

MECH0064 MSc Group Design Project

Compact Continuum Robotic Manipulator Platform

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Abstract

This is the Abstract of the final report.

Key Words: Continuum Robotic e.g.

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1 Introduction

This is the Introduction of the final report.[1]

Introduction including market survey. Introduction including market survey.

1.1 Background

This is the background part.

1.2 Motivation

This is the motivation part.

2 Literature Review

This is the Literature Review of the final report.

2.1 part ??

unknown

2.2 part ??

3 Design

This is the Design of the final report.

3.1 part ??

unknown

3.2 part ??

unknown

3.3 part ??

4 Result and Discussion

This is the Result and Discussion of the final report.

4.1 part ??

unknown

4.2 part ??

unknown

4.3 part ??

unknown

4.4 part ??

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4.5 part ??

unknown

4.6 part ??

unknown

4.7 part ??

unknown

4.8 part ??

4.9 part ??

unknown

4.10 part ??

unknown

4.11 part ??

5 Conclusion

This is the Conclusion of the final report.

References

1. Benner, S. A. Synthetic biology: Act natural. $Nature~\mathbf{421},~118-118~(2003).$

Appendix A

TEST

This is the Appendix 1.

Appendix B

Test

This is the Appendix 2.