

## Expression Flow for Face Editing



Fei Yang<sup>1</sup>, Jue Wang<sup>2</sup>, Eli Shechtman<sup>2</sup>, Lubomir Bourdev<sup>2</sup> and Dimitris Metaxas<sup>1</sup>

<sup>1</sup>CBIM, Rutgers University <sup>2</sup>Adobe Systems

## Recovery 3D geometry from images Decouple expression and identity $s_t = \bar{s} + V \otimes \beta_t \otimes \gamma_t$ How to fit the model ?

Minimize geometric error

Same identity  $\gamma_t$  across all frames

Video: Expression changes smoothly

New shape is close to distribution of training set

Expression  $\beta_t$  change over time





