Design Principles

Design Principle: Encapsulate what varies

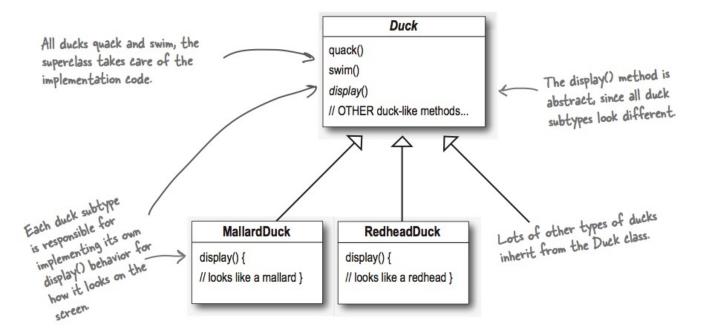
Take the parts that vary and encapsulate them, so that later you can alter or extend the parts that vary without affecting those that don't.

Case Study: Duck Hunt Simulation Game

• Suppose a company is building a duck hunt simulation game ...

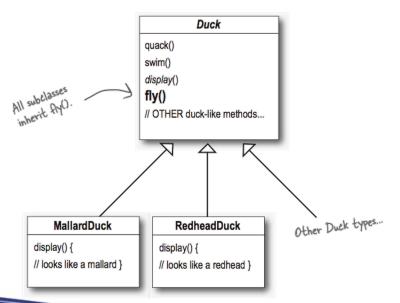


Modeling Ducks



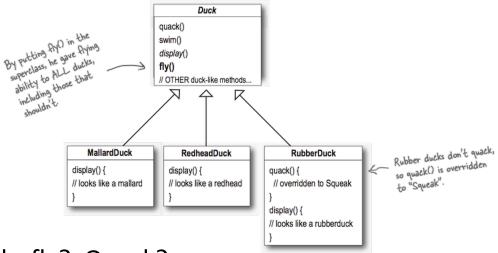
Making Ducks Fly

Need to add code to make ducks fly in the simulation ...



Making Ducks Fly: Problem

• The company decides to add a RubberDuck to the game as an Easter egg



Should all ducks fly? Quack?

- Solutions?
 - We could override the fly method in RubberDuck to do nothing ...

```
RubberDuck

quack() { // squeak}
display() { // rubber duck }
fly() {
    // override to do nothing
}
```

- This isn't a horrible solution, but what about when we add a DecoyDuck class for hunters in the game?
 - And decoys should neither quack nor fly ...

```
DecoyDuck

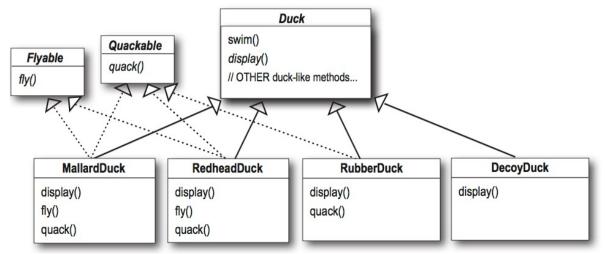
quack() {
    // override to do nothing
}

display() { // decoy duck}

fly() {
    // override to do nothing
}
```

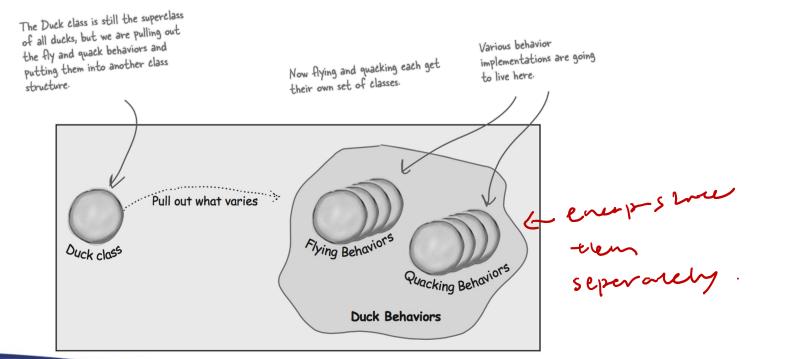
- Inheritance probably isn't the answer in this case
- As we add new types of ducks, we will have to examine and perhaps override fly and quack for each new class
- We will likely have a lot of duplicate code in the subclasses
- How many different ways can a duck really fly?

• Another option: use an abstract class (or in Java, an interface)

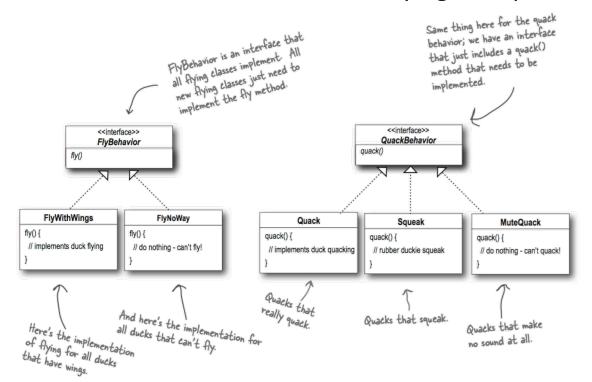


• Has this solved the problem?

- We know:
 - New ducks will be added to the system as time passes
 - Duck behaviours differ from duck type to duck type
 - Certain behaviours are not appropriate for all ducks
- We need to keep these considerations in mind when designing the system ...



We create an interface/abstract class for flying and quacking behaviour



- Now the functionality that might change between subclasses has been encapsulated in its own set of classes
- We will store the flying and quacking behaviours of a duck as instance variables in the Duck class
- A duck will delegate its flying and quacking behaviours, rather than implementing them itself

The behavior variables are declared as the behavior INTERFACE type.

These methods replace fly() and quack().

Instance variables hold a reference to a specific behavior at runtime.

Duck

FlyBehavior flyBehavior QuackBehavior quackBehavior

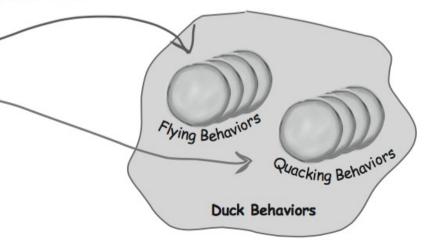
performQuack()

swim()

display()

performFly()

// OTHER duck-like methods...



```
class FlyBehaviour
   public:
      virtual void fly() = 0;
class FlyWithWings : public FlyBehaviour
   public:
      virtual void fly() {
        cout << "I'm flying with my wings!" << endl;</pre>
class FlyNoWay : public FlyBehaviour
   public:
      virtual void fly() {
         cout << "I can't actually fly!" << endl;</pre>
};
```

```
class Duck {
   public:
      Duck() { }
      ~Duck() {
         delete this-> flyBehaviour;
         delete this-> quackBehaviour;
      void performFly() {
         this-> flyBehaviour->fly();
      void performQuack() {
         this-> quackBehaviour->quack();
   protected:
      FlyBehaviour* flyBehaviour;
      QuackBehaviour* quackBehaviour;
};
```

```
class MallardDuck : public Duck
{
   public:
        MallardDuck() {
        this->_quackBehavior = new Quack();
        this->_flyBehavior = new FlyWithWings();
   }
};
```

Benefits:

- Eliminated code duplication
- Other types of objects can reuse the fly and quack behaviours
- Can easily add / modify existing behaviours without necessarily (or heavily) modifying our duck classes
- Can dynamically change behaviours at run-time