

# *Part 1*

## CHAPTER 3

### Architecture and Organization



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# The Instruction Set Architecture

In this chapter, we will:

- ❑ **Revisit** the *stored program machine* and **show** how an instruction is executed
- ❑ **Introduce** instruction formats, including
  - *memory-to-register*,
  - *register-to-memory*, and
  - *register-to-register*
- ❑ **Demonstrate** how a processor implements *conditional behavior*
- ❑ **Describe** a set of computer assembly instructions (*instructions set*)
- ❑ **Show** how computers access data (*addressing modes*)
- ❑ **Introduce** an ARM's *Integrated Development Environment* (IDE) and **show** how ARM programs are written

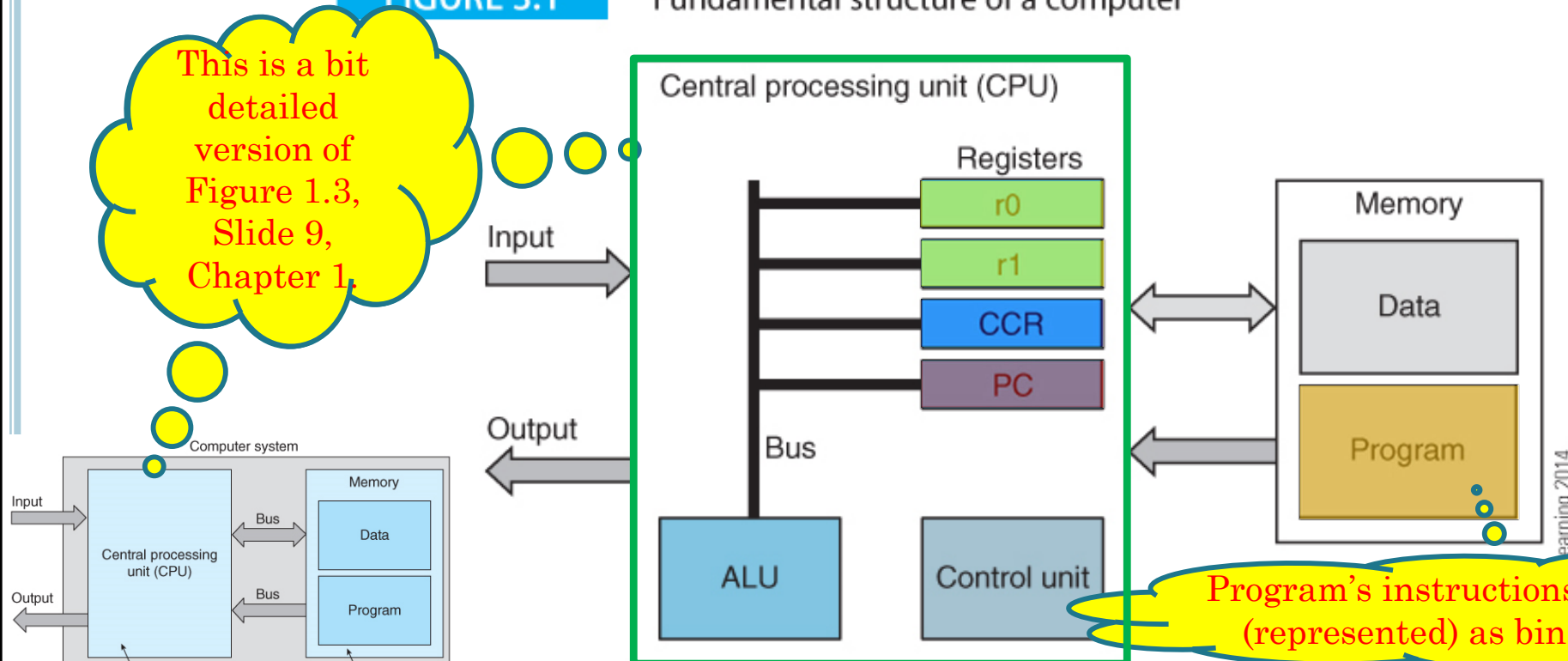
# The Instruction Set Architecture

- ❑ Figure 3.1 illustrate the structure of a **simple *hypothetical stored program computer***.
- ❑ The **CPU** reads instructions from memory and executes them.
- ❑ *Temporary data* is stored in **registers** such as *r0* and *r1*.
- ❑ The **PC**, *program counter*, is the register that *points at (i.e., contains the address of) the next instruction to be executed*.
- ❑ The **CCR**, *Condition Code Register*, is a collection of flag bits for a processor.

Intel calls it the "**Instruction Address Pointer**", a better name than the **PC**

FIGURE 3.1

Fundamental structure of a computer



This is a bit detailed version of Figure 1.3, Slide 9, Chapter 1.

Program's instructions are encoded (represented) as binary values.

## Instruction Formats

- ❑ A computer executes instructions from 8-bits wide to multi-bytes wide.
- ❑ The **instruction format** defines the *anatomy of an instruction*
  - the **number of operands**, and
  - the number of **bits** devoted to **defining each operation**,
  - the **format of each operand**.
- ❑ Below are several *hypothetical* examples of assembly instructions:

**LDR** **registerDestination**,memorySource

**STR** registerSource,**memoryDestination**

**Operation** **registerDestination**,registerSource1,registerSource2

LDR     **r1**, 1234

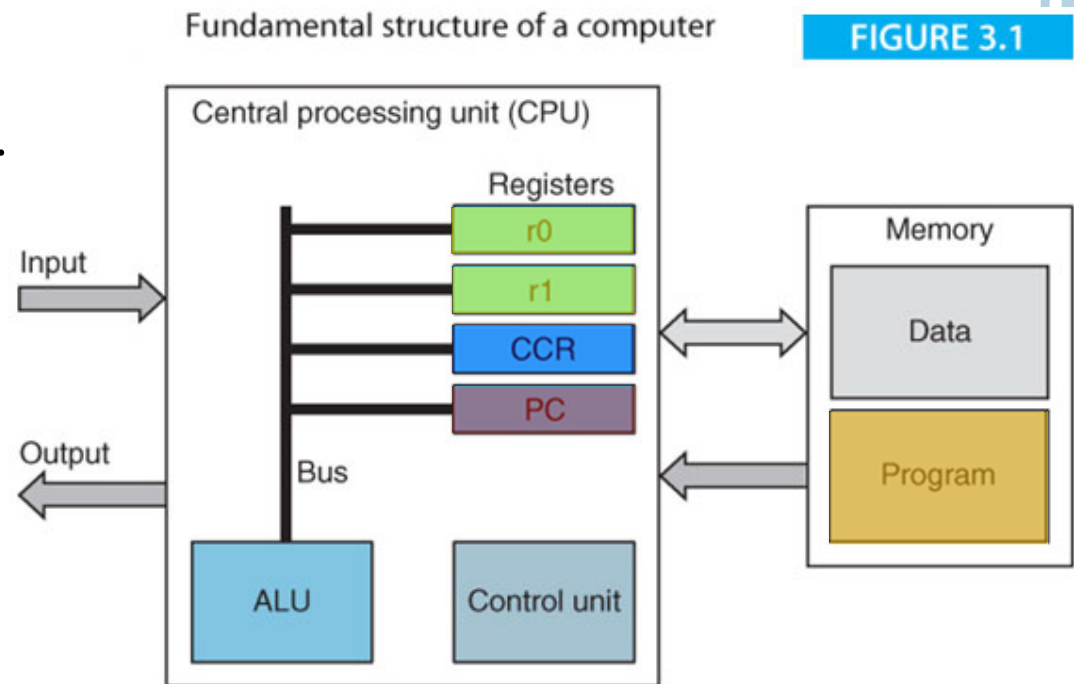
STR     r3, **2000**

ADD     **r1**, r2, r3

SUB     **r3**, r3, r1

# Features

- ❑ A stored program machine is a computer that has a program in binary form in its main memory.
- ❑ The program and data are stored in the same memory.
- ❑ The program counter (PC) points to the next instruction to be executed and is incremented after executing each instruction.
- ❑ A stored program operates in a *fetch/execute two-phase mode*.
  - In the *fetch phase* the next instruction is read from memory and decoded.
  - In the *execute phase* the instruction is interpreted and executed by the CPU's logic.
- ❑ Modern computers are *pipelined*, where *fetch* and *execute* operations *overlap*.



Review Slides 28 and 29 in Chapter 1.

## Features

A stored program computer has several registers.

**r0 - r<sub>i</sub>** The register file is a *set of general-purpose registers*, e.g., r0, r1, r2, ..., r<sub>i</sub> that store temporary (working) data, for example, the intermediate results of calculations, where *i* is typically 8, 16, or 32.

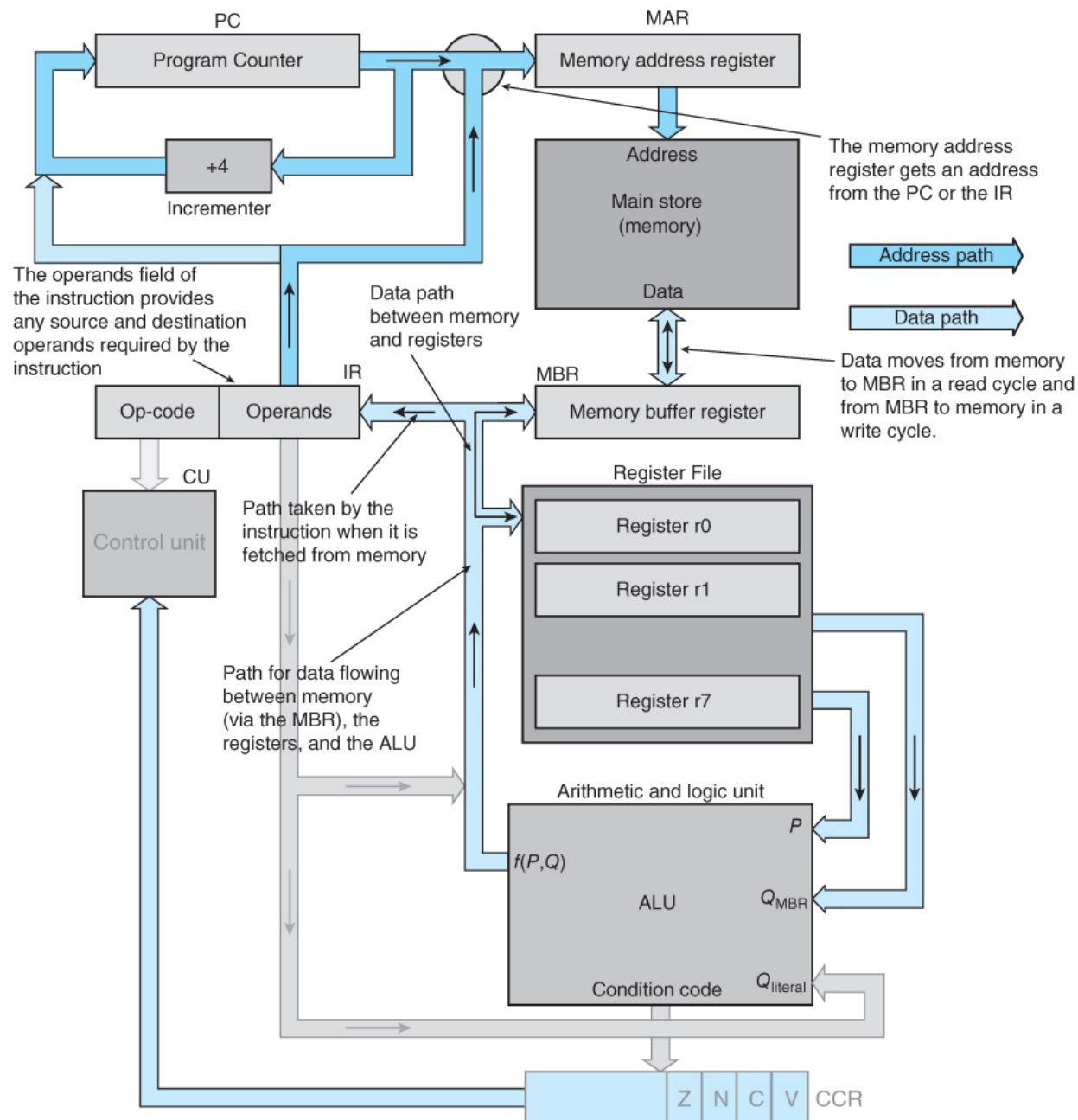
A computer requires at *least one* general-purpose register.

**PC** The *program counter* contains the *address* of the next instruction to be executed. Thus, the PC *points* to the location in memory that holds the next instruction.

**IR** The *instruction register* stores the instruction most recently read from main memory. This is the instruction currently being executed.

**MAR** The *memory address register* stores the *address* of the location in main memory that is currently being accessed by a *read* or *write* operation.

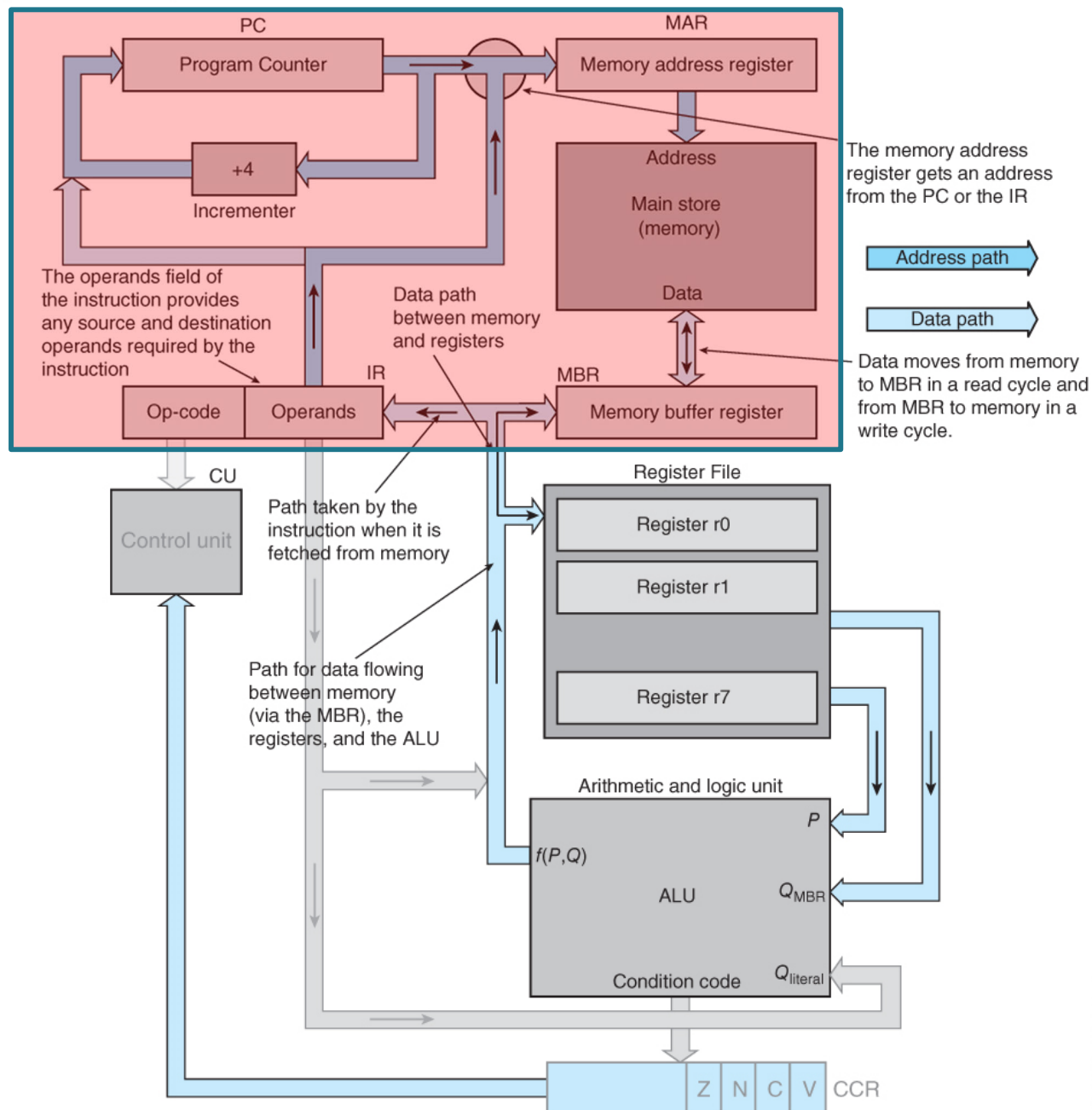
**MBR** The *memory buffer register* stores *data* that has just been *read* from main memory, or *data* to be immediately *written* to main memory.

**FIGURE 3.2** Partial structure of a hypothetical stored program machine

## Structure of a Computer

- We are going to use an ARM processor to introduce assembly language and a modern ISA.
- *However*, it would be better to begin with the description of a very simple hypothetical computer to keep things simple.

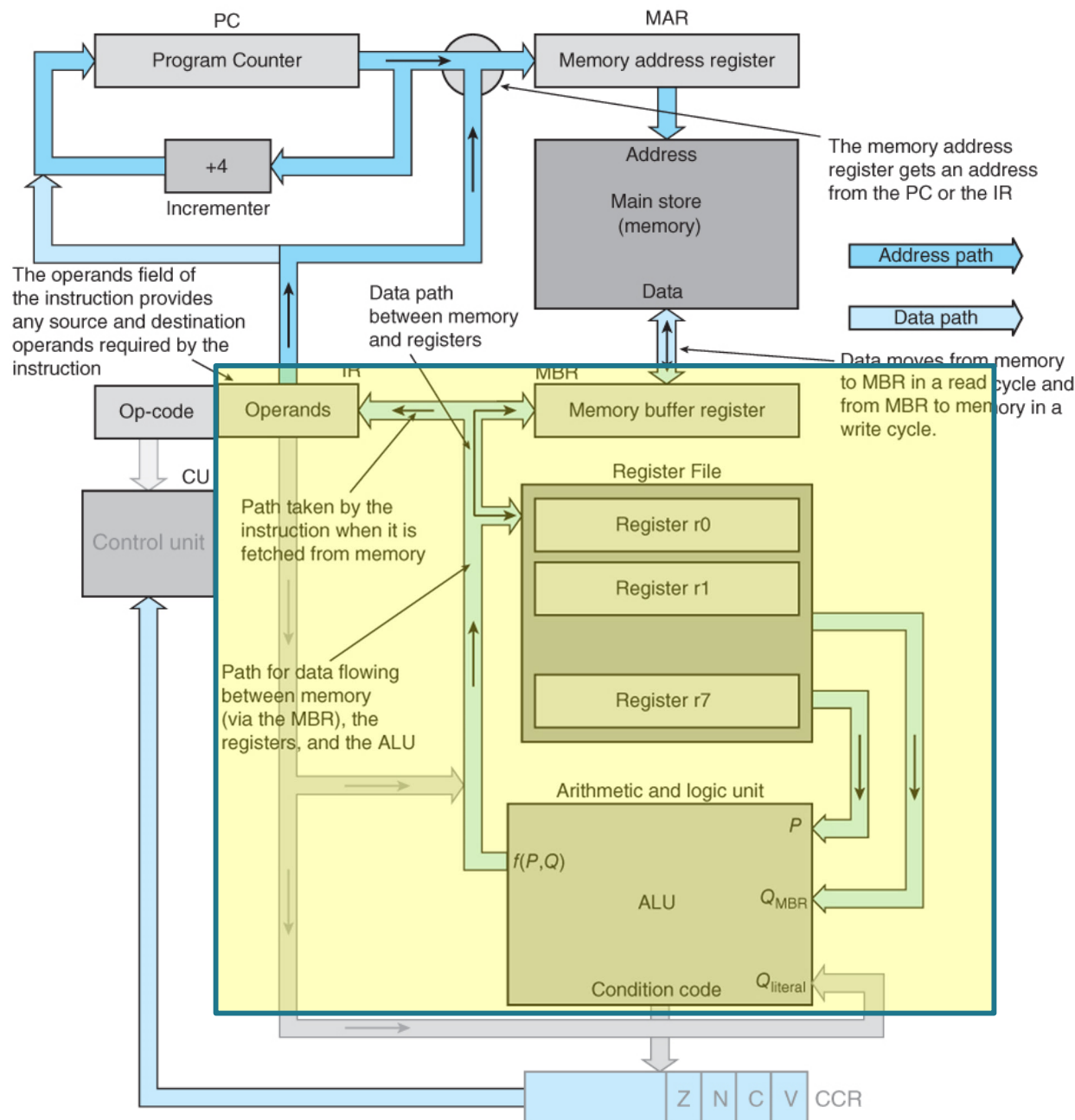


**FIGURE 3.2** Partial structure of a hypothetical stored program machine

## Structure of a Computer

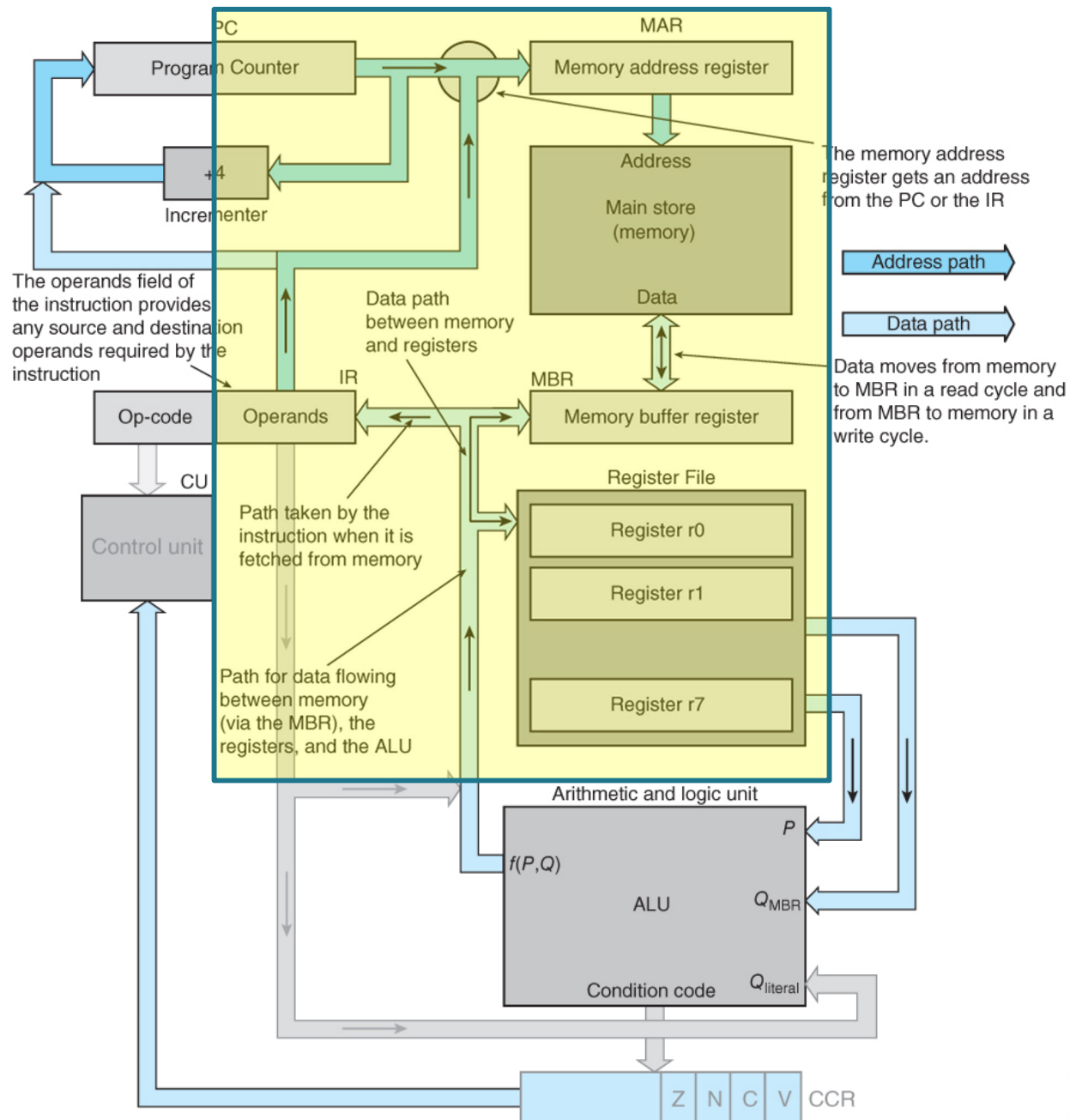
- ❑ In the *fetch phase*, the Program Counter, **PC**, supplies the address of the next instruction to be executed to the **MAR** to read this instruction and the PC is *incremented by the size of an instruction*.
- ❑ The instruction is read and loaded into the Memory Buffer Register, **MBR**, and then copied to the Instruction Register, **IR**, where the op-code is decoded.



**FIGURE 3.2** Partial structure of a hypothetical stored program machine

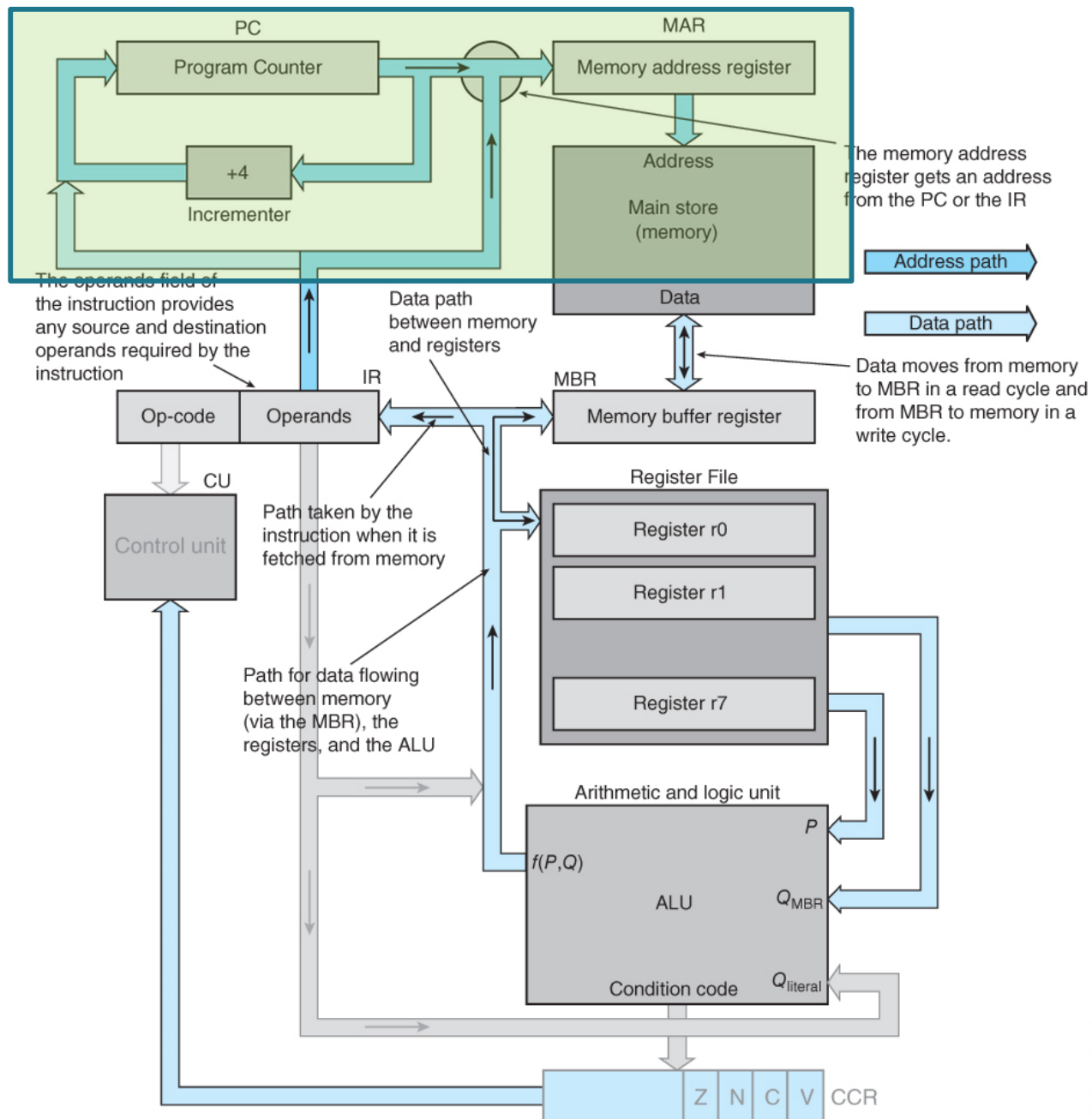
## Structure of a Computer

- In the *execute phase*, the operands may be read from the *register file*, transferred to the *ALU (arithmetic and logic unit)* where they are operated on and then the result passed to the *destination register*. This is what we call, *register-to-register* operation.

**FIGURE 3.2** Partial structure of a hypothetical stored program machine

## Structure of a Computer

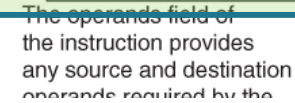
- If the operation requires a memory access (e.g., a load or store), the memory address in the instruction register is sent to the **MAR** and a read or write operation performed.

**FIGURE 3.2** Partial structure of a hypothetical stored program machine

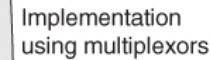
## Structure of a Computer

- But how can we combine two input data lines together?

FIGURE 3.2



- ❑ But how can we combine two input data lines together?



# Structure of a Computer

## □ Fetch/execute cycle in RTL .

Review Slide 26 in Chapter 1.

**FETCH**  $[MAR] \leftarrow [PC]$  ; Step 1: copy PC to MAR  
 $[PC] \leftarrow [PC] + 4$  ; Step 1: increment PC

$[MBR] \leftarrow [[MAR]]$  ; Step 2: read instruction pointed at by MAR  
 $[IR] \leftarrow [MBR]$  ; Step 3: copy instruction in MBR to IR

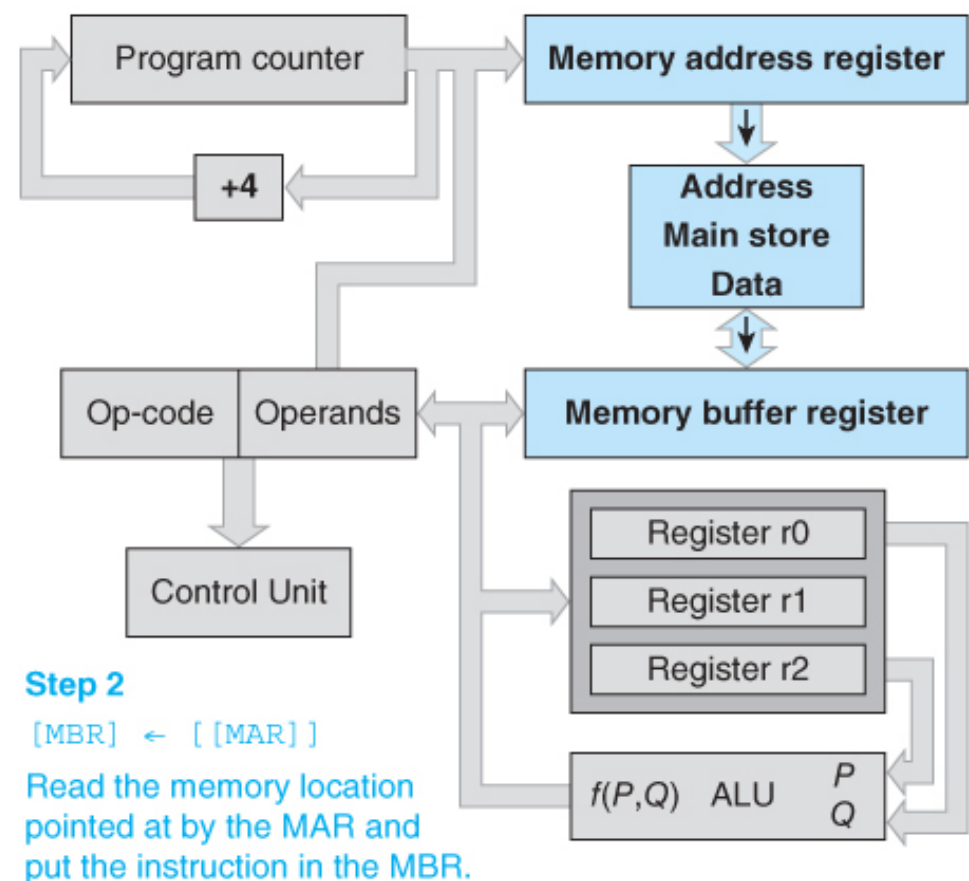
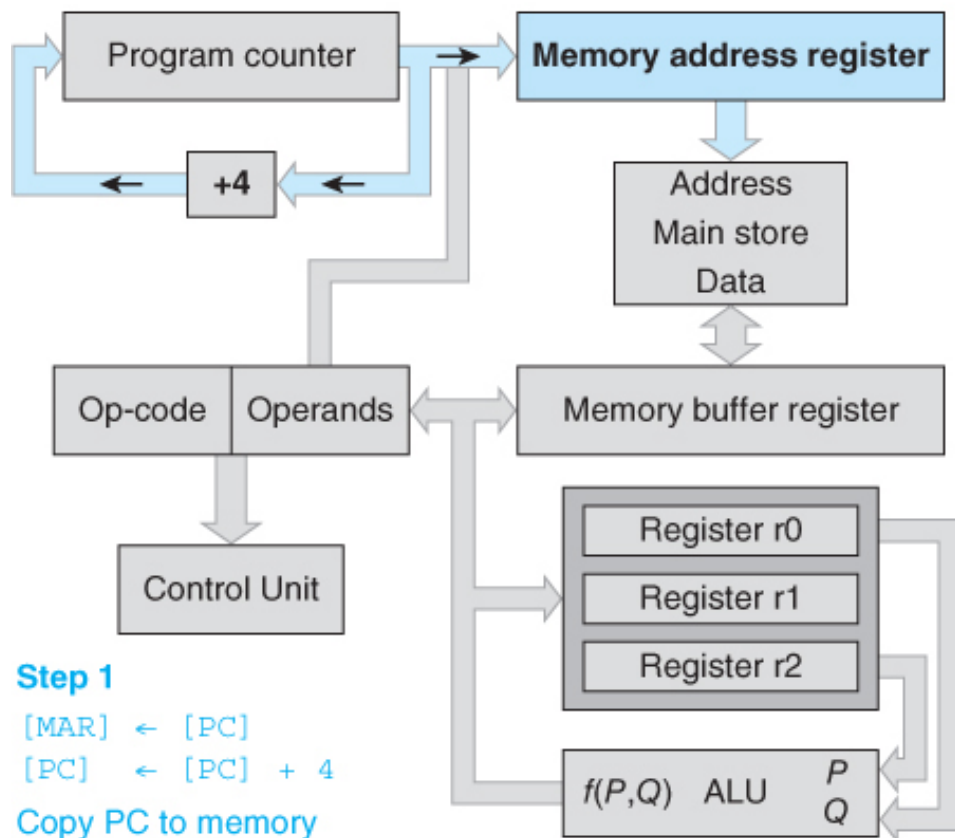
## EXECUTE

**LDR**  $[MAR] \leftarrow [IR(\text{address})]$  ; Step 4: copy operand address from IR to MAR  
 $[MBR] \leftarrow [[MAR]]$  ; Step 5: read operand value from memory  
 $[r1] \leftarrow [MBR]$  ; Step 6: copy the operand to a register, e.g., r1

Review Slides 28 and 29 in Chapter 1.

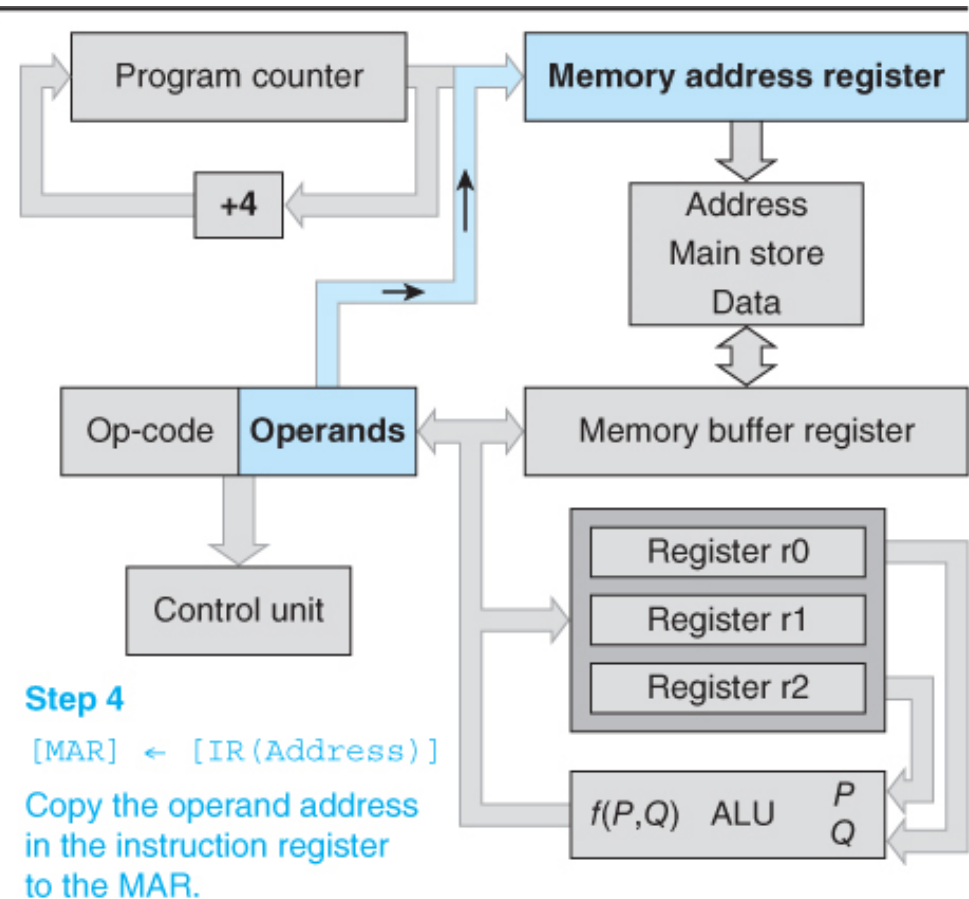
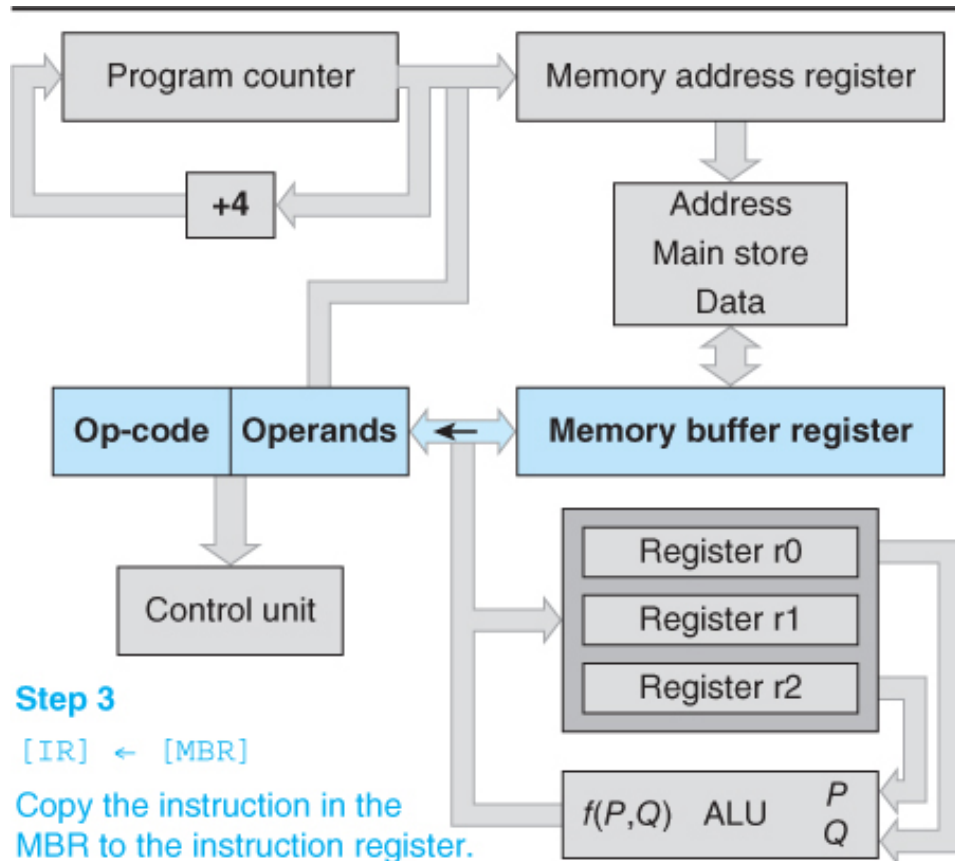
The coming 3 slides show the above steps graphically.

# Fetching and Executing an Instruction

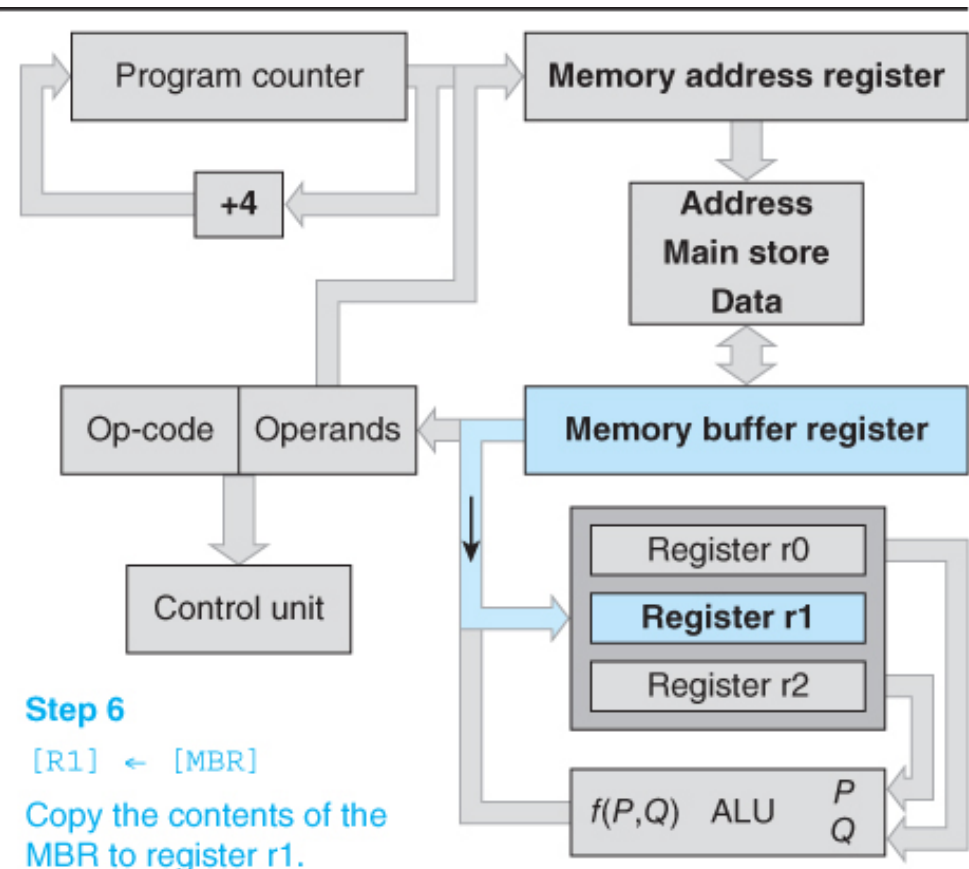
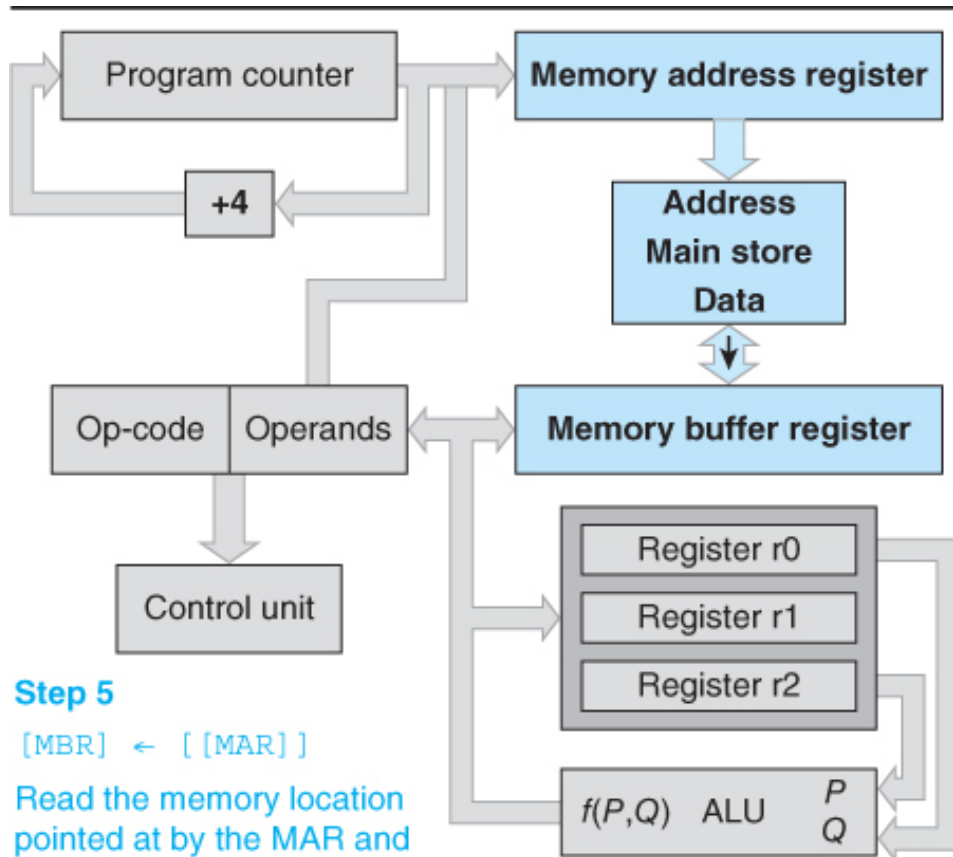




# Fetching and Executing an Instruction

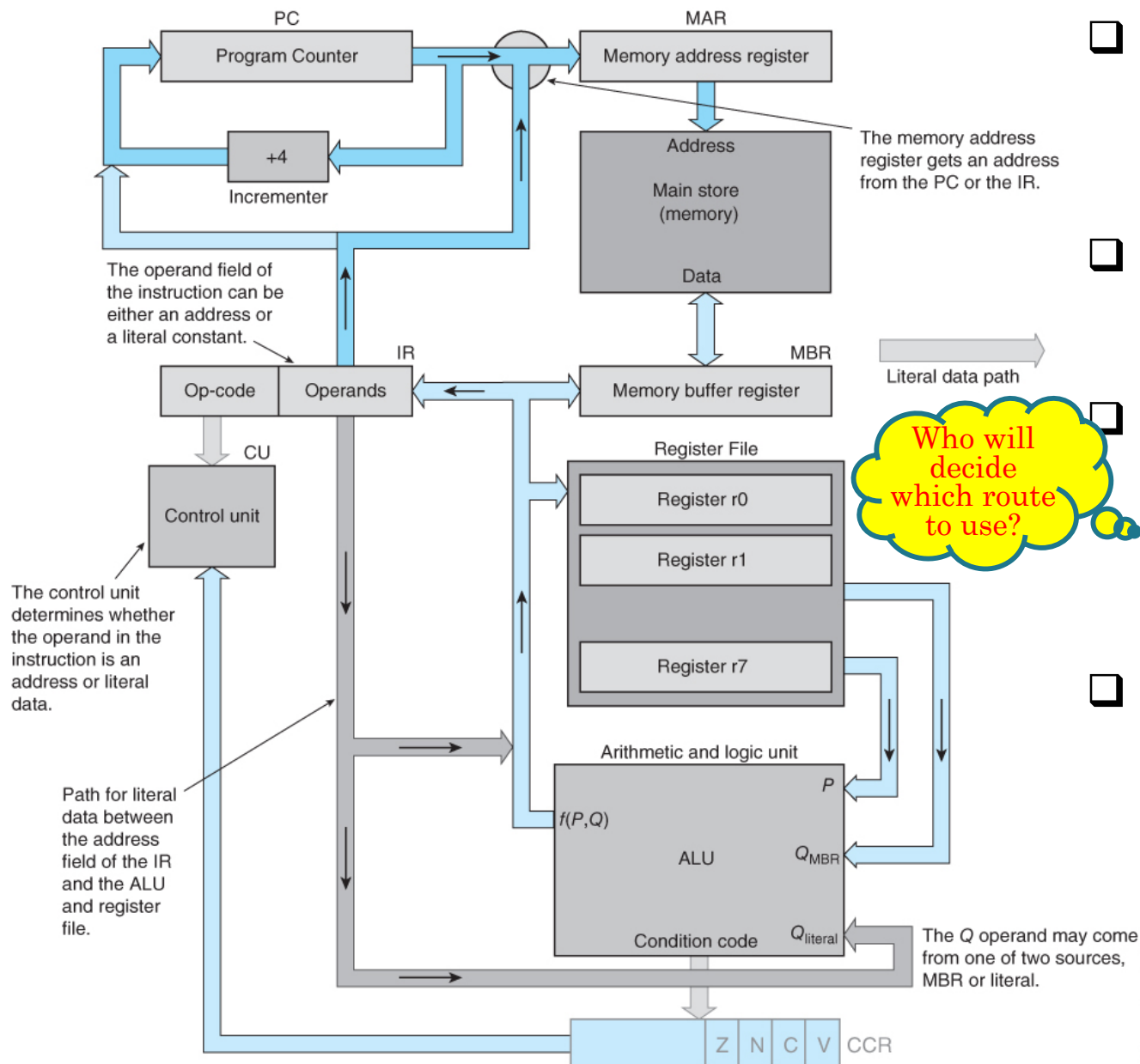


# Fetching and Executing an Instruction



## Dealing with Constants

FIGURE 3.4 Information paths for literal operands



- ❑ Suppose we want to **load the number 1234 itself (a.k.a. literal operand)** into register r1.
- ❑ **ADD r0,r1,#25** adds the value 25 to the content of r1 and puts the sum in r0
- ❑ A path from the instruction register, **IR**, routes a literal operand to **either the register file, MBR, and ALU**
- ❑ When **ADD r0,r1,#25** is executed, the operand to be added to r1, i.e., **#25**, is routed from the operand field of the **IR**, rather than from registers.

- ❑ *Flow control* refers to any action that *modifies* the normal instruction sequence.
- ❑ *Conditional behavior* allows a processor (*based on the values in the CCR register*) to select one of two possible courses of actions:
  - Continuing executing the *next instruction* in sequence, or
  - Loading the Program Counter with a new value and executing a *branch to another region* of code.

PC

Program Counter

Multiplexor

Incrementer +4

Sequential address path

MAR

Memory address register

Address

Main store (memory)

Data

MBR

Memory buffer register

IR

Op-code

Operands

CU

Control unit

Register File

Register r0

Register r1

Register r7

Arithmetic and logic unit

$f(P, Q)$

ALU

Condition code

$Q_{MBR}$

$Q_{literal}$

CCR

Z

N

C

V

Branch control selects next sequential address from incrementer or address from IR.

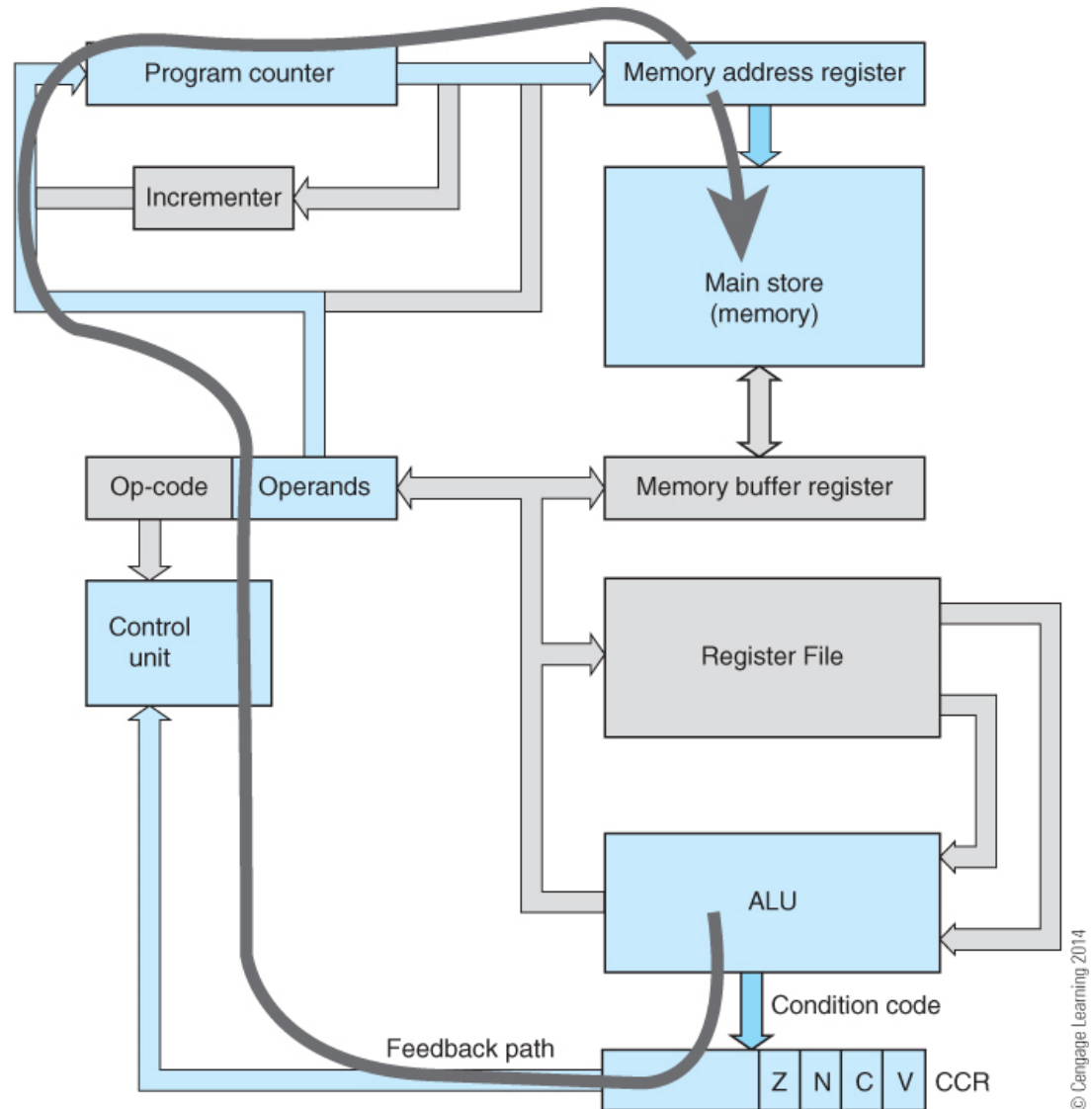
The operand field of the instruction can be either an address or a literal (constant).

The control unit uses the condition code bits either to select the next instruction in sequence or to load the program counter with a new address.

# Flow Control

**FIGURE 3.6** Feedback from ALU to instruction


Figure 3.6 illustrate how the result from the ALU can be used to modify the sequence of instructions.



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## Status Bits (Flags)

- ❑ When a computer performs an operation, it stores the *status* or *condition* information in the *Condition Code Register (CCR)*.
- ❑ The processor records whether the result is
  - **Zero (Z)**,
  - **Negative in two's complement terms (N)**,
  - **generated a Carry (C)**, or • • •
  - **generated an arithmetic oVerflow (V)**.



This is the  
carry-out



## Status Bits (Flags)

- Example (*assume that we are dealing with an 8-bit processor*):

00110011	11111111	01011100	11011100
+01000010	+00000001	+01000001	+11000001
<u>01110101</u>	<u>10000000</u>	<u>10011101</u>	<u>11001101</u>
Z = 0, N = 0	Z = 1, N = 0	Z = 0, N = 1	Z = 0, N = 1
C = 0, V = 0	C = 1, V = 0	C = 0, V = 1	C = 1, V = 0
51	-1	92	-36
+66	+1	+65	-63
---	---	---	---
117	0	-99	-99

**CISC means COMPLEX Instruction Set Computer**

- **CISC** processors, like the *Intel IA32*,
- automatically update status flags after each operation.

**RISC means REDUCED Instruction Set Computer**

- **RISC** processors, like the *ARM*,
- require the programmer to request updating the status flags.
- In *ARM* processors, *programmers need to request updating the status flags by appending an S to the instruction*;
- for example, SUBS (instead of SUB) or ADDS (instead of ADD).