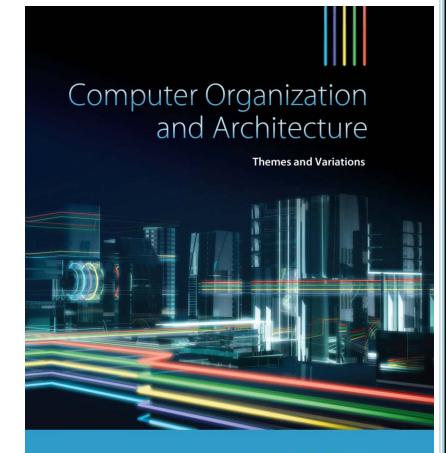
Part OxA

CHAPTER 3

Architecture and Organization



Alan Clements

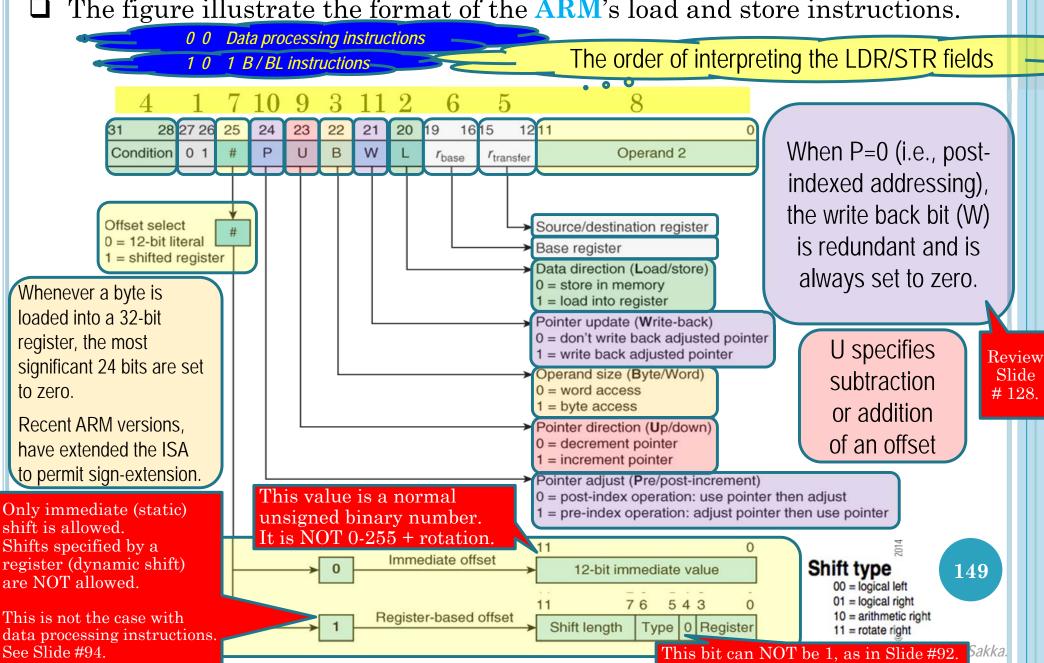
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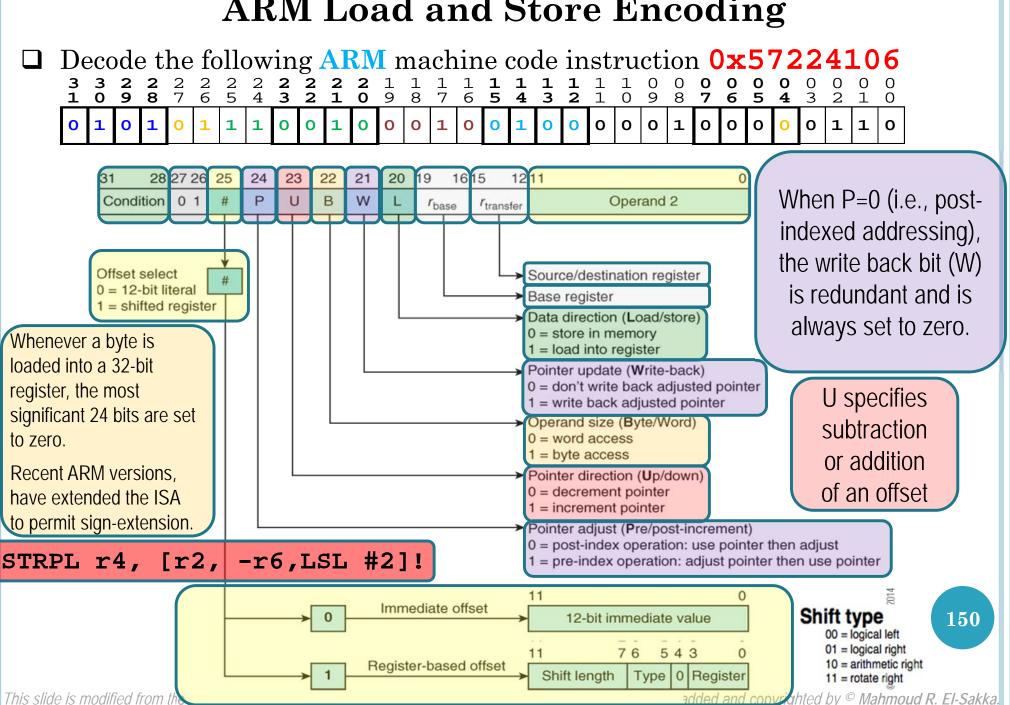
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The figure illustrate the format of the ARM's load and store instructions.

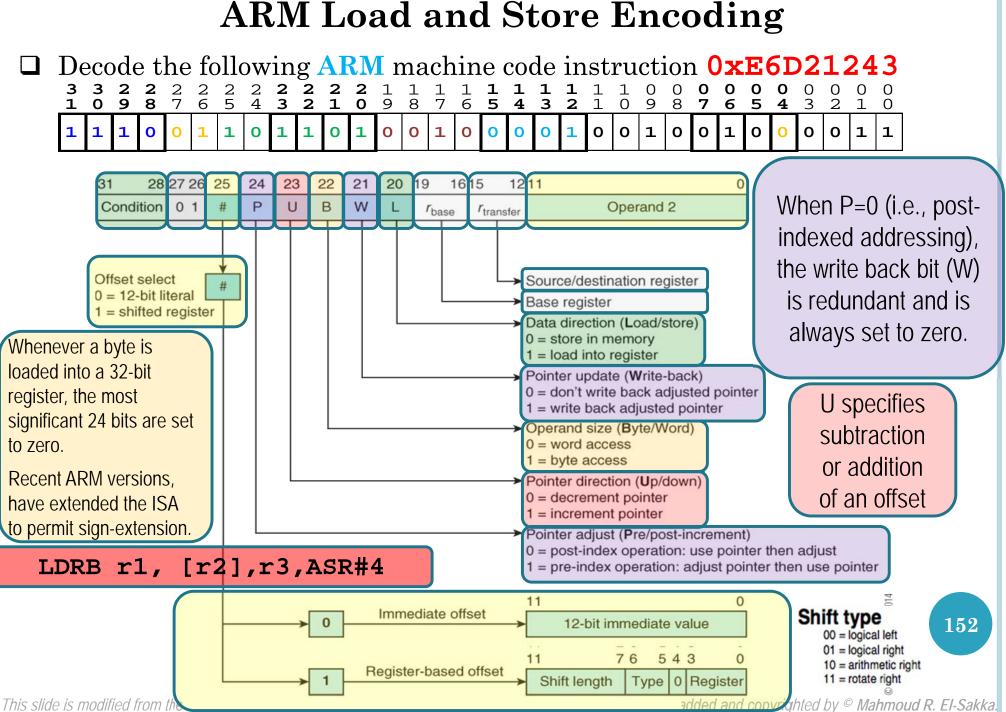




Decoding the ARM Instruction STRPL r4,[r2,-r6,LSL#2]!

Field Name	Value	Action	Interpretation
Condition	0101	PL	Execute on positive
OP-code	01		Defines load/store instruction
#	1	Operand 2 format	Operand is a shifted register
Р	1	Pre/post adjust	Adjust pointer before using
U	0	Pointer direction	Decrement pointer
В	0	Byte/word	This is a word access
W	1	Pointer write back	Update pointer after use
L	0	Load/store	Store data in memory
r _{base}	0010	Base register	r2 is the base (pointer) register
r _{transfer}	0100	Source/destination	r4 is the source in this store instruction
Shift length	00010	Shift length	Shift the register 2 places
Shift type	00	Logical shift left	Logical shift left the offset in r6
Op-code	0		
Shift register	0110	Specified register to be shifted	r6 is shifted twice

Operand 2

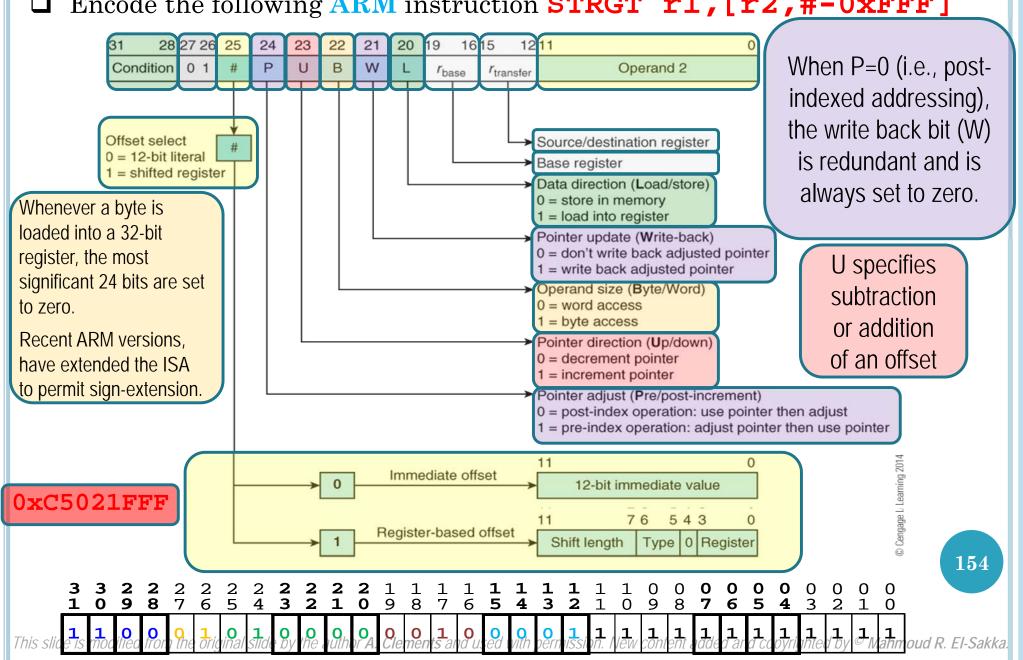


Decoding the ARM InstructionLDR r1, [r2],r3,ASR#4

Field Name	Value	Action	Interpretation	
Condition	1110	AL	Always (default)	
OP-code	01		Defines load/store instruction	
#	1	Operand 2 format	Operand is a shifted register	
Р	0	Pre/post adjust	Adjust pointer after using	
U	1	Pointer direction	Increment pointer	
В	0	Byte/word	This is a word access	
W	0	Pointer write back	As P=0, W is redundant and always=0	
L	1	Load/store	Load data from memory	
r _{base}	0010	Base register	r2 is the base (pointer)register	
r _{transfer}	0001	Source/destination	r1 is the destination in this loadinstruction	
Shift length	00100	Shift length	Shift the register 4 places	
Shift type	10	Arithmetic shift right	Arithmetic shift right the offset in r3	
Op-code	0			
Shift register	0011	Specified register to be shifted	r3 is shifted four times	

Operand 2

Encode the following ARM instruction STRGT r1, [r2, #-0xFFF]



Decoding the ARM Instruction **STRGT r1,[r2,#-0xFFF]**

Field Name	Value	Action	Interpretation
Condition	1100	GT	Execute on greater than
OP-code	01		Defines load/store instruction
#	0	Operand 2 format	Operand is immediate
Р	1	Pre/post adjust	Adjust pointer before using
U	0	Pointer direction	Decrement pointer
В	0	Byte/word	This is a word access
W	0	Pointer write back	Update pointer before use
L	0	Load/store	Store data in memory
r _{base}	0010	Base register	r2 is the base (pointer) register
r _{transfer}	0001	Source/destination	r1 is the source in this store instruction
Immediate offset	111111111111	Shift length	Offset value = 0xFFF

Decoding the ARM Instruction LDREQ r3,[r6],#-0xFFF

Field Name	Value	Action	Interpretation
Condition	0000	EQ	Execute on equal
OP-code	01		Defines load/store instruction
#	0	Operand 2 format	Operand is immediate
Р	0	Pre/post adjust	Adjust pointer after using
U	0	Pointer direction	Decrement pointer
В	0	Byte/word	This is a word access
W	0	Pointer write back	Update pointer before use
L	1	Load/store	Load data from memory
r _{base}	0110	Base register	r6 is the base (pointer) register
r _{transfer}	0011	Source/destination	r3 is the destination in this load instruction
Immediate	111111111111	Shift length	Offset value = 0xFFF
offset			

□ Encode the following ARM instructions.

LDR R1,[R2]

LDR R1,[R2],#0

LDR R1,[R2,#0]

LDR R1,[R2,#0]!

STR R1,[R2]

STR R1,[R2],#0

STR R1,[R2],#0

STR R1,[R2,#0]!

- ☐ Is there any *effective* difference between the 4 LDR instructions?
- ☐ Is there any *effective* difference between the 4 LDR instructions?

```
AREA various STR and LDR instructions, code, READONLY
     ENTRY
     ADR r2, X
     LDR R1, [R2]
     LDR R1, [R2], #0
     LDR R1, [R2, #0]
     LDR R1, [R2, #0]!
     ADR r2, Y
     STR R1, [R2]
     STR R1, [R2], #0
     STR R1, [R2, #0]
     STR R1,[R2,#0]!
loop B loop
X
     DCD 0 \times 12345678
     DCD 0x87654321
Y
     END
```

