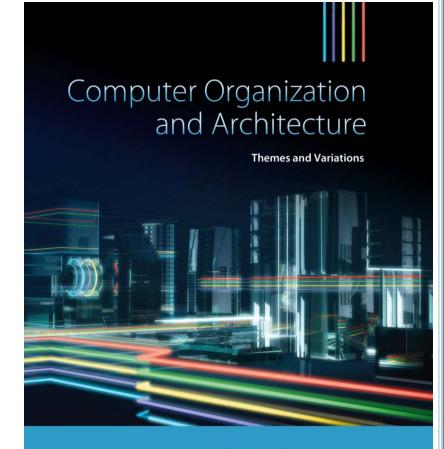
# Part 2

# CHAPTER 1

# Computer Systems Architecture



Alan Clements

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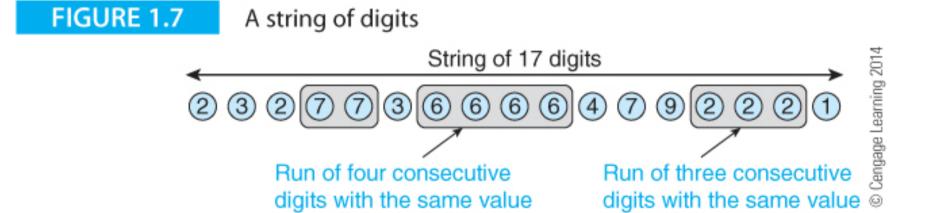
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# Introducing the Computer by Solving a Problem

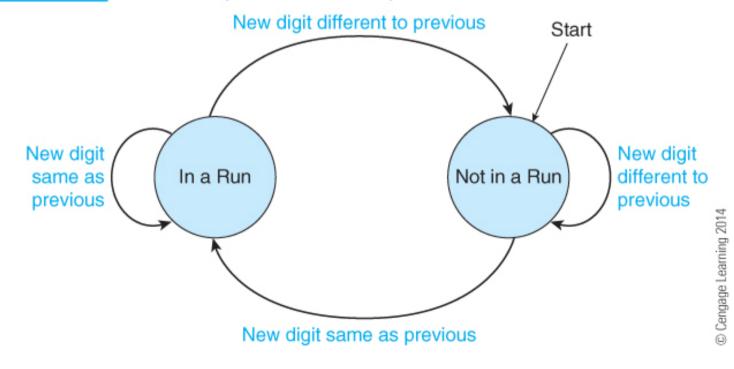
- ☐ Before introducing the computer itself, let us look at what is needed to solve a simple problem.
- ☐ We want to find the longest sequence of repeated digits in a stream of digits.
- ☐ In figure 1.7 the longest run of repeated digits is four consecutive sixes.
- ☐ How can we automate this? What do we need to do?



# Introducing the Computer by Solving a Problem

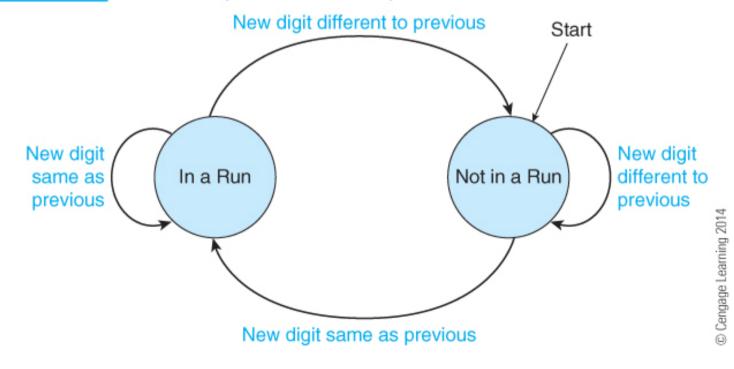
- ☐ We are going to solve this problem sequentially by examining one digit at a time.
- One way of solving this problem is to note that we are always in one of two states:
  - o in a sequence of repeated digits, or
  - o at the start of a new sequence.
- ☐ Figure 1.8 demonstrates how we can illustrate this with a state diagram.

FIGURE 1.8 A state diagram for a run-length counter



- ☐ Each circle represents a possible state
- ☐ There are two states: In a Run and Not in a Run
- ☐ A state change takes place each time we examine a new digit
- ☐ A state transition can
  - o take you from the current state to a new state or
  - keep you in the current state.

FIGURE 1.8 A state diagram for a run-length counter



- ☐ Figure 1.9 shows the state we are in after picking up each digit
- ☐ We start at the left hand end

FIGURE 1.8 A state diagram for a run-length counter

The 4 terminates the run

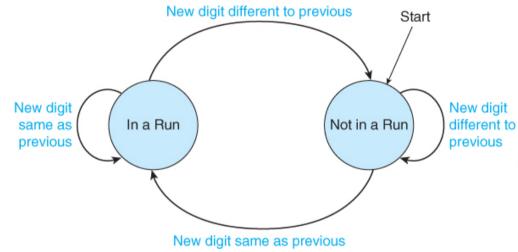
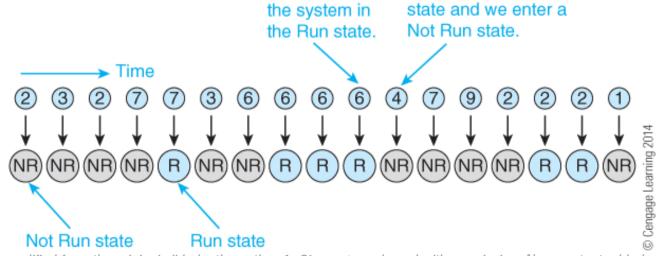


FIGURE 1.9

State changes when reading the string of Figure 1.7

This 6 keeps



- Table 1.1 represents the problem in a table form
- The top line gives the position or location of each digit from 1 to 17
- The second line gives the value of each element (i.e., the string itself)
- The third line gives the current run value. This is the same as the previous digit.

### TABLE 1.1

### Turning the String into a Table of Values

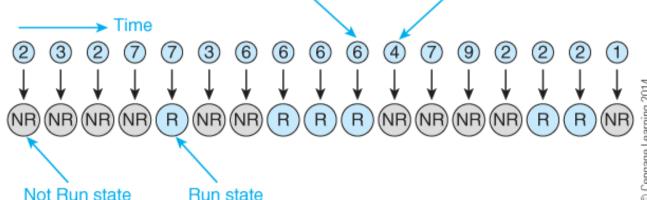
Position in String Element Value Current Run Value

10

FIGURE 1.9

### State changes when reading the string of Figure 1.7

This 6 keeps the system in the Run state. The 4 terminates the run state and we enter a Not Run state.



Not Run state

18

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- Table 1.2 is an extension of table 1.1
- We have added a new row at the bottom: the length of the current run

### TABLE 1.1

### Turning the String into a Table of Values

Position in String	1	2	3	4
Element Value	2	3	2	7
Current Run Value	?	2	3	2

			Strin													
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
2	3	2	7	7	3	6	6	6	6	4	7	9	2	2	2	1
?	2	3	2	7	7	3	6	6	6	6	4	7	9	2	2	2

### TABLE 1.2

### The Current Run Length at Each Position Along the String of Digits

Position in String	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
<b>Element Value</b>	2	3	2	7	7	3	6	6	6	6	4	7	9	2	2	2	1
<b>Current Run Value</b>	?	2	3	2	7	7	3	6	6	6	6	4	7	9	2	2	2
Current Run Length	1	1	1	1	2	1	1	2	3	4	1	1	1	1	2	3	1

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- Table 1.3 adds a new bottom line, the length of the longest run found so far
- We can now look at how we would solve the problem mechanically.

### TABLE 1.1

### Turning the String into a Table of Values

**Position in String** Element Value

Current Run Value

2

3

6

6

6

10

9

15

15

15

16

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### TABLE 1.2

### The Current Run Length at Each Position Along the String of Digits

Position in String **Element Value** 

**Current Run Value Current Run Length** 

10

10

2 2 3

16

### TABLE 1.3

### Expanding Table 1.2 to Include the Maximum Run Length

Position in String **Element Value** Current Run Value

**Current Run Length** Maximum Run Length

11

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### The Data

☐ We now invent some names for the variables in Table 1.3

i The *current position* in the string

New\_Digit The *value* of the *current digit* just read from the string of digits

Current\_Run\_Value The value of the elements in the current run

Current\_Run\_length The length of the current run

Max\_Run The *length* of the *longest run* we've found so far

### TABLE 1.3 Expanding Table 1.2 to Include the Maximum Run Length

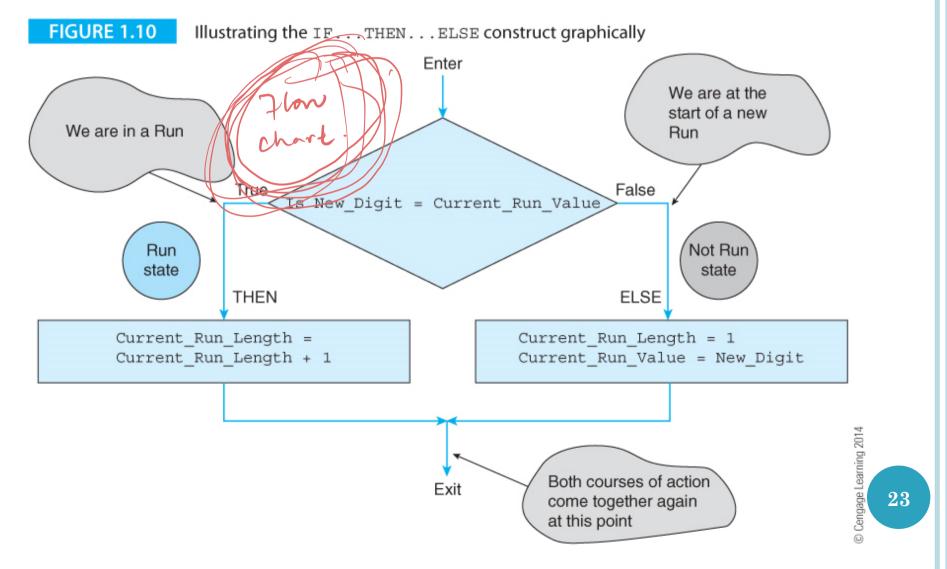
Position in String	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
Element Value	2	3	2	7	7	3	6	6	6	6	4	7	9	2	2	2	1
Current Run Value	?	2	3	2	7	7	3	6	6	6	6	4	7	9	2	2	2
Current Run Length	1	1	1	1	2	1	1	2	3	4	1	1	1	1	2	3	1
Maximum Run Length	1	1	1	1	2	2	2	2	3	4	4	4	4	4	4	4	4

# The Algorithm in Pseudo-code

- ☐ We can now look at how we would solve the problem.
- 1. Read the first digit in the string and call it New\_Digit
- 2. Set the Current\_Run\_Value to New\_Digit
- 3. Set the Current\_Run\_Length to 1
- 4. Set the Max\_Run to 1
- 5. REPEAT
- 6. Read the next digit in the sequence (i.e., read a New\_Digit)
- 7. IF its value is the same as Current\_Run\_Value
- 8. THEN Current\_Run\_Length = Current\_Run\_Length + 1
- 9. ELSE {Current\_Run\_Length = 1
- 10. Current\_Run\_Value = New\_Digit}
- 11. IF Current\_Run\_Length > Max\_Run
- 12. THEN Max\_Run = Current\_Run\_Length
- 13. UNTIL The last digit is read

# The Algorithm in Pseudo-code

Figure 1.10 illustrates the use of the IF...THEN...ELSE construct where we test whether we are in a run or not to either increment the run length or reset it to 1.



# **Program and Data**

- ☐ Figure 1.11 provides a table that includes
  - o the operations,
  - o the variables, and
  - o the string of digits to be tested.
- This table can be modelled as a memory array.
  - The line-number 0 to 37 corresponds to an address
  - The contents of each location represent either
    - A program instruction or
    - o data.
- Note that real computer instructions are not exactly like these. Whiles But they are very similar.
- ☐ From the bit pattern point of view, there is no way to differentiate between encoded data and encoded program instruction.

FIGUR	E 1.11 Memory map of a program and its data									
0	i = 21									
1	New_Digit = Memory(i)									
2	Set Current_Run_Value to New_Digit									
3	Set the Current_Run_Length to 1									
4	Set the Max_Run to 1									
5	REPEAT									
6	i = i + 1									
7	New_Digit = Memory(i)									
8	IF New_Digit = Current_Run_Value									
9	THEN Current_Run_Length = Current_Run_Length + 1									
10	JUMP to 13									
11	ELSE Current_Run_Length = 1;									
12	Current_Run_Value = New_Digit									
13	IF Current_Run_Length > Max_Run									
14	THEN Max_Run = Current_Run_Length									
15	UNTIL i = 37									
16	Stop									
17	New_Digit									
18	Current_Run_Value									
19	Current_Run_Length									
20	Max_Run									
21	2 (the first digit in the string)									
22	3									
23	2									
23	7 24									
37	1 (the last digit in the string)									

# The Naming of Parts

Constant – a value that doesn't change during the execution of a program. For example, if  $c = 2\pi r$ , then both '2' and ' $\pi$ ' are constants.

Variable – a value that <u>can change</u> during the execution of a program. In the previous example, both **c** and **r** are variables.

**Symbolic name** – we often refer to a *variable* or a *constant* by a name that makes it easier for us to remember.

For example, we give the irrational number 3.1415926 the symbolic name  $\pi$ . When a program is compiled, symbolic names are replaced by actual values.

Address – information in a computer is stored in memory locations and each location has a unique address. Think of computer memory as if it is an array and the index of this array is the address of the memory locations.

Rather than trying to remember actual address locations in memory, we give addresses symbolic names; in this case the address may be called r.

Value and Location – When we write  $c = 2\pi r$ , what is r? We (humans) see r as the symbolic name for the value of the radius, say 5. But, the computer sees r as the symbolic address 1234 which has to be read to provide the value. If we write r = r + 1, we mean r = 5 + 1 = 6 or do we mean r = 1234 + 1 = 1235?

It is very important to distinguish between an address and its contents. This factor becomes significant when we introduce pointers.

Pointer – A pointer is a variable whose value is an address. If you modify the value of a pointer, it points to a different value.

In conventional arithmetic we write  $x_i$  where i is really a pointer; we just call it an index. If you change the pointer (index) we can step through the elements of a table, array or matrix, i.e.,  $x_1$ ,  $x_2$ ,  $x_3$ ,  $x_4$ .

# Register Transfer Language (RTL) Notation

- ☐ In RTL notation, square brackets indicate the contents of a memory location.
  - o For example, The expression [15] = Max\_Run means

    "the content of memory location 15 is equal to the value of Max\_Run",

    I.e., it is a sort of initialization not an assignment.
- ☐ The backward arrow symbol, ←, indicates a data transfer.
  - For example, [15] ← [15] + 1 means
     "the content of memory location 15 is increased by 1" and
    - "the result is put in memory location 15".
- ☐ Consider:
  - a. [20] = 6
  - b.  $[20] \leftarrow 6$
  - c.  $[20] \leftarrow [6]$

initialization

- (a) states that the content of memory location 20 is equal to the number 6.
- (b) states that the number 6 is put into memory location 20. \*\*Signment:
- (c) states that the contents of memory location 6 is copied into memory location 20.

☐ The following pseudo-code expresses the fundamental action of a stored program machine.

Stored\_program\_machine
Point to the first instruction in memory
REPEAT

- 1. Read the instruction at the memory location pointed at
- 2. Point to the next instruction
- 3. Decode the instruction just read from memory
- 4. Execute the instruction

**FOREVER** 

End



☐ This pseudo-code sequence tells us that a *memory reference* (i.e., a memory read) is required to fetch each instruction from memory.

☐ We can expand the action **Execute the instruction** to give

### **Execute the instruction**

IF the instruction requires data
THEN fetch the data from memory
END\_IF

Perform the operation defined by the instruction

IF the instruction requires data to be stored in memory
THEN store the data in memory
END IF

### End

☐ As you see, **Execute the instruction** may require a *memory read and/or* a *memory write* 

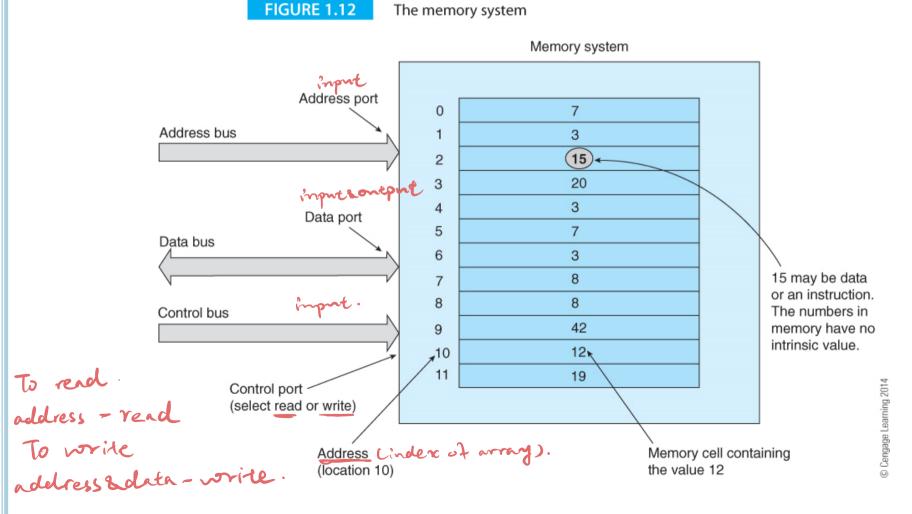
☐ We can also express this sequence of actions in C or Java as follows:

```
In the book, the post increment is missing

do
{ instruction = memory[InstructionPointer++]; using it.

/* read the instruction */
decode(instruction); /* decode the instruction */
fetch(operands); /* fetch data required */
execute(); /* execute the instruction */
store(results); /* store the result */
} while (instruction != stop);
```

- ☐ A key component of a computer is the <u>memory</u> that holds the program (instructions) and data.
- ☐ Figure 1.12 illustrates the elements of a computer's *memory system*.



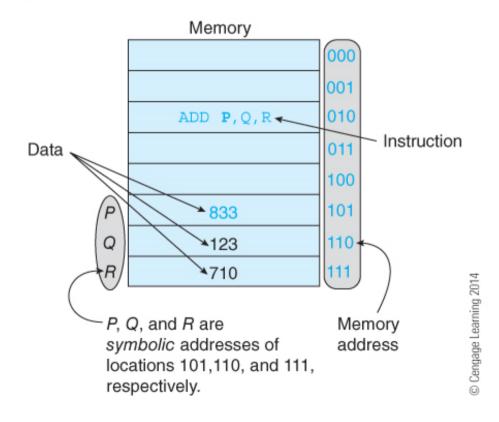
# **Three Address Instructions**

- ☐ Consider the <u>three-address</u> format:
  - o *Operation Address 1*, *Address 2*, *Address 3* where *Operation* specifies the action of the instruction, whereas *Address 1*, *Address 2*, and *Address 3*, are locations of the three operands in memory.
  - We use **bold** font to indicate the address that is the destination of data.
- ☐ In this example, the operands are the addresses of data and not the data itself.
- $\square$  ADD P, Q, R, is a three-operand instruction
  - $\circ$  **P**, **Q**, and **R** are the *symbolic names* of the *addresses of three memory locations*.
- $\square$  The three-operand format *can be expressed in RTL notation* as:
  - [Address1] ← [Address2] Operation [Address3]
- ☐ The contents of the memory locations specified by *Address2* and *Address3* are operated on by the *operation* (e.g., *add*, *subtract*, ...), and the result is placed in the memory location specified by *Address1*.

# **Three Address Instructions**

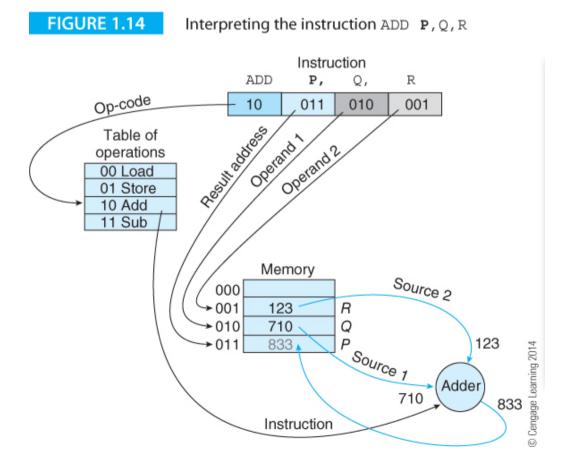
- ☐ Although memory addresses are numeric (in this case we use binary numbers *000* to *111*), we normally use symbolic names because they are easier for us to remember.
- $\square$  If you write P in a program, it is automatically translated to address 101.

FIGURE 1.13 Relationship between instruction and operands



### **Three Address Instructions**

- □ Figure 1.14 shows a hypothetical computer that has an instruction with three addresses; for example, ADDP, Q, R which implements  $[P] \leftarrow [Q] + [R]$ . Here P, Q, and R are the symbolic names of their locations in memory.
- ☐ The purpose of this figure is to show the flow of information when an instruction is executed and to demonstrate the possible structure of an instruction.



### Two Address Instructions

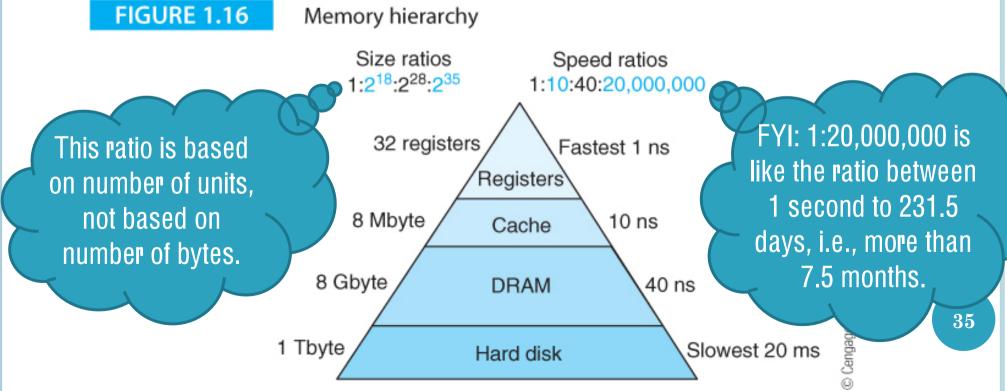
- □ Some computers implement a <u>two-address</u> instruction format of the form

  Operation Address1, Address2
  - where *Address2* is a *source operand* and
  - o *Address1* is both a source and a destination operand.
    - This operand is accessed, operated on, and the result placed in the same location.
  - The definition of ADD P,Q, is  $[P] \leftarrow [P] + [Q]$
- $\square$  A two-address instruction <u>destroys</u> one of the operands; that is, source operand P is replaced (overwritten) by the result.
- ☐ <u>Practical computers</u> do not generally allow you to use three or two <u>main</u> memory addresses in the same instruction.
  - Computers like the Core i7 processors specify one address in memory and a second address is a register.
- $\square$  A register is a single storage element in the computer with a name like r0, r1, r2 ... or r31 and is used to hold temporary data during calculations.
- □ A register behaves like a memory location except that it is located within the CPU.

# **Memory Hierarchy**

- ☐ An important characteristic of modern computers is the wide range of technologies used to implement computers.
- ☐ Figure 1.16 illustrates memory hierarchy that covers the memory system of a typical computer.
- At the top are small amounts of on-chip register memory.

  At the bottom are the large quantities of storage provides by hard disks.

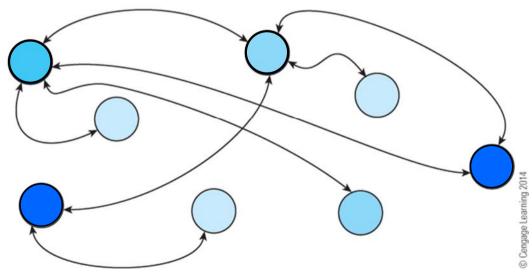


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### The Bus

- ☐ Buses link together two or more functional parts of a computer and allow the exchange of data;
  - o for example, the bus between the CPU and its graphics card.
- ☐ Buses also link computers to external peripherals;
  - o for example, the USB bus that connects a printer to a computer.
- ☐ Figure 1.17 illustrates the structure of a *hypothetical system without a bus*. Imagine that the blue circles are processing units that have to communicate with each other.
- ☐ In this example some units communicate directly with only one other unit, whereas other units have to communicate with several devices.

FIGURE 1.17 An arbitrary interconnect structure—life without the bus

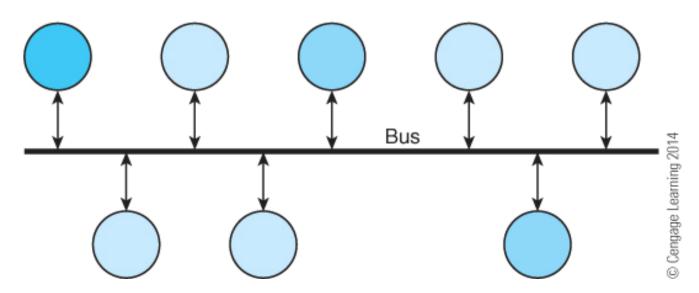


### The Bus

- ☐ Figure 1.18 illustrates the structure of *a system with a bus*.
- ☐ Functional units may
  - □ request the bus,
- use release 24. use it to communicate with other units and then
  - □ relinquish the bus.
- ☐ *Internal* buses (within the CPU or on the motherboard) and external buses (USB, FireWire) are vital components of the computer system and contribute to its overall performance.

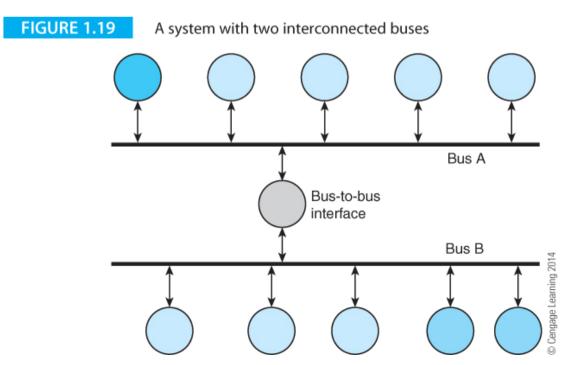
### **FIGURE 1.18**

A common bus connecting all units



### The Bus

- ☐ Figure 1.19 illustrates the structure of *a system with two buses*.
- ☐ Multiple buses permit parallel operation because transactions on each bus can take place simultaneously.
- ☐ Each bus may be optimized for its specific application (e.g., a high speed bus for graphics and a lower speed bus for peripherals).



# Bus Terminology

### Width

The width of a bus is defined as the number of parallel data paths. A 64-bit bus can carry 64-bits (8 bytes) of data at a time.

However, the same term can also be used to indicate the total number of wires (connections) that make up a bus. For example, a bus may have 50 information paths of which 32 of them carry data (the rest may be paths for *control signals* or even power lines).

Bandwidth The bandwidth of a bus is a measure of the rate at which information can be transported across the bus. The bandwidth is expressed in either bytes per second or bits per second.

> Increasing the width of a bus while keeping the data rate per wire constant increases the bandwidth.

### Latency

Latency is the waiting period between a data transfer request and the actual data transmission completed.

Typically, a bus's latency includes the time taken to arbitrate for the bus before transmission can take place.