

Unified M-estimation of Matrix Exponential Dynamic Panel Specification *

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Abstract

In this paper unified M-estimation method is proposed for the matrix exponential spatial dynamic panel specification (MESDPS) with fixed effect in short panels. The quasi-maximum likelihood (QML) estimation for dynamic panel data (DPD) model has long been known to have the initial condition specification difficulty, which leads to bias and inconsistency. The MESDPS also suffers from this problem. The initial-condition free M-estimator in this paper solves this problem and is proved to be consistent and asymptotic normal. An outer product of martingale difference (OPMD) estimator for the variance-covariance (VC) matrix of the M-estimator is also derived and proved to be consistent. MESDPS with a matrix exponential spatial specification (MESS) in the dependent variable, the lagged dependent variable and the disturbances are represented by MESDPS(1,1,1). Monte Carlo experiments results for finite sample properties of the M-estimator and the OPMD estimator of MESDPS(1,1,1) and various submodels are reported. The method is applied to US outward FDI data to show its validity.

Key Words: MESDPS, M-estimation, Martingale difference, OPMD, Initial-condition free

JEL Codes: C10, C13, C15, C21, C23.

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1 Introduction

Panel data (PD) models and dynamic panel data (DPD) models are important elements in Economics literature. Adding spatial dependence into PD and DPD models, the resulting spatial panel data (SPD) models (Baltagi et al. (2003), Anselin (2013)) and spatial dynamic panel data (SDPD) models (Anselin (2001), Yu et al. (2008), Lee & Yu (2010c), Yu & Lee (2010), Elhorst (2010), Su & Yang (2015)) have gained much attention. Some papers (Lee & Yu (2010b), Lee & Yu (2013), Xu & Lee (2019)) provide excellent survey on these models.

For both SPD and SDPD models, two estimation methods—general method of moment (GMM) (Mutl (2006)) and quasi maximum likelihood (QML) (Elhorst (2010), Lee & Yu (2010a), Su & Yang (2015), Yang (2018))—are available. The QML estimators (QMLE) are more efficient than GMM estimators (GMME). However there is one difficulty with QML estimation for SDPD models with short panels: the “initial condition” problem. The first observation Δy_1 for the first differenced data is endogenous in models with fixed effects, no matter whether y_0 is endogenous or exogenous. To solve this problem, the traditional way is to use the predicted value obtained from the values of regressors (Elhorst (2010), Su & Yang (2015)). But this method has its disadvantages. First process starting time is unknown and the time-varying regressors need to be trend or first-difference stationary. Second, the method does not apply to SDPD models with only spatial lags (SL) because the initial difference contains spatial effect in the exogenous part when expanded using backward substitutions. To deal with these problems, Yang (2018) proposes an initial-condition free M-estimator. The estimator is derived from a set of estimating equations based on the unbiased adjusted quasi score (AQS) functions and is consistent and asymptotically normal. It also proposes an outer product of martingale difference (OPMD) estimator for the variance-covariance (VC) matrix of the M-estimator and proves that it is consistent.

On the other hand, matrix exponential spatial specification (MESS) is first proposed by LeSage & Pace (2007). It has advantages over traditional spatial autoregressive (SAR) models: a simpler log-likelihood function without the Jacobian matrix and an unrestricted parameter space for its spatial coefficients. Debarsy et al. (2015) derive QMLE and GMME of MESS(1,1) models and explore their large sample properties, with 1’s representing MESS in the dependent variable and disturbances. Similar to SPD models, MESS can be extended to the panel models (Figueiredo & Da Silva (2015), LeSage & Chih (2018), Zhang et al. (2019)).

In this paper, the M-estimator in Yang (2018) is extended to the matrix exponential spatial dynamic panel specification (MESDPS) with fixed effect in short panels. Similar to SDPD model, the MESDPS also suffers from the “initial condition” problem. As discussed above, the traditional way of solving this problem, which is to use the predicted value derived from the values of the regressors, does not provide a satisfactory solution. A consistent way to estimate the coefficients and its VC matrix is needed. We first derive a set of conditional quasi score (CQS) functions treating the initial differences as exogenous, even if they are not. Then we modify these score functions to get the adjusted quasi score (AQS) functions which are unbiased. M-estimators thus are derived by setting AQS functions equaling to zero. To get a consistent estimate for the VC matrix of the M-estimator, a martingale difference (M.D.) of the AQS at the true value is established. The average of the outer product of M.D. (OPMD), referred to as the OPMD estimator, is shown to generate a consistent estimate of the VC matrix when substituted into the “sandwich” estimate of it. In Monte Carlo simulations six types of submodels, MESDPS(1,0,0), MESDPS(0,1,0), MESDPS(1,1,0), MESDPS(1,0,1), MESDPS(0,1,1) and MESDPS(1,1,1) are estimated, where 1’s denote

MESS in the dependent variable, the lagged dependent variable and the disturbances respectively. The results show that the M-estimator has good finite sample properties and is robust to the way the initial observation is generated, which implies that it solves the “initial condition” difficulty. The OPMD estimator of the VC matrix generates asymptotic standard errors that’s much closer to the true standard deviation than other candidates, especially when the disturbance is non-normal, emphasizing its importance in research when the normality of disturbances is in doubt. Different types of MESDPS are also applied on US outward FDI data to examine the validity of the model. [Blonigen et al. \(2007\)](#) propose four types of FDI based on different motivations of multinational enterprises and distinguish them by the sign of spatial lag term and surrounding market-potential. A modified gravity model that incorporates MESDPS is established to show the validity of the estimation. STLE from [Yang \(2018\)](#) is also reported to emphasize the relation for the spatial coefficients of these two models.

The contribution of this paper is two-fold. First the unified M-estimator is extended to MESDPS. MESS is not simply considered as substitute for SAR models. Although the relation for the spatial coefficients exists under row-normalized spatial weight matrix,¹ the difference in the parameter spaces does not grant the equivalency of these two models. The spatial coefficients in SARAR models are restricted to the range $(-1, 1)$, but the spatial coefficients in MESS has range $(-\infty, \infty)$. So it remains to be explored whether the M-estimation designed for SDPD model in [Yang \(2018\)](#) can be extended to MESDPS. Second, to our best knowledge, this is the first paper to consider MESS in a dynamic panel setting. Previous literature ([Figueiredo & Da Silva \(2015\)](#), [LeSage & Chih \(2018\)](#), [Zhang et al. \(2019\)](#)) study MESS in a panel data model. As mentioned previously, the “initial condition” problem remains when the spatial effects in the dynamic panel data model are in forms of MESS, so a consistent estimator for the coefficients and corresponding standard errors need to be designed, which is accomplished in this paper.

The rest of the paper is organized as follows. Section 2 introduces the M-estimation method. Section 3 presents the asymptotic distribution of the M-estimator and introduces the OPMD estimator of its VC matrix. Section 4 presents Monte Carlo simulation results. Section 5 applies the model to US outward FDI. Section 6 concludes.

2 M-estimation of Matrix Exponential Spatial Dynamic Panel Specification

In this section we first discuss the literature that incorporate MESS in panel data setting. Although these literature are in panel data instead of dynamic panel data setting, we include them in the review to underline the importance of our study, i.e., MESDPS has not been explored in the literature. The M-estimation and the OPMD estimator thus provide researchers who want to work with MESDPS a reliable method to estimate the parameters and conduct inference. In the second subsection we present the M-estimation in MESDPS(1,1,1) in short panel. Short panel assumes large n and small T , which is typical for most real world datasets. M-estimation first formulates a set of conditional quasi score (CQS) functions assuming that the initial difference is exogenous, and then modify it to get a set of adjusted quasi score (AQS) functions which result in consistent parameter estimates. If T becomes large but grows at the same rate with n , the approach is shown

¹In cross-section context, the spatial coefficients in SARAR(1,1) model $y_n = \lambda W_n y_n + X_n \beta + u_n$, $u_n = \tau M_n u_n + \epsilon_n$ and MESS(1,1) model $e^{\alpha W_n} y_n = X_n \beta + u_n$, $e^{\tau M_n} u_n = \epsilon_n$ have the relation $\lambda = 1 - e^\alpha$. See [Debarsy et al. \(2015\)](#), p3.

to work perfectly as well.

2.1 Matrix Exponential Spatial Dynamic Panel Specification

The matrix exponential spatial dynamic panel specification with fixed effect is given by

$$e^{\alpha_1 W_1} y_t = \tau y_{t-1} + e^{\alpha_2 W_2} y_{t-1} + X_t \beta + Z \gamma + \mu + \lambda_t l_n + u_t, \quad e^{\alpha_3 W_3} u_t = \epsilon_t, \quad t = 1, 2, \dots, T, \quad (2.1)$$

where y_t is an $n \times 1$ vector of observations on the dependent variable; W_r for $r = 1, 2, 3$ are three $n \times n$ spatial weight matrices, with corresponding spatial coefficients α_r capturing MESS in the dependent variable, lagged dependent variable and disturbances; y_{t-1} is the lagged vector of y_t with coefficient τ capturing the dynamic effect; X_t is an $n \times k$ matrix of time-varying exogenous variables with corresponding coefficient vector β ; Z is an $n \times p$ matrix of time-invariant exogenous variables, which might include the intercept, with corresponding coefficient vector γ ; μ is an $n \times 1$ vector of unobserved fixed effects; λ_t is the time-specific effects; l_n is an $n \times 1$ vector of 1; and ϵ_t is a vector of disturbances independent and identically distributed across i and t with mean zero and variance σ_ϵ^2 . The matrix exponential $e^{\alpha_r W_r}$ is defined as $\sum_{j=0}^{\infty} \frac{\alpha_r^j W_r^j}{j!}$ for $r = 1, 2$ and 3 and is always invertible with inverse $e^{-\alpha_r W_r}$ (Chiu et al. (1996)). The specification in (2.1) is comprehensive. It incorporates different submodels by setting the spatial coefficients $\alpha_r = 0$ for $r = 1, 2$ or 3.

By setting $\alpha_2 = 0$, we have MESDPS(1,0,1) with MESS in the dependent variable and disturbances:

$$e^{\alpha_1 W_1} y_t = (\tau + 1) y_{t-1} + X_t \beta + Z \gamma + \mu + \lambda_t l_n + u_t, \quad e^{\alpha_3 W_3} u_t = \epsilon_t, \quad t = 1, 2, \dots, T. \quad (2.2)$$

Without $(\tau + 1) y_{t-1}$, $Z \gamma$ and merging $\lambda_t l_n$ into $X_t \beta$, Zhang et al. (2019) study the QML estimation of (2.2) in panel data setting under heteroskedasticity. They allow large n and small or large T and establish the consistency and asymptotic normality under unknown heteroskedasticity when the spatial weight matrices in y_t and u_t are commutable.

By setting $\alpha_2 = 0$ and $\alpha_3 = 0$, we get MESDPS(1,0,0):

$$e^{\alpha_1 W_1} y_t = (\tau + 1) y_{t-1} + X_t \beta + Z \gamma + \mu + \lambda_t l_n + \epsilon_t, \quad t = 1, 2, \dots, T. \quad (2.3)$$

Figueiredo & Da Silva (2015) discusses (2.3) without $(\tau + 1) y_{t-1}$ and $Z \gamma$. It uses the deviation from mean operator to get rid of the individual and time effect and present the ML estimation of the transformed model. This approach, however, results in linear dependent disturbance after transformation. Instead, we can pre- and post-multiply the model by the orthonormal eigenvector matrix of the individual and time mean deviation operators respectively (Lee & Yu (2010a)).

The literature above incorporate MESS into a panel data model. To the best of our knowledge, MESS in a dynamic panel setting has not been studied in previous literature. The M-estimation proposed in this paper provides consistent and asymptotically normal estimates. The OPMD estimate for the VC matrix also provides excellent finite sample properties. The method is useful for those who want to utilize MESDPS in empirical research.

2.2 M-estimation of MESDPS with Fixed Effect

Different from the geometrical decay in SDPD model, (2.1) has an exponential decay. It also has a simpler quasi log-likelihood function without the Jacobian of the transformation and has an unrestricted parameter space for α_r for $r = 1, 2, 3$. The MESS can be extended to contain multiple spatial weight matrices, i.e., $e^{\sum_{s=1}^q \alpha_{rs} W_{rs}}$ for $r = 1, 2$ and 3². However, they suffer from the “initial condition” problem discussed below.

²See Debarsy et al. (2015), Appendix B.1.

Denote the true value of the parameter vector by $\theta_0 = (\beta'_0, \sigma_{\epsilon 0}^2, \tau_0, \alpha'_0)'$, where $\alpha_0 = (\alpha_{10}, \alpha_{20}, \alpha_{30})'$. Let $A_{20} = \tau_0 I_n + e^{\alpha_{20} W_2}$. Taking first difference for (2.1), we get:

$$e^{\alpha_{10} W_1} \Delta y_t = A_{20} \Delta y_{t-1} + \Delta X_t \beta_0 + \Delta u_t, e^{\alpha_{30} W_3} \Delta u_t = \Delta \epsilon_t, t = 2, 3, \dots, T. \quad (2.4)$$

where $\Delta \lambda_{t0} l_n$ is merged into $\Delta X_t \beta_0$. Note (2.4) is not defined for $t = 1$ because Δy_1 depends on Δy_0 and the latter is not observed. So even if y_0 and Δy_0 is exogenous, the likelihood function which conditions on Δy_0 cannot be formulated. Also y_1 and thus Δy_1 are not exogenous. This “initial condition” problem prevents us from deriving consistent estimates of MESDPS. The traditional way is to use the predicted values based on the observed values of regressors. However, it requires that the time-varying regressors be trend or first-difference stationary. Besides, for MESDPS with MESS in the dependent variable, for example MESDPS(1,0,0), the first differenced equation is given by $e^{\alpha_{10} W_1} \Delta y_t = (\tau_0 + 1) \Delta y_{t-1} + \Delta X_t \beta_0 + \Delta \epsilon_t$. By backward substitution, we get $\Delta y_1 = (e^{-\alpha_{10} W_1})^m \Delta y_{-m+1} + \sum_{i=0}^{m-1} (\tau_0 + 1)^i (e^{-\alpha_{10} W_1})^{i+1} \Delta X_{-i+1} \beta_0 + \sum_{i=0}^{m-1} (\tau_0 + 1)^i (e^{-\alpha_{10} W_1})^{i+1} \Delta \epsilon_{-i+1}$, where $-m$ is the process starting time. Note the exogenous part contains the spatial effect $e^{-\alpha_{10} W_1}$. The linear structure no longer exists due to the existence of the spatial effect and the linear projection method fails. Thus we need a unified way to estimate the model.

To express the model in vector form, we define the following matrices: $\Delta Y = (\Delta y'_2, \dots, \Delta y'_T)'$, $\Delta Y_{-1} = (\Delta y'_1, \dots, \Delta y'_{T-1})'$, $\Delta X = (\Delta X'_2, \dots, \Delta X'_T)'$, $\Delta u = (\Delta u'_2, \dots, \Delta u'_T)'$, $\Delta \epsilon = (\Delta \epsilon'_2, \dots, \Delta \epsilon'_T)$, $A_{20} = I_{T-1} \otimes A_{20}$ and $e^{\alpha_{r0} W_r} = I_{T-1} \otimes e^{\alpha_{r0} W_r}$ for $r = 1, 2$ and 3 . Stacking the observations vertically, the model can be expressed as:

$$e^{\alpha_{10} W_1} \Delta Y = A_{20} \Delta Y_{-1} + \Delta X \beta_0 + \Delta u, e^{\alpha_{30} W_3} \Delta u = \Delta \epsilon. \quad (2.5)$$

So $\text{var}(\Delta u) = \text{var}(e^{-\alpha_{30} W_3} \Delta \epsilon) = \sigma_{\epsilon 0}^2 (B \otimes e^{-\alpha_{30} W_3} e^{-\alpha_{30} W_3'}) = \sigma_{\epsilon 0}^2 \Sigma(\alpha_3)$, where

$$B = \begin{pmatrix} 2 & -1 & 0 & \dots & 0 & 0 & 0 \\ -1 & 2 & -1 & \dots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & -1 & 2 & -1 \\ 0 & 0 & 0 & \dots & 0 & -1 & 2 \end{pmatrix}.$$

Under normally distributed ϵ_t , the joint distribution of Δu_t can be used to derive the log-likelihood function of parameters θ :

$$\begin{aligned} \ell(\theta) = & -\frac{n(T-1)}{2} \log(2\pi) - \frac{n(T-1)}{2} \log(\sigma_{\epsilon}^2) - \frac{1}{2} \log|\Sigma(\alpha_3)| + \log|e^{\alpha_1 W_1}| \\ & - \frac{1}{2\sigma_{\epsilon}^2} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi), \end{aligned} \quad (2.6)$$

with $\theta = (\beta', \sigma_{\epsilon}^2, \tau, \alpha')'$ and $\phi = (\beta', \tau, \alpha_1, \alpha_2)'$ where ϕ are the parameters in $\Delta u(\phi) = e^{\alpha_1 W_1} \Delta Y - A_{20} \Delta Y_{-1} - \Delta X \beta$. Note $\log|\Sigma(\alpha_3)| = n \log|B| + 2(T-1) \log(e^{-\alpha_3 \text{tr}(W_3)}) = n \log|B|$ which is a constant and $\log(|e^{\alpha_1 W_1}|) = (T-1) \log(|e^{\alpha_1 \text{tr}(W_1)}|) = 0$ because the spatial weight matrices have zero diagonals. So we can ignore the constants and simplify the log-likelihood function to:

$$\ell(\theta) = -\frac{n(T-1)}{2} \log(\sigma_{\epsilon}^2) - \frac{1}{2\sigma_{\epsilon}^2} \Delta u(\phi)' \Sigma(\alpha_3)^{-1} \Delta u(\phi). \quad (2.7)$$

Given $\zeta = (\tau, \alpha')'$ with $\alpha = (\alpha_1, \alpha_2, \alpha_3)'$, we can derive the constrained estimator of β and σ_{ϵ}^2 as following:

$$\tilde{\beta}(\zeta) = (\Delta X' \Sigma(\alpha_3)^{-1} \Delta X)^{-1} \Delta X' \Sigma(\alpha_3)^{-1} (e^{\alpha_1 W_1} \Delta Y - A_{20} \Delta Y_{-1}), \quad (2.8)$$

$$\tilde{\sigma}_{\epsilon}^2(\zeta) = \frac{1}{n(T-1)} \Delta \tilde{u}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta \tilde{u}(\zeta), \quad (2.9)$$

where $\Delta \tilde{u}(\zeta) = e^{\alpha_1 W_1} \Delta Y - A_{20} \Delta Y_{-1} - \Delta X \tilde{\beta}(\zeta)$. Substituting them back into (2.7), ignoring constant, we get the concentrated log-likelihood function:

$$l^c(\zeta) = -\frac{n(T-1)}{2} \log[\Delta \tilde{u}(\zeta)' \Sigma(\alpha_3)^{-1} \Delta \tilde{u}(\zeta)] \quad (2.10)$$

The unconstrained conditional QML (CQML) estimators $\tilde{\zeta} = (\tilde{\tau}, \tilde{\alpha}')'$ are then derived by maximizing (2.10). The unconstrained CQML estimators $\tilde{\beta} = \tilde{\beta}(\tilde{\zeta})$ and $\tilde{\sigma}_\epsilon^2 = \tilde{\sigma}_\epsilon^2(\tilde{\zeta})$ are subsequently derived by substituting $\tilde{\zeta}$ into (2.8) and (2.9).

Consider the STLE model in Yang (2018), i.e., $y_t = \rho y_{t-1} + \lambda_1 W_1 y_t + \lambda_2 W_2 y_{t-1} + X_t \beta + Z \gamma + \mu + \alpha_t l_n + u_t$, $u_t = \lambda_3 W_3 u_t + \epsilon_t$, the log-likelihood function (2.7) and the concentrated log-likelihood function (2.10) are simpler without the Jacobian $\log|\mathbf{B}_1(\lambda_1)|$ where $\mathbf{B}_1(\lambda_1) = I_{T-1} \otimes B_1(\lambda_1)$ and $B_1(\lambda_1) = I_n - \lambda_1 W_1$. It makes the MESDPS computationally easier, especially for large sample sizes. A correspondence of relation for the parameters also exist for MESDPS and STLE model. Consider (2.1), assuming the spatial weight matrix is row-normalized, the total impact of a shock Δx_t on the k th independent variable X_{tk} for MESDPS is given by $\Delta y_t = e^{-\alpha_1 W_1} l_n \Delta x_t \beta_k$, so the average total impact is $\frac{1}{n} l_n' \Delta y_t = e^{-\alpha_1} \Delta x_t \beta_k$, where $W_1^k l_n = W_1 l_n = l_n$ is used. Similarly for STLE, the average total impact is given by $\frac{1}{1-\lambda_1} \Delta x_t \beta_k$. Equating them gives us the relation $\lambda_1 = 1 - e^{\alpha_1}$. For y_{t-1} , a shock $\Delta \nu_{t-1}$ leads to the average total impact $e^{-\alpha_1}(\tau + e^{\alpha_2}) \Delta \nu_{t-1}$ for MESDPS and $\frac{\rho + \lambda_2}{1-\lambda_1} \Delta \nu_{t-1}$ for STLE. So $\tau + e^{\alpha_2} = \rho + \lambda_2$. Setting $\alpha_2 = 0$ and $\lambda_2 = 0$ gives us $\rho = \tau + 1$, which implies $\lambda_2 = e^{\alpha_2} - 1$. On contrary to the negative relation between α_1 and λ_1 , the relation between α_2 and λ_2 is positive. When $-1 < \lambda_2 < 0$, α_2 also takes negative values and vice versa. However, the two models cannot be considered as substitutes of each other. When α_1 or α_2 is bigger than $\ln(2)$, the corresponding values for λ_1 is less than -1 and for λ_2 is bigger than 1. So we need to explore whether the M-estimation and the OPMD estimator of standard error can be applied to MESDPS.

The CQML estimator $\tilde{\theta} = (\tilde{\beta}', \tilde{\sigma}_\epsilon^2, \tilde{\tau}, \tilde{\alpha}')'$ derived above encounters a bias when T is small and an asymptotic bias even when T is large but grows at the same rate with n as shown below. We simplify the notation by denoting $\Sigma = \Sigma(\alpha_3)$ and $\Sigma_0 = \Sigma(\alpha_{30})$. The conditional quasi score (CQS) function $S(\theta) = \frac{\partial \ell(\theta)}{\partial \theta}$ is given by

$$S(\theta) = \begin{cases} \frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma^{-1} \Delta u(\phi), \\ -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} \Delta u(\phi)' \Sigma^{-1} \Delta u(\phi), \\ \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1}, \\ -\frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_1 e^{\alpha_1 \mathbf{W}_1} \Delta Y, \\ \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \mathbf{W}_2 e^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}, \\ -\frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi), \end{cases} \quad (2.11)$$

where $E_3 = e^{\alpha_3 W_3'} (W_3 + W_3') e^{\alpha_3 W_3}$. We will show that τ , α_1 and α_2 elements of CQS function are biased, meaning their expected values are nonzero at the true parameter values, leading to the inconsistency of the CQML estimators. First let's make Assumption 1 below.

Assumption 1: For model (2.1), (i) the processes started m periods before the start of data collection, the 0th period, (ii) if $m \geq 1$, Δy_0 is independent of future disturbances $\{\epsilon_t, t \geq 1\}$; if $m = 0$, y_0 is independent of future disturbances $\{\epsilon_t, t \geq 1\}$.

Assumption 1 is the same as the Assumption A in Yang (2018). Compared with the assumptions in previous literature (e.g. Su & Yang (2015)), Assumption 1 requires minimum information about the past processes. It does not require the time-varying regressors to be trend-stationary or first-difference stationary. This is one of the advantages of M-estimation, i.e., some restrictive

assumptions on the initial values and initial differences are removed. Denote $A_{21,0} = A_{20}e^{-\alpha_{10}W_1}$. The following lemma is necessary to compute the bias of CQS function.

Lemma 2.1. Under Assumption 1, $E(\Delta Y \Delta \epsilon') = -\sigma_{\epsilon_0}^2 e^{-\alpha_{10}W_1} D_0 e^{-\alpha_{30}W_3}$ and $E(\Delta Y_{-1} \Delta \epsilon') = -\sigma_{\epsilon_0}^2 e^{-\alpha_{10}W_1} D_{-1,0} e^{-\alpha_{30}W_3}$, where

$$D_{-1,0} = \begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_{21,0} - 2I_n & I_n & \ddots & \dots & \vdots \\ (A_{21,0} - I_n)^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ A_{21,0}^{T-4} (A_{21,0} - I_n)^2 & \dots & (A_{21,0} - I_n)^2 & A_{21,0} - 2I_n & I_n \end{pmatrix} \text{ and}$$

$$D_0 = \begin{pmatrix} A_{21,0} - 2I_n & I_n & \dots & \dots & 0 \\ (A_{21,0} - I_n)^2 & A_{21,0} - 2I_n & \ddots & \dots & \vdots \\ \vdots & \vdots & \ddots & \ddots & I_n \\ A_{21,0}^{T-3} (A_{21,0} - I_n)^2 & \dots & \dots & (A_{21,0} - I_n)^2 & A_{21,0} - 2I_n \end{pmatrix}.$$

Here we used the fact that ϵ_{it} is i.i.d. across i and t , and that $e^{\alpha_{r0}W_r}$ is always invertible for $r = 1, 3$. The latter is an advantage of MESS over the traditional SAR models, i.e., the matrix exponential is always invertible so that the VC matrix of the dependent variable always exists and is positive definite. Thus no restrictions need to be imposed on the parameter space of α .

Utilizing Lemma 2.1, we have

$$E(\Delta u' \Sigma_0^{-1} \Delta Y_{-1}) = -\sigma_{\epsilon_0}^2 \text{tr}(D_{-1,0} B^{-1} e^{-\alpha_{10}W_1}), \quad (2.12)$$

$$E(\Delta u' \Sigma_0^{-1} W_1 e^{\alpha_{10}W_1} \Delta Y) = -\sigma_{\epsilon_0}^2 \text{tr}(D_0 B^{-1} W_1), \quad (2.13)$$

$$E(\Delta u' \Sigma_0^{-1} W_2 e^{\alpha_{20}W_2} \Delta Y_{-1}) = -\sigma_{\epsilon_0}^2 \text{tr}(D_{-1,0} B^{-1} W_{21,0}), \quad (2.14)$$

where $W_{21,0} = W_2 e^{\alpha_{20}W_2} e^{-\alpha_{10}W_1}$ and $B = B \otimes I_n$. These equations imply that $E(\frac{\partial \ell(\theta)}{\partial \tau})$, $E(\frac{\partial \ell(\theta)}{\partial \alpha_1})$ and $E(\frac{\partial \ell(\theta)}{\partial \alpha_2})$ are nonzero, making τ , α_1 and α_2 elements of the CQS function biased. The set of CQS functions (2.11) are estimating functions for the CQML estimator. From previous literature (e.g., [Van der Vaart \(2000\)](#) Chapter 5), we know the consistency of an M-estimator requires the estimating function to have a probability limit of zero at the true parameter values, i.e., $\text{plim}_{n \rightarrow \infty} \frac{1}{nT} S(\theta_0) = 0$. However Lemma 2.1 implies that it does not hold for CQMLE. Typically $E(\frac{\partial \ell(\theta)}{\partial \tau})$, $E(\frac{\partial \ell(\theta)}{\partial \alpha_1})$ and $E(\frac{\partial \ell(\theta)}{\partial \alpha_2})$ are of order n , which implies $E[\sqrt{nT}(\tilde{\theta} - \theta_0)] = O(\sqrt{\frac{n}{T}})$. Even if $T \rightarrow \infty$ but grows at as fast as n , the asymptotic bias does not vanish. The bias vanishes when $\frac{n}{T} \rightarrow 0$, which refers to a large panel and is not of interest in our study. So the CQML estimation fails to produce consistent estimates.

To have a set of unbiased estimating functions, we modify them to get the adjusted quasi score (AQS) functions:

$$S^*(\theta) = \begin{cases} \frac{1}{\sigma_\epsilon^2} \Delta X' \Sigma^{-1} \Delta u(\phi), \\ -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \Delta u(\phi), \\ \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1} + \text{tr}(D_{-1} B^{-1} e^{-\alpha_1 W_1}), \\ -\frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} W_1 e^{\alpha_1 W_1} \Delta Y - \text{tr}(D B^{-1} W_1), \\ \frac{1}{\sigma_\epsilon^2} \Delta u(\phi)' \Sigma^{-1} W_2 e^{\alpha_2 W_2} \Delta Y_{-1} + \text{tr}(D_{-1} B^{-1} W_{21}), \\ -\frac{1}{2\sigma_\epsilon^2} \Delta u(\phi)' (B^{-1} \otimes E_3) \Delta u(\phi). \end{cases} \quad (2.15)$$

The M-estimator derived from the AQS functions are consistent and asymptotic normal, which will be shown in Theorem 3.1 and 3.2 respectively. It is interesting to compare the AQS functions with those in SDPD model in Yang (2018). First the bias term $tr(\mathbf{D}_{-1}\mathbf{B}^{-1}\mathbf{e}^{-\alpha_1\mathbf{W}_1})$ in the τ elements has similar format with that for the τ element³ in Yang (2018) (with MESS instead of SAR process as the multiplier). This means that while inherent spatial processes are different, the format of bias that come from the dynamic effect is not affected by the nature of the spatial structure. second thing to note is that, similar to SDPD model, the adjustments in AQS functions are free from MESS in the disturbance term, i.e., $e^{\alpha_3\mathbf{W}_3}$ is not involved in the trace terms. This implies that the AQS adjustments will not change if MESS in the disturbance term changes to other forms of spatial relationship, e.g., higher order MESS, autoregressive, moving average, etc. Third the adjustments modify the estimation of τ , α_1 and α_2 so that they become nonlinear, implying some hidden information is surfaced.

To derive the M-estimator, we first solve for the constrained M-estimators of β and σ_ϵ^2 , given $\zeta = (\tau, \alpha')'$, as

$$\hat{\beta}_M(\zeta) = (\Delta X' \Sigma^{-1} \Delta X)^{-1} \Delta X' \Sigma^{-1} (\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1}), \quad (2.16)$$

$$\hat{\sigma}_{\epsilon, M}^2(\zeta) = \frac{1}{n(T-1)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \Delta \hat{u}(\zeta), \quad (2.17)$$

where $\Delta \hat{u}(\zeta) = \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1} - \Delta X \hat{\beta}_M(\zeta)$. Then $\hat{\beta}_M(\zeta)$ and $\hat{\sigma}_{\epsilon, M}^2(\zeta)$ are substituted back into the other four elements of the AQS function $S^*(\theta)$ to get the concentrated AQS function:

$$S^{*c}(\zeta) = \begin{cases} \frac{1}{\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1} + tr(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ -\frac{1}{\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - tr(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \frac{1}{\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1} + tr(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \\ -\frac{1}{2\hat{\sigma}_{\epsilon, M}^2(\zeta)} \Delta \hat{u}(\zeta)' (\mathbf{B}^{-1} \otimes \mathbf{E}_3) \Delta \hat{u}(\zeta). \end{cases} \quad (2.18)$$

The unconstrained M-estimator $\hat{\zeta}_M = (\hat{\tau}_M, \hat{\alpha}'_M)'$ can be solved by letting $S^{*c}(\zeta) = 0$. The unconstrained M-estimators $\hat{\beta}_M$ and $\hat{\sigma}_{\epsilon, M}^2$ are then derived by substituting $\hat{\zeta}_M$ into $\hat{\beta}_M(\zeta)$ and $\hat{\sigma}_{\epsilon, M}^2(\zeta)$. Note CQMLE and M-estimator use the same set of constrained estimators of β and σ_ϵ^2 to derive unconstrained ones, i.e., $\hat{\beta}_M(\zeta) = \tilde{\beta}(\zeta)$ and $\hat{\sigma}_{\epsilon, M}^2(\zeta) = \tilde{\sigma}_\epsilon^2(\zeta)$. The advantage of M-estimation comes from the AQS function (2.15). It adjusts the estimation function so that they become unbiased. For the CQML estimation, the unconstrained estimators $\tilde{\beta}$ and $\tilde{\sigma}^2$ are biased because of the spillover from the bias of the unconstrained estimators $\tilde{\zeta}$ when being substituted into (2.8) and (2.9).

After deriving the M-estimators $\hat{\theta}_M = (\hat{\beta}'_M, \hat{\sigma}_{\epsilon, M}^2, \hat{\tau}_M, \hat{\alpha}'_M)'$, the next task is to prove its consistency, establish its asymptotic distribution and provide a consistent estimator for the VC matrix. To get a consistent estimate of VC matrix is not as straightforward as it seems, i.e., substituting the consistent M-estimator into its asymptotic VC matrix. A consistent method is needed which is presented in section 3.

3 Asymptotic Properties of the M-estimator

In this section we explore the asymptotic properties of the M-estimator. We first prove it is consistent and then derive its asymptotic distribution. To facilitate valid inference, an OPMD

³Note the differences in the definition of matrix \mathbf{D} and \mathbf{D}_{-1} with those in Yang (2018).

estimator of the VC matrix is also proposed. Valid inference can thus be based on standard errors implied by the OPMD-estimator of the VC matrix.

3.1 Consistency of the M-estimator

To prove the consistency and to later derive the asymptotic distribution of the M-estimator, we first make some regularity assumptions. Let C_n be an $n \times n$ matrix. Then C'_n , $tr(C_n)$, $|C_n|$, $\|C_n\|$, $\gamma_{min}(C_n)$ and $\gamma_{max}(C_n)$ denote the transpose, trace, determinant, Euclidean norm, the smallest and largest eigenvalues of C_n respectively.

Assumption 2. Matrices $\{W_1\}$, $\{W_2\}$ and $\{W_3\}$ are bounded in both row and column sum norms. The diagonal elements of W_1 , W_2 and W_3 are zeroes.

Assumption 3. $\{X_t\}$ is exogenous, with uniformly bounded elements, and has full column rank. Also $\lim_{n \rightarrow \infty} \frac{1}{nT} \Delta X' \Delta X$ exists and is nonsingular.

Assumption 4. There exists a constant $\delta > 0$ such that $|\alpha_r| \leq \delta$ for $r = 1, 2$ and 3 , and the true α_0 is in the interior of the parameter space \mathcal{A} . Also there exist a lower bound \underline{c}_{α_r} and an upper bound \bar{c}_{α_r} such that $0 < \underline{c}_{\alpha_r} \leq \inf_{\alpha_r \in \mathcal{A}_r} \gamma_{min}(e^{\alpha_r W'_r} e^{\alpha_r W_r}) \leq \sup_{\alpha_r \in \mathcal{A}_r} \gamma_{max}(e^{\alpha_r W'_r} e^{\alpha_r W_r}) \leq \bar{c}_{\alpha_r} < \infty$ for $r = 1, 2$ and 3 .

Assumption 5. The $\{\epsilon_{it}\}$ are i.i.d. with mean zero and variance σ_ϵ^2 , and $E|\epsilon_{it}|^{4+a}$ exists for some $a > 0$.

Assumption 6. For an $n \times n$ matrix C_n which is uniformly bounded in row and column sums, with elements of uniform order g_n^{-1} , and an $n \times 1$ vector c_n with elements of uniform order $g_n^{-1/2}$, (i) $\frac{g_n}{n} \Delta y'_1 C_n \Delta y_1 = O_p(1)$ and $\frac{g_n}{n} \Delta y'_1 C_n \Delta \epsilon_2 = O_p(1)$; (ii) $\frac{g_n}{n} [\Delta y_1 - E(\Delta y_1)]' c_n = o_p(1)$; (iii) $\frac{g_n}{n} [\Delta y'_1 C_n \Delta y_1 - E(\Delta y'_1 C_n \Delta y_1)] = o_p(1)$; (iv) $\frac{g_n}{n} [\Delta y'_1 C_n \Delta \epsilon_2 - E(\Delta y'_1 C_n \Delta \epsilon_2)] = o_p(1)$.

Assumptions 1-5 are standard in literature (e.g. [Debarsy et al. \(2015\)](#)). Assumption 6 is the same as Assumption F in [Yang \(2018\)](#). It imposes some mild conditions on the initial difference Δy_1 which will be used in the later proofs.

To prove the consistency of $\hat{\theta}_M$, we note that it follows from the consistency of $\hat{\zeta}_M$ since $\hat{\beta}_M = \hat{\beta}_M(\hat{\zeta}_M)$ and $\hat{\sigma}_{\epsilon, M}^2 = \hat{\sigma}_{\epsilon, M}^2(\hat{\zeta}_M)$. To prove the consistency of $\hat{\zeta}_M$, we first define the population counterpart of the AQS function as:

$$\bar{S}^*(\theta) = E[S^*(\theta)] = \begin{cases} \frac{1}{\sigma_\epsilon^2} E[\Delta X' \Sigma^{-1} \Delta u(\phi)], \\ -\frac{n(T-1)}{2\sigma_\epsilon^2} + \frac{1}{2\sigma_\epsilon^4} E[\Delta u(\phi)' \Sigma^{-1} \Delta u(\phi)], \\ \frac{1}{\sigma_\epsilon^2} E[\Delta u(\phi)' \Sigma^{-1} \Delta Y_{-1}] + tr(\mathbf{D}_{-1} \mathbf{B}^{-1} e^{-\alpha_1 \mathbf{W}_1}), \\ -\frac{1}{\sigma_\epsilon^2} E[\Delta u(\phi)' \Sigma^{-1} \mathbf{W}_1 e^{\alpha_1 \mathbf{W}_1} \Delta Y] - tr(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \frac{1}{\sigma_\epsilon^2} E[\Delta u(\phi)' \Sigma^{-1} \mathbf{W}_2 e^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}] + tr(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \\ -\frac{1}{2\sigma_\epsilon^2} E[\Delta u(\phi)' (\mathbf{B}^{-1} \otimes \mathbf{E}_3) \Delta u(\phi)]. \end{cases} \quad (3.1)$$

Similar to deriving the M-estimator, we can first solve for $\bar{\beta}_M(\zeta)$ and $\bar{\sigma}_{\epsilon, M}^2(\zeta)$ as:

$$\bar{\beta}_M(\zeta) = (\Delta X' \Sigma^{-1} \Delta X)^{-1} \Delta X' \Sigma^{-1} [e^{\alpha_1 \mathbf{W}_1} E(\Delta Y) - \mathbf{A}_2 E(\Delta Y_{-1})], \quad (3.2)$$

$$\bar{\sigma}_{\epsilon, M}^2(\zeta) = \frac{1}{n(T-1)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \Delta \bar{u}(\zeta)], \quad (3.3)$$

where $\Delta \bar{u}(\zeta) = e^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1} - \Delta X \bar{\beta}_M(\zeta)$. By substituting them into the last four elements of $\bar{S}^*(\theta)$, we get the population counterpart of the concentrated AQS function (2.18) as

$$\bar{S}^{*c}(\zeta) = \begin{cases} \frac{1}{\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \Delta Y_{-1}] + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{e}^{-\alpha_1 \mathbf{W}_1}), \\ -\frac{1}{\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_1 \mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y] - \text{tr}(\mathbf{D} \mathbf{B}^{-1} \mathbf{W}_1), \\ \frac{1}{\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' \Sigma^{-1} \mathbf{W}_2 \mathbf{e}^{\alpha_2 \mathbf{W}_2} \Delta Y_{-1}] + \text{tr}(\mathbf{D}_{-1} \mathbf{B}^{-1} \mathbf{W}_{21}), \\ -\frac{1}{2\bar{\sigma}_{\epsilon, M}^2(\zeta)} E[\Delta \bar{u}(\zeta)' (\mathbf{B}^{-1} \otimes \mathbf{E}_3) \Delta \bar{u}(\zeta)]. \end{cases} \quad (3.4)$$

Note ζ_0 is a zero of $\bar{S}^{*c}(\zeta)$. According to Theorem 5.9 of [Van der Vaart \(2000\)](#), if $\hat{\zeta}_M$ is a zero of $S^{*c}(\zeta)$ and ζ_0 is a zero of $\bar{S}^{*c}(\zeta)$, then $\hat{\zeta}_M$ is a consistent estimator of ζ_0 if $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} \|S^{*c}(\zeta) - \bar{S}^{*c}(\zeta)\| \xrightarrow{p} 0$ and the following Assumption holds.

Assumption 7. $\inf_{\zeta: d(\zeta, \zeta_0) \geq \nu} \|\bar{S}^{*c}(\zeta)\| > 0$ for every $\nu > 0$, where $d(\zeta, \zeta_0)$ is a measure of distance between ζ and ζ_0 .

Before we show $\sup_{\zeta \in \mathcal{Z}} \frac{1}{n(T-1)} \|S^{*c}(\zeta) - \bar{S}^{*c}(\zeta)\| \xrightarrow{p} 0$, let's first define some convenient expressions. Let $\Delta \bar{u}^*(\zeta) = \Sigma^{-\frac{1}{2}} \Delta \bar{u}(\zeta)$, $\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} = \Sigma^{-\frac{1}{2}} \mathbf{e}^{\alpha_1 \mathbf{W}_1}$, $\mathbf{A}_2^* = \Sigma^{-\frac{1}{2}} \mathbf{A}_2$, $\Delta Y^\dagger = \Delta Y - E(\Delta Y)$, $\Delta Y_{-1}^\dagger = \Delta Y_{-1} - E(\Delta Y_{-1})$, $\mathbf{P} = \Sigma^{-\frac{1}{2}} \Delta X (\Delta X' \Sigma^{-1} \Delta X)^{-1} \Delta X' \Sigma^{-\frac{1}{2}}$ and $\mathbf{M} = \mathbf{I}_{n(T-1)} - \mathbf{P}$. Then we have

$$\Delta \bar{u}^*(\zeta) = \mathbf{P}(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y^\dagger - \mathbf{A}_2^* \Delta Y_{-1}^\dagger) + \mathbf{M}(\mathbf{e}^{\alpha_1 \mathbf{W}_1^*} \Delta Y - \mathbf{A}_2^* \Delta Y_{-1}). \quad (3.5)$$

The expression will be useful in deriving $\bar{\sigma}_{\epsilon, M}^2(\zeta)$ in (3.3) in the proof for Theorem 3.1 below.

Theorem 3.1. Suppose Assumptions 1-7 hold and further the following condition $0 < \underline{c}_{\Delta Y} \leq \inf_{\zeta \in \mathcal{Z}} \gamma_{\min}[\text{var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})] \leq \sup_{\zeta \in \mathcal{Z}} \gamma_{\max}[\text{var}(\mathbf{e}^{\alpha_1 \mathbf{W}_1} \Delta Y - \mathbf{A}_2 \Delta Y_{-1})] \leq \bar{c}_{\Delta Y} < \infty$, we have $\hat{\theta}_M \xrightarrow{p} \theta_0$ as $n \rightarrow \infty$.

3.2 Asymptotic Distribution of the M-estimator

To derive the asymptotic distribution of $\hat{\theta}_M$, we apply the mean value theorem (MVT) to $S^*(\hat{\theta}_M) = 0$ at the true θ_0 to get $\sqrt{n(T-1)}(\hat{\theta}_M - \theta_0) = -(\frac{1}{n(T-1)} \frac{\partial S^*(\bar{\theta})}{\partial \theta'})^{-1} \frac{1}{\sqrt{n(T-1)}} S^*(\theta_0)$ for some $\bar{\theta}$ between θ_0 and $\hat{\theta}_M$ elementwise. Then we show that $\frac{1}{n(T-1)} \frac{\partial S^*(\bar{\theta})}{\partial \theta'}$ carries appropriate asymptotic properties and that $\frac{1}{\sqrt{n(T-1)}} S^*(\theta_0)$ is asymptotically normal. One thing to note here is that Δy_1 might not be exogenous and is unspecified, so the regular law of large numbers (LLN) and central limit theorem (CLT) for linear-quadratic forms is not sufficient. Instead we use extended LLN and CLT for bilinear-quadratic forms from [Yang \(2018\)](#) and [Su & Yang \(2015\)](#), which is listed in Lemmata A.3 and A.4. The following lemma that expresses ΔY and ΔY_{-1} in a convenient format will be crucial in deriving the asymptotic distribution and later a consistent estimate of the VC matrix. Let $\text{blkdiag}(C_1, \dots, C_n)$ be the block diagonal matrix with diagonal $n \times n$ matrices C_1, \dots, C_n . Denote $\mathbf{A}_{12,0} = e^{-\alpha_{10} \mathbf{W}_1} \mathbf{A}_{20}$.

Lemma 3.1. Under Assumptions 1, 3 and 5,

$$\Delta Y = G \Delta \mathbf{y}_1 + \boldsymbol{\delta} + K \Delta \epsilon, \quad (3.6)$$

$$\Delta Y_{-1} = G_{-1} \Delta \mathbf{y}_1 + \boldsymbol{\delta}_{-1} + K_{-1} \Delta \epsilon, \quad (3.7)$$

where $\Delta \mathbf{y}_1 = \mathbf{I}_{T-1} \otimes \Delta y_1$, $G = \text{blkdiag}[\mathbf{A}_{12,0}, (\mathbf{A}_{12,0})^2, \dots, (\mathbf{A}_{12,0})^{T-1}]$, $G_{-1} = \text{blkdiag}[\mathbf{I}_n, \mathbf{A}_{12,0}, \dots, (\mathbf{A}_{12,0})^{T-2}]$, $\boldsymbol{\delta} = \mathbf{J} e^{-\alpha_{10} \mathbf{W}_1} \Delta X \beta_0$, $\boldsymbol{\delta}_{-1} = \mathbf{J}_{-1} e^{-\alpha_{10} \mathbf{W}_1} \Delta X \beta_0$, $K = \mathbf{J} e^{-\alpha_{10} \mathbf{W}_1} e^{-\alpha_{30} \mathbf{W}_3}$, $K_{-1} = \mathbf{J}_{-1} e^{-\alpha_{10} \mathbf{W}_1} e^{-\alpha_{30} \mathbf{W}_3}$,

$$J = \begin{pmatrix} I_n & 0 & \dots & \dots & 0 \\ A_{12,0} & \ddots & \ddots & \ddots & \vdots \\ A_{12,0}^2 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ A_{12,0}^{T-2} & \dots & A_{12,0}^2 & A_{12,0} & I_n \end{pmatrix} \text{ and } J_{-1} = \begin{pmatrix} 0 & 0 & \dots & \dots & 0 \\ I_n & \ddots & \ddots & \ddots & \vdots \\ A_{12,0} & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ A_{12,0}^{T-3} & \dots & A_{12,0} & I_n & 0 \end{pmatrix}.$$

By substituting (3.6) and (3.7) into τ , α_1 and α_2 elements and $\Delta u = e^{-\alpha_{30} \mathbf{W}_3} \Delta \epsilon$ into the β, σ_ϵ^2 and α_3 elements of the AQS function (2.15) at the true value θ_0 , we get

$$S^*(\theta_0) = \begin{cases} R'_1 \Delta \epsilon, \\ -\frac{n(T-1)}{2\sigma_{\epsilon 0}^2} + \Delta \epsilon' O_1 \Delta \epsilon, \\ \Delta \epsilon' F_1 \Delta \mathbf{y}_1 + R'_2 \Delta \epsilon + \Delta \epsilon' O_2 \Delta \epsilon + tr(\mathbf{D}_{-1,0} \mathbf{B}^{-1} e^{-\alpha_{10} \mathbf{W}_1}), \\ -\Delta \epsilon' F_2 \Delta \mathbf{y}_1 - R'_3 \Delta \epsilon - \Delta \epsilon' O_3 \Delta \epsilon - tr(\mathbf{D}_0 \mathbf{B}^{-1} \mathbf{W}_1), \\ \Delta \epsilon' F_3 \Delta \mathbf{y}_1 + R'_4 \Delta \epsilon + \Delta \epsilon' O_4 \Delta \epsilon + tr(\mathbf{D}_{-1,0} \mathbf{B}^{-1} \mathbf{W}_{21,0}), \\ \Delta \epsilon' O_5 \Delta \epsilon, \end{cases} \quad (3.8)$$

where $R_1 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \Delta X$, $R_2 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \boldsymbol{\delta}_{-1}$, $R_3 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \mathbf{W}_1 e^{\alpha_{10} \mathbf{W}_1} \boldsymbol{\delta}$, $R_4 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \mathbf{W}_2 e^{\alpha_{20} \mathbf{W}_2} \boldsymbol{\delta}_{-1}$, $O_1 = \frac{1}{2\sigma_{\epsilon 0}^4} (B^{-1} \otimes I_n)$, $O_2 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) K_{-1}$, $O_3 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \mathbf{W}_1 e^{\alpha_{10} \mathbf{W}_1} K$, $O_4 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \mathbf{W}_2 e^{\alpha_{20} \mathbf{W}_2} K_{-1}$, $O_5 = -\frac{1}{2\sigma_{\epsilon 0}^2} [B^{-1} \otimes (\mathbf{W}_3 + \mathbf{W}_3')]$, $F_1 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) G_{-1}$, $F_2 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \mathbf{W}_1 e^{\alpha_{10} \mathbf{W}_1} G$ and $F_3 = \frac{1}{\sigma_{\epsilon 0}^2} (B^{-1} \otimes e^{\alpha_{30} \mathbf{W}_3}) \mathbf{W}_2 e^{\alpha_{20} \mathbf{W}_2} G_{-1}$.

Using $S^*(\theta_0)$ in (3.8), we can derive the expected Hessian of loglikelihood function and the expected variance of score function at the true value to get the asymptotic distribution of the M-estimator.

Theorem 3.2. Suppose assumptions of Theorem 3.1 hold, we have

$$\sqrt{n(T-1)}(\hat{\theta}_M - \theta_0) \xrightarrow{d} N[0, \lim_{n \rightarrow \infty} \Psi^{*-1}(\theta_0) \Omega^*(\theta_0) \Psi^{*-1}(\theta_0)], \quad (3.9)$$

where $\Psi^*(\theta_0) = -\frac{1}{n(T-1)} E \left[\frac{\partial S^*(\theta_0)}{\partial \theta'} \right]$ and $\Omega^*(\theta_0) = \frac{1}{n(T-1)} var[S^*(\theta_0)]$ are assumed to exist and $\Psi^*(\theta_0)$ is positive definite for sufficiently large n .

3.3 The OPMD Estimator of VC Matrix

In this section we derive a feasible estimator for the VC matrix $\Psi^{*-1}(\theta_0) \Omega^*(\theta_0) \Psi^{*-1}(\theta_0)$. Denote the Hessian matrix by $H^*(\theta) = \frac{\partial S^*(\theta)}{\partial \theta'}$. Then a consistent estimate of $\Psi^*(\theta_0)$ is easily derived by substituting the consistent M-estimates in, i.e., $\Psi^*(\hat{\theta}_M) = -\frac{1}{n(T-1)} H^*(\hat{\theta}_M)$. The detailed expression and the proof for the consistency of $\Psi^*(\hat{\theta}_M)$ are provided in the proof of Theorem 3.2 in Appendix C.

For $\Omega^*(\theta_0)$, however, this method does not work. This is because from (3.8) we know that τ , α_1 and α_2 element of $\Omega^*(\theta_0)$ contain the initial difference $\Delta \mathbf{y}_1$, which is unspecified. So we need to design a method that is free from the initial condition. Following Yang (2018), we propose an outer product of martingale difference (OPMD) method to consistently estimate $\Omega^*(\theta_0)$. The OPMD method first transforms $S^*(\theta_0)$ in (3.8) into a sum of vector martingale difference sequence (MDS). To be specific, we will write $R'_r \Delta \epsilon$, $\Delta \epsilon' O_r \Delta \epsilon - E(\Delta \epsilon' O_r \Delta \epsilon)$ and $\Delta \epsilon' F_r \Delta \mathbf{y}_1 - E(\Delta \epsilon' F_r \Delta \mathbf{y}_1)$ for suitable r as sums of MDS. The transformation enables us to write $\Omega^*(\theta_0)$, which is the variance

of the outer product of the sum of elements of a vector MDS, as the expected outer product of the elements of MDS because MDS has mean zero and the terms in the sum are independent (See (3.14) below). Then the averaged sum of the outer product of elements of the estimated vector MDS can be derived to be a consistent estimate of $\Omega^*(\theta_0)$.

For a square matrix $A = A^u + A^l + A^d$, let A^u , A^l and A^d be the upper-triangular, lower-triangular and diagonal matrix of A respectively. In the following we suppress the subscripts in R_r , O_r and F_r for suitable r to simplify notations. Let R_t be the $n \times k$ submatrix or $n \times 1$ subvector of R , where R could be a $n(T-1) \times K$ matrix (R_1) or $n(T-1) \times 1$ vector (R_2, R_3, R_4). Let O_{ts} and F_{ts} be the $n \times n$ submatrix of $n(T-1) \times n(T-1)$ matrix O and F respectively. Note R_t , O_{ts} and F_{ts} are partitioned by the $t, s = 2, \dots, T$. Define $F_t^+ = \sum_{s=2}^T F_{ts}$, for $t = 2, \dots, T$, $F_2^{++} = F_2^+ e^{-\alpha_{10} W_1} e^{\alpha_{30} W_3}$, $\Delta y_1^\diamond = e^{\alpha_3 W_3} e^{\alpha_{10} W_1} \Delta y_1$, $\Delta \xi = (F_2^{++u} + F_2^{++l}) \Delta y_1^\diamond$, $\Delta \eta_t = \sum_{s=2}^T (O_{st}^u + O_{st}^l) \Delta \epsilon_s$, $\Delta \epsilon_t^* = \sum_{s=2}^T O_{ts}^d \Delta \epsilon_s$, d_{it} is the i th diagonal element of BO and $\Delta y_{1t}^* = F_t^+ \Delta y_1$. Let $\{\Pi_{n,i}\}$ be the increasing sequence of σ -fields generated by $\{\epsilon_{j1}, \dots, \epsilon_{jT}; j = 1, \dots, i\}$, $i = 1, \dots, n$, $n \geq 1$. Let $\Phi_{n,0}$ be the σ -field generated by $\{\epsilon_0, \Delta y_0\}$. Define $\Phi_{n,i} = \Phi_{n,0} \otimes \Pi_{n,i}$ as the σ -field on the Cartesian product generated by subset of the form $\phi_{n,0} \times \pi_{n,i}$, where $\phi_{n,0} \in \Phi_{n,0}$ and $\pi_{n,i} \in \Pi_{n,i}$. We show in the following lemma that $S^*(\theta_0)$ can be written as sums of vector MDS.

Lemma 3.2. Suppose the assumptions of Lemma 3.1 hold, define $a_{1i} = \sum_{t=2}^T R'_{it} \Delta \epsilon_{it}$, $a_{2i} = \sum_{t=2}^T (\Delta \epsilon_{it} \Delta \eta_{it} + \Delta \epsilon_{it} \Delta \epsilon_{it}^* - \sigma_{\epsilon_0}^2 d_{it})$ and $a_{3i} = \Delta \epsilon_{2i} \Delta \xi_i + F_{2,ii}^{++} (\Delta \epsilon_{2i} \Delta y_{1i}^\diamond + \sigma_{\epsilon_0}^2) + \sum_{t=3}^T \Delta \epsilon_{it} \Delta y_{1it}^*$. Then

$$R' \Delta \epsilon = \sum_{i=1}^n a_{1i}, \quad (3.10)$$

$$\Delta \epsilon' O \Delta \epsilon - E(\Delta \epsilon' O \Delta \epsilon) = \sum_{i=1}^n a_{2i}, \quad (3.11)$$

$$\Delta \epsilon' F \Delta y_1 - E(\Delta \epsilon' F \Delta y_1) = \sum_{i=1}^n a_{3i}. \quad (3.12)$$

and $\{(a'_{1i}, a_{2i}, a_{3i})', \Phi_{n,i}\}_{i=1}^n$ forms a vector MDS.

Now using Lemma 3.3, for each R_r , define $a_{1ri} = \sum_{t=2}^T R'_{rit} \Delta \epsilon_{it}$ for $r = 1, 2, 3$ and 4; for each O_r , define $a_{2ri} = \sum_{t=2}^T (\Delta \epsilon_{it} \Delta \eta_{rit} + \Delta \epsilon_{it} \Delta \epsilon_{rit}^* - \sigma_{\epsilon_0}^2 d_{rit})$ for $r = 1, 2, 3, 4$ and 5; for each F_r , define $a_{3ri} = \sum_{t=2}^T [\Delta \epsilon_{2i} \Delta \xi_{ri} + F_{2,rii}^{++} (\Delta \epsilon_{2i} \Delta y_{1i}^\diamond + \sigma_{\epsilon_0}^2) + \sum_{t=3}^T \Delta \epsilon_{it} \Delta y_{r1it}^*]$ for $r = 1, 2$ and 3. Then we can construct a vector $a_i = (a'_{11i}, a_{21i}, a_{31i} + a_{12i} + a_{22i}, -a_{32i} - a_{13i} - a_{23i}, a_{33i} + a_{14i} + a_{24i}, a_{25i})'$. Here for the first element $E(R'_1 \Delta \epsilon) = 0$. For the second element $E(\Delta \epsilon' O_1 \Delta \epsilon) = \frac{n(T-1)}{2\sigma_{\epsilon_0}^2}$. For the third element $E(\Delta \epsilon' F_1 y_1 + R'_2 \Delta \epsilon + \Delta \epsilon' O_2 \Delta \epsilon) = -tr(D_{-1,0} B^{-1} e^{-\alpha_{10} W_1})$. For the fourth element $E(\Delta \epsilon' F_2 y_1 + R'_3 \Delta \epsilon + \Delta \epsilon' O_3 \Delta \epsilon) = -tr(D_0 B^{-1} W_1)$. For the fifth element $E(\Delta \epsilon' F_3 \Delta y_1 + R'_4 \Delta \epsilon + \Delta \epsilon' O_4 \Delta \epsilon) = -tr(D_{-1,0} B^{-1} W_2 e^{-\alpha_{10} W_1})$. For the sixth element $E(\Delta \epsilon' O_5 \Delta \epsilon) = 0$. So

$$S^*(\theta_0) = \sum_{i=1}^n a_i. \quad (3.13)$$

Since $E(a_i | \Phi_{n,i-1}) = 0$, $\{a_i, \Phi_{n,i}\}$ form a vector MDS. Together with (3.13), we thus have

$$var[S^*(\theta_0)] = E[(\sum_{i=1}^n a_i)(\sum_{i=1}^n a_i)'] - [E(\sum_{i=1}^n a_i)][E(\sum_{i=1}^n a_i)]' = \sum_{i=1}^n E(a_i a_i') \quad (3.14)$$

A consistent estimator of $\Omega^*(\theta_0)$ is then given by $\hat{\Omega}^* = \frac{1}{n(T-1)} \sum_{i=1}^n \hat{a}_i \hat{a}_i'$, where \hat{a}_i is derived by replacing θ_0 in a_i by the M-estimator $\hat{\theta}_M$. The consistency of $\hat{\Omega}^*$ and thus of the VC matrix $\Psi^{*-1}(\hat{\theta}_M) \hat{\Omega}^* \Psi^{*-1}(\hat{\theta}_M)$ follows in the theorem below.

Theorem 3.3. Under the assumptions of Theorem 3.1, as $n \rightarrow \infty$,

$$\hat{\Omega}^* - \Omega^*(\theta_0) = \frac{1}{n(T-1)} [\sum_{i=1}^n \hat{a}_i \hat{a}_i' - \sum_{i=1}^n a_i a_i'] \xrightarrow{P} 0 \quad (3.15)$$

$$\text{and thus } [\Psi^{*-1}(\hat{\theta}_M) \hat{\Omega}^* \Psi^{*-1}(\hat{\theta}_M) - \Psi^{*-1}(\theta_0) \Omega^*(\theta_0) \Psi^{*-1}(\theta_0)] \xrightarrow{P} 0. \quad (3.16)$$

The M-estimator and OPMD estimator of the VC matrix subsume submodels that contain MESS

in dependent variable, lagged dependent variable and/or disturbances. Their formats are derived in Appendix D. Different submodels are also explored in the Monte Carlo simulations in next section.

4 Monte Carlo Simulation

To fully investigate the performance of M-estimator and OPMD-based standard error, we establish the following models in the Monte Carlo simulation.

$$\text{MESDPS}(0,1,0): y_t = \tau y_{t-1} + \alpha_2 W_2 y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z \gamma + \mu + \epsilon_t,$$

$$\text{MESDPS}(1,0,0): e^{\alpha_1 W_1} y_t = \tau y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z \gamma + \mu + \epsilon_t,$$

$$\text{MESDPS}(1,1,0): e^{\alpha_1 W_1} y_t = \tau y_{t-1} + \alpha_2 W_2 y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z \gamma + \mu + \epsilon_t,$$

$$\text{MESDPS}(0,1,1): y_t = \tau y_{t-1} + \alpha_2 W_2 y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z \gamma + \mu + u_t, e^{\alpha_3 W_3} u_t = \epsilon_t,$$

$$\text{MESDPS}(1,0,1): e^{\alpha_1 W_1} y_t = \tau y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z \gamma + \mu + u_t, e^{\alpha_3 W_3} u_t = \epsilon_t,$$

$$\text{MESDPS}(1,1,1): e^{\alpha_1 W_1} y_t = \tau y_{t-1} + \alpha_2 W_2 y_{t-1} + \beta_0 l_n + X_t \beta_1 + Z \gamma + \mu + u_t, e^{\alpha_3 W_3} u_t = \epsilon_t.$$

The elements of X_n is drawn from $N(0, 4)$. Elements of Z and μ are drawn from $U(0, 1)$ and $N(0, 1)$ respectively. The spatial weight matrices are based on rook and queen contiguity. Three specifications of the disturbances ϵ_t are generated: (i) normal, (ii) normal mixture (10% $N(0, 5^2)$ and 90% $N(0, 1)$), (iii) standardized $\gamma(2, 1)$. Both (ii) and (iii) are standardized to have the same variance with (i). Four sample sizes are considered, corresponding to $n = (49, 100)$ and $T = (3, 7)$.

The values of parameters are $\beta_0 = 10$, $\beta_1 = 1$, $\gamma = 1$ and $\sigma_\epsilon = 1$ or 2. For ρ and α_r , $r = 1, 2, 3$, we select from a set of values $(-1.5, -1.1, -0.5, -0.1, 0, 0.5, 1.1, 1.5)$ in different submodels. Each experiment is replicated 1000 times. To compare the performance of the OPMD estimator, we report the empirical standard deviations (*sd*), OPMD-based standard errors (*se*), standard errors based on $\hat{\Omega}^{*-1}(\hat{se})$ and standard errors based on $\Psi^{*-1}(\hat{\theta}_M)(\hat{se})$. Better performance is represented by closer approximation to *sd*.

Table 1a presents partial results for for empirical means of CQMLE and M-estimator and Table 1b presents the empirical standard deviations and standard errors for MESDPS(0,1,0). All tables in the main paper are partial and full results can be found in the Appendix. The results show that both the M-estimator and OPMD-based standard error exhibit excellent finite sample properties. For the empirical means in Table 1a, M-estimator provides almost unbiased estimates to the true coefficients in all three disturbance specifications while the CQMLE is biased. The bias of CQMLE are significant in many cases. When n grows larger to 100, the bias does not vanish. But when T grows bigger, the bias of CQMLE nearly disappears. On the other hand, the M-estimator is nearly unbiased for all coefficients for all n and T . The rational choice of n and T means that the M-estimator is useful in many real-world applications. It brings nearly unbiased results for studies with relatively small sample sizes. For the standard errors in Table 1b, the OPMD estimator has superior performance, exhibiting much closer approximation to the empirical sd than the other two candidates in most cases, especially when disturbance follows a gamma distribution. The OPMD estimator stays close to the empirical sd for all parameters under all n , T and σ_ϵ^2 . Paying specific attention to τ under disturbance that follows gamma distribution, we find that the OPMD estimator gives especially better performance than the other two candidates of ses. This highlights the importance of conducting inference using the proposed OPMD estimator when the normality of the disturbance is in doubt. Overall the M-estimator and OPMD estimator provides good

estimates and exhibits perfect finite sample property.

Table 2a and 2b present results for MESDPS(1,0,0). Similar conclusions can be made, i.e., the M-estimator and the OPMD estimator exhibit perfect finite sample properties. From Table 2a, we observe that the M-estimation gives nearly unbiased estimates while CQMLE is quite biased in many cases. The CQMLE again does not converge to the true value when n increases to 100 while the M-estimator remains nearly unbiased regardless of the size of n . From Table 2b we see the OPMD-based ses also has good performance. It is closer to the empirical sd in nearly most parameter combinations and provides especially better results for τ when the disturbance follows gamma distribution.

Table 3a and 3b contain partial results for MESDPS(1,1,0). We observe similar results. The M-estimator performs much better than the CQMLE when $T = 3$ in most cases. For α_1 , CQMLE is almost as unbiased as M-estimator even when $T = 3$. For other coefficients, the M-estimator remains nearly unbiased for small and large T . For Table 3b, the OPMD method gives good estimates for ses, especially when disturbances are non-normal.

Table 4a and 4b present the results for MESDPS(1,0,1). It again shows that the proposed M-estimator and OPMD-based ses perform well. The M-estimator has smaller bias than CQMLE for all parameters, in many cases nearly unbiased. The OPMD-based ses better approximate the empirical standard deviations in most cases.

Table 5a and 5b present the estimation results for MESDPS(0,1,1). The CQMLE has much smaller bias when T is increased from 3 to 7, but it remains biased when n is increased from 49 to 100. For α_3 , the CQMLE and M-estimator are both biased by a similar magnitude when $T = 3$. Larger n and T erase the biases for both. For other parameters, M-estimator remains nearly perfect, even when n and T are small. The OPMD-based ses approximates the empirical sd well, especially when disturbance follows gamma distribution.

Table 6a and 6b present the results for the full model MESDPS(1,1,1). The M-estimator also provides better results than CQMLE in most cases. The bias is relatively big for α_3 when T is small even for M-estimator, but vanishes when n grows to 100 or T grows to 7. The OPMD-based se remains reliable and provides quite good estimates to the empirical sd.

5 Empirical Application to US Outward FDI

Foreign direct investment (FDI) has been discussed a lot in the literature. The FDI stock grows at a much faster rate than export and GDP. The multinational enterprises (MNEs) play important role in the process. Formal MNS theory was developed in the 1980s. Markusen (1984) and Helpman (1984) establish general equilibrium models with different motives for MNEs and coined the term "*horizontal*" and "*vertical*" FDI respectively. Horizontal FDI is for market access while vertical FDI is for access to cheaper factor inputs. A weakness of the two country framework is that it ignores third markets. Later work relax this assumption to develop more complicated models. Ekholm et al. (2007) and Yeaple (2003) propose a model in which the parent country invests in the host country to serve third market and is named "*export-platform*" FDI. Baltagi et al. (2007), on the other hand, argue MNEs can exploit local comparative advantages and set up plants in third markets. This motive is called "*complex vertical*".

Recent literature explore third market as a determinant of bilateral FDI. Coughlin et al. (1999) is the first paper to study FDI using spatial econometrics. They find a positive spatial lag (SL) and spatial error (SE) effect for China's inward FDI for neighboring regions. Baltagi et al. (2007) use

the industries and countries FDI data to explore the knowledge-capital model of US outbound FDI using generalized moments (GM) estimators. They find that the spatial coefficients are significant while evidence of various modes of FDI emerges. [Blonigen et al. \(2007\)](#) study the US outward FDI by including spatial lag in the model and find that the estimates of the traditional determinants of FDI are robust to the inclusion of spatial lag. They find a positive and significant spatial lag using the whole sample which suggests complex-vertical motivations for MNE activity. [Garretsen & Peeters \(2009\)](#) apply a spatial lag model (SLM) and spatial error model (SEM) for Dutch FDI and find positive and significant spatial effects in both. [Debarsy et al. \(2015\)](#) utilizes a cross-sectional MESS model on Belgium’s outward FDI and find evidence of pure vertical FDI. They argue that this is because Belgium has high production costs such as labor. In our study, the focus will be placed on the spatial coefficients since the dynamic nature of the model changes the situation in a significant way.

We explore the US outward FDI using MESDPS. Our data contains 40 countries from both developed and developing world over 7 years (2011-2017). The list of countries are listed in Table 7.

Table 7. List of Countries

Argentina	Australia	Belgium	Brazil	Canada	Chile	China
Cyprus	Czech	Denmark	Estonia	Finland	France	Germany
Hungary	India	Ireland	Italy	Japan	South Korea	Luxembourg
Malaysia	Mexico	Netherlands	New Zealand	Norway	Poland	Portugal
Romania	Russia	Singapore	South Africa	Spain	Sweden	Switzerland
Thailand	Turkey	Ukraine	United Kingdom	Vietnam		

The model to be estimated is a dynamic panel version of a modified gravity-type framework,

$$LFDI_{it} = \tau LFDI_{i,t-1} + \beta_1 LGDP_{it} + \beta_2 LPOP_{it} + \beta_3 LRISK_{it} + \beta_4 MP_{it} + u_{it}, \quad (3.17)$$

with corresponding spatial effects built in different models. Here $LFDI_{it}$ is the log of stock of outward FDI from US to host country i in year t . FDI are US outward positions (stocks) from International Direct Investment Statistics. The independent variables are a set of host country variables which includes log of GDP (LGDP), log of population (LPOP), log of an investment risk variable (LRISK), which is found to be important in the International Finance literature, and a surrounding-market potential variable (MP). As shown in Table 7, MP is an important characteristic to distinguish between export-platform and pure vertical FDI. We follow [Garretsen & Peeters \(2009\)](#) and compute it as the distance-weighted sums of other countries’ GDP in the sample where the distance is the bilateral distance between capitals from [Mayer & Zignago \(2011\)](#). GDP and population data are extracted from the World Bank’s World Development Indicators (WDI). Risk is the inverse of an investment profile index from International Country Risk Guide. Table 8 contains the summary statistics of these variables. The spatial weight matrix is an inverse arc-distance between capitals of host countries. Similar to [Blonigen et al. \(2007\)](#), we multiply the weights by the shortest distance between capitals (80.98 km between capitals of Estonia and Finland). The same spatial weight matrix will be applied to all spatial processes.

As discussed in section 2.2, there exists a relation between the spatial coefficients in STLE model and MESDPS⁴, i.e., $\lambda_1 = 1 - e^{\alpha_1}$, $\rho = \tau + 1$ and $\lambda_2 = e^{\alpha_2} - 1$. The M-estimation results of corresponding models in [Yang \(2018\)](#) are thus also reported to highlight the relation in

⁴STLE specification is the comprehensive model which contains the spatial lag effect, dynamic effect, space-time effect and spatial error effect. It corresponds to our MESDPS(1,1,1). See section 2.2 for the detailed model specification.

Table 8. Descriptive Statistics

Variable	Mean	Std	Min	Max
Log of FDI (\$millions)	10.09	1.97	4.09	13.75
Log of host country GDP(2010 constant dollars)	27.02	1.34	23.77	29.95
Log of host country population	17.05	1.64	13.16	21.05
Log of investment risk	-2.22	0.2	-2.48	-1.73
Surrounding market potential	25.66	2.07	22.5	27.16

interpretations of the two methods.

Table 10a and 10b summarize the estimation results. We run four specifications: SL model, MESDPS(1,0,0), STL model and MESDPS(1,1,0) for the full sample and the last 5 years. The SL and STL models are based on [Yang \(2018\)](#). All specifications contain an CQMLE and an M estimator. Table 10a contains results for SL and MESDPS(1,0,0) and 10b for STL and MESDPS(1,1,0).

We make three important observations. First we would like to emphasize the fact that the results perfectly capture the expected relation between coefficient estimates. For spatial coefficients, they satisfy the relation discussed above. In table 10a, the coefficient estimates for dynamic effects of CQMLE for SL is 0.3890 and for MESDPS(1,0,0) is -0.6074 for the full sample. For the M-estimator they are 0.6979 and -0.2978 respectively. They satisfy the relation $\rho = \tau + 1$. The similar situation is also found for the last-5-year sample. For W_1 , which represents the spatial lag in SL model and MESS in MESDPS(1,0,0) for the dependent variables, we find that the signs of CQMLE and M-estimator of coefficients are positive and negative respectively. For CQMLE, the SL model has a coefficient of -0.3058 and MESDPS(1,0,0) has a coefficient of 0.2044. For M-estimators they are -0.3415 and 0.2154 respectively. These are in line with the relation $\lambda_1 = 1 - e^{\alpha_1}$. For table 10b, the similar situation is also found. The estimates for the dynamic effect and W_1 have the similar signs and magnitudes with those in table 10a and thus satisfy the expected relation. For W_2 , we find that the coefficients are both positive. For the full sample the CQMLE are 0.1684 for STL and 0.1195 for MESDPS(1,1,0). Combined with their magnitudes, the expected relation $\lambda_2 = e^{\alpha_2} - 1$ holds. The similar situation also applies to the last-5-year sample. On the other hand, for the host variables, their coefficient estimates of CQMLE are similar for those in SL/STL and MESDPS(1,0,0)/(1,1,0) in the full sample and last-5-years sample. The similarity is also found for the M-estimator. Thus the results confirm our proposed relation between the coefficient estimates in the theory.

The second observation is that the inclusion of dynamic effects makes the coefficients of host country variables insignificant compared with the panel data case. In [Blonigen et al. \(2007\)](#) where the data from 1983 to 1998 are used, the signs for LGDP is positive and for LPOP and RISK are negative (see table 3 on p1315). The estimates are mostly significant in their study except MP variable. The insignificance of MP, combined with a positive coefficient estimate for spatially lag of LFDI, point to complex vertical FDI. In our study, however, adding in a lagged dependent variable changes the model estimates extensively. Although the estimates (except LPOP) have the same signs with those in [Blonigen et al. \(2007\)](#), they are no longer significant. The sign for spatial lag of LFDI stays significant but becomes negative. The significance of the coefficient estimates for $LFDI_{t-1}$ tells us that the inclusion of dynamic effect is an relatively important variable in explaining the variation in LFDI. The spatial terms are also significant in most cases.

The third observation is the difference between of the CQMLE and M-estimator. While in most cases they have same signs in respective groups, their magnitudes differ. For example, in table

Table 10a. Estimation results of US outbound log(FDI) for SL and MESDPS(1,0,0)

Variables	Full sample				Last 5 years			
	(1) SL		(2) MEDPS(1,0,0)		(3) SL		(4) MEDPS(1,0,0)	
	CQMLE	M-Est	CQMLE	M-Est	CQMLE	M-Est	CQMLE	M-Est
LGDP	0.7953	0.2510 (0.445)	0.7799	0.2325 (0.673)	0.2651	-0.2861 (0.441)	0.2240	-0.3909 (0.995)
LPOP	1.4047	1.1872 (1.077)	1.4003	1.1824 (0.950)	1.6485	1.1407 (1.1)	1.6142	1.0465 (1.301)
RISK	-0.1007	-0.1121 (0.101)	-0.0927	-0.1014 (0.116)	-0.0138	-0.0453 (0.156)	-0.0003	-0.0339 (0.168)
MP	-0.1953	0.0187 (1.004)	-0.2877	-0.1075 (0.850)	-0.0608	0.3485 (0.940)	-0.0684	0.3729 (1.029)
LFDI _{t-1}	0.3890	0.6979 (0.246)***	-0.6074	-0.2978 (0.306)	0.2285	0.5371 (0.116)***	-0.7579	-0.4140 (0.509)
W ₁	-0.3058	-0.3415 (0.278)	0.2044	0.2154 (0.152)*	-0.4574	-0.4573 (0.166)***	0.2898	0.2801 (0.104)***

Table 10b. Estimation results of US outbound log(FDI) for STL and MESDPS(1,1,0)

Variables	Full sample				Last 5 years			
	(5) STL		(6) MESDPS(1,1,0)		(7) STL		(8) MESDPS(1,1,0)	
	CQMLE	M-Est	CQMLE	M-Est	CQMLE	M-Est	CQMLE	M-Est
LGDP	0.7843	0.2602 (0.346)	0.7767	0.2381 (0.275)	0.2336	-0.3787 (0.541)	0.2087	-0.4591 (0.511)
LPOP	1.4665	1.2709 (0.972)*	1.4572	1.2526 (0.980)	1.609	1.0292 (1.130)	1.5947	0.9613 (1.129)
RISK	-0.0965	-0.1032 (0.108)	-0.0895	-0.0959 (0.111)	-0.0034	-0.0191 (0.167)	0.0052	-0.0123 (0.195)
MP	-0.607	-0.5238 (0.623)	-0.6047	-0.4934 (0.559)	-0.1416	0.1522 (0.908)	-0.1101	0.2051 (0.961)
LFDI _{t-1}	0.4063	0.7049 (0.147)***	-0.5977	-0.292 (0.077)***	0.2433	0.5815 (0.171)***	-0.7507	-0.3804 (0.161)***
W ₁	-0.3508	-0.3674 (0.104)***	0.2322	0.2378 (0.083)***	-0.4650	-0.4597 (0.101)***	0.2917	0.2796 (0.066)***
W ₂	0.1684	0.1991 (0.077)***	0.1195	0.1333 (0.056)***	0.0695	0.1679 (0.298)	0.0341	0.1213 (0.222)

OPMD standard errors are in parenthesis. W_1 and W_2 are spatial weight matrix in terms of SAR in SL and STL models and MESS in MESDPS(1,0,0) and MESDPS(1,1,0).

* Correspond to significance at 10%.

** Correspond to significance at 5%.

*** Correspond to significance at 1%.

10b, the estimate for $LGDP$ is 0.7843 for CQMLE in STL and 0.2602 for M-estimator in the full sample. This tells us that the M-estimator might correctly captures the impact of $LGDP$ on $LFDI$. Although we do not have a reference in this field to examine its validity, the difference do tell us that we need to be careful in using the CQMLE which provide biased results.

6 Conclusion

In this paper we proposed a consistent way to estimate the matrix exponential spatial dynamic panel specification. To the best of our knowledge, this is the first paper to tackle this problem. The comprehensive model includes matrix exponential in the dependent variable, spatial effect in the lagged dependent variable and disturbance. We also propose an OPMD estimator for the VC matrix. Valid inference can be based on the standard error derived from the OPMD estimator,

especially when the normality of the disturbance is in doubt. The method can be applied to submodels and works perfectly. The method is free from the initial condition specification and simple to use. It provides scholars a reliable way to conduct empirical research. Future research might focus on modifying the type of spatial processes in the model, for example to moving average.

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Table 1a. Empirical mean of CQMLE and M-estimator, MESDPS(0,1,0)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9537	0.9987	0.9565	1.0007	0.9934	1.0000	0.9936	1.0001
	1	0.9163	0.9607	0.9442	0.9883	0.9873	0.9942	0.9872	0.9937
	0.5	0.4245	0.5000	0.4269	0.5011	0.4948	0.5000	0.4951	0.5001
	-0.1	-0.0217	-0.1011	-0.0236	-0.1016	-0.0944	-0.1000	-0.0946	-0.1000
2	1	0.9529	0.9988	0.9560	1.0004	0.9947	1.0012	0.9941	1.0004
	1	0.9302	0.9756	0.9393	0.9828	0.9825	0.9892	0.9865	0.9930
	0.5	0.4263	0.5022	0.4265	0.5002	0.4951	0.5002	0.4950	0.5000
	-0.1	-0.0237	-0.1038	-0.0231	-0.1005	-0.0947	-0.1003	-0.0946	-0.1000
3	1	0.9565	1.0023	0.9558	0.9996	0.9916	0.9981	0.9950	1.0014
	1	0.9261	0.9731	0.9362	0.9801	0.9828	0.9896	0.9852	0.9917
	0.5	0.4267	0.5037	0.4266	0.5005	0.4951	0.5002	0.4951	0.5001
	-0.1	-0.0239	-0.1052	-0.0230	-0.1007	-0.0946	-0.1002	-0.0947	-0.1001
1	1	0.9469	0.9994	0.9465	0.9992	0.9837	0.9994	0.9848	1.0002
	1	0.9174	0.9700	0.9333	0.9853	0.9754	0.9912	0.9813	0.9968
	0	-0.1022	0.0010	-0.1026	0.0001	-0.0283	0.0008	-0.0286	0.0001
	-0.1	0.0044	-0.1029	0.0057	-0.1008	-0.0699	-0.1011	-0.0694	-0.1001
2	1	0.9481	1.0009	0.9473	0.9994	0.9835	0.9992	0.9851	1.0004
	1	0.9213	0.9743	0.9376	0.9896	0.9740	0.9897	0.9779	0.9931
	0	-0.1014	0.0023	-0.1033	-0.0010	-0.0286	0.0005	-0.0285	-0.0001
	-0.1	0.0036	-0.1044	0.0064	-0.0995	-0.0694	-0.1007	-0.0695	-0.1000
3	1	0.9490	1.0011	0.9460	0.9977	0.9853	1.0009	0.9842	0.9993
	1	0.9148	0.9675	0.9346	0.9870	0.9709	0.9866	0.9761	0.9913
	0	-0.1015	0.0009	-0.1013	0.0008	-0.0281	0.0008	-0.0272	0.0009
	-0.1	0.0044	-0.1019	0.0044	-0.1016	-0.0699	-0.1009	-0.0708	-0.1011
1	1	0.9523	0.9960	0.9555	0.9994	0.9898	0.9995	0.9908	1.0006
	1	0.9298	0.9733	0.9511	0.9952	0.9808	0.9904	0.9846	0.9942
	-0.5	-0.6050	-0.5026	-0.6011	-0.4982	-0.5390	-0.5011	-0.5384	-0.5002
	-0.1	0.0074	-0.0982	0.0040	-0.1023	-0.0594	-0.0991	-0.0595	-0.0996
2	1	0.9565	1.0002	0.9570	1.0007	0.9895	0.9994	0.9895	0.9992
	1	0.9345	0.9780	0.9450	0.9880	0.9781	0.9877	0.9855	0.9951
	-0.5	-0.6006	-0.4987	-0.6032	-0.5017	-0.5390	-0.5010	-0.5394	-0.5012
	-0.1	0.0027	-0.1028	0.0056	-0.0990	-0.0602	-0.1000	-0.0589	-0.0989
3	1	0.9523	0.9964	0.9570	1.0003	0.9907	1.0006	0.9914	1.0011
	1	0.9359	0.9811	0.9411	0.9841	0.9828	0.9926	0.9836	0.9932
	-0.5	-0.6035	-0.5005	-0.6008	-0.5000	-0.5389	-0.5007	-0.5374	-0.4996
	-0.1	0.0056	-0.1010	0.0030	-0.1012	-0.0589	-0.0989	-0.0611	-0.1008

Note: Disturbance 1=normal, 2=normal-mixture and 3=gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_2)'$.

W_2 is generated by rook contiguity.

Table 1b. Empirical sd and asymptotic standard errors of M-estimator, MESDPS(0,1,0)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.056	.055	.060	.055	.039	.039	.040	.039	.030	.029	.032	.030	.021	.020	.021	.021
	1	.148	.143	.159	.144	.103	.103	.109	.103	.082	.082	.088	.083	.059	.057	.060	.058
	0.5	.040	.040	.041	.036	.027	.028	.027	.025	.004	.004	.004	.004	.003	.003	.003	.003
	-0.1	.045	.049	.042	.041	.030	.034	.027	.028	.004	.005	.004	.004	.003	.003	.003	.003
2	1	.058	.056	.060	.055	.040	.039	.040	.038	.031	.029	.032	.030	.021	.021	.021	.021
	1	.149	.145	.162	.146	.106	.103	.108	.103	.083	.081	.088	.082	.058	.057	.060	.058
	0.5	.040	.040	.041	.036	.027	.028	.027	.025	.004	.004	.004	.004	.003	.003	.003	.003
	-0.1	.044	.049	.042	.041	.030	.034	.027	.028	.004	.005	.004	.004	.003	.003	.003	.003
3	1	.055	.055	.062	.055	.040	.038	.041	.038	.029	.029	.032	.029	.021	.020	.022	.021
	1	.209	.188	.131	.146	.142	.137	.084	.103	.123	.118	.063	.082	.086	.085	.041	.058
	0.5	.042	.039	.042	.037	.028	.026	.027	.025	.004	.004	.004	.004	.003	.003	.003	.003
	-0.1	.045	.047	.044	.041	.031	.031	.029	.028	.004	.004	.004	.004	.003	.003	.003	.003
1	1	.057	.057	.061	.056	.041	.040	.041	.039	.030	.030	.032	.030	.022	.021	.022	.021
	1	.153	.148	.161	.147	.103	.105	.109	.104	.084	.082	.089	.083	.059	.058	.060	.059
	0	.052	.052	.052	.046	.037	.036	.035	.032	.015	.014	.015	.013	.010	.010	.010	.009
	-0.1	.059	.064	.052	.052	.041	.044	.035	.036	.017	.017	.015	.015	.011	.012	.010	.011
2	1	.057	.057	.061	.056	.041	.040	.041	.039	.031	.030	.032	.030	.022	.021	.022	.021
	1	.150	.147	.164	.147	.109	.105	.110	.105	.083	.081	.090	.083	.059	.058	.060	.058
	0	.052	.052	.052	.046	.036	.035	.035	.032	.015	.014	.015	.014	.010	.010	.010	.009
	-0.1	.058	.064	.053	.052	.040	.043	.035	.036	.017	.018	.015	.015	.011	.012	.010	.011
3	1	.059	.056	.063	.056	.040	.039	.042	.039	.031	.030	.033	.030	.021	.021	.022	.021
	1	.195	.188	.133	.146	.146	.138	.087	.104	.117	.117	.065	.083	.086	.085	.042	.058
	0	.053	.049	.053	.046	.038	.034	.035	.032	.014	.014	.015	.013	.010	.010	.010	.009
	-0.1	.058	.059	.055	.051	.040	.040	.036	.036	.015	.017	.016	.015	.011	.012	.010	.011
1	1	.058	.055	.060	.055	.042	.039	.041	.039	.031	.029	.032	.030	.021	.021	.022	.021
	1	.149	.143	.161	.146	.104	.104	.110	.104	.084	.081	.089	.083	.056	.057	.060	.058
	-0.5	.055	.052	.057	.050	.040	.037	.038	.035	.024	.022	.026	.023	.016	.015	.017	.016
	-0.1	.062	.065	.058	.056	.044	.046	.039	.040	.027	.027	.026	.026	.018	.020	.018	.018
2	1	.057	.055	.060	.055	.039	.039	.040	.038	.030	.029	.032	.030	.020	.021	.021	.021
	1	.147	.144	.162	.146	.107	.103	.108	.103	.081	.081	.089	.082	.057	.058	.060	.058
	-0.5	.053	.052	.057	.050	.037	.036	.038	.035	.023	.022	.026	.023	.017	.015	.017	.016
	-0.1	.060	.065	.058	.056	.042	.045	.039	.039	.027	.028	.027	.026	.019	.020	.018	.018
3	1	.058	.055	.062	.055	.041	.038	.041	.038	.030	.029	.033	.030	.021	.021	.022	.021
	1	.212	.191	.132	.147	.149	.137	.085	.103	.129	.118	.064	.083	.085	.086	.042	.058
	-0.5	.057	.053	.058	.050	.040	.035	.038	.035	.025	.022	.026	.023	.017	.015	.018	.016
	-0.1	.063	.064	.060	.056	.043	.043	.040	.039	.028	.027	.027	.026	.019	.019	.018	.018

Note: Same configuration as Table 1a. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table 2a. Empirical mean of CQMLE and M-estimator, MESDPS(1,0,0)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9659	0.9995	0.9676	1.0006	0.9963	1.0001	0.9963	1.0000
	1	0.9279	0.9619	0.9549	0.9886	0.9901	0.9941	0.9897	0.9934
	0.5	0.4566	0.5009	0.4571	0.5011	0.4966	0.4999	0.4970	0.4999
	1.1	1.0785	1.1019	1.0776	1.1006	1.1047	1.1003	1.1039	1.1002
2	1	0.9649	0.9995	0.9677	1.0009	0.9971	1.0009	0.9968	1.0004
	1	0.9419	0.9776	0.9505	0.9837	0.9845	0.9885	0.9896	0.9933
	0.5	0.4574	0.5029	0.4574	0.5009	0.4966	0.5000	0.4970	0.4999
	1.1	1.0795	1.1037	1.0778	1.1005	1.1046	1.1002	1.1040	1.1002
3	1	0.9684	1.0024	0.9674	1.0002	0.9943	0.9980	0.9978	1.0013
	1	0.9372	0.9733	0.9480	0.9814	0.9852	0.9892	0.9880	0.9916
	0.5	0.4579	0.5032	0.4578	0.5013	0.4967	0.5001	0.4971	0.5000
	1.1	1.0789	1.1030	1.0775	1.1002	1.1044	1.1000	1.1037	1.1000
1	1	0.9539	1.0004	0.9528	0.9995	0.9924	0.9992	0.9938	1.0004
	1	0.9231	0.9723	0.9389	0.9864	0.9837	0.9910	0.9904	0.9973
	0	-0.0710	0.0026	-0.0717	0.0009	-0.0101	0.0000	-0.0099	0.0001
	1.1	1.0390	1.1041	1.0371	1.1011	1.1100	1.1022	1.1098	1.1008
2	1	0.9541	1.0012	0.9539	1.0004	0.9922	0.9990	0.9939	1.0006
	1	0.9250	0.9749	0.9436	0.9914	0.9828	0.9899	0.9867	0.9935
	0	-0.0711	0.0029	-0.0718	0.0008	-0.0099	0.0001	-0.0100	0.0000
	1.1	1.0386	1.1041	1.0367	1.1007	1.1093	1.1013	1.1099	1.1010
3	1	0.9548	1.0019	0.9522	0.9985	0.9941	1.0008	0.9926	0.9992
	1	0.9198	0.9693	0.9403	0.9885	0.9795	0.9865	0.9840	0.9909
	0	-0.0708	0.0028	-0.0708	0.0018	-0.0094	0.0006	-0.0096	0.0004
	1.1	1.0359	1.1011	1.0378	1.1019	1.1083	1.1003	1.1091	1.1005
1	1	0.9573	0.9982	0.9598	1.0003	0.9884	0.9996	0.9896	1.0005
	1	0.9351	0.9782	0.9547	0.9973	0.9793	0.9905	0.9832	0.9941
	-0.5	-0.5783	-0.4976	-0.5772	-0.4964	-0.5341	-0.5003	-0.5336	-0.5001
	1.1	0.9868	1.1042	0.9884	1.1061	1.0683	1.1011	1.0666	1.0994
2	1	0.9604	1.0014	0.9611	1.0012	0.9880	0.9995	0.9881	0.9990
	1	0.9382	0.9820	0.9481	0.9898	0.9763	0.9875	0.9839	0.9949
	-0.5	-0.5775	-0.4958	-0.5797	-0.4997	-0.5346	-0.5009	-0.5347	-0.5012
	1.1	0.9892	1.1086	0.9848	1.1016	1.0709	1.1036	1.0660	1.0988
3	1	0.9565	0.9972	0.9605	1.0000	0.9896	1.0009	0.9901	1.0010
	1	0.9389	0.9824	0.9427	0.9839	0.9819	0.9933	0.9821	0.9931
	-0.5	-0.5785	-0.4983	-0.5787	-0.5000	-0.5332	-0.4996	-0.5333	-0.5000
	1.1	0.9869	1.1037	0.9878	1.1024	1.0672	1.0998	1.0692	1.1016

Note: Disturbance 1=normal, 2=normal-mixture and 3=Gamma. Parameters $\theta = (\beta, \sigma_\epsilon^2, \tau, \alpha_1)'$.

W_1 is generated by queen contiguity.

Table 2b. Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,0,0)

dis	par	<i>sd</i>	se	\tilde{se}	\hat{se}	<i>sd</i>	se	\tilde{se}	\hat{se}	<i>sd</i>	se	\tilde{se}	\hat{se}	<i>sd</i>	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.055	.068	.059	.054	.037	.047	.040	.038	.030	.030	.032	.029	.020	.021	.021	.021
	1	.147	.153	.157	.141	.101	.112	.108	.102	.081	.112	.088	.091	.058	.072	.060	.062
	0.5	.028	.034	.027	.025	.019	.024	.018	.018	.004	.005	.004	.004	.002	.003	.002	.002
	1.1	.026	.027	.026	.024	.018	.019	.018	.017	.006	.008	.006	.006	.004	.004	.004	.004
2	1	.056	.069	.059	.054	.039	.048	.039	.038	.030	.031	.031	.029	.021	.021	.021	.021
	1	.150	.156	.160	.143	.105	.111	.107	.101	.084	.111	.088	.090	.057	.072	.060	.062
	0.5	.028	.034	.028	.025	.019	.024	.018	.018	.004	.005	.004	.004	.002	.003	.002	.002
	1.1	.026	.027	.026	.025	.018	.019	.018	.017	.006	.008	.006	.006	.004	.005	.004	.004
3	1	.054	.069	.060	.054	.039	.048	.040	.038	.029	.030	.032	.029	.021	.021	.021	.021
	1	.210	.205	.128	.143	.142	.150	.083	.101	.123	.156	.063	.090	.086	.104	.041	.062
	0.5	.031	.036	.027	.025	.020	.026	.018	.018	.004	.006	.004	.004	.002	.003	.002	.002
	1.1	.024	.026	.029	.025	.017	.018	.019	.017	.006	.009	.006	.006	.004	.005	.004	.004
1	1	.056	.075	.060	.055	.039	.053	.040	.039	.030	.031	.032	.030	.022	.022	.021	.021
	1	.153	.164	.160	.144	.104	.117	.109	.102	.083	.093	.088	.085	.059	.065	.060	.060
	0	.042	.051	.038	.035	.028	.036	.026	.025	.009	.010	.009	.009	.006	.007	.006	.006
	1.1	.051	.055	.049	.046	.036	.039	.033	.032	.020	.023	.020	.020	.014	.015	.013	.014
2	1	.058	.076	.060	.055	.040	.053	.040	.039	.030	.031	.032	.030	.021	.022	.021	.021
	1	.152	.164	.163	.144	.108	.117	.109	.102	.083	.092	.089	.085	.058	.065	.060	.059
	0	.043	.052	.038	.035	.029	.036	.026	.025	.008	.010	.009	.009	.006	.007	.006	.006
	1.1	.053	.056	.049	.046	.035	.039	.033	.032	.019	.023	.020	.020	.013	.015	.013	.014
3	1	.058	.077	.062	.055	.041	.053	.041	.039	.031	.031	.032	.029	.021	.022	.021	.021
	1	.195	.212	.131	.143	.147	.157	.085	.102	.116	.131	.063	.085	.085	.095	.041	.059
	0	.043	.056	.038	.035	.030	.039	.025	.025	.009	.011	.009	.009	.006	.008	.006	.006
	1.1	.046	.054	.054	.045	.033	.038	.036	.032	.020	.024	.020	.020	.014	.016	.013	.014
1	1	.058	.073	.060	.055	.042	.051	.040	.039	.031	.032	.032	.030	.021	.023	.022	.021
	1	.150	.162	.162	.144	.105	.118	.110	.103	.084	.085	.089	.083	.056	.060	.060	.058
	-0.5	.049	.059	.045	.042	.034	.042	.031	.029	.021	.021	.021	.019	.014	.015	.014	.013
	1.1	.101	.107	.097	.090	.069	.076	.065	.063	.052	.051	.052	.049	.035	.036	.035	.035
2	1	.056	.073	.060	.055	.040	.051	.040	.038	.030	.032	.032	.030	.020	.023	.022	.021
	1	.150	.163	.162	.145	.107	.117	.108	.102	.081	.084	.089	.082	.057	.060	.060	.058
	-0.5	.048	.059	.046	.042	.033	.042	.031	.029	.021	.021	.021	.019	.014	.015	.014	.013
	1.1	.099	.107	.097	.090	.070	.076	.065	.063	.052	.051	.051	.049	.036	.036	.035	.035
3	1	.058	.075	.062	.055	.040	.051	.041	.038	.030	.032	.033	.030	.021	.023	.022	.021
	1	.212	.216	.131	.145	.149	.155	.084	.102	.129	.123	.064	.083	.085	.089	.042	.058
	-0.5	.051	.064	.045	.042	.035	.045	.029	.029	.021	.022	.021	.019	.014	.016	.014	.013
	1.1	.100	.107	.103	.090	.066	.075	.068	.063	.049	.050	.053	.049	.035	.036	.035	.035

Note: Same configuration as Table 2a. Here *sd* is empirical standard deviation, **se** is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table 3a. Empirical mean of CQMLE and M-estimator, MESDPS(1,1,0)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9865	0.9977	0.9878	0.9991	0.9981	0.9995	0.9990	1.0005
	1	0.9544	0.9661	0.9784	0.9900	0.9860	0.9875	0.9913	0.9928
	-1.5	-1.5307	-1.5001	-1.5295	-1.4988	-1.5098	-1.4998	-1.5095	-1.4994
	1.1	1.1007	1.1031	1.1013	1.1027	1.0953	1.0986	1.0982	1.1017
	-0.5	-0.4636	-0.5023	-0.4662	-0.5038	-0.4863	-0.4982	-0.4879	-0.5002
2	1	0.9892	1.0003	0.9902	1.0013	0.9980	0.9995	0.9978	0.9993
	1	0.9568	0.9685	0.9728	0.9840	0.9830	0.9845	0.9923	0.9939
	-1.5	-1.5285	-1.4978	-1.5302	-1.5001	-1.5096	-1.4995	-1.5102	-1.5001
	1.1	1.1012	1.1027	1.0985	1.1002	1.0958	1.0992	1.0958	1.0991
	-0.5	-0.4664	-0.5038	-0.4613	-0.4981	-0.4870	-0.4989	-0.4869	-0.4990
3	1	0.9854	0.9964	0.9896	1.0006	0.9990	1.0006	0.9995	1.0010
	1	0.9597	0.9718	0.9694	0.9808	0.9878	0.9894	0.9900	0.9915
	-1.5	-1.5313	-1.5007	-1.5301	-1.5000	-1.5089	-1.4987	-1.5093	-1.4993
	1.1	1.1006	1.1028	1.0993	1.1010	1.0991	1.1025	1.0962	1.0996
	-0.5	-0.4651	-0.5036	-0.4668	-0.5041	-0.4863	-0.4983	-0.4892	-0.5013

Note: Disturbance 1=normal, 2=normal-mixture and 3=Gamma. Parameters $\theta = (\beta, \sigma_e^2, \tau, \alpha_1, \alpha_2)'$.

W_1 and W_2 are generated by rook and queen contiguity respectively.

Table 3b. Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,1,0)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.054	.051	.057	.052	.038	.036	.038	.036	.030	.029	.032	.029	.021	.020	.021	.021
	1	.141	.135	.158	.140	.100	.099	.106	.100	.084	.080	.089	.082	.056	.057	.060	.057
	-1.5	.037	.034	.040	.035	.026	.024	.027	.025	.019	.018	.021	.019	.013	.013	.014	.013
	1.1	.073	.071	.079	.072	.050	.051	.053	.051	.043	.043	.047	.043	.030	.031	.032	.031
	-0.5	.079	.077	.084	.077	.056	.055	.057	.055	.041	.040	.044	.041	.028	.029	.030	.029
2	1	.052	.051	.057	.052	.037	.036	.038	.036	.029	.029	.032	.029	.020	.020	.021	.021
	1	.141	.136	.157	.140	.103	.098	.105	.100	.080	.080	.089	.081	.057	.057	.060	.058
	-1.5	.036	.034	.040	.035	.025	.024	.027	.025	.019	.018	.021	.019	.014	.013	.014	.013
	1.1	.073	.071	.079	.072	.052	.050	.053	.051	.043	.043	.047	.043	.031	.030	.032	.031
	-0.5	.077	.075	.083	.076	.056	.055	.056	.054	.042	.041	.044	.041	.029	.029	.030	.029
3	1	.054	.051	.060	.052	.037	.036	.039	.036	.029	.029	.033	.029	.021	.020	.021	.020
	1	.206	.183	.127	.141	.145	.134	.081	.099	.128	.117	.064	.082	.085	.085	.041	.057
	-1.5	.036	.034	.042	.035	.025	.024	.027	.025	.019	.018	.021	.019	.013	.013	.014	.013
	1.1	.074	.071	.082	.072	.051	.050	.054	.051	.045	.043	.048	.043	.031	.030	.032	.031
	-0.5	.080	.076	.086	.076	.054	.054	.058	.054	.040	.040	.045	.041	.029	.029	.030	.029

Note: Same configuration as Table 3a. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table 4a. Empirical mean of CQMLE and M-estimator, MESDPS(1,0,1)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9769	0.9971	0.9793	0.9997	0.9941	0.9992	0.9956	1.0005
	1	0.9374	0.9634	0.9629	0.9898	0.9809	0.9868	0.9866	0.9926
	-0.5	-0.5608	-0.5012	-0.5589	-0.4982	-0.5241	-0.5010	-0.5235	-0.5000
	0.5	0.4398	0.5050	0.4382	0.5067	0.4915	0.5027	0.4866	0.4998
	-1.1	-1.0764	-1.1122	-1.0687	-1.1082	-1.0999	-1.1071	-1.0901	-1.0987
2	1	0.9796	0.9996	0.9802	1.0003	0.9933	0.9984	0.9948	0.9997
	1	0.9419	0.9682	0.9569	0.9832	0.9783	0.9842	0.9875	0.9935
	-0.5	-0.5580	-0.4983	-0.5611	-0.5012	-0.5243	-0.5011	-0.5245	-0.5010
	0.5	0.4455	0.5117	0.4356	0.5035	0.4960	0.5077	0.4856	0.4986
	-1.1	-1.0694	-1.1073	-1.0672	-1.1070	-1.0990	-1.1069	-1.0923	-1.1008
3	1	0.9760	0.9963	0.9788	0.9989	0.9956	1.0007	0.9956	1.0004
	1	0.9436	0.9707	0.9527	0.9790	0.9836	0.9897	0.9853	0.9913
	-0.5	-0.5606	-0.5004	-0.5600	-0.5004	-0.5233	-0.5000	-0.5233	-0.5000
	0.5	0.4389	0.5067	0.4389	0.5070	0.4900	0.5016	0.4900	0.5026
	-1.1	-1.0599	-1.0995	-1.0665	-1.1079	-1.0978	-1.1050	-1.0938	-1.1020

Note: Disturbance 1=normal, 2=normal-mixture and 3=Gamma. Parameters $\theta = (\beta, \sigma_e^2, \tau, \alpha_1, \alpha_3)'$.

W_1 and W_3 are generated by rook and queen contiguity respectively.

Table 4b. Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,0,1)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.044	.042	.046	.042	.031	.029	.031	.029	.024	.024	.026	.024	.017	.017	.017	.017
	1	.144	.137	.159	.141	.102	.100	.108	.102	.084	.081	.089	.082	.056	.057	.060	.058
	-0.5	.041	.037	.041	.037	.029	.026	.028	.027	.019	.017	.019	.018	.013	.012	.013	.013
	0.5	.121	.116	.123	.115	.084	.082	.083	.081	.068	.069	.071	.068	.048	.049	.049	.048
	-1.1	.159	.153	.166	.152	.110	.105	.110	.105	.087	.085	.094	.086	.059	.060	.063	.061
2	1	.044	.042	.046	.042	.029	.029	.031	.029	.025	.024	.026	.024	.016	.017	.017	.017
	1	.144	.138	.159	.142	.105	.100	.107	.101	.080	.080	.089	.082	.057	.058	.060	.058
	-0.5	.040	.037	.042	.037	.028	.026	.028	.026	.018	.017	.020	.018	.013	.012	.013	.013
	0.5	.116	.116	.123	.114	.085	.082	.083	.081	.069	.068	.072	.068	.048	.049	.049	.048
	-1.1	.158	.154	.166	.152	.109	.105	.110	.105	.085	.085	.093	.086	.061	.060	.063	.060
3	1	.044	.043	.048	.042	.029	.030	.031	.029	.024	.023	.026	.024	.017	.017	.017	.017
	1	.207	.184	.129	.142	.147	.134	.083	.100	.129	.118	.064	.082	.085	.085	.042	.058
	-0.5	.042	.039	.041	.037	.030	.027	.027	.026	.019	.017	.020	.018	.013	.012	.013	.013
	0.5	.122	.112	.131	.114	.083	.080	.086	.080	.067	.067	.074	.067	.048	.049	.049	.048
	-1.1	.152	.152	.174	.152	.106	.103	.115	.105	.085	.084	.097	.086	.062	.059	.064	.060

Note: Same configuration as Table 4a. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table 5a. Empirical mean of CQMLE and M-estimator, MESDPS(0,1,1)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9915	0.9983	0.9930	0.9999	0.9985	0.9994	0.9996	1.0005
	1	0.9585	0.9650	0.9821	0.9888	0.9862	0.9872	0.9916	0.9926
	-1.5	-1.5282	-1.5000	-1.5264	-1.4979	-1.5097	-1.5005	-1.5090	-1.4996
	0.5	0.5108	0.5011	0.5095	0.4994	0.4993	0.4999	0.5000	0.5002
	-1.1	-1.0753	-1.0769	-1.0883	-1.0891	-1.0945	-1.0947	-1.0931	-1.0932
2	1	0.9936	1.0003	0.9945	1.0012	0.9988	0.9997	0.9985	0.9993
	1	0.9599	0.9665	0.9775	0.9840	0.9830	0.9840	0.9928	0.9938
	-1.5	-1.5253	-1.4967	-1.5284	-1.5004	-1.5098	-1.5006	-1.5095	-1.5002
	0.5	0.5085	0.4983	0.5100	0.5002	0.4983	0.4987	0.4993	0.4996
	-1.1	-1.0554	-1.0563	-1.0884	-1.0889	-1.0886	-1.0889	-1.0988	-1.0990
3	1	0.9894	0.9961	0.9934	1.0001	0.9996	1.0005	0.9999	1.0008
	1	0.9624	0.9691	0.9731	0.9797	0.9884	0.9894	0.9904	0.9914
	-1.5	-1.5299	-1.5014	-1.5275	-1.4994	-1.5090	-1.4998	-1.5087	-1.4994
	0.5	0.5111	0.5009	0.5087	0.4987	0.5007	0.5011	0.4985	0.4988
	-1.1	-1.0554	-1.0563	-1.0844	-1.0848	-1.0892	-1.0894	-1.0954	-1.0956

Note: Disturbance 1=normal, 2=normal-mixture and 3=Gamma. Parameters $\theta = (\beta, \sigma_e^2, \tau, \alpha_2, \alpha_3)'$.

W_2 and W_3 are generated by rook and queen contiguity respectively.

Table 5b. Empirical sd and asymptotic standard errors of M-estimator, MESDPS(0,1,1)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.047	.044	.050	.045	.033	.032	.034	.032	.027	.025	.028	.026	.018	.018	.019	.018
	1	.140	.134	.157	.139	.099	.098	.106	.100	.084	.080	.088	.082	.056	.057	.060	.057
	-1.5	.037	.035	.040	.036	.027	.025	.027	.025	.018	.018	.020	.018	.013	.013	.013	.013
	0.5	.033	.032	.035	.032	.023	.023	.024	.023	.022	.021	.023	.022	.015	.015	.016	.015
	-1.1	.198	.199	.214	.197	.142	.139	.143	.138	.111	.109	.119	.110	.076	.078	.081	.078
2	1	.046	.045	.050	.045	.032	.031	.033	.032	.026	.025	.028	.026	.017	.018	.019	.018
	1	.141	.135	.156	.139	.102	.098	.105	.099	.080	.080	.089	.081	.057	.057	.060	.057
	-1.5	.038	.035	.041	.036	.025	.024	.027	.025	.018	.018	.020	.018	.013	.013	.013	.013
	0.5	.033	.032	.035	.032	.023	.022	.024	.023	.022	.021	.023	.021	.015	.015	.016	.015
	-1.1	.202	.197	.213	.196	.140	.138	.144	.138	.111	.109	.119	.110	.078	.078	.081	.078
3	1	.048	.044	.052	.045	.032	.031	.034	.032	.025	.025	.029	.026	.018	.018	.019	.018
	1	.204	.182	.125	.139	.145	.133	.080	.099	.128	.117	.064	.082	.085	.085	.041	.057
	-1.5	.037	.035	.042	.036	.025	.025	.027	.025	.018	.018	.020	.018	.013	.013	.013	.013
	0.5	.034	.032	.036	.032	.023	.023	.024	.023	.022	.021	.024	.021	.015	.015	.016	.015
	-1.1	.204	.194	.224	.196	.136	.136	.148	.137	.111	.107	.122	.110	.077	.077	.083	.078

Note: Same configuration as Table 5a. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.

Table 6a. Empirical mean of CQMLE and M-estimator, MESDPS(1,1,1)

dis	par	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est	CQMLE	M-est
		n=49, T=3		n=100, T=3		n=49, T=7		n=100, T=7	
1	1	0.9360	0.9979	0.9392	1.0001	0.9839	1.0003	0.9840	1.0004
	1	0.8965	0.9568	0.9269	0.9868	0.9702	0.9845	0.9767	0.9909
	-0.5	-0.6370	-0.4984	-0.6328	-0.4961	-0.5502	-0.4997	-0.5506	-0.5002
	1.1	1.0286	1.1000	1.0337	1.1031	1.0815	1.1013	1.0805	1.1000
	1.1	1.0893	1.1006	1.0913	1.1019	1.1016	1.1012	1.1009	1.1002
	1.1	1.1984	1.1643	1.1591	1.1287	1.1277	1.1169	1.1235	1.1131
2	1	0.9392	1.0009	0.9409	1.0013	0.9826	0.9994	0.9831	0.9994
	1	0.8995	0.9604	0.9209	0.9798	0.9666	0.9808	0.9778	0.9919
	-0.5	-0.6339	-0.4945	-0.6354	-0.4998	-0.5509	-0.5004	-0.5510	-0.5007
	1.1	1.0290	1.1001	1.0333	1.1024	1.0796	1.0996	1.0802	1.0997
	1.1	1.0882	1.0990	1.0916	1.1022	1.1002	1.0998	1.1007	1.1001
	1.1	1.2135	1.1844	1.1568	1.1275	1.1332	1.1226	1.1175	1.1074
3	1	0.9357	0.9969	0.9400	1.0001	0.9841	1.0010	0.9851	1.0013
	1	0.8995	0.9607	0.9172	0.9759	0.9717	0.9862	0.9764	0.9905
	-0.5	-0.6364	-0.4982	-0.6329	-0.4985	-0.5509	-0.5001	-0.5489	-0.4988
	1.1	1.0241	1.0944	1.0302	1.0985	1.0807	1.1009	1.0815	1.1007
	1.1	1.0856	1.0957	1.0883	1.0986	1.1012	1.1010	1.1010	1.1003
	1.1	1.2181	1.1889	1.1647	1.1360	1.1320	1.1209	1.1202	1.1102

Note: Disturbance 1=normal, 2=normal-mixture and 3=Gamma. Parameters $\theta = (\beta, \sigma_e^2, \tau, \alpha_1, \alpha_2, \alpha_3)'$.

W_1 , W_2 and W_3 are generated by queen, rook and queen contiguity respectively.

Table 6b. Empirical sd and asymptotic standard errors of M-estimator, MESDPS(1,1,1)

dis	par	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}	sd	se	\tilde{se}	\hat{se}
		n=49, T=3				n=100, T=3				n=49, T=7				n=100, T=7			
1	1	.064	.063	.067	.062	.045	.044	.044	.043	.033	.032	.034	.032	.022	.022	.023	.022
	1	.152	.147	.167	.148	.106	.107	.113	.107	.085	.082	.091	.083	.056	.058	.061	.058
	-0.5	.070	.062	.068	.061	.048	.043	.045	.043	.027	.026	.028	.026	.019	.018	.019	.018
	1.1	.095	.100	.099	.094	.066	.069	.065	.065	.048	.048	.049	.046	.033	.034	.033	.033
	1.1	.075	.080	.080	.076	.053	.056	.053	.053	.041	.041	.042	.040	.028	.029	.028	.028
	1.1	.231	.229	.240	.221	.161	.158	.158	.153	.121	.121	.130	.120	.084	.086	.088	.085
2	1	.063	.063	.067	.061	.043	.044	.044	.043	.033	.032	.034	.032	.022	.022	.023	.022
	1	.153	.147	.168	.149	.108	.106	.112	.106	.082	.082	.091	.083	.057	.059	.061	.058
	-0.5	.070	.062	.068	.061	.047	.043	.044	.042	.028	.025	.029	.026	.019	.018	.019	.018
	1.1	.093	.100	.099	.094	.063	.068	.065	.065	.048	.048	.049	.046	.033	.034	.033	.033
	1.1	.075	.081	.080	.076	.051	.055	.052	.052	.041	.041	.042	.040	.028	.029	.028	.028
	1.1	.235	.228	.239	.220	.156	.157	.158	.153	.125	.121	.130	.120	.085	.086	.088	.085
3	1	.064	.062	.070	.061	.044	.044	.045	.043	.032	.032	.035	.032	.023	.022	.023	.022
	1	.209	.192	.141	.149	.151	.140	.090	.105	.129	.118	.067	.083	.086	.086	.043	.058
	-0.5	.072	.063	.070	.061	.049	.043	.045	.042	.029	.025	.029	.026	.019	.018	.019	.018
	1.1	.097	.100	.104	.095	.063	.068	.067	.065	.047	.048	.050	.046	.032	.034	.033	.033
	1.1	.078	.081	.084	.076	.050	.055	.054	.052	.040	.041	.043	.040	.027	.029	.029	.028
	1.1	.236	.227	.252	.221	.151	.155	.163	.153	.121	.119	.134	.120	.085	.085	.090	.085

Note: Same configuration as Table 6a. Here sd is empirical standard deviation, se is OPMD estimator, \tilde{se} is standard error based on $\hat{\Omega}^{*-1}$ and \hat{se} based on $\Psi^{*-1}(\hat{\theta}_M)$.