C++ Programming

Preprocessor Directives and Namespaces

- In C++ (as in C), before compilation, a preprocessor goes through your code, doing a variety of things
- In particular, the preprocessor looks for directives that give it instructions on things it should do with or to your code
- Preprocessor directives begin with a # and generally take an entire single line of code
- Unlike regular code, they do not end with a ;

- You have already seen a couple of these so far ...
- #include
 - Used to include the contents of another source file into the current file, like:

```
#include <iostream> // C++ standard headers drop the .h.
```

- Generally, this is used to include header files containing various declarations, type definitions, other preprocessor directives, and so on
- That said, you can include code files (and other things!) as well, but doing so is generally frowned upon

 To prevent multiple inclusion of the same header file (which can have bad consequences like duplicate definitions of various things) we can use preprocessor directives to create include guards:

```
#ifndef MYHEADER_H then regime it a define!
#define MYHEADER_H

... definition of MYHEADER_H.

#endif
```

- #define
 - Used to define constants, replaced during compilation, as discussed earlier
 - Can also be used to define macros that are also processed before compilation, such as:

```
#define square(x) (x * x)

cout << square(2) << endl;

define while = first works
```

- There are other directives as well for various purposes
 - Conditional compilation (#ifdef, #if, #elif, #endif, ...) specific for will OS
 - Throwing errors (#error) & wanty in conjunction with # of statements.
 - Line control (#line)
 - Various other things (generally under #pragma) only one.

- Namespaces provide a method for <u>explicitly defining scope</u> to the identifiers within it (e.g. types, functions, variables, etc.)
- This allows us to logically organize our code better and avoid name collisions that can occur in large projects with multiple programmers (or when code is used from multiple sources)
 - Only one entity can exist with a particular name in a particular scope; Large group otherwise we have a name conflict or collision
- Namespaces allow us to group named entities that otherwise would have global scope <u>into narrower scopes</u>

• The syntax to declare a namespace is:

```
namespace identifier
{
    named_entities
}
```

```
• For example:

namespace myNamespace

{

surre when up

int a, b; more space

}
```

hamespace NSIS

int n, bg

nonespace NS2S

int a, b].

NSI:: a j these are different

NS2:: a variables.

• The variables can be accessed from within their namespace normally, (as a and b), but if accessed from outside the myNamespace namespace, they have to be properly qualified with the scope operator (::) as myNamespace::a and myNamespace::b

a new some obj.

- As a shorthand, we can declare that we are using a namespace, to introduce direct visibility of all the names of the namespace into the current code file
- Recall that entities (variable, types, constants, and functions) of the standard C++ library are declared within the std namespace, and we can avoid explicitly using std:: each time we reference them by:

where is the ranges using namespace std;

how supp using instead of std:: cont,

we could use come directly.

- It is generally considered poor form to make use of the using namespace syntax in a header file
 - This can lead to inadvertently opening up access to namespaces in unanticipated ways, leading to name collisions and other problems
- It is also potentially dangerous to use multiple namespaces at a time with this declaration for similar reasons; if more than one namespace uses the same name, you've got problems
- For these reasons, some purists would suggest avoiding this syntax entirely and always explicitly identify scope when required to do so