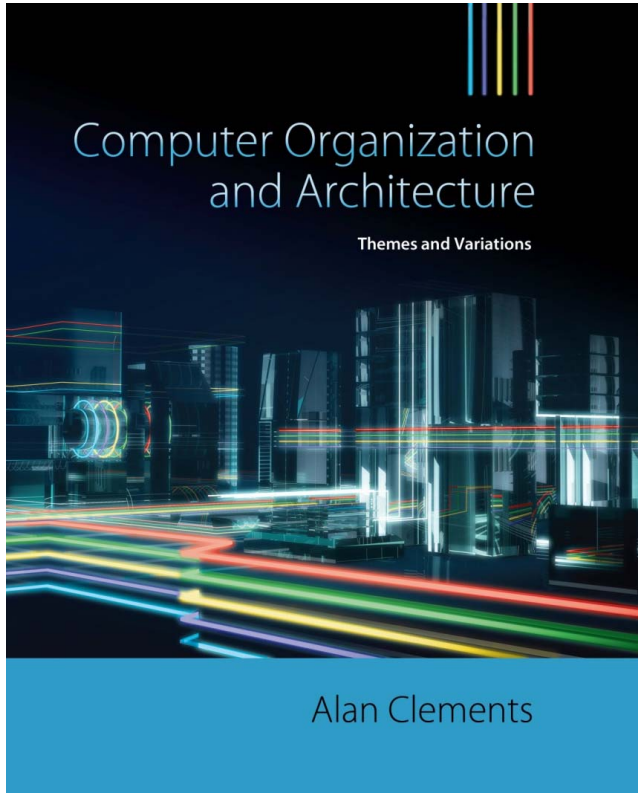
Part 0x1

CHAPTER 3

Architecture and Organization



CENGAGE Learning

The Instruction Set Architecture

In this chapter, we will:

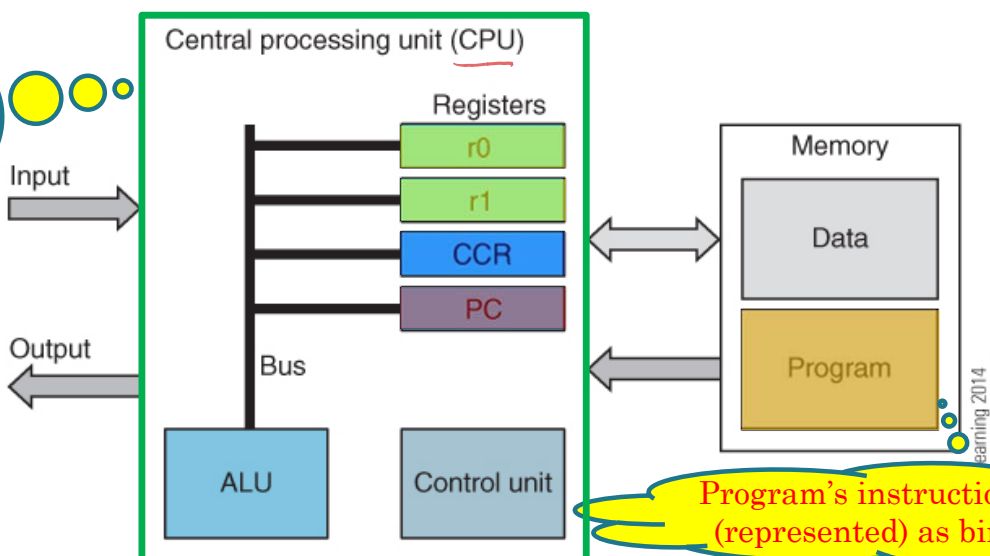
- **Revisit** the *stored program machine* and **show** how an instruction is executed
- **Introduce** instruction formats, including
  - *memory-to-memory*,
  - *register-to-memory*, and
  - *register-to-register*
- **Demonstrate** how a processor implements *conditional behavior*
- **Describe** a set of computer assembly instructions (*instructions set*)
- **Show** how computers access data (*addressing modes*)
- **Introduce** an ARM's *Integrated Development Environment* (IDE) and **show** how ARM programs are written

The Instruction Set Architecture

- Figure 3.1 illustrate the structure of a **simple** *hypothetical stored program computer*.
- The ***CPU*** *reads* instructions from memory and *executes* them.
- *Temporary data* is stored in *registers* such as *r0* and *r1*.
- The ***PC***, *program counter*, is the register that *points at (i.e., contains the address of) the next instruction to be executed*.
- The ***CCR***, *Condition Code Register*, is a collection of flag bits for a processor.

Intel calls it the "***Instruction Address Pointer***", a better name than the ***PC***

FIGURE 3.1 Fundamental structure of a computer



This is a bit detailed version of Figure 1.3, Slide 9, Chapter 1.

Program's instructions are encoded (represented) as binary numbers.

Instruction Formats

- A computer executes instructions from 8 bits wide to multi-bytes wide.
- The instruction format defines the ***anatomy*** *of an instruction*
  - the number of operands, and
  - the number of bits devoted to defining each operation,
  - the format of each operand.
- Below are several *hypothetical* examples of assembly instructions:

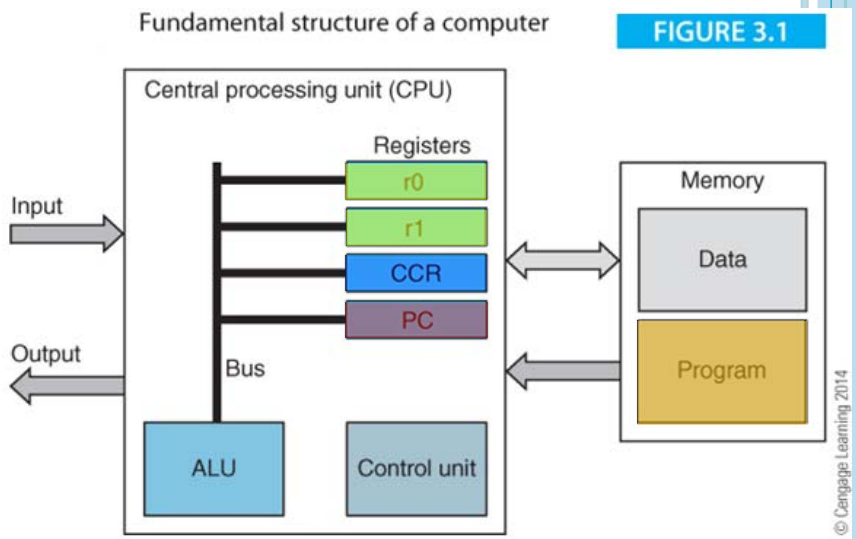
LDR **registerDestination**,memorySource
STR registerSource,**memoryDestination**
Operation **registerDestination**,registerSource1,registerSource2

```
LDR   r1,1234   load the content on location 1234 to r1
STR   r3,2000   store the content in r3 to location 2000.
ADD   r1,r2,r3  add up r1, r2 and store the result in r3
SUB   r3,r3,r1  r3 = r3 - r1.
```

bold stands the destination memory.

Features

- A stored program machine is a computer that has a program in binary form in its main memory.
- The program and data are stored in the same memory.
- The program counter (PC) points to the next instruction to be executed and is incremented after executing each instruction.



- A stored program operates in a *fetch*/execute two-phase mode.
  - In the *fetch phase* the next instruction is read from memory and decoded. memory → CPU
  - In the *execute phase* the instruction is interpreted and executed by the CPU's logic. CPU execute, meanwhile memory doing nothing.

Review Slides 27 and 28 in Chapter 1.

- Modern computers are ***pipelined***, where fetch and execute operations ***overlap***. Fetch Exute / Fetch Exute / Fetch Exute. Let both CPU and memory work

Features

A stored program computer has several registers.

r0 - r*i* The register file is a *set of general-purpose registers*, e.g., r0, r1, r2, …, r*i* that store temporary (working) data, for example, the intermediate results of calculations, where *i* is typically 8, 16, or 32.

A computer requires at *least one* general-purpose register.

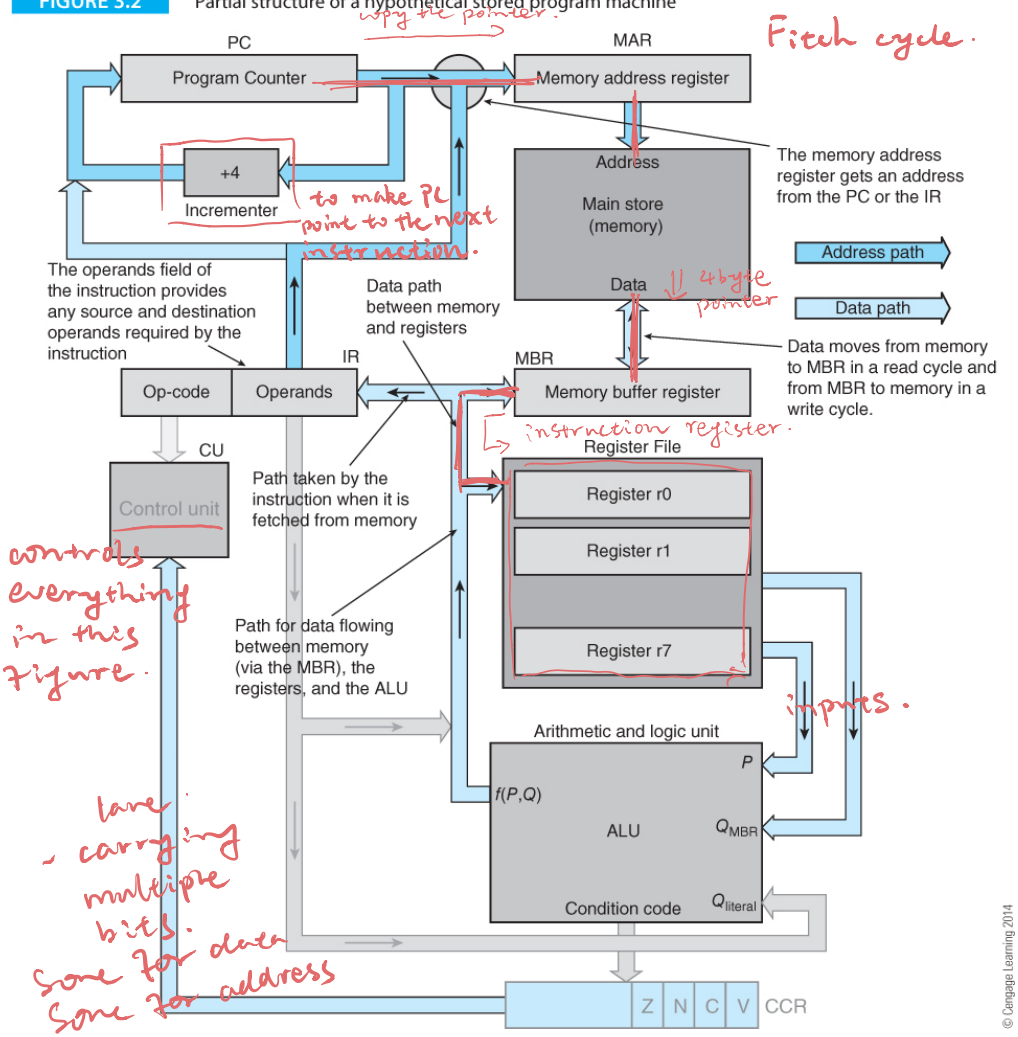
PC The *program counter* contains the *address* of the next instruction to be executed. Thus, the PC *points* to the location in memory that holds the next instruction.

IR The *instruction register* stores the instruction most recently read from main memory. This is the instruction currently being executed.

MAR The *memory address register* stores the *address* of the location in main memory that is currently being accessed by a read or write operation.

MBR The *memory buffer register* stores data that has just been read from main memory, or data to be immediately *written* to main memory.

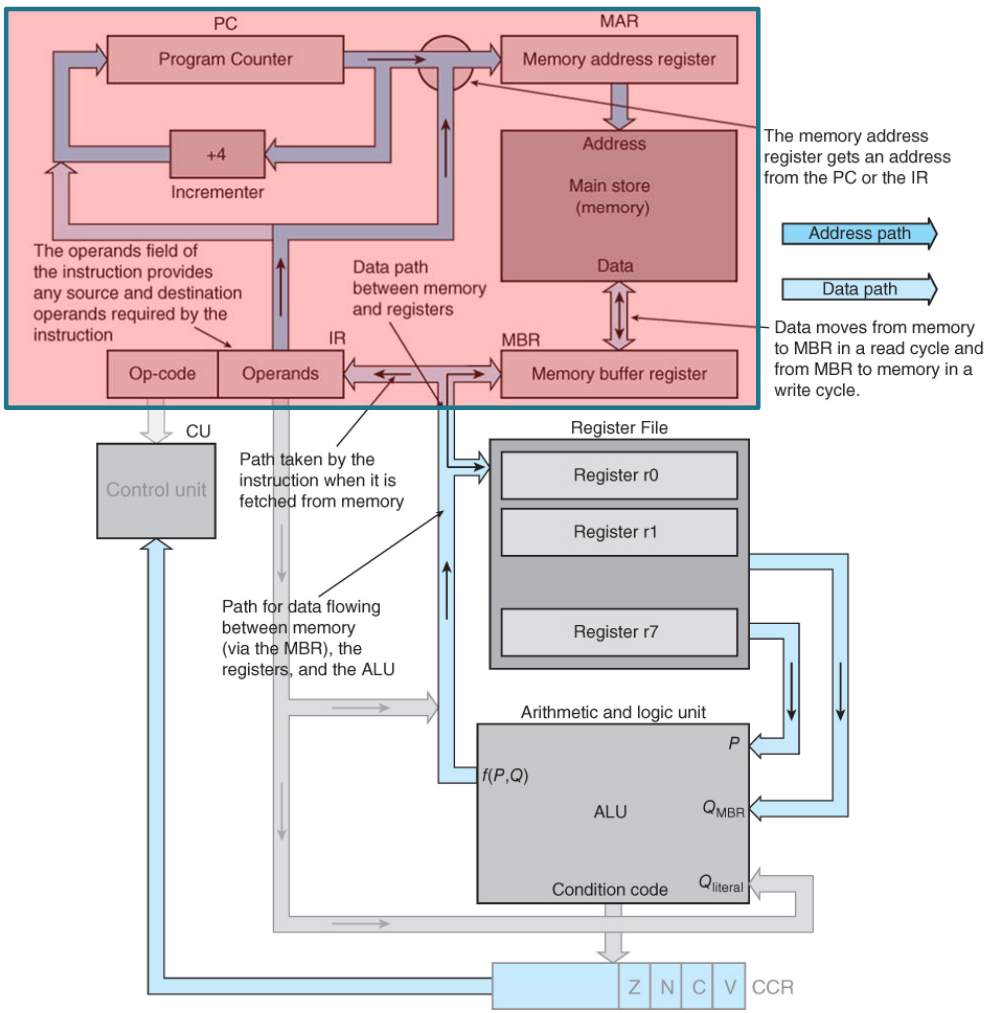
FIGURE 3.2 Partial structure of a hypothetical stored program machine



Structure of a Computer

- We are going to use an ARM processor to introduce assembly language and a modern ISA.
- *However*, it would be better to begin with the description of a very simple *hypothetical* computer to keep things simple.

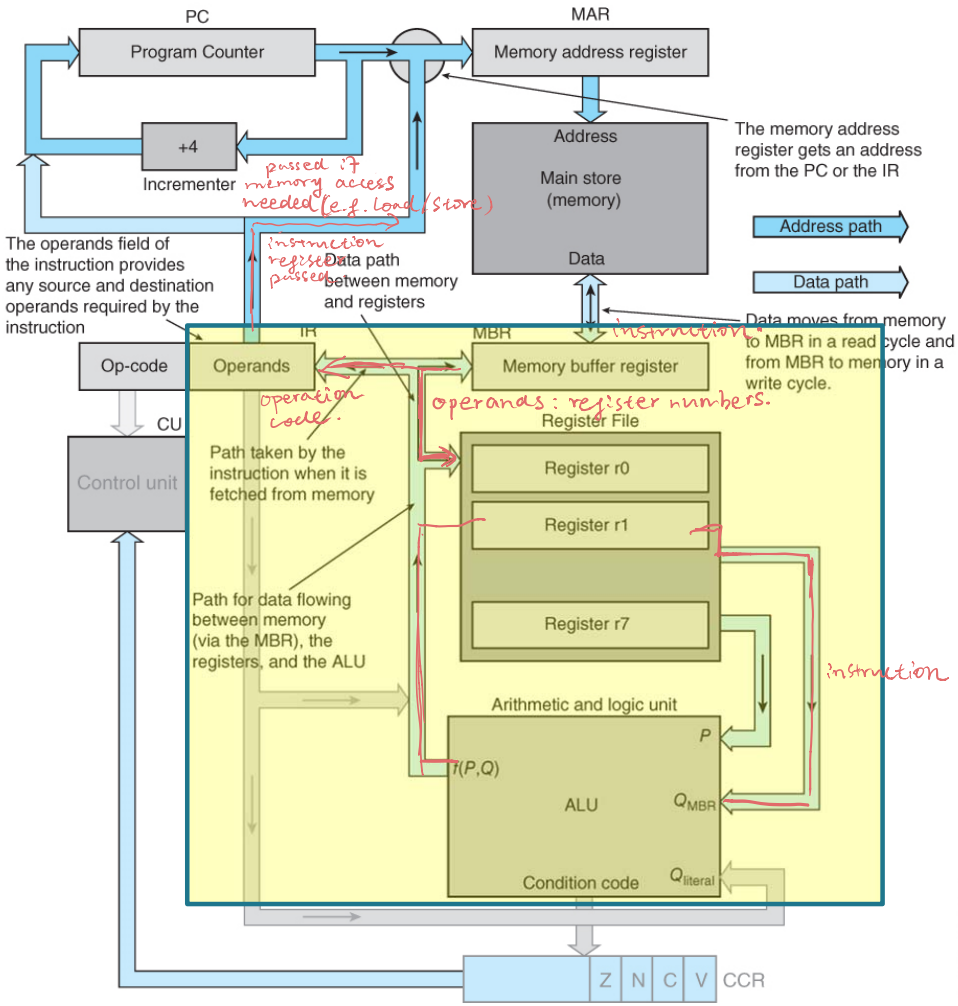
FIGURE 3.2 Partial structure of a hypothetical stored program machine



Structure of a Computer

- In the ***fetch phase***, the Program Counter, PC, supplies the address of the next instruction to be executed to the MAR to read this instruction ***and*** the PC is *incremented by the size of an instruction*.
- The instruction is read and loaded into the Memory Buffer Register, MBR, ***and*** then copied to the Instruction Register, IR, where the op-code is decoded.

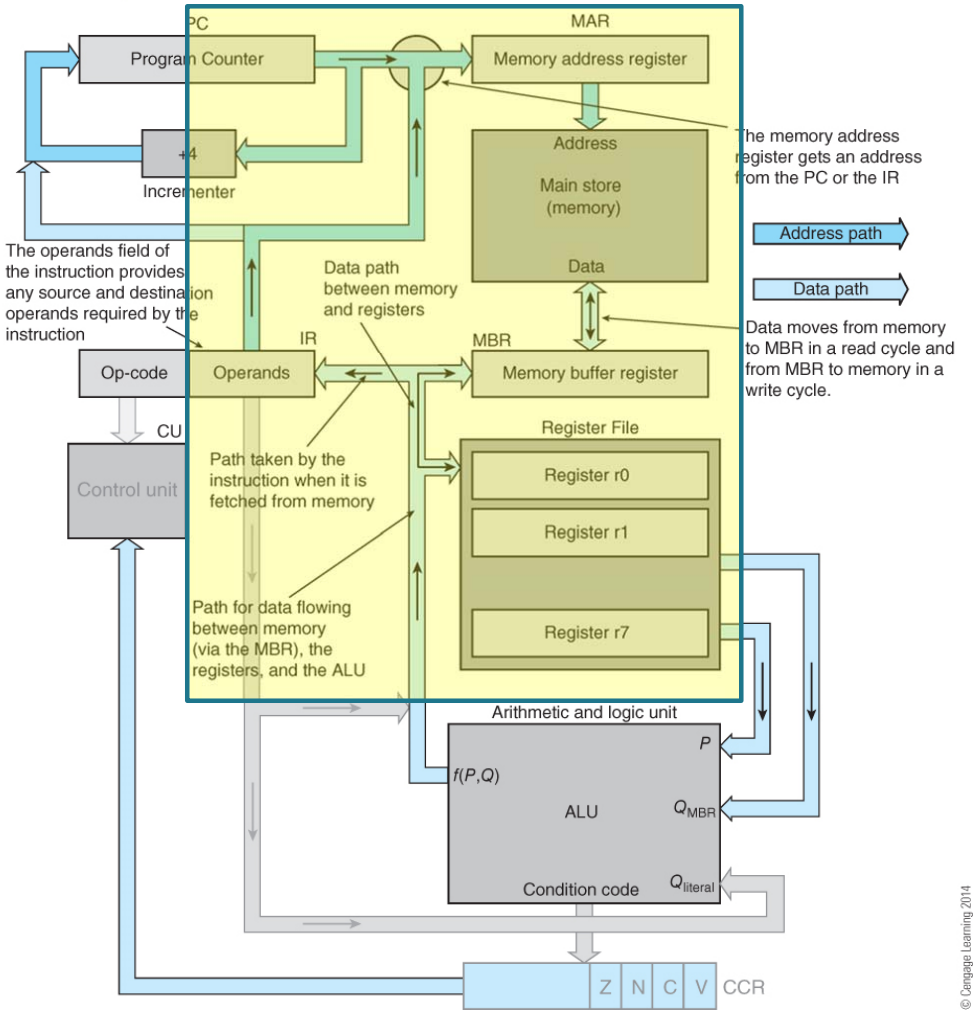
FIGURE 3.2 Partial structure of a hypothetical stored program machine



Structure of a Computer

- In the ***execute phase***, the operands may be read from the *register file*, transferred to the ALU (*arithmetic and logic unit*) where they are operated on and then the result passed to the *destination register*.
  This is what we call, *register-to-register* operation

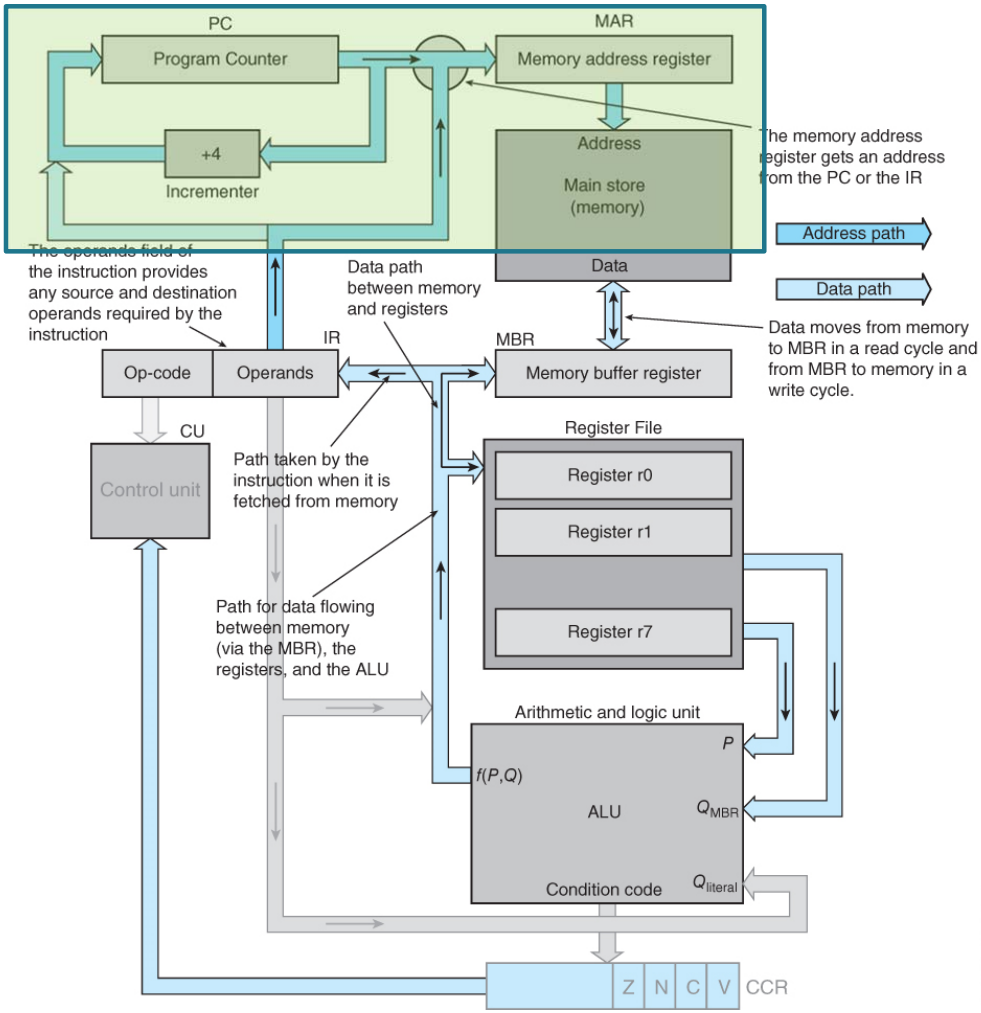
FIGURE 3.2 Partial structure of a hypothetical stored program machine



Structure of a Computer

- If the operation requires a memory access (e.g., a load or store), the memory address in the instruction register is sent to the MAR and a read or write operation performed.

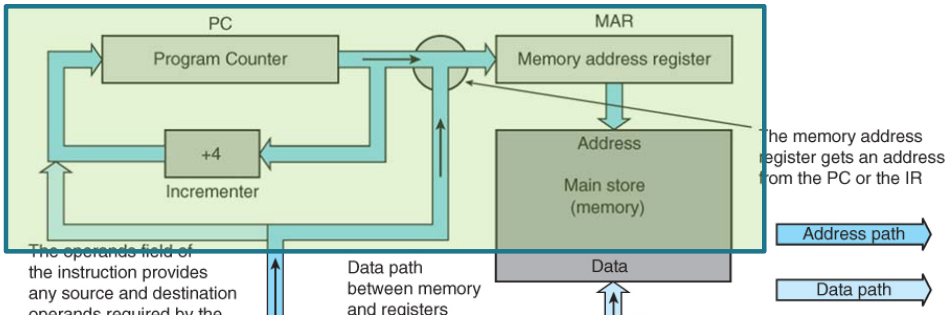
FIGURE 3.2 Partial structure of a hypothetical stored program machine



Structure of a Computer

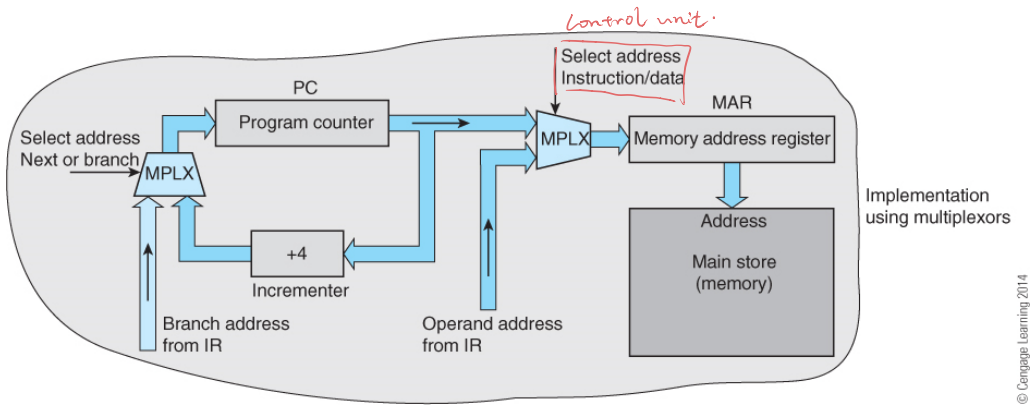
- But, how can we combine two input data lines together?

FIGURE 3.2 Partial structure of a hypothetical stored program machine



Structure of a Computer

- But, how can we combine two input data lines together?

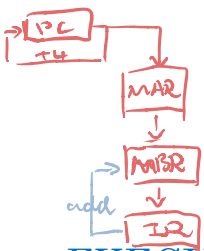


Structure of a Computer

Register Translation Language.

- Fetch/execute cycle in RTL .

Review Slide 26 in Chapter 1.

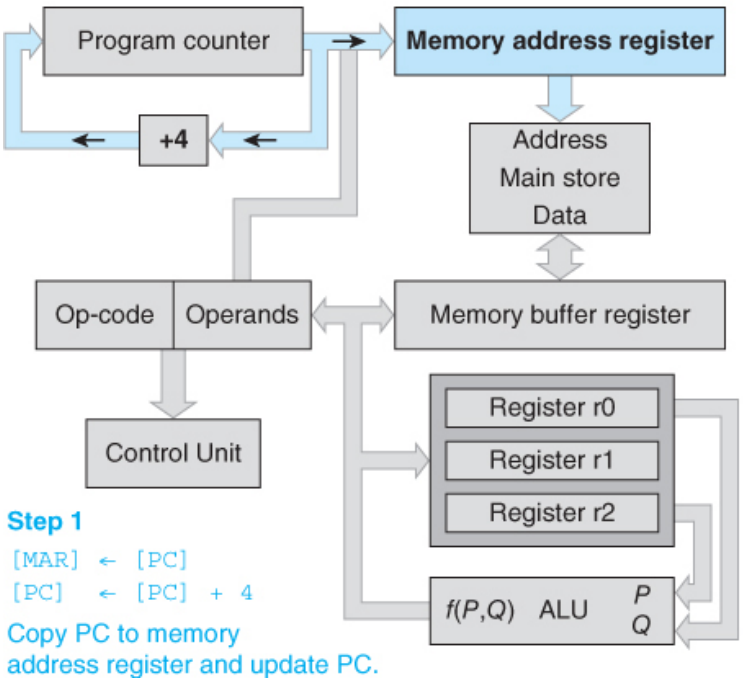


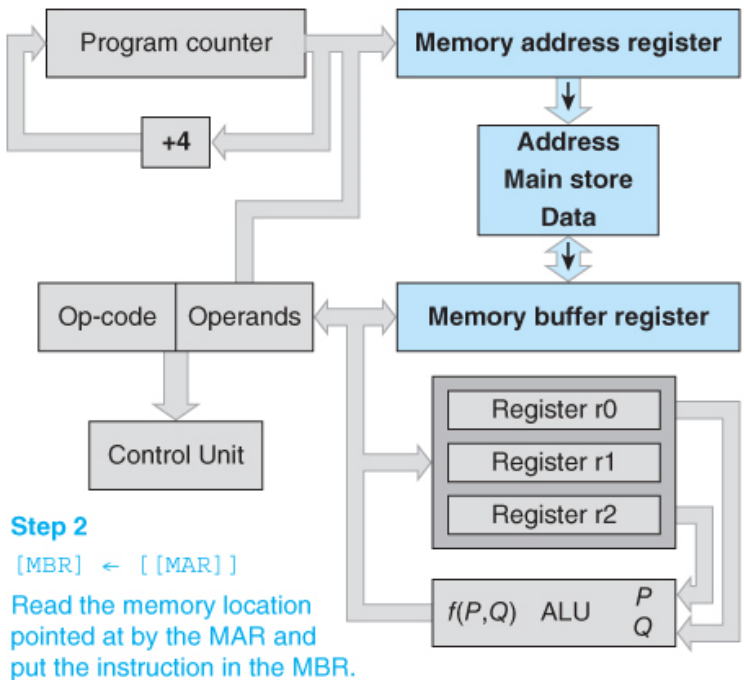

```
FETCH [MAR] ← [PC]          ; Step 1: copy PC to MAR
      [PC] ← [PC] + 4       ; Step 1: increment PC

      [MBR] ← [[MAR]]       ; Step 2: read instruction pointed at by MAR
      [IR] ← [MBR]          ; Step 3: copy instruction in MBR to IR
EXECUTE
LDR   [MAR] ← [IR(address)]
                            ; Step 4: copy operand address from IR to MAR
      [MBR] ← [[MAR]]       ; Step 5: read operand value from memory
      [r1] ← [MBR]          ; Step 6: copy the operand to a register, e.g., r1
```

Review Slides 27 and 28 in Chapter 1.

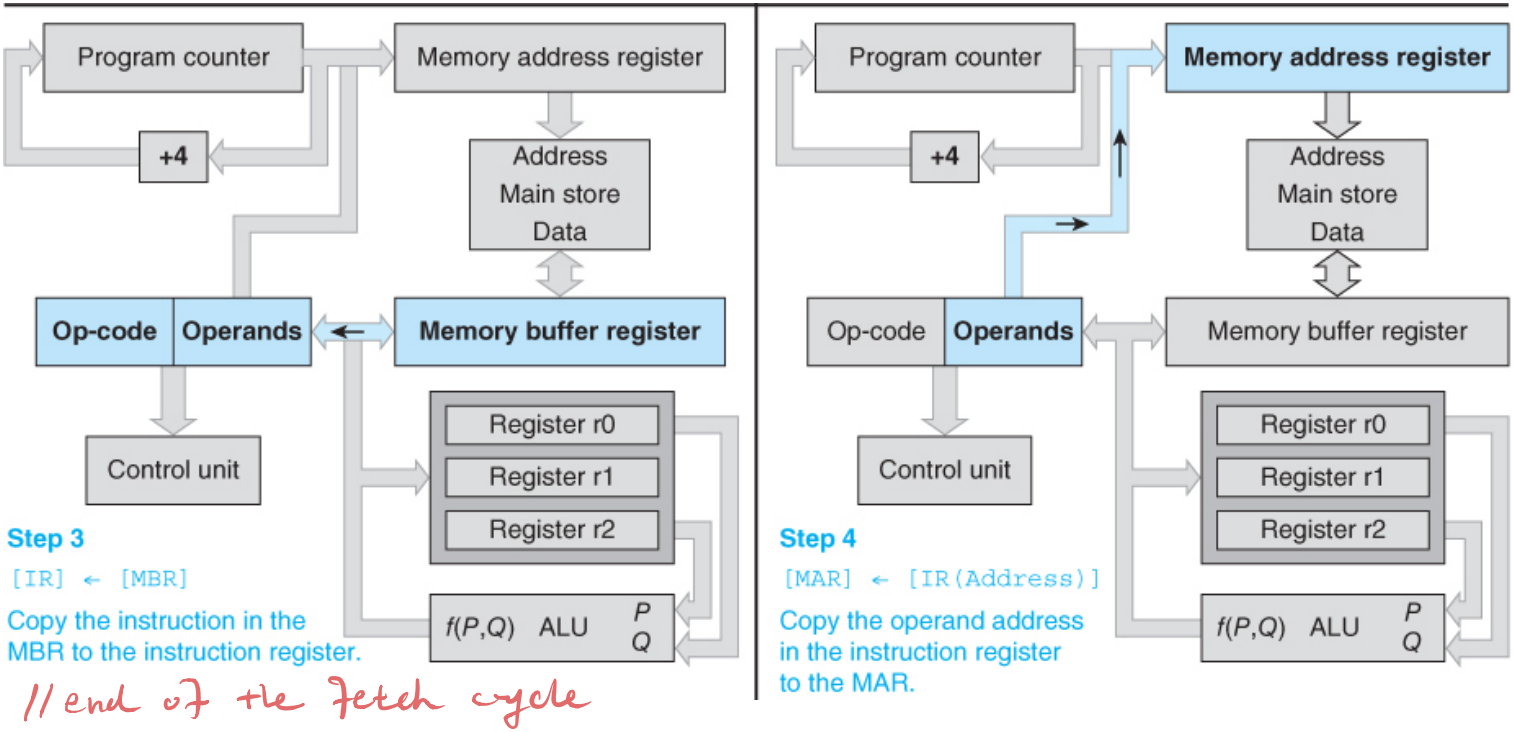
The coming 3 slides show the above 6 steps graphically.

Fetching and Executing an Instruction

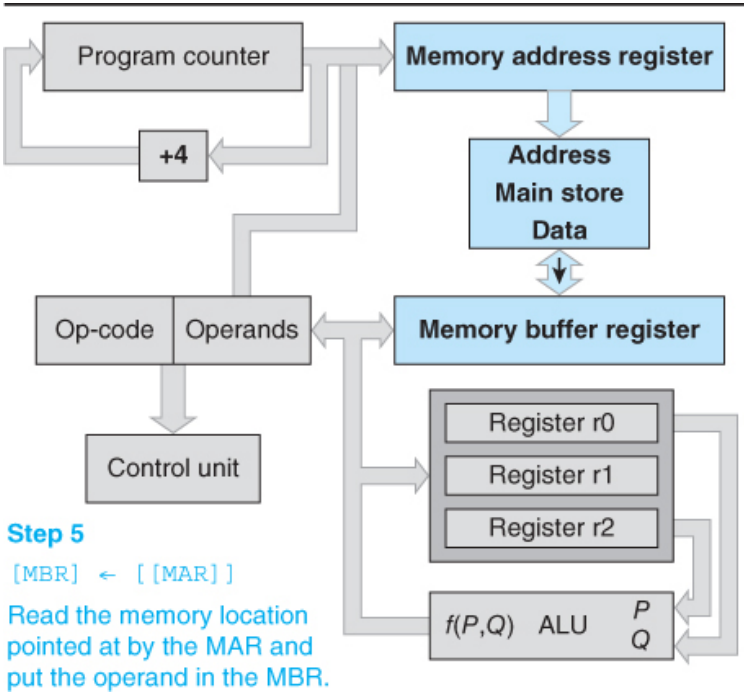


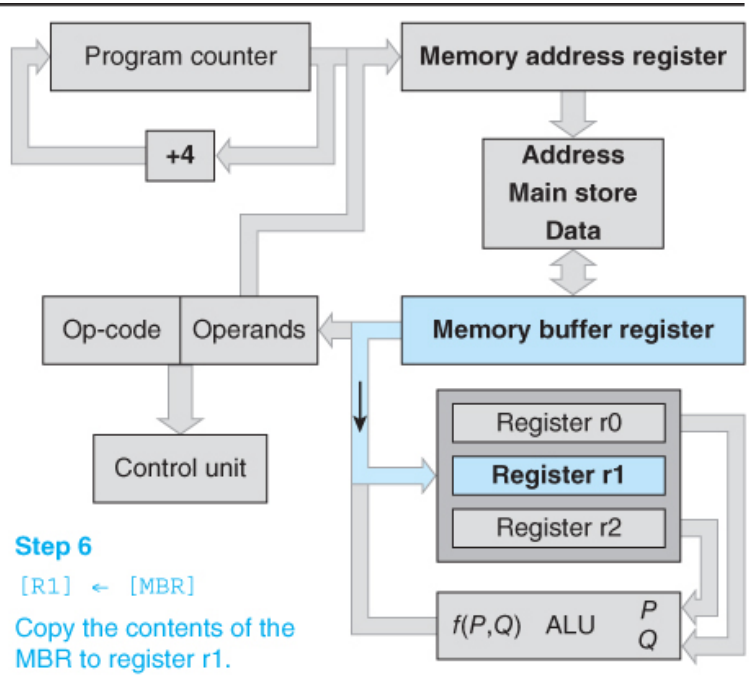


Fetching and Executing an Instruction



Fetching and Executing an Instruction

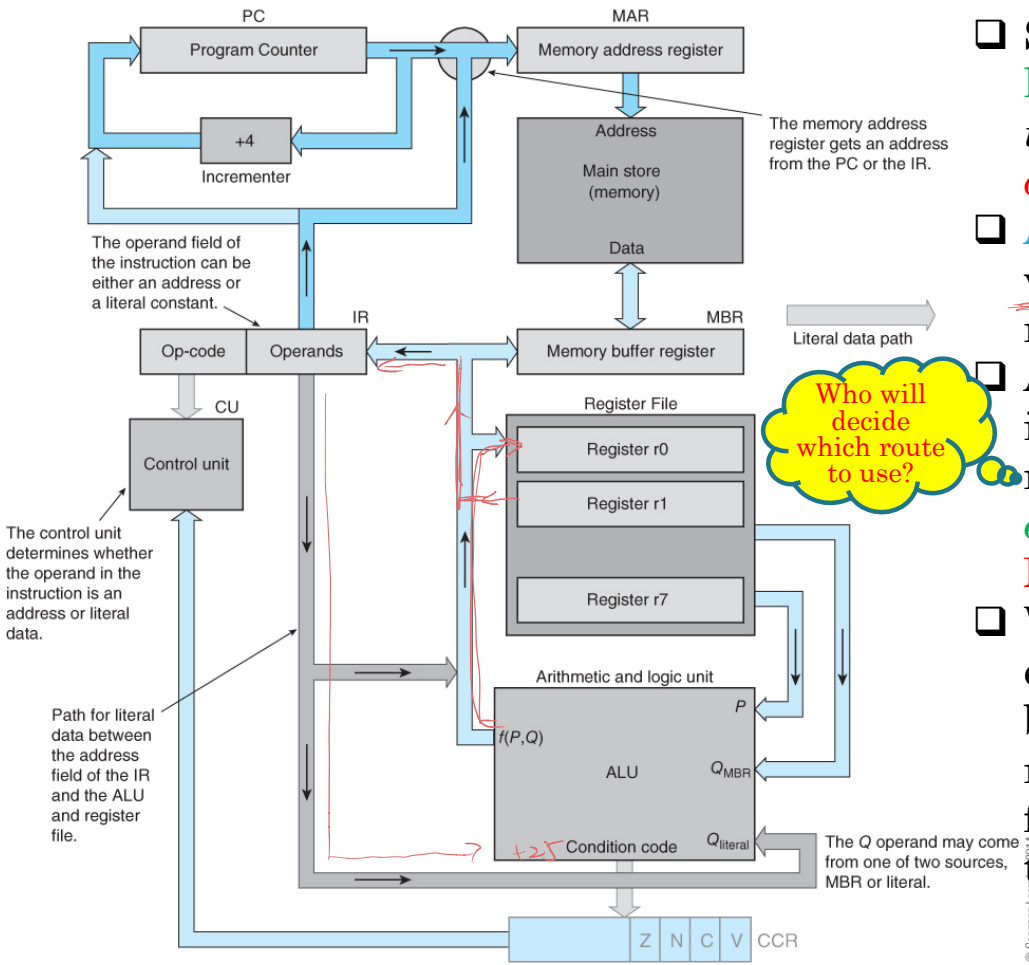




Dealing with Constants

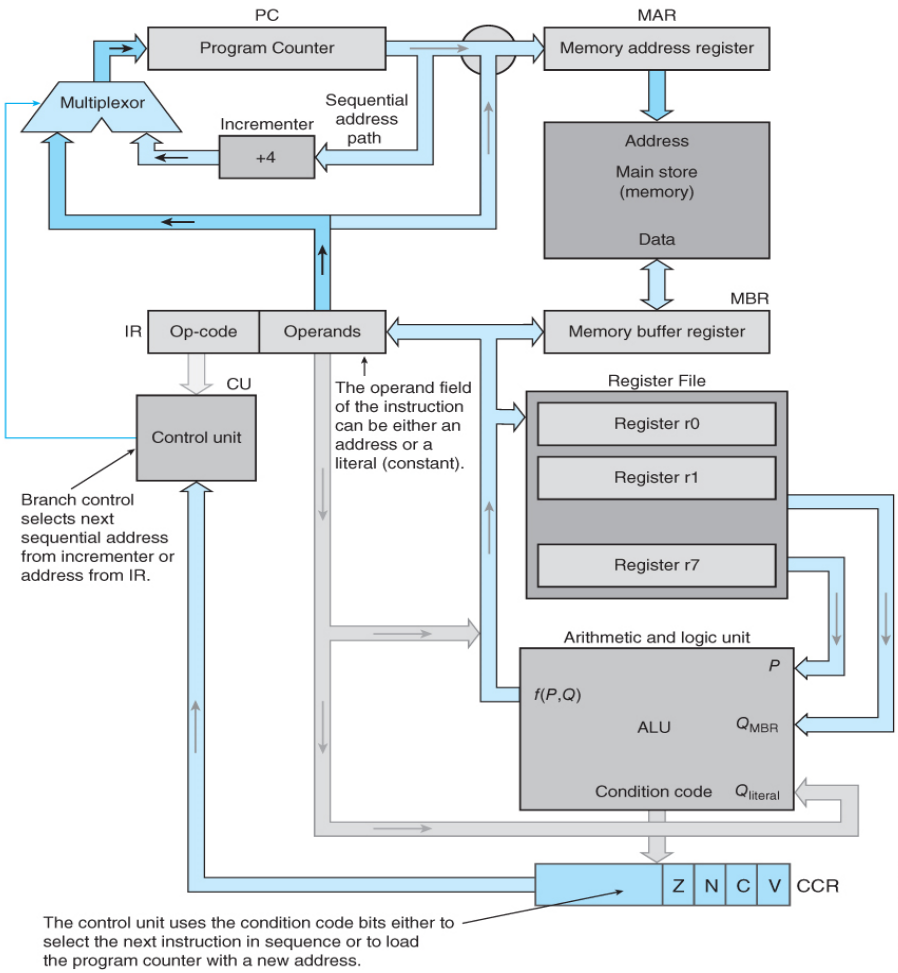
- Suppose we want to load the *number 1234 itself (a.k.a. literal operand)* into register r1.
- ADD **r0**,r1,#25 adds the value 25 to the content of r1 and puts the sum in r0
- A path from the instruction register, IR, routes a literal operand to *either* the register file, MBR, and ALU
- When ADD **r0**,r1,#25 is executed, the operand to be added to r1, i.e., #25, is routed from the operand field of the IR, rather than from registers.

FIGURE 3.4 Information paths for literal operands



Flow Control

FIGURE 3.5 Implementing conditional behavior at the machine level

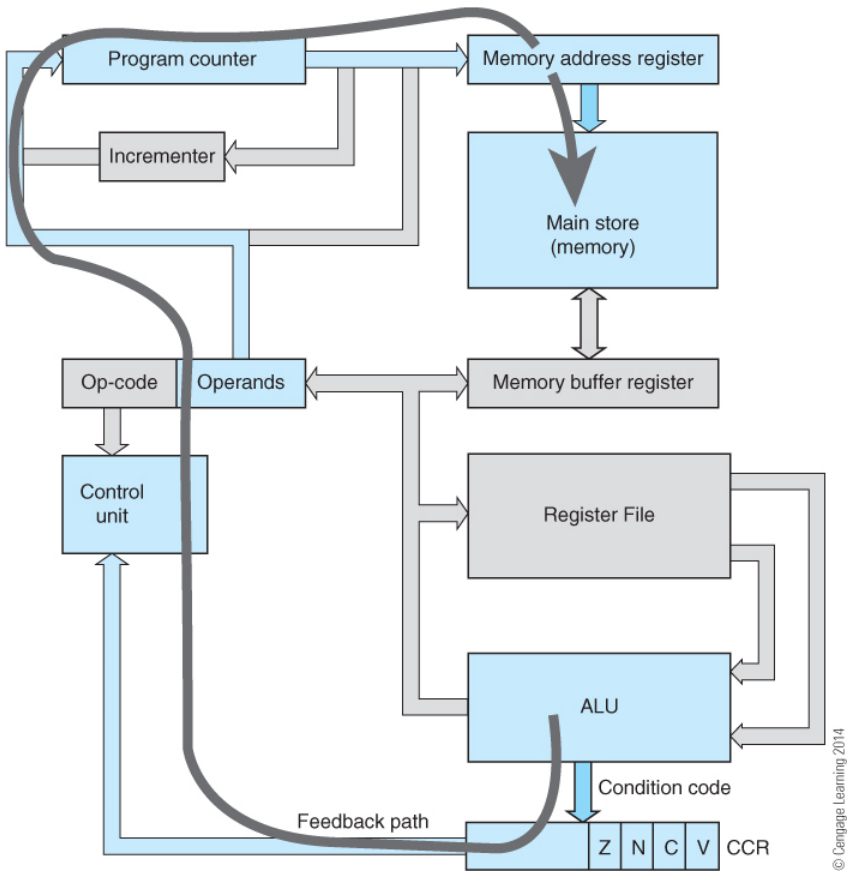


- *Flow control* refers to any action that *modifies* the normal instruction sequence.
- *Conditional behavior* allows a processor (*based on the values in the CCR register*) to select one of two possible courses of actions:
  - Continuing executing the *next instruction* in sequence, or
  - Loading the Program Counter with a new value and executing a *branch to another region* of code.

Flow Control

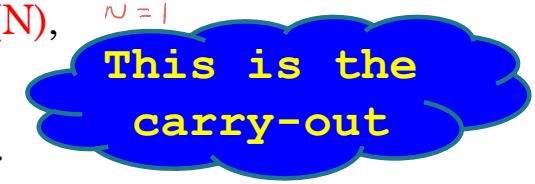
Figure 3.6 illustrate how the result from the ALU can be used to modify the sequence of instructions.

FIGURE 3.6 Feedback from ALU to instruction



Status Bits (Flags)

- When a computer performs an operation, it stores the *status* or *condition* information in the *Condition Code Register* (***CCR***).
- The processor records whether the result is
  - **Z**ero (Z),
  - **N**egative in two's complement terms (N),
  - generated a **C**arry (C), or
  - generated an arithmetic o**V**erflow (V).



Status Bits (Flags)

- Example (*assume that we are dealing with an 8-bit processor*):

00110011	11111111	01011100	11011100
+01000010	+00000001	+01000001	+11000001
01110101	100000000	10011101	110011101
Z = 0, N = 0	Z = 1, N = 0	Z = 0, N = 1	Z = 0, N = 1
C = 0, V = 0	C = 1, V = 0	C = 0, V = 1	C = 1, V = 0
51	-1	92	-36
+66	+1	+65	-63
---	---	---	---
117	0	-99	-99

Carry out

CISC means COMPLEX Instruction Set Computer

- CISC processors, like the *Intel IA32*,
  - automatically update status flags after each operation.

RISC means REDUCED Instruction Set Computer

- RISC processors, like the *ARM*,
  - require the programmer to request updating the status flags.
- In *ARM* processors, *programmers need to request updating* the *status flags by appending an S to the instruction*;
  - for example, SUBS (instead of SUB) or ADDS (instead of ADD).