

STAT 7330  
Final Project

# Change-point Detection for Financial Markets Using Bayesian Inference

Yanghong Guo  
yxg190031@utdallas.edu

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Simulation Data Analysis

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Reference



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- ▶ Cryptocurrencies including Bitcoin have become an important investment instrument in the recent years from 2016. But this market fluctuates frequently.



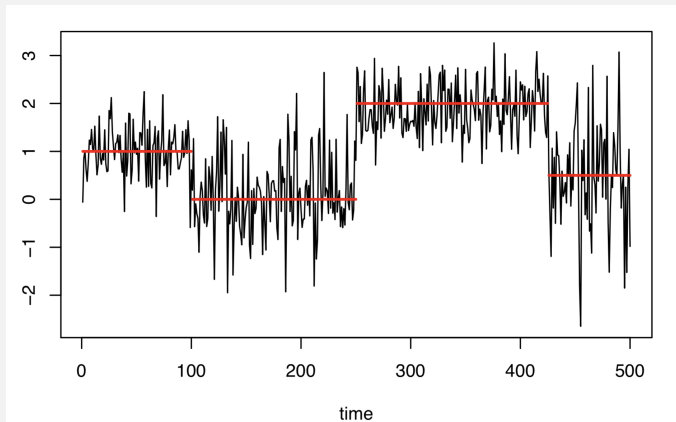
- ▶ Financial markets have long been in the spotlight. A lot of researchers come up with methods to forecast upcoming market volatility and make investment decisions accordingly.
- ▶ There were several significant market movements in the history. The famous one being 2008 credit crisis.
- ▶ Cryptocurrencies including Bitcoin have become an important investment instrument in the recent years from 2016. But this market fluctuates frequently.
- ▶ This project focuses on the change-point detection problems in the financial markets, i.e., stock market and cryptocurrency market.

# Methods for Change-points Detection

## Two Commonly Used Methods



Many time series are characterised by abrupt changes in structure. We consider change-points as time points that divides a data set into several distinct homogeneous segments.



# Methods for Change-points Detection

## Two Commonly Used Methods



Numbers of methods have been developed to solve change-point detection problems, and Bayesian Inference is widely used in those methods.

There are two main Bayesian approaches as to solve change-point detection problems when the total number of segments is unknown:



# Methods for Change-points Detection

## Two Commonly Used Methods



Numbers of methods have been developed to solve change-point detection problems, and Bayesian Inference is widely used in those methods.

There are two main Bayesian approaches as to solve change-point detection problems when the total number of segments is unknown:

- ▶ Classical Dirichlet process modeling.
- ▶ Designed Bayesian fusion modeling.



In this work, we consider the following Gaussian mean problem:

$$y_i = \theta_i + \epsilon_i$$

where  $\epsilon_i$ 's are iid normal error with unknown variance  $\sigma^2$ . Suppose we have in total  $n$  data points in the time series, i.e.,  $i = 1, 2, 3, \dots, n$ , and we aim at finding a partition  $\{B_1, \dots, B_s\}$  of  $\{1, \dots, n\}$  such that  $\theta_i$ 's are constant for all  $i \in B_k$ .

Since the number of blocks  $s$  with the partition is unknown, it can be treated as a clustering problem. The estimated  $\theta_i^*$ ,  $i = 2, \dots, n$ , could be clustered by the criteria  $I(|\theta_{i+1}^* - \theta_i^*| \leq c)$ , where  $c$  is a chosen critical value. We assume that  $\theta_i$  is a constant within each block, and differs between blocks.



There are multiple choices for the prior in this problem, such as **Laplace shrinkage prior, spike-and-slab shrinkage prior, Horseshoe shrinkage prior, and t-shrinkage prior.**

In this paper, we only consider Horseshoe shrinkage prior and t-shrinkage prior. These two have an advantage over the others, that thanks to the heavier tail of the distribution, the estimated  $\theta_i^*$  tends to be less smooth, and the blocks are more distinguishable.



The t-shrinkage prior specification is

$$\begin{aligned}\theta_1 | \sigma^2 &\sim N(0, \lambda_0 \sigma^2) \\ (\theta_i - \theta_{i-1}) | \sigma^2 &\stackrel{\text{ind}}{\sim} t_\nu(m \sigma^2), \text{ for } i = 2, \dots, n-1 \\ \sigma^2 &\sim IG(a_\sigma, b_\sigma)\end{aligned}$$

where  $\lambda_0$ ,  $a_\sigma$ ,  $b_\sigma$  are positive hyperparameters, and  $t_\nu(\xi)$  denotes a  $t$ -distribution with  $\text{df} = \nu$  and scale parameter  $\xi$ . Since the  $t$ -distribution can be expressed as a Normal-scale mixture with inverse Gamma, we can rewrite the prior as

$$\begin{aligned}\theta_1 | \sigma^2 &\sim N(0, \lambda_0 \sigma^2) \\ (\theta_i - \theta_{i-1}) | \sigma^2 &\stackrel{\text{ind}}{\sim} N(0, \lambda_i \sigma^2), \text{ for } i = 2, \dots, n-1 \\ \lambda_i &\stackrel{\text{ind}}{\sim} IG(a_t, b_t), \text{ for } i = 2, \dots, n-1 \quad \sigma^2 \sim IG(a_\sigma, b_\sigma)\end{aligned}$$

where hyperparameters  $a_t$  and  $b_t$  satisfy  $\nu = 2a_t$  and  $m = \sqrt{b_t/a_t}$ . Here  $m$  is chosen so as to satisfy  $P(|t_\nu(m)|) \geq \sqrt{\log(n)/n} \approx n^{-1}$

# Methods With Designed Prior

t-shrinkage prior - Posterior Distribution



Given the Gaussian likelihood and prior specification, the conditional posterior distribution of the parameters of interest are in closed form and be estimated by Gibbs sampling.

$$\lambda_i | \cdot \sim IG(a_t + \frac{1}{2}, b_t + \frac{(\theta_i - \theta_{i-1})^2}{2\sigma^2}), i = 2, \dots, n$$

$$\sigma^2 | \cdot \sim IG(a_\sigma + n, b_\sigma + \frac{\theta_1^2}{2\lambda_0} + \|y - \theta\|_2^2 + \sum_{i=2}^n \frac{(\theta_i - \theta_{i-1})^2}{2\lambda_i})$$

$$\theta_i | \cdot \sim N(\mu_i, \nu_i), i = 1, \dots, n$$

where

$$\nu_i^{-1} = \frac{1}{\sigma^2} \left(1 + \frac{1}{\lambda_i} + \frac{1}{\lambda_{i+1}}\right), \quad \mu_i = \frac{\nu_i}{\sigma^2} \left(y_i + \frac{\theta_{i-1}}{\lambda_i} + \frac{\theta_{i+1}}{\lambda_{i+1}}\right), \quad i = 2, \dots, n-1$$

$$\nu_1^{-1} = \frac{1}{\sigma^2} \left(1 + \frac{1}{\lambda_2}\right), \quad \mu_1 = \frac{\nu_1}{\sigma^2} \left(y_1 + \frac{\theta_2}{\lambda_2}\right)$$

$$\nu_n^{-1} = \frac{1}{\sigma^2} \left(1 + \frac{1}{\lambda_n}\right), \quad \mu_n = \frac{\nu_n}{\sigma^2} \left(y_1 + \frac{\theta_{n-1}}{\lambda_n}\right)$$



The Horseshoe shrinkage prior specification is

$$\begin{aligned}\theta_1 | \lambda_1^2, \sigma^2 &\sim N(0, \lambda_1^2 \sigma^2) \\ \eta_i | \lambda_1^2, \tau^2, \sigma^2 &\stackrel{\text{ind}}{\sim} N(0, \lambda_i^2 \tau^2 \sigma^2), i = 2, \dots, n \\ \lambda_i^2 | \nu_i &\stackrel{\text{ind}}{\sim} IG(1/2, 1/\nu_i), i = 2, \dots, n \\ \tau^2 | \xi &\sim IG(1/2, 1/\xi) \\ \nu_2, \dots, \nu_n, \xi &\stackrel{\text{ind}}{\sim} IG(1/2, 1) \\ \sigma^2 &\sim IG(a_\sigma, b_\sigma)\end{aligned}$$

The hyperparameters  $a_\sigma$  and  $b_\sigma$  can be chosen in such a way that the corresponding prior becomes non-informative. The local scale parameter  $\lambda_1$  is considered to be fixed as well.

# Methods With Designed Prior

Horseshoe shrinkage prior - Posterior distributions



The conditional posteriors for the rest of the parameters are given by

$$\lambda_i^2 | \cdot \sim IG(1, \frac{1}{\nu_i} + \frac{(\theta_i - \theta_{i-1})^2}{2\tau^2\sigma^2}), i = 2, \dots, n$$

$$\sigma^2 | \cdot \sim IG(n + a_\sigma, b_\sigma + \frac{1}{2} [\|y - \theta\|_2^2 + \frac{1}{\tau^2} \sum_{i=2}^n \frac{(\theta_i - \theta_{i-1})^2}{\lambda_i^2} + \frac{\theta_1^2}{\lambda_1^2}])$$

$$\tau^2 | \cdot \sim IG(\frac{n}{2}, \frac{1}{\xi} + \frac{1}{2\sigma^2} \sum_{i=2}^n \frac{(\theta_i - \theta_{i-1})^2}{\lambda_i^2})$$

$$\nu_i | \cdot \sim IG(1, 1 + \frac{1}{\lambda_i^2}), i = 2, \dots, n$$

$$\xi | \cdot \sim IG(1, 1 + \frac{1}{\tau^2})$$

By Gibbs sampler, we would generate MCMC samples for each parameter and associated hyperparameters.

# Simulation Data Analysis

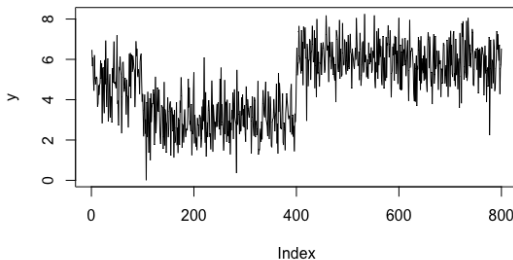


The first set of data was generated from three normal distributions with different mean values and same variance  $\sigma = 1$ .

$$y1 \sim N(5, 1), n1 = 100$$

$$y2 \sim N(3, 1), n2 = 300$$

$$y3 \sim N(6, 1), n3 = 400$$





# Simulation Data Analysis

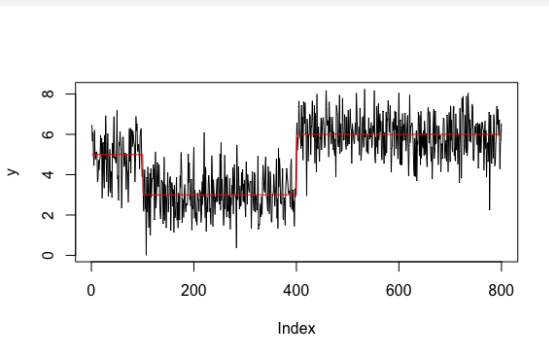


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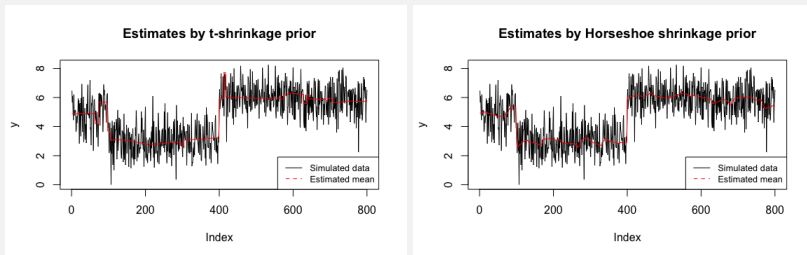
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Let's see how these two priors perform on this simulated data set.



**Figure:** The performance of two priors on the first simulated data set.

We can see compared with Horseshoe prior, there are some undesired jumps in the figure of performance of t-shrinkage prior. Horseshoe prior performs a more stable and smooth estimation in this case.

# Simulation Data Analysis

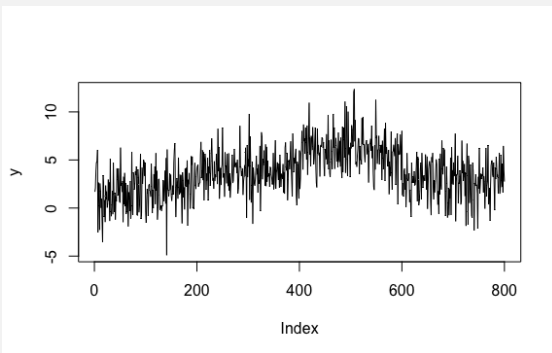


For the second set of simulated data, we increase the variance to  $\sigma = 2$ , and narrow the 'time interval' for each block.

$$y_1 \sim N(2, 4), \quad n_1 = 200 \quad y_2 \sim N(4, 4), \quad n_2 = 200$$

$$y_3 \sim N(6, 4), \quad n_3 = 200 \quad y_3 \sim N(3, 4), \quad n_3 = 200$$

The simulated data is



# Simulation Data Analysis

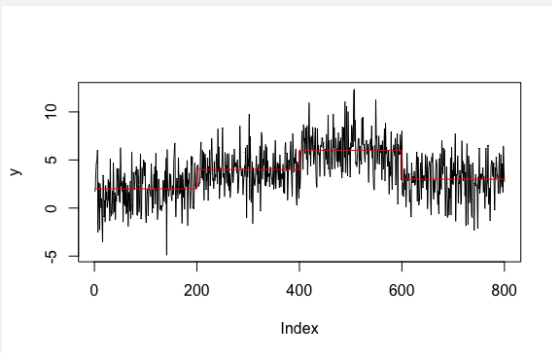


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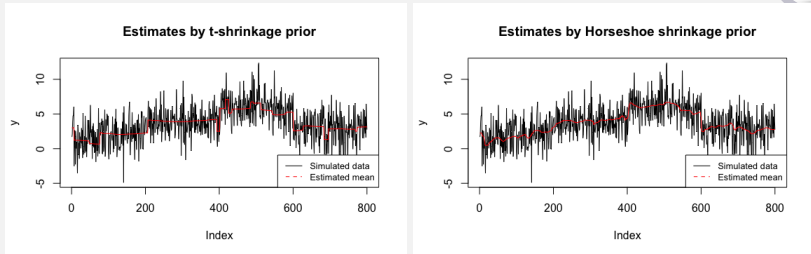
$$y1 \sim N(2, 2), n1 = 200 \quad y2 \sim N(4, 2), n2 = 200$$

$$y3 \sim N(6, 2), n3 = 200 \quad y3 \sim N(3, 2), n3 = 200$$

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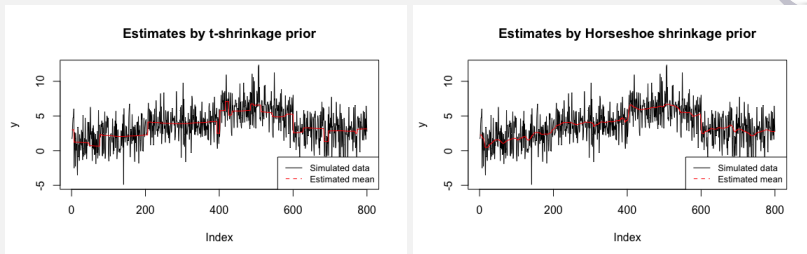


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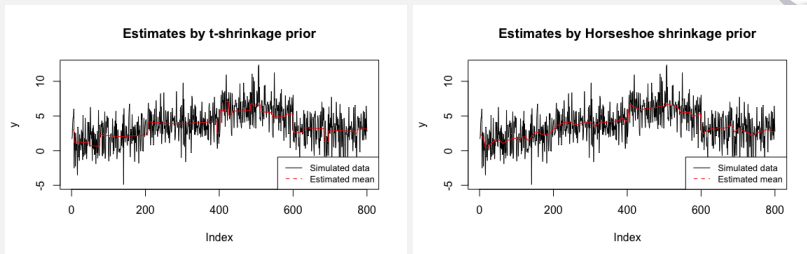
**Figure:** The performance of two priors on the second simulated data set.

# Simulation Data Analysis



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The Horseshoe shrinkage prior generates a smooth estimation, while the result of t-shrinkage prior is more discrete. We can see in this case the t-shrinkage prior outperforms the horseshoe shrinkage prior.



**Figure:** The performance of two priors on the second simulated data set.

The Horseshoe shrinkage prior generates a smooth estimation, while the result of t-shrinkage prior is more discrete. We can see in this case the t-shrinkage prior outperforms the horseshoe shrinkage prior.

In the real world, the stock market has a high volatility from its unstable nature, and the difference of mean values between blocks is not that distinguishable, so we can deduce that t-shrinkage prior will have a better performance when applying to real financial data set.



- ▶ We consider the change-point detection problem in the cumulative returns of two different markets in two different time periods, one for the Dow Jones Industrial Average (DJI) and the other for Bitcoin returns against USD (BTC). We carefully choose the two different time periods so as to include the known market crash or thrive phenomena.





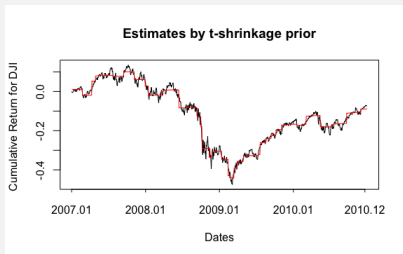
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- ▶ The time period that we choose to study DJI is from January 2007 to Dec 2010, that encompasses the 2008 Recession and the following recovery.
- ▶ The time period we choose to study BTC is from Jun 2018 to Jun 2020, that encompasses the main crash of Bitcoin in 2019 and the following recovery.

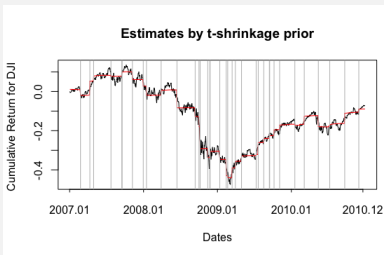
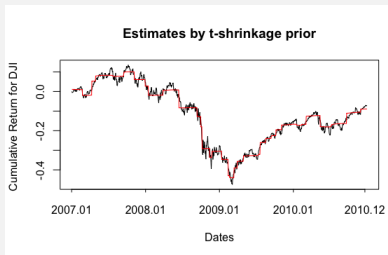
# Real Data Analysis

DJI - t-shrinkage prior



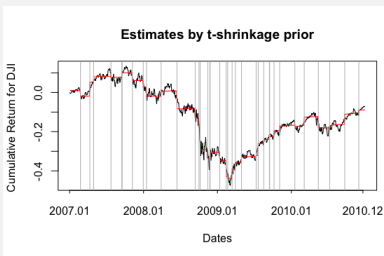
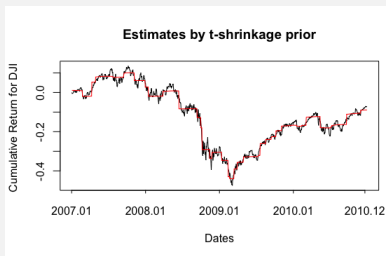
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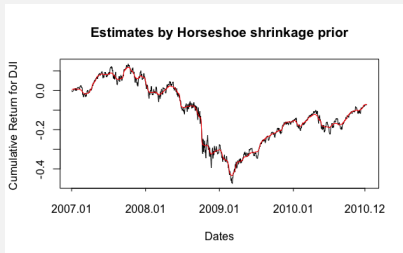
DJI - t-shrinkage prior



The criteria we applied to define a change-point is by  $I(|\theta_j^* - \theta_j^*| \leq c)$ , and the value  $c$  is chosen to be  $c = \hat{\sigma} m t_{1/2n}$ , where  $\hat{\sigma}$  is the Bayesian estimates of  $\sigma$  given by the posterior mean, and  $t_{1/2n}$  is the  $(1 - 1/2n)$ -quantile of a  $t$  distribution with  $2a_t$  degrees of freedom.

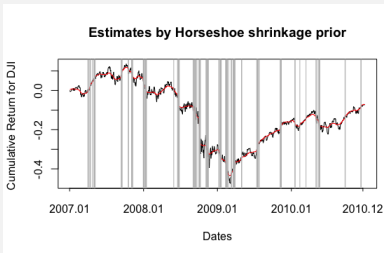
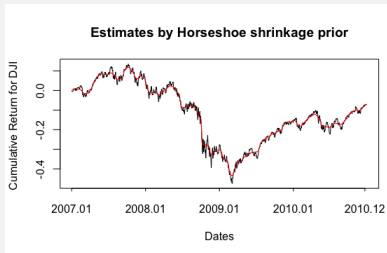
# Real Data Analysis

DJI - Horseshoe shrinkage prior



# Real Data Analysis

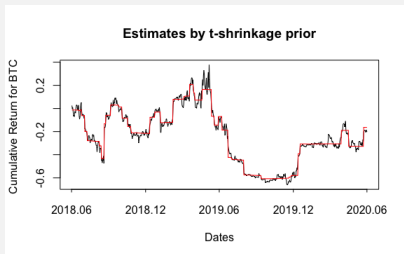
DJI - Horseshoe shrinkage prior



We find that the Horseshoe shrinkage prior method solution suffers from severe over-fitting problems, which is quite different from the solution given by t-shrinkage method that produces almost piecewise constant estimates. It's difficult to locate the change-points in this case.

# Real Data Analysis

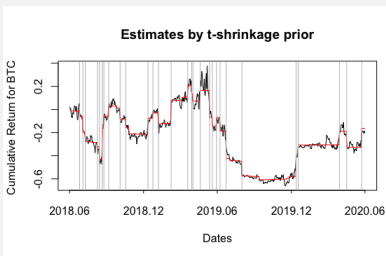
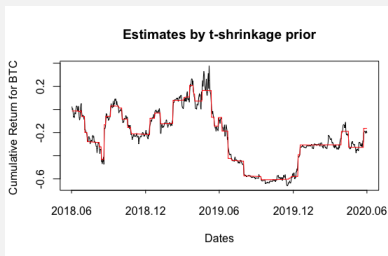
BTC - t-shrinkage prior





# Real Data Analysis

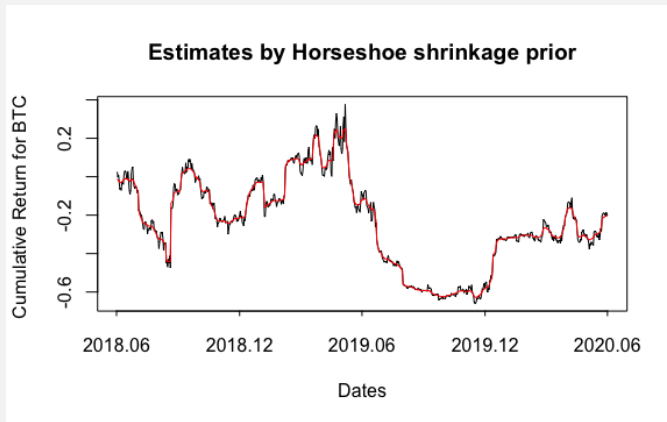
BTC - t-shrinkage prior



Unlike the traditional stock market, the cryptocurrency market fluctuates severe among time. t-shrinkage method successfully captures the most volatility period (2018.6 - 2019.6) and the relatively stable period (2019.6 - 2020.6).

# Real Data Analysis

BTC - Horseshoe shrinkage prior



Horseshoe shrinkage prior method solution again suffers from severe over-fitting problems.



- ▶ Horseshoe shrinkage prior and t-shrinkage prior can both be applied in change-point detection problems.



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- ▶ Horseshoe shrinkage prior and t-shrinkage prior can both be applied in change-point detection problems.
- ▶ Horseshoe shrinkage prior outperforms t-shrinkage prior when the variance of the data is relatively small and the differences between blocks are significant.
- ▶ t-shrinkage prior performs better when the variance of the data is relatively large, and the difference between blocks are insignificant.
- ▶ The data set from financial market such as stocks and cryptocurrencies have a high volatility in nature, thus t-shrinkage fusion model has an overall better perform on these data sets.



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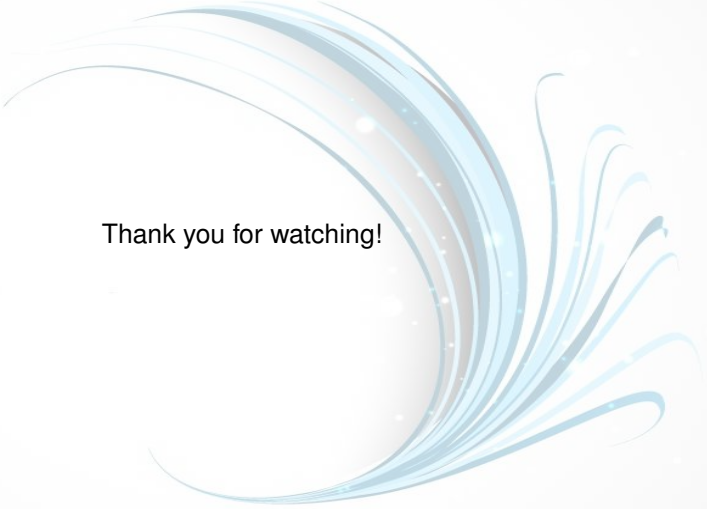
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Thank you for watching!