

Module 1 | Lesson 1 (Part 1)

# The Squared Error Criterion and the Method of Least Squares

# Module 1 | Least Squares

## In this module

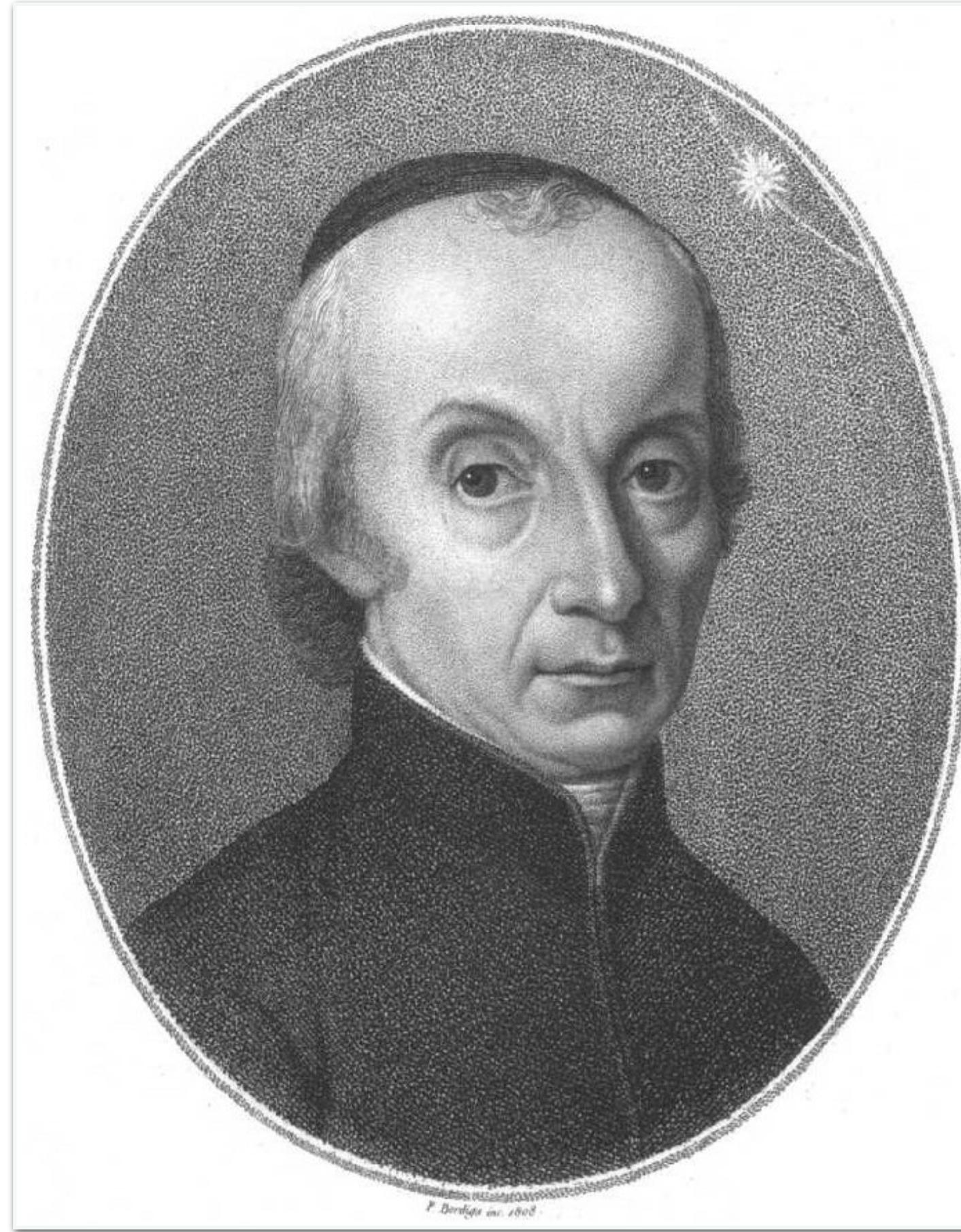
- The history of the method of *least squares*
- Ordinary and weighted least squares
- Recursive least squares
- Maximum likelihood and the method of least squares

# The Squared Error Criterion and the Method of Least Squares

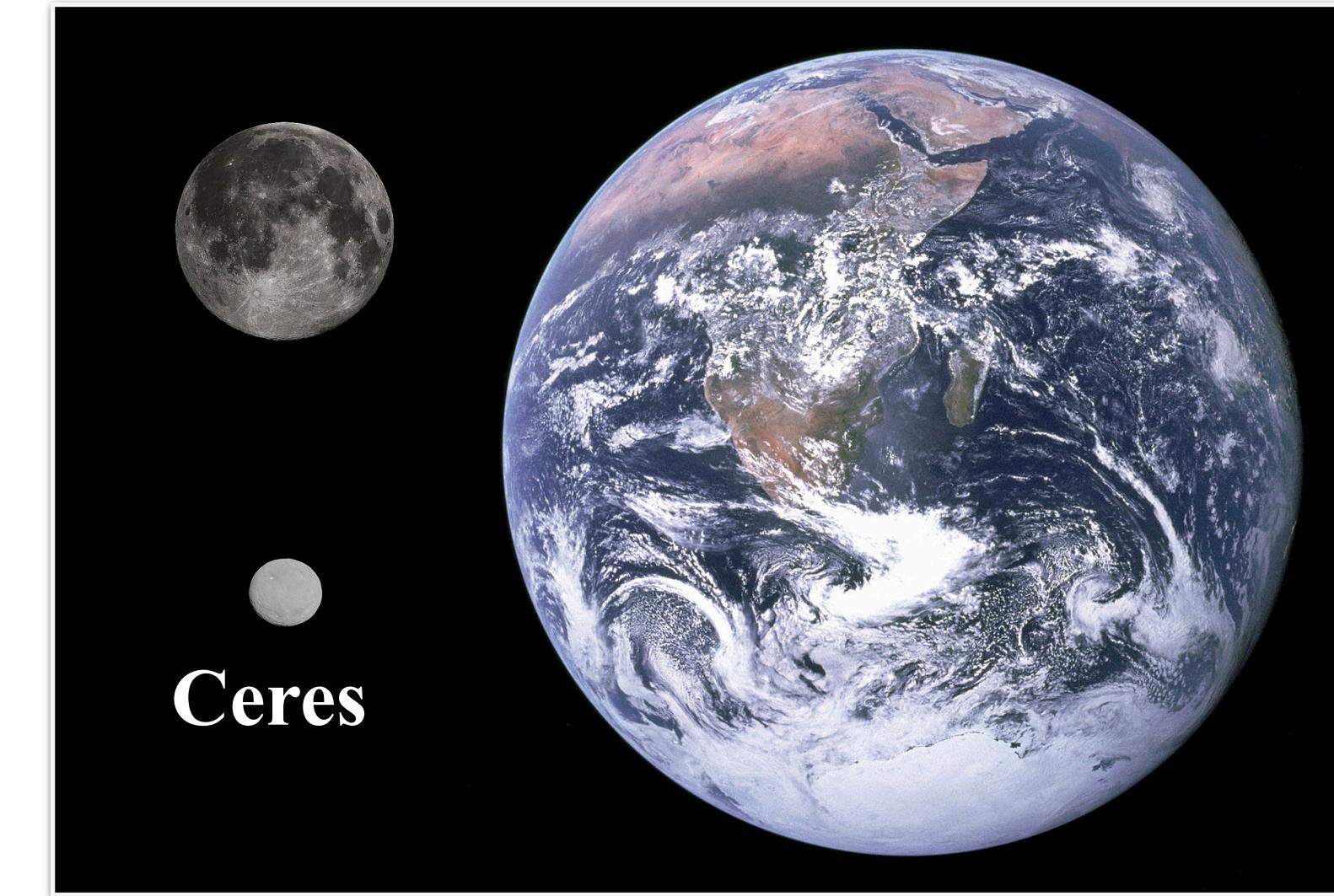
By the end of this video, you will be able to...

- Describe how the method of least squares was used in the discovery of Ceres
- Describe the least error criterion and how it's used in parameter estimation
- Derive the normal equations for least squares parameter estimation

# Giuseppe Piazzi and Ceres



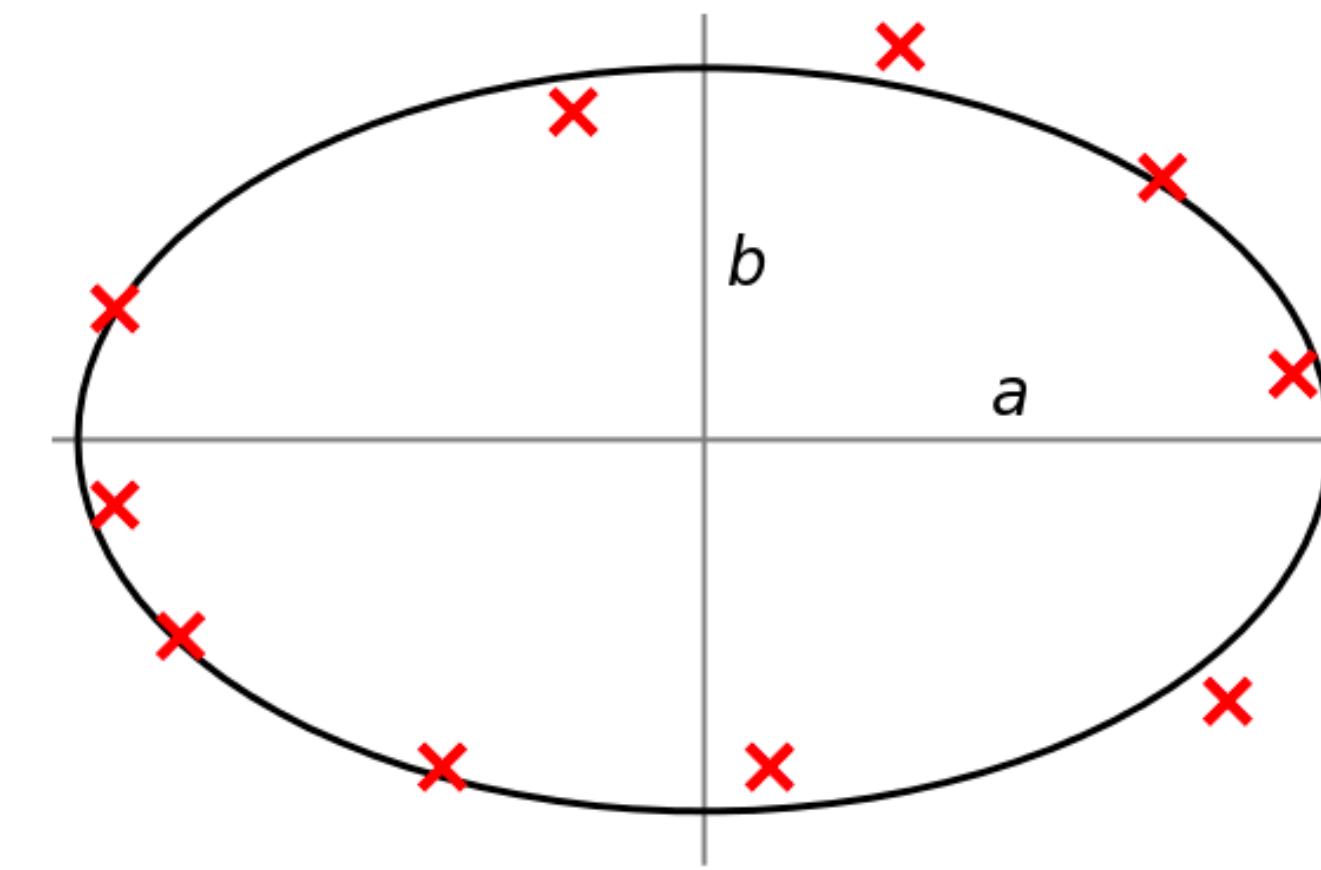
Giuseppe Piazzi



Beobachtungen des zu Palermo d. 1. Jan. 1801 von Prof. Piazzi neu entdeckten Gasteins.										
1801	Mittlere sonnen- Zeit	Grade Aufstieg in Zeit	Grade Auf- steigung in Gradern.	Nördl. Abweich.	Geocentr. liche Länge	Geocentr. Breite	Ort der Sonne + 20° Aberration	Logar. d. Distanz Aberration	Z	Logar. d. Distanz Aberration
Jan.	1	8 43 27,8	3 27 11,25 51 47 48,8	15 37 43,5	1 23 22 58,3	3 6 42,1	9 II 1 30,9	9,9926156		
	2	8 39 24,6	3 26 53,85 51 43 27,8	15 41 55,5	1 23 19 44,3	3 2 24,9	9 II 2 28,6	9,9926317		
	3	8 34 53,3	3 26 38,45 51 39 36,0	15 44 31,6	1 23 16 58,6	2 53 9,9	9 II 3 26,6	9,9926324		
	4	8 30 42,1	3 26 23,15 51 35 47,3	15 47 57,6	1 23 14 75,5	2 53 55,6	9 II 4 24,9	9,9926418		
	5	8 6 15,8	3 25 32,11 51 23 15,5	15 10 32,0	1 23 7 59,1	2 29 0,6	9 II 5 17,5	9,9927641		
	6	8 2 17,5	3 25 29,73 51 22 26,6	.....	.....	.....	.....	.....		
	7	7 54 26,2	3 25 30,30 51 22 34,5	16 22 49,5	1 23 10 37,6	1 16 59,7	9 II 12 13,8	9,9928490		
	8	7 50 31,7	3 25 31,72 51 22 55,8	16 27 5,7	1 23 12 1,2	2 12 56,7	9 II 14 13,5	9,9928809		
	9	.....	.....	16 40 13,0	.....	.....	.....	.....		
	10	7 35 11,3	3 25 55,11 51 28 45,0	.....	.....	.....	.....	.....		
	11	7 31 28,5	3 26 8,15 51 32 2,3	16 49 16,1	1 23 25 59,2	1 53 38,2	9 II 19 53,8	9,9930607		
	12	7 24 2,7	3 26 34,27 51 38 34,1	16 58 35,9	1 23 34 21,3	1 45 6,0	10 I 20 40,3	9,9931434		
	13	7 20 21,7	3 26 49,42 51 42 21,6	17 3 18,5	1 23 39 1,6	1 41 28,1	10 II 21 32,0	9,9931886		
	14	7 16 45,5,3	3 26 90,51 51 46 43,5	17 8 5,5	1 23 44 15,7	1 38 52,1	10 II 22 22,7	9,9932348		
	15	6 58 51,3	3 28 54,53 52 13 38,3	17 32 54,1	1 24 15 15,7	1 21 6,9	10 II 26 20,1	9,9935061		
	16	6 51 52,9	3 29 48,14 52 27 2,7	17 43 11,0	1 24 30 9,0	1 14 16,0	10 II 27 46,2	9,9936332		
	17	6 48 26,4	3 30 17,25 52 34 18,8	17 48 21,5	1 24 38 7,3	1 10 54,6	10 II 28 28,5	9,9937007		
	18	6 44 59,9	3 30 47,2,1 52 41 48,0	17 53 36,3	1 24 46 19,3	1 7 30 9	10 II 29 9,6	9,9937703		
	19	6 41 35,8	3 31 19,0,6 52 49 45,9	17 58 57,5	1 24 54 57,9	1 4 12,5	10 II 29 49,9	9,9938423		
	20	6 31 31,5	3 33 2,70 53 15 49,5	18 15 1,0	1 25 22 43,4	0 54 23,9	10 II 31 45,5	9,9940751		
	21	5 21 39,2	3 34 58,50 53 44 37,5	18 31 23,2	1 25 53 29,5	0 45 5,0	10 II 33 33,3	9,9943276		
	22	5 11 58,2	3 37 6,54 54 16 38,1	18 47 58,8	1 26 26 40,0	0 36 2,9	10 II 35 11,4	9,9945823		

Piazzi's 24 observations

# Karl Friedrich Gauss



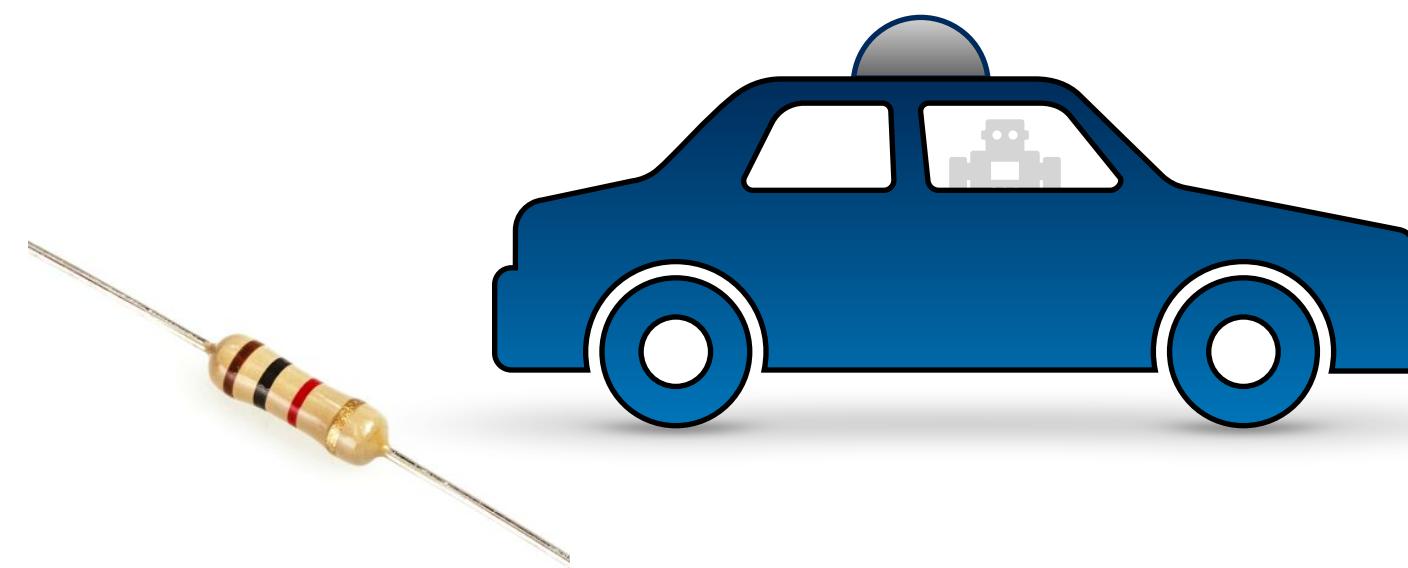
Gauss used the **method of least squares** to determine the orbital parameters of Ceres.

*Karl Friedrich Gauss  
'Princeps mathematicorum'*

# Least Squares

*The **most probable value** of the unknown quantities will be that in which the **sum of the squares** of the differences between the actually observed and the computed values multiplied by numbers that measure the degree of precision is a **minimum**.*

- Karl Friedrich Gauss



*Resistor in the drive-system of a car*



*Multimeter*

# Estimating Resistance

Measurement	Resistance (Ohms)
1	1068
2	988
3	1002
4	996



# Estimating Resistance

Measurement	Resistance (Ohms)
1	1068
2	988
3	1002
4	996

Let  $x$  be the resistance. Assume it is a **constant**, but **unknown**.

We make measurements,  $y$ , of the resistance.

We model our measurements as corrupted by noise  $\nu$ .

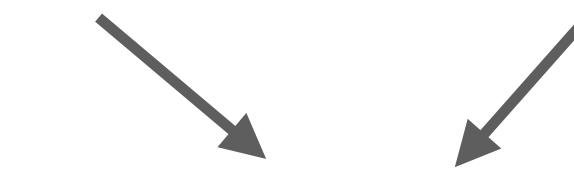
$$y = x + \nu$$

# Estimating Resistance

Measurement	Resistance (Ohms)
1	1068
2	988
3	1002
4	996

## Measurement Model

'Actual' resistance      Measurement noise



$$y_1 = x + v_1$$

$$y_2 = x + v_2$$

$$y_3 = x + v_3$$

$$y_4 = x + v_4$$

# Estimating Resistance

#	Resistance (Ohms)
1	1068
2	988
3	1002
4	996

## Measurement Model

$$y_1 = x + \nu_1$$

$$y_2 = x + \nu_2$$

$$y_3 = x + \nu_3$$

$$y_4 = x + \nu_4$$

## Squared Error

$$e_1^2 = (y_1 - x)^2$$

$$e_2^2 = (y_2 - x)^2$$

$$e_3^2 = (y_3 - x)^2$$

$$e_4^2 = (y_4 - x)^2$$

The squared error *criterion*:

$$\hat{x}_{\text{LS}} = \operatorname{argmin}_x (e_1^2 + e_2^2 + e_3^2 + e_4^2) = \mathcal{L}_{\text{LS}}(x)$$

*The ‘best’ estimate of resistance is the one that minimizes the sum of squared errors*

# Minimizing the Squared Error Criterion

$$\hat{x}_{\text{LS}} = \operatorname{argmin}_x (e_1^2 + e_2^2 + e_3^2 + e_4^2) = \mathcal{L}_{\text{LS}}(x)$$

Let's re-write our criterion using vectors:

$$\begin{aligned} \mathbf{e} &= \begin{bmatrix} e_1 \\ e_2 \\ e_3 \\ e_4 \end{bmatrix} = \mathbf{y} - \mathbf{H}\mathbf{x} \\ &= \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \mathbf{x} \end{aligned}$$

*This matrix is called the 'Jacobian'*



# Minimizing the Squared Error Criterion

$$\hat{x}_{\text{LS}} = \operatorname{argmin}_x (e_1^2 + e_2^2 + e_3^2 + e_4^2) = \mathcal{L}_{\text{LS}}(x)$$

Now, we can express our criterion as follows,

$$\begin{aligned}\mathcal{L}_{\text{LS}}(x) &= e_1^2 + e_2^2 + e_3^2 + e_4^2 = \mathbf{e}^T \mathbf{e} \\ &= (\mathbf{y} - \mathbf{H}x)^T (\mathbf{y} - \mathbf{H}x) \\ &= \mathbf{y}^T \mathbf{y} - x^T \mathbf{H}^T \mathbf{y} - \mathbf{y}^T \mathbf{H}x + x^T \mathbf{H}^T \mathbf{H}x\end{aligned}$$

# Minimizing the Squared Error Criterion

$$\mathcal{L}(x) = \mathbf{e}^T \mathbf{e} = \mathbf{y}^T \mathbf{y} - x^T \mathbf{H}^T \mathbf{y} - \mathbf{y}^T \mathbf{H} x + x^T \mathbf{H}^T \mathbf{H} x$$

To minimize this, we can compute the partial derivative with respect to our parameter, set to 0, and solve for an extremum:

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial x} \Big|_{x=\hat{x}} &= -\mathbf{y}^T \mathbf{H} - \mathbf{y}^T \mathbf{H} + 2\hat{x}^T \mathbf{H}^T \mathbf{H} = 0 \\ &-2\mathbf{y}^T \mathbf{H} + 2\hat{x}^T \mathbf{H}^T \mathbf{H} = 0\end{aligned}$$

Re-arranging, we arrive at:

$$\hat{x}_{\text{LS}} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \mathbf{y}$$

*x-hat minimizes our squared error criterion!*

# Minimizing the Squared Error Criterion

Careful! We will only be able to solve for  $\hat{x}$  if  $(\mathbf{H}^T \mathbf{H})^{-1}$  exists.

If we have  $m$  measurements, and  $n$  unknown parameters, then:

$$\mathbf{H} \in \mathbb{R}^{m \times n} \quad \mathbf{H}^T \mathbf{H} \in \mathbb{R}^{n \times n}$$

This means that  $(\mathbf{H}^T \mathbf{H})^{-1}$  exists only if there are at least as many measurements as there are unknown parameters:

$$m \geq n$$

# Minimizing the Squared Error Criterion



Returning to our problem, we see that:

$$\mathbf{y} = \begin{bmatrix} 1068 \\ 988 \\ 1002 \\ 996 \end{bmatrix} \quad \mathbf{H} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

#	Resistance (Ohms)
1	1068
2	988
3	1002
4	996

$$\hat{x}_{\text{LS}} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \mathbf{y}$$

$$= \left( [1111] \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right)^{-1} [1111] \begin{bmatrix} 1068 \\ 988 \\ 1002 \\ 996 \end{bmatrix} = \frac{1}{4}(1068 + 988 + 1002 + 996) = 1013.5 \text{ Ohms}$$

*The least squares solution is just the mean of our measurements!*

# Method of Least Squares | Assumptions

- Our measurement model,  $y = x + \nu$ , is **linear**.
- Measurements are **equally weighted**.  
*(we do not suspect that some have more noise than others).*

# Summary | The Method of Least Squares

- Pioneered by Gauss to determine the orbit of the planetoid *Ceres*
- Least squares finds the parameters which minimize the *Least Squares Criterion*
- Ordinary least squares assumes that measurements are weighted equally, measurement model is linear