

Matrix equation  
SLE  
Inverse matrix (2)

## Recap

Consider  $m$  linear equations with  $n$  variables  $x_1, x_2, \dots, x_n$

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

The **coefficient matrix** of an SLE is

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

We have a matrix equation

$$\begin{aligned} A\vec{x} &= \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \\ &= \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \end{bmatrix} = \vec{b} \end{aligned}$$

where  $\vec{x} = [x_1 \ x_2 \ \dots \ x_n]^T$  and  $\vec{b} = [b_1 \ b_2 \ \dots \ b_n]^T$ .

The matrix equation  $A\vec{x} = \vec{b}$  exactly represents the SLE.

In particular, if the coefficient matrix  $A$  is a square matrix and  $A$  is invertible, then we multiply  $A^{-1}$  on the both sides of the equation

$$A\vec{x} = \vec{b}$$

$$A^{-1}(A\vec{x}) = A^{-1}\vec{b}$$

$$(A^{-1}A)\vec{x} = A^{-1}\vec{b}$$

$$I\vec{x} = A^{-1}\vec{b}$$

$$\vec{x} = A^{-1}\vec{b}$$

Hence, the SLE has a unique solution  $\vec{x} = A^{-1}\vec{b}$ .

## Example

Now we consider the SLE

$$x - y + z = 3$$

$$2y - z = 0$$

$$2x + y + 2z = 1$$

The matrix equation is

$$A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}.$$

Use the method of inverse matrix to find the solution.

# Examples

(Lecture note Example 8.6)

For what value(s) of  $c$  does the following SLE not have a unique solution?

$$x + y + z = 1$$

$$x + 2y + 3z = 1$$

$$x + 2y + cz = 1$$

# The theory of SLE

- Tell some information for SLEs from matrix equations

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Now let  $\vec{w}(t) = (1 - t)\vec{x}_1 + t\vec{x}_2$ , where  $t$  is a parameter.

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Let us check

$$\begin{aligned} A\vec{w}(t) &= A((1 - t)\vec{x}_1 + t\vec{x}_2) \text{ (definition of } \vec{w}(t)) \\ &= (1 - t)(A\vec{x}_1) + t(A\vec{x}_2) \text{ (Distributivity and scalars factor out)} \\ &= (1 - t)\vec{b} + t\vec{b} \text{ (because } A\vec{x}_1 = \vec{b} = A\vec{x}_2) \\ &= \vec{b} - t\vec{b} + t\vec{b} = \vec{b}. \end{aligned}$$

**Corollary** For any system of linear equations there are exactly 3 possibilities:

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Next, we see how to determine which situation an SLE has.

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Recall that every matrix can be reduced to a **unique** RREF.



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**Definition** The **rank** of a matrix is the number of non-zero rows in the row-reduced echelon form of the matrix. We can use  $r(A)$  to denote the rank of matrix  $A$ .

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Also, we say that the  $m \times n$  matrix  $A$  has **full rank** if  $r(A) = n$ , i.e. if every column of the RREF of  $A$  contains the leading one for some row.

# Examples

Find the rank of each matrix. Which has a full rank?

$$(a) \quad A = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 2 & 1 \\ -2 & -3 & 4 \end{bmatrix} \quad (b) \quad A = \begin{bmatrix} 1 & 1 & 1 \\ -2 & -2 & -2 \\ 3 & 3 & 3 \end{bmatrix}$$

$$(c) \quad [A \mid \vec{b}] = \left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 2 & 1 & 3 \\ 3 & 3 & 4 \end{array} \right] \quad (d) \quad [A \mid \vec{b}] = \left[ \begin{array}{cc|c} 3 & 4 & 1 \\ 2 & 1 & 2 \end{array} \right]$$

## Examples

We wish to solve a system of linear equations of the form  $A\vec{x} = \vec{b}$ , where  $A$  is a  $4 \times 4$  nonsingular coefficient matrix. If we know that the inverse of  $A$  is

$$A^{-1} = \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -2 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix},$$

find a formula for the solution vector  $\vec{x}$  in terms of components of the right hand side vector  $\vec{b}$ .

What is the coefficient matrix  $A$ ?