



MECH0064 MSc Group Design Project

# Compact Continuum Robotic Manipulator Platform

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# Abstract

This is the Abstract of the final report.

*Key Words: Continuum Robotic e.g.*

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# **1 Introduction**

This is the Introduction of the final report.[1]

Introduction including market survey.

## **1.1 Background**

This is the background part.

## **1.2 Motivation**

This is the motivation part.

## 2 Literature Review

This is the Literature Review of the final report.

### 2.1 part ??

unknown

### 2.2 part ??

unknown



### **3 Design**

This is the Design of the final report.

#### **3.1 part ??**

unknown

#### **3.2 part ??**

unknown

#### **3.3 part ??**

unknown

## 4 Result and Discussion

This is the Result and Discussion of the final report.

### 4.1 part ??

unknown

### 4.2 part ??

unknown

### 4.3 part ??

unknown

### 4.4 part ??

unknown

### 4.5 part ??

unknown

### 4.6 part ??

unknown

### 4.7 part ??

unknown

### 4.8 part ??

unknown

## **4.9 part ??**

unknown

## **4.10 part ??**

unknown

## **4.11 part ??**

unknown

## 5 Conclusion

This is the Conclusion of the final report.

# References

1. Benner, S. A. Synthetic biology: Act natural. *Nature* **421**, 118–118 (2003).

# Appendix A

## TEST

This is the Appendix 1.

# Appendix B

## Test

This is the Appendix 2.