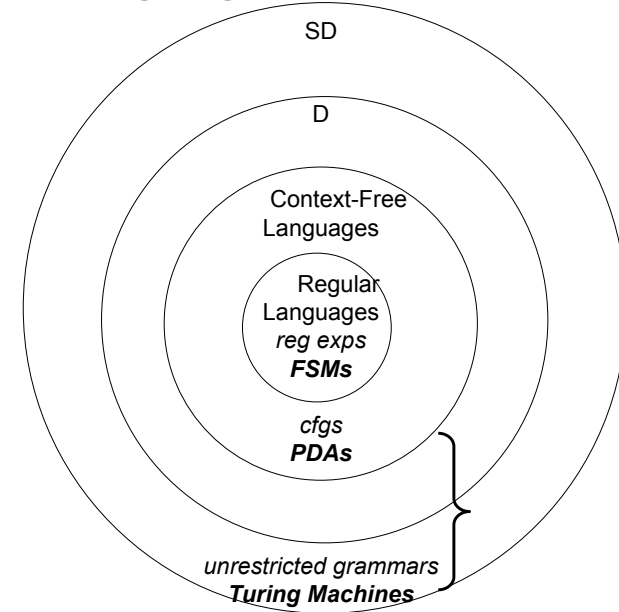


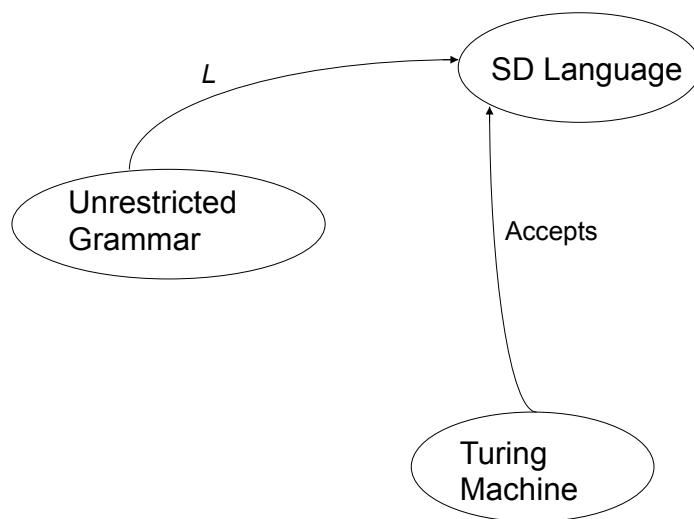
Turing Machines

Chapter 17

Languages and Machines



Grammars, SD Languages, and Turing Machines

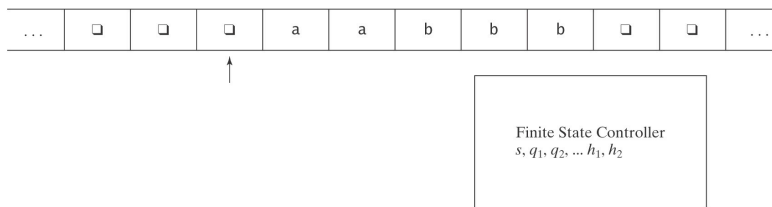


Turing Machines

Can we come up with a new kind of automaton that has two properties:

- powerful enough to describe all computable things
unlike FSMs and PDAs.
- simple enough that we can reason formally about it
like FSMs and PDAs,
unlike real computers.

Turing Machines



At each step, the machine must:

- choose its next state,
- write on the current square, and
- move left or right.

A Formal Definition

A Turing machine M is a sextuple $(K, \Sigma, \Gamma, \delta, s, H)$:

- K is a finite set of **states**;
- Σ is the **input alphabet**, which does not contain □;
- Γ is the **tape alphabet**, which must contain □ and have Σ as a subset.
- $s \in K$ is the **initial state**;
- $H \subseteq K$ is the set of **halting states**;
- δ is the **transition function**:

$(K - H) \times \Gamma$ to $K \times \Gamma \times \{\rightarrow, \leftarrow\}$
 non-halting state \times tape char state \times tape char \times action (R or L)

Notes on the Definition

1. The input tape is infinite in both directions.
2. δ is a function, not a relation. So this is a definition for **deterministic** Turing machines.
3. δ must be defined for all state, input pairs unless the state is a halting state.
4. Turing machines do not necessarily halt (unlike FSM's and PDAs). Why? To halt, they must enter a halting state. Otherwise they loop.
5. Turing machines generate output so they can compute functions.

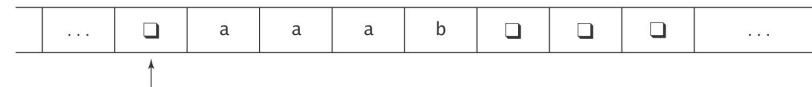
An Example

M takes as input a string in the language:

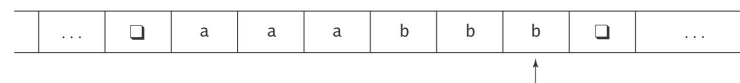
$$\{a^i b^j, 0 \leq j \leq i\},$$

and adds b 's as required to make the number of b 's equal the number of a 's.

The input to M will look like this:

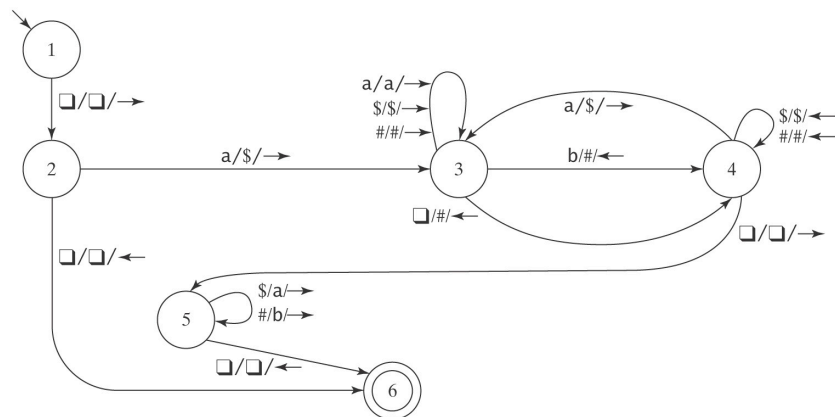


The output should be:



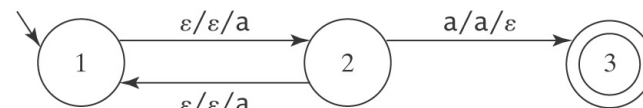
The Details

$K = \{1, 2, 3, 4, 5, 6\}$, $\Sigma = \{a, b\}$, $\Gamma = \{a, b, \square, \$, \#\}$,
 $s = 1$, $H = \{6\}$, $\delta =$



Halting

- A DFMSM M , on input w , is guaranteed to halt in $|w|$ steps.
- A PDA M , on input w , is not guaranteed to halt. To see why, consider again $M =$



But there exists an algorithm to construct an equivalent PDA M' that is guaranteed to halt.

A TM M , on input w , is not guaranteed to halt. And there exists no algorithm to construct one that is guaranteed to do so.

Formalizing the Operation

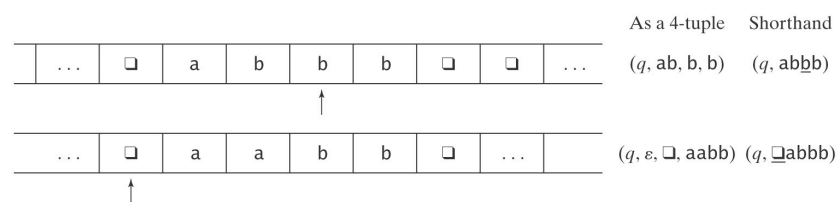
A **configuration** of a Turing machine

$M = (K, \Sigma, \Gamma, s, H)$ is an element of:

$$K \times ((\Gamma - \{\square\})^* \cup \{\epsilon\}) \times \Gamma \times ((\Gamma - \{\square\})^* \cup \{\epsilon\})$$

state	up to scanned square	scanned square	after scanned square
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Example Configurations



$$\begin{aligned} (1) \quad (q, ab, b, b) &= (q, abbb) \\ (2) \quad (q, \epsilon, \square, aabb) &= (q, \square aabb) \end{aligned}$$

Initial configuration is $(s, \square w)$.

Yields

$(q_1, w_1) \vdash_M (q_2, w_2)$ iff (q_2, w_2) is derivable, via δ , in one step.

For any TM M , let \vdash_M^* be the reflexive, transitive closure of \vdash_M .

Configuration C_1 **yields** configuration C_2 if: $C_1 \vdash_M^* C_2$.

A **path** through M is a sequence of configurations C_0, C_1, \dots, C_n for some $n \geq 0$ such that C_0 is the initial configuration and:

$$C_0 \vdash_M C_1 \vdash_M C_2 \vdash_M \dots \vdash_M C_n.$$

A **computation** by M is a path that halts.

If a computation is of *length* n or has n steps, we write:

$$C_0 \vdash_M^n C_n$$

A Notation for Turing Machines

(1) Define some basic machines

- Symbol writing machines

For each $x \in \Gamma$, define M_x , written just x , to be a machine that writes x , then halts.

- Head moving machines

R: for each $x \in \Gamma$, $\delta(s, x) = (s, x, \rightarrow)$

L: for each $x \in \Gamma$, $\delta(s, x) = (s, x, \leftarrow)$

- Machines that simply halt:

h, which simply halts.

n, which halts and rejects.

y, which halts and accepts.

Checking Inputs and Combining Machines

Next we need to describe how to:

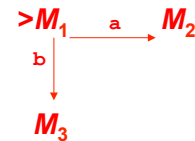
- Check the tape and branch based on what character we see, and
- Combine the basic machines to form larger ones.

To do this, we need two forms:

- $M_1 M_2$
 - Begin in start state of M_1 , run M_1 until halts, begin M_2 in start state, run M_2 until halts, then halt. If either fails to halt, then $M_1 M_2$ fails to halt.
- $M_1 \xrightarrow{\langle \text{condition} \rangle} M_2$
 - The same, except that $\langle \text{condition} \rangle$ is checked to move from M_1 to M_2 .

A Notation for Turing Machines, Cont'd

Example:



- Start in the start state of M_1 . ("**>**" marks the beginning)
- Compute until M_1 reaches a halt state.
- Examine the tape and take the appropriate transition.
- Start in the start state of the next machine, etc.
- Halt if any component reaches a halt state and has no place to go.
- If any component fails to halt, then the entire machine may fail to halt.

becomes

becomes

Variables

becomes

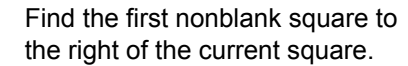
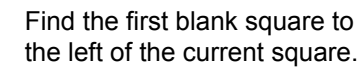
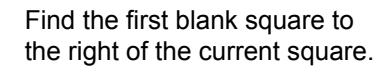
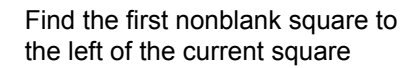
and x takes on the value of
the current square

becomes

and x takes on the value of
the current square

if $x = y$ then take the transition

if the current square is not blank, go right and copy it.

R₀

Find the first occurrence of `a` to the left of the current square.

Find the first occurrence of `a` or `b` to the right of the current square.

Find the first occurrence of a or b to the left of the current square, then go to M_1 if the detected character is a ; go to M_2 if the detected character is b .

 M_2

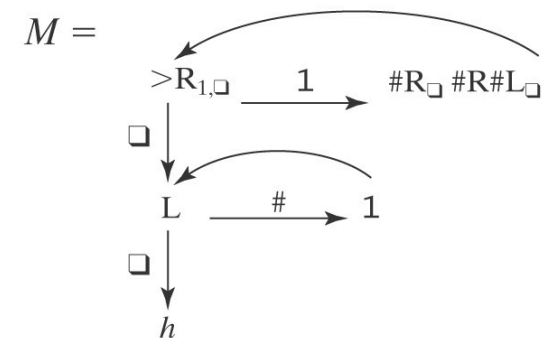
Find the first occurrence of a or b to the left of the current square and set x to the value found.

Find the first occurrence of a or b to the left of the current square, set x to the value found, move one square to the right, and write x (a or b).

W

 $\square w^3$

01110000000000000000

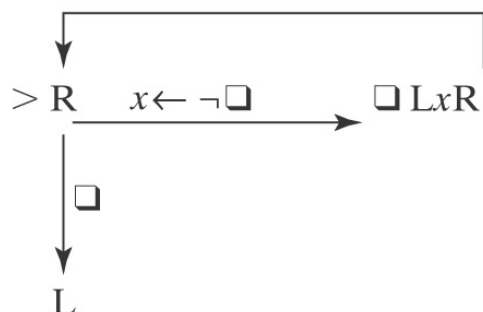


A Shifting Machine S_{\leftarrow}

Input: $\square u \square w \square$

Output: $\square u w \square$

Example: $\square ba \square abba \square \square \square \square \square \square \square \square \square \square \square \square$



Turing Machines as Language Recognizers

Convention: We will write the input on the tape as:

$\square w \square$, w contains no \square s

The **initial configuration** of M will then be:

$(s, \square w)$

Let $M = (K, \Sigma, \Gamma, \delta, s, \{y, n\})$.

- M **accepts** a string w iff $(s, \square w) \vdash_M^* (y, w')$ for some string w' .
- M **rejects** a string w iff $(s, \square w) \vdash_M^* (n, w')$ for some string w' .

Turing Machines as Language Recognizers

M **decides** a language $L \subseteq \Sigma^*$ iff:

For any string $w \in \Sigma^*$ it is true that:

if $w \in L$ then M accepts w , and

if $w \notin L$ then M rejects w .

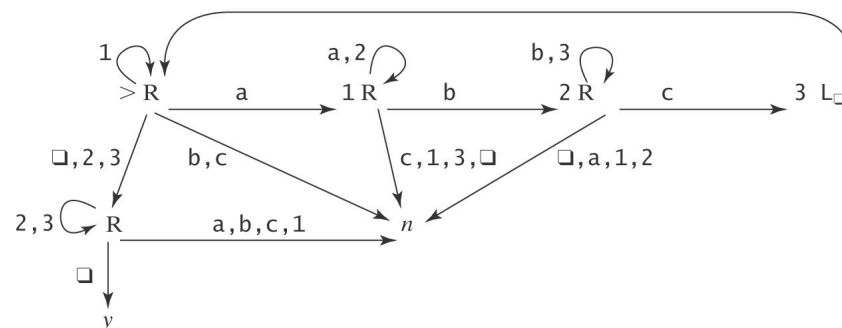
A language L is **decidable** iff there is a Turing machine M that decides it. In this case, we will say that L is in **D**.

A Deciding Example

$A^n B^n C^n = \{a^n b^n c^n : n \geq 0\}$

Example: $\square aabbcc \square \square \square \square \square \square \square \square$

Example: $\square aacccb \square \square \square \square \square \square \square \square$

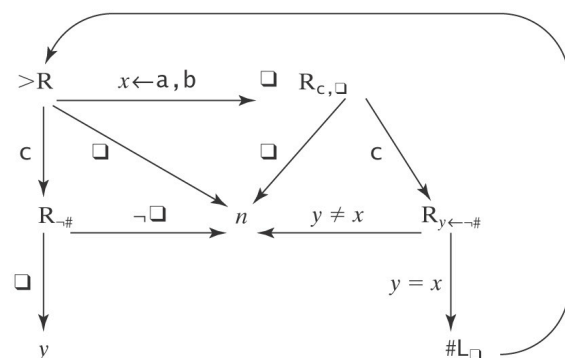


Another Deciding Example

$WcW = \{wcw : w \in \{a, b\}^*\}$

Example: $\square abbcabb\square\square\square$

Example: $\square acabb\square\square\square$



Semideciding a Language

Let Σ_M be the input alphabet to a TM M . Let $L \subseteq \Sigma_M^*$.

M **semidecides** L iff, for any string $w \in \Sigma_M^*$:

- $w \in L \rightarrow M$ accepts w
- $w \notin L \rightarrow M$ does not accept w . M may either: reject or fail to halt.

A language L is **semidecidable** iff there is a Turing machine that semidecides it. We define the set **SD** to be the set of all semidecidable languages.

Example of Semideciding

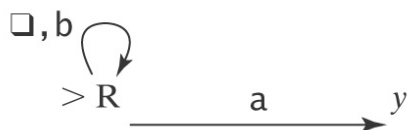
Let $L = b^*a(a \cup b)^*$

We can build M to semidecide L :

1. Loop

- 1.1 Move one square to the right. If the character under the read head is an a , halt and accept.

In our macro language, M is:



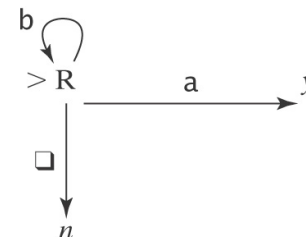
Example of Semideciding

$L = b^*a(a \cup b)^*$. We can also decide L :

Loop:

- 1.1 Move one square to the right.
- 1.2 If the character under the read/write head is an a , halt and accept.
- 1.3 If it is \square , halt and reject.

In our macro language, M is:



Computing Functions

Let $M = (K, \Sigma, \Gamma, \delta, s, \{h\})$. Its initial configuration is $(s, \sqcup w)$.

Define $M(w) = z$ iff $(s, \sqcup w) \vdash_M^* (h, \sqcup z)$.

Let $\Sigma' \subseteq \Sigma$ be M 's *output alphabet* (i.e., the set of symbols that M may leave on its tape when it halts)

Let f be any function from Σ^* to Σ'^* .

M **computes** f iff for all $w \in \Sigma^*$, $M(w) = f(w)$.

A function f is **recursive** or **computable** iff there is a Turing machine M that computes it.

(Note that M always halts.)

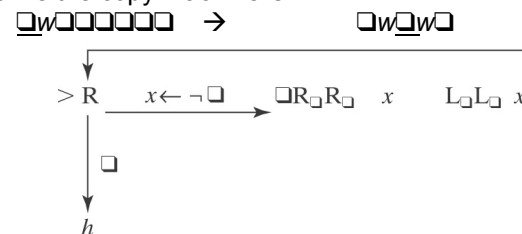
Example of Computing a Function

Let $\Sigma = \{a, b\}$. Let $f(w) = ww$.

Input: $\sqcup w \sqcup \sqcup \sqcup \sqcup \sqcup \sqcup \sqcup$

Output: $\sqcup ww \sqcup$

Define the copy machine C :



Remember the S_{\sqcup} machine:

$\sqcup u \sqcup w \sqcup \rightarrow \sqcup uw \sqcup$

Then the machine to compute f is just $>C S_{\sqcup} L_{\sqcup}$

Computing Numeric Functions

For any positive integer k , $value_k(n)$ returns the nonnegative integer that is encoded, base k , by the string n .

For example:

- $value_2(101) = 5$.
- $value_8(101) = 65$.

TM M computes a function f from \mathbb{N}^m to \mathbb{N} iff, for some k :

$$value_k(M(n_1; n_2; \dots n_m)) = f(value_k(n_1), \dots value_k(n_m)).$$

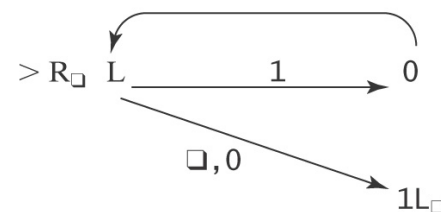
Computing Numeric Functions

Example: $succ(n) = n + 1$

We will represent n in binary. So $n \in 0 \cup 1\{0, 1\}^*$

Input: $\sqcup n \sqcup \sqcup \sqcup \sqcup \sqcup \sqcup \sqcup$
 $\sqcup 1111 \sqcup \sqcup \sqcup \sqcup \sqcup \sqcup \sqcup$

Output: $\sqcup n+1 \sqcup$
 Output: $\sqcup 10000 \sqcup$



Not All Functions Are Computable

Let T be the set of all TMs that:

- Have tape alphabet $\Gamma = \{\square, 1\}$, and
- Halt on a blank tape.

Define the **busy beaver functions** $S(n)$ and $\Sigma(n)$:

- $S(n)$: the maximum number of steps that are executed by any element of T with n -nonhalting states, when started on a blank tape, before it halts.
- $\Sigma(n)$: the maximum number of 1's left on the tape by any element of T with n -nonhalting states, when it halts.

n	$S(n)$	$\Sigma(n)$
1	1	1
2	6	4
3	21	6
4	107	13
5	$\geq 47,176,870$	4098
6	$\geq 3 \cdot 10^{1730}$	$\geq 1.29 \cdot 10^{865}$

Why Are We Working with Our Hands Tied Behind Our Backs?

Turing machines

Are more powerful than any of the other formalisms we have studied so far.



Turing machines

Are a **lot** harder to work with than all the real computers we have available.



Why bother?

The very simplicity that makes it hard to program Turing machines makes it possible to reason formally about what they can do. If we can, once, show that anything a real computer can do can be done (albeit clumsily) on a Turing machine, then we have a way to reason about what real computers can do.