MATH 1600 Linear Algebra — Winter 2020

Tutorial 4 - Wednesday

REFs and RREFs

1. Consider the following matrices with real coefficients.

$$M = \begin{bmatrix} 1 & 2 & 0 & | & 0 \\ 1 & 1 & 1 & | & 0 \\ 0 & 1 & 0 & | & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 2 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & -1 & -1 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 3 & -1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

- (a) Which of the above matrices are in row echelon form? Explain your answer.
- (b) Which of the above matrices are in reduced row echelon form? Explain your answer.
 (c) Find a sequence of elementary row operations that would turn M into B and a sequence of row operations that would turn C into B. Y₁ = Y₁ Y₂ Y₃ Y₃
- (e) Conclude that D is the RREF of M, B and C.
- (f) Suppose that M is an augmented matrix of a linear system, that is $M = (A|\mathbf{b})$ for some 3×3 matrix A and some column vector $\mathbf{b} \in \mathbb{R}^3$. Find A and \mathbf{b} , and solve the linear system $A\mathbf{x} = \mathbf{b}$.

Linear Systems

2. Consider the following matrix with real coefficients:

where a is a parameter, that is, it is allowed to vary over \mathbb{R} .

(a) Find the values of a for which the system $A\mathbf{x} = \mathbf{0}$ is consistent.

(b) Find the values of a for which the system $A\mathbf{x} = \mathbf{b}$, with $\mathbf{b} = \langle -1, -1/2 \rangle$, has for solutions, exactly and infinitely many solutions. $\mathcal{L} = \mathcal{L} = \mathcal{L} = \mathcal{L} = \mathcal{L}$

3. Consider the following linear system with coefficients in \mathbb{Z}_3 .

- (a) Find the coefficient matrix and the augmented matrix system for this system of linear equations.
- (b) Solve this system over \mathbb{Z}_3 . (Your solution vector(s) must have entries in \mathbb{Z}_3 only)
- (c) Let $B = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \end{bmatrix}$ be a matrix with entries in \mathbb{Z}_3 . Find the RREF of B over \mathbb{Z}_3 (Your elementary row operations must involve scalars in \mathbb{Z}_3 only). Why doesn't the system $B\mathbf{x} = 0$ have infinitely

$$\begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \end{bmatrix} \cdot \frac{V_1 = \vec{2} V_1}{V_2 = N_2 \vec{2} V_1} \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 0 \end{bmatrix} \cdot \frac{V_2 = \frac{2}{3} V_2}{V_1 = V_1 - \frac{1}{3} V_2} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}.$$

Pivots and Free Variables

4. Consider the following \mathbb{R} -valued matrix:

You are given the information that R is the reduced row echelon form of some 5×7 matrix A.

- (a) How many pivots (a.k.a. leading 1's) does R have? How many free variables does R have?
- (b) How many free variables does A have? Explain your answer. Which variables among x_1, \ldots, x_7 are (c) Without computing, explain why the system $A\mathbf{x} = 0$ has infinitely many solutions.

 Variable numbers = 27 CA = 2