

# SIGGRAPH 2008

## Simulation and Rendering Massive Crowds of Intelligent and Detailed Creatures on GPU

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# Outline

- Motivation
- Crowd movement simulation on GPU
  - Global and local navigation and avoidance
- Lighting solution
- Crowd rendering and scene management on GPU
- Conclusions



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# Driving Visual Experience Frontiers

- Our task is to push the envelope for interactive visual experience
  - “What does it mean to have better interactive experiences?”
- Beyond just the pretty face
  - We know we can do that... We've done it!
  - Can we make them think?



rhinofx

ATI



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# We Can Even Make Them Dream!



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# Motivation

- Making the gameplay more fun: A game is a series of choices...
  - It helps when choices are interesting!
- Artificial intelligence is ubiquitous in current games
  - Non-player and player characters require a form of AI
  - Path finding, obstacle avoidance, decisions, etc.



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# Motivation

- CPU can spend > 50% time on path finding computations alone in games
  - Limits possible decision complexity
  - Thus we frequently see “zombie-like” NPCs
  - Gameplay suffers
- Emergent behaviors improve any game with many characters
  - Making it more fun!



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# Top Level Overview

- Goal: Simulate and render massive crowds of characters on GPU at a scale that's both breathtaking and challenging
- Direct3D® 10.1
- Tessellation
- 4X MSAA
- HD resolution and HDR rendering



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# A Smörgåsbord of Features

- Dynamic pathfinding AI computations on GPU
- Massive crowd rendering with LOD management
- Tessellation for high quality close-ups and stable performance
- HDR lighting and post-processing effects with gamma-correct rendering
- Terrain system
- Cascade shadows for large-range environments
- Advanced global illumination system



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# Introducing the Froblins



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**Radeon**  
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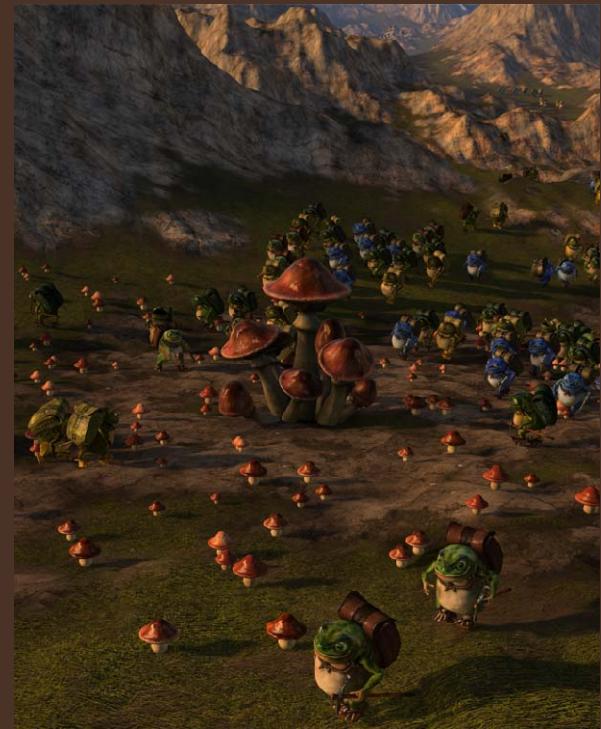


# Motivation: Beware of Ghosts!!



# Dynamic and Engaging World Through AI

- Combine global path finding with local avoidance and individual decisions
- Crowd movement is more stable and realistic solved on a global scale
  - Crowd dynamics similar to fluids
  - Agents “flow” towards the closest goal, along the path of least resistance
  - Froblins follow correct paths and do not “get stuck”



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# Global Path Finding

- Based on *Continuum Crowds* [TCP06]
- Convert motion planning into an optimization problem
  - Use continuum model
  - Computational algorithms from optics
- Smooth flow-like crowd movement
  - Congestion avoidance and emergent behavior



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# Pathfinding on GPU

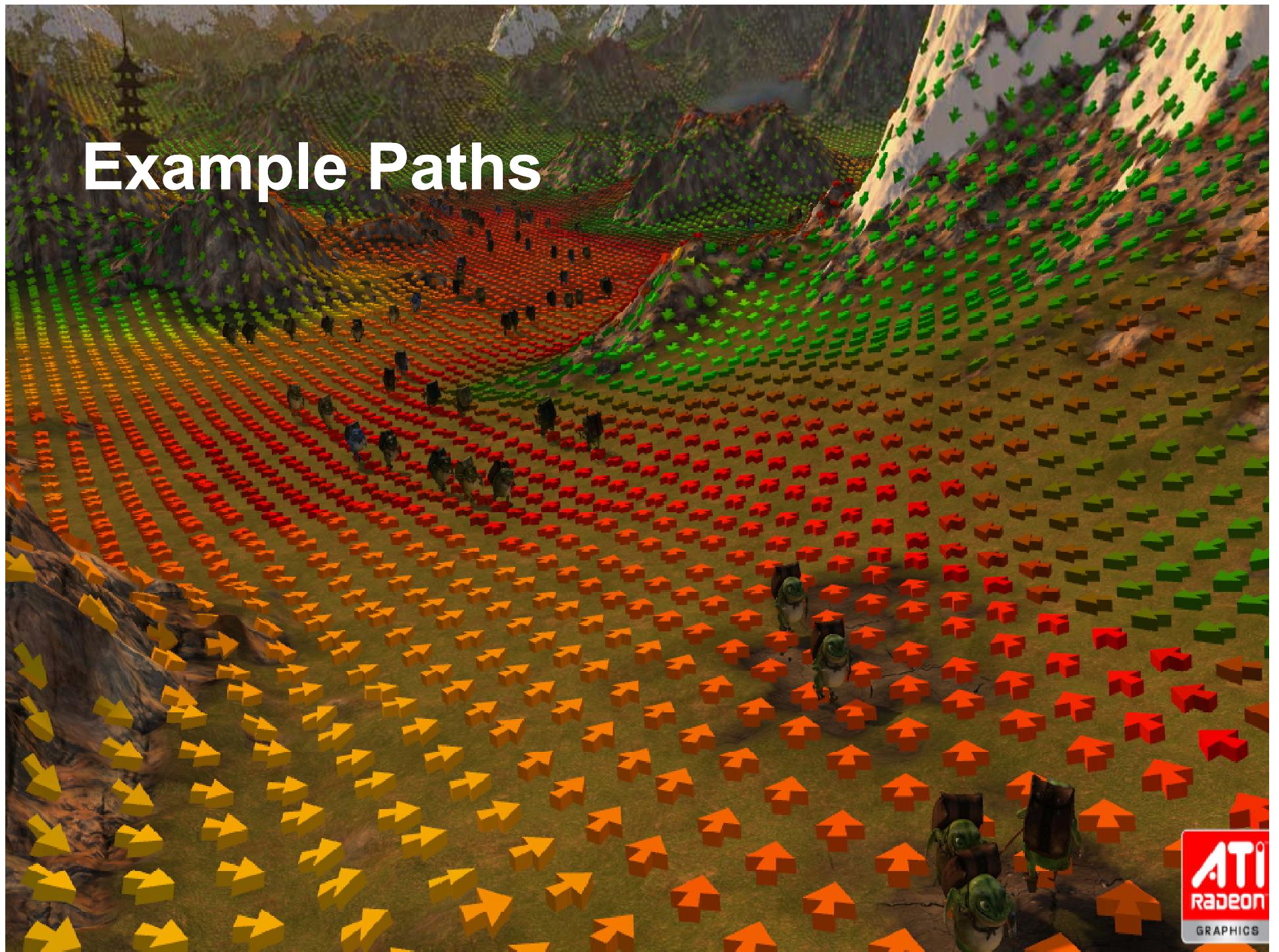
- Numerically solve a 2<sup>nd</sup> order PDE on GPU with a computational iterative approach (eikonal solver)
  - Represent environment as a cost field
  - Through discretization of the eikonal equation
- Applicable to many general algorithms and areas



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# Example Paths



# Solver: From Cost to Travel Time

- Solve for travel time as a function of potential
- *Potential*  $\varphi$  = integrated cost  $F$  along shortest path to goal
  - Follow negative gradient
- Set potential = 0 at goal, eikonal equation elsewhere
- Comes from optimization algorithms

$$\|\nabla \varphi(x)\| = F$$



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# Eikonal Solver via Fast Marching Method

- Emulates Dijkstra's shortest path algorithm
- A finite difference approximation to the continuous eikonal equation
  - Start from known potential ( $\varphi=0$  at goal) and propagate to neighbors until convergence
  - Compute potential for neighbor cells based on known cells
- Serial algorithm; requires an ordered data structure



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# Parallel Eikonal Solver

- Using *Fast Iterative Method* [JW07]
- Use upwind finite difference approximation but no ordered data structures
- We use small grid resolutions ( $128^2$  - $256^2$ )
- Solve for four goals at once
  - Taking advantage of vectorization – use RGBA FP16 texture
- Convergence determined empirically



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# Environment As Cost Function

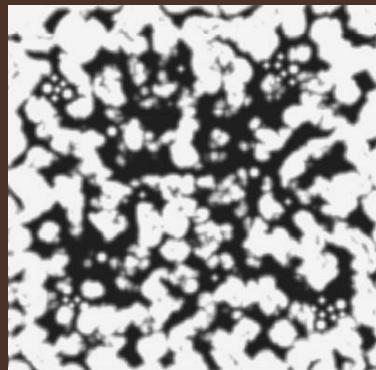
- Continuum Model models environment as a positive cost function
  - Can't be zero otherwise agents would move at infinite speed; add some small base amount
- Incorporate information about terrain and obstacles (static and dynamic)
  - Splat dynamic obstacles, including agents into the cost function



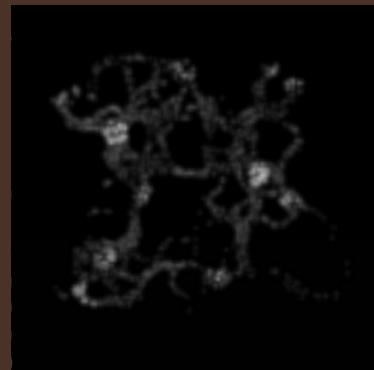
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# Cost Function Formulation



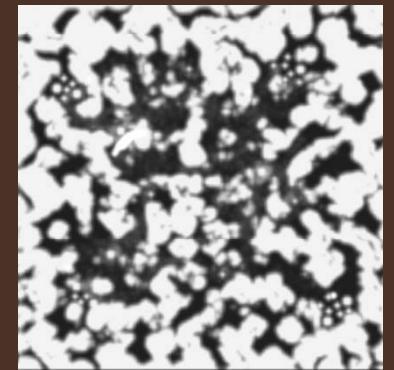
+



+



=



Static Cost

Agent Density

Hazards

Total Cost



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# Local Navigation and Avoidance

- Global model not great for local obstacles
  - Performance & No need to avoid agent far away
- Update velocity based on positions and velocities of nearby agents/obstacles
  - Based on Velocity Obstacle formulation [Fiorini and Shiller 1998]
  - See course notes for more details & Jeremy Shopf's talk on in ***Beyond Programmable Shading: In Action*** course

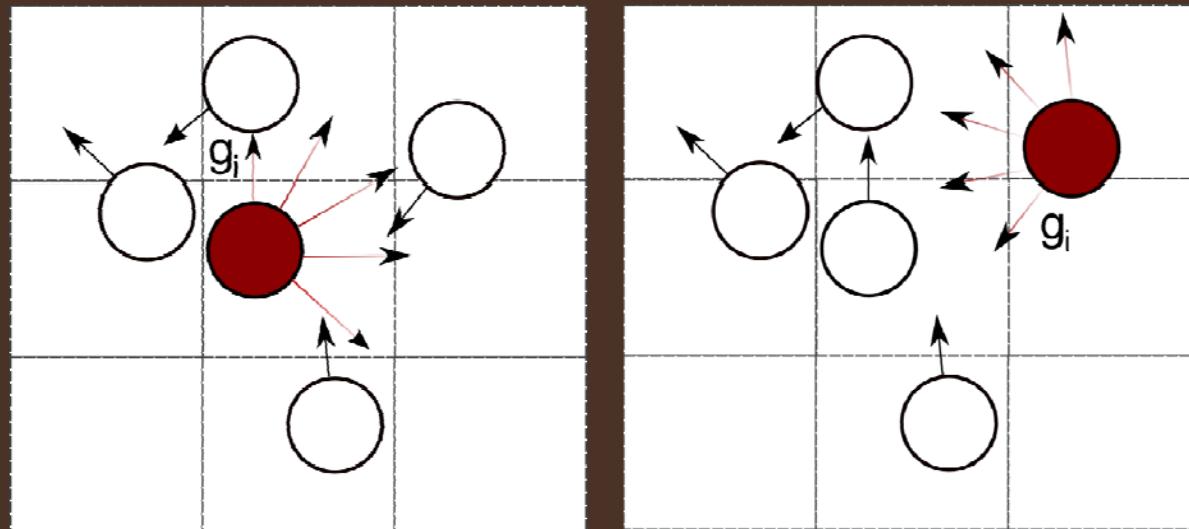


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# Direction Determination

- Evaluate a fixed set of possible directions relative to global navigation direction



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# Spatial Queries

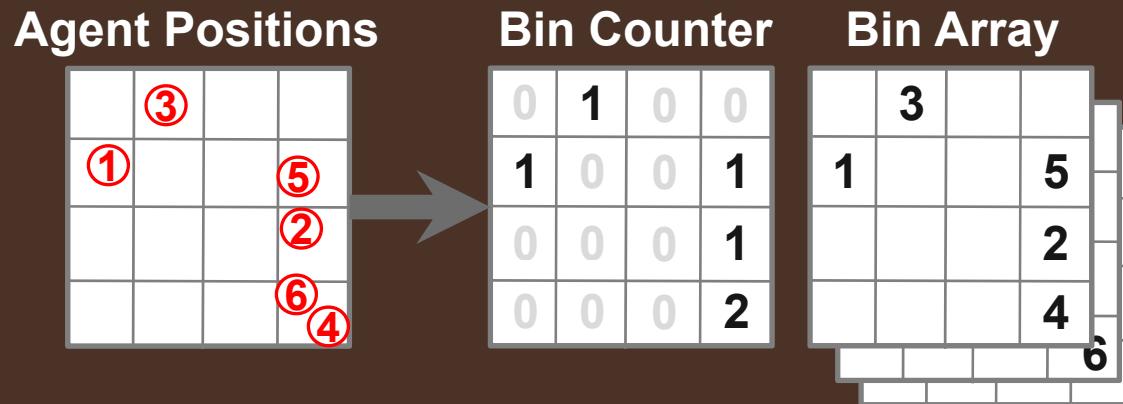
- Need to query nearby agent positions and velocities
- Spatial data structure
- Agents “binned” by position:
  - Bin Counter : Color buffer
  - Bin Array : Depth Buffer Array



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# Spatial Data Structure: Bins



- World space position mapped to 2D index
- Bin Counter: color buffer, tracks bin loads
- ID Array: depth array, binned agent IDs



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# Bin Queries

Agent Positions

			★

Bin Counter

0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

Bin Array

	3		
1			5
			2
			4
			6

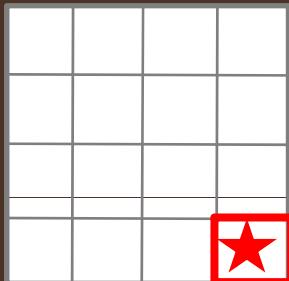


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# Bin Queries

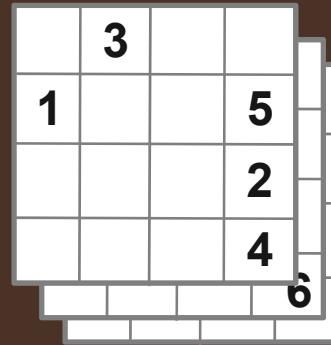
Agent Positions



Bin Counter

0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

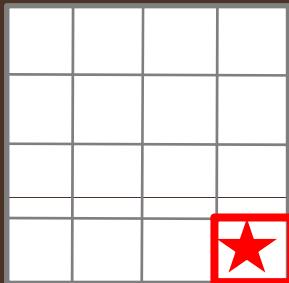
Bin Array



- Translate position to 2D index

# Bin Queries

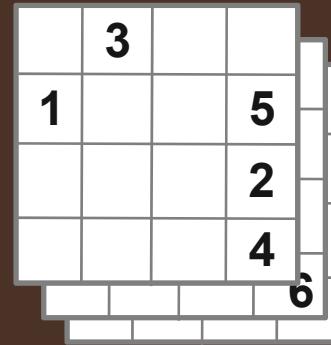
Agent Positions



Bin Counter

0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

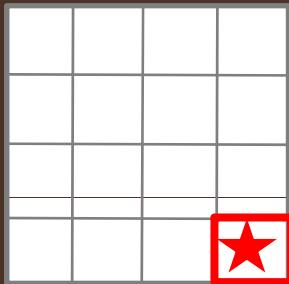
Bin Array



- Translate position to 2D index
- Fetch load from *Bin Counter* (color buffer)

# Bin Queries

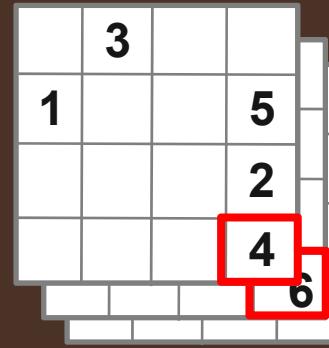
Agent Positions



Bin Counter

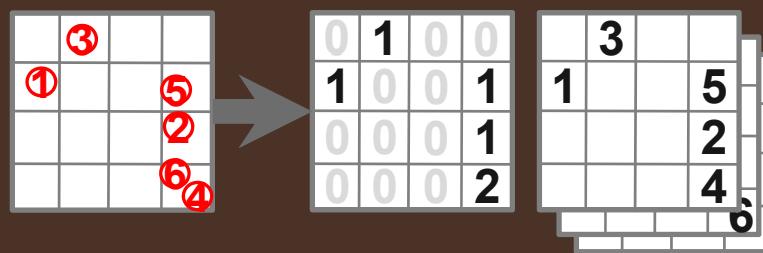
0	1	0	0
1	0	0	1
0	0	0	1
0	0	0	2

Bin Array



- Translate position to 2D index
- Fetch load from *Bin Counter* (color buffer)
- Fetch agent IDs from *Bin Array* (depth array)
  - Efficient: *known number of sorted agents*

# Data Structure Updates: Overview



- Binning is a multi-pass algorithm
  - Update one slice of *Bin Array* per pass
  - Once binned, agents removed from working set
  - Algorithm repeats until working set is empty
  - Overflow is possible & detectable



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# Data Structure Updates: Initialization

- Initialize data structure
  - Clear bin counter (color buffer) to 0
  - Clear bin array (depth array) to **MAX\_DEPTH**
  - Working set is array of **all** agent IDs
    - No VB necessary



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# Data Structure Updates: Pass 1

- Bind bin counter & first slice of bin array
- Draw working set as point primitives
- Vertex shader:
  - Map agent position to 2D bin array index
  - Set point's depth to normalized agent ID
- Pixel shader: output “1”
- Depth test: **LESS\_THAN**



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# Data Structure Updates: Pass 2...n

- Next slice of bin array bound as depth buffer
- VS: Sample ID from previous slice of bin array
  - Reject points less than or equal to previous
- GS: stream out non-rejected points
- PS: write pass number
- Depth test: **LESS\_THAN**



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# Results of Pass 2..n

- VS test ensures only points that haven't yet been binned get streamed-out and rasterized
- Depth test ensures the point with lowest ID gets binned
- Results in points binned in sorted order
  - Like depth peeling
- Stream-out buffer becomes new working set



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# Early Termination

- We want to halt the algorithm once all points are binned
  - Do not query size of stream out buffer each pass
  - CPU/GPU synchronization results in pipeline stalls
- Would like to hand the whole thing off to the GPU to control execution



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# Avoiding Synchronization Stalls

- We know max number of iterations
  - Number of bin array slices
- Make all the draw calls for the max number of iterations
  - Use cascading predicated draw calls
  - Use along with “**DrawAuto**” to issue draws
  - Predicate on number of stream-out elements



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# Avoiding Synchronization Stalls

- GPU terminates algorithm once all agents are binned
  - Once working set (stream out buffer) goes to 0
  - Remaining draw calls are skipped
- The algorithm either terminates or overflows



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# Binning on the GPU

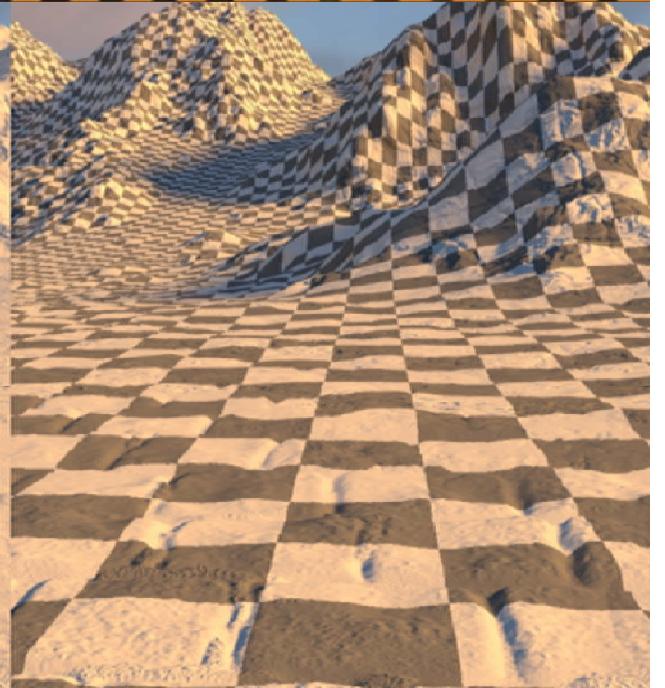
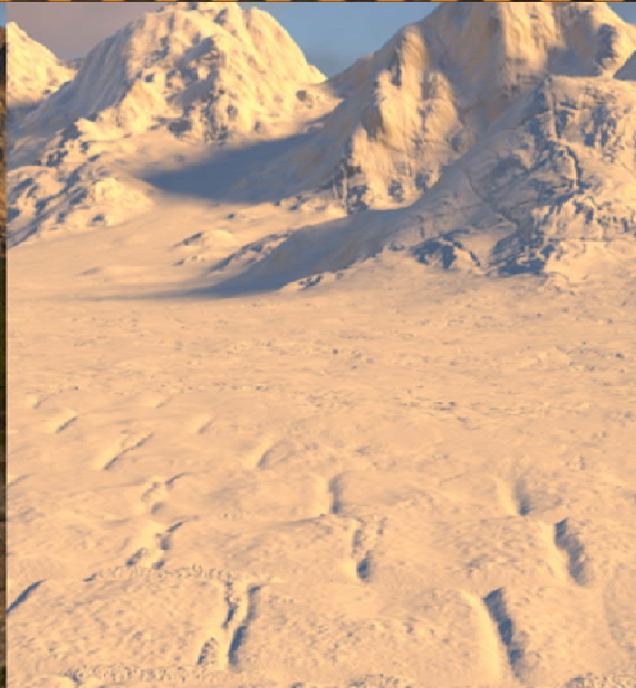
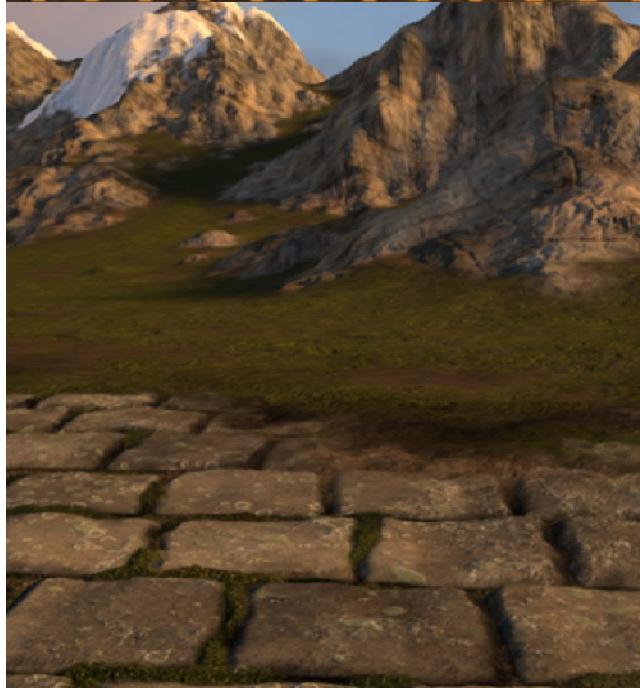
- GPU Binning
  - Efficient queries
    - Early-out on empty bins, known bin load, sorted order
  - Overflow detection
  - Stream-out reduction of working set
  - GPU termination control
- Many applications beyond local avoidance



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# Spherical Harmonic Light Map



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# Diffuse lighting with Shadow Map

- Extracted dominant directional light:  $L_d$ 
  - Dominant directional light color:  $L_c$
- Left over residual lighting environment:  $L_e$
- Dynamic shadow term:  $V_s$
- Surface normal:  $N$

$$\max(N \cdot L_d, 0) * L_c * V_s + \text{SH\_Eval}(N, L_e)$$



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# Dynamic Shadows Cast on Terrain



- Dynamic characters cast shadows on terrain
  - Shadow map shadows mingle with SHLM shadows
  - Shadow map attenuates *dominant* lighting term



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# Double Shadows



- Results in double shadows...
  - Characters in shadow still cast shadows



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# Detecting Direct Sun Light

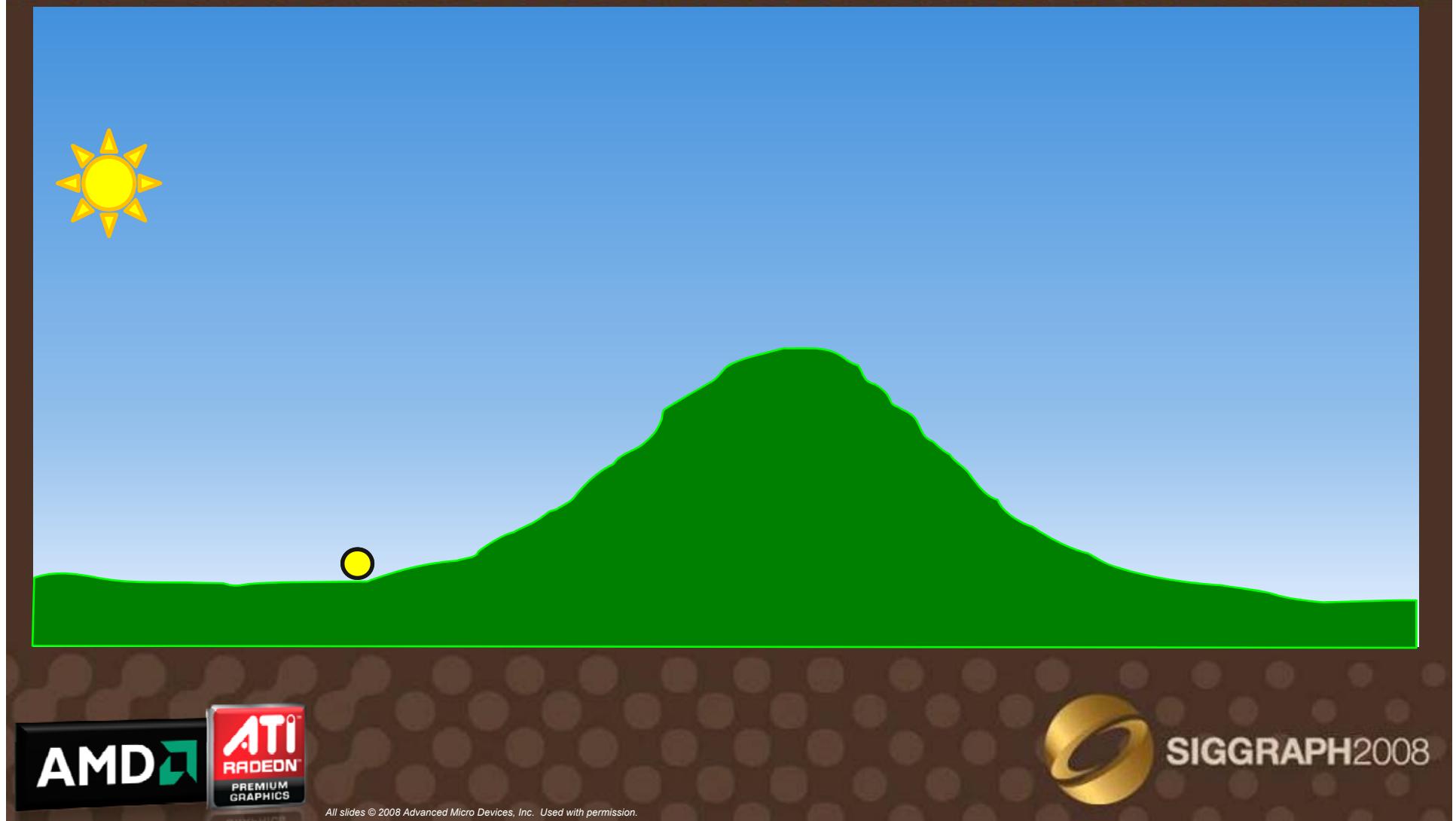


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# Detecting Direct Sun Light



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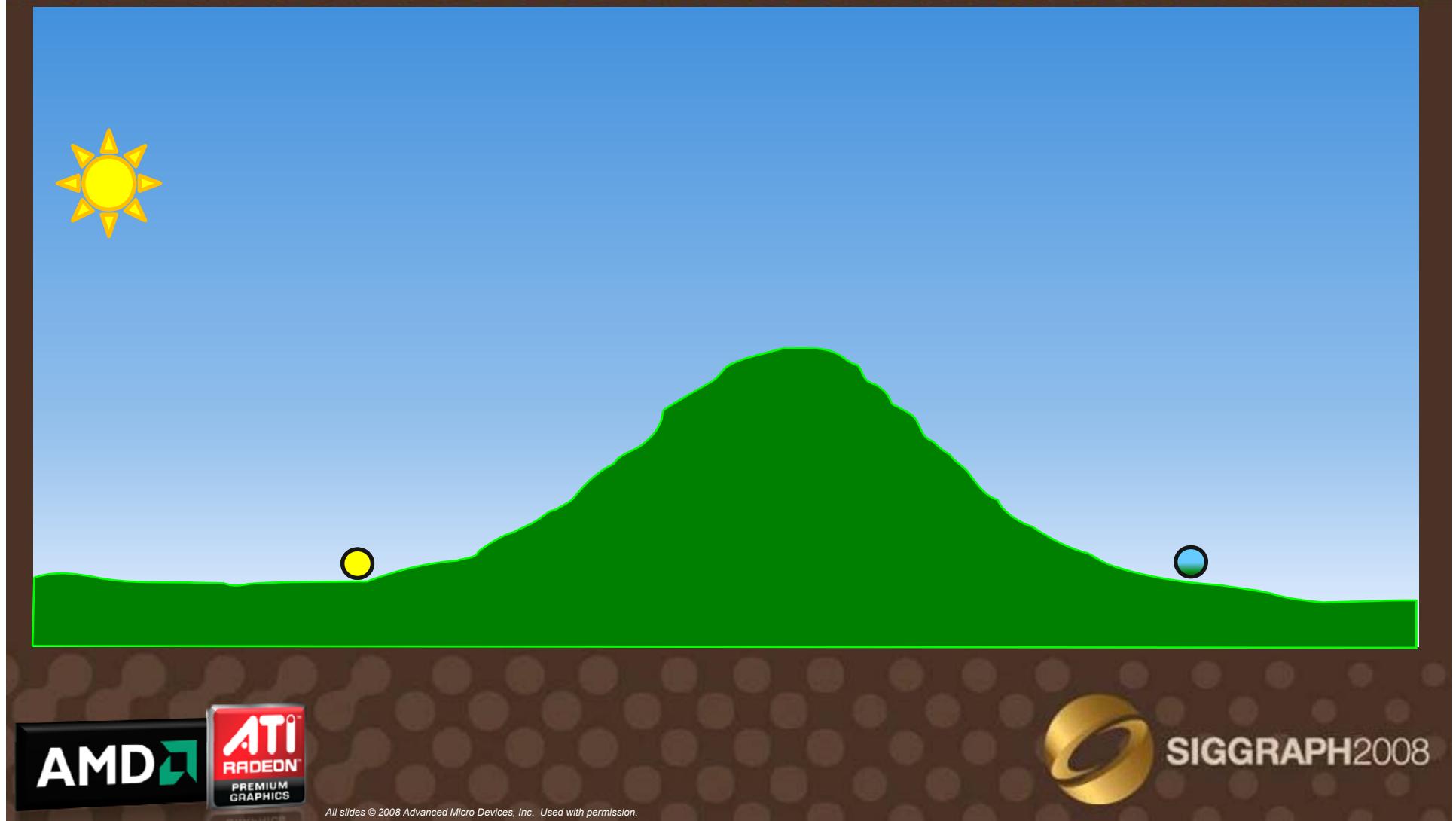
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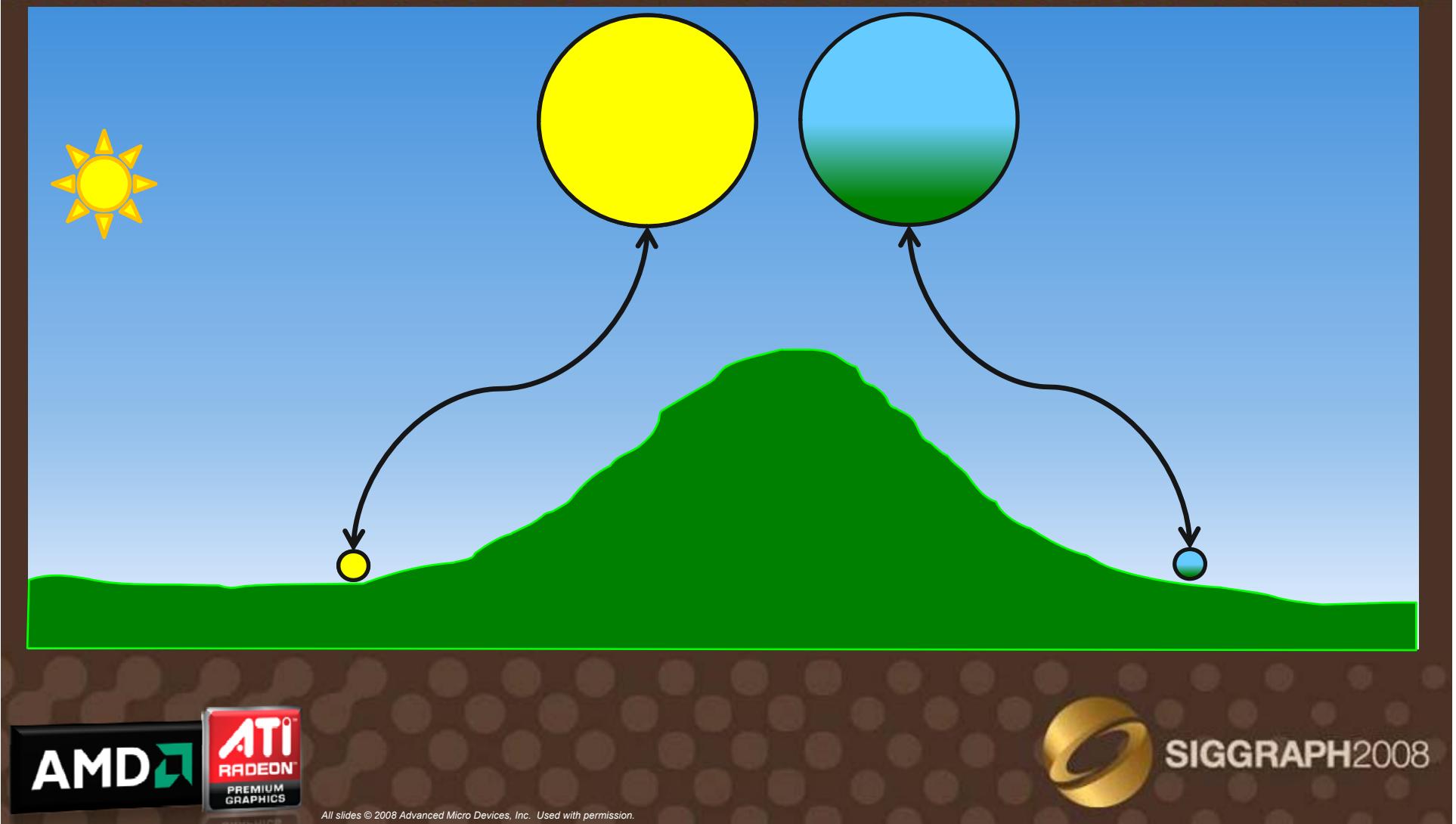
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# Detecting Direct Sun Light



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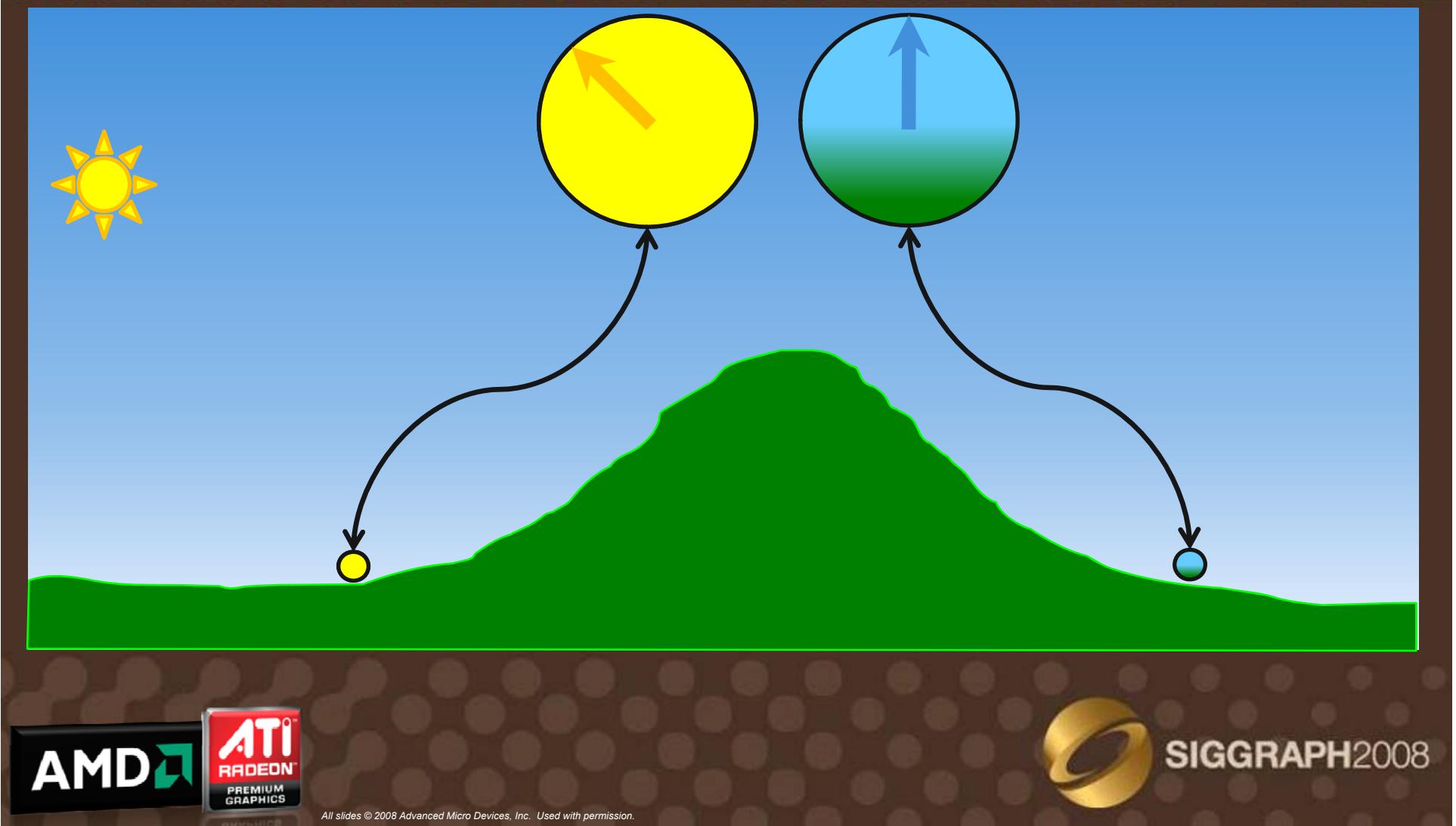
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# Detecting Direct Sun Light



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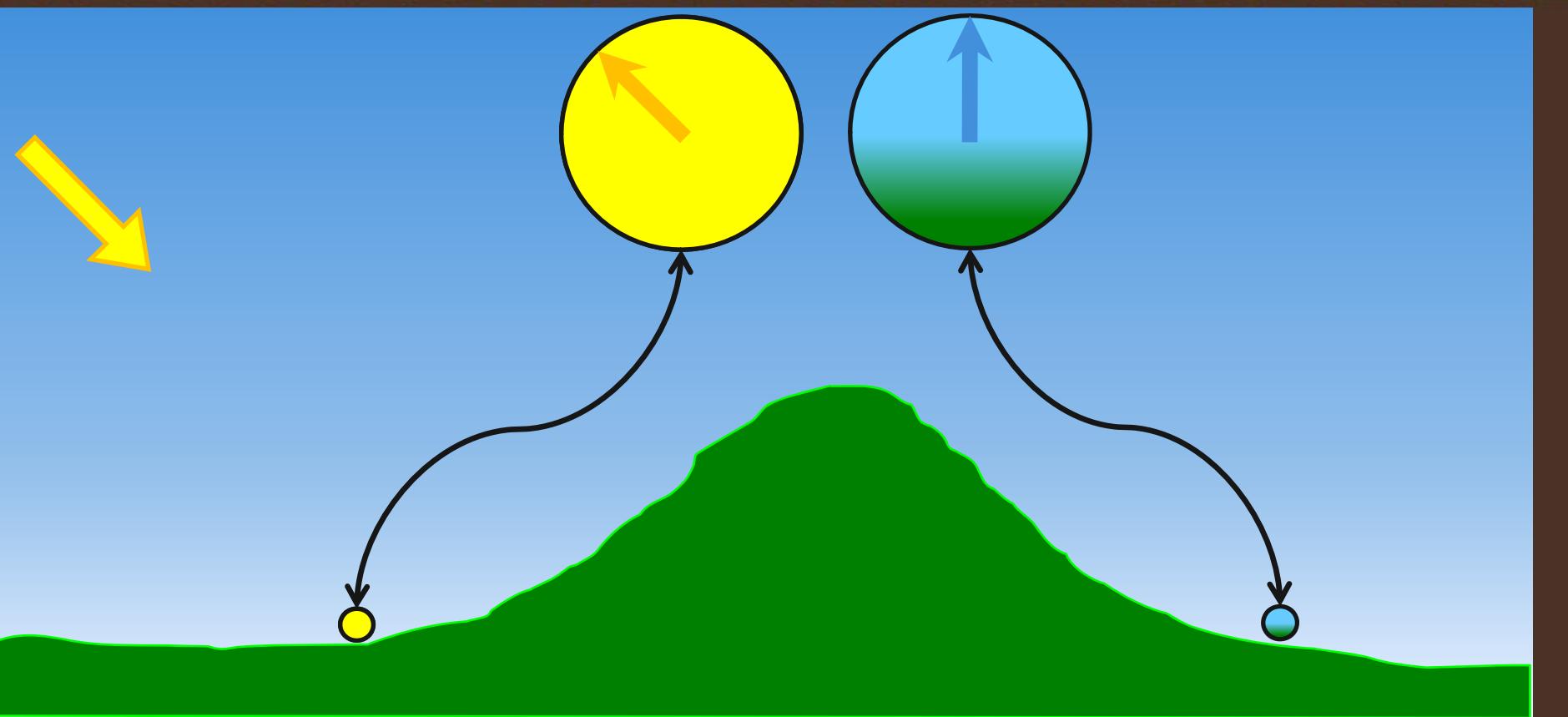
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# Detecting Direct Sun Light

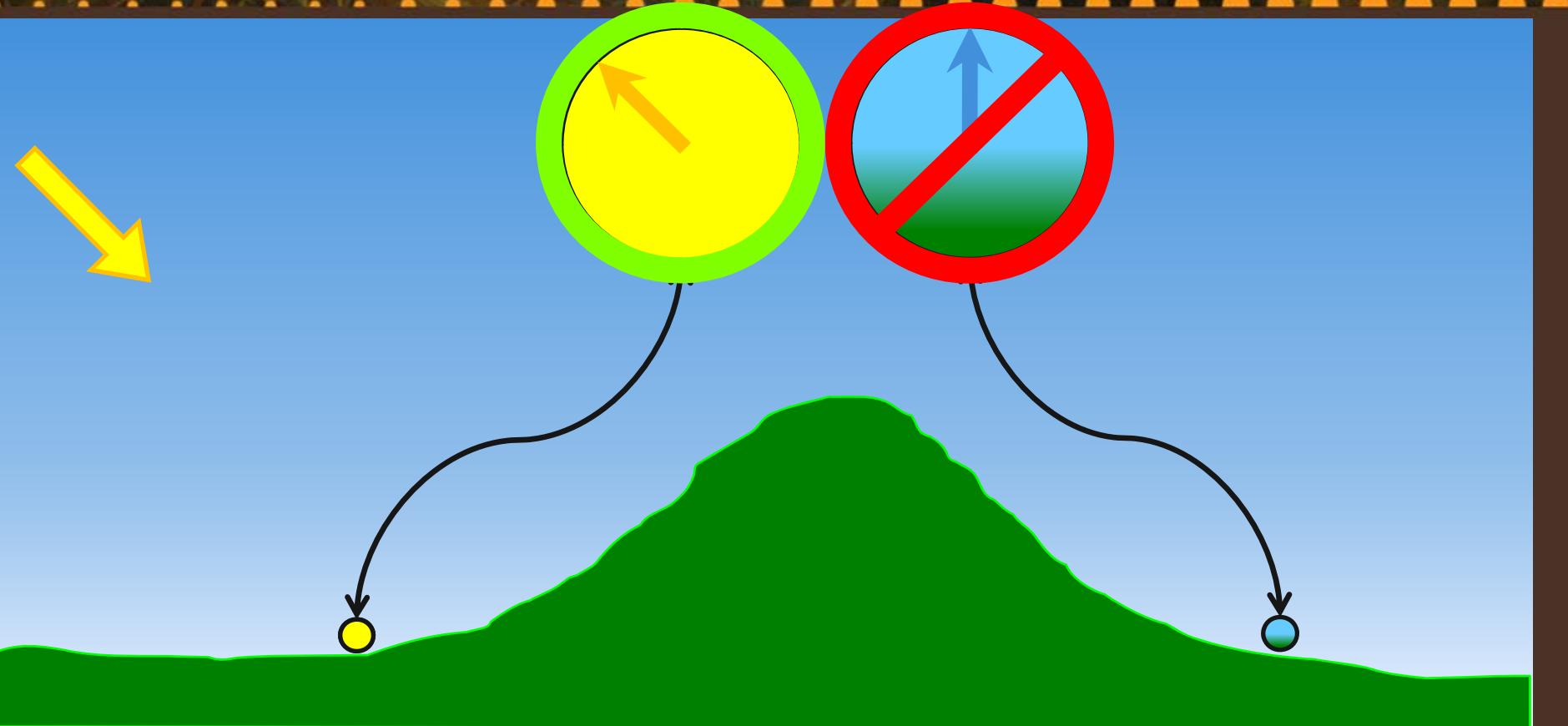


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# Detecting Direct Sun Light



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# Double Shadow Fix



- Shadow map only used on non-occluded regions of terrain



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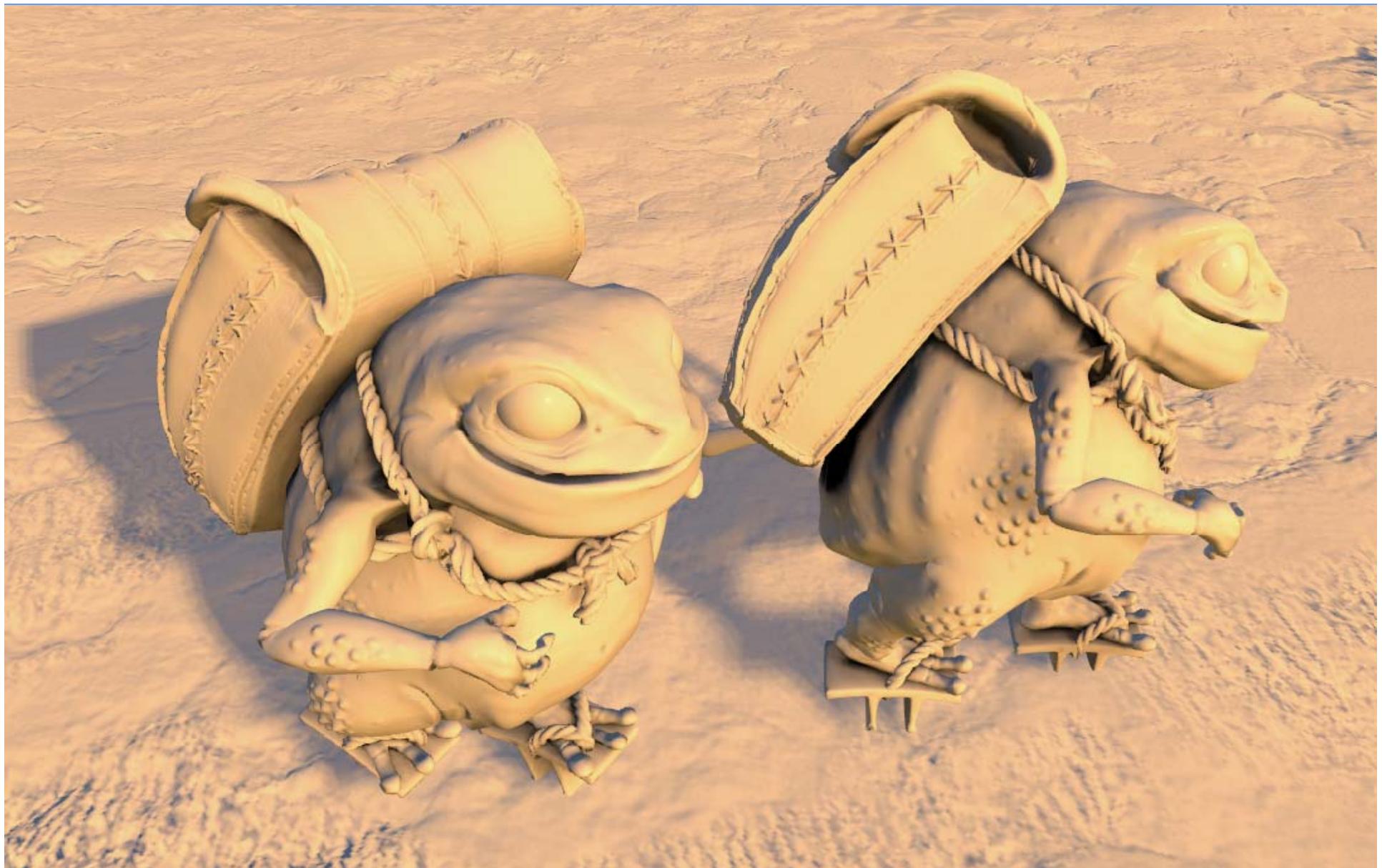












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# The Need for GPU Character Management

- Need scalability and stable performance
- Don't want to render thousands million-poly characters
  - Wasteful if details are unseen
- CPU side character management is impractical when doing GPU simulation
  - Requires a read-back
- Solution: Perform GPU –side scene management



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# GPU Scene Management



# GPU Scene Management

- We use Direct3D®10.1 features for GPU scene management and level of detail management
- Render froblins as an army of instanced characters
- 3 discrete LODs
- Use tessellation to get maximum amount of details with stable performance for close-ups



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# Geometry Shaders as *Filters*

- Act on instances
- A set of point primitives (instance data) as input
- Re-emit only points that pass a specific test
  - Discard the rest
  - Use *DrawAuto* for multiple tests or combine into a single GS invocation for efficiency



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# GPU Character Management Overview

1. Render the occluder geometry
2. Construct the Hi-Z map
3. Run all characters through the view frustum culling filter
4. Results are run through the occlusion culling
5. Run through a series of LOD selection filters
6. Render each LOD



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# View Frustum Culling

- Using the filtering GS perform view frustum culling
  - Using standard methods
- VS checks for intersection between character bounding volume and the view frustum
  - Regular methods apply
- If the test passes, the character is visible: emit it
  - Otherwise it's culled



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# Occlusion Culling

- Render all occluders prior to rendering characters
- Determine which characters are occluded by the environment or structures
  - Use resulting depth buffer
  - Cull against arbitrary, dynamic occluders
- Novel formulation: *Hi-Z map*



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# Hi-Z Map

- A hierarchical depth image
  - Uses the Z buffer information
- A mip-mapped, *screen-resolution* image
  - Each texel at level  $i = \max$  ( all texels at level  $i - 1$  )
- Does not require a separate depth pass



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# Occlusion Culling with Hi-Z Map

- Use constructed Hi-Z map
- Examine the depth information for pixels covered by the object's projected bounding sphere
  - Compare the max fetch depth to the projected depth of the point on the sphere closest to the camera
- Conservative culling
  - Does not result in false culling
- Details in the course notes



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# Hi-Z Map Construction

- Finest level – use the main depth buffer
  - DepthStencil view (with MS DB in Direct3D® 10.1)
- Generate the mip chain levels with *reduction* passes
  - Mind the dimensions – screen-space images don't mip well!
  - Use integer operations to avoid incorrect indexing



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# Reduction Pass for Hi-Z Levels

- Render into one mip level while sampling the previous level
  - Rendering into smaller mip *reducing* the larger one
- Fetch 2×2 neighborhood and compute *max* value
- Fetch additional texels on the odd-sized boundary



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# GS Filtering for LOD Selection

- Use a discrete LOD scheme
  - Each LOD is selected by character's distance to camera
- Three successive filtering passes
  - Separate the characters into three disjoint sets
  - LOD parameters easily specified for each set



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# GS Filtering for LOD Selection

- Compute LOD selection *post* culling
  - Only process visible characters
  - Culling results are only computed once and re-used
- Render closest LOD using tessellation and displacement
- Conventional rendering for middle LOD
- Simplified geometry and shaders for furthest LOD



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# Organize Draw Calls Around Queries

- Need instance count for issuing the draw call for each LOD
- This requires a stream out stats query
  - Can cause significant stall when results are used in the same frame issuing the query
- Re-organize the draw-calls to fill the gap between issuing the query and using the results
  - We perform AI simulation steps



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# CPU Animation Sampling

- Traditionally matrix palettes are computed on the CPU per character
  - Loaded into constant store
- Limitations on the number of characters handled in one draw-call with this approach
  - Large crowds of characters require numerous draw calls
- GPU character management makes this tricky



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# Froblin Character Animation

- Agents have a set number of actions with associated animation sequence



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# GPU Animation Sampling and Control

- At preprocessing time, bake animation data into texture arrays
  - Slice number = animation sequence
  - X and Y = key frame and bone index
- At rendering time, determine per-instance animation sequence index and time offset
  - During simulation in our case



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# GPU Animation Sampling and Control

- Sample and interpolate animation data when rendering the character
  - Sample the animation textures



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# Character Animation on GPU



- At preprocessing, flatten the transform hierarchy
- Compute bone transforms for each key frame transforming that bone into object space
- During simulation, assign an animation sequence to each character
  - Including a time offset into that sequence



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# Animation Texture Layout



		Key 0	Key 1	...	→	...	Key N
Bone 1	Matrix Row 0						
	Matrix Row 1						
	Matrix Row 2						
Bone 2	Matrix Row 0						
	Matrix Row 1						
	Matrix Row 2						
↓							



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# Character Animation on GPU



- During rendering VS fetches, interpolates, and blends the key frames for each bone
  - Using per-character information
- Each instanced character performs its skinning in object space
- Transforms the result using its position and orientation



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# Tessellation and Crowd Rendering

- Combine with Direct3D® 10 instancing support
- Render using interpolative planar tessellation
  - Fast evaluation
  - With displacement mapping for fine-scale detail
- Control tessellation level per-draw call
  - Use character location
- The same art assets as conventional rendering



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# The Benefits of Tessellation

- Tessellation reduces memory footprint and bandwidth
  - Only store low resolution mesh
  - Always relevant, especially for consoles

	Polygons	Total Memory
Low resolution Froblin model	5160 polygons	VB/IB: 100K 2K x 2K 16 bit displacement map: 10MB
ZBrush High res Froblin model	>15M polygons	~270MB VB and 180MB IB storage



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# The Benefits of Tessellation

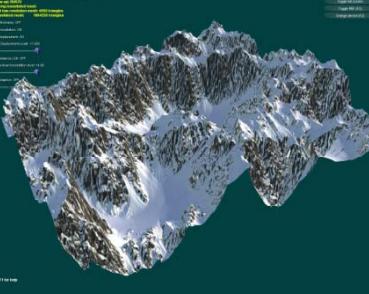
- Scalability
- Stable and predictable performance



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# Tessellation Performance Analysis

Rendering Mode	Num faces:			Far away view		Close-up view
		ATI Radeon™ HD 4870	ATI Radeon™ HD 2900 XT	ATI Radeon™ HD 4870	ATI Radeon™ HD 2900 XT	
$N_T = 411 \times N_L$						
Original low res mesh ( $N_L$ )	4,050 triangles	852 fps	359 fps	850 fps	275	
Continuously tessellated mesh ( $N_T$ )	1.6 M triangles	232 fps	143 fps	213 fps	101	
Adaptively tessellated mesh $N_A$	Dynamic, $1.6M > N_A > 4K$ triangles	845 fps	356 fps	574 fps	207	



\*Configuration: AMD reference platform with AMD Athlon™ 64 X2 Dual-Core Processor 4600+, 2.40GHz, 2GB RAM. Motherboard: ASUSTek M2R32-MVP. Memory: DDR2-800 400 MHz. Operating System: Windows Vista® SP1."

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# Tessellation Pre Direct3D® 11

- GPU tessellation already available
  - Supported on Xbox™ 360
  - ATI Radeon™ HD 2000 Series and beyond: supported on all models
    - *Even on the integrated chipsets!*
- Subset of Direct3D® 11 tessellation features
- Contact AMD ATI developer relations for details on accessing tessellation



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# Preview and Prepare for Direct3D® 11

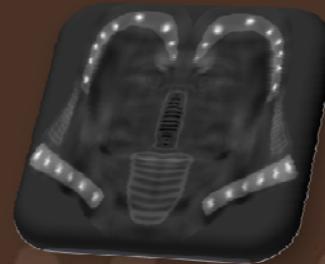
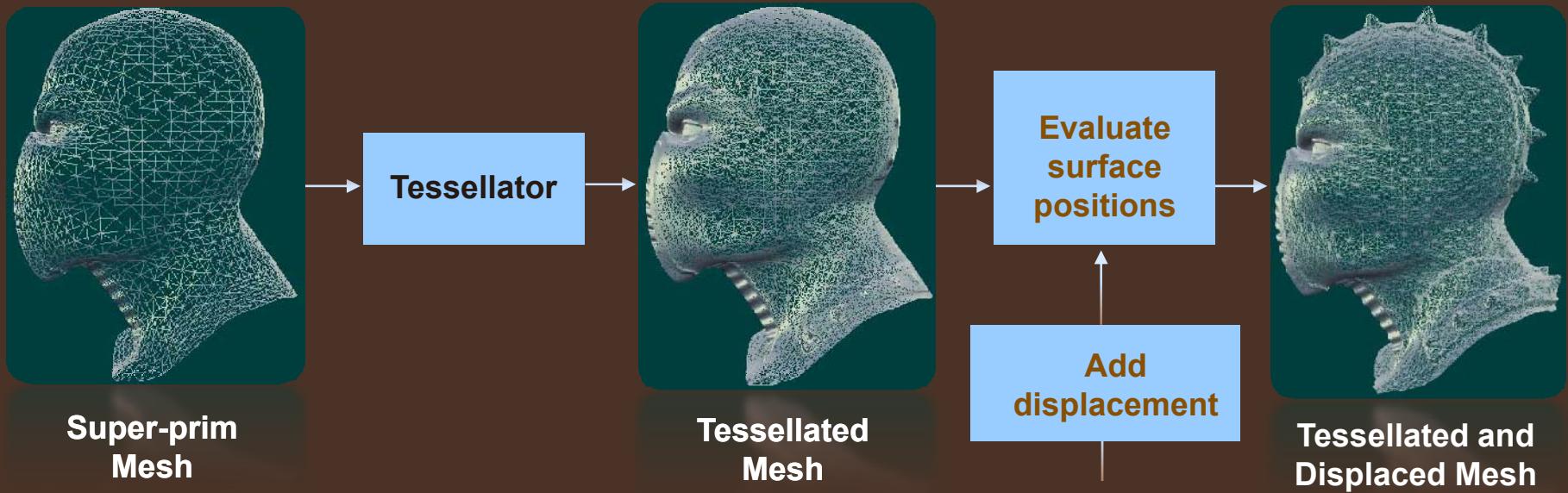
- Support across most APIs gives you best bang for the buck for this feature
  - Support on Microsoft® Windows® XP as well as Microsoft® Windows® Vista
  - PC versions can use Xbox™ 360 native features
  - Reach more players
- Developing artwork takes time
  - Integrating tessellation early gives you and your artists time to design and polish



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# Tessellation Process



Displacement  
Map



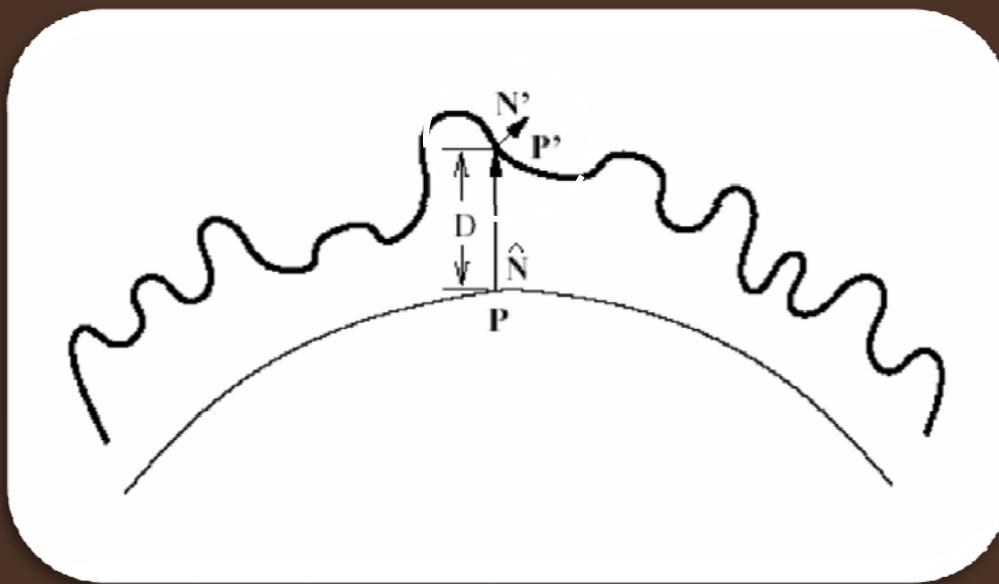
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# Combining Normal Maps and Displacement Maps

- As we displace, we change the actual displayed normal



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# Lighting with Displacement

- Use TS normal maps even with displacement
- Generate displacement and normal maps using the same tangent space
  - The same TS computations for preprocessing
  - The normal encoded in TS normal map will match the normal from displacement



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Regularly drawn Froblin

No tessellation used



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## High Detail Froblin with Tessellation and Displacement Mapping



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## Froblin Close-up:

No tessellation



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## Froblin With Tessellation and Displacement Mapping Close-up



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# Tessellated Characters LOD Control

- Dynamic number of detailed characters in view
  - Simulation changes interactively, no a priori control
- Need stable frame rate in dense crowd simulations
- Compute tessellation level as a function of tessellated characters in view
  - Avoid polygonal count explosion



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# Tessellation Level Computation

$$T_l = \text{clamp}( M T_{\max} / N, 1, T_{\max} )$$

- $N$  characters rendered with tessellation
- Bound the number of amplified triangles
- Primitive count never exceeds than the cost of  $M$  fully tessellated characters



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# Control Cage Pre-Pass

- Perform animation and transformation on control cage in a *pre-pass*
  - Allows for more complex per-vertex operations
- Combine with vertex (de)compression for reducing bandwidth

Pass 1: Control cage animation and transforms

↓  
Stream Out Buffer

↓  
Pass 2:  
Tessellate the control cage



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# PrePass and Vertex Compression

- Shader-based vertex compression / decompression
- Reduce stream out memory footprint between the pre-pass and tessellated pass
- Reduce fetch bandwidth for tessellated pass



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# PrePass and Vertex Compression

- Pack transformed vertex positions into 128 bit format
  - Lets us load each vertex with one fetch
  - Gives as much as 30% speedup
  - More details in the course notes



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# Froblin Land: Terrain Rendering



# Froblin Land: Terrain Rendering

- Smooth, crack-free LOD without degenerates
- Tessellation and instancing
- Leverages Direct3D® 10.1 functionality to help minimize memory footprint
- Complex material system



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# Froblins Performance Details\*

- Staggering polygon count at interactive rates (>20fps)
  - From 900 polygons -> 6K -> 1.6M at the closest tessellated level of details
  - Up to 18M triangles per frame at fast interactive rates
  - 6M-8M triangles on average at 20-25 fps
- Full high quality lighting and shadowing solution
  - Rendering all objects into multiple shadow maps more than doubles polygon count per frame
- Rendering and simulating high quality detailed 3K froblins at 21 fps on average



\*Configuration: AMD reference platform with AMD Athlon™ 64 X2 Dual-Core Processor 4600+, 2.40GHz, 2GB RAM. GPU: ATI Radeon™ HD 4870 Graphcis. Motherboard: ASUSTek M2R32-MVP. Memory: DDR2-800 400 MHz. Operating System: Windows Vista® SP1."

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# Simulation Performance Details\*

- All modes render with 4X MSAA HDR and post-processing
- Simulate behavior and render > 65K agents at 30 fps
- AI simulation for 65K agents alone – 45 fps
- Rendering and simulating 65K agents – 31 fps
- Rendering 9,800,000 polygons each frame
- AI simulation executes with high efficiency resulting in ~1 teraflops!



\*Configuration: AMD reference platform with AMD Athlon™ 64 X2 Dual-Core Processor 4600+, 2.40GHz, 2GB RAM. GPU: ATI Radeon™ HD 4870 Graphcis. Motherboard: ASUSTek M2R32-MVP. Memory: DDR2-800 400 MHz. Operating System: Windows Vista® SP1."

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# Conclusions

- Practical and efficient simulation and rendering of large crowds of characters on GPU
- New GPU algorithms for
  - Global and local navigation and spatial data structures
  - Scene management
  - etc
- And a number of other advanced techniques!



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# Learn More about Our Approaches

- All shaders are included in the course notes
- Course notes are available for download:
  - ACM Digital Library: <http://portal.acm.org/dl.cfm>
  - AMD Graphics Technical Publications webpage:  
<http://ati.amd.com/developer/techreports.html>



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# Questions?



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