	0.9900	0.9915
	-1.5	-1.5313	-1.5007	-1.5301	-1.5000	-1.5089	-1.4987	-1.5093	-1.4993
	1.1	1.1006	1.1028	1.0993	1.1010	1.0991	1.1025	1.0962	1.0996
	-0.5	-0.4651	-0.5036	-0.4668	-0.5041	-0.4863	-0.4983	-0.4892	-0.5013

Note: Disturbance 1=normal, 2=normal-mixture and 3=gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_1, \alpha_2)'$. W_1 and W_2 are generated by rook and queen contiguity respectively.

Table E.2: Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,1,0)

dis	par	sd	se	\hat{se}	\hat{se}	sd	se	\hat{se}	\hat{se}	sd	se	\hat{se}	\hat{se}	sd	se	\hat{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.052	.051	.057	.052	.036	.036	.038	.036	.029	.029	.032	.029	.020	.020	.021	.020
	1	.143	.140	.155	.140	.098	.102	.106	.101	.081	.088	.089	.085	.058	.060	.060	.059
	1.5	.015	.014	.016	.014	.010	.010	.011	.010	.000	.000	.000	.000	.000	.000	.000	.000
	1.1	.014	.014	.015	.014	.010	.010	.010	.010	.000	.000	.000	.000	.000	.000	.000	.000
	-0.5	.028	.027	.030	.027	.020	.019	.020	.019	.000	.000	.000	.000	.000	.000	.000	.000
2	1	.054	.051	.057	.052	.037	.036	.038	.036	.030	.029	.032	.029	.021	.020	.021	.020
	1	.146	.142	.158	.142	.103	.102	.105	.101	.084	.088	.088	.084	.057	.060	.060	.059
	1.5	.015	.014	.016	.015	.010	.010	.010	.010	.000	.000	.000	.000	.000	.000	.000	.000
	1.1	.015	.015	.016	.014	.009	.010	.010	.010	.000	.000	.000	.000	.000	.000	.000	.000
	-0.5	.028	.027	.030	.027	.019	.019	.020	.019	.000	.000	.000	.000	.000	.000	.000	.000
3	1	.052	.051	.059	.052	.037	.036	.039	.036	.029	.029	.032	.029	.020	.020	.021	.020
	1	.205	.187	.126	.141	.140	.138	.081	.100	.123	.127	.063	.084	.085	.089	.041	.058
	1.5	.016	.015	.015	.014	.011	.011	.010	.010	.000	.000	.000	.000	.000	.000	.000	.000
	1.1	.014	.015	.016	.014	.010	.010	.011	.010	.000	.000	.000	.000	.000	.000	.000	.000
	-0.5	.029	.028	.031	.027	.019	.019	.020	.019	.000	.000	.000	.000	.000	.000	.000	.000
1	1	.056	.054	.060	.055	.039	.038	.040	.038	.030	.029	.032	.030	.022	.021	.021	.021
	1	.151	.150	.161	.146	.102	.107	.109	.103	.083	.105	.089	.090	.059	.070	.060	.062
	0	.036	.030	.034	.031	.024	.021	.022	.021	.009	.013	.010	.011	.007	.008	.006	.007
	1.1	.087	.086	.083	.080	.059	.060	.056	.056	.018	.025	.019	.020	.013	.015	.012	.013
	-0.5	.066	.064	.063	.060	.043	.045	.042	.042	.007	.007	.006	.006	.004	.005	.004	.004
2	1	.057	.054	.060	.055	.040	.038	.040	.038	.030	.029	.032	.030	.021	.021	.021	.021
	1	.150	.149	.163	.146	.106	.107	.109	.104	.083	.104	.089	.090	.058	.069	.060	.062
	0	.037	.030	.034	.031	.025	.021	.022	.021	.009	.013	.010	.011	.006	.008	.006	.007
	1.1	.089	.086	.083	.080	.060	.061	.056	.056	.018	.025	.019	.020	.012	.015	.012	.013
	-0.5	.061	.063	.063	.060	.044	.045	.043	.042	.007	.007	.006	.006	.004	.005	.004	.004
3	1	.058	.054	.062	.055	.040	.038	.041	.038	.031	.029	.032	.029	.021	.021	.022	.021
	1	.193	.194	.133	.146	.145	.143	.086	.104	.116	.144	.064	.090	.085	.099	.042	.062
	0	.038	.033	.033	.031	.027	.023	.021	.021	.010	.013	.010	.011	.006	.008	.006	.007
	1.1	.085	.087	.088	.080	.057	.060	.058	.056	.019	.026	.019	.020	.012	.016	.012	.013
	-0.5	.065	.064	.065	.060	.044	.045	.043	.042	.006	.007	.006	.006	.004	.005	.004	.004
1	1	.054	.051	.057	.052	.038	.036	.038	.036	.030	.029	.032	.029	.021	.020	.021	.021
	1	.141	.135	.158	.140	.100	.099	.106	.100	.084	.080	.089	.082	.056	.057	.060	.057
	-1.5	.037	.034	.040	.035	.026	.024	.027	.025	.019	.018	.021	.019	.013	.013	.014	.013
	1.1	.073	.071	.079	.072	.050	.051	.053	.051	.043	.043	.047	.043	.030	.031	.032	.031
	-0.5	.079	.077	.084	.077	.056	.055	.057	.055	.041	.040	.044	.041	.028	.029	.030	.029
2	1	.052	.051	.057	.052	.037	.036	.038	.036	.029	.029	.032	.029	.020	.020	.021	.021
	1	.141	.136	.157	.140	.103	.098	.105	.100	.080	.080	.089	.081	.057	.057	.060	.058
	-1.5	.036	.034	.040	.035	.025	.024	.027	.025	.019	.018	.021	.019	.014	.013	.014	.013
	1.1	.073	.071	.079	.072	.052	.050	.053	.051	.043	.043	.047	.043	.031	.030	.032	.031
	-0.5	.077	.075	.083	.076	.056	.055	.056	.054	.042	.041	.044	.041	.029	.029	.030	.029
3	1	.054	.051	.060	.052	.037	.036	.039	.036	.029	.029	.033	.029	.021	.020	.021	.020
	1	.206	.183	.127	.141	.145	.134	.081	.099	.128	.117	.064	.082	.085	.085	.041	.057
	-1.5	.036	.034	.042	.035	.025	.024	.027	.025	.019	.018	.021	.019	.013	.013	.014	.013
	1.1	.074	.071	.082	.072	.051	.050	.054	.051	.045	.043	.048	.043	.031	.030	.032	.031
	-0.5	.080	.076	.086	.076	.054	.054	.058	.054	.040	.040	.045	.041	.029	.029	.030	.029

Note: Same configuration as Table E.1. Here sd is empirical standard deviation, se is OPMD estimator, \hat{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table E.3: Empirical mean of CQMLE and M-estimator, MESDPS(1,0,1)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9734	0.9996	0.9746	1.0005	0.9956	0.9994	0.9962	1.0000
	1	0.9263	0.9510	0.9576	0.9825	0.9871	0.9905	0.9885	0.9918
	0.5	0.4604	0.5002	0.4610	0.5006	0.4972	0.4999	0.4973	0.5000
	0.5	0.4846	0.5014	0.4835	0.5003	0.5022	0.5002	0.5019	0.5000
	-1.1	-1.0778	-1.0916	-1.0861	-1.1000	-1.1049	-1.1039	-1.0990	-1.0986
2	1	0.9734	1.0004	0.9746	1.0005	0.9968	1.0005	0.9965	1.0002
	1	0.9386	0.9639	0.9536	0.9781	0.9820	0.9853	0.9881	0.9914
	1.5	0.4617	0.5020	0.4613	0.5003	0.4972	0.5000	0.4973	0.5000
	0.5	0.4862	0.5030	0.4837	0.5002	0.5024	0.5004	0.5022	0.5002
	-1.1	-1.0851	-1.0984	-1.0900	-1.1042	-1.1044	-1.1041	-1.1034	-1.1026
3	1	0.9747	1.0011	0.9748	1.0005	0.9955	0.9992	0.9969	1.0006
	1	0.9341	0.9600	0.9503	0.9752	0.9823	0.9856	0.9866	0.9899
	1.5	0.4617	0.5019	0.4614	0.5008	0.4973	0.5001	0.4973	0.5000
	0.5	0.4855	0.5024	0.4830	0.4997	0.5021	0.5001	0.5021	0.5001
	-1.1	-1.0899	-1.1027	-1.0867	-1.1012	-1.1041	-1.1034	-1.0996	-1.0992
1	1	0.9700	1.0000	0.9686	0.9990	0.9903	0.9992	0.9908	0.9996
	1	0.9276	0.9591	0.9487	0.9804	0.9793	0.9875	0.9870	0.9951
	0	-0.0574	0.0013	-0.0589	0.0002	-0.0140	0.0002	-0.0141	0.0000
	0.5	0.4618	0.5040	0.4576	0.5010	0.5013	0.5025	0.4995	0.5007
	-1.1	-1.0711	-1.1008	-1.0657	-1.0957	-1.0997	-1.1013	-1.0998	-1.1014
2	1	0.9692	0.9995	0.9703	1.0003	0.9901	0.9991	0.9911	0.9999
	1	0.9314	0.9631	0.9538	0.9855	0.9784	0.9865	0.9832	0.9913
	0	-0.0578	0.0012	-0.0589	-0.0001	-0.0139	0.0003	-0.0142	-0.0001
	0.5	0.4619	0.5044	0.4568	0.4998	0.5001	0.5010	0.4995	0.5007
	-1.1	-1.0743	-1.1046	-1.0702	-1.1000	-1.0989	-1.1002	-1.0997	-1.1011
3	1	0.9715	1.0017	0.9681	0.9980	0.9915	1.0003	0.9907	0.9994
	1	0.9255	0.9572	0.9493	0.9811	0.9750	0.9832	0.9812	0.9892
	0	-0.0569	0.0015	-0.0580	0.0007	-0.0136	0.0004	-0.0135	0.0005
	0.5	0.4580	0.5000	0.4580	0.5010	0.4998	0.5009	0.4998	0.5012
	-1.1	-1.0660	-1.0945	-1.0688	-1.0987	-1.1034	-1.1047	-1.1014	-1.1029
1	1	0.9769	0.9971	0.9793	0.9997	0.9941	0.9992	0.9956	1.0005
	1	0.9374	0.9634	0.9629	0.9898	0.9809	0.9868	0.9866	0.9926
	-0.5	-0.5608	-0.5012	-0.5589	-0.4982	-0.5241	-0.5010	-0.5235	-0.5000
	0.5	0.4398	0.5050	0.4382	0.5067	0.4915	0.5027	0.4866	0.4998
	-1.1	-1.0764	-1.1122	-1.0687	-1.1082	-1.0999	-1.1071	-1.0901	-1.0987
2	1	0.9796	0.9996	0.9802	1.0003	0.9933	0.9984	0.9948	0.9997
	1	0.9419	0.9682	0.9569	0.9832	0.9783	0.9842	0.9875	0.9935
	-0.5	-0.5580	-0.4983	-0.5611	-0.5012	-0.5243	-0.5011	-0.5245	-0.5010
	0.5	0.4455	0.5117	0.4356	0.5035	0.4960	0.5077	0.4856	0.4986
	-1.1	-1.0694	-1.1073	-1.0672	-1.1070	-1.0990	-1.1069	-1.0923	-1.1008
3	1	0.9760	0.9963	0.9788	0.9989	0.9956	1.0007	0.9956	1.0004
	1	0.9436	0.9707	0.9527	0.9790	0.9836	0.9897	0.9853	0.9913
	-0.5	-0.5606	-0.5004	-0.5600	-0.5004	-0.5233	-0.5000	-0.5233	-0.5000
	0.5	0.4389	0.5067	0.4389	0.5070	0.4900	0.5016	0.4900	0.5026
	-1.1	-1.0599	-1.0995	-1.0665	-1.1079	-1.0978	-1.1050	-1.0938	-1.1020

Note: Disturbance 1=normal, 2=normal-mixture and 3=gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_1, \alpha_3)'$. W_1 and W_3 are generated by rook and queen contiguity respectively.

Table E.4: Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,0,1)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.041	.041	.045	.041	.029	.029	.030	.029	.022	.021	.024	.022	.015	.015	.016	.015
	1	.144	.135	.156	.139	.099	.099	.107	.101	.081	.083	.089	.083	.058	.058	.060	.058
	0.5	.027	.025	.029	.026	.019	.018	.019	.018	.003	.003	.004	.003	.002	.002	.002	.002
	0.5	.031	.030	.033	.030	.022	.022	.023	.022	.006	.006	.006	.006	.004	.004	.004	.004
	-1.1	.145	.143	.155	.142	.100	.099	.103	.099	.081	.080	.086	.080	.058	.057	.058	.056
2	1	.044	.041	.045	.041	.029	.029	.030	.029	.022	.022	.024	.022	.015	.015	.016	.015
	1	.146	.137	.159	.141	.104	.099	.106	.100	.083	.082	.089	.082	.057	.058	.060	.058
	1.5	.028	.025	.029	.026	.018	.018	.019	.018	.003	.003	.004	.003	.002	.002	.002	.002
	0.5	.032	.031	.034	.031	.022	.022	.022	.022	.006	.006	.006	.006	.004	.004	.004	.004
	-1.1	.151	.144	.154	.142	.098	.099	.103	.099	.082	.079	.086	.080	.058	.056	.058	.056
3	1	.043	.041	.046	.041	.030	.029	.031	.029	.022	.021	.024	.022	.015	.015	.016	.015
	1	.206	.181	.128	.141	.140	.134	.082	.100	.123	.120	.063	.083	.085	.086	.042	.058
	1.5	.030	.027	.029	.026	.020	.019	.018	.018	.004	.003	.004	.003	.002	.002	.002	.002
	0.5	.030	.029	.036	.031	.022	.021	.024	.022	.006	.006	.007	.006	.004	.005	.004	.004
	-1.1	.150	.142	.163	.143	.101	.097	.107	.099	.081	.079	.088	.080	.056	.056	.060	.056
1	1	.042	.041	.046	.042	.029	.029	.031	.029	.022	.022	.025	.022	.017	.016	.016	.016
	1	.148	.138	.158	.141	.100	.099	.107	.101	.083	.082	.089	.083	.059	.058	.060	.058
	0	.038	.034	.037	.034	.026	.024	.025	.024	.010	.010	.011	.010	.007	.007	.007	.007
	0.5	.059	.057	.061	.056	.041	.040	.041	.040	.025	.025	.025	.024	.018	.018	.017	.017
	-1.1	.154	.144	.156	.144	.101	.099	.105	.100	.081	.080	.086	.080	.056	.056	.059	.057
2	1	.042	.041	.046	.042	.030	.029	.030	.029	.022	.022	.024	.022	.016	.016	.016	.016
	1	.145	.137	.161	.142	.104	.100	.108	.101	.082	.081	.090	.082	.058	.058	.060	.058
	0	.037	.033	.037	.034	.026	.024	.025	.024	.010	.010	.011	.010	.007	.007	.007	.007
	0.5	.059	.057	.061	.056	.041	.040	.041	.040	.024	.025	.025	.024	.017	.018	.017	.017
	-1.1	.145	.144	.156	.143	.098	.099	.105	.100	.081	.080	.086	.080	.059	.056	.059	.057
3	1	.044	.042	.047	.042	.031	.029	.031	.029	.022	.022	.024	.022	.016	.016	.017	.016
	1	.190	.179	.130	.141	.143	.134	.084	.101	.116	.117	.065	.082	.085	.086	.042	.058
	0	.038	.035	.037	.034	.027	.025	.024	.024	.010	.010	.011	.010	.007	.007	.007	.007
	0.5	.054	.053	.065	.056	.039	.038	.044	.040	.025	.025	.026	.024	.017	.018	.017	.017
	-1.1	.148	.142	.164	.143	.103	.098	.108	.100	.082	.079	.089	.080	.057	.056	.060	.057
1	1	.044	.042	.046	.042	.031	.029	.031	.029	.024	.024	.026	.024	.017	.017	.017	.017
	1	.144	.137	.159	.141	.102	.100	.108	.102	.084	.081	.089	.082	.056	.057	.060	.058
	-0.5	.041	.037	.041	.037	.029	.026	.028	.027	.019	.017	.019	.018	.013	.012	.013	.013
	0.5	.121	.116	.123	.115	.084	.082	.083	.081	.068	.069	.071	.068	.048	.049	.049	.048
	-1.1	.159	.153	.166	.152	.110	.105	.110	.105	.087	.085	.094	.086	.059	.060	.063	.061
2	1	.044	.042	.046	.042	.029	.029	.031	.029	.025	.024	.026	.024	.016	.017	.017	.017
	1	.144	.138	.159	.142	.105	.100	.107	.101	.080	.080	.089	.082	.057	.058	.060	.058
	-0.5	.040	.037	.042	.037	.028	.026	.028	.026	.018	.017	.020	.018	.013	.012	.013	.013
	0.5	.116	.116	.123	.114	.085	.082	.083	.081	.069	.068	.072	.068	.048	.049	.049	.048
	-1.1	.158	.154	.166	.152	.109	.105	.110	.105	.085	.085	.093	.086	.061	.060	.063	.060
3	1	.044	.043	.048	.042	.029	.030	.031	.029	.024	.023	.026	.024	.017	.017	.017	.017
	1	.207	.184	.129	.142	.147	.134	.083	.100	.129	.118	.064	.082	.085	.085	.042	.058
	-0.5	.042	.039	.041	.037	.030	.027	.027	.026	.019	.017	.020	.018	.013	.012	.013	.013
	0.5	.122	.112	.131	.114	.083	.080	.086	.080	.067	.067	.074	.067	.048	.049	.049	.048
	-1.1	.152	.152	.174	.152	.106	.103	.115	.105	.085	.084	.097	.086	.062	.059	.064	.060

Note: Same configuration as Table E.3. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table E.5: Empirical mean of CQMLE and M-estimator, MESDPS(0,1,1)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9771	0.9999	0.9781	1.0006	0.9979	0.9994	0.9985	1.0001
	1	0.9304	0.9503	0.9624	0.9826	0.9889	0.9905	0.9903	0.9918
	1.5	1.4704	1.5004	1.4708	1.5006	1.4997	1.5000	1.4997	1.5000
	0.5	0.5167	0.4997	0.5165	0.4998	0.5002	0.5000	0.5002	0.5000
	-1.1	-1.0526	-1.0531	-1.0850	-1.0848	-1.0883	-1.0886	-1.0879	-1.0882
2	1	0.9757	0.9993	0.9772	0.9999	0.9992	1.0008	0.9991	1.0006
	1	0.9429	0.9634	0.9571	0.9769	0.9837	0.9852	0.9899	0.9914
	1.5	1.4711	1.5017	1.4703	1.4996	1.4997	1.5000	1.4997	1.5000
	0.5	0.5160	0.4987	0.5168	0.5003	0.5002	0.5000	0.5002	0.5000
	-1.1	-1.0574	-1.0574	-1.0863	-1.0876	-1.0886	-1.0891	-1.0940	-1.0944
3	1	0.9784	1.0016	0.9771	0.9996	0.9971	0.9987	0.9997	1.0012
	1	0.9389	0.9598	0.9551	0.9751	0.9845	0.9860	0.9885	0.9900
	1.5	1.4708	1.5014	1.4709	1.5004	1.4997	1.5000	1.4997	1.5000
	0.5	0.5165	0.4992	0.5166	0.5000	0.5002	0.5000	0.5002	0.5000
	-1.1	-1.0582	-1.0582	-1.0868	-1.0874	-1.0873	-1.0876	-1.0906	-1.0909
1	1	0.9515	1.0001	0.9499	0.9995	0.9840	0.9992	0.9846	0.9997
	1	0.9152	0.9581	0.9367	0.9802	0.9732	0.9876	0.9807	0.9950
	0	-0.0960	0.0011	-0.0972	0.0003	-0.0320	0.0006	-0.0324	-0.0001
	0.5	0.5540	0.4989	0.5550	0.4998	0.5192	0.4996	0.5194	0.5001
	-1.1	-1.0597	-1.0602	-1.0748	-1.0753	-1.0842	-1.0872	-1.0910	-1.0948
2	1	0.9504	0.9998	0.9508	0.9998	0.9844	0.9996	0.9853	1.0004
	1	0.9188	0.9623	0.9411	0.9845	0.9715	0.9858	0.9773	0.9915
	0	-0.0963	0.0017	-0.0979	-0.0011	-0.0322	0.0003	-0.0323	0.0000
	0.5	0.5541	0.4984	0.5555	0.5007	0.5193	0.4998	0.5193	0.5000
	-1.1	-1.0674	-1.0671	-1.0834	-1.0837	-1.0822	-1.0862	-1.0912	-1.0949
3	1	0.9520	1.0010	0.9492	0.9980	0.9853	1.0006	0.9844	0.9994
	1	0.9136	0.9571	0.9374	0.9812	0.9682	0.9825	0.9752	0.9896
	0	-0.0968	0.0004	-0.0966	0.0004	-0.0321	0.0004	-0.0313	0.0011
	0.5	0.5552	0.5003	0.5548	0.4999	0.5192	0.4997	0.5188	0.4993
	-1.1	-1.0621	-1.0611	-1.0790	-1.0788	-1.0893	-1.0927	-1.0928	-1.0971
1	1	0.9915	0.9983	0.9930	0.9999	0.9985	0.9994	0.9996	1.0005
	1	0.9585	0.9650	0.9821	0.9888	0.9862	0.9872	0.9916	0.9926
	-1.5	-1.5282	-1.5000	-1.5264	-1.4979	-1.5097	-1.5005	-1.5090	-1.4996
	0.5	0.5108	0.5011	0.5095	0.4994	0.4993	0.4999	0.5000	0.5002
	-1.1	-1.0753	-1.0769	-1.0883	-1.0891	-1.0945	-1.0947	-1.0931	-1.0932
2	1	0.9936	1.0003	0.9945	1.0012	0.9988	0.9997	0.9985	0.9993
	1	0.9599	0.9665	0.9775	0.9840	0.9830	0.9840	0.9928	0.9938
	-1.5	-1.5253	-1.4967	-1.5284	-1.5004	-1.5098	-1.5006	-1.5095	-1.5002
	0.5	0.5085	0.4983	0.5100	0.5002	0.4983	0.4987	0.4993	0.4996
	-1.1	-1.0554	-1.0563	-1.0884	-1.0889	-1.0886	-1.0889	-1.0988	-1.0990
3	1	0.9894	0.9961	0.9934	1.0001	0.9996	1.0005	0.9999	1.0008
	1	0.9624	0.9691	0.9731	0.9797	0.9884	0.9894	0.9904	0.9914
	-1.5	-1.5299	-1.5014	-1.5275	-1.4994	-1.5090	-1.4998	-1.5087	-1.4994
	0.5	0.5111	0.5009	0.5087	0.4987	0.5007	0.5011	0.4985	0.4988
	-1.1	-1.0554	-1.0563	-1.0844	-1.0848	-1.0892	-1.0894	-1.0954	-1.0956

Note: Disturbance 1=normal, 2=normal-mixture and 3=gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_2, \alpha_3)'$. W_2 and W_3 are generated by rook and queen contiguity respectively.

Table E.6: Empirical sd and asymptotic standard errors of M-estimator, MESDPS(0,1,1)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.047	.047	.052	.047	.033	.033	.035	.033	.026	.025	.028	.026	.018	.018	.019	.018
	1	.143	.135	.155	.139	.099	.099	.106	.100	.081	.081	.089	.082	.058	.057	.060	.057
	1.5	.022	.021	.024	.021	.016	.015	.016	.015	.000	.000	.001	.000	.000	.000	.000	.000
	0.5	.016	.015	.017	.015	.011	.011	.011	.011	.000	.000	.000	.000	.000	.000	.000	.000
	-1.1	.205	.197	.214	.196	.138	.138	.144	.138	.113	.109	.118	.110	.078	.078	.081	.078
2	1	.050	.047	.052	.048	.034	.033	.035	.033	.027	.025	.028	.026	.018	.018	.019	.018
	1	.144	.137	.159	.141	.103	.098	.106	.100	.083	.080	.089	.081	.057	.057	.060	.057
	1.5	.023	.021	.024	.022	.015	.015	.016	.015	.000	.000	.001	.000	.000	.000	.000	.000
	0.5	.016	.015	.017	.015	.011	.010	.011	.011	.000	.000	.000	.000	.000	.000	.000	.000
	-1.1	.208	.199	.212	.196	.141	.137	.144	.137	.108	.108	.119	.110	.079	.077	.081	.078
3	1	.048	.047	.055	.048	.034	.033	.036	.033	.025	.025	.029	.026	.018	.018	.019	.018
	1	.205	.181	.127	.140	.139	.134	.082	.100	.123	.117	.063	.082	.085	.085	.041	.057
	1.5	.023	.022	.025	.022	.016	.015	.016	.015	.000	.000	.001	.000	.000	.000	.000	.000
	0.5	.015	.014	.018	.015	.011	.010	.012	.011	.000	.000	.000	.000	.000	.000	.000	.000
	-1.1	.204	.194	.223	.197	.138	.137	.147	.138	.109	.108	.121	.110	.077	.077	.083	.078
1	1	.052	.050	.056	.051	.037	.036	.038	.036	.027	.026	.029	.027	.020	.019	.019	.019
	1	.148	.141	.160	.144	.102	.102	.109	.103	.083	.081	.090	.083	.059	.058	.061	.058
	0	.054	.049	.053	.049	.039	.035	.035	.034	.017	.016	.018	.016	.012	.011	.012	.011
	0.5	.035	.032	.035	.032	.025	.023	.023	.022	.010	.010	.011	.010	.007	.007	.007	.007
	-1.1	.212	.198	.214	.197	.140	.138	.143	.138	.112	.109	.119	.110	.077	.078	.081	.078
2	1	.052	.050	.056	.051	.037	.036	.037	.036	.027	.026	.029	.027	.019	.018	.020	.019
	1	.148	.140	.163	.144	.107	.102	.109	.103	.083	.081	.090	.083	.059	.058	.060	.058
	0	.055	.049	.054	.049	.037	.035	.036	.034	.017	.016	.018	.016	.012	.011	.012	.011
	0.5	.035	.032	.035	.032	.024	.023	.023	.022	.011	.010	.011	.010	.007	.007	.007	.007
	-1.1	.204	.196	.214	.196	.141	.139	.143	.138	.111	.110	.118	.110	.077	.077	.081	.078
3	1	.052	.050	.058	.051	.037	.036	.038	.036	.027	.026	.029	.026	.019	.019	.020	.019
	1	.191	.182	.133	.143	.144	.136	.086	.103	.116	.116	.066	.082	.085	.085	.043	.058
	0	.054	.050	.055	.049	.037	.035	.036	.034	.017	.016	.018	.016	.011	.011	.012	.011
	0.5	.032	.031	.038	.032	.022	.022	.025	.022	.010	.009	.011	.010	.007	.007	.007	.007
	-1.1	.201	.195	.224	.197	.145	.136	.148	.137	.114	.108	.122	.110	.080	.077	.082	.078
1	1	.047	.044	.050	.045	.033	.032	.034	.032	.027	.025	.028	.026	.018	.018	.019	.018
	1	.140	.134	.157	.139	.099	.098	.106	.100	.084	.080	.088	.082	.056	.057	.060	.057
	-1.5	.037	.035	.040	.036	.027	.025	.027	.025	.018	.018	.020	.018	.013	.013	.013	.013
	0.5	.033	.032	.035	.032	.023	.023	.024	.023	.022	.021	.023	.022	.015	.015	.016	.015
	-1.1	.198	.199	.214	.197	.142	.139	.143	.138	.111	.109	.119	.110	.076	.078	.081	.078
2	1	.046	.045	.050	.045	.032	.031	.033	.032	.026	.025	.028	.026	.017	.018	.019	.018
	1	.141	.135	.156	.139	.102	.098	.105	.099	.080	.080	.089	.081	.057	.057	.060	.057
	-1.5	.038	.035	.041	.036	.025	.024	.027	.025	.018	.018	.020	.018	.013	.013	.013	.013
	0.5	.033	.032	.035	.032	.023	.022	.024	.023	.022	.021	.023	.021	.015	.015	.016	.015
	-1.1	.202	.197	.213	.196	.140	.138	.144	.138	.111	.109	.119	.110	.078	.078	.081	.078
3	1	.048	.044	.052	.045	.032	.031	.034	.032	.025	.025	.029	.026	.018	.018	.019	.018
	1	.204	.182	.125	.139	.145	.133	.080	.099	.128	.117	.064	.082	.085	.085	.041	.057
	-1.5	.037	.035	.042	.036	.025	.025	.027	.025	.018	.018	.020	.018	.013	.013	.013	.013
	0.5	.034	.032	.036	.032	.023	.023	.024	.023	.022	.021	.024	.021	.015	.015	.016	.015
	-1.1	.204	.194	.224	.196	.136	.136	.148	.137	.111	.107	.122	.110	.077	.077	.083	.078

Note: Same configuration as Table E.5. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table E.7: Empirical mean of CQMLE and M-estimator, MESDPS(1,0,0)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9659	0.9995	0.9676	1.0006	0.9963	1.0001	0.9963	1.0000
	1	0.9279	0.9619	0.9549	0.9886	0.9901	0.9941	0.9897	0.9934
	0.5	0.4566	0.5009	0.4571	0.5011	0.4966	0.4999	0.4970	0.4999
	1.1	1.0785	1.1019	1.0776	1.1006	1.1047	1.1003	1.1039	1.1002
2	1	0.9649	0.9995	0.9677	1.0009	0.9971	1.0009	0.9968	1.0004
	1	0.9419	0.9776	0.9505	0.9837	0.9845	0.9885	0.9896	0.9933
	0.5	0.4574	0.5029	0.4574	0.5009	0.4966	0.5000	0.4970	0.4999
	1.1	1.0795	1.1037	1.0778	1.1005	1.1046	1.1002	1.1040	1.1002
3	1	0.9684	1.0024	0.9674	1.0002	0.9943	0.9980	0.9978	1.0013
	1	0.9372	0.9733	0.9480	0.9814	0.9852	0.9892	0.9880	0.9916
	0.5	0.4579	0.5032	0.4578	0.5013	0.4967	0.5001	0.4971	0.5000
	1.1	1.0789	1.1030	1.0775	1.1002	1.1044	1.1000	1.1037	1.1000
1	1	0.9539	1.0004	0.9528	0.9995	0.9924	0.9992	0.9938	1.0004
	1	0.9231	0.9723	0.9389	0.9864	0.9837	0.9910	0.9904	0.9973
	0	-0.0710	0.0026	-0.0717	0.0009	-0.0101	0.0000	-0.0099	0.0001
	1.1	1.0390	1.1041	1.0371	1.1011	1.1100	1.1022	1.1098	1.1008
2	1	0.9541	1.0012	0.9539	1.0004	0.9922	0.9990	0.9939	1.0006
	1	0.9250	0.9749	0.9436	0.9914	0.9828	0.9899	0.9867	0.9935
	0	-0.0711	0.0029	-0.0718	0.0008	-0.0099	0.0001	-0.0100	0.0000
	1.1	1.0386	1.1041	1.0367	1.1007	1.1093	1.1013	1.1099	1.1010
3	1	0.9548	1.0019	0.9522	0.9985	0.9941	1.0008	0.9926	0.9992
	1	0.9198	0.9693	0.9403	0.9885	0.9795	0.9865	0.9840	0.9909
	0	-0.0708	0.0028	-0.0708	0.0018	-0.0094	0.0006	-0.0096	0.0004
	1.1	1.0359	1.1011	1.0378	1.1019	1.1083	1.1003	1.1091	1.1005
1	1	0.9573	0.9982	0.9598	1.0003	0.9884	0.9996	0.9896	1.0005
	1	0.9351	0.9782	0.9547	0.9973	0.9793	0.9905	0.9832	0.9941
	-0.5	-0.5783	-0.4976	-0.5772	-0.4964	-0.5341	-0.5003	-0.5336	-0.5001
	1.1	0.9868	1.1042	0.9884	1.1061	1.0683	1.1011	1.0666	1.0994
2	1	0.9604	1.0014	0.9611	1.0012	0.9880	0.9995	0.9881	0.9990
	1	0.9382	0.9820	0.9481	0.9898	0.9763	0.9875	0.9839	0.9949
	-0.5	-0.5775	-0.4958	-0.5797	-0.4997	-0.5346	-0.5009	-0.5347	-0.5012
	1.1	0.9892	1.1086	0.9848	1.1016	1.0709	1.1036	1.0660	1.0988
3	1	0.9565	0.9972	0.9605	1.0000	0.9896	1.0009	0.9901	1.0010
	1	0.9389	0.9824	0.9427	0.9839	0.9819	0.9933	0.9821	0.9931
	-0.5	-0.5785	-0.4983	-0.5787	-0.5000	-0.5332	-0.4996	-0.5333	-0.5000
	1.1	0.9869	1.1037	0.9878	1.1024	1.0672	1.0998	1.0692	1.1016

Note: Disturbance 1=normal, 2=normal-mixture and 3=gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_1)'$. W_1 is generated by rook contiguity.

Table E.8: Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,0,0)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7					
1	1	.055	.068	.059	.054	.037	.047	.040	.038	.030	.030	.032	.029	.020	.021	.021	.021
	1	.147	.153	.157	.141	.101	.112	.108	.102	.081	.112	.088	.091	.058	.072	.060	.062
	0.5	.028	.034	.027	.025	.019	.024	.018	.018	.004	.005	.004	.004	.002	.003	.002	.002
	1.1	.026	.027	.026	.024	.018	.019	.018	.017	.006	.008	.006	.006	.004	.004	.004	.004
2	1	.056	.069	.059	.054	.039	.048	.039	.038	.030	.031	.031	.029	.021	.021	.021	.021
	1	.150	.156	.160	.143	.105	.111	.107	.101	.084	.111	.088	.090	.057	.072	.060	.062
	0.5	.028	.034	.028	.025	.019	.024	.018	.018	.004	.005	.004	.004	.002	.003	.002	.002
	1.1	.026	.027	.026	.025	.018	.019	.018	.017	.006	.008	.006	.006	.004	.005	.004	.004
3	1	.054	.069	.060	.054	.039	.048	.040	.038	.029	.030	.032	.029	.021	.021	.021	.021
	1	.210	.205	.128	.143	.142	.150	.083	.101	.123	.156	.063	.090	.086	.104	.041	.062
	0.5	.031	.036	.027	.025	.020	.026	.018	.018	.004	.006	.004	.004	.002	.003	.002	.002
	1.1	.024	.026	.029	.025	.017	.018	.019	.017	.006	.009	.006	.006	.004	.005	.004	.004
1	1	.056	.075	.060	.055	.039	.053	.040	.039	.030	.031	.032	.030	.022	.022	.021	.021
	1	.153	.164	.160	.144	.104	.117	.109	.102	.083	.093	.088	.085	.059	.065	.060	.060
	0	.042	.051	.038	.035	.028	.036	.026	.025	.009	.010	.009	.009	.006	.007	.006	.006
	1.1	.051	.055	.049	.046	.036	.039	.033	.032	.020	.023	.020	.020	.014	.015	.013	.014
2	1	.058	.076	.060	.055	.040	.053	.040	.039	.030	.031	.032	.030	.021	.022	.021	.021
	1	.152	.164	.163	.144	.108	.117	.109	.102	.083	.092	.089	.085	.058	.065	.060	.059
	0	.043	.052	.038	.035	.029	.036	.026	.025	.008	.010	.009	.009	.006	.007	.006	.006
	1.1	.053	.056	.049	.046	.035	.039	.033	.032	.019	.023	.020	.020	.013	.015	.013	.014
3	1	.058	.077	.062	.055	.041	.053	.041	.039	.031	.031	.032	.029	.021	.022	.021	.021
	1	.195	.212	.131	.143	.147	.157	.085	.102	.116	.131	.063	.085	.085	.095	.041	.059
	0	.043	.056	.038	.035	.030	.039	.025	.025	.009	.011	.009	.009	.006	.008	.006	.006
	1.1	.046	.054	.054	.045	.033	.038	.036	.032	.020	.024	.020	.020	.014	.016	.013	.014
1	1	.058	.073	.060	.055	.042	.051	.040	.039	.031	.032	.032	.030	.021	.023	.022	.021
	1	.150	.162	.162	.144	.105	.118	.110	.103	.084	.085	.089	.083	.056	.060	.060	.058
	-0.5	.049	.059	.045	.042	.034	.042	.031	.029	.021	.021	.021	.019	.014	.015	.014	.013
	1.1	.101	.107	.097	.090	.069	.076	.065	.063	.052	.051	.052	.049	.035	.036	.035	.035
2	1	.056	.073	.060	.055	.040	.051	.040	.038	.030	.032	.032	.030	.020	.023	.022	.021
	1	.150	.163	.162	.145	.107	.117	.108	.102	.081	.084	.089	.082	.057	.060	.060	.058
	-0.5	.048	.059	.046	.042	.033	.042	.031	.029	.021	.021	.021	.019	.014	.015	.014	.013
	1.1	.099	.107	.097	.090	.070	.076	.065	.063	.052	.051	.051	.049	.036	.036	.035	.035
3	1	.058	.075	.062	.055	.040	.051	.041	.038	.030	.032	.033	.030	.021	.023	.022	.021
	1	.212	.216	.131	.145	.149	.155	.084	.102	.129	.123	.064	.083	.085	.089	.042	.058
	-0.5	.051	.064	.045	.042	.035	.045	.029	.029	.021	.022	.021	.019	.014	.016	.014	.013
	1.1	.100	.107	.103	.090	.066	.075	.068	.063	.049	.050	.053	.049	.035	.036	.035	.035

Note: Same configuration as Table E.7. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table E.9: Empirical mean of CQMLE and M-estimator, MESDPS(0,1,0)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9537	0.9987	0.9565	1.0007	0.9934	1.0000	0.9936	1.0001
	1	0.9163	0.9607	0.9442	0.9883	0.9873	0.9942	0.9872	0.9937
	0.5	0.4245	0.5000	0.4269	0.5011	0.4948	0.5000	0.4951	0.5001
	-0.1	-0.0217	-0.1011	-0.0236	-0.1016	-0.0944	-0.1000	-0.0946	-0.1000
2	1	0.9529	0.9988	0.9560	1.0004	0.9947	1.0012	0.9941	1.0004
	1	0.9302	0.9756	0.9393	0.9828	0.9825	0.9892	0.9865	0.9930
	0.5	0.4263	0.5022	0.4265	0.5002	0.4951	0.5002	0.4950	0.5000
	-0.1	-0.0237	-0.1038	-0.0231	-0.1005	-0.0947	-0.1003	-0.0946	-0.1000
3	1	0.9565	1.0023	0.9558	0.9996	0.9916	0.9981	0.9950	1.0014
	1	0.9261	0.9731	0.9362	0.9801	0.9828	0.9896	0.9852	0.9917
	0.5	0.4267	0.5037	0.4266	0.5005	0.4951	0.5002	0.4951	0.5001
	-0.1	-0.0239	-0.1052	-0.0230	-0.1007	-0.0946	-0.1002	-0.0947	-0.1001
1	1	0.9469	0.9994	0.9465	0.9992	0.9837	0.9994	0.9848	1.0002
	1	0.9174	0.9700	0.9333	0.9853	0.9754	0.9912	0.9813	0.9968
	0	-0.1022	0.0010	-0.1026	0.0001	-0.0283	0.0008	-0.0286	0.0001
	-0.1	0.0044	-0.1029	0.0057	-0.1008	-0.0699	-0.1011	-0.0694	-0.1001
2	1	0.9481	1.0009	0.9473	0.9994	0.9835	0.9992	0.9851	1.0004
	1	0.9213	0.9743	0.9376	0.9896	0.9740	0.9897	0.9779	0.9931
	0	-0.1014	0.0023	-0.1033	-0.0010	-0.0286	0.0005	-0.0285	-0.0001
	-0.1	0.0036	-0.1044	0.0064	-0.0995	-0.0694	-0.1007	-0.0695	-0.1000
3	1	0.9490	1.0011	0.9460	0.9977	0.9853	1.0009	0.9842	0.9993
	1	0.9148	0.9675	0.9346	0.9870	0.9709	0.9866	0.9761	0.9913
	0	-0.1015	0.0009	-0.1013	0.0008	-0.0281	0.0008	-0.0272	0.0009
	-0.1	0.0044	-0.1019	0.0044	-0.1016	-0.0699	-0.1009	-0.0708	-0.1011
1	1	0.9523	0.9960	0.9555	0.9994	0.9898	0.9995	0.9908	1.0006
	1	0.9298	0.9733	0.9511	0.9952	0.9808	0.9904	0.9846	0.9942
	-0.5	-0.6050	-0.5026	-0.6011	-0.4982	-0.5390	-0.5011	-0.5384	-0.5002
	-0.1	0.0074	-0.0982	0.0040	-0.1023	-0.0594	-0.0991	-0.0595	-0.0996
2	1	0.9565	1.0002	0.9570	1.0007	0.9895	0.9994	0.9895	0.9992
	1	0.9345	0.9780	0.9450	0.9880	0.9781	0.9877	0.9855	0.9951
	-0.5	-0.6006	-0.4987	-0.6032	-0.5017	-0.5390	-0.5010	-0.5394	-0.5012
	-0.1	0.0027	-0.1028	0.0056	-0.0990	-0.0602	-0.1000	-0.0589	-0.0989
3	1	0.9523	0.9964	0.9570	1.0003	0.9907	1.0006	0.9914	1.0011
	1	0.9359	0.9811	0.9411	0.9841	0.9828	0.9926	0.9836	0.9932
	-0.5	-0.6035	-0.5005	-0.6008	-0.5000	-0.5389	-0.5007	-0.5374	-0.4996
	-0.1	0.0056	-0.1010	0.0030	-0.1012	-0.0589	-0.0989	-0.0611	-0.1008

Note: Disturbance 1=normal, 2=normal-mixture and 3=gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_2)'$. W_2 is generated by rook contiguity.

Table E.10: Empirical sd and asymptotic standard errors of M-estimator, MESDPS(0,1,0)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.056	.055	.060	.055	.039	.039	.040	.039	.030	.029	.032	.030	.021	.020	.021	.021
	1	.148	.143	.159	.144	.103	.103	.109	.103	.082	.082	.088	.083	.059	.057	.060	.058
	0.5	.040	.040	.041	.036	.027	.028	.027	.025	.004	.004	.004	.004	.003	.003	.003	.003
	-0.1	.045	.049	.042	.041	.030	.034	.027	.028	.004	.005	.004	.004	.003	.003	.003	.003
2	1	.058	.056	.060	.055	.040	.039	.040	.038	.031	.029	.032	.030	.021	.021	.021	.021
	1	.149	.145	.162	.146	.106	.103	.108	.103	.083	.081	.088	.082	.058	.057	.060	.058
	0.5	.040	.040	.041	.036	.027	.028	.027	.025	.004	.004	.004	.004	.003	.003	.003	.003
	-0.1	.044	.049	.042	.041	.030	.034	.027	.028	.004	.005	.004	.004	.003	.003	.003	.003
3	1	.055	.055	.062	.055	.040	.038	.041	.038	.029	.029	.032	.029	.021	.020	.022	.021
	1	.209	.188	.131	.146	.142	.137	.084	.103	.123	.118	.063	.082	.086	.085	.041	.058
	0.5	.042	.039	.042	.037	.028	.026	.027	.025	.004	.004	.004	.004	.003	.003	.003	.003
	-0.1	.045	.047	.044	.041	.031	.031	.029	.028	.004	.004	.004	.004	.003	.003	.003	.003
1	1	.057	.057	.061	.056	.041	.040	.041	.039	.030	.030	.032	.030	.022	.021	.022	.021
	1	.153	.148	.161	.147	.103	.105	.109	.104	.084	.082	.089	.083	.059	.058	.060	.059
	0	.052	.052	.052	.046	.037	.036	.035	.032	.015	.014	.015	.013	.010	.010	.010	.009
	-0.1	.059	.064	.052	.052	.041	.044	.035	.036	.017	.017	.015	.015	.011	.012	.010	.011
2	1	.057	.057	.061	.056	.041	.040	.041	.039	.031	.030	.032	.030	.022	.021	.022	.021
	1	.150	.147	.164	.147	.109	.105	.110	.105	.083	.081	.090	.083	.059	.058	.060	.058
	0	.052	.052	.052	.046	.036	.035	.035	.032	.015	.014	.015	.014	.010	.010	.010	.009
	-0.1	.058	.064	.053	.052	.040	.043	.035	.036	.017	.018	.015	.015	.011	.012	.010	.011
3	1	.059	.056	.063	.056	.040	.039	.042	.039	.031	.030	.033	.030	.021	.021	.022	.021
	1	.195	.188	.133	.146	.146	.138	.087	.104	.117	.117	.065	.083	.086	.085	.042	.058
	0	.053	.049	.053	.046	.038	.034	.035	.032	.014	.014	.015	.013	.010	.010	.010	.009
	-0.1	.058	.059	.055	.051	.040	.040	.036	.036	.015	.017	.016	.015	.011	.012	.010	.011
1	1	.058	.055	.060	.055	.042	.039	.041	.039	.031	.029	.032	.030	.021	.021	.022	.021
	1	.149	.143	.161	.146	.104	.104	.110	.104	.084	.081	.089	.083	.056	.057	.060	.058
	-0.5	.055	.052	.057	.050	.040	.037	.038	.035	.024	.022	.026	.023	.016	.015	.017	.016
	-0.1	.062	.065	.058	.056	.044	.046	.039	.040	.027	.027	.026	.026	.018	.020	.018	.018
2	1	.057	.055	.060	.055	.039	.039	.040	.038	.030	.029	.032	.030	.020	.021	.021	.021
	1	.147	.144	.162	.146	.107	.103	.108	.103	.081	.081	.089	.082	.057	.058	.060	.058
	-0.5	.053	.052	.057	.050	.037	.036	.038	.035	.023	.022	.026	.023	.017	.015	.017	.016
	-0.1	.060	.065	.058	.056	.042	.045	.039	.039	.027	.028	.027	.026	.019	.020	.018	.018
3	1	.058	.055	.062	.055	.041	.038	.041	.038	.030	.029	.033	.030	.021	.021	.022	.021
	1	.212	.191	.132	.147	.149	.137	.085	.103	.129	.118	.064	.083	.085	.086	.042	.058
	-0.5	.057	.053	.058	.050	.040	.035	.038	.035	.025	.022	.026	.023	.017	.015	.018	.016
	-0.1	.063	.064	.060	.056	.043	.043	.040	.039	.028	.027	.027	.026	.019	.019	.018	.018

Note: Same configuration as Table E.9. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

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