

# Package ‘optimise2’

April 13, 2015

**Type** Package  
**Title** optim corrections.  
**Version** 1.0  
**Date** 2014-04-17  
**Author** Yifan Yang  
**Maintainer** Yifan Yang <yifan.yang@uky.edu>  
**Description** The rule used here is gsl\_min\_fminimizer\_quad\_golden with more than one guess. Constrained (linear/equal region ) MLE.  
**License** GPL  
**Depends** Rcpp (>= 0.10.2), RcppGSL, quadprog  
**NeedsCompilation** yes

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optimise2-package	<i>Optimization in one dimensional problem.</i>
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## Description

Minimizer: gsl\_min\_fminimizer\_quad\_golden This is a variant of Brent’s algorithm which uses the safeguarded step-length algorithm of Gill and Murray.

## Details

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License: GPL2

The usage is exactly the same as `optimise(stats)` unless you want to enlarge the number of iterations.

### Author(s)

Yifan Yang

Maintainer: Yifan Yang <yifan.yang@uky.edu>

### References

Richard Brent, Algorithms for minimization without derivatives, Prentice-Hall (1973), republished by Dover in paperback (2002), ISBN 0-486-41998-3.

### See Also

`optimise`

### Examples

```
f <- function(x) sin(x^2) + x/10
optimise(f, c(1, 4), tol = 1e-06)
optimise(f, c(1.5, 11)) # WRONG!!!
optimise2(f, c(1.5, 11), tol = 1e-06)
```

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lmcholsolve

*lmcholsolve*

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### Description

This function solves

$$H\beta = y$$

, where  $H \succeq 0$ ;

### Usage

```
lmcholsolve(x, y)
```

### Arguments

x	Must be a numeric matrix: integer matrix are NOT allowed.
y	Response variable

### Details

Considering:

$$H\beta = y$$

, in each iteration newton's scalar is

$$\beta_{LSE}$$

. The fastest algorithm is 'sweeping method'/Cholesky Decomposition. The main reason is that:  $H \succeq 0$ . If we tend not to check the condition, then

$$H = LL^T$$

, where  $L$  is low tri-angle matrix. Hence we derive

$$[H, y]^T [H, y] = \begin{pmatrix} L & 0 \\ l^T & d \end{pmatrix} \times \begin{pmatrix} L^T & l \\ 0 & d \end{pmatrix}$$

and

$$Ll = H^T y, L^T \beta = l, d^2 = \|y - \hat{y}\|_{\ell_2}^2$$

The performance could be found in inst/doc.

## Value

beta                      The estimations.

Convergences      Number of non-zero diag-elements.

### Note

tol=1e-9 in Cholesky decomposition.

**Author(s)**

Yifan Yang

## References

Lange, Kenneth. Numerical analysis for statisticians. chap 7. Springer, 2010.

## Examples

```
x <- matrix(runif(100), 10)
y = rnorm(10) * 2
x <- t(x) %*% x
lmcholsolve(x, y)
solve(x, y)
```

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lmconst	<i>LSE with equal constraint</i>
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### Description

$$Y = X\beta \text{ with } x_0\beta = y_0 \text{ constraint.}$$

## Usage

$$\text{lmconst}(y, x, x_0, y_0)$$

## Arguments

y	length n vector: response Variable
x	n by p matrix: corresponding Variables
x0	p by 1 matrix: constraint beta coef
y0	length l vector: value to constraints

**Details**

Use quadratic programming.

**Value**

coef                      Constraint LSE/MLE(Normal assumption ).

**Note**

The function will only output the coefficients.

**Author(s)**

Yifan Yang

**References**

Richard Brent, Algorithms for minimization without derivatives, Prentice-Hall (1973), republished by Dover in paperback (2002), ISBN 0-486-41998-3.

**Examples**

```
# Example 1: dim =1
x=seq( 0,10,0.1)
y = matrix( 6*x+7+runif( 101,min=-1,max=1) ,ncol=1)
x=matrix( x,ncol=1)
re = lmconst( y,x,2,19)
re
re[ 1] +2*re[ 2]

# Example 2: multi dim
# R CMD check will skip %...
#x = matrix(runif(100),ncol=2)
#y = x %*% c(6,2) +1 + rnorm( 50)
#re = lmconst(y=y,x=x,x0=c(2,1),y0=15)
#re
#re[1] +2*re[2] +re[ 3]
```

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optimise2

*OPTIMISE2*

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**Description**

One-dimensional optimization problem.

**Usage**

```
optimise2(f, interval, ..., lower = min(interval), upper = max(interval),
          maximum = FALSE, tol = .Machine$double.eps^0.25, initials = runif(1, lower,
          upper), trace = F, maxit = 100)
```

**Arguments**

<code>f</code>	target function
<code>interval</code>	Interval used to identify the optimization problem, can't be inf!
<code>...</code>	Other parameters used by <code>f</code> .
<code>lower</code>	Lower bound of the interval.
<code>upper</code>	Upper bound of the interval.
<code>maximum</code>	Max number of iterations performed.
<code>tol</code>	$ a - b  < \text{tol} + \text{epsrel} \min( a ,  b )$ . <code>epsrel=0</code> is my case.
<code>initials</code>	Testing, no use right now.
<code>trace</code>	Testing, no use right now.
<code>maxit</code>	Max number of simulations used.

**Details**

Minimizer: `gsl_min_fminimizer_goldensection` The golden section algorithm is the simplest method of bracketing the minimum of a function. It is the slowest algorithm provided by the library, with linear convergence.

On each iteration, the algorithm first compares the subintervals from the endpoints to the current minimum. The larger subinterval is divided in a golden section (using the famous ratio  $(3 - \sqrt{5})/2 = 0.3189660\dots$ ) and the value of the function at this new point is calculated. The new value is used with the constraint  $f(a') > f(x') < f(b')$  to select a new interval containing the minimum, by discarding the least useful point. This procedure can be continued indefinitely until the interval is sufficiently small. Choosing the golden section as the bisection ratio can be shown to provide the fastest convergence for this type of algorithm.

Minimizer: `gsl_min_fminimizer_brent` The Brent minimization algorithm combines a parabolic interpolation with the golden section algorithm. This produces a fast algorithm which is still robust.

The outline of the algorithm can be summarized as follows: on each iteration Brent's method approximates the function using an interpolating parabola through three existing points. The minimum of the parabola is taken as a guess for the minimum. If it lies within the bounds of the current interval then the interpolating point is accepted, and used to generate a smaller interval. If the interpolating point is not accepted then the algorithm falls back to an ordinary golden section step. The full details of Brent's method include some additional checks to improve convergence.

Minimizer: `gsl_min_fminimizer_quad_golden` This is a variant of Brent's algorithm which uses the safeguarded step-length algorithm of Gill and Murray.

Notice that, in original `optimise(stats)`, the condition " $f(a') > f(x') < f(b')$ " will not be checked.

**Value**

<code>maximum</code>	Optimization point.
<code>minimum</code>	Optimization point.
<code>objective</code>	Function value.

**Note**

The function will ignore the discontinuous points.

**Author(s)**

Yifan Yang

**References**

Richard Brent, Algorithms for minimization without derivatives, Prentice-Hall (1973), republished by Dover in paperback (2002), ISBN 0-486-41998-3.

**Examples**

```
f <- function(x) sin(x^2) + x/10
optimise(f, c(1, 4), tol = 1e-06)
optimise(f, c(1.5, 11)) #WRONG
optimise2(f, c(1.5, 11), tol = 1e-06)
```

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