```
import numpy as np
import pandas as pd
from scipy.stats import norm
import scipy.interpolate as spi
import scipy.sparse as sp
import scipy.linalg as sla
from scipy.sparse.linalg import inv
from scipy.sparse.linalg import spsolve
import scipy.stats as stats
import math
```

We learn about a put option with stock price S = 100, strike price K = 100, interest rate of 0.025, dividend rate of 0, maturity of 0.642 years and volatility of 0.2, which has the following characteristics:

Properties	Symbol	Value
Stock price	S	100
exercise price	K	100
continuous interest rate	r	0.025
continuous dividend rate	q	0
volatility	σ	0.2
years to maturity	T	0.642

```
In [ ]: #init param
        (S, K, r, q, T, sigma, option_type) = (100, 100, 0.025, 0.00, 231 / 360, 0.2, 'p
        (Smin, Smax, Ns, Nt) = (0, 4*np.maximum(S,K), 200, 200)
        class init_option():
            def __init__(self, S, K, r, q, T, sigma, option_type, Smin, Smax, Ns, Nt):
                self.S = S
                self.K = K
                self.r = r
                self.q = q
                self.T = T
                self.sigma = sigma
                self.option_type = option_type
                self.is_call = (option_type[0].lower()=='c')
                self.omega = 1 if self.is_call else -1
                self.Smin = Smin
                self.Smax = Smax
                self.Ns = int(Ns)
                self.Nt = int(Nt)
                self.dS = (Smax-Smin)/Ns * 1.0
                self.dt = T/Nt*1.0
                self.Svec = np.linspace(Smin, Smax, self.Ns+1)
                self.Tvec = np.linspace(0, T, self.Nt+1)
                self.grid = np.zeros(shape=(self.Ns+1, self.Nt+1))
```

```
def _set_terminal_condition_(self):
    self.grid[:, -1] = np.maximum(self.omega*(self.Svec - self.K), 0)
def _set_boundary_condition_(self):
   tau = self.Tvec[-1] - self.Tvec;
   DFq = np.exp(-q*tau)
   DFr = np.exp(-r*tau)
    self.grid[0, :] = np.maximum(self.omega*(self.Svec[0]*DFq - self.K*DFr)
    self.grid[-1, :] = np.maximum(self.omega*(self.Svec[-1]*DFq - self.K*DFr
def set coefficient (self):
    drift = (self.r-self.q)*self.Svec[1:-1]/self.dS
    diffusion_square = (self.sigma*self.Svec[1:-1]/self.dS)**2
   self.l = 0.5*(diffusion_square - drift)
    self.c = -diffusion_square - self.r
    self.u = 0.5*(diffusion square + drift)
def _solve_(self):
    pass
def interpolate (self):
    tck = spi.splrep( self.Svec, self.grid[:,0], k=3 )
    return spi.splev( self.S, tck )
   #return np.interp(self.S, self.Svec, self.grid[:,0])
def price(self):
    self. set terminal condition ()
    self. set boundary condition ()
    self._set_coefficient__()
    self._set_matrix_()
    self._solve_()
    return self._interpolate_()
```

Part a Using crank nicolson to price a European put vanilla

Part b Using crank nicolson to price an American put vanilla

```
In [ ]: class CrankNicolsonAm(init_option):
            def __init__(self, S, K, r, q, T, sigma, option_type, Smin, Smax, Ns, Nt, th
                 super().__init__(S, K, r, q, T, sigma, option_type, Smin, Smax, Ns, Nt)
                 self.theta = theta
                self.lbd = lbd
                 self.epsilon = epsilon
                 self.max_iter = 10*Nt
            def set matrix (self):
                 self.A = sp.diags([self.1[1:], self.c, self.u[:-1]], [-1, 0, 1], format=
                self.I = sp.eye(self.Ns-1)
            def _solve_(self):
                 (theta, dt) = (self.theta, self.dt)
                 payoff = self.grid[1:-1, -1]
                 pastval = payoff.copy()
                G = payoff.copy()
                for j in reversed(np.arange(self.Nt)):
                     counter = 0
                     noBreak = 1
                     newval = pastval.copy()
                    while noBreak:
                         counter += 1
                         oldval = newval.copy()
                         D = sp.diags( (G > (1-theta)*pastval + theta*newval).astype(int)
                         z = (self.I + (1-theta)*dt*(self.A - self.lbd*D))*pastval + dt*s
                         z[0] += theta*self.l[0]*dt*self.grid[0, j] \setminus
                         + (1-theta)*self.l[0]*dt*self.grid[0, j+1]
                         z[-1] += theta*self.u[-1]*dt*self.grid[-1, j] \
                          + (1-theta)*self.u[-1]*dt*self.grid[-1, j+1]
                         M = self.I - theta*dt*(self.A - self.lbd*D)
                         newval = spsolve(M,z)
                         noBreak = CrankNicolsonAm.trigger( oldval, newval, self.epsilon,
                     pastval = newval.copy()
                     self.grid[1:-1, j] = pastval
            def trigger( oldval, newval, tol, counter, maxIteration ):
```

```
noBreak = 1
if np.max( np.abs(newval-oldval)/np.maximum(1,np.abs(newval)) ) <= tol:
    noBreak = 0
elif counter > maxIteration:
    print('The results may not converge.')
    noBreak = 0
return noBreak
```

```
In [ ]: (theta, lbd, epsilon) = (0.5, 1e6, 1e-6)
amer_opt = CrankNicolsonAm(S, K, r, q, T, sigma, option_type, Smin, Smax, Ns, Nt
partb_answer=amer_opt.price()
print(partb_answer.round(4))
```

5.6921

The Black-Scholes-Merton PDE:

$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV = 0$$

Approximation of derivative terms:

$$egin{aligned} rac{\partial V}{\partial t} &pprox rac{V_i^{n+1}-V_i^n}{\Delta t} \ & rac{\partial V}{\partial S} pprox rac{V_{i+1}^n-V_{i-1}^n}{2\Delta S} \ & rac{\partial^2 V}{\partial S^2} pprox rac{V_{i+1}^n-2V_i^n+V_{i-1}^n}{\Delta S^2} \end{aligned}$$

Crank-Nicolson method:

$$V_i^{n+1} - V_i^n = rac{\Delta t}{2} \left[\left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{\Delta S^2} + r S_i rac{V_{i+1}^n - V_{i-1}^n}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{\Delta S^2} + r S_i rac{V_{i+1}^n - V_{i-1}^n}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{\Delta S^2} + r S_i rac{V_{i+1}^n - V_{i-1}^n}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{\Delta S^2} + r S_i rac{V_{i+1}^n - V_{i-1}^n}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{\Delta S^2} + r S_i rac{V_{i+1}^n - V_{i-1}^n}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{\Delta S^2} + r S_i rac{V_{i+1}^n - V_{i-1}^n}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{2 \Delta S} - r V_i^n
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ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{2 \Delta S} - r V_i^n
ight) + \left(rac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_{i-1}^n)}{2 \Delta S} - r V_i^n
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ight) + \left(\frac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_i^n)}{2 \Delta S} - r V_i^n
ight) + \left(\frac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_i^n)}{2 \Delta S} - r V_i^n
ight) + \left(\frac{\sigma^2 S_i^2 (V_{i+1}^n - 2 V_i^n + V_i^n)}{2 \Delta S} - r V_i^n$$

Boundary conditions for an up-and-out call option:

$$V = \left\{ egin{aligned} \max(S-K,0), & ext{if } S < B \ 0, & ext{if } S \geq B \end{aligned}
ight.$$

```
In [ ]: def barrier_option_price(S, K, r, q, T, sigma, H):
    # Calculate d1 and d2 parameters
    d1 = (np.log(S / K) + (r - q + 0.5 * sigma ** 2) * T) / (sigma * np.sqrt(T))
    d2 = d1 - sigma * np.sqrt(T)

# Calculate lambda and x1 through y parameters
    lambda_ = (r - q + sigma ** 2) / (sigma ** 2)
    x1 = np.log(S / H) / (sigma * np.sqrt(T)) + lambda_ * sigma * np.sqrt(T)
    y1 = np.log(H / S) / (sigma * np.sqrt(T)) + lambda_ * sigma * np.sqrt(T)
    x2 = np.log(S / H) / (sigma * np.sqrt(T)) - lambda_ * sigma * np.sqrt(T)
    y2 = np.log(H**2 / (S * K)) / (sigma * np.sqrt(T)) + lambda_ * sigma * np.sqrt(T)

# Calculate the price based on the type of barrier option
```

```
price = K * np.exp(-r * T) * (stats.norm.cdf(-y1) - stats.norm.cdf(-y2)) - S
    price += -1 * S * np.exp(-q * T) * (H / S)**(2 * lambda_) * (stats.norm.cdf(
    price -= -1 * K * np.exp(-r * T) * (H / S)**(2 * lambda_ - 2) * (stats.norm.

    return price

# Test the function

H = 80  # Barrier Level

partc_answer = barrier_option_price(S, K, r, q, T, sigma, H)
print("Barrier Option Price:", partc_answer.round(4))
```

Barrier Option Price: 38.8974

According to the BS formula, the analytical solution of the Euclidean option is

$$V = e^{-rT} \cdot E\left[\left[\omega\left(S_T - K
ight)
ight]^+
ight] = \omega \cdot \left[e^{-qT}S_0\Phi(\omega \cdot d_+) - e^{-rT}K\Phi(\omega \cdot d_-)
ight]$$

where

$$d_{\pm} = rac{1}{\sigma\sqrt{T}} \mathrm{ln} igg(rac{S_0 e^{(r-q)T}}{K}igg) \pm rac{\sigma\sqrt{T}}{2}$$

The call option corresponds to $\omega=1$ and the put option corresponds to $\omega=-1$.

Using the BS model the option price is 5.5697 the part a and c answer are 5.5574 38.8974

To calculate the potential stock price movements, we use:

- Up: $S_u = Su$
- Down: $S_d = Sd$
- Flat: $S_m = Sm$

For a put option, the exercise value at each node is calculated as:

Exercise Value =
$$\max(K - S, 0)$$

The discounted expected future value at each node (assuming risk-neutral probabilities p, q, and 1-p-q for up, down, and flat movements respectively) is given by:

Expected Future Value =
$$e^{-r\Delta t} \left[pV_{\rm up} + qV_{\rm down} + (1-p-q)V_{\rm flat} \right]$$

where $V_{
m up}$, $V_{
m down}$, and $V_{
m flat}$ are the option values at the next time step for up, down, and flat movements respectively.

The value of the put option at each node is then the maximum of the exercise value and the discounted expected future value:

$$V = \max\left(K - S, e^{-r\Delta t}\left[pV_{
m up} + qV_{
m down} + (1-p-q)V_{
m flat}
ight]
ight)$$

In the trinomial model, the probabilities p, q, and 1-p-q and the factors u, d, and m are determined using the risk-free rate, the volatility of the stock, and the time step size.

```
In [ ]: def american_trinominal_model(S, T, K, r, q, sigma, call):
            dt = 1. / 360
             N = int(T / dt)
             mu = r - q - (sigma ** 2) / 2.0
             smax = 2 * abs(mu) * dt ** .5
             smax = max(smax, sigma * (2 ** .5))
             if smax == 0:
                 return -9999
             M = int(5 * (N ** .5))
             C_{-} = np.empty(2 * M + 1, dtype=np.float64)
             pC_{=} np.empty(2 * M + 1, dtype=np.float64)
             S_= np.empty(2 * M + 1, dtype=np.float64, )
             p = float(0.5 * (sigma ** 2)) / (smax ** 2)
             p_u = p + 0.5 * mu * dt ** .5 / float(smax)
             p_m = 1 - 2 * p
             p_d = p - 0.5 * mu * dt ** .5 / float(smax)
             D = 1.0 / (1 + r * dt)
             E = math.exp(smax * dt ** .5)
             for j in range(0, len(S_)):
                 if j == 0:
                     S[j] = S * math.exp(-M * smax * dt ** .5)
                    S_{[j]} = S_{[j-1]} * E
                 if call == True:
                    C_{[j]} = \max(S_{[j]} - K, 0)
                 else:
                     C_{[j]} = max(K - S_{[j]}, 0)
             for k in range(0, N):
                 for j in range(1, 2 * M):
                     pC_{[j]} = (p_u * C_{[j+1]} + p_m * C_{[j]} + p_d * C_{[j-1]}) * D
                 pC_[0] = 2 * pC_[1] - pC_[2]
                 pC_[2 * M] = 2 * pC_[2 * M - 1] - pC_[2 * M - 2]
                 for n in range(0, 2 * M + 1):
                     if call == True:
                         C_[n] = max(pC_[n], max(S_[n] - K, 0))
                         C_[n] = max(pC_[n], max(K - S_[n], 0))
             ret = C_[M]
```

```
return ret

partd_answer2=american_trinominal_model(S=S, K=K, r=r, q=q, T=T, sigma=sigma, ca
print("Using the trinominal model the price is",partd_answer2.round(4))
print("The part b price is ", partb_answer.round(4))
```

Using the trinominal model the price is 5.7037 The part b price is 5.6921 e part

Use a Monte Carlo pricer to reconcile with price from part a.

```
In [ ]: def monte_carlo_european_put(S0, K, r, sigma, T, num_simulations):
            np.random.seed(42) # For reproducibility
            num_timesteps = 10
            dt = T / num_timesteps
            total payoff = 0
            for i in range(num simulations):
                S = S0
                for j in range(num_timesteps):
                    z = np.random.standard normal()
                    S *= np.exp((r - 0.5 * sigma**2) * dt + sigma * np.sqrt(dt) * z)
                total_payoff += max(K - S, 0)
            price = np.exp(-r * T) * total_payoff / num_simulations
            return price
        # Parameters from part (a)
        num simulations = 10000
        monte_carlo_price = monte_carlo_european_put(S, K, r, sigma, T, num_simulations)
        print("Monte Carlo European Put price:", monte_carlo_price.round(4))
```

Monte Carlo European Put price: 5.6675