Recitation 8

DS-GA 1013 Mathematical Tools for Data Science

- 1. Let $x : \mathbb{R} \to \mathbb{C}$ be periodic with period 1 and square integrable on [0,1). For each of the following functions, give a formula for the Fourier coefficients in terms of the Fourier coefficients of x.
 - 1. $y_1: \mathbb{R} \to \mathbb{C}$ with $y_1(t) = x(t-s)$ for some fixed $s \in \mathbb{R}$.
 - 2. $y_2: \mathbb{R} \to \mathbb{C}$ with $y_2(t) = e^{2\pi i pt} x(t)$ for some fixed $p \in \mathbb{Z}$.
 - 3. $y_3: \mathbb{R} \to \mathbb{C}$ with $y_3(t) = x(-t)$
 - 4. $y_4: \mathbb{R} \to \mathbb{C}$ with $y_3(t) = x^*(t)$

Solution:

1. Note that

$$\widehat{y_1}[k] = \int_0^1 x(t-s)e^{-2\pi ikt} dt$$

$$= \int_{-s}^{1-s} x(u)e^{-2\pi ik(u+s)} du$$

$$= e^{-2\pi iks}\widehat{x}[k].$$

2. Note that

$$\widehat{y_2}[k] = \int_0^1 e^{2\pi i pt} x(t) e^{-2\pi i kt} dt$$

$$= \int_0^1 x(t) e^{-2\pi i t(k-p)}$$

$$= \widehat{x}[k-p].$$

3. Note that

$$\hat{y_3}[k] = \int_0^1 x(-t)e^{-2\pi ikt} dt
= -\int_0^- 1x(t)e^{-2\pi it(-k)}
= \hat{x}[-k].$$

4. Note that

$$\hat{y_4}[k] = \int_0^1 x^*(t)e^{-2\pi ikt} dt$$

$$= (\int_0^1 x(t)e^{-2\pi it(-k)} dt)^*$$

$$= \hat{x}^*[-k].$$

2. Let x(t) be a square wave, i.e $x(t) = 1 for 0 \le t \le 0.5 and - 1 for 0.5 < t \le 1$. What are the Fourier series coefficients for x(t)? Simulation. Discontinuity.

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Solution:

$$\begin{split} \widehat{x}[k] &= \int_0^1 x(t)e^{-2\pi ikt} \, dt \\ &= \int_0^{0.5} e^{-2\pi ikt} \, dt - \int_{0.5}^1 e^{-2\pi ikt} \, dt \\ &= (e^{-\pi ik} - 1) - (e^{-2\pi ik} - e^{\pi ik})) \frac{1}{-2\pi ik} \\ &= \frac{(1 - (-1)^k)}{i\pi k} \end{split}$$

if k is even $\widehat{x}[k] = 0$ and if k is odd $\widehat{x}[k] = \frac{2}{i\pi k} = -\frac{2i}{\pi k}$

Note that the coefficients are purely imaginary, therefore the cosine term will be zero (HW6).

3. Let n be a positive integer and define $f: \mathbb{Z}^2 \to \mathbb{C}$ by

$$f(j,k) = e^{2\pi i jk/N}.$$

1. Show that f is periodic with period N in both arguments. That is, show that

$$f(j + pN, k + qN) = f(j, k)$$

for all $j, k, p, q \in \mathbb{Z}$.

2. Let $\vec{\varphi}_j = (1, e^{2\pi i j/N}, \dots, e^{2\pi i (N-1)j/N})^T \in \mathbb{C}^N$ for $j \in \mathbb{Z}$. When does $\vec{\varphi}_j = \vec{\varphi}_k$?

Solution:

Solution.

1. Note that

$$e^{2\pi i(j+pN)(k+qN)/N} = e^{2\pi ij(k+qN)/N}e^{2\pi ip(k+qN)} = e^{2\pi ijk/N}e^{2\pi ijq} = e^{2\pi ijk/N}.$$

- 2. Iff $j \equiv k \pmod{N}$. This allows us to abuse notation when indexing our sampled signals and discrete Fourier coefficients using negative indices.
- 4. A matrix $A \in \mathbb{C}^{n \times n}$ is called unitary if $A^*A = I$.
 - 1. Prove that unitary matrices preserve inner products:

$$\langle x, y \rangle = \langle Ax, Ay \rangle$$

for all $x, y \in \mathbb{C}^n$.

2. Is the matrix $\widetilde{F}_{[N]} \in \mathbb{C}^{N \times N}$, $N = 2k_c + 1$ unitary?

$$\widetilde{F}_{[N]} = \begin{bmatrix} 1 & 1 & \cdots & 1 \\ \exp\left(\frac{i2\pi(-k_c)}{N}\right) & \exp\left(\frac{i2\pi(-k_c+1)}{N}\right) & \cdots & \exp\left(\frac{i2\pi k_c}{N}\right) \\ \cdots & \cdots & \cdots & \cdots \\ \exp\left(\frac{i2\pi(-k_c)j}{N}\right) & \exp\left(\frac{i2\pi(-k_c+1)j}{N}\right) & \cdots & \exp\left(\frac{i2\pi k_cj}{N}\right) \\ \cdots & \cdots & \cdots & \cdots \\ \exp\left(\frac{i2\pi(-k_c)(N-1)}{N}\right) & \exp\left(\frac{i2\pi(-k_c+1)(N-1)}{N}\right) & \cdots & \exp\left(\frac{i2\pi k_c(N-1)}{N}\right) \end{bmatrix}$$

Solution:

Solution.

1. Note that

$$\langle Ax, Ay \rangle = (Ay)^*(Ax) = y^*A^*Ax = y^*x = \langle x, y \rangle.$$

2. No, but $\frac{1}{\sqrt{N}}\widetilde{F}_{[N]}$ is.

5. There is a signal x given by

$$x(t) = \sum_{k=-k_c}^{k_c} a_k e^{2\pi i kt},$$

where k_c is known. Suppose we are given n samples

$$x(t_1), x(t_2), \ldots, x(t_n)$$

where $0 \le t_1 < t_2 < \dots < t_n < 1$ need not be uniformly spaced.

- 1. Under what conditions can we exactly recover the a_k values, and how would this be done?
- 2. Suppose n is large, but the samples are corrupted by noise. Give a method for estimating the a_k values.

Solution:

Solution.

1. The $x(t_i)$ values are given by the system

$$\begin{bmatrix} e^{2\pi i(-k_c)t_1} & e^{2\pi i(-k_c+1)t_1} & \cdots & e^{2\pi i(k_c)t_1} \\ e^{2\pi i(-k_c)t_2} & e^{2\pi i(-k_c+1)t_2} & \cdots & e^{2\pi i(k_c)t_2} \\ \vdots & \vdots & \ddots & \vdots \\ e^{2\pi i(-k_c)t_n} & e^{2\pi i(-k_c+1)t_n} & \cdots & e^{2\pi i(k_c)t_n} \end{bmatrix} \begin{bmatrix} a_{-k_c} \\ a_{-k_c+1} \\ \vdots \\ a_{k_c} \end{bmatrix} = \begin{bmatrix} x(t_1) \\ x(t_2) \\ \vdots \\ x(t_n) \end{bmatrix}.$$

This has a unique solution when $n \ge 2k_c + 1$ since the corresponding matrix is a Vandermonde matrix, and thus has full rank. That said, it becomes ill-conditioned as the t_i become close.

2. Apply least squares regression to the above overdetermined linear system.