

**Suggested Solutions to Problem Set 5**

Today's Date: November 10, 2017

1. JR Exercise 3.4

**Soln:** Since  $x^1$  is on the same ray from the origin as is  $x^0$ ,  $t \geq 0$  exists such that  $x^1 = tx^0$ . We must prove  $t = f^{-1}(y)/f^{-1}(1)$ . Now, since  $f(g(x^0)) = 1$ , we have

$$g(x^0) = f^{-1}(1). \quad (1)$$

Similarly, since  $f(g(tx^0)) = y$ , we have

$$g(tx^0) = f^{-1}(y).$$

This and the linear homogeneity of  $g$  imply

$$tg(x^0) = f^{-1}(y).$$

Lastly, this and (1) yield the desired result:

$$t = \frac{f^{-1}(y)}{g(x^0)} = \frac{f^{-1}(y)}{f^{-1}(1)}.$$

■

2. Prove this part of JR's Theorem 3.4: If  $f$  is homogeneous of degree  $\alpha > 0$ , then

$$c(w, y) = y^{1/\alpha} c(w, 1), \quad x(w, y) = y^{1/\alpha} x(w, 1).$$

**Soln:** We obtain the first equation as follows:

$$\begin{aligned} c(w, y) &= \min_x w \cdot x \text{ such that } f(x) \geq y \\ &= \min_x w \cdot x \text{ such that } y^{-1} f(x) \geq 1 \\ &= \min_x w \cdot x \text{ such that } f(y^{-1/\alpha} x) \geq 1 \text{ } (\because \text{homogeneity}) \\ &= \min_z w \cdot y^{1/\alpha} z \text{ such that } f(z) \geq 1 \text{ } \left( \text{change variable to } z := y^{-1/\alpha} x \right) \\ &= y^{1/\alpha} \left\{ \min_z w \cdot z \text{ such that } f(z) \geq 1 \right\} \\ &= y^{1/\alpha} c(w, 1). \end{aligned}$$

We obtain the second equation from Hotelling's lemma: for any  $i$ ,

$$x_i(w, y) = \frac{\partial c(w, y)}{\partial w_i} = \frac{\partial y^{1/\alpha} c(w, 1)}{\partial w_i} = y^{1/\alpha} x_i(w, 1).$$

■

3. JR Exercise 3.25

**Soln:** We assume  $f$  has positive first derivatives, and consider prices  $(p, w)$  such that  $y := y(p, w) > 0$ . The FOC for maximizing profit using the cost function is then

$$p = mc(y).$$

Letting  $x := x(p, w)$ , the FOC for profit maximization using the production function directly is, for each  $i$ ,

$$pMP_i(x) \leq w_i \quad (= \text{ if } x_i > 0).$$

Substituting  $mc(y)$  for  $p$  in this FOC yields the desired result:

$$mc(y) \leq \frac{w_i}{MP_i(x)} \quad (= \text{ if } x_i > 0).$$

Think about the interpretation of this result. ■

4. JR Exercise 3.34 (in (c), “shares” should be “cost shares,”  $s_i = w_i x_i(w, y)/c(w, y)$ ).

- (a) **Soln:** By Euler’s theorem (JR page 564),  $c(w, y)$  is homogeneous of degree 1 in  $w$  iff for all  $(w, y)$ ,

$$\sum_k c_k(w, y) w_k = c(w, y).$$

where  $c_k = \partial c / \partial w_k$ . Simplify notation by using  $\hat{\cdot}$  for  $\ln$ , as in  $\hat{w}_k = \ln(w_k)$ . Then, differentiating the expression that defines  $c$  with respect to  $w_k$  yields

$$\frac{c_k(w, y)}{c(w, y)} = \frac{\alpha_k}{w_k} + \sum_j \gamma_{kj} \frac{\hat{w}_j}{w_k}.$$

Hence, using the given restriction that  $\sum_k \gamma_{kj} = 0$  for all  $j$ , we have

$$\begin{aligned} \sum_k c_k(w, y) w_k &= \left( \sum_k \alpha_k + \sum_k \sum_j \gamma_{kj} \hat{w}_j \right) c(w, y) \\ &= \left( \sum_k \alpha_k + \sum_j \hat{w}_j \sum_k \gamma_{kj} \right) c(w, y) = \left( \sum_k \alpha_k \right) c(w, y). \end{aligned}$$

We conclude that  $c$  is linearly homogeneous in  $w$  iff  $\sum_k \alpha_k = 1$ . ■

- (b) **Soln:** The sufficient condition for  $c$  to take the Cobb-Douglas form is that  $\gamma_{ij} = 0$  for all  $i, j$ . For, if this holds we have

$$c(w, y) = \exp \left( \alpha_0 + \sum_i \alpha_i \hat{w}_i + \hat{y} \right) = \exp(\alpha_0) y \prod_i w_i^{\alpha_i},$$

which is of the Cobb-Douglas form. ■

(c) **Soln:** The input cost share for good  $i$  is given by

$$\begin{aligned}
 s_i &= \frac{w_i x_i(w, y)}{c(w, y)} \\
 &= \frac{\partial c(w, y)}{\partial w_i} \frac{w_i}{c(w, y)} \quad (\because \text{Hotelling's Lemma}) \\
 &= \frac{\partial \ln(c(w, y))}{\partial \ln(w_i)} \\
 &= \alpha_i + \sum_j \gamma_{ij} \ln(w_j) \quad (\because \gamma_{ij} = \gamma_{ji}),
 \end{aligned}$$

which is linear in logs of input prices (and, trivially, output). ■

#### 5. JR Exercise 3.36

**Soln:** Wlog, by appropriately choosing the units in which output is measured, we can assume the Cobb-Douglas production function is  $f(x) = x_1^\alpha x_2^{1-\alpha}$  for some  $\alpha \in (0, 1)$ . The long-run cost function is

$$C^L(w, y) = \min_{x_1, x_2 \geq 0} w_1 x_1 + w_2 x_2 \text{ such that } y \leq x_1^\alpha x_2^{1-\alpha}.$$

Assuming  $y > 0$ , the constraint implies that the solution satisfies  $x \gg 0$ , and the constraint clearly binds (as otherwise costs could be lowered by lowering each  $x_i$ ). Hence, the FOCs are

$$\begin{aligned}
 w_1 &= \lambda \alpha x_1^{\alpha-1} x_2^{1-\alpha}, \\
 w_2 &= \lambda (1 - \alpha) x_1^\alpha x_2^{-\alpha},
 \end{aligned}$$

where  $\lambda$  is the Lagrangian multiplier on the constraint. We thus have

$$\frac{w_1}{w_2} = \frac{\alpha}{1 - \alpha} \frac{x_2}{x_1},$$

or  $x_2 = \frac{1-\alpha}{\alpha} \frac{w_1}{w_2} x_1$ . Substituting this into  $y = x_1^\alpha x_2^{1-\alpha}$  yields

$$y = x_1^\alpha \left( \frac{1-\alpha}{\alpha} \frac{w_1}{w_2} x_1 \right)^{1-\alpha} \Leftrightarrow x_1(w, y) = \left( \frac{1-\alpha}{\alpha} \frac{w_1}{w_2} \right)^{\alpha-1} y,$$

and so

$$x_2(w, y) = \left( \frac{1-\alpha}{\alpha} \frac{w_1}{w_2} \right)^\alpha y.$$

Thus,

$$C^L(w, y) = w_1 x_1(w, y) + w_2 x_2(w, y) = K w_1^\alpha w_2^{1-\alpha} y,$$

where  $K = (1 - \alpha)^{\alpha-1} \alpha^{-\alpha}$ . The long-run average and marginal cost functions are thus

$$\begin{aligned}
 lac(w, y) &= \frac{C^L(w, y)}{y} = K w_1^\alpha w_2^{1-\alpha}, \\
 lmc(w, y) &= \frac{\partial C^L(w, y)}{\partial y} = K w_1^\alpha w_2^{1-\alpha}.
 \end{aligned}$$

We see that  $lac$  and  $lmc$  are constant in  $y$  and equal to each other.

The short-run cost function, for any fixed  $x_2 = \bar{x}_2 > 0$ , is

$$C^S(w, \bar{x}_2, y) = \min_{x_1 \geq 0} w_1 x_1 + w_2 \bar{x}_2 \text{ such that } y \leq x_1^\alpha \bar{x}_2^{1-\alpha}.$$

Again we see that the constraint binds, and so  $x_1 = (\bar{x}_2^{\alpha-1} y)^{1/\alpha}$ . Substituting this into the objective function yields

$$C^S(w, \bar{x}_2, y) = w_1 \bar{x}_2^{1-\frac{1}{\alpha}} y^{1/\alpha} + w_2 \bar{x}_2.$$

The short-run average cost function is

$$sac(w, \bar{x}_2, y) = w_1 \bar{x}_2^{1-\frac{1}{\alpha}} y^{\frac{1}{\alpha}-1} + w_2 \bar{x}_2 y^{-1}.$$

Letting  $y^{\min}$  be the  $y$  that minimizes  $sac(w, \bar{x}_2, y)$ , we find  $y^{\min}$  from the FOC:

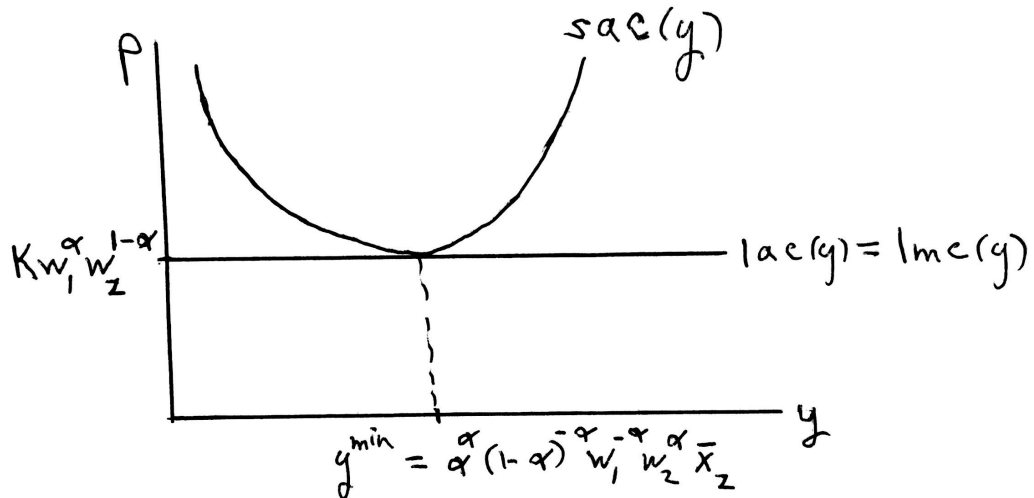
$$\begin{aligned} \frac{\partial sac(w, \bar{x}_2, y)}{\partial y} = 0 &\Leftrightarrow \left( \frac{1}{\alpha} - 1 \right) w_1 \bar{x}_2^{1-\frac{1}{\alpha}} y^{\frac{1}{\alpha}-2} - w_2 \bar{x}_2 y^{-2} = 0 \\ &\Leftrightarrow \left( \frac{1}{\alpha} - 1 \right) w_1 \bar{x}_2^{1-\frac{1}{\alpha}} y^{\frac{1}{\alpha}} - w_2 \bar{x}_2 = 0 \\ &\Leftrightarrow y = \alpha^\alpha (1-\alpha)^{-\alpha} w_1^{-\alpha} w_2^\alpha \bar{x}_2 =: y^{\min}. \end{aligned}$$

To complete the problem, we need only show that  $sac(w, \bar{x}_2, y^{\min}) = lac(w, y^{\min})$ :

$$\begin{aligned} sac(w, \bar{x}_2, y^{\min}) &= w_1 \bar{x}_2^{1-\frac{1}{\alpha}} \left\{ \alpha^\alpha (1-\alpha)^{-\alpha} w_1^{-\alpha} w_2^\alpha \bar{x}_2 \right\}^{\frac{1}{\alpha}-1} + w_2 \bar{x}_2 \left\{ \alpha^\alpha (1-\alpha)^{-\alpha} w_1^{-\alpha} w_2^\alpha \bar{x}_2 \right\}^{-1} \\ &= \alpha^{1-\alpha} (1-\alpha)^{\alpha-1} w_1^\alpha w_2^{1-\alpha} + \alpha^{-\alpha} (1-\alpha)^\alpha w_1^\alpha w_2^{1-\alpha} \\ &= \left\{ \alpha \alpha^{-\alpha} (1-\alpha)^{\alpha-1} + \alpha^{-\alpha} (1-\alpha)^{\alpha-1} (1-\alpha) \right\} w_1^\alpha w_2^{1-\alpha} \\ &= \alpha^{-\alpha} (1-\alpha)^{\alpha-1} \{ \alpha + (1-\alpha) \} w_1^\alpha w_2^{1-\alpha} \\ &= \alpha^{-\alpha} (1-\alpha)^{\alpha-1} w_1^\alpha w_2^{1-\alpha} \\ &= K w_1^\alpha w_2^{1-\alpha} = lac(w, y^{\min}). \end{aligned}$$

■

The figure below is for  $\alpha \leq 1/2$  (for  $\alpha > 1/2$ ,  $sac(y)$  becomes concave as  $y \rightarrow \infty$ ).



Vertical = cost per unit output, Horizontal = output

6. A competitive firm has a  $C^2$  production function  $f(x_1, x_2)$  for which, at any  $x \in \mathbb{R}_+^2$ ,  $\nabla f(x) \gg 0$  and  $J(x) := [f_{ij}(x)]$  is negative definite. Let  $x(p, w)$  and  $y(p, w)$  be the firm's demand and supply functions. Using the first-order conditions for profit maximization, show that at any  $(p, w) \gg 0$  for which the the firm's input demands are positive, we have

- (a)  $\partial y / \partial p > 0$  (Strict Law of Supply),
- (b)  $\partial x_1 / \partial p > 0$  or  $\partial x_2 / \partial p > 0$ , and
- (c)  $\partial x_i / \partial w_i < 0$  (Strict Law of Demand).

[Hint: The inverse of a ND matrix is also ND.]

**Soln:** Since  $y(p, w) = f(x(p, w))$ , we have

$$\frac{\partial y}{\partial p} = f_1 \frac{\partial x_1}{\partial p} + f_2 \frac{\partial x_2}{\partial p} = \nabla f \cdot \frac{\partial x}{\partial p}. \quad (2)$$

Hence, since  $\nabla f(x) \gg 0$ , (b) follows immediately from (a). It remains to prove (a) and (b). To do so, we use the FOC conditions,

$$\begin{aligned} p f_1(x(p, w)) &= w_1, \\ p f_2(x(p, w)) &= w_2. \end{aligned}$$

To prove (a), differentiating with respect to  $p$ , and dropping the arguments of the functions to improve readability, yields

$$\begin{aligned} f_1 + p f_{11} \frac{\partial x_1}{\partial p} + p f_{12} \frac{\partial x_2}{\partial p} &= 0, \\ f_2 + p f_{21} \frac{\partial x_1}{\partial p} + p f_{22} \frac{\partial x_2}{\partial p} &= 0, \end{aligned}$$

or rather,

$$\begin{bmatrix} p & f_{11} & f_{12} \\ & f_{21} & f_{22} \end{bmatrix} \begin{pmatrix} \partial x_1 / \partial p \\ \partial x_2 / \partial p \end{pmatrix} = \begin{pmatrix} -f_1 \\ -f_2 \end{pmatrix},$$

which can be written even more parsimoniously as

$$p J \frac{\partial x}{\partial p} = -(\nabla f).$$

We can solve this system of equations for the vector  $\partial x / \partial p$  by dividing by  $p$  and left-multiplying both sides by the matrix  $J^{-1}$  to obtain

$$\frac{\partial x}{\partial p} = -\frac{1}{p} J^{-1} (\nabla f).$$

Now multiply both sides on the left by the transpose of  $\nabla f$  to obtain

$$\nabla f \cdot \frac{\partial x}{\partial p} = -\frac{1}{p} (\nabla f)^T J^{-1} (\nabla f).$$

Thus, in light of (2), we have

$$\frac{\partial y}{\partial p} = -\frac{1}{p} (\nabla f)^T J^{-1} (\nabla f) > 0,$$

where the inequality holds because  $J^{-1}$  is ND,  $\nabla f \neq 0$ , and  $p > 0$ .

We prove (c) similarly, and just for  $i = 1$  (the proof for  $i = 2$  is the same). Differentiating the FOC with respect to  $w_1$  again yields two linear equations that can be solved for  $\partial x / \partial w_1 = (\partial x_1 / \partial w_1, \partial x_2 / \partial w_1)^T$ . Doing so yields

$$\frac{\partial x}{\partial w_1} = \frac{1}{p} J^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{p} \begin{pmatrix} a \\ c \end{pmatrix},$$

where  $a$  is the  $(i, j) = (1, 1)$  element of  $J^{-1}$  and  $c$  is the  $(i, j) = (2, 1)$  element. Hence,

$$\frac{\partial x}{\partial w_1} = \frac{1}{p} a < 0,$$

where the inequality holds because  $a < 0$ , since  $J^{-1}$  is ND, and  $p > 0$ . ■