

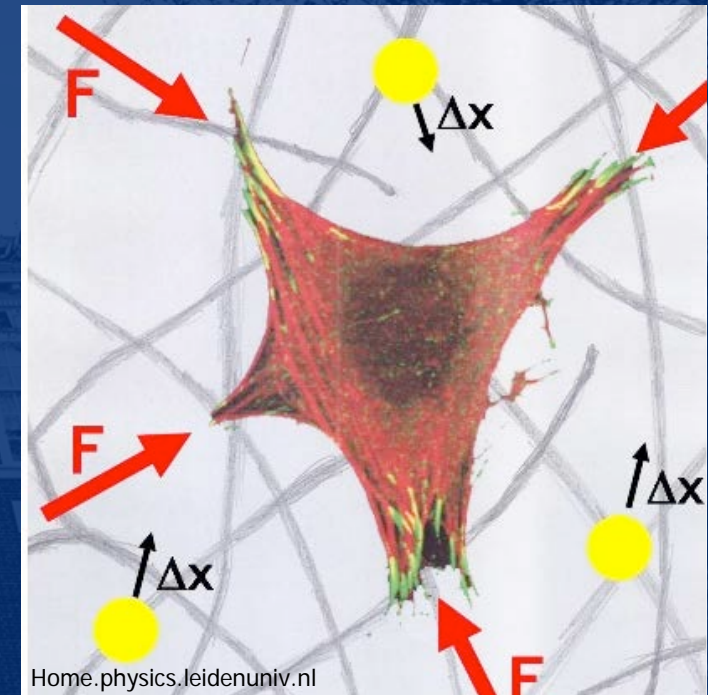


JOHNS HOPKINS

WHITING SCHOOL
of ENGINEERING

Cell and Tissue Engineering

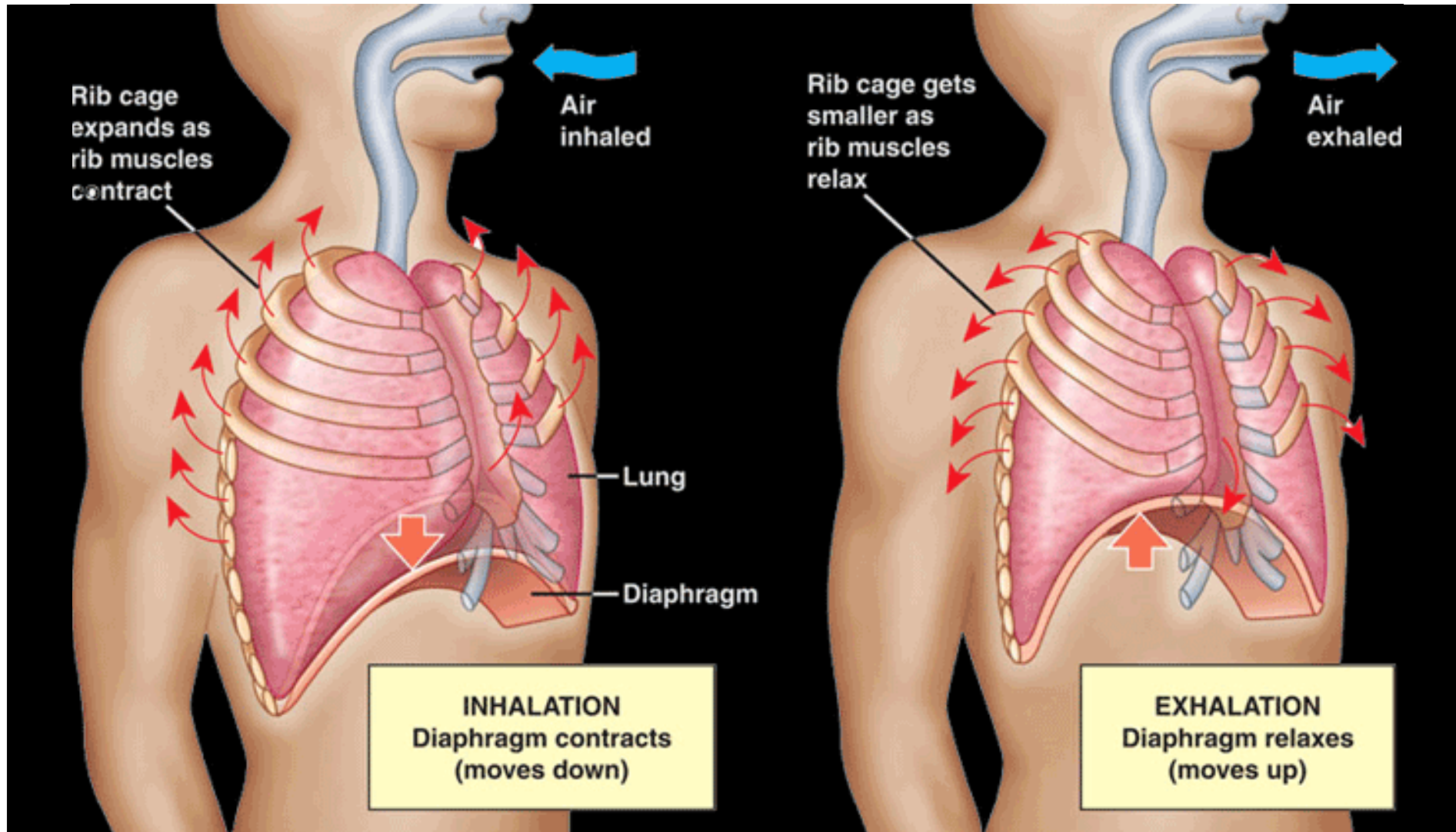
Basic Solid Mechanics

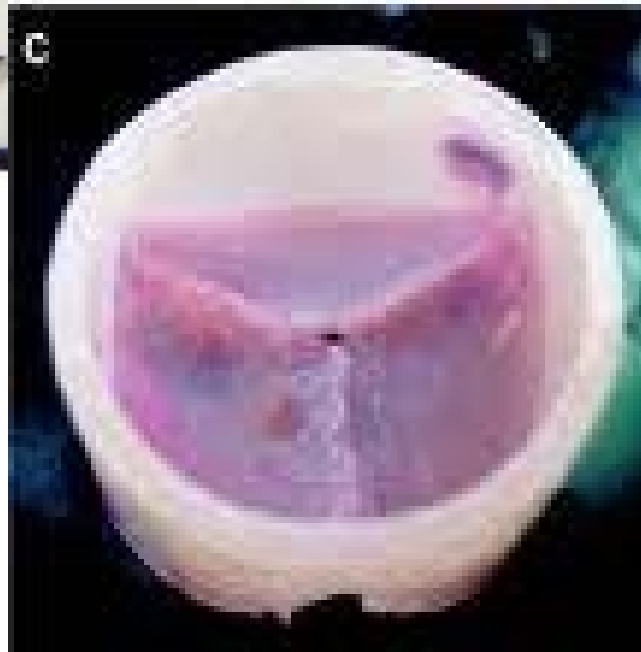




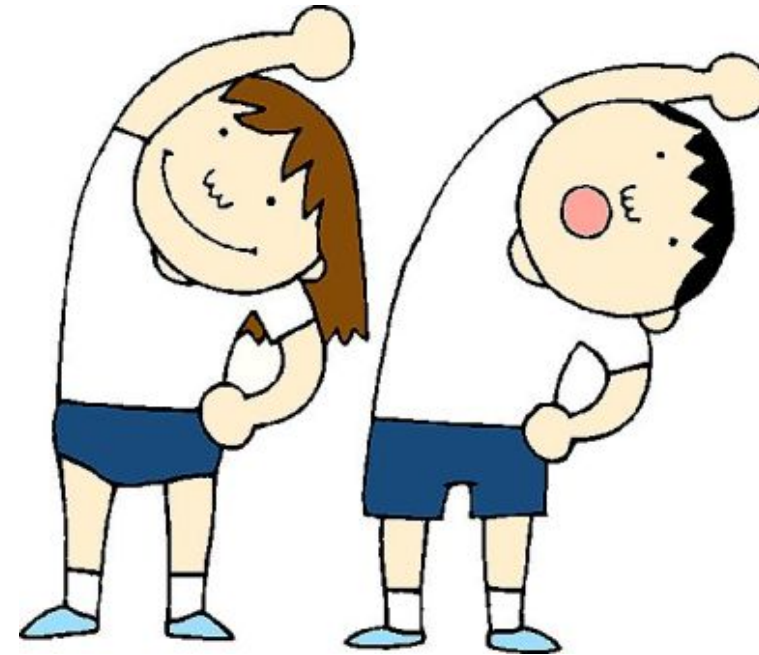
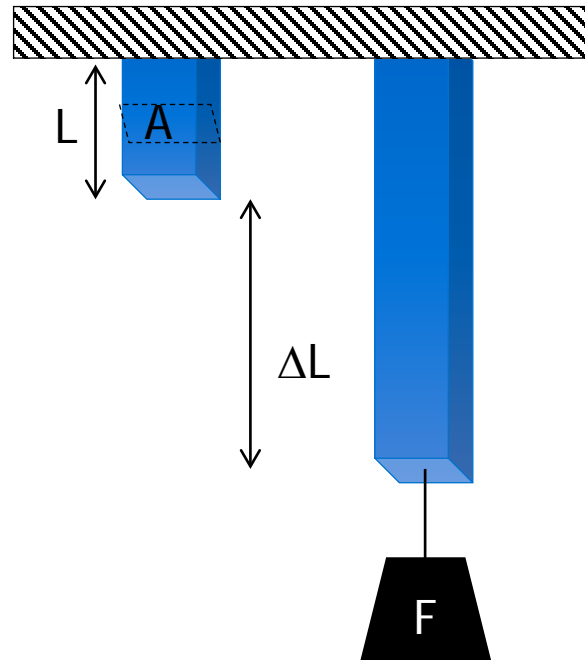
**TAKE A
DEEP BREATH**

Breathing dilates and stretches cells in your lungs

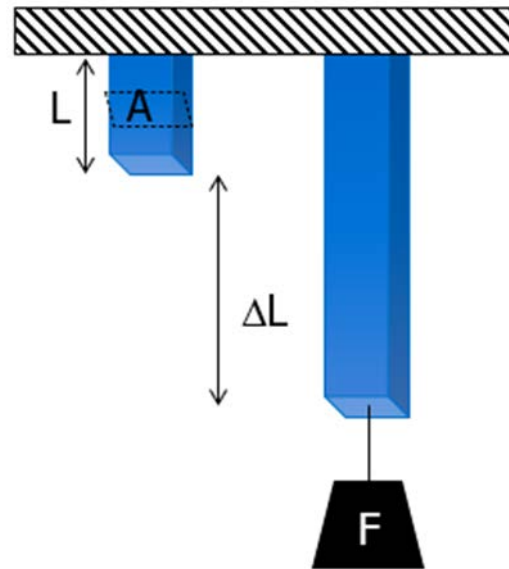




Elementary solid mechanics...

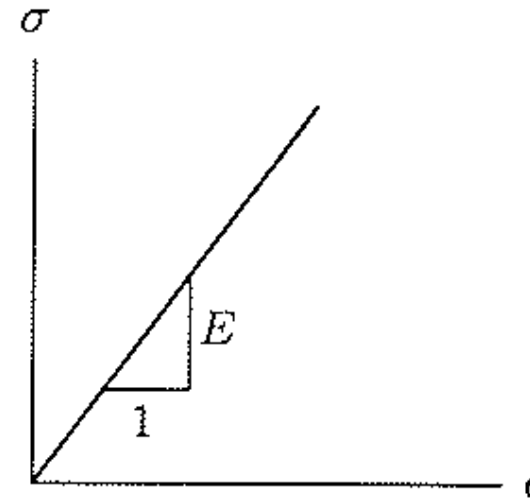


Elastic deformation



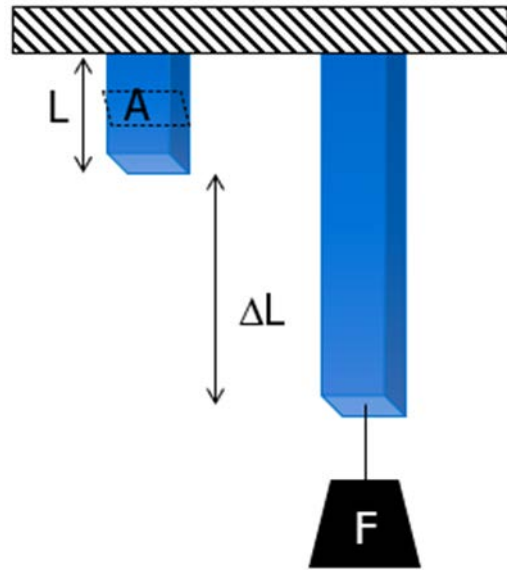
$$\sigma = \frac{F}{A} = E \times \epsilon = \frac{E \times \Delta L}{L}$$

Hooke's Law



σ = stress
 F = force
 A = area
 E = elastic or Young's modulus
 ϵ = strain

Young's modulus is a material property



$$\sigma = \frac{F}{A} = E \times \varepsilon = \frac{E \times \Delta L}{L}$$

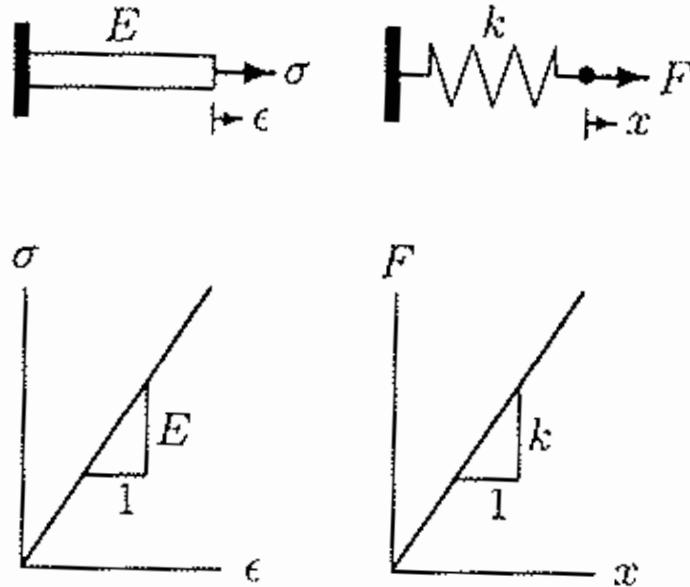
Hooke's Law

E = Elastic/Young's modulus

Material	Modulus (MPa)
Long bone	15-30,000
Skull bone	6,500
cartilage	1-10
tendon	1-2,000
skin	0.1-2
brain	0.067
polystyrene	2,300-3,300
Stainless steel	210,000

Elastic materials behave as springs

$$\sigma = E\varepsilon \quad F = kx$$



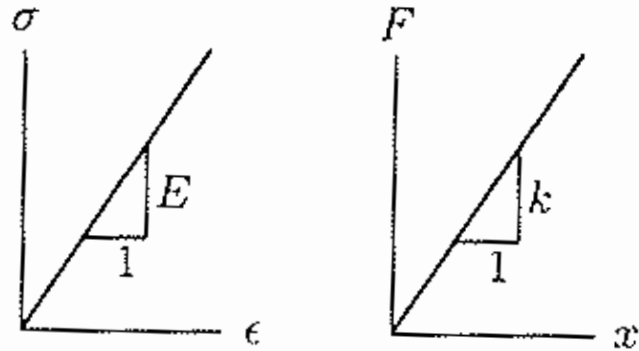
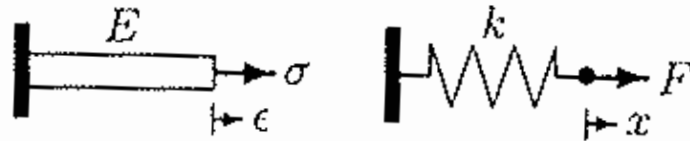
σ = stress
 E = elastic or Young's modulus
 ε = strain
 F = force
 x = displacement
 k = spring constant

$$\sigma = \frac{F}{A} = E \times \varepsilon = \frac{E \times \Delta L}{L}$$

Hooke's Law

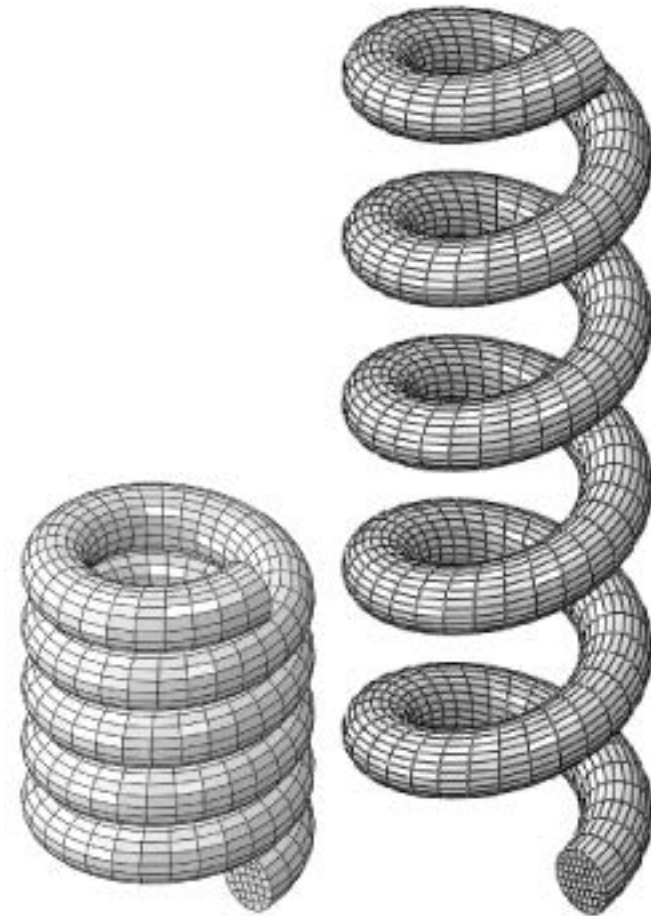
Elastic materials behave as springs (cont.)

$$\sigma = E\varepsilon \quad F = kx$$



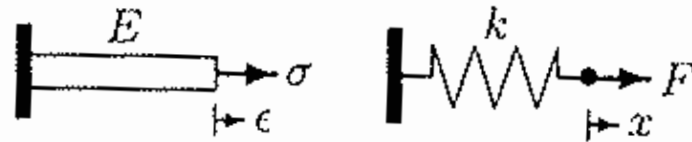
$$\sigma = \frac{F}{A} = E \times \varepsilon = \frac{E \times \Delta L}{L}$$

Hooke's Law

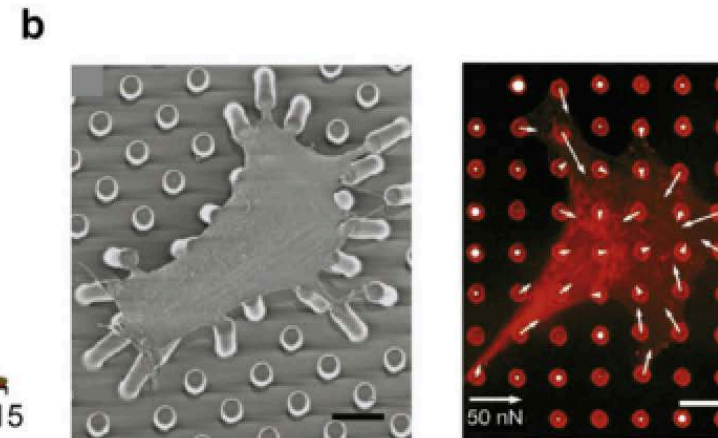
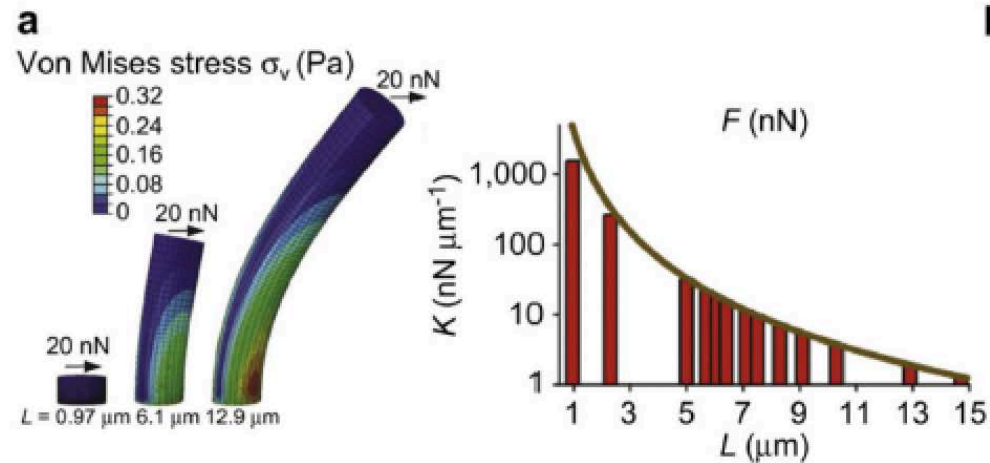


Elastic materials behave as springs (cont.)

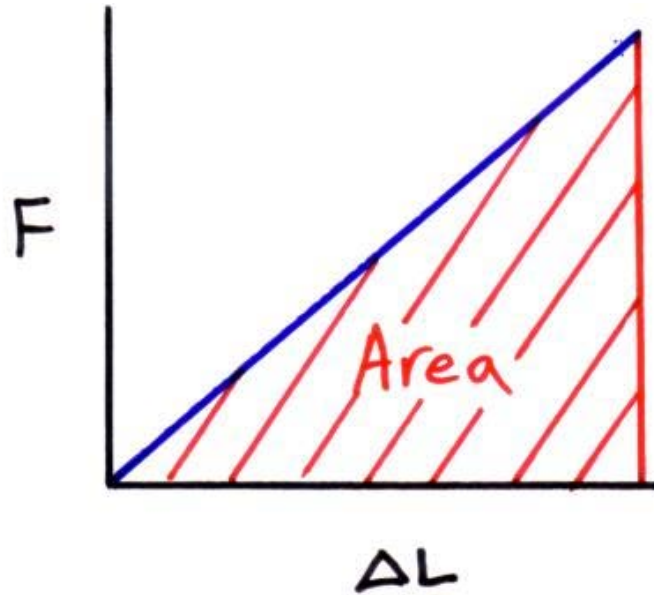
$$\sigma = E\varepsilon \quad F = kx$$



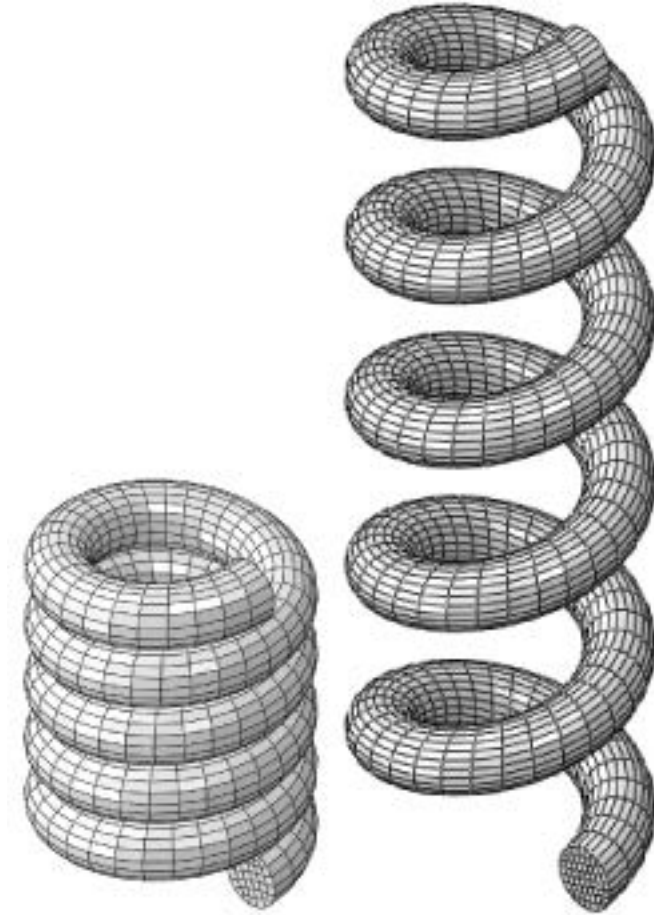
$$F = k \cdot \Delta x = \left(\frac{3}{4} \pi E \frac{r^4}{L^3} \right) \cdot \Delta x$$



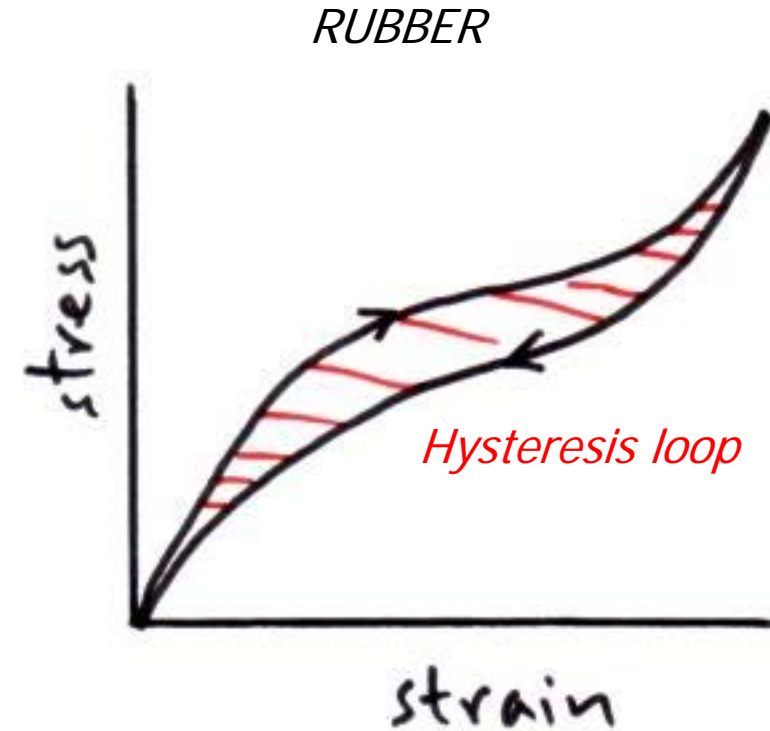
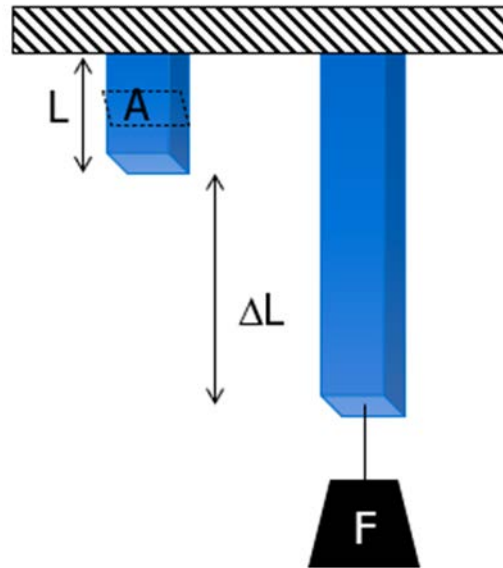
Elastic materials behave as springs (cont.)



Strain Energy $\frac{F \cdot \Delta L}{2} = \frac{\sigma \cdot \varepsilon}{2}$



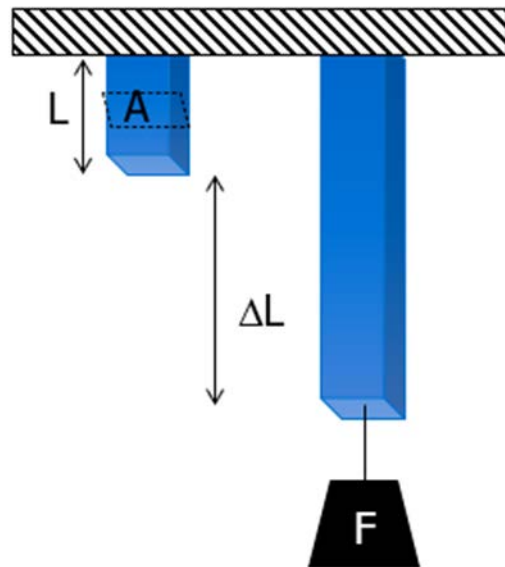
Materials can be elastic and NOT obey Hooke's law!



$$\sigma = \frac{F}{A} = E \times \varepsilon = \frac{E \times \Delta L}{L}$$

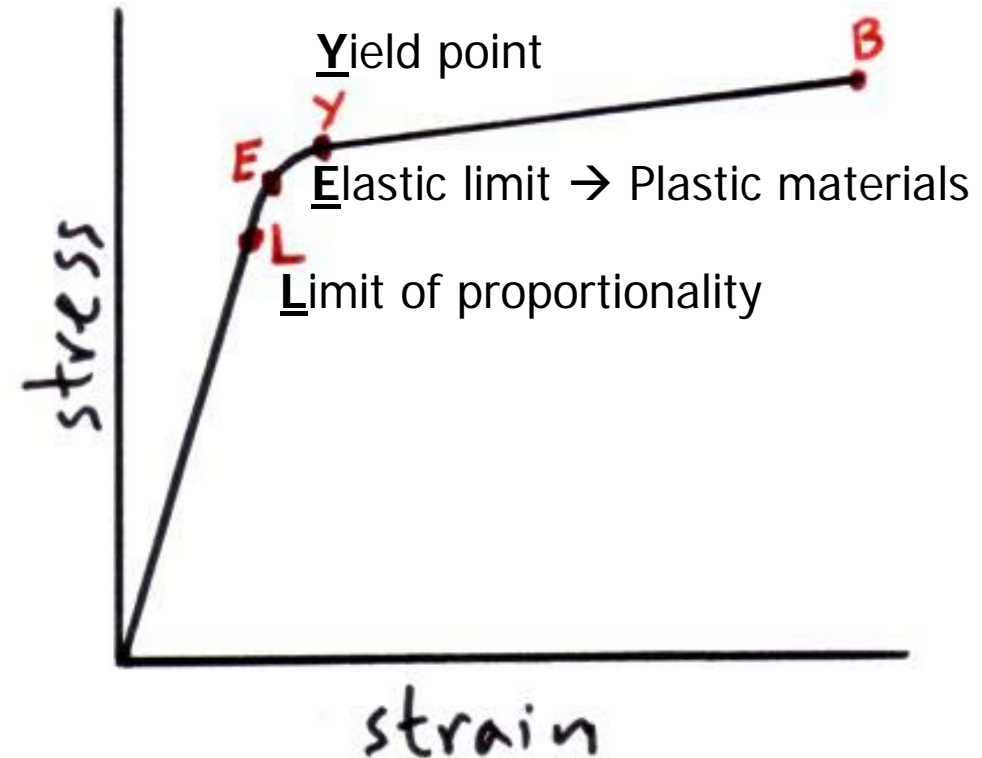
Hooke's Law

Not all materials are elastic!

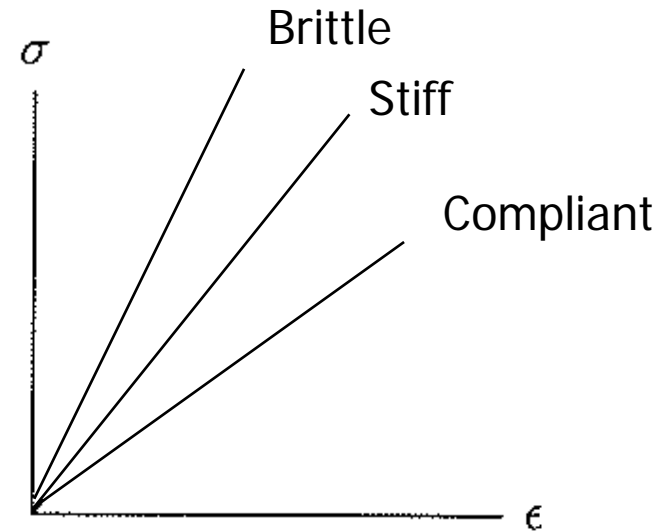
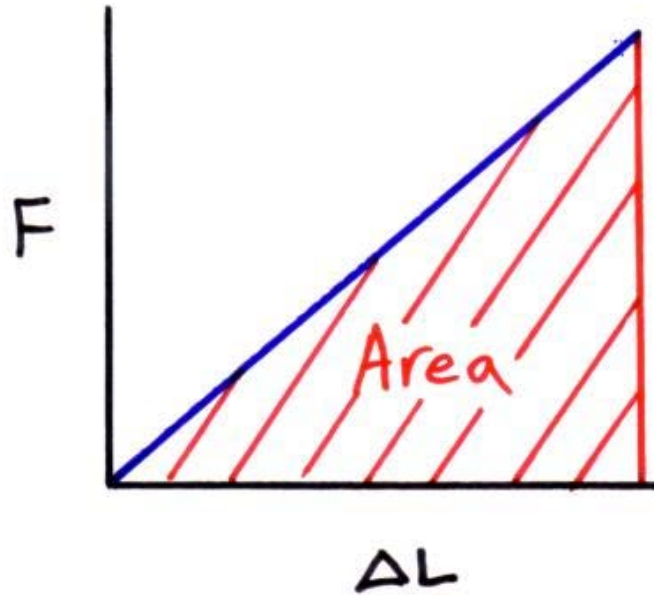


$$\sigma = \frac{F}{A} = E \times \varepsilon = \frac{E \times \Delta L}{L}$$

Hooke's Law



Compliant materials store the most energy

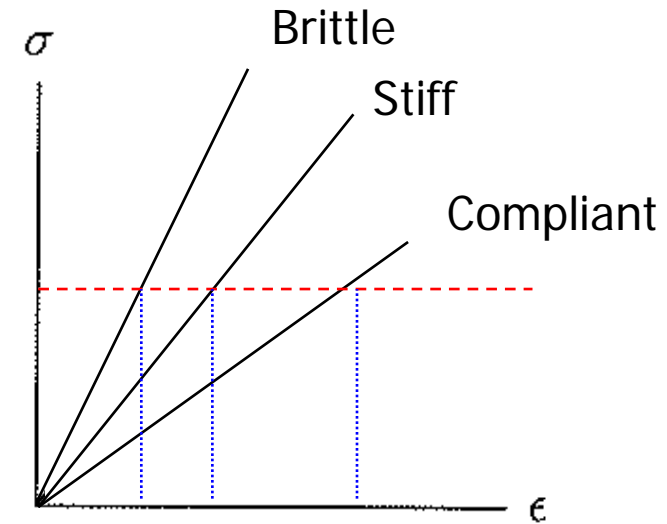


Strain Energy $\frac{F \cdot \Delta L}{2} = \frac{\sigma \cdot \epsilon}{2}$

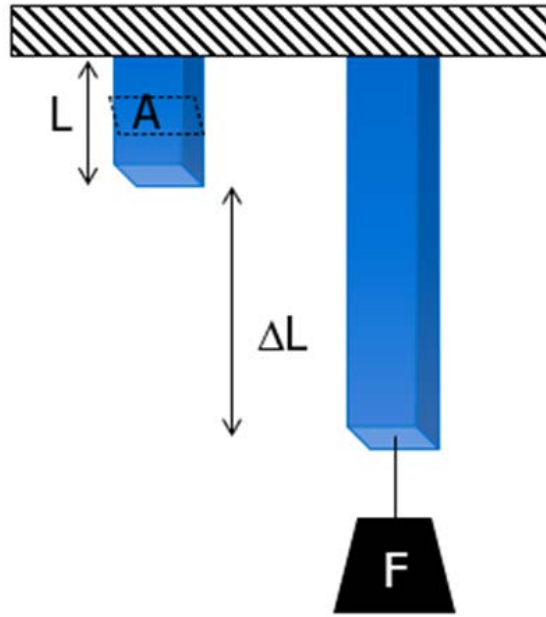
Compliant materials store the most energy (cont.)



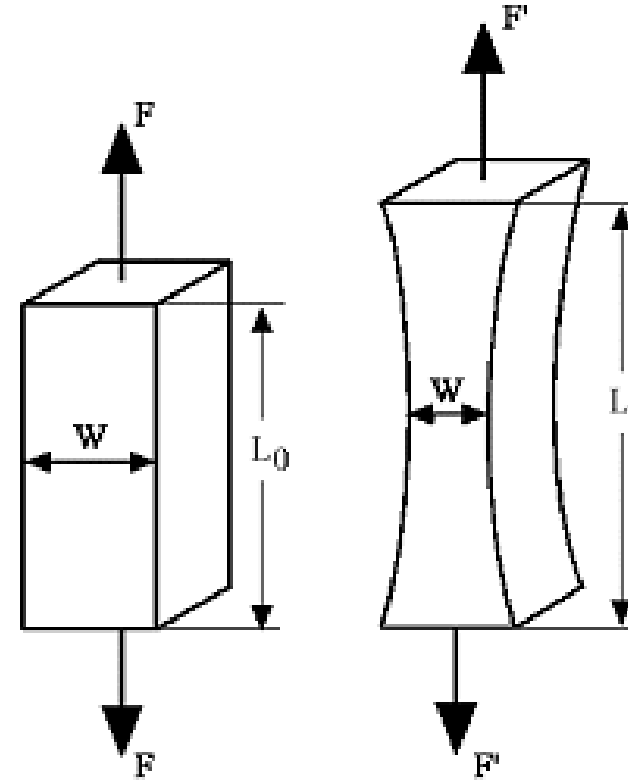
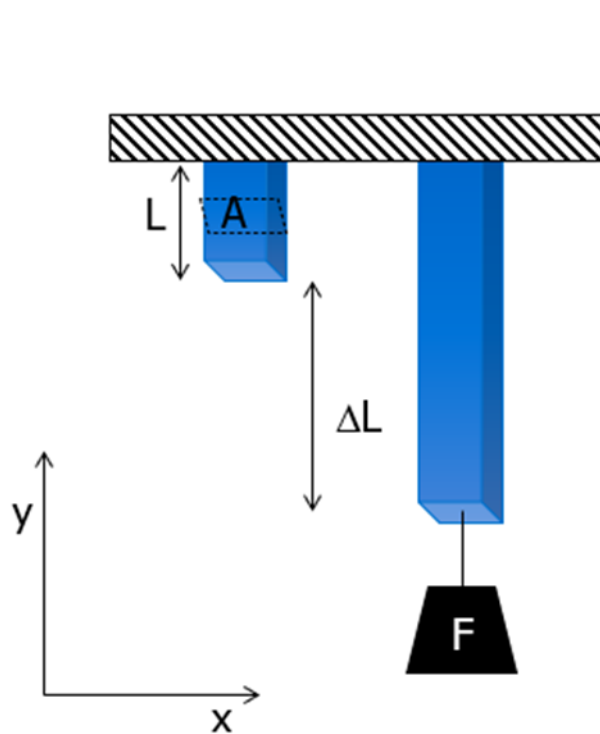
Clock springs store energy through mechanical deformation



Materials elongate in the direction of force



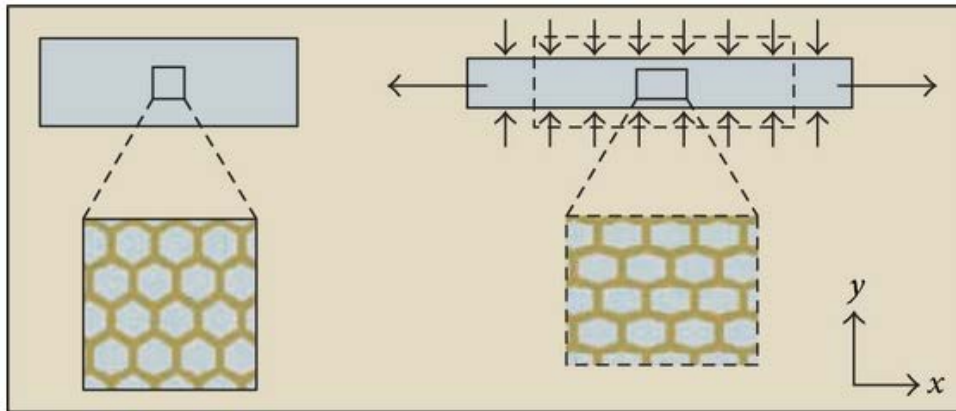
Poisson's ratio tells us about deformation perpendicular to force application



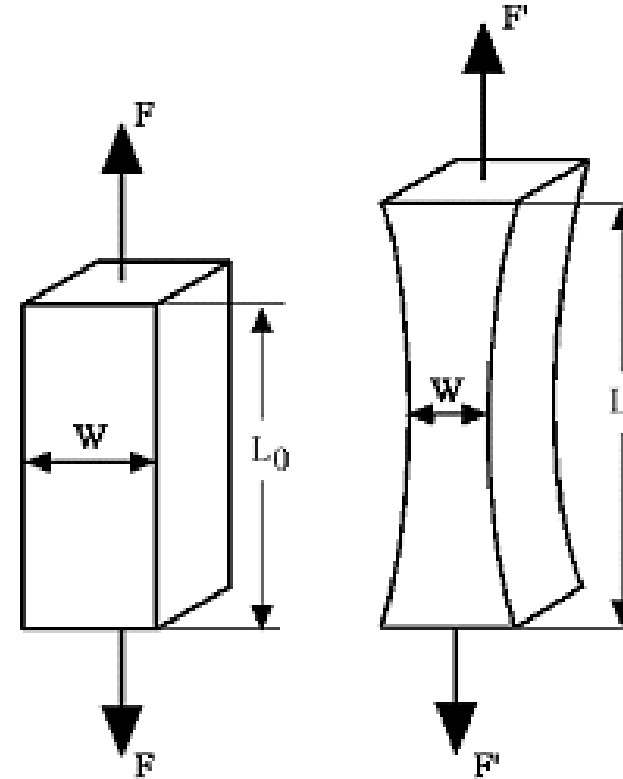
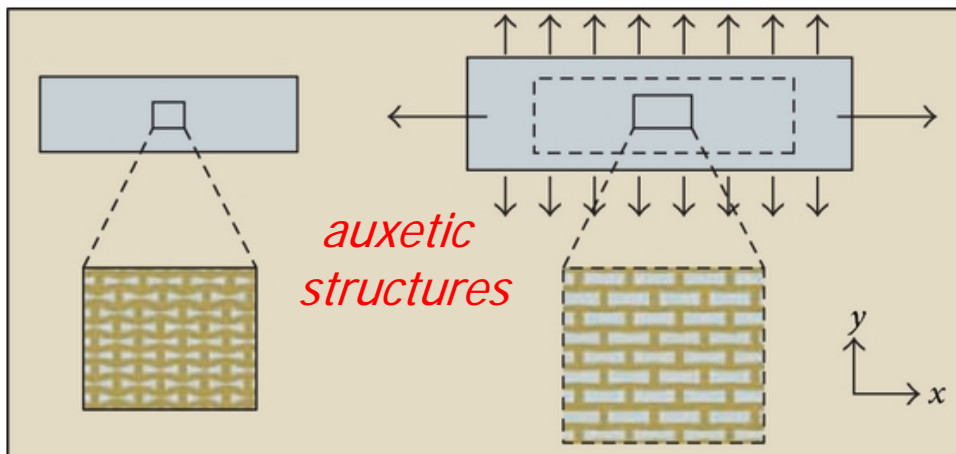
Positive Poisson's ratio $\nu_{xy} = -\frac{\epsilon_x}{\epsilon_y}$ or z (transverse)
(axial)

Poisson's ratio tells us about deformation perpendicular to force application (cont.)

Positive Poisson's ratio



Negative Poisson's ratio

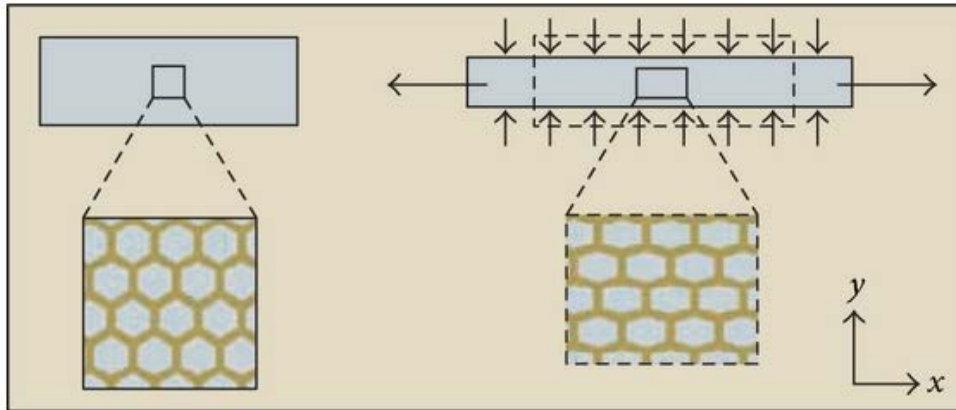


$$\nu_{xy} = -\frac{\epsilon_x}{\epsilon_y} \quad \begin{array}{l} \text{or } z \text{ (transverse)} \\ \text{(axial)} \end{array}$$

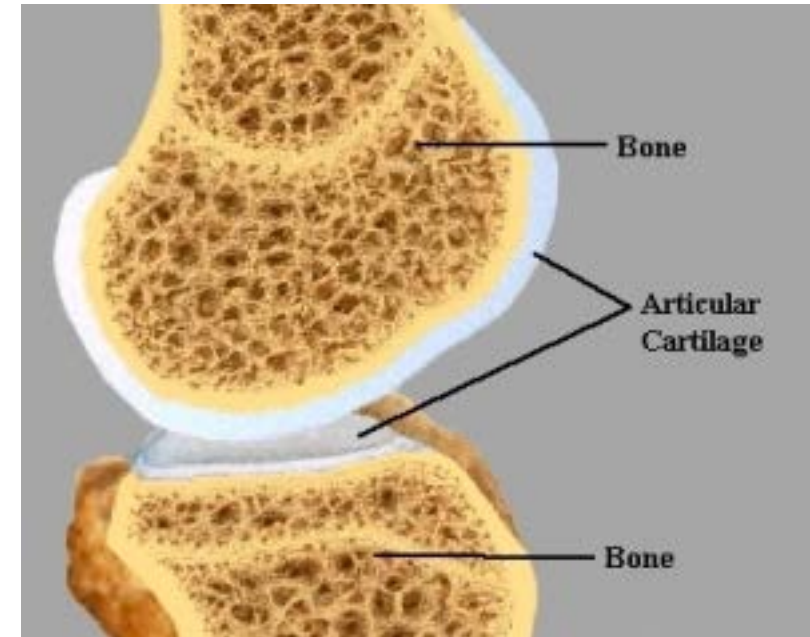
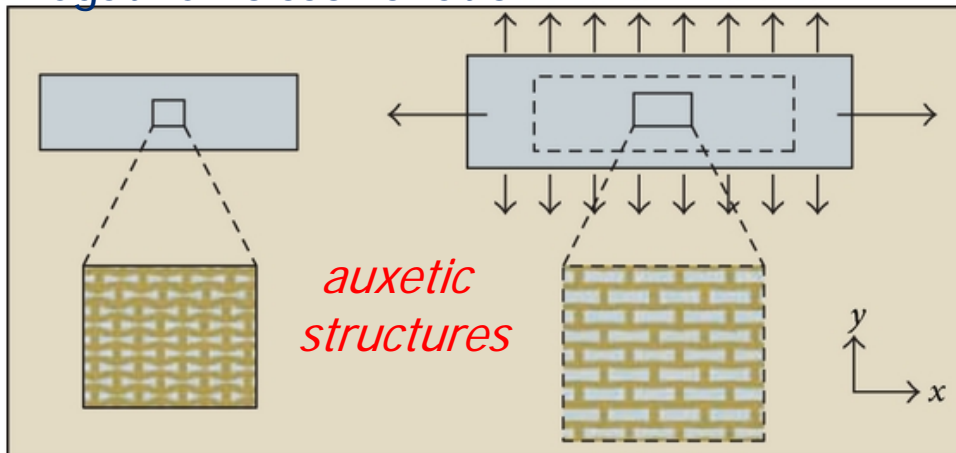
Positive Poisson's ratio

Poisson's ratio tells us about deformation perpendicular to force application (cont.)

Positive Poisson's ratio

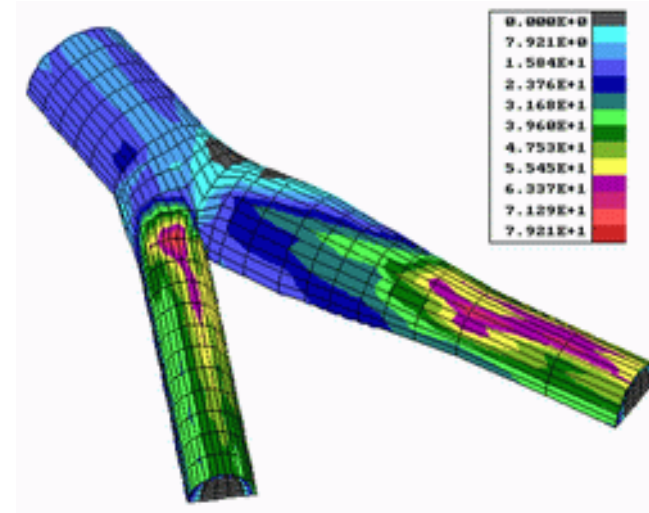
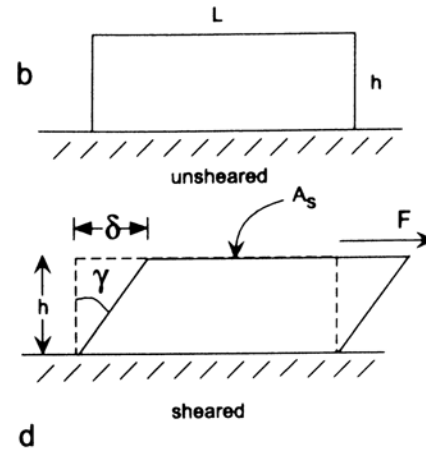


Negative Poisson's ratio

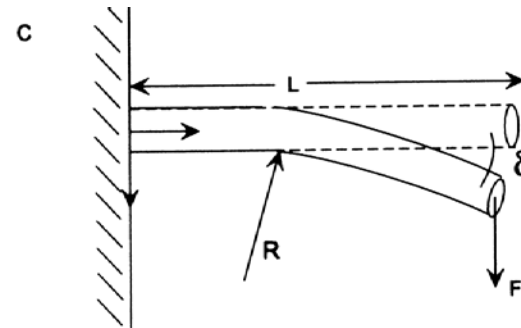


$$\nu_{xy} = -\frac{\epsilon_x}{\epsilon_y}$$

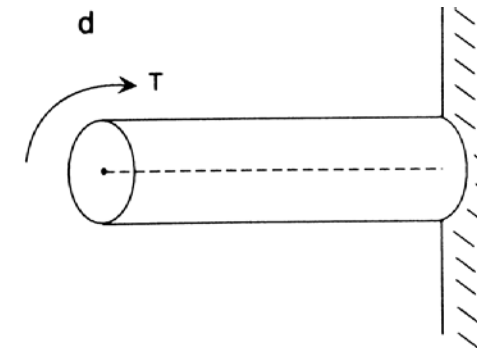
Quantifying deformation in other geometries



Shear stress



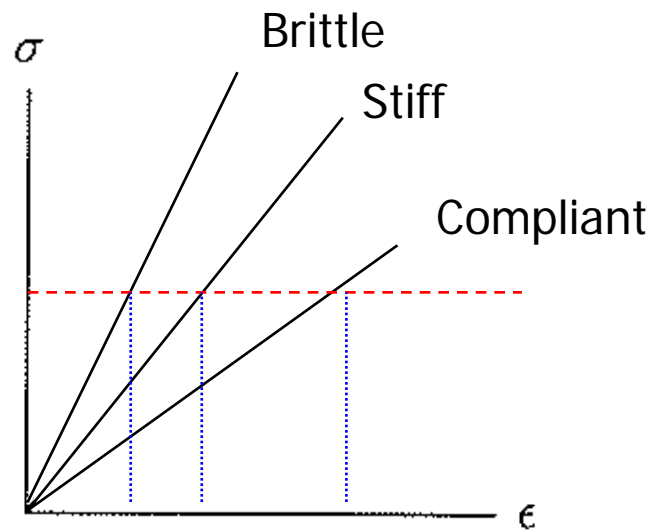
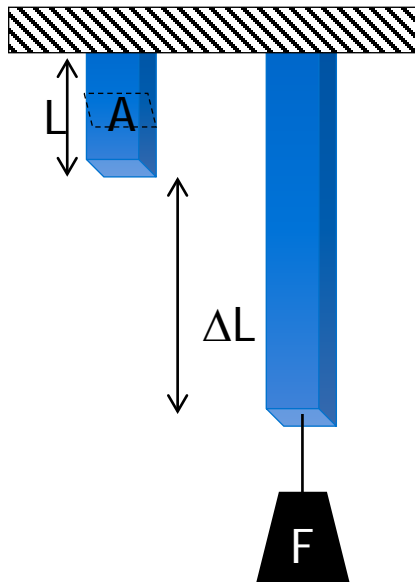
Bending



Torsion

Review and rewind

Elastic solid mechanics



$$\sigma = \frac{F}{A} = E \times \epsilon = \frac{E \times \Delta L}{L}$$

Hooke's Law

$$\nu_{xy} = -\frac{\epsilon_x}{\epsilon_y}$$

Poisson's ratio



JOHNS HOPKINS UNIVERSITY