

# Part 5

## CHAPTER 3

### Architecture and Organization



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## Pseudo instructions

- ❑ A *pseudo instruction* is an operation that the programmer can use when writing code.
  - The actual instruction **does not** have a **direct** machine language equivalent.
    - For example, you **can't** write `MOV r0,#0x12345678` to load register r0 with the 32-bit value 0x12345678 because the instruction is only 32 bits long in total.
    - Instead, you can use `LDR r0, = 0x12345678` *pseudo instruction*,  
**Yes, it is = not #** **It is NOT** `MOV r0, = 0x12345678`
      - the assembler will generate suitable code to carry out the same action.
        - *store the constant* 12345678<sub>16</sub> in a so-called *literal pool* or *constant pool* somewhere in memory after the current AREA
        - *generates suitable code* to load the stored constant 12345678<sub>16</sub> to r0

## Pseudo instructions

- ❑ Another *pseudo instruction* is **ADR r0, label**, which loads the 32-bit address of the line 'label' into register r0, using the appropriate code generated by the assembler.
- ❑ The following fragment demonstrates the use of the **ADR** *pseudo instruction*.

**ADR r1, MyArray** ;set up r1 to point to MyArray  
; loads register r1 with the 32-bit address of MyArray

...

**LDR r3, [r1]** ;read an element using the pointer

**MyArray DCD 0x12345678** ;the address of this data will be loaded to r1

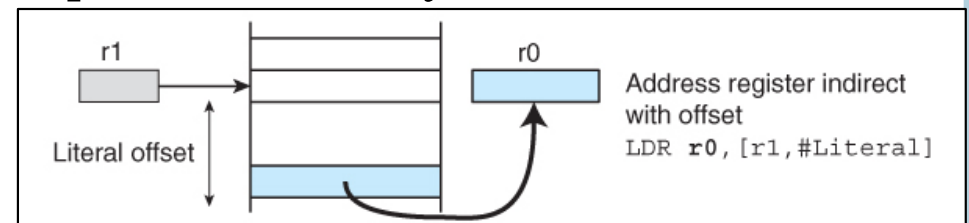
- ❑ The programmer does not have to know how the assembler generates suitable code to implement such *pseudo instructions*.
- ❑ All this is done automatically.
- ❑ This can be realized by utilizing the *program counter relative addressing*

This LDR instruction here is **NOT** a pseudo instruction

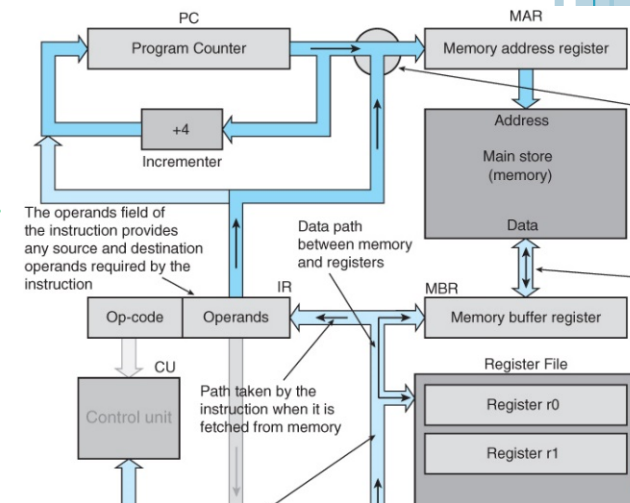
**But as a student, you need to know it!!**

- ❑ Register *indirect relative addressing allows* us to
  - *specify the location of an operand with respect to a register value.*

- ❑ LDR **r0**, [r1] specifies that the operand address is in r1
- ❑ LDR **r0**, [r1, #16] specifies that the operand is 16 bytes onward from r1.



- Suppose that we use *r15*, i.e., *the PC*, to generate an address by writing `LDR r0, [PC, #16]`.
  - The operand is 16 bytes onward from the PC
  - i.e.,  $8 + 16 = 24$  bytes from the current instruction.
    - *The ARM's PC in most of the cases is 8 bytes from the current instruction to be executed, due to **pipelining** (automatically fetches the next instruction before the current one has been executed).*



- ❑ If the program and its data are relocated elsewhere in memory, the *relative offset* does not change.

Having **ADR r4, P3** at line 08 will utilize the ADD instruction and the PC value to load the address of P3 in R4. To be translated to: **ADD r4, PC, #0x4**

## Pseudo instructions

FIGURE 3.20

To understand all these questions, try to put each pair of instructions in an assembly program and analyze the disassembly result.

What is the difference between **LDR r4, P3** and **ADR r4, P3**?

The **LDR** will load the value of P3 in r4. The **ADR** will utilize ADD/SUB to load the address of P3 in r4.

What will be the generated code if you replaced **LDR r4, P3** by **ADR r4, P3**?

What is the difference between **ADR r4, P3** and **LDR r4, = P3**?

Note that there is a difference between **LDR r4, P3** and **LDR r4, = P3**

The 1<sup>st</sup> one will load the VALUE of P3 in R4.

The 2<sup>nd</sup> one will copy the ADDRESS of P3 at the literal pool and then load the value of this address in R4.

Note that there is a difference between **LDR r4, = 0x1234** and **LDR r4, = P3**

The 1<sup>st</sup> one will copy 0x1234 at the literal pool and then load the value of this address in R4.

The 2<sup>nd</sup> one will copy the ADDRESS of P3 at the literal pool and then load the value of this address in R4.

4:	LDR	r0,=0x12345678	
0x00000000	E59F0018	LDR	R0,[PC,#0x0018]
5:	ADR	r1,Table	
0x00000004	E28F1008	ADD	R1,PC,#0x00000008
6:	ADR	r2,Table1	
0x00000008	E28F2008	ADD	R2,PC,#0x00000008
7:	LDR	r3, = 0xAAAAAAAA	
0x0000000C	E59F3010	LDR	R3,[PC,#0x0010]
8:	LDR	r4,P3	
0x00000010	E59F4004	LDR	R4,[PC,#0x0004]
0x00000014	ABCD DCBA	BLGE	0xFF377304
0x00000018	FFFFFF	(???)	
0x0000001C	22222222	EORCS	R2,R2,#0x20000002
0x00000020	12345678	EORNES	R5,R4,#0x07800000
0x00000024	AAAAAAA	BGE	0xFEAAAAAD4
0x00000028	00000000	ANDEQ	R0,R0,R0

PseudoInst.asm			
01	AREA	ConstPool, CODE, READONLY	
02	ENTRY		
03			
04	LDR	r0,=0x12345678	
05	ADR	r1,Table	
06	ADR	r2,Table1	
07	LDR	r3, = 0xAAAAAAAA	
08	LDR	r4,P3	
09			
10	Table	DCD	0xABCD DCBA
11	Table1	DCD	0xFFFFFFFF
12	P3	DCD	0x22222222

In "**ADR r4, P3**", the distance between **P3** and the **ADR** instruction MUST be represented as 0-255 and a rotation!!, while in "**LDR r4, = P3**", the distance Must be < 4096 (i.e., < 4K).



# ARM's Data-Processing Instructions

Addition      ADD,    ADC,  
                  **ADDS,    ADCS**

Subtraction    SUB,    RSB,  
                  **SUBS,    RSBS**

Negation        NEG,  
                  **NEGS**

Move            MOV,    MVN,  
                  **MOVS,    MVNS**

Multiplication    MUL,    MLA,  
                  **MULS,    MLAS**

Bitwise logic    AND,    ORR,    EOR,    BIC,  
                  **ANDS,    ORRS,    EORS,    BICS**

Comparison      **CMP,    CMN,    TEQ,    TST**

Shift            LSL,    LSR,    ASR,    ROR,    RRX,  
                  **LSLS,    LSRS,    ASRS,    RORS,    RRXS**

**There are 4 groups of ARM's instructions**

- ✓ **Data-Processing instructions**
- ✓ **Branching instructions**
- ✓ **Loading/Storing a single-register instructions**
- ✓ **Loading/Storing multi-registers instructions**

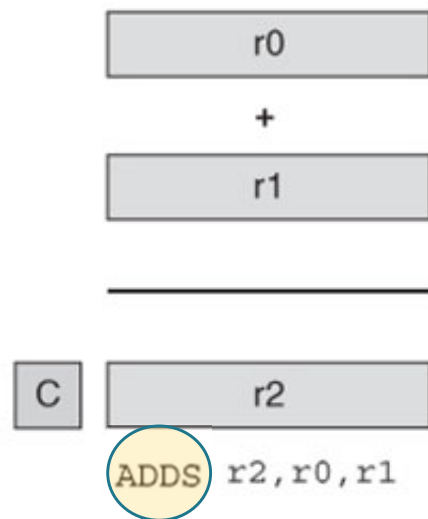
To learn more about any ARM assembly instruction,  
you can just Google the words  
**ARM Keil + the operation-code.**

For example, to learn more about "ADD" instruction,  
you need to Google("ARM Keil add").  
**It is usually the first link.**

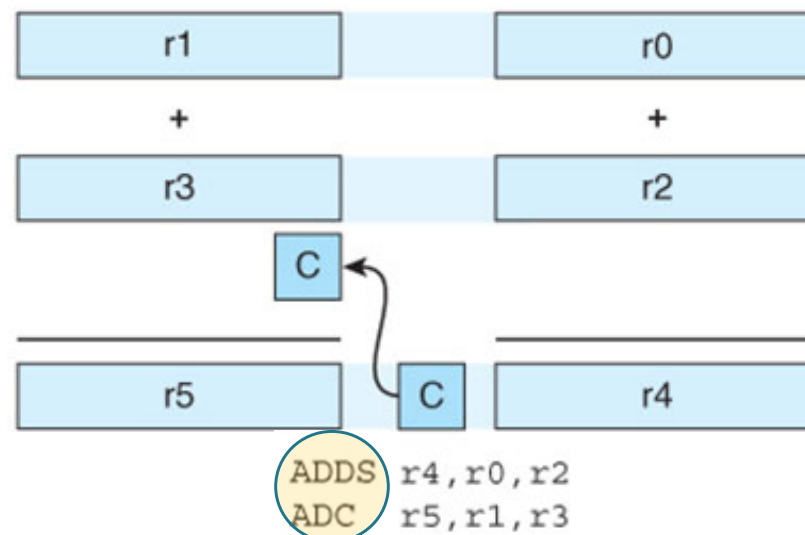
## ARM's Data-Processing Instructions (Arithmetic Instructions: Addition)

- ❑ A simple ADD (and ADDS) instruction adds two 32-bit values.
- ❑ ARM also has an ADC (add with carry), as well as ADCS, that adds two 32-bit values together with the carry bit.
  - This allows extended precision arithmetic as Figure 3.21 demonstrates.

**FIGURE 3.21** Single- and extended-precision addition



(a) Single-precision addition. When `r0` is added to `r1`, the result is loaded into `r2`, and the carry bit is loaded into the carry flag.



(b) Double-precision extended addition. When `r0` is added to `r2`, any carry out is stored in the carry bit. When `r1` is added to `r3`, the carry bit is added to their sum. In other words, the carry out generated by `ADDS r4, r0, r2` becomes the carry in used by `ADC r5, r1, r3`.

It can be extended to integers of arbitrary lengths.

## ARM's Data-Processing Instructions (Arithmetic Instructions: Subtraction)

- Beside the *normal subtraction* (SUB), ARM also provides *reverse subtraction* (RSB)

- SUB **r1**, r2, r3 ; [r1] ← [r2] - [r3]
- RSB **r1**, r2, r3 ; [r1] ← [r3] - [r2]

- RSB is useful, as ARM treats its operands differently.

- For example, to perform [r1] ← 10 - [r2], you can **not** use  
SUB **r1**, #10, r2 ; **THIS IS WRONG**  
instead, you can use  
RSB **r1**, r2, #10 ; **CORRECT**



## ARM's Data-Processing Instructions (Arithmetic Instructions: Subtraction)

□ Note that

RSB **r1**, #5

means

RSB **r1**, r1, #5

ADD **r1**, #5

means

ADD **r1**, r1, #5

When having a 3-operands instruction, if the 1<sup>st</sup> and 2<sup>nd</sup> operands are the same registers, it is allowed to short-hand the instruction by typing the register once. The assembler will take care of this short-hand and repeat the operand.

## ARM's Data-Processing Instructions (Arithmetic Instructions: Negation)

□ Negation is to subtract a number from 0

(*arithmetic complement, i.e., 2's complement*)

The end effect as if  
multiplying the  
operand by -1

○ ARM does **not** have a negation instruction as such

○ Instead, ARM provides a *pseudo instruction* called NEG

NEG **r1**, r2

NEG instruction has only two operands.

○ The RSB instruction is utilized to implement NEG

▪ To negate r2 (i.e., calculating  $0 - [r2]$ ) and store the result in r1,

NEG **r1**, r2

or

RSB **r1**, r2, #0

▪ To negate r2 (i.e., calculating  $0 - [r2]$ ) and store the result in r2,

NEG **r2**, r2

or

RSB **r2**, r2, #0

Or simple

RSB **r2**, #0

Can not be shortened to NEG r2

## ARM's Data-Processing Instructions (Arithmetic Instructions: Move and Move NOT)

- ❑ ARM provides a MOV instruction that copies the value of the second operand into the first operand

- To copy the content of r1 to r0,

MOV **r0**, r1 . . .

MOV instruction has only two operands.

- ❑ ARM also provides MVN (*move not*) that performs a **bitwise logical complement operation (i.e., logical NOT)** on the value of the second operand (i.e., *flipping each zero to one and each one to zero*), and places the result into the first operand

- To copy the **logical complement** of the content of r1 to r0,

MVN **r0**, r1 . . .

MVN instruction has only two operands.

### MOVS and MVNS

- ✓ **Update the N, Z and C flags according to the result**
- ✓ **Do NOT affect the V flag**

# ARM's Data-Processing Instructions

## (Arithmetic Instructions: Multiplication)

**MUL can not be shortened to two operands**

- ❑ The *multiply* instruction, MUL Rd, Rm, Rs
  - Takes two 32-bit signed integer values from registers Rm and Rs
  - Forms their 64-bit product
  - Stores in 32-bit register Rd *the lower-order 32 bits of the 64-bit product.*

```
MOV    r0, #121      ;load r0 with 121
MOV    r1, #96        ;load r1 with 96
MUL    r2, r0, r1      ;r2 = r0 x r1
```

- ❑ A 32-bit by 32-bit **multiplication** is *truncated* to the **lower-order 32 bits**.
- ❑ In MUL instruction, *same register can't* be used to specify both the *destination* Rd and the *operand* Rm,
  - because ARM's implementation uses **Rd as a temporary register** during multiplication. This is a feature of the ARM processor.
- ❑ ARM *does not* allow multiply by a constant

### MULS

- ✓ *Updates the N and Z flags according to the result*
- ✓ *Corrupts the C and V flags*

## ARM's Data-Processing Instructions (Arithmetic Instructions: Multiplication)

- ❑ ARM has a *multiply and accumulate* instruction, MLA, that
  - performs a multiplication and adds the product to a running total.

- ❑ MLA instruction has a four-operand form:

MLA **Rd**, Rm, Rs, Rn ; [Rd] = [Rm] × [Rs] + [Rn] .

**MLA can not be shortened to three operands**

- ❑ As in the normal MUL instruction,
  - A 32-bit by 32-bit **multiplication** is *truncated* to the **lower-order 32 bits**.
  - *same register can't* be used to specify both the *destination* **Rd** and the *operand* Rm
- ❑ ARM *does not* allow *multiply by a constant*

### MLAS

- ✓ *Updates the N and Z flags according to the result*
- ✓ *Corrupts the C and V flags*

## ARM's Data-Processing Instructions (Arithmetic Instructions: Multiplication)

- ❑ ARM's *multiply and accumulate* supports the calculation of an *inner product* (a.k.a. *dot product*).
- ❑ The inner product of two vectors  $\mathbf{a} = [a_1, a_2, \dots, a_n]$  and  $\mathbf{b} = [b_1, b_2, \dots, b_n]$  is defined as

$$s = \mathbf{a} \cdot \mathbf{b} = \sum_{i=1}^n a_i b_i = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$$



# ARM's Data-Processing Instructions

## (Arithmetic Instructions: Multiplication)

- ❑ The following program shows how the multiply and accumulate instruction is used to form the **inner product** between n-component vectors, Vector1 and Vector2

```

AREA MultiplyAndAccumulateExample, CODE, READONLY
ENTRY
n    EQU    4                ;4 components in this example
MOV    r4, #n                ;r4 is the loop counter
MOV    r3, #0                ;clear the inner product
ADR    r5, Vector1           ;r5 points to vector 1
ADR    r6, Vector2           ;r6 points to vector 2

Loop LDR    r0, [r5], #4      ;REPEAT
                                ; read a component of A
                                ; and update the pointer
    LDR    r1, [r6], #4      ; get the second element
                                ; and update the pointer
    MLA    r3, r0, r1, r3    ; add new product term to the total
                                ; (r3 = r3 + r0·r1)
    SUBS   r4, r4, #1        ; decrement the loop counter
                                ; (and remember to set the CCR)
    BNE    Loop              ;UNTIL all done

Vector1 DCD    1, 2, 3, 4
Vector2 DCD    2, 3, 4, 5
END

```

## ARM's Data-Processing Instructions (Arithmetic Instructions: Multiplication)

- ❑ In addition to the 32-bit MUL and MLA, ARM includes several forms of multiplication instruction, including
- UMLL      Unsigned long multiply  
              ( $R_m \times R_d$  yields 64-bit product in two registers)
  - UMLAL    Unsigned long multiply-accumulate
  - SMULL    Signed long multiply
  - SMLAL    Signed long multiply-accumulate



**We will NOT  
cover these  
instructions.**

## ARM's Data-Processing Instructions (Arithmetic Instructions: Division)

- ❑ ARM *does not implement a division* operation
- ❑ If needed, the programmer must write a suitable division routine to implement division

# ARM's Data-Processing Instructions (Bitwise Logical Operations)

The rest of the bits  
in these instructions  
are zeros.

- ❑ Logical operations are known as *bitwise operations* because they are applied to the individual bits of a register

It is  
**ORR**,  
*not*  
**OR**.

AND **r2**, r1, r0 → Example: 11001010 . 00001111 → 00001010

ORR **r2**, r1, r0 → Example: 11001010 + 00001111 → 11001111

EOR **r2**, r1, r0 → Example: 11001010 ⊕ 00001111 → 11000101

MVN **r2**, r0 → Example: 11001010 →  
1111111111111111111111111111111100110101

- ❑ The **MVN** operation can also be performed by using an **EOR** with the second operand equal to FFFFFFFF<sub>16</sub> (i.e., 32 1's *in a register*)
- the value of  $x \oplus (11...1111)_2$  is = **NOT**  $x$ .

MOV r1, #0xFFFFFFFF

EOR **r2**, r1, r0 ; Same as MVN **r2**, r0

## ANDS, ORRS, EORS, and MVNS

- ✓ Update the N, Z and C flags according to the result
- ✓ Do NOT affect the V flag

## ARM's Data-Processing Instructions (Bitwise Logical Operations)

❑ **Example 1:** suppose that


- register r0 contains the 8 bits **bbbbbbxx**,
- register r1 contains the 8 bits **bbbyyybb** and
- register r2 contains the 8 bits **zzzbbbb**,

where

- **xx**, **yyy**, and **zzz** represent the bits of desired fields and
- the **b**'s are unwanted bits.

❑ We wish to pack these bits to get the final value **zzzyyyxx** stored in r0.

❑ We can achieve this by:



```

AND    r0, r0, #2_11           ;Mask r0 to two bits xx
AND    r1, r1, #2_11100        ;Mask r1 to three bits yyy
AND    r2, r2, #2_11100000      ;Mask r2 to three bits zzz
ORR    r0, r0, r1               ;Merge r1 and r0 to get 000yyyxx
ORR    r0, r0, r2               ;Merge r2 and r0 to get zzzzyyyxx
  
```

❑ *The Keil assembler uses a prefix*

- **2\_** to indicate binary
- **8\_** to indicate octal
- **0x** or **&** to indicate hexadecimal
- **no prefix** to indicate decimal

## ARM's Data-Processing Instructions (Bitwise Logical Operations)

- ❑ **Example 2:** suppose we have an 8-bit value **abcdefgh** and
- ❑ we wish to
  - clear bits **b** and **d**,
  - set bits **a**, **e**, and **f**, and
  - toggle (invert) bit **h**,
 i.e., generate the following output **10c011g $\bar{h}$**

- ❑ We can achieve this by:

```

AND  r0, r0, #2_10101111 ;Clear bits b and d to get  a0c0efgh
ORR  r0, r0, #2_10001100 ;Set bits a, e, and f to get 10c011gh
EOR  r2, r2, #2_1         ;Toggle bit h to get the result

```



## ARM's Data-Processing Instructions (Bitwise Logical Operations)

- ❑ **ARM** provides a *bit clear* instruction, **BIC**, that
  - ANDs its first operand with the complement of its second operand.
- ❑ **Example:** suppose we have  $r1 = 10101010$  and  $r2 = 00001111$ .
  - The instruction **BIC r0, r1, r2** yield  $10100000$

### BICS

- ✓ *Updates the N, Z and C flags according to the result*
- ✓ *Does NOT affect the V flag*

## ARM's Data-Processing Instructions (Arithmetic Instructions: Comparison)

- ❑ In ARM, updating the condition flags can be *implicit* or *explicit*.
- ❑ Both implicit and explicit flags' updates modify the contents of *the condition code register (CCR)*, a.k.a. *current program status register (CPSR)*, which is later can be tested to determine whether execution continues in sequence, or a branch is taken

- Example of *implicit* updates for the condition flags

SUBS **r1**, r1, r2

- Example of *explicit* updates for the condition flags

CMP r1, r2

This instruction will evaluate  $r1 - r2$  *without storing the result*, and set the *condition code register*

```

CMP    r1, r2           ;is r1 = r2?
BEQ    DoThis           ;if equal then goto DoThis
ADD    r1, r1, #1      ;else add 1 to r1
B      Next            ;jump past the then part
.
DoThis SUB r1, r1, #1    ;subtract 1 from r1
Next   ...             ;both forks end up here

```

## ARM's Data-Processing Instructions

### (Arithmetic Instructions: Comparison)

- **ARM** has *four* instructions in its *test-and-compare* group which *explicitly update the condition code flags* (i.e., *no need to append an S to any of them*)
- **CMP** (compare instruction)
    - *Subtracts* the second operand from the first and *update all flags*
  - **TEQ** (test equivalent instruction)
    - Determines whether two operands are equivalent or not (*similar to EORS, except that the result is discarded*)
  - **TST** (test instruction)
    - Compares two operands by **ANDing** them together and *update flags*
    - Usually used to *test individual bits*;
    - `TST r0, #2_00100000 ;AND r0 with 00100000 to test bit 5`  
*••• BNE LowerCase ;If bit 5 is 1, jump to lowercase*
  - **CMN** (compare negative instruction).
    - 2's complements the second operand before performing the comparison  
`CMN r1, r2 ; evaluates [r1] - (-[r2])`  
*••• ; i.e., evaluate [r1] + [r2]*

It is  
**BNE**,  
*not*  
**BEQ**.

It is **CMN**, *not* **CPN**. Correct the book, page 178

#### TEQ and TST

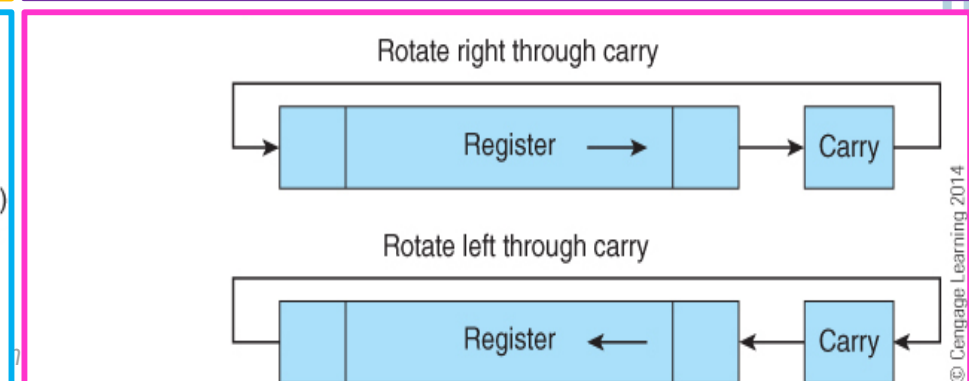
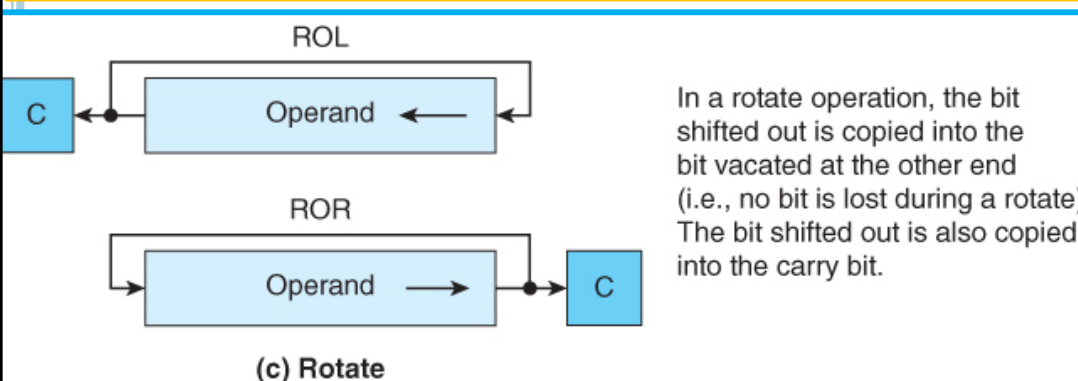
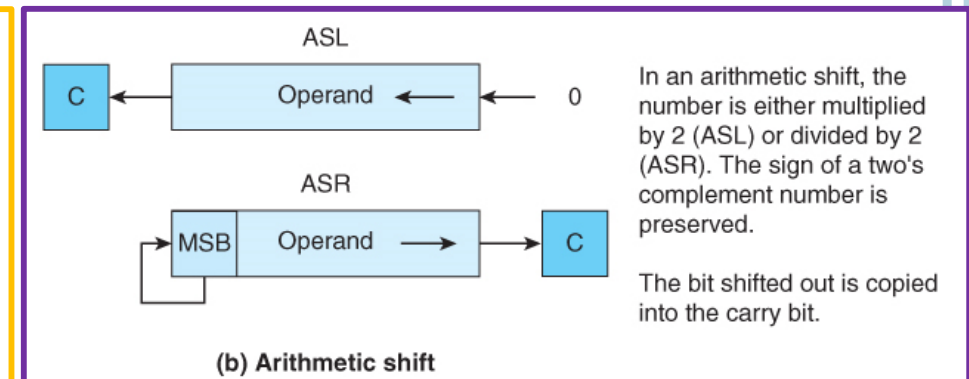
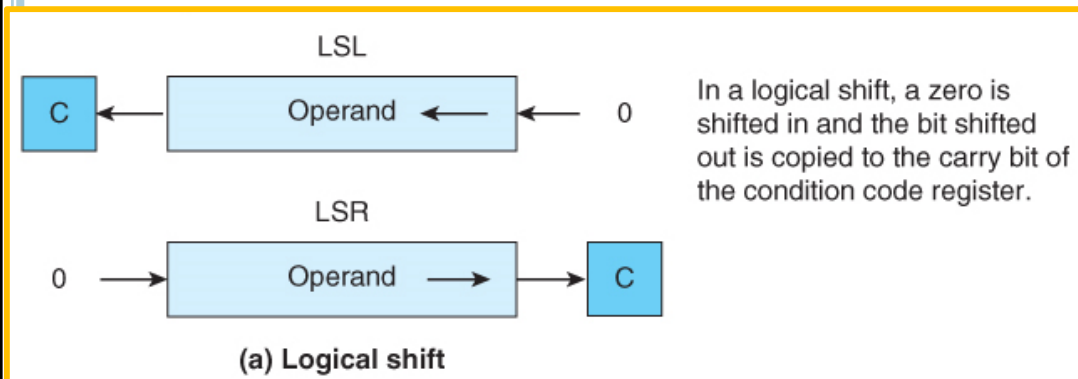
- ✓ *Update the N, Z and C flags according to the result*
- ✓ *Do NOT affect the V flag*

**CMP and CMN** *update ALL flags according to the result*

# ARM's Data-Processing Instructions

## (Shift Operations)

- ❑ *Shift* operations **move bits** one **or more** places **left** or **right**.
  - **Logical shifts**
    - *insert a 0* in the vacated position.
  - **Arithmetic shifts**
    - *replicate the sign-bit* during a right shift
  - **Circular shifts**
    - *the bit shifted-out of one end is shifted-in the other end*  
i.e., the register is treated as a ring
  - **Circular shifts through carry**
    - *included the carry bit in the shift path*



## ARM's Data-Processing Instructions (Shift Operations)

Examples of **logical shifts** on a *16-bit value*

Source string	Direction	Number of shifts	Destination string
<b>0</b> 110011111010111	Left	1	110011111010111 <b>0</b>
<b>01</b> 10011111010111	Left	2	10011111010111 <b>00</b>
<b>011</b> 0011111010111	Left	3	0011111010111 <b>000</b>
011001111101011 <b>1</b>	Right	1	<b>0</b> 011001111101011
01100111110101 <b>11</b>	Right	2	<b>00</b> 01100111110101
0110011111010 <b>111</b>	Right	3	<b>000</b> 0110011111010

These examples are hypothetical, as ARM registers are 32 bits, not 16 bits.

## ARM's Data-Processing Instructions (Shift Operations)

- ❑ The *rotate through carry* instruction (sometimes called *extended shift*) included the carry bit in the shift path.
  - The carry bit is shifted into the bit of the word vacated, and
  - the bit of the word shifted out is shifted into the carry.
- ❑ If the **carry** = 1 and the *eight-bit word* to be shifted is 01101110, a *rotate left through carry* would give 11011101 and

**carry** = 0

**FIGURE 3.24**

The rotate through carry



This example is hypothetical, as ARM registers are 32 bits, not 8 bits.



# Implementing a Shift Operation on the ARM

- ❑ **ARM** *has no explicit shift operations!!*.
- ❑ **ARM** *combines shifting with other data processing operations*, where
  - the **second operand** in the arithmetic operation (i.e., the **LAST parameter in the assembly arithmetic instruction**) is allowed to be shifted **before** it is used.
  - For example,  
ADD **r0**, r1, r2, LSL #1 ;  $[r0] \leftarrow [r1] + [r2] \times 2$ 
    - logically shift left the contents of r2,
    - add the result to the contents of r1, and
    - put the results in r0
- ❑ **ARM** *also combines shifting with MOV and MVN instructions*
  - For example,  
MOV **r3**, r3, LSL #1 ;  $[r3] \leftarrow [r3] \times 2$
  - **ARM** provides **pseudo** shift instructions, which are translated to **MOV** instructions.
  - For example,  
LSL **r3**, r3, #1 ; will be converted to:  
MOV **r3**, r3, LSL #1  
or simply  
LSL **r3**, #1

# Implementing a Shift Operation on the ARM

- ❑ **ARM** support both *static* and *dynamic* shifts (except *rotate through carry* instruction which allows *only one single shift* per instruction)
  - In *static shift*, the number of shift places
    - is determined *when the code is written*
    - can only have the following values, inclusive:
      - **LSL**: allowable values are from **#0** to **#31** (*32 different values*)
      - **LSR**: allowable values are from **#1** to **#32** (*32 different values*)
      - **ASR**: allowable values are from **#1** to **#32** (*32 different values*)
      - **ROR**: allowable values are from **#1** to **#31** (*31 different values*)
  - The remaining value is used to encode RRX*
  - In *dynamic shift*, the number of shift places
    - is determined *when the code is executed, i.e., at run time*
- ❑ You can perform *dynamic shifts* as follow

MOV **r4**, r3, LSL r2                                   ; [r4] ← [r3] × 2<sup>r2</sup>  
 or  
 LSL **r4**, r3, r2                                       ; [r4] ← [r3] × 2<sup>r2</sup>

This instruction

- shifts the contents of r3 left by the value in r2 and
- puts the result in r4.

○ *If the value in r2 is ≥ 32, zero will be stored in r4*

# Implementing a Shift Operation on the ARM

- ❑ **ARM** implements only the following five shifts

LSL   logical shift left

LSR   logical shift right

ASR   arithmetic shift right

ROR   rotate right

RRX   rotate right through carry                      (one shift)

- ❑ *Other shift operations must be synthesized by the programmer.*

# Implementing a Shift Operation on the ARM

## ❑ *Other shift operations must be synthesized by the programmer.*

- An *arithmetic shift left* is effectively the same as a *logical shift left*
- For a 32-bit value,  
an *n-bit rotate shift left* is identical to a *32 – n rotate shift right*
- *Rotate left through carry* can be implemented by means of  
ADCS `r0, r0, r0 ; add r0 to r0 with carry and set the flags`
  - The instruction means  $r0 + r0 + C$ , i.e.,  $2 \times r0 + C$ , i.e.,
    - shifting left the content of r0
    - store the value of C in the vacant bit to the left, and
    - storing the shifted-out bit in the carry flag