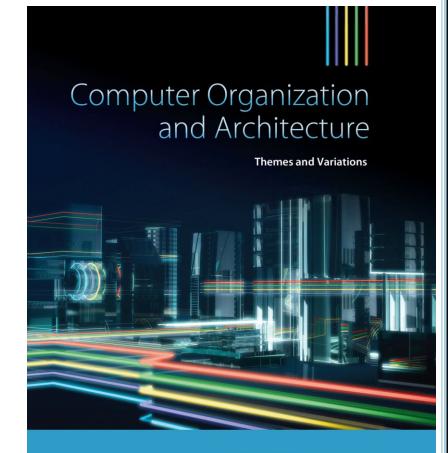
Part 1

CHAPTER 3

Architecture and Organization



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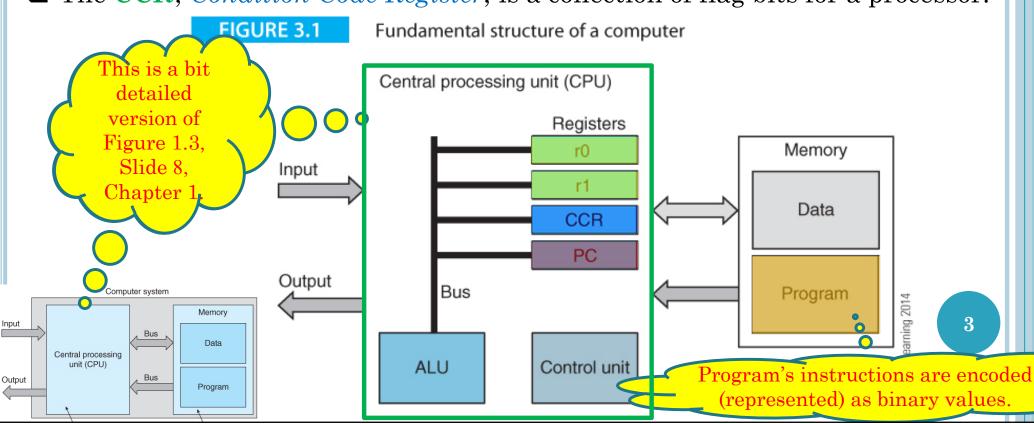
The Instruction Set Architecture

In this chapter, we will:

- □ Revisit the *stored program machine* and **show** how an instruction is executed
- ☐ Introduce instruction formats, including
 - o memory-to-register,
 - o register-to-memory, and
 - o register-to-register
- ☐ Demonstrate how a processor implements *conditional behavior*
- ☐ **Describe** a set of computer assembly instructions (*instructions set*)
- □ Show how computers access data (addressing modes)
- ☐ Introduce an ARM's Integrated Development Environment (IDE) and
 - **show** how ARM programs are written

The Instruction Set Architecture

- ☐ Figure 3.1 illustrate the structure of a **simple** *hypothetical stored program computer*.
- ☐ The *CPU reads* instructions from memory and *executes* them.
- \square *Temporary data* is stored in *registers* such as r0 and r1.
- ☐ The **PC**, program counter, is the register that points at (i.e., contains the address of) the next instruction to be executed.
- ☐ The *CCR*, *Condition Code Register*, is a collection of flag bits for a processor.



Instruction Formats

- ☐ A computer executes instructions from 8-bits wide to multi-bytes wide.
- ☐ The instruction format defines the <u>anatomy</u> of an instruction
 - o the number of operands, and
 - the number of bits devoted to defining each operation,
 - o the format of each operand.
- \square Below are several <u>hypothetical</u> examples of assembly instructions:

LDR registerDestination, memorySource

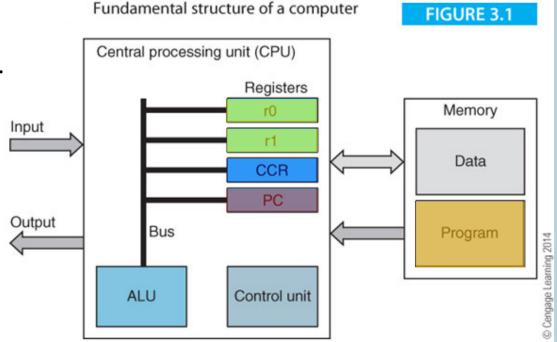
STR registerSource, memoryDestination

Operation registerDestination,registerSource1,registerSource2

```
LDR r1, 1234
```

Features

- ☐ A stored program machine is a computer that has a program in binary form in its main memory.
- ☐ The program and data are stored in the same memory.
- ☐ The program counter (PC)
 points to the next instruction
 to be executed and is incremented
 after executing each instruction.



- ☐ A stored program operates in a *fetch*/execute two-phase mode.
 - o In the *fetch phase* the next instruction is read from memory and decoded.
 - o In the *execute phase* the instruction is interpreted and executed by the CPU's logic.

Review Slides 24 and 25 in Chapter 1.

□ Modern computers are *pipelined*, where fetch and execute operations *overlap*.

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Features

A stored program computer has several registers.

- r0 ri The register file is a set of general-purpose registers, e.g., r0, r1, r2, ..., ri that store temporary (working) data, for example, the intermediate results of calculations, where i is typically 8, 16, or 32.
- PC The *program counter* contains the *address* of the next instruction to be executed. Thus, the PC *points* to the location in memory that holds the next instruction.
- The *instruction register* stores the instruction most recently read from main memory. This is the instruction currently being executed.
- MAR The *memory address register* stores the *address* of the location in main memory that is currently being accessed by a read or write operation.
- MBR The *memory buffer register* stores data that has just been read from main memory, or data to be immediately *written* to main memory.

FIGURE 3.2 Partial structure of a hypothetical stored program machine Program Counter Memory address register The memory address Address register gets an address from the PC or the IR Main store Incrementer (memory) Address path The operands field of Data path Data the instruction provides between memory Data path any source and destination and registers operands required by the Data moves from memory instruction MBR to MBR in a read cycle and from MBR to memory in a Op-code Operands Memory buffer register write cycle. Register File CU Path taken by the Register r0 instruction when it is fetched from memory Register r1 Path for data flowing between memory Register r7 (via the MBR), the registers, and the ALU Arithmetic and logic unit f(P,Q) Q_{MBR} ALU Q_{literal} Condition code ZN С V

Structure of a Computer

- We are going to use an ARM processor to introduce assembly language and a modern ISA.
- ☐ However, it would be better to begin with the description of a very simple <u>hypothetical</u> computer to keep things simple.

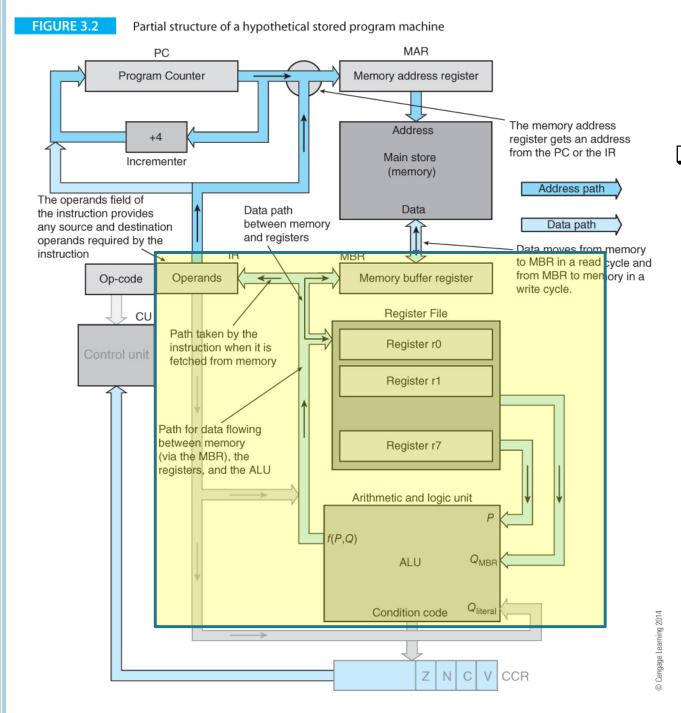
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FIGURE 3.2 Partial structure of a hypothetical stored program machine PC Program Counter Memory address register The memory address Address register gets an address from the PC or the IR Main store Incrementer (memory) Address path The operands field of Data path the instruction provides between memory Data path any source and destination and registers operands required by the Data moves from memory instruction **MBR** to MBR in a read cycle and from MBR to memory in a Op-code Operands Memory buffer register write cycle. Register File CU Path taken by the Register r0 instruction when it is fetched from memory Register r1 Path for data flowing between memory Register r7 (via the MBR), the registers, and the ALU Arithmetic and logic unit f(P,Q) $Q_{\rm MBR}$ ALU Q_{literal} Condition code ZNC V

Structure of a Computer

- □ In the *fetch phase*,
 the Program Counter,
 PC, supplies the
 address of the next
 instruction to be
 executed to the MAR to
 read this instruction
 and the PC is
 incremented by the size
 of an instruction.
- ☐ The instruction is read and loaded into the Memory Buffer Register, MBR, <u>and</u> then copied to the Instruction Register, 8 IR, where the

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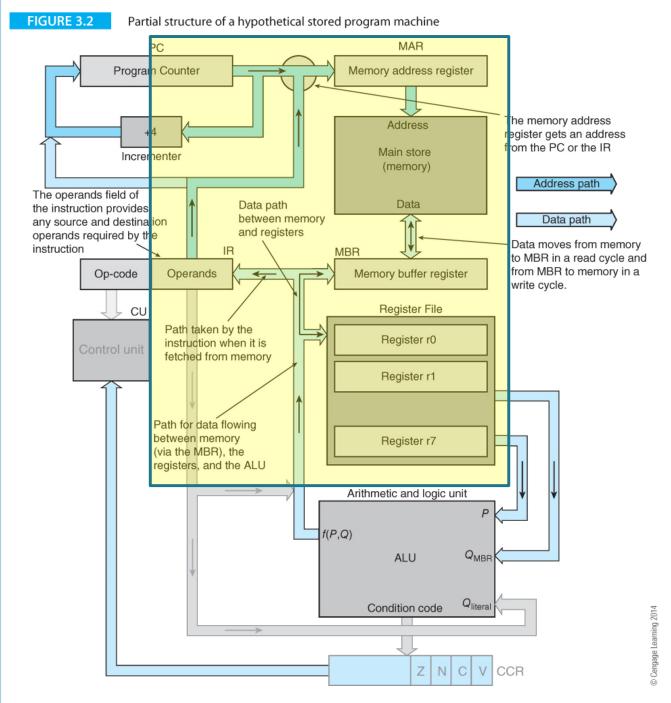
☐ In the *execute phase*, the operands may be read from the *register file*, transferred to the ALU (*arithmetic and logic unit*) where they are operated on and then the result passed to the *destination register*.

This is what we call,

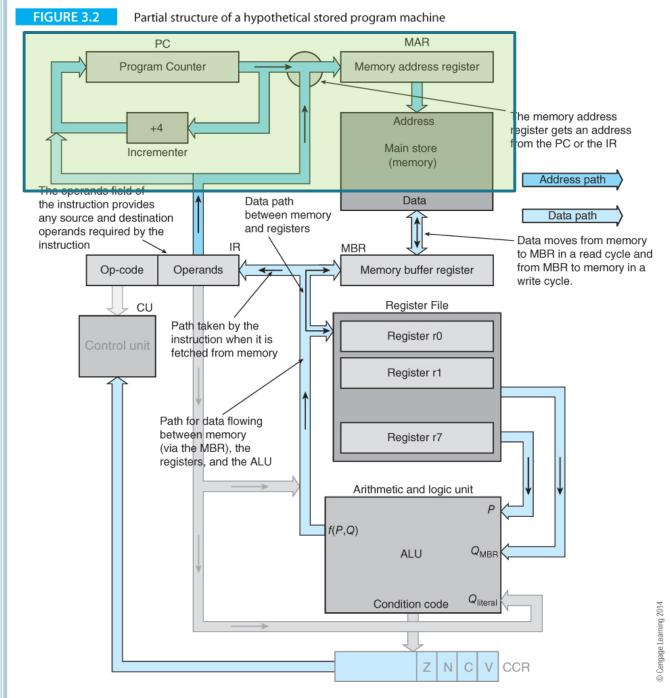
register-to-register

operation.

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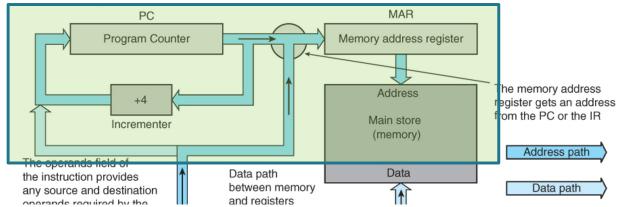


☐ If the operation requires a memory access (e.g., a load or store), the memory address in the instruction register is sent to the MAR and a read or write operation performed.



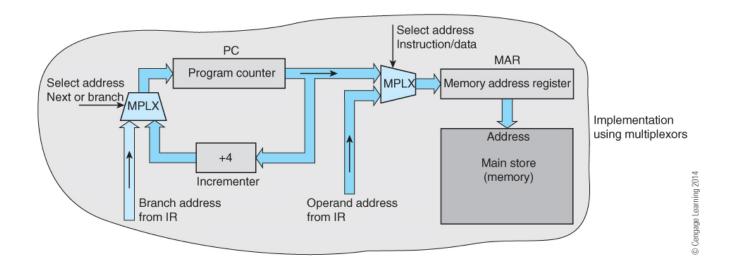
☐ But how can we combine two input data lines together?

FIGURE 3.2 Partial structure of a hypothetical stored program machine



Structure of a Computer

☐ But how can we combine two input data lines together?



□ Fetch/execute cycle in RTL.

Review Slide 28 in Chapter 1.

```
FETCH [MAR] \leftarrow [PC] ; Step 1: copy PC to MAR [PC] \leftarrow [PC] + 4 ; Step 1: increment PC
```

```
[MBR] ← [[MAR]]; Step 2: read instruction pointed at by MAR
```

[IR] \leftarrow [MBR] ; Step 3: copy instruction in MBR to IR

```
EXECUTE
```

```
LDR [MAR] \leftarrow [IR(address)]
```

; Step 4: copy operand address from IR to MAR

 $[MBR] \leftarrow [[MAR]]$; Step 5: read operand value from memory

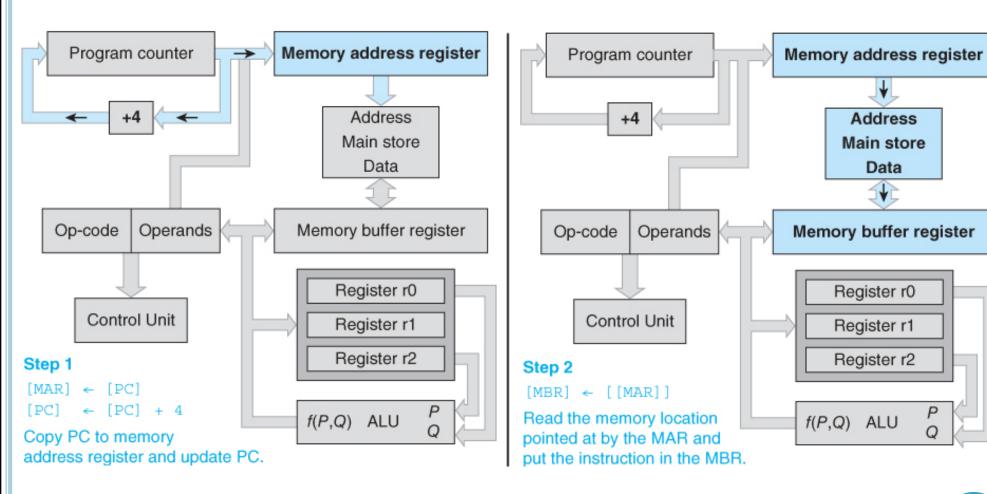
 $[r1] \leftarrow [MBR]$; Step 6: copy the operand to a register, e.g., r1

Review Slides 24 and 25 in Chapter 1.

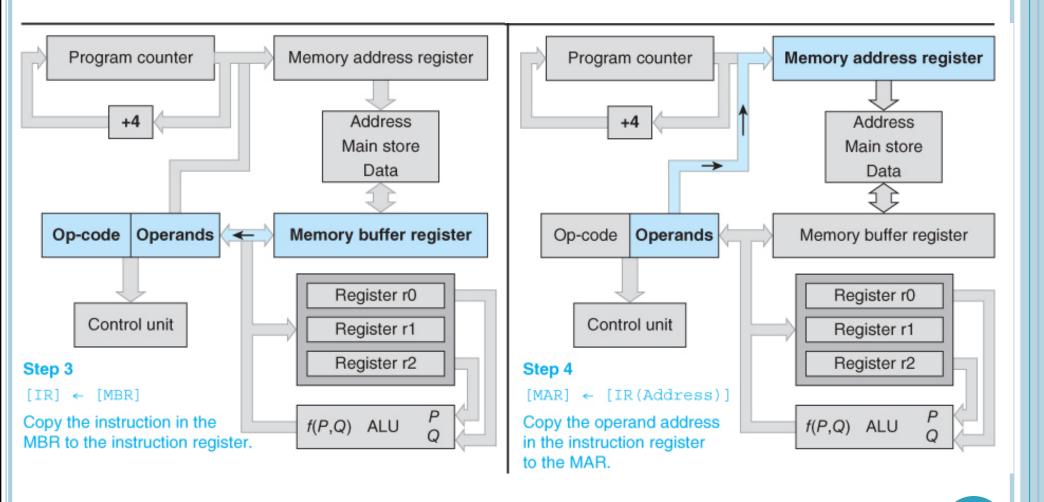
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The coming 3 slides show the above steps graphically.

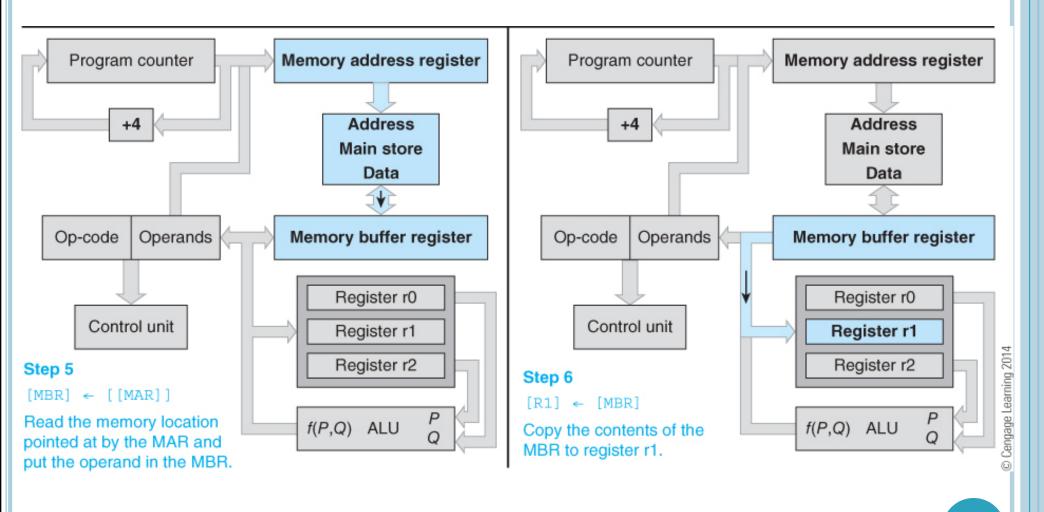
Fetching and Executing an Instruction



Fetching and Executing an Instruction



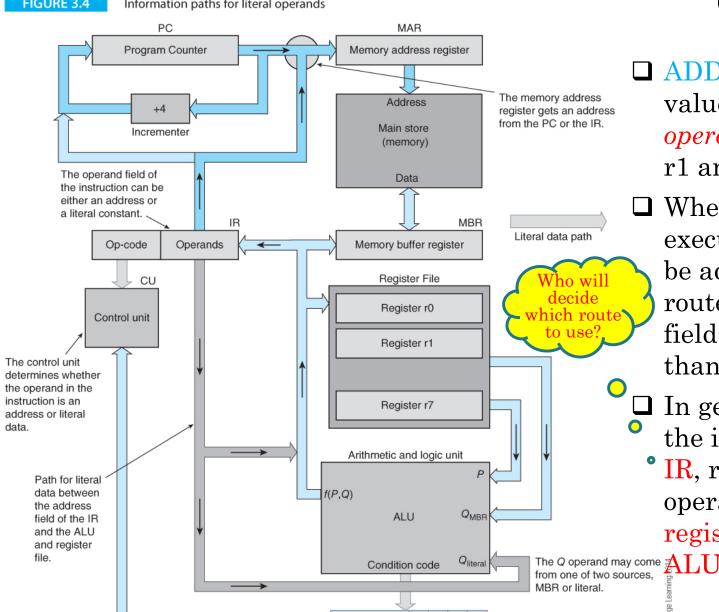
Fetching and Executing an Instruction



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Dealing with Constants

- ADD r0,r1,#25 adds the value 25 (a.k.a. literal operand) to the content of r1 and puts the sum in r0
 - When ADD r0,r1,#25 is executed, the operand to be added to r1, i.e., #25, is routed from the operand field of the IR, rather than from registers.
 - ☐ In general, the path from the instruction register,
 ÎR, routes a literal operand to *either* the register file, MBR, and



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FIGURE 3.5 Implementing conditional behavior at the machine level PC MAR Memory address register **Program Counter** Sequential Multiplexor address Incrementer path Address Main store (memory) Data Memory buffer register Op-code Operands Register File CU The operand field of the instruction Register r0 can be either an Control unit address or a literal (constant). Register r1 Branch control selects next sequential address from incrementer or Register r7 address from IR. Arithmetic and logic unit f(P,Q) Q_{MBR} ALU Condition code $Q_{literal}$ ZNC CCR The control unit uses the condition code bits either to select the next instruction in sequence or to load the program counter with a new address.

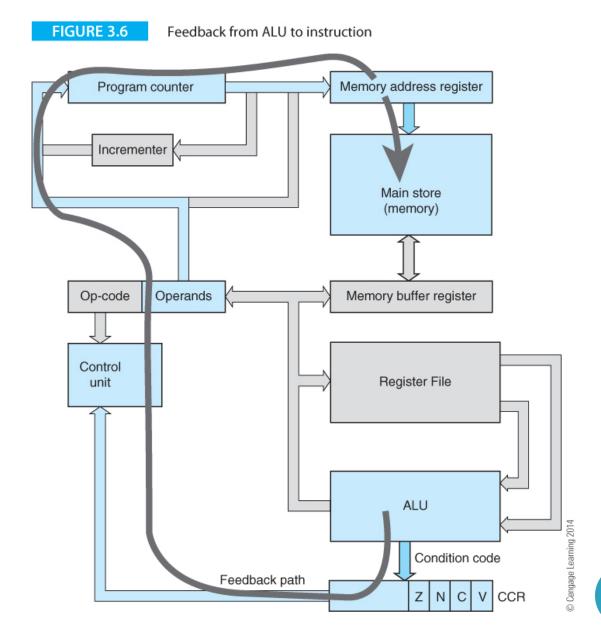
Flow Control

- □ *Flow control* refers to any action that *modifies* the normal instruction sequence.
- □ Conditional behavior
 allows a processor (based on the values in the CCR register) to select one of two possible courses of actions:
 - Continuing executing the *next instruction* in sequence, or
 - Counter with a new value and executing a *branch to another region* of code.

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Flow Control

Figure 3.6 illustrate how the result from the ALU can be used to modify the sequence of instructions.



Status Bits (Flags)

- □ When a computer performs an operation, it stores the *status* or *condition* information in the *Condition Code Register* (*CCR*).
- ☐ The processor records whether the result is
 - o Zero (Z),
 - Negative in two's complement terms (N),
 - o generated a Carry (C), or •
 - o generated an arithmetic oVerflow (V).

This is the carry-out

Status Bits (Flags)

□ Example (assume that we are dealing with an 8-bit processor):

00110011	11111111	01011100	11011100
+01000010	+00000001	+01000001	+11000001
$\overline{\texttt{01110101}}$	10000000	10011101	$1\overline{10011101}$
z=0, N=0	z = 1, $N = 0$	Z = 0, N = 1	z=0, N=1
C = 0, V = 0	C=1, $V=0$	C=0, V=1	C = 1, V = 0
51	-1	92	-36
+66	+1	+65	-63

CISC means COMPLEX Instruction Set Computer

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- □ CISC processors, like the *Intel IA32*,
 - o automatically update status flags after each operation.

RISC means REDUCED Instruction Set Computer

 \square RISC processors, like the *ARM*,

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- o require the programmer to request updating the status flags.
- ☐ In ARM processors, programmers need to request updating the status flags by appending an S to the instruction;
 - ☐ for example, SUBS (instead of SUB) or ADDS (instead of ADD).

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