

#### MECH0064 MSc Group Design Project

# Compact Continuum Robotic Manipulator Platform

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#### Abstract

This is the Abstract of the final report.

Key Words: Continuum Robotic e.g.

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This is the Introduction of the final report.

#### 1.1 Background

This is the background part.

#### 1.2 Motivation

This is the motivation part.

#### 2 Literature Review

This is the Literature Review of the final report.

#### 2.1 part ??

unknown

#### 2.2 part ??

#### 3 Design

This is the Design of the final report.

#### 3.1 part ??

unknown

#### 3.2 part ??

unknown

#### 3.3 part ??

#### 4 Result and Discussion

This is the Result and Discussion of the final report.

#### 4.1 part ??

unknown

#### 4.2 part ??

unknown

#### 4.3 part ??

unknown

#### 4.4 part ??

unknown

#### 4.5 part ??

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#### 4.6 part ??

unknown

#### 4.7 part ??

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#### 4.8 part ??

#### 4.9 part ??

unknown

#### 4.10 part ??

unknown

#### 4.11 part ??

### 5 Conclusion

This is the Conclusion of the final report.

# Appendix 1: test

This is the Appendix 1.