### **Sensor Fusion Nanodegree**

## **Camera-Based 2D Tracking: Midterm Project Report**

#### MP.0 Mid-Term Report

This report briefly describes the implementation of each task.

#### MP.1 Data Buffer Optimization

```
/// STUDENT ASSIGNMENT
/// TASK MP.1 -> replace the following code with ring buffer of size dataBufferSize

// push image into data frame buffer
DataFrame frame;
frame.cameraImg = imgGray;
if (dataBuffer.size() < dataBufferSize)

{
    dataBuffer.push_back(frame);
}
else
{
    dataBuffer.push_back(frame);
    dataBuffer.erase(dataBuffer.begin());
}

/// EOF STUDENT ASSIGNMENT</pre>
```

Using the *std::vector* functions *push\_back* and *erase*, new images are added to the end of the buffer and old ones are removed from the top, if the size of the data buffer had reached the predefined size.

#### MP.2 Keypoint Detection

The Harris detector was implemented in the function *detKeypointsHarris* along with Non Maximum Supression. The rest of the detectors are implemented in the function *detKeypointsModern*, where each detector type uses the default parameters.

## MP.3 Keypoint Removal

Keypoints that do not belong to the predefined region of interest (the preceding vehicle) are removed using the *cv::rect::contains* function.

### MP.4 Keypoint Descriptors

The different descriptor types are implemented in *descKeypoints* and can be selected based on the string *descriptorType*. The descriptors are created with the default parameters and assigned to the *extractor* variable.

#### MP.5 Descriptor Matching

The FLANN-based matching was implemented in *matchDescriptors* and is selectable based on *matcherType*. Also, a workaround for the opency bug is implemented to convert binary descriptors to float for FLANN-based matching.

#### MP.6 Descriptor Distance Ration

For the KNN matching, the best two matches for each descriptor in the source are detected and saved to the array *knnmatches*. Afterwards, looping over *knnmatches*, only unambiguous matches are saved to the output array *matches* based on a distance ratio of 0.8.

# MP.7 Performance Evaluation 1

			Mean	Standard		T	
Detector Type	lmg#	No. Of keypoints	neighborhood size	deviation of neighborhood	Computation	Example	Notes
	lmg1	125	4	0			- Constant neighborhood size
	Img2	118 123		0			- No overlap
	Img3 Img4	123	4	0			- Keypoint clusters around number plate
	Img5	120		0			place
Shi-Tomasi	Img6	113	4	0			
	Img7	114	4	0			
	Img8	123	4	0			
	Img9	111	4	0			
	Img10 Img1	112 17	6	0			- Constant neighborhood size
	Img2	15	6	0			- No overlap
	Img3	19		0			- No distinctive clusters
	Img4	19		0	(		- Keypoints only detected at very
Harris	Img5	25	6	0			high changes in intensity
	Img6	46 17	6	0			
	Img7 Img8	31	6	0			
	Img9	25	6	0			
	Img10	34		0			
	lmg1	149	7	0	~1 ms		- Constant neighborhood size
	Img2	152	7	0		Later and a first transfer of the same of	- The majority of keypoints are
	Img3	150		0			overlapping
	Img4 Img5	155 149	7	0			- Clusters around large changes in intensity
FAST	Img6	149	7	0	-		intensity
	Img7	156	7	0			
	Img8	150	7	0			
	Img9	138		0			
	Img10	143		0			
	Img1	264		212.5	-		- Relatively large keypoints -
	Img2 Img3	282 282		212.13 191.0			The majority of keypoints are overlapping
	Img4	277		159.23			Overlapping
DDICK	Img5	297	22.59	220.7		7/100	
BRISK	Img6	279	22.94	249.96			
	Img7	289	21.80	215.38			
	Img8	272		226.02			
	Img9 Img10	266 254	22.56 22.04	230.7 215.12			
	Img1	92	57		~8 ms		- Very large keypoints -
	Img2	102		680.59		The second secon	The majority of keypoints are
	Img3	106	56.5	672.11			overlapping
	Img4	113		629.78			A lot of concentric keypoints
ORB	Img5	109		625.65			
	Img6	125 130		596.8 646.4			
	Img7 Img8	130 129		646.4 611.9			
	Img9	127	54.67	638.1			
	Img10	128		560.29			
	Img1	166		15.3	~120 ms		- Relatively small keypoints -
	Img2	157	7.49	12.42			Few overlapping keypoints
	Img3	161	7.45	12.62	-		- Evenly distributed
	Img4 Img5	155 163	7.57 7.73	11.96 11.8			
AKAZE	Img6	164		11.4			
	Img7	173		11.78	-		
	Img8	175	7.82	12.32			
	Img9	177	7.82	12.2			
	Img10	179 138		12.97	~170 ms		Marsh and the color
	Img1 Img2	138		35.0 38.1			- Mostly small keypoints - A few overlapping keypoints
	Img2	132		36.24		The second of th	A rew overlapping keypoints
	Img4	137	4.73	27.46			
SIFT	Img5	134		30.37			
SIFI	Img6	140		31.1			
	Img7	137	5.4	42.42			
	Img8	148		26.45			
	Img9 Img10	159 137		44.49 44.64			
	TimBTO	13/	5.02	44.64		ļ	

## MP.8 Performance Evaluation II

AKAZE SIFT					ORB							BRISK							FAST							Harris												Shi-Tomasi						Detector Type																
9.10.80	0 .0	1 0.5	6.7	5 6	4.5	3.4	2.3	1.2	8.9	7.8	6.7	5.6	4.5	3.4	2.3	1.2	9,10	8.9	7.8	6.7	5.6	4.5	2 2	2 3 74	9,10	8.9	7.8	6.7	5.6	4.5	3.4	2.3	1.2	9,10	00 5	7.0	5.6	4.5	3.4	2.3	1.2	9,10 17	0 0	7.0	5.6	4.5	3.4	2.3	1.2	9,10	8.9	7.8	6.7	5.6	4 5	3 4 5	1.2	lmg#		
80	04	1	2 5	59	66	63	66	64									91	88	90	92	79	8 3	79	74	184	171	173	188	174	176	157	176	171	100	100	107	5 85	98	101	104	97	17	17	13 13	16	13	14	11	9.00	82	86	85	79	82	90	8 8	95.00	ng# matches	No of	
254.46	177.1	101.77	191 77	187.07	259.66	225 37	218.32	238.22									16.94	8.92	8.59	8.42	9.86	0.6	9 20	9.8/	48.2	47.44	47.1	47.94	48.06	47.47	48.65	49.53	52	0.95	1.78	1 27	0.9	0.9	0.89	0.9	1.29	28.66	20.0	20.8	41.42	21.02	23.15	18.9	19.53	18.85	18.63	19.39	18.3	18.76	20.1	19.65	29.5	time	Detector	
1.79	2.04	200	207	1.97	2.03	2 17	1.8	1.75									2.14	1.98	1.87	1.87	1.8	1.7	1 66	2 14	3.2	3.41	3.42	3.62	3.55	3.67	3.4	9. 5	3.5	2.0	30 5	1 0	2.0	2.2	2.0	3.2	2.94	1.62	1 54	1.50	1.83	1.56	1.54	1.45	1.43	2.53	3.79	2.64	2.59	2.51	2.59	3.02	5.04	time	Descriptor	BRISK
256.25 88	174.34 70	220,001	182 84 74	189.04.69	261.69 85	227 54 76	220.12 78	239.97 86									19.08 66	10.90 84	10.46 68	10.29 78	11.66 53	10.30 59	10 98 45	11.44.49	51.40 183	50.85 189	50.52 207	51.56 195	51.61 183	51.14 179	52.05 185	53.03 205	55.50 176	2.95 119	3.17 125	2.00 123	2.90 108	3.10 126	2.89 118	4.10 130	4.23 119	30.28 24	24.74.25	22 42 24	43.25 24	22.58 17	24.69 15	20.35 13	20.96 12	21.38 100.00	22.42 109	22.03 100	20.89 102		Ť	Ť	34.54 115	귷		
228.44	170 00 14	107.1	254 1	182.0	171.8	164	197.14	174.8									9.93	7.8	10.49	7.63	8.36	00	97	10.25	47.3	50.62	46.96	51.32	47.55	49.74	47.46	49.45	48.9	0.87	10	0 0	0.8	0.8	0.89	0.97	2.11	24.76	10.00	20.1	39.16	20.4	1.16	19.57		16.96								s time		
0.86	) ·	• • •	۱,۰	2		_,	0	٠,									0.74	1.12	0.73	1.14	0.99	0.77	0.75	0.6	1.2	1.15	1.18	1.28	1.23	1.31	1.78	1.2	1.29	0.79	1 98	0.04	1.33	1.1	1.14	1.93	1.87	1.82	1 78	1.5	1.97	1.32	18.08	1.3	1.36	1.8	1.67	1.73	1.75	1.7				time		BRIEF
229.30	470 E7	200.00	255.05	184.57	173.12	165 33	197.92	175.99									10.67 93	8.92 93	11.22 92	8.77 101	9.35 91	8.87 84	9 95 72	11 04 70	48.50 172	51.77 171	48.14 167	52.60 182	48.78 160	51.05 167	49.24 158	50.65 175	50.19 162	1.66 119	2.98 123	1 77 177	2.13 106	1.90 126	2.03 112	2.90 123	3.98 118	26.58 25	20,77	21 70 13	41.13 23	21.72 17	19.24 16	20.87 13	20.42 11	18.76 97	21.16 104	24.31 98	19.75 97	20.13 103	21.22 102	20 73 99	22.36 106	Total time matches	No of	
																	8.36	8.33	10.0	13.29	13.67	9.82	11 54	17.05	47.0	47.56	47.77	52.0	53.34	48	48.34	49.7	49.7	0.94	0 94	0 1.00	1.47	0.96	0.86	0.85	1.29	27.3	19 522	21 12	44.3	20.04	19.78	19.57	18.35	19.9	18.64	18.3	22	19.24	18.3	19 76	20.62		Detector	
																								5 93																								0.93	1.11	1.47	1.03	1.09	1.833	1.05	1.02	1 23	1.45			ORB
																	14	13	16	19	20	16	19	17	51	52	52	57	58	53	53	54	55	2	2	2 6	2	2	2	2	2	28	20	22	45	20	20	20	19	21	19	19	23	20	19	20	22	Total time	ptor	
79	n 4	n (	n (	59	55	n A	72	65									.79 48	13.73 48	.28 52	19.22 51	20.93 44	81 47	97 44	17 98 36	.85 168	.58 178	.79 169	.00 183	.16 161	.20 173	.34 155	.70 177	.30 160	.04 105	04 101	0.49	2.58 85	.06 98	.76 91	2.15 99		28.19 18	A2 10	77 36 10	.39 18	.96 14	.68 14	20.50 10	.46 12	21.37 85	.67 86	.39 81	23.83 80	20.29 86	19.32 88	20 99 86	.07 86	matches	No of	
797 97 247 13	177.2	1001	217.02	167.4	206.2	203.8	175.0	160.65									9.15	9.15	8.11	8.25	9.0	00 0	20" 8	10.3	47.2	48.45	46.96	47.36	55.8	58.65	54.04	53.00	49.88	0.8	0.86	0011	1 19	0.93	0.9	2.27	0.97	21.8	15.5	17.0	32.89	14	16.5	17.9	19.2	15.3	12.9	13.48	13.77	12.5	14.2	12 9	18.32	time		
51.3	04.4	1 1	n 7 n	53.6	55.09	0.95	50.6	48.82									50.7	50.7	48.6	50.59	59.0	50.8	51 57	53.68	48.58	53.8	52.3	54.33	52.52	49.58	52.02	52.2	53.74	64.29	47.76	00.0	56.06	54.7	56.53	66.8	55.3	49.7	57.7	61.2	48.5	47.78	55.9	50	48.3	65.2	58.28	50.58	58.84	50.95		49.12		time		FREAK
υ r.	2 2		2 1	2:	21	2	2:	20											_							11		12	11	11		=	11								.										_							Total ti	9	
344.27	5 0	1 1	50 60	00	1.29	08 6	5.60	)9.47	151	147	146	129	127	133	138	138	59.85	9.85	6.71	8.84	68.00	9.60	9 67	72 60	35.78	)2.25	99.26	)1.69	)8.32	)8.23	106.06	)5.20	103.62	65.09	62 2	24.11	57.25	55.63	57.43	59.07	6.27	71.50	77 70	70 10	31.39	51.78	72.40	57.90	57.50	80.50	71.18	54.06	72.61	3.45	75.82	37.40	68.66	ne matches	No of	
									183.02	156.0	127	110.7	109.9	123.8	126.8	113.8																																											Detector	
									2 141.56																																																	L		AKAZE
									, 66	4		5	15	26	22																																												Descriptor	
104	s R	3 8	2 2	8	£	œ e	22	8	324.58	288.39	262.00	222.85	224.05	228.14	241.67	215.66									Tis.	15	19	19	17	18	16	19	ä¹	10	= 1	i t	114	E	11	12	ΕĪ	24	2 5	13 12	3 23	1 17	16	13	12	97	10	96	10	99	10	10	112	Total time m	z	
																																																										ches		
188.35																																65.55					0.79					25.44					ľ										12.08			SIFT
113.2	101.5	100.55	169 35	194.67	144.2	17.7	99.58	94.94																	65.5	73.6	68.2	74.04	72.7	103.73	86.64	77.07	58.74	33.26	10.47	36.00	30.3	38.4	40.7	47.67	10.23	18	75.7	32.52	27.9	25.98	27.723	26.26	25.07	17.67	23.66	17.32	27.64	16.5	17.47	17.69	19.91	time	Descriptor	T
301.55	27.2	370	224	377	324	257	259	237.																	117.36	125.69	117.	124.	137	157	138.47	142.	118.82	34.12	41	27	31.	39	41.	48	41	43.44	45	40.00	71.48	44	48.79	46.51	43.25	32	44	29	43.07	28.73	30.21	30.46	31.99	Total time		

#### MP.9 Performance Evaluation II

				[	Descriptor		
		BRISK	BRIEF	ORB	FREAK	AKAZE	SIFT
	Shi-Tomasi						
	Harris						
tor	FAST						
etecto	BRISK						
De	ORB						
	AKAZE						
	SIFT						

The performance evaluation was carried out as follows:

- All detector/descriptor combination that yield significantly low amounts of matches or significantly high computation times were directly excluded and are indicated in red in the table above. Some of these combinations required a computation time of several hundreds of milliseconds, which might be critical in real-time applications, depending on the computation time of the rest of the processing pipeline. The rest of the eliminated combinations only found fewer than a hundred matches, which is comparatively low.
- 2. The remaining combinations from step 1 are combinations of the Shi-Tomasi, FAST and BRISK detectors with multiple descriptors. So the next step was to determine the best combination for each detector type, which yields the Shi-Tomasi/BRIEF, FAST/BRIEF and BRISK/BRIEF combinations, as indicated in green in the table above.
- 3. Since the results of all three combinations are similar in terms of computation power and number of matches (2-50 ms and over 100 matches), another metric for the comparison could be the relation between the number of matches to the number keypoints detected. This metric shows how many keypoints could not be matched or were too ambiguous and were filtered out by the distance ratio. The results are shown in the table below.

With the highest matches-to-keypoints percentage and the fastest computation time, the FAST/BRIEF can be considered the best combination. Since it has the highest absolute number of matches and a larger neighborhood size, the BRISK/BRIEF combination can be considered second best. With a relatively high computation time and a relatively low amounts of keypoints and matches, the Shi-Tomasi/BRIEF combination comes last.

	Average		
	no. of	Average no.	Percentage of
Combination	keypoints	of matches	matches
Shi-Tomasi/BRIEF	118.00	105.00	88.98
FAST/BRIEF	134.00	122.00	91.04
BRISK/BRIEF	267.00	189.00	70.79