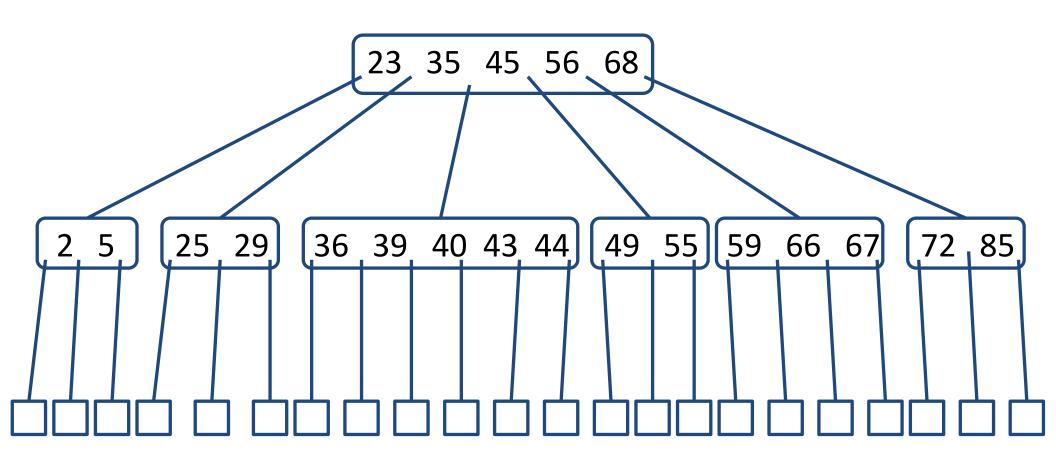
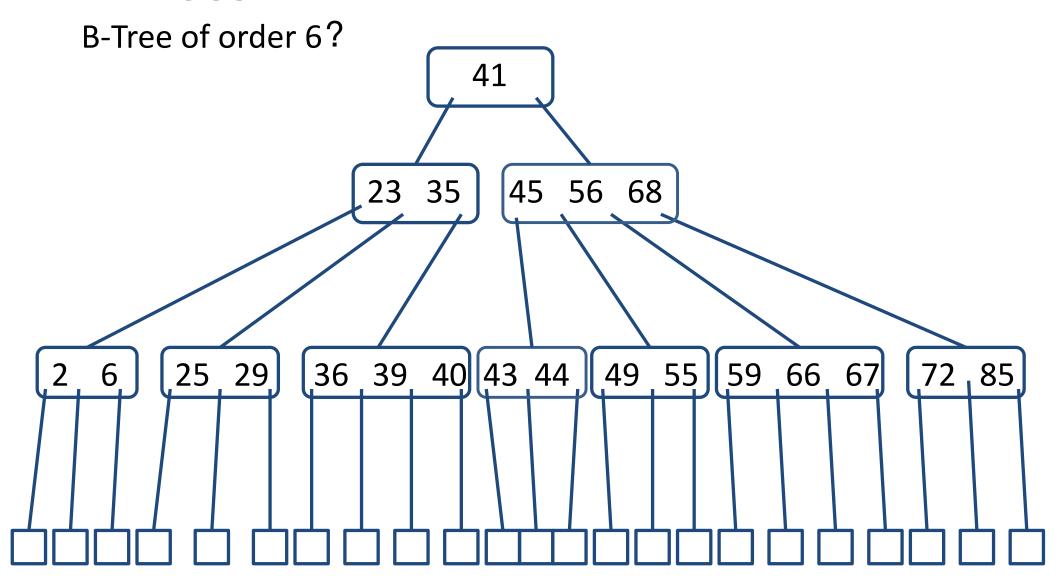
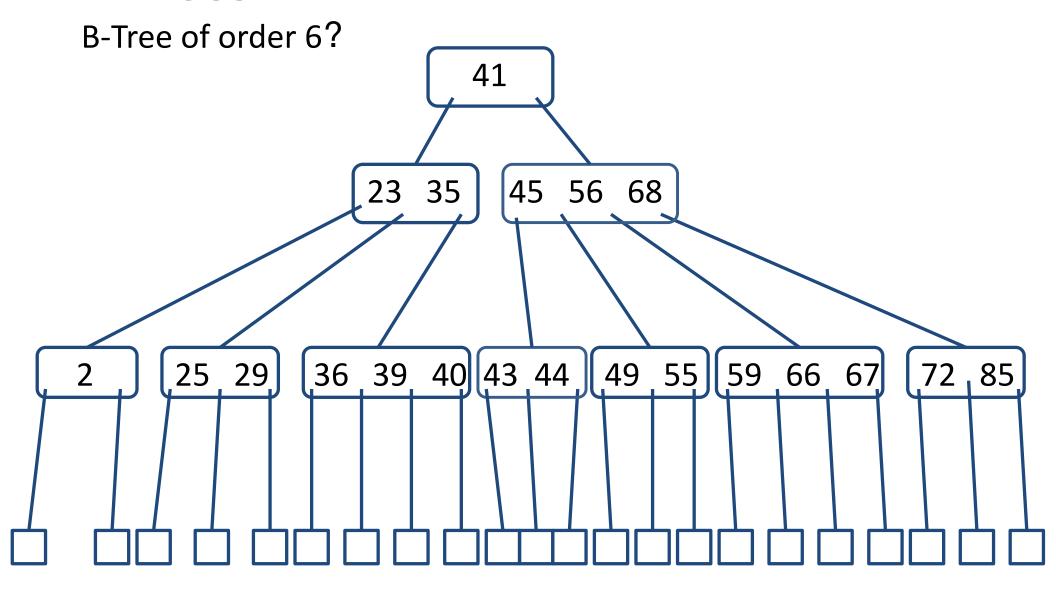
A B-tree of order *d* is a multiway search tree with the following properties:

- The root has at least 2 children and at most d.
- All internal nodes other than the root have at least $\left| \frac{a}{2} \right|$ and at most d children
- All the leaves are at the same level

B-Tree of order 6?



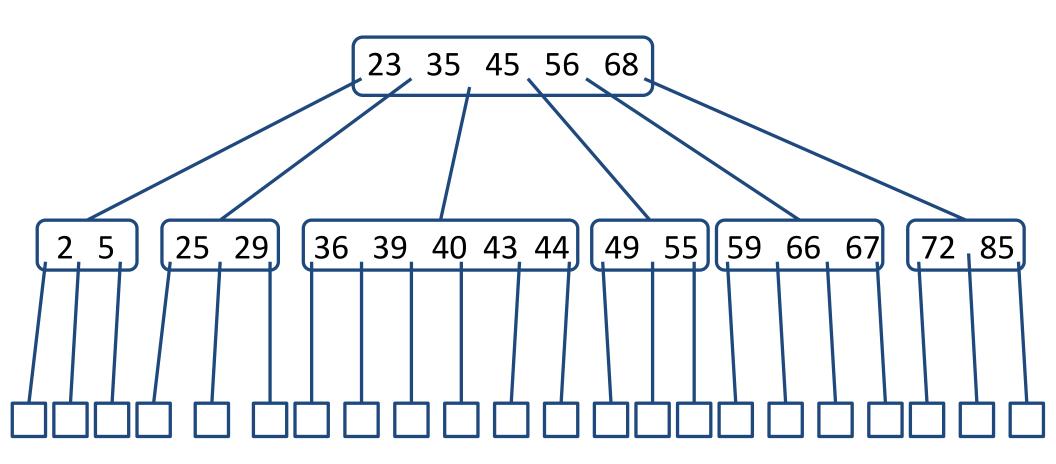




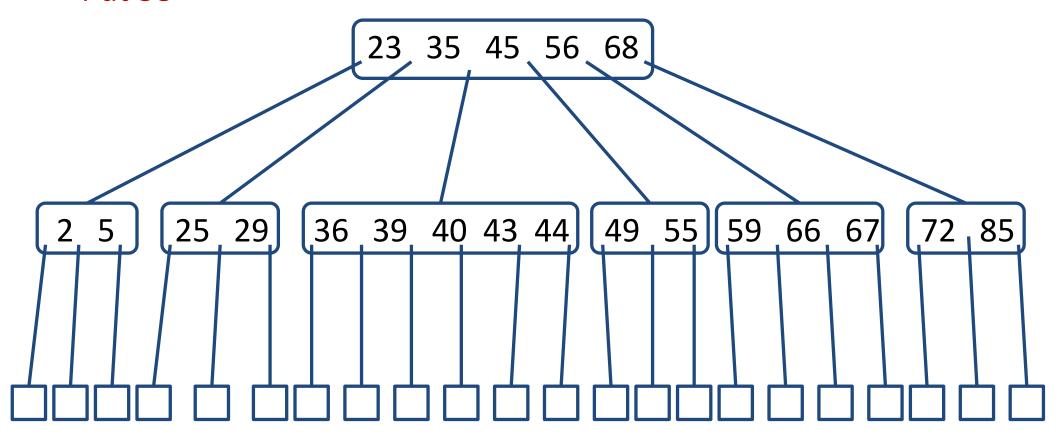
What is the Maximum Height of a B-Tree?

Height is O(log_d n)

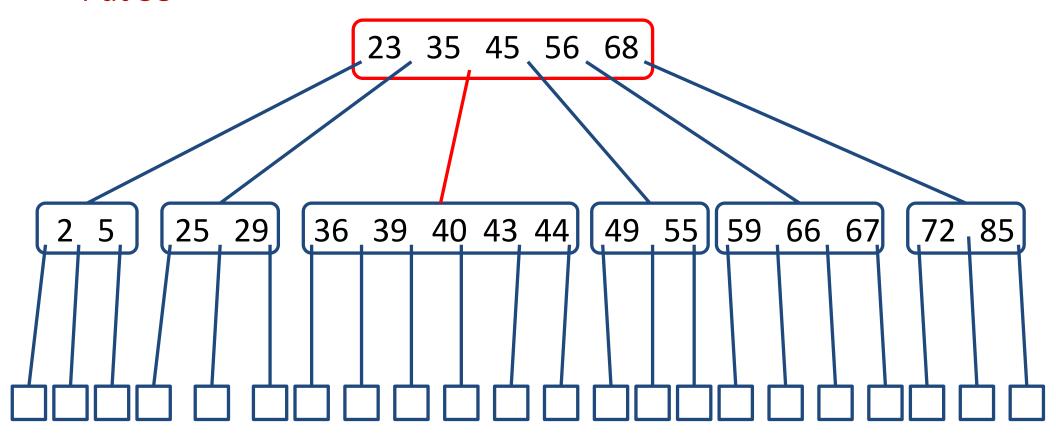
B-Tree of order 6



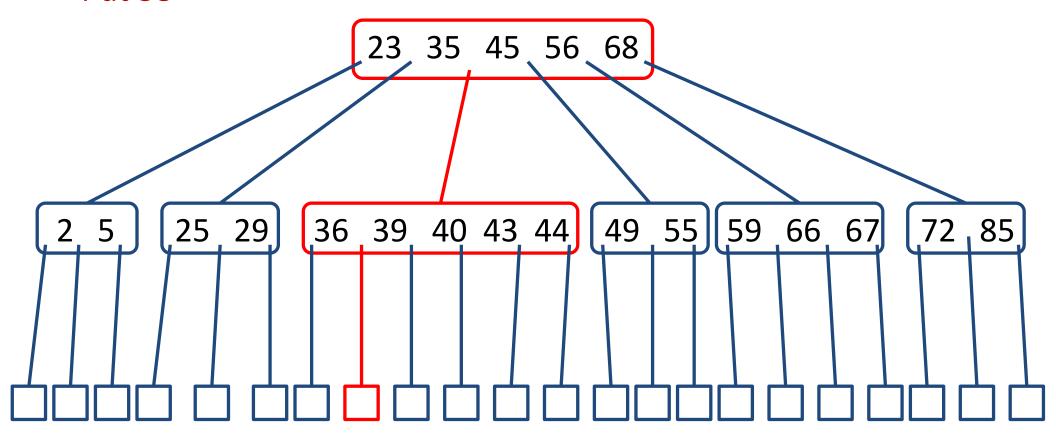
B-Tree of order 6



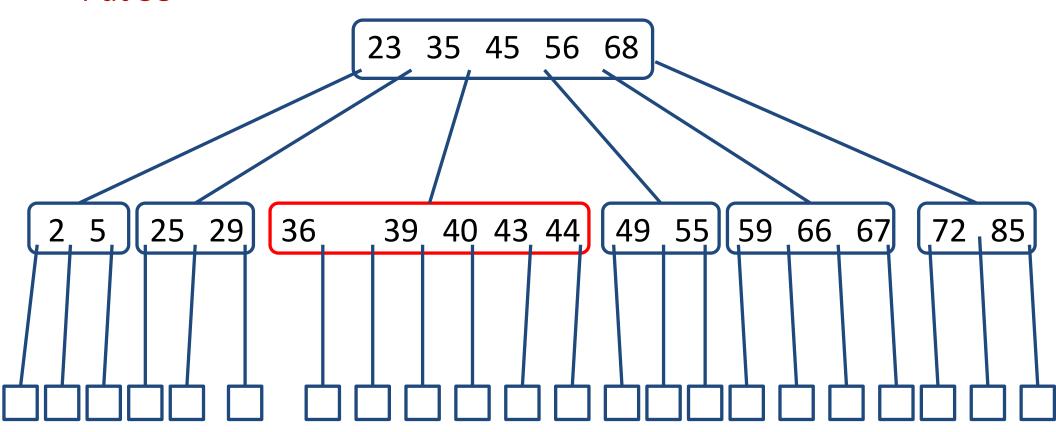
B-Tree of order 6



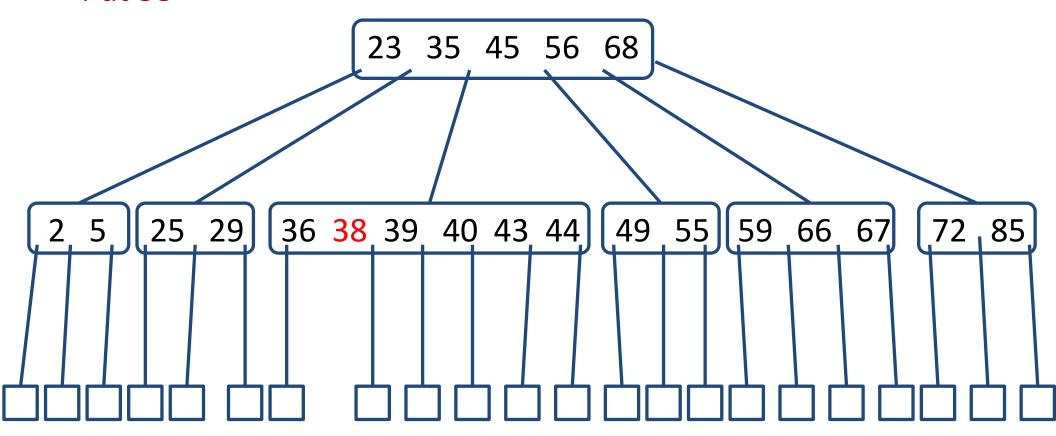
B-Tree of order 6



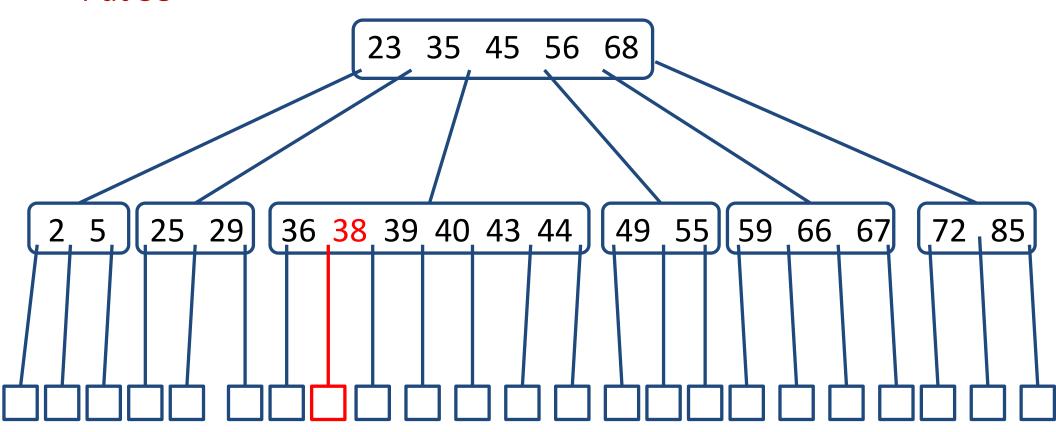
B-Tree of order 6



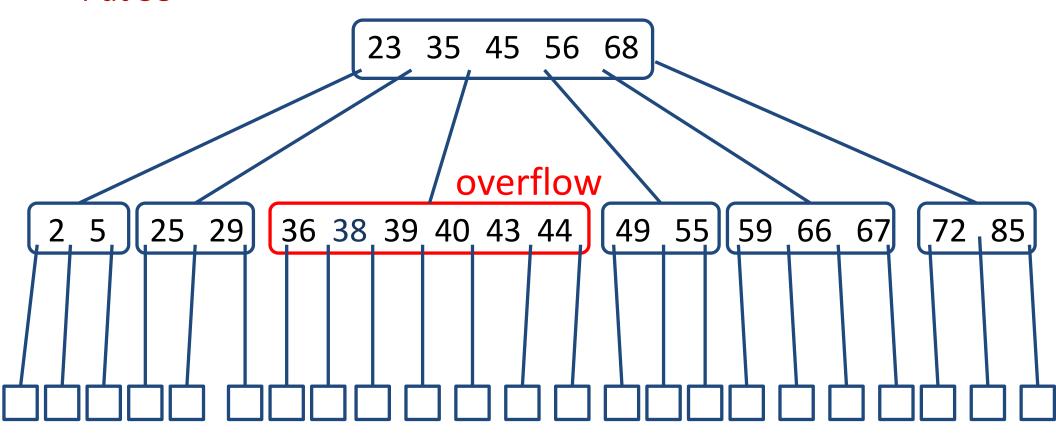
B-Tree of order 6



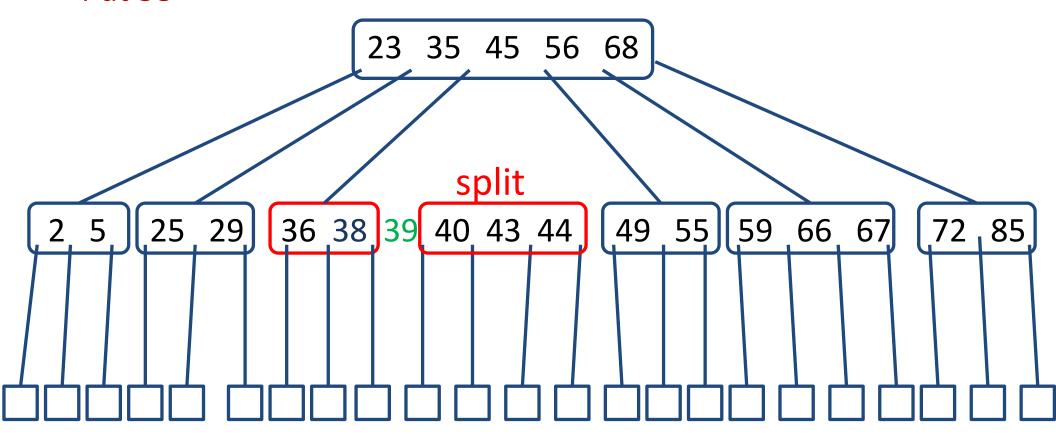
B-Tree of order 6



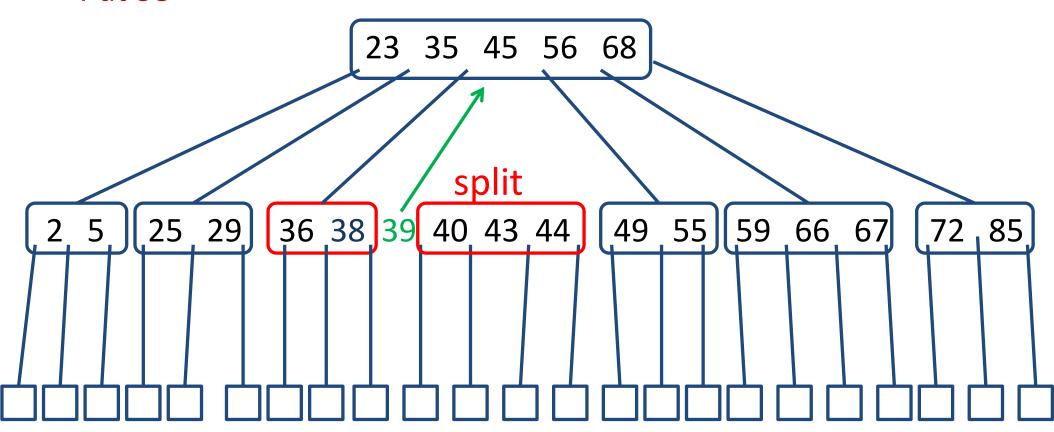
B-Tree of order 6



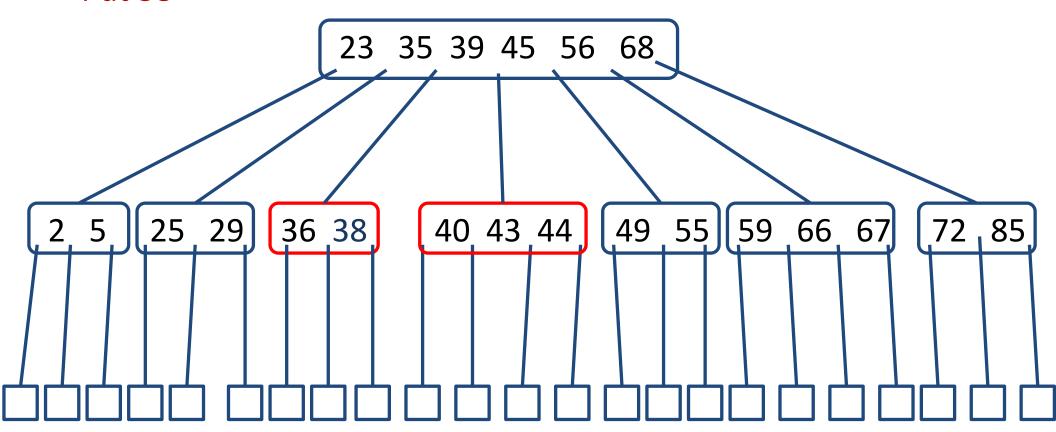
B-Tree of order 6



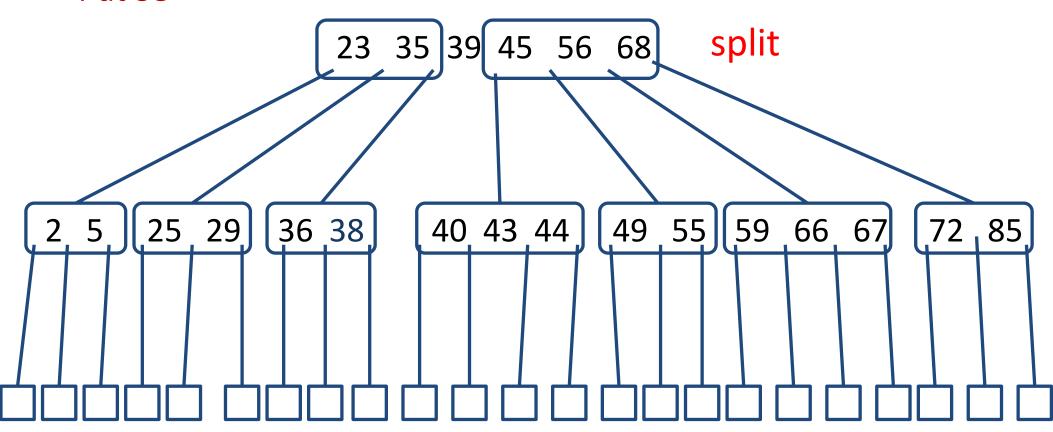
B-Tree of order 6

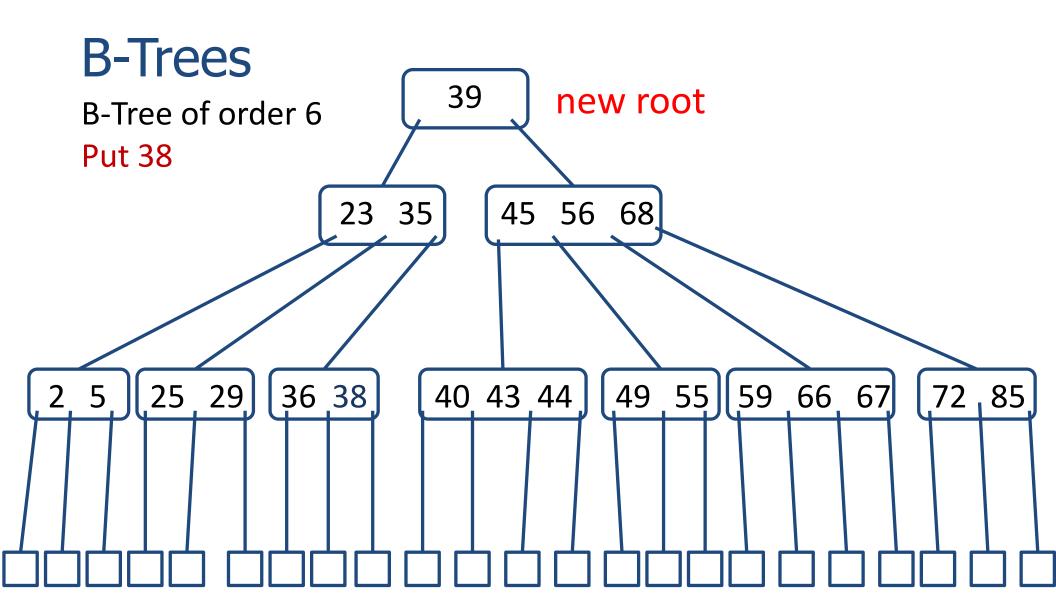


B-Tree of order 6



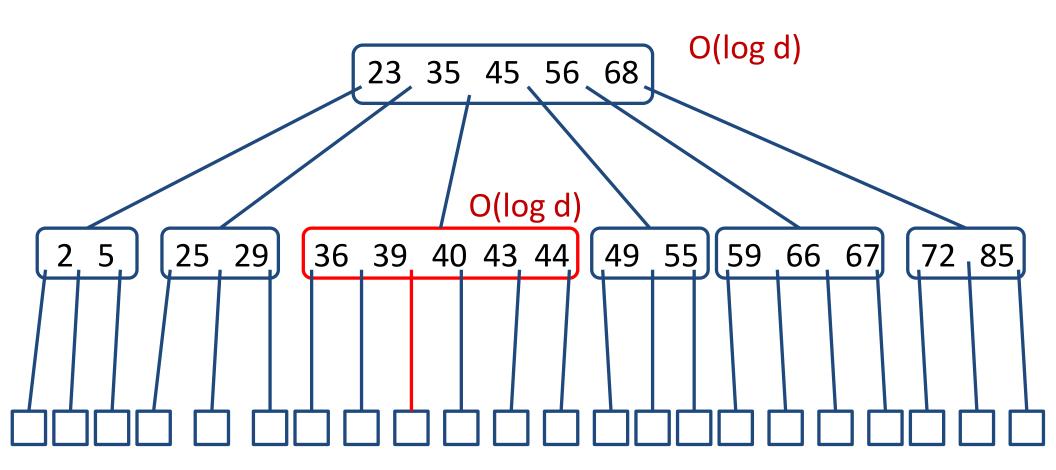
B-Tree of order 6





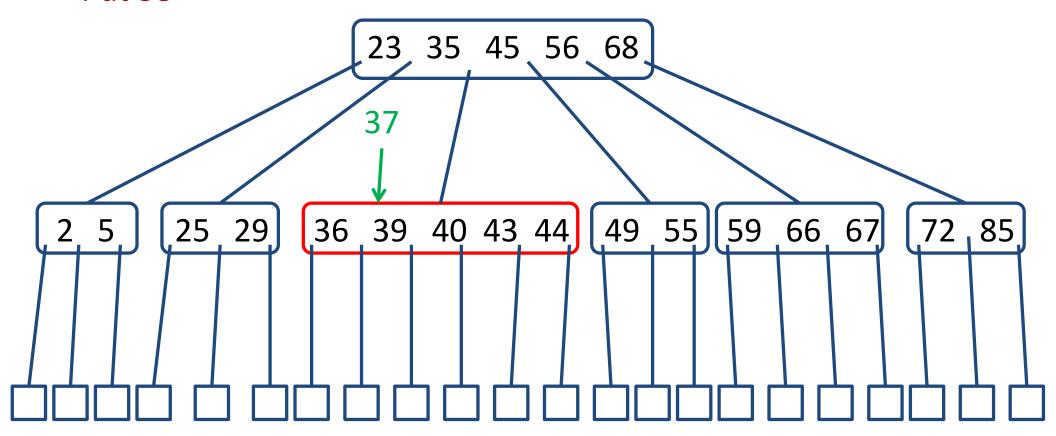
```
Algorithm put (r,k,o)
In: Root r of a B-tree, data item (k,o)
Out: {Insert data item (k,o) in the B-tree
    Search for k to find the lowest insertion internal node v \vdash
   Add the new data item (k, o) at node v
   while node v overflows do {
      if v is the root then
            Create a new empty root and set as parent of v
      Split v around the middle key k', move k' to parent, and
      update parent's children
      v \leftarrow \text{parent of } v
```

B-Tree of order 6

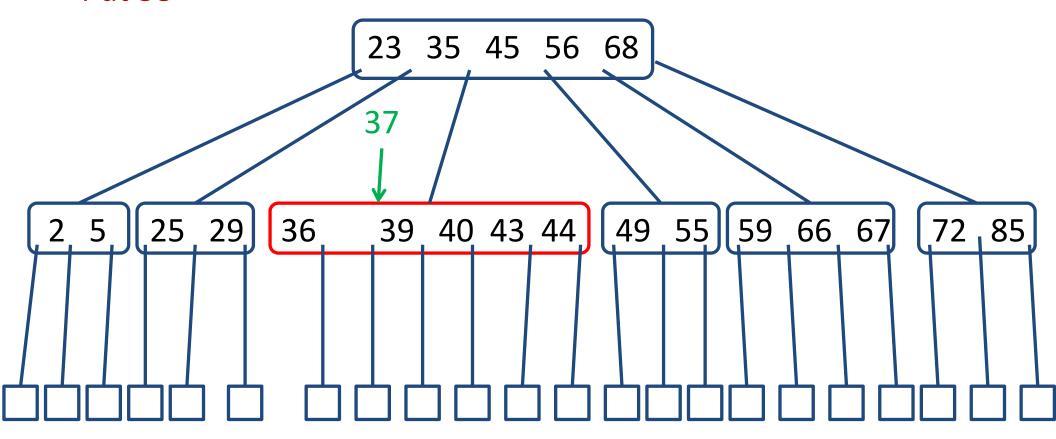


```
Algorithm put (r,k,o)
In: Root r of a B-tree, data item (k,o)
                                                       O(\log d \times \log_d n)
Out: {Insert data item (k,o) in the B-tree
    Search for k to find the lowest insertion internal node v
   Add the new data item (k, o) at node v
   while node v overflows do {
      if v is the root then
            Create a new empty root and set as parent of v
      Split v around the middle key k', move k' to parent, and
      update parent's children
      v \leftarrow \text{parent of } v
```

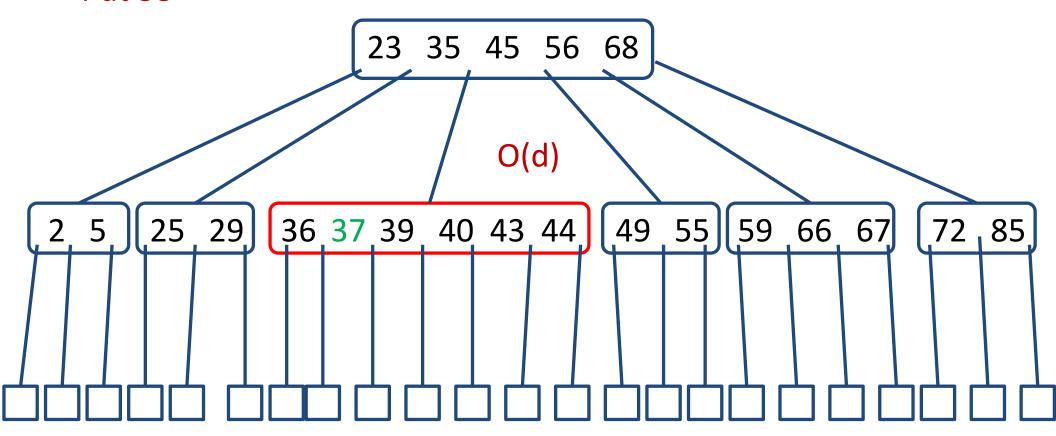
B-Tree of order 6



B-Tree of order 6



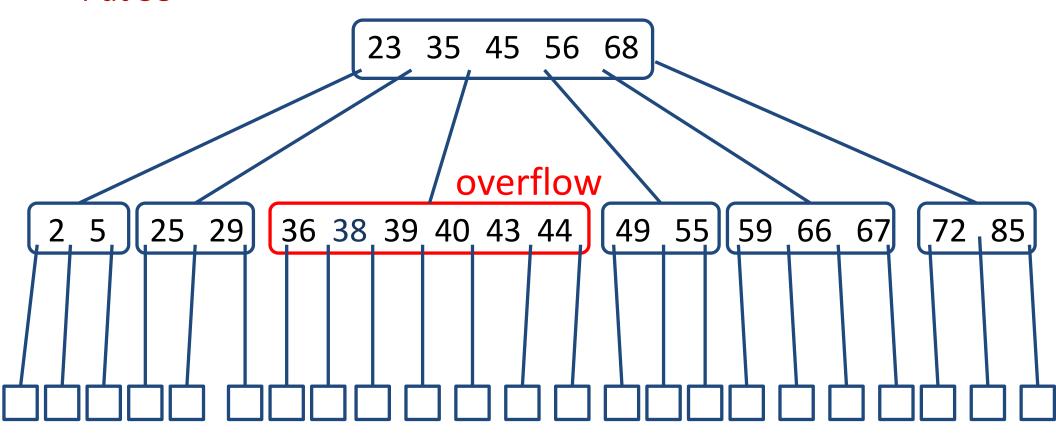
B-Tree of order 6



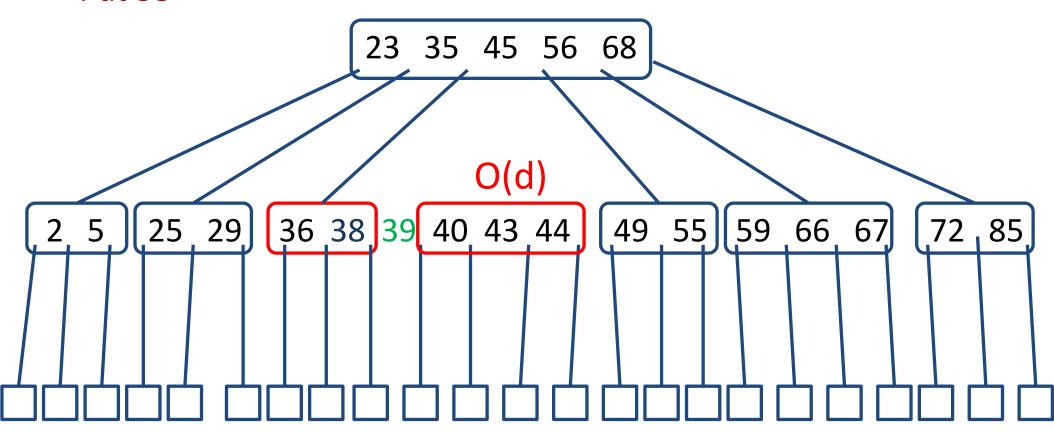
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                                                            O(\log d \times \log_d n)
    Search for k to find the lowest insertion internal node v \vdash
   Add the new data item (k, o) at node v
                                                         O(d)
   while node v overflows do {
      if v is the root then
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                                                            O(\log d \times \log_d n)
    Search for k to find the lowest insertion internal node v \vdash
   Add the new data item (k, o) at node v
                                                         O(d)
   while node v overflows do {
      if v is the root then
             Create a new empty root and set as parent of v
      Split v around the middle key k', move k' to parent, and
      update parent's children
      v \leftarrow \text{parent of } v
```

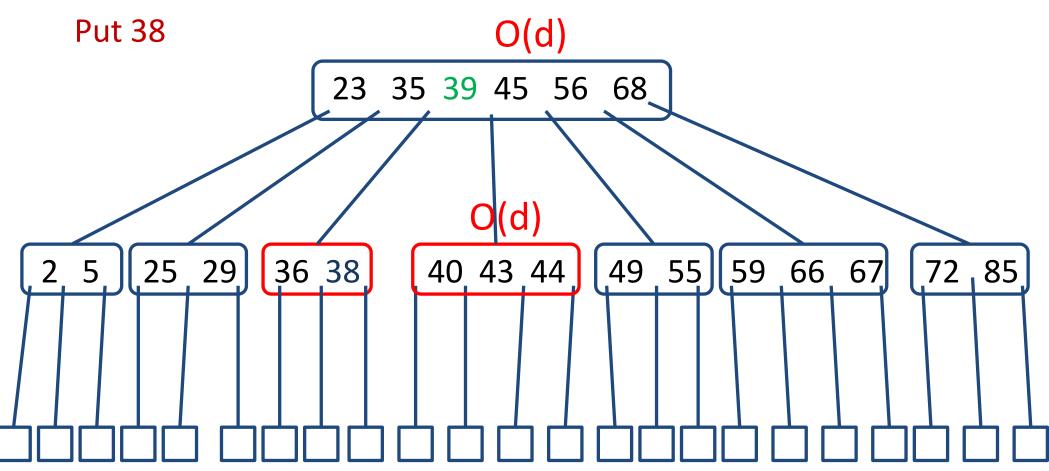
B-Tree of order 6



B-Tree of order 6

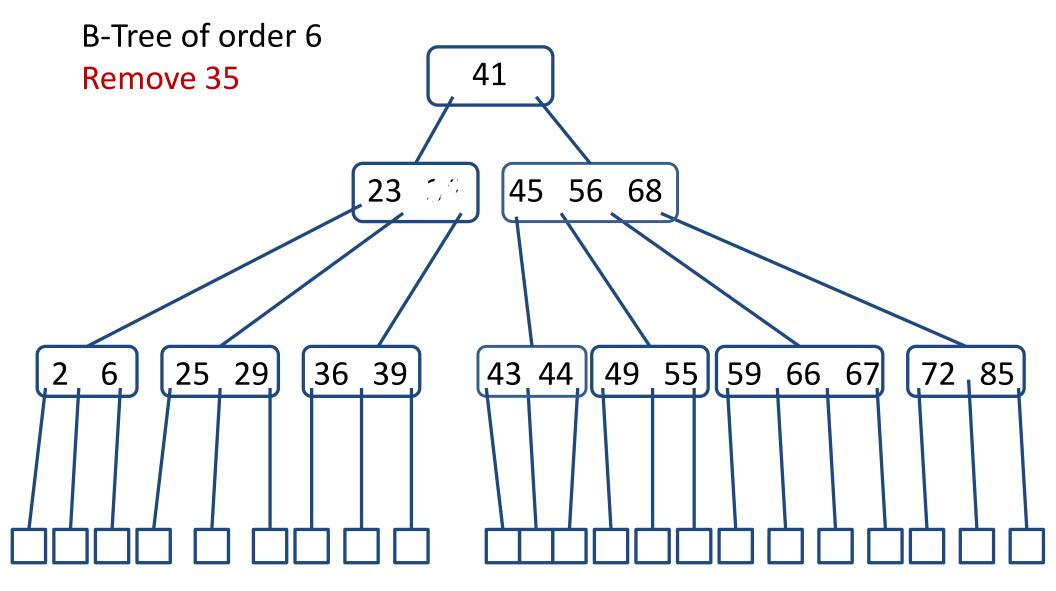


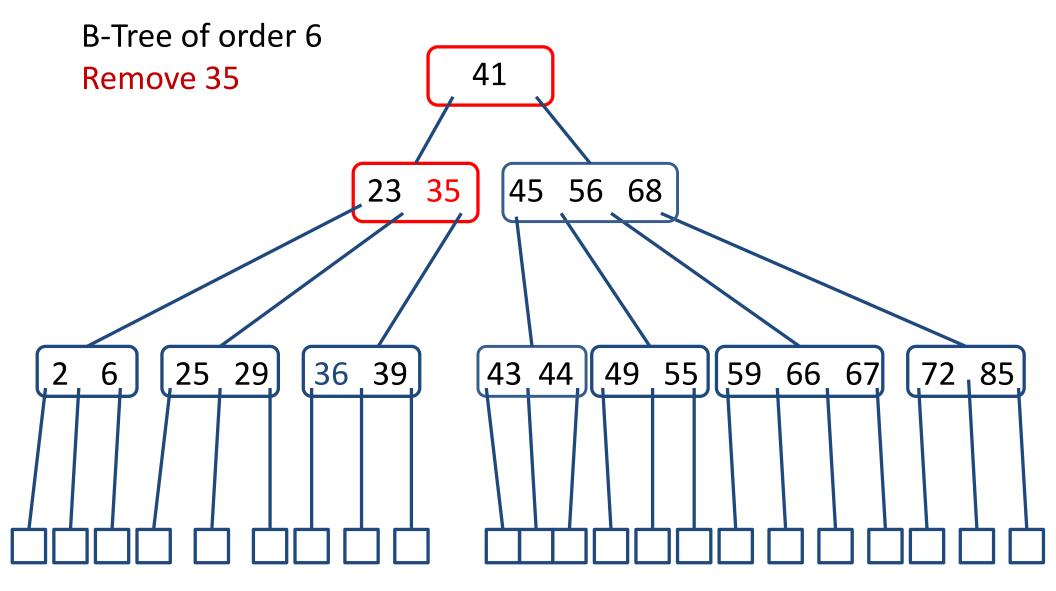
B-Tree of order 6

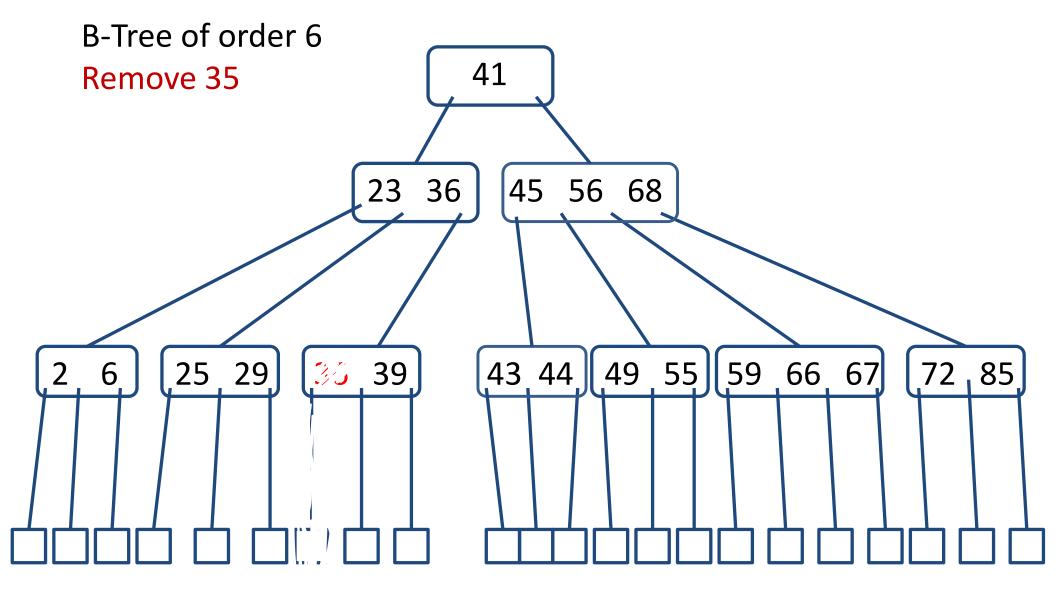


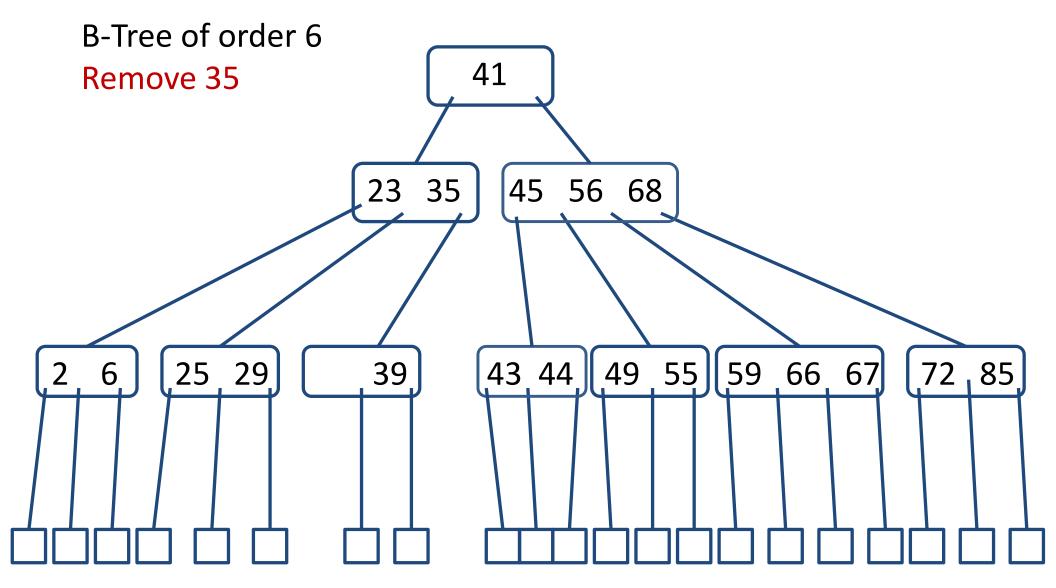
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Out: {Insert data item (k,o) in the B-tree
                                                            O(\log d \times \log_d n)
    Search for k to find the lowest insertion internal node v \vdash
   Add the new data item (k, o) at node v
                                                         O(d)
   while node v overflows do {
      if v is the root then
             Create a new empty root and set as parent of v
      Split v around the middle key k', move k' to parent, and
      update parent's children
      v \leftarrow \text{parent of } v
```

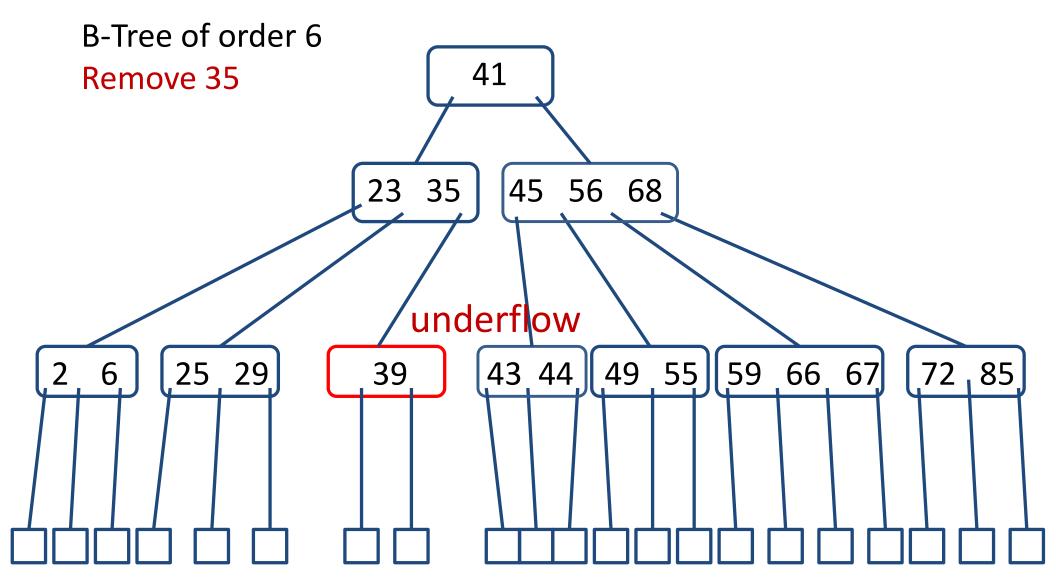
```
Algorithm put (r,k,o)
In: Root r of a B-tree, data item (k,o)
Out: {Insert data item (k,o) in the B-tree
                                                            O(\log d \times \log_d n)
    Search for k to find the lowest insertion internal node v \vdash
   Add the new data item (k, o) at node v
                                                         O(d)
   while node v overflows do {
      if v is the root then
                                                          O(d)
             Create a new empty root and set as parent of v
      Split v around the middle key k', move k' to parent, and
      update parent's children
      v \leftarrow \text{parent of } v
 Time complexity of put is O(d log<sub>d</sub> n)
```

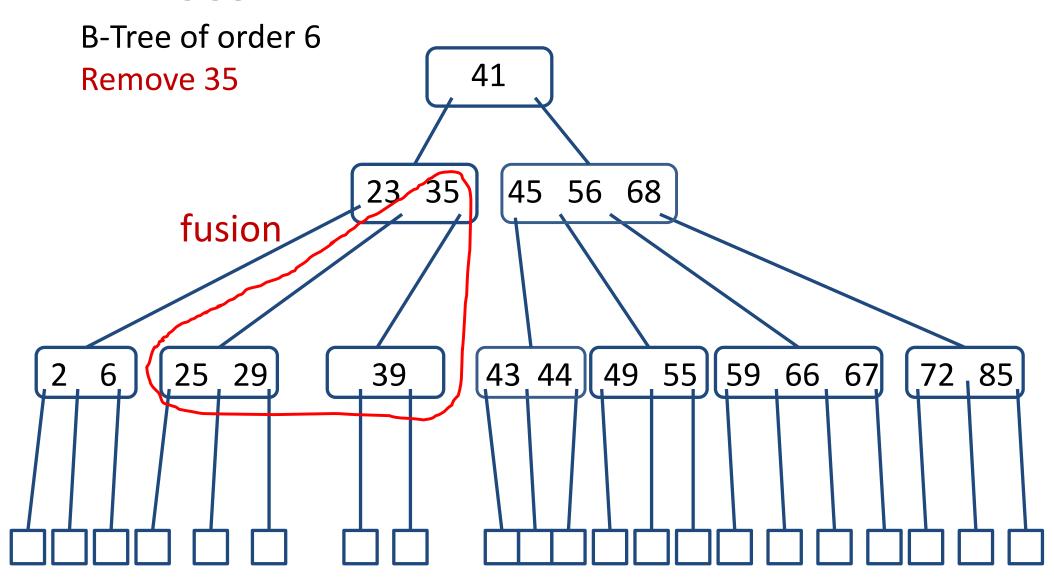


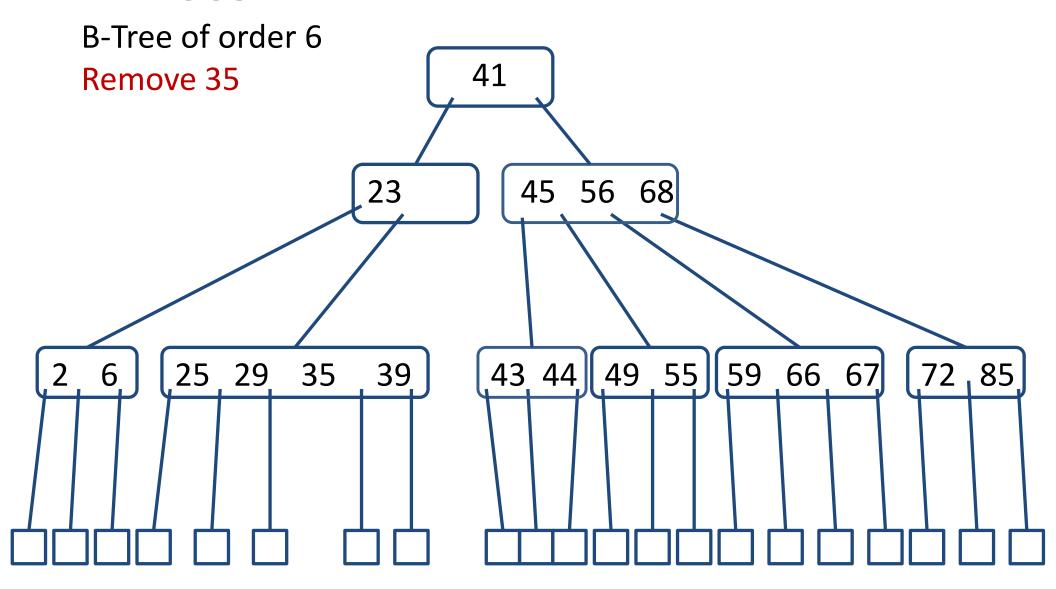


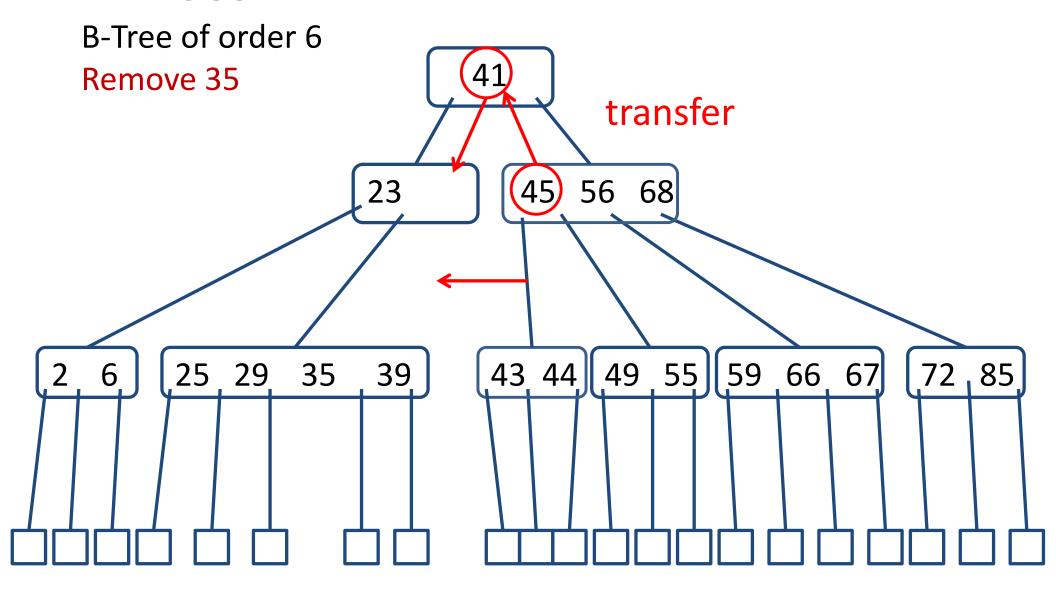


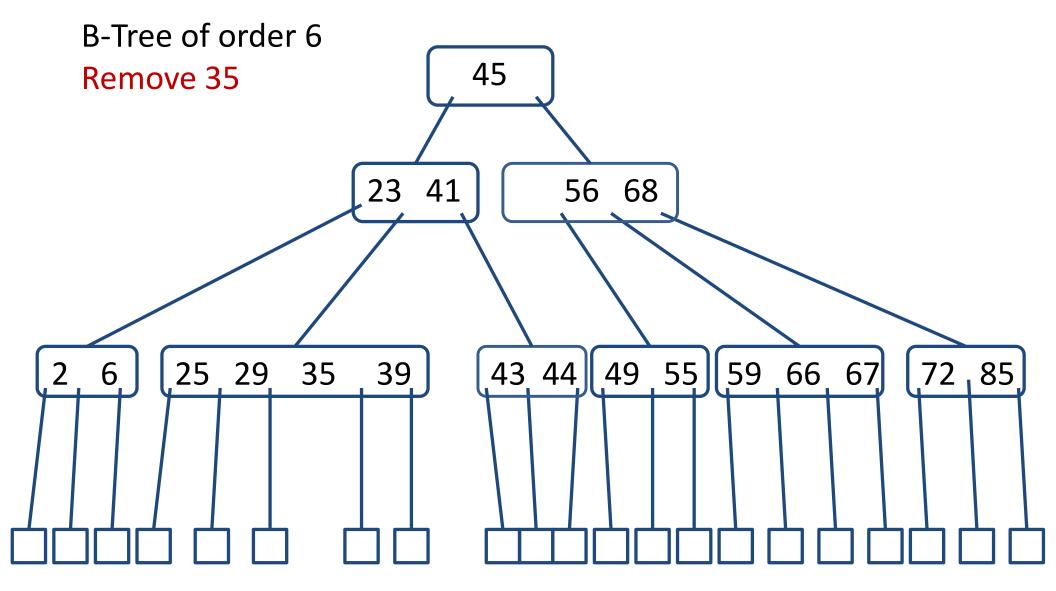






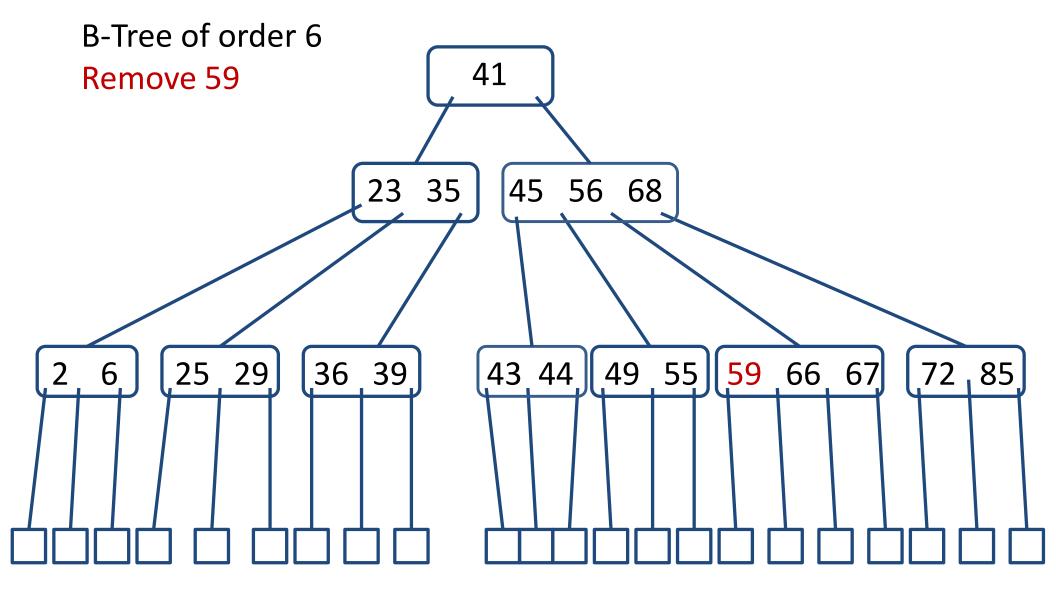


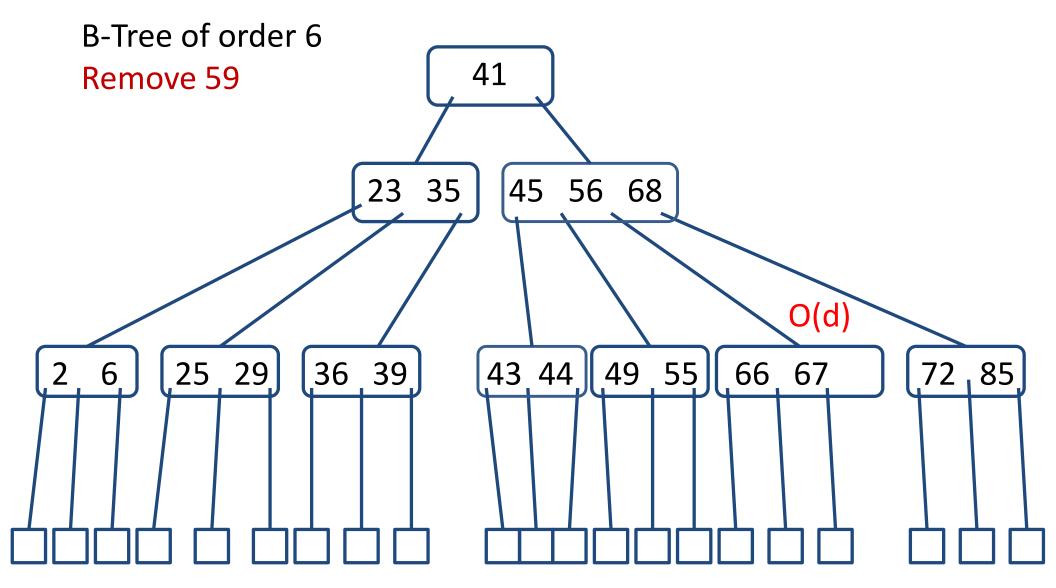




```
Algorithm remove(r,k)
In: Root r of a B-tree, key k
Out: {remove data item with key k from the tree}
   Find the node v storing key k
   Remove (k, o) from v replacing it with successor if needed
   while node v underflows do {
      if v is the root then
           make the first child of v the new root
      else if a sibling has more than \lceil d/2 \rceil keys then
                perform a transfer operation
            else {
                perform a fusion operation
                v \leftarrow \text{parent of } v
```

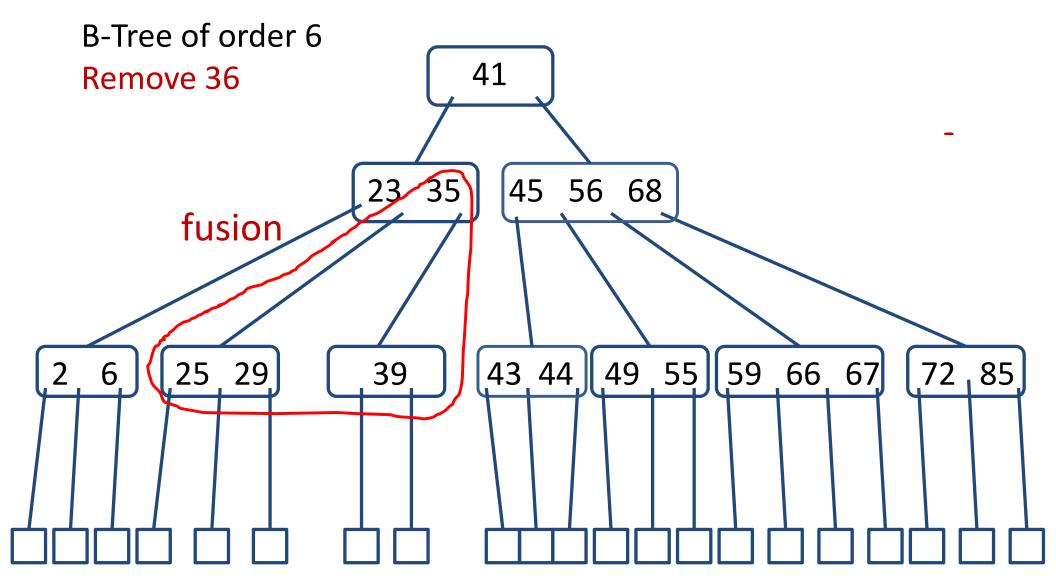
```
Algorithm remove(r,k)
In: Root r of a B-tree, key k
Out: {remove data item with key k from the tree}
                                                \vdash O(log d × log<sub>d</sub> n)
   Find the node v storing key k
   Remove (k, o) from v replacing it with successor if needed
   while node v underflows do {
      if v is the root then
           make the first child of v the new root
      else if a sibling has at least | d/2 | keys then
                perform a transfer operation
            else {
                perform a fusion operation
                v \leftarrow \text{parent of } v
```

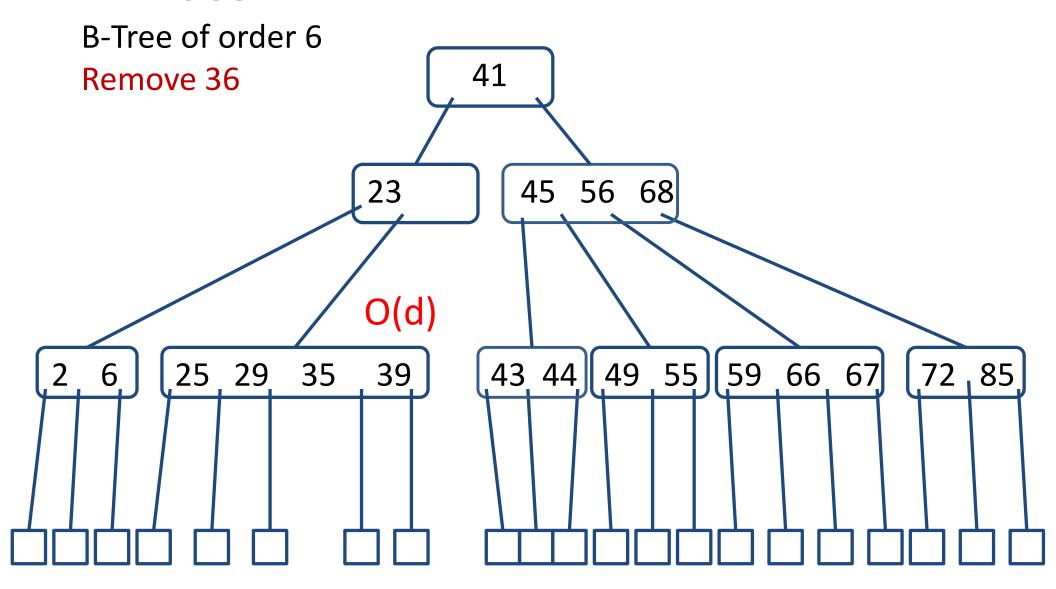


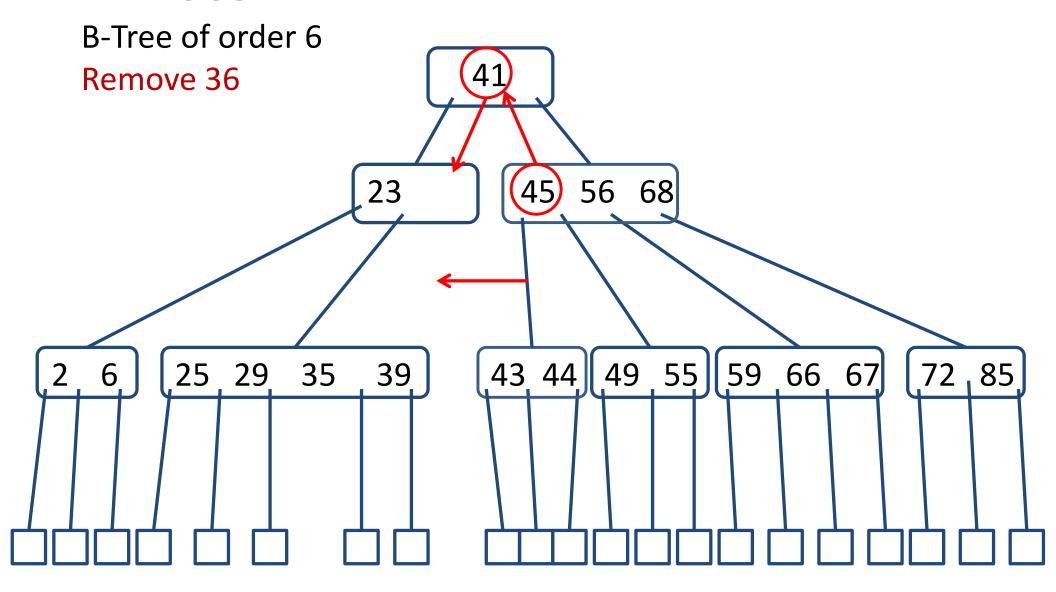


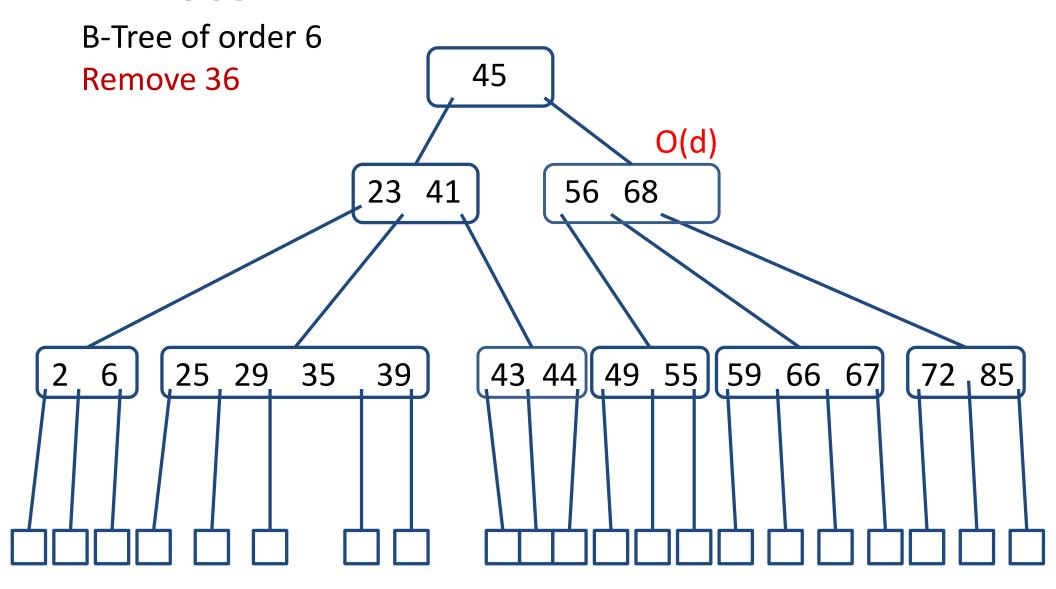
```
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In: Root r of a B-tree, key k
Out: {remove data item with key k from the tree}
                                                - O(log d × log<sub>d</sub> n)
   Find the node v storing key k
   Remove (k, o) from v replacing it with successor if needed
   while node v underflows do {
                                                  O(d)
      if v is the root then
           make the first child of v the new root
      else if a sibling has at least | d/2 | keys then
                perform a transfer operation
            else {
                perform a fusion operation
                v \leftarrow \text{parent of } v
```

```
Algorithm remove(r,k)
In: Root r of a B-tree, key k
Out: {remove data item with key k from the tree}
                                                - O(log d × log<sub>d</sub> n)
   Find the node v storing key k
   Remove (k, o) from v replacing it with successor if needed
   while node v underflows do {
                                                  O(d + \log d \times \log_d n)
      if v is the root then
           make the first child of v the new root
      else if a sibling has at least | d/2 | keys then
                perform a transfer operation
            else {
                 perform a fusion operation
                 v \leftarrow \text{parent of } v
```









Algorithm remove(r,k)

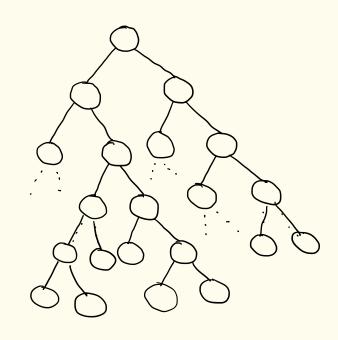
```
In: Root r of a B-tree, key k
Out: {remove data item with key k from the tree}
                                                   \vdash O(log d × log<sub>d</sub> n)
   Find the node v storing key k
   Remove (k, o) from v replacing it with successor if needed
   while node v underflows do {
                                                           O(d + \log d \times \log_d n)
       if v is the root then
            make the first child of v the new root
       else if a sibling has at least | d/2 | keys then
                                                          O(d)
                 perform a transfer operation
            else {
                 perform a fusion operation
                 v \leftarrow \text{parent of } v
```

```
Algorithm remove(r,k)
                                   Time complexity O(d log<sub>d</sub> n)
   In: Root r of a B-tree, key k
   Out: {remove data item with key k from the tree}
                                                        \vdash O(log d × log<sub>d</sub> n)
       Find the node v storing key k
       Remove (k, o) from v replacing it with successor if needed
       while node v underflows do {
                                                                O(d + \log d \times \log_d n)
          if v is the root then
               make the first child of v the new root
O(d|\log_d n)
          else if a sibling has at least \[ \frac{d}{2} \] keys then
                                                               O(d)
                     perform a transfer operation
                else {
                     perform a fusion operation
                     v \leftarrow \text{parent of } v
                                      70
```

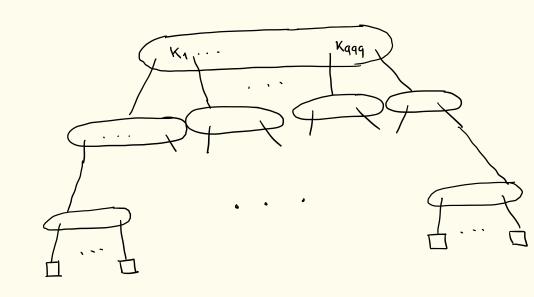
Collection of 109 records

AVL tree

B-tree of degree 103



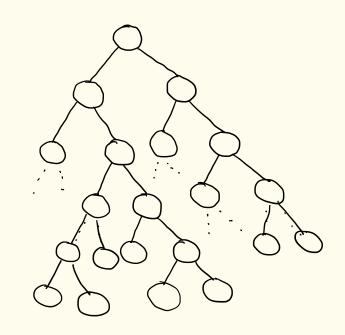
Height: $O(\log_2 n)$ $\log_2 10^9 \approx 30$



Height: $O(\log_d n)$ $\log_{1000} 10^9 = 3$

Collection of 109 records

AVL tree

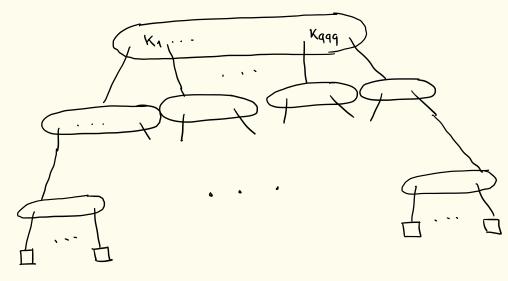


Height: $O(\log_2 n)$ $\log_2 10^9 \approx 30$

Number of comparisons \$\infty 30\$

B-tree of degree 103

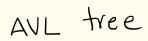
Binary Search: O(log2d)

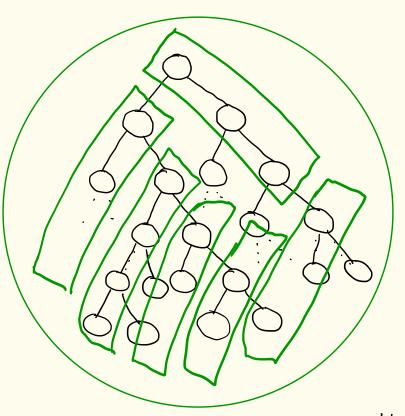


Height: $O(\log_{1000} 10^9 = 3$

Memory Hierarchy CPU volatile 100's of bytes Registers internal 10-100 times slower memory Few Mega Cache bytes 100 times slower Few Giga Main memory bytes 10-106 times slower Persistent Few Tera bytes memory Disk

Collection of 109 records

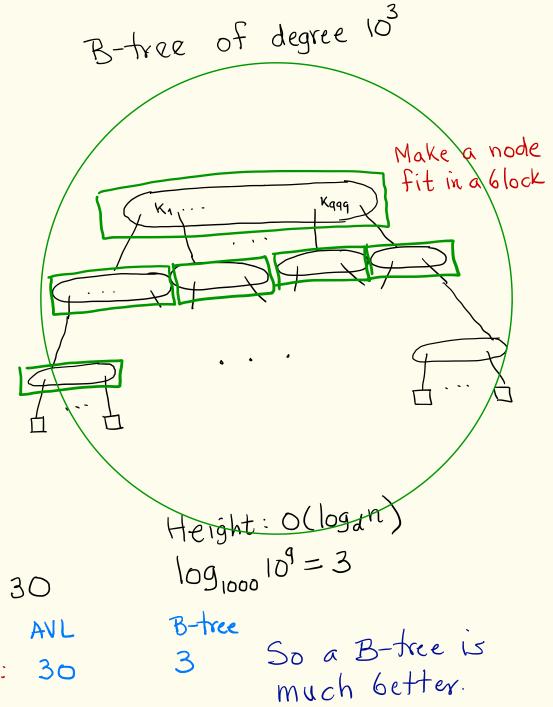




Height: O(logzn)

109,10° 30

Number of disk accesses: 30



Disk Blocks

- Consider the problem of maintaining a large collection of items that does not fit in main memory, such as a typical database.
- In this context, we refer to the external memory is divided into blocks, which we call disk blocks.
- The transfer of a block between external memory and primary memory is a disk transfer or I/O.
- There is a great time difference that exists between main memory accesses and disk accesses
- Thus, we want to minimize the number of disk transfers needed to perform a query or update. We refer to this count as the I/O complexity of the algorithm involved.

Memory Hierarchies

- Computers have a hierarchy of different kinds of memories, which vary in terms of their size and distance from the CPU.
- Closest to the CPU are the internal registers. Access to such locations is very fast, but there are relatively few such locations.
- At the second level in the hierarchy are the memory caches.
- At the third level in the hierarchy is the internal memory, which is also known as main memory or core memory.
- Another level in the hierarchy is the external memory, which usually consists of disks.

