

# Final Report

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## Group Members

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Yang Haocheng 1004883

Lu Mingrui 1005354

## 1. Problem Statement

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This project aims to develop a deep learning model that can accurately classify CT scans as either COVID-19 positive or negative, using a dataset of labeled CT scans of COVID-19 and non-COVID-19 patients. It can aid healthcare professionals in accurately and quickly diagnosing COVID-19 from CT scans.

## 2. Dataset and Collection

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We collected a dataset of COVID-19 chest CT scans from various sources, including publicly available datasets and hospitals. The dataset consists of 500 CT scans from COVID-19 positive patients, and 500 CT scans from healthy patients. The CT scans were collected from different hospitals across the world, using different CT scanner models and settings. The dataset was annotated by radiologists to indicate the presence or absence of COVID-19 infection.

the source: <https://github.com/UCSD-AI4H/COVID-CT/tree/master/Images-processed>

## 3. Data Pre-processing

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This code is used to split a dataset consisting of CT scans of patients into a training set and a test set. The dataset contains two classes: COVID-19 scans and non-COVID-19 scans. The code first creates two directories to store the COVID and non-COVID images separately. It then loops through each image in the original dataset and copies it to the appropriate directory while also appending its file path to the `data_target` list and its label to the `data_label` list.

Next, the code uses the `train_test_split` function from the `sklearn` library with `test_size=0.3` to randomly split the `data_target` and `data_label` lists into a training set and a test set. The training set and test set are each split into two subdirectories, one for COVID images and one for non-COVID images. The images in each set are then copied to their respective subdirectories.

## 4. Algorithm/Model:

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# Data Augmentation

In this project we generate an ImageDataGenerator that reads image data, reads image files, decodes jpeg images into RGB pixel networks, converts these pixels into floating-point tensors and scales them between 0 and 1.

And we also performed data augmentation via ImageDataGenerator to make our model more robust.

```
train_datagen = tf.keras.preprocessing.image.ImageDataGenerator(  
    rescale=1. / 255,  
    rotation_range=40,  
    width_shift_range=0.2,  
    height_shift_range=0.2,  
    shear_range=0.2,  
    zoom_range=0.2,  
    horizontal_flip=True,  
    fill_mode='nearest')
```

After preprocessed by ImageDataGenerator, the images are shaped into (150, 150, 3)

ImageDataGenerator parameters are introduced as follows:

rotation\_range is an angle value (in the range of 0~180), indicating the angle range of the random rotation of the image.

width\_shift and height\_shift are the extent to which the image is shifted horizontally or vertically (relative to the total width degree or overall height).

shear\_range is the angle of the random shear transformation.

zoom\_range is the range in which the image is randomly zoomed.

horizontal\_flip randomly flips the image horizontally.

fill\_mode is the method used to fill newly created pixels, which may come from rotation or width/height translation.

## Our Model

Here we decided to use Convolutional Neural Network to capture spatial dependency and utilize monophily of pixels. The model is structures inside `cnn.py`.

The total number of parameters to be trained is: 3453121, the size of the first layer convolution kernel is: 33, the number of convolution kernels is 32, and the activation function is RELU; the second layer is the pooling layer, pooling The size is 22, the third layer convolution kernel size is: 33, the number of convolution kernels is 64, and the activation function is RELU; the fourth layer is a pooling layer, and the pooling size is 2 2. The size of the fifth layer convolution kernel is: 33, the number of convolution kernels is 128, and the activation function is RELU; the sixth layer is the pooling layer, the pooling size is 22, and the seventh layer The size of the convolution kernel is 33, the number of convolution kernels is 128, and the activation function is RELU; the eighth layer is the pooling layer, and the pooling size is 22, and the ninth layer uses the size of the eighth layer Perform tiling, then add the DROUPOUT layer, randomly drop 50% of the convolution kernel, add a dropout layer to further improve the recognition rate, then add a fully connected layer with a length of 512, the activation function is RELU, and finally add a classification layer , the classification function is SIGMOID.

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 148, 148, 32)	896
max_pooling2d (MaxPooling2D)	(None, 74, 74, 32)	0
conv2d_1 (Conv2D)	(None, 72, 72, 64)	18496
max_pooling2d_1 (MaxPooling2D)	(None, 36, 36, 64)	0
conv2d_2 (Conv2D)	(None, 34, 34, 128)	73856
max_pooling2d_2 (MaxPooling2D)	(None, 17, 17, 128)	0
conv2d_3 (Conv2D)	(None, 15, 15, 128)	147584
max_pooling2d_3 (MaxPooling2D)	(None, 7, 7, 128)	0
flatten (Flatten)	(None, 6272)	0
dropout (Dropout)	(None, 6272)	0
dense (Dense)	(None, 512)	3211776
dense_1 (Dense)	(None, 1)	513
Total params: 3,453,121		
Trainable params: 3,453,121		
Non-trainable params: 0		

## Hyperparameters tuning

First we have decided to Evaluate performance of model using **Accuracy**, so that we can decide the best combination of hyperparameters through choosing the combination with best accuracy on validation set.

### Learning rate, num of epochs, optimizer

For these we are using grid search to determine the best combination

For learning rate we have tried 1e-2, 1e-3, 1e-4, 1e-5;

For num of epochs we have tried 100, 200, 500, 1000;

Finally we decided to use RMSprop with learning\_rate=1e-4 and train for 500 epochs with batchsize 20.

### Structure of model

We have combined the method of grid search and random search when deciding the structure of model.

Which is use random search initially to explore the hyperparameter space to determine the size of filters, number of layers, etc. Then use grid search to fine-tune the optimal values.

## 5. Evaluation Methodology:

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### Loss function: Binary Cross-entropy

The Binary cross-entropy loss function is often used in binary classification problems.

### Evaluation metric of model: Accuracy on test set

The dataset is split into training set and a test set with `test_size=0.3` randomly. And the effectiveness of model is reflected via the accuracy on test set.

Accuracy is the easiest to understand. It refers to the samples that are correctly classified in all samples, including all sample categories.

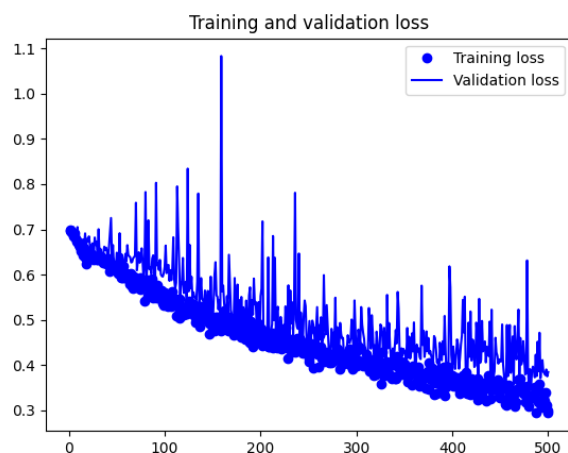
## 6. Results

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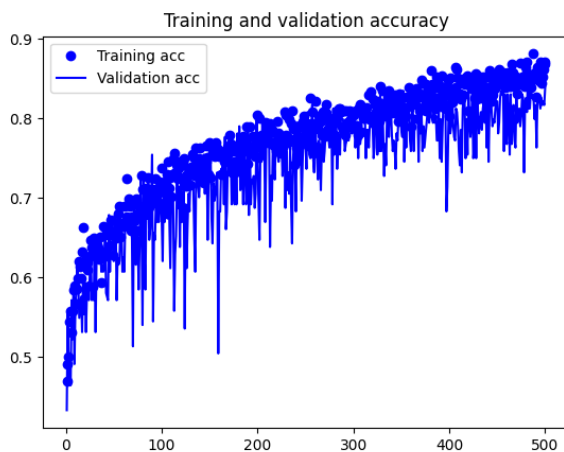
Here we use 500 epochs, and the number of CT images for each training iteration(batch size) is 50, and the number of test images is also 50 for one validation.

The training error at the beginning is relatively large. As the number of epochs gradually increases, training The error gradually decreases and tends to be stable, and the validation accuracy gradually increases.

The results of training loss and validation loss are as follows:



The results of the training set and validation set on the accuracy index are as follows:



Finally, the accuracy of our model on the test set is: **0.8393**.

## 7. Compare our model with existing ones

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In this project we also use transfer learning where we use a pre-trained model as a starting point for a new task and compared its performance with our final model which we build and train from scratch

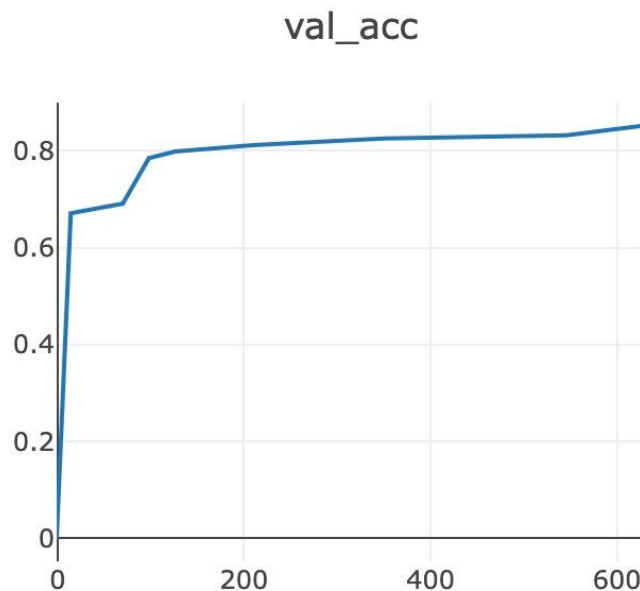
Firstly, we loaded a pre-trained model ResNet-18 with its weights which is a pre-trained convolutional neural network architecture that has shown remarkable performance on the ImageNet dataset. So it possibly has better ability to extract meaningful features from images than our final model.

Then we extract the pre-trained model's feature extractor layers, which exclude the final classification layer. The original last layer of ResNet-18 is a fully connected layer that outputs a tensor of shape [batch\_size, num\_classes], where num\_classes is the number of classes in the ImageNet dataset. Since our new task is binary classification task (COVID-19 vs Non-COVID-19), we need to remove this last layer and replace it with our own classification layer.

Thus we need to flatten the output of the feature extractor layers to a 1D tensor first. This is necessary because the output of the ResNet-18 feature extractor layers has a shape of [batch\_size, num\_channels, height, width], where num\_channels, height, and width depend on the size of the input image. We need to flatten this tensor to a 1D tensor so that we can pass it through the fully-connected classification layer. Finally, we add a full-connected layer with 512 input features (which is the output size of the last convolutional layer in ResNet-18) and 2 output features (which is the number of classes in our new binary classification task). This layer is the classification layer that maps the output of the feature extractor layer to the binary classification output.

Overall, in this transfer learning we created a new model that reuses the pre-trained ResNet-18 architecture for feature extraction and replaces the final classification layer with a new binary classification.

The accuracy on test set of the model with transfer learning is **0.82666**



And when we compare the performance of this pre-trained model with our final model, the result turns out that our own model has the better performance. We think the reason is because transfer learning models require a large amount of data to learn meaningful representations. but our dataset is relatively small so ResNet-18 may not have enough data to learn good representations, and another reason we think is because ResNet-18 was pre-trained on the ImageNet dataset, which is a very large dataset of diverse natural images but our own dataset contains only COVID-19 chest CT scans which is a very different images distribution from the ImageNet dataset, hence ResNet-18 may not be able to learn meaningful representations for our specific task. So finally we still choosed our own CNN model which we build and train from scratch as our final model.

## Steps to re-train the model from scratch

### required libraries

`tensorflow 2.12.0`, `matplotlib`, `scikit-learn 1.2.2`, `PIL`, `shutil`

### Step1

The original project folder is structured in this way:

```
.
├── dataset/
│   ├── CT_COVID
│   └── CT_NonCOVID
├── cnn.py
├── inference.py
├── data_preprocess.py
└── main.py
```

Run `data_preprocess.py` to preprocess the `dataset` and generate `train_set` and `test_set`

Detail of the code for `data_preprocess.py` can refer to '3. Data Pre-processing'

After running the file the folder will look like this:

```
.
├── dataset/
│   ├── CT_COVID
│   └── CT_NonCOVID
├── covid
├── non_covid
├── train_set/
│   ├── covid
│   └── non_covid
├── test_set/
│   ├── covid
│   └── non_covid
├── cnn.py
├── inference.py
├── data_preprocess.py
└── main.py
```

## Step2

Run `main.py`

This will trigger training on `train_set` and validation on `test_set`

After the training is done the model will be saved to `savedmodel/ourmodel`

The figure for Training and validation acc/loss will also be saved as `accuracy.png` and `loss.png`

After running the file the folder will look like this:

```
.
├── dataset/
│   ├── CT_COVID
│   └── CT_NonCOVID
├── covid
├── non_covid
├── train_set/
│   ├── covid
│   └── non_covid
├── test_set/
│   ├── covid
│   └── non_covid
├── cnn.py
├── inference.py
├── data_preprocess.py
├── main.py
└── savedmodel/
```

```
|   └─ ourmodel
|   └─ accuracy.png
|   └─ loss.png`
```

## How to make prediction using our trained model

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This can be done by changing the path of Input CT scan inside `inference.py` and run `inference.py`

The result will be printed.

## How to recreate the exact trained model

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The trained model is saved in `savedmodel/ourmodel`

This can be done by loading the trained model via `reconstructed_model =`  
`tf.keras.models.load_model("savedmodel/ourmodel")`