



MECH0064 MSc Group Design Project

Compact Continuum Robotic Manipulator Platform

Group members:

Zehao Ye (23119333) Zehao Ye (23119333)

Zehao Ye (23119333) Zehao Ye (23119333)

Zehao Ye (23119333) Zehao Ye (23119333)

Supervised by Dr Reza Haqshenas

Abstract

This is the Abstract of the final report.

Key Words: Continuum Robotic e.g.

Contents

	Page
Abstract	I
List of Figures	II
List of Tables	III
1. Introduction	1
1.1 Background	1
1.2 Motivation	1
2. Literature Review	2
2.1 part ??	2
2.2 part ??	2
3. Design	3
3.1 part ??	3
3.2 part ??	3
3.3 part ??	3
4. Result and Discussion	4
4.1 part ??	4
4.2 part ??	4
4.3 part ??	4
4.4 part ??	4
4.5 part ??	4
4.6 part ??	4
4.7 part ??	4
4.8 part ??	4
4.9 part ??	5
4.10 part ??	5

4.11	part ??	5
5.	Conclusion	6
References		i
A. TEST		ii
B. Test		iii

List of Figures

List of Tables

1 Introduction

This is the Introduction of the final report.[1]

Introduction including market survey. Introduction including market survey.

1.1 Background

This is the background part.

1.2 Motivation

This is the motivation part.

2 Literature Review

This is the Literature Review of the final report.

2.1 part ??

unknown

2.2 part ??

unknown

3 Design

This is the Design of the final report.

3.1 part ??

unknown

3.2 part ??

unknown

3.3 part ??

unknown

4 Result and Discussion

This is the Result and Discussion of the final report.

4.1 part ??

unknown

4.2 part ??

unknown

4.3 part ??

unknown

4.4 part ??

unknown

4.5 part ??

unknown

4.6 part ??

unknown

4.7 part ??

unknown

4.8 part ??

unknown

4.9 part ??

unknown

4.10 part ??

unknown

4.11 part ??

unknown

5 Conclusion

This is the Conclusion of the final report.

References

1. Benner, S. A. Synthetic biology: Act natural. *Nature* **421**, 118–118 (2003).

Appendix A

TEST

This is the Appendix 1.

Appendix B

Test

This is the Appendix 2.