## CALCULUS 2402A LECTURE 7

14.7 Maximum and minimum values Part B

The Second Derivative Test of functions of two variables Suppose the 2nd partial derivatives of f are continuous on a disk with center  $(a_1b)$  and suppose that  $f_x(a_1b) = 0$  and  $f_y(a_1b) = 0$ , ie,  $(a_1b)$  is a CP of f. Let

$$D = \begin{cases} f_{xx}(a_1b) & f_{xy}(a_1b) \\ f_{yx}(a_1b) & f_{yy}(a_1b) \end{cases} = f_{xx}(a_1b) f_{yy}(a_1b) - f_{xy}(a_1b) \\ f_{yx}(a_1b) & f_{yy}(a_1b) - (f_{xy}(a_1b)) \end{cases}$$

- a) If D>O and  $f_{xx}(a_1b)>0$ , then f(a,b) is a local minimum
- b) If D>0 and  $f_{xx}(a,b)<0$ , then f(a,b) is a heal maximum
- c) If D<0 then f has (a,b) as a saddle point
- d) If D = O the test is inconclusive. We need further investigation

 $\frac{\mathcal{E}_{x6}}{\mathcal{E}_{x6}}$ : Find the local min or max values and Saddle points of  $f(z,y) = x^2 + xy + y^2 + y$ 

Solution

$$\int_X = 2x + y = 0 \Rightarrow y = -2x \Rightarrow y = -\frac{2}{3}$$

$$\int_Y = x + 2y + 1 = 0 \Rightarrow x + 2(-2x) = -1$$

 $-3x = -1 \Rightarrow x = \frac{1}{3}$ 

! The paid  $\left(\frac{1}{3}, -\frac{2}{3}\right)$  is a CP.

$$\int_{xx} = 2$$
,  $\int_{xy} = 1$ 

$$f_{\gamma\gamma} = 2$$
 ,  $f_{\gamma\chi} = 1$ 

Because  $f_{xx} = 2 > 0$ ,  $\left(\frac{1}{3}, -\frac{2}{3}\right)$  is a local min

and 
$$f\left(\frac{1}{3}, -\frac{2}{3}\right) = \left(\frac{1}{3}\right)^2 + \left(\frac{1}{3}\right)\left(-\frac{2}{3}\right) + \left(-\frac{2}{3}\right)^2 + \left(-\frac{2}{3}\right)$$

$= \frac{1}{9} - \frac{2}{9} + \frac{4}{9} - \frac{2}{3} = \frac{1}{3} - \frac{2}{3} = -\frac{1}{3} \text{ // Ans}.$
We note that $-\int (x,y) can he written as$
$f(z,y) = (z + \frac{y}{2})^2 + \frac{3}{4}(y + \frac{1}{3})^2 - \frac{1}{3}$
> 0 > 0
f(2,5) has a local min value -1 if
$x + \frac{5}{2} = 0 \Rightarrow x = -\frac{3}{2} = -\frac{1}{2}(-\frac{2}{3}) = \frac{1}{3}$
$y + \frac{2}{3} = 0 \Rightarrow y = -\frac{2}{3} \checkmark$
The Hessian
Consider the function $f(x,y)$ . The matrix
$H(z,y) = \int \int f_{xx}(z,y) \int f_{xy}(z,y)$
fyx (x,5) fyy (2,5)
is called the Hessian of f at (a, y). We define the trace of
H, denoted as Tr (H), as
$\overline{I}_{\Lambda}(H) = f_{xx}(z_{1}y) + f_{yy}(z_{1}y)$
because $f_{xy}(x,y) = f_{yx}(z,y)$ , $H(z,y)$ is a symmetric matrix.
det (H(215)) = fxx(215) fyy(2,5) - (fxy(215)) (= D)
The Second Derivative Test in terms of the Hessian
Suppose that (a,b) is a CP of f and f has continuous
2nd order partial derivatives in some neighborhood of $(a,b)$ . Then  a) f has a local minimum value at $(a,b)$ if $Tr(H(a,b)) > 0$
and but (H(a,b)) > 0 (N.B: If Tr (H(a,b1) > 0 Hen fox (a,b) > 0)
b) I have been maximum value at (a,b) if Te (H(a,b)) < 0
and det $(H(a,b)) > 0$
c) $f$ has $(a,b)$ as a saddle point if $det$ $(H(a,b)) < D$ d) If $det$ $(H(a,b)) = D$ , the test is inconclusive.

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Recall Eigenvalues and Eigenvectors
     A non-zero veda V is called an eigenveda of a matrix A
    corresponding to an eigenvalue of if
                      A \underline{v} = \lambda \underline{v}
                                                           (1)
    If all eigenvalues of A are positive, A is called we definite.
    If all eigenvalues of A are negative, A is called -ve definite
   If some are +ve and some are -ve, A is called indefinite
    Rewriting (1) as
                     A V = A I V where I is the identity matix
                                                           (I\underline{v} = \underline{v})
                  A_{\dot{\lambda}} - \lambda I_{\dot{\nu}} = 0
                  (A - \lambda I) \bar{\Lambda} = \bar{O}
         Since V is a non- Zero vector, we must have
                    \left[\det\left(A-\lambda I\right)=0\right]
                                                  (2)
        Which is called the Characteristic Equation.
          Consider A as a 2x2 matrix. Let
                       A = | a | b | c | d |
                and V = \begin{bmatrix} h \\ k \end{bmatrix}
             A - \lambda I = \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a - \lambda & b \\ c & d - \lambda \end{bmatrix}
            det (A- XI) = 0
                  \begin{vmatrix} a - \lambda & b \\ c & d - \lambda \end{vmatrix} = 0
                                                                   A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}
            Expandy
                                                                     In(A) = a + d
                  (a-\lambda)(d-\lambda) - bc = 0
                                                                      det (A) = ad - bc
                     ad - a\lambda - d\lambda + \lambda^2 - bc = 0
                      \lambda^2 - (a+d)\lambda + ad -bc = 0
                      \lambda^2 - \lambda \operatorname{Tr}(A) + \operatorname{det}(A) = 0
                                                                   (3)
                      \lambda_1 + \lambda_2 = T_2(A)
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A is +ve definite if Tn(A) > 0 and det(A) > 0
A is -ve definite if Tr(A) <0 and let(A) >0
A is indefinite if det (A) < 0
Goback to the Hessian
$H(x_{1}y) = \begin{bmatrix} f_{xx}(x_{1}y) & f_{xy}(x_{1}y) \\ f_{yx}(x_{1}y) & f_{yy}(x_{1}y) \end{bmatrix}$
At the CP (a,b)
$\begin{array}{cccccccccccccccccccccccccccccccccccc$
$H(a_1b) = \begin{bmatrix} f_{xx}(a_1b) & f_{xy}(a_1b) \\ f_{yx}(a_1b) & f_{yy}(a_1b) \end{bmatrix}$
$\det (H(a_1h)) = f_{xx}(a_1h) f_{yy}(a_1h) - (f_{xy}(a_1h))^2$
(1) f has a local minimum value at (a,b) if H (a,b) is
+ve definite
(ii) f has a local maximum value at (a,b) if H(a,b) is
-ve definite
(iii) f has (a,b) as a saddle point if H(a,b) is indefinite
We will generalize to the case of f is a function of 3 variables
or more in the next lecture.
See you on Friday.