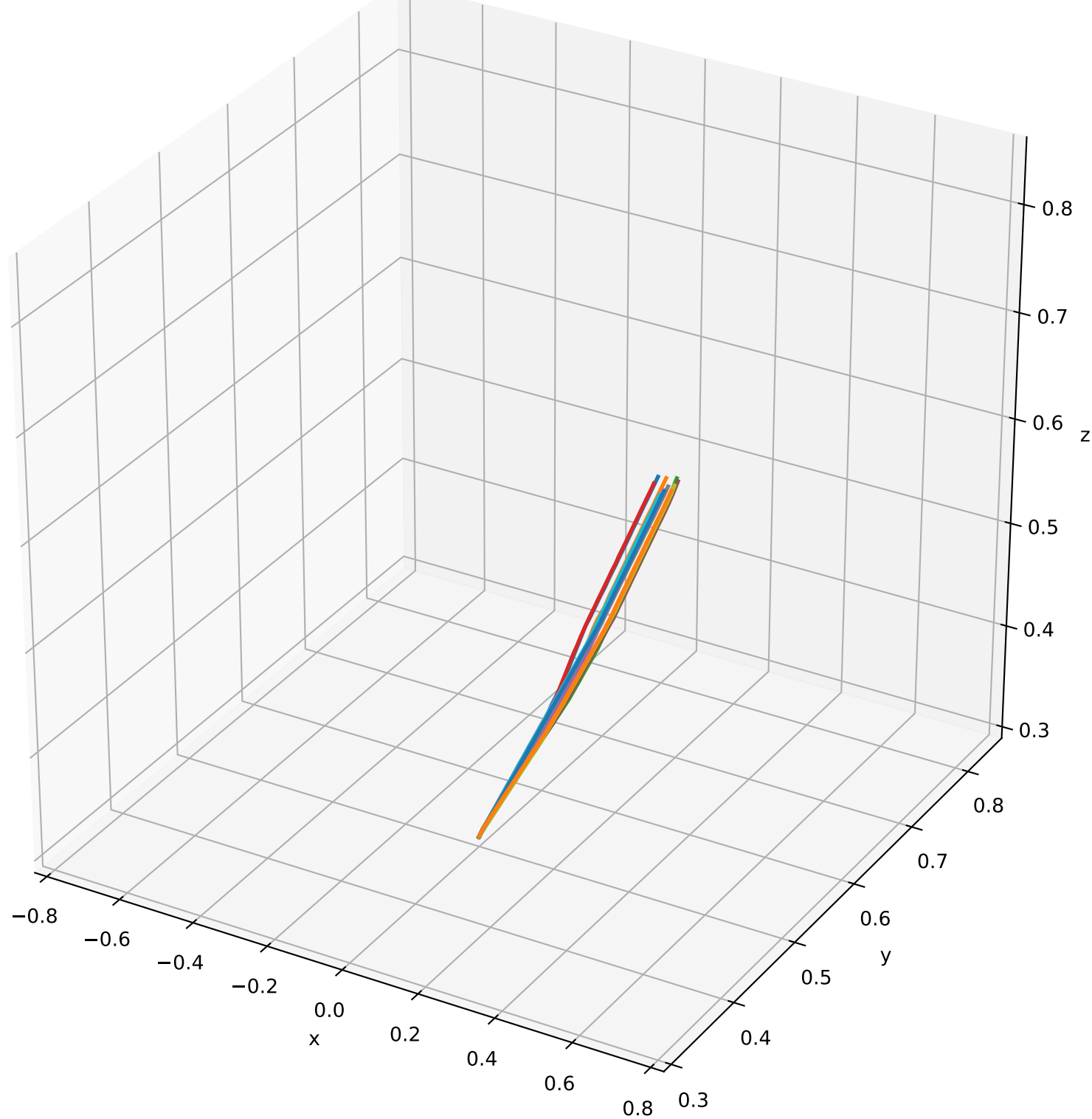
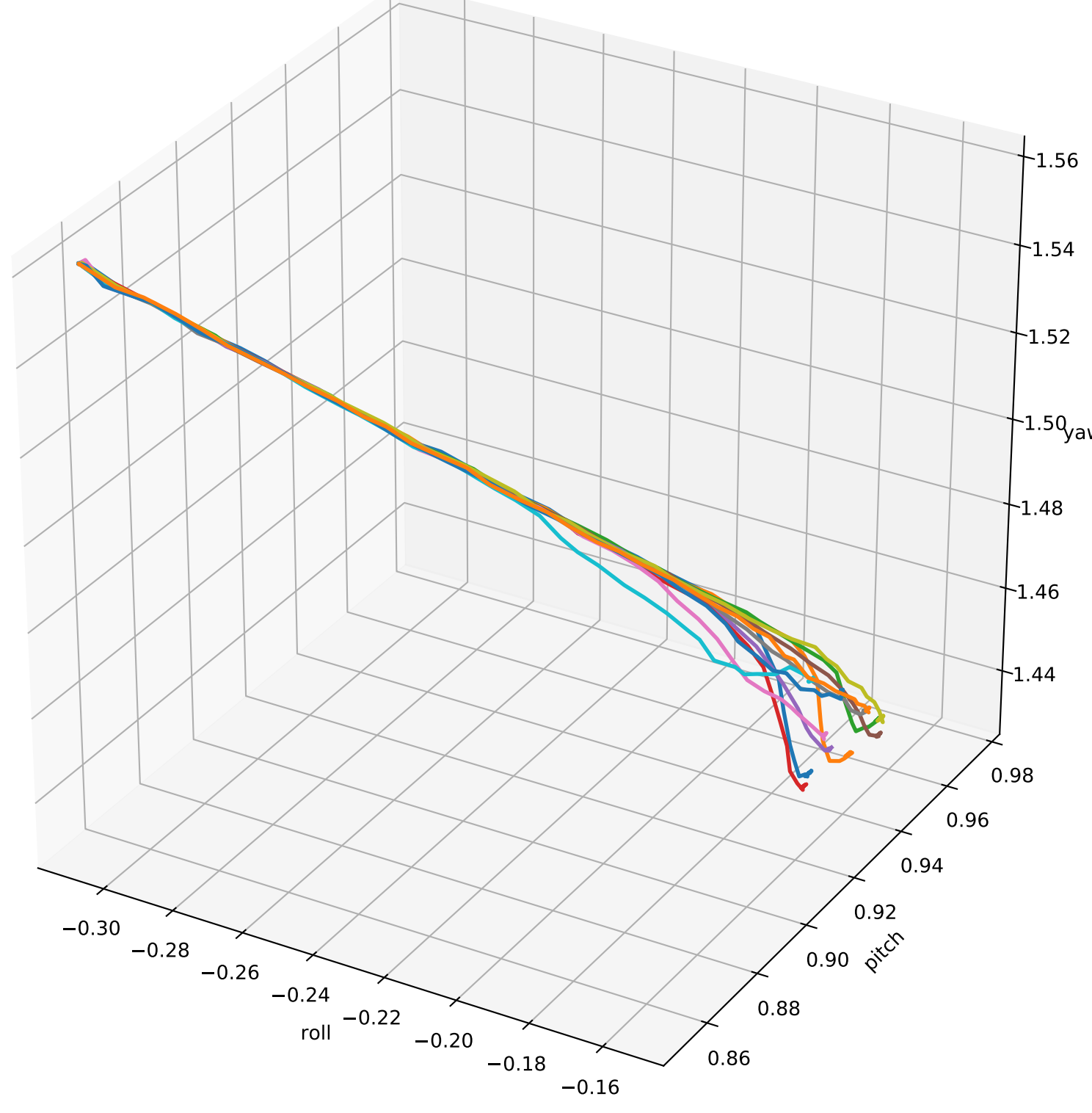


Derivative learning method, experiment 4  
init\_pose = [0.178, 0.395, 0.376, -0.308, 0.851, 1.561]  
goal\_pose = [0.447, 0.585, 0.738, -0.094, 0.888, 1.448]

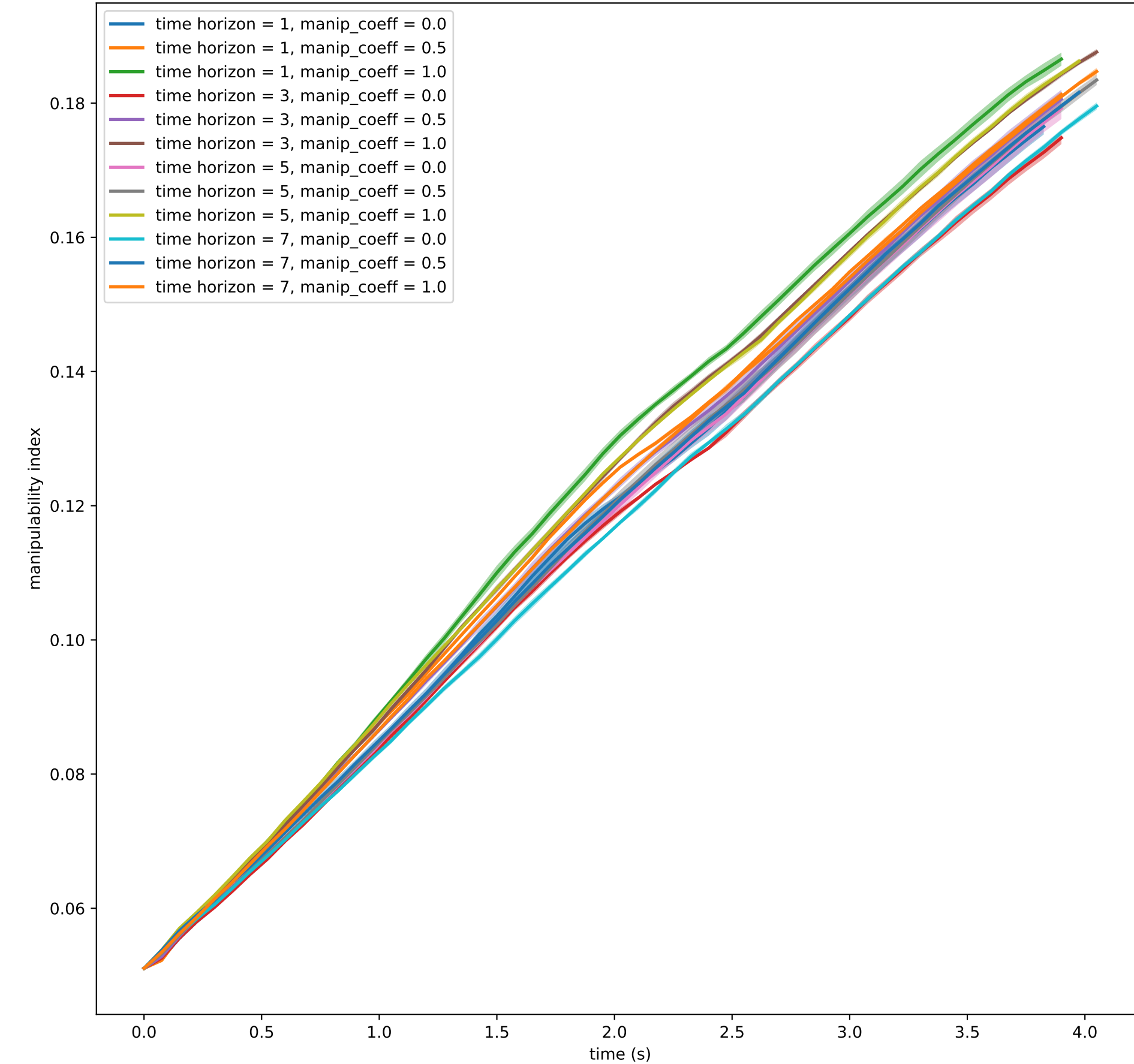
trajectory (translation)



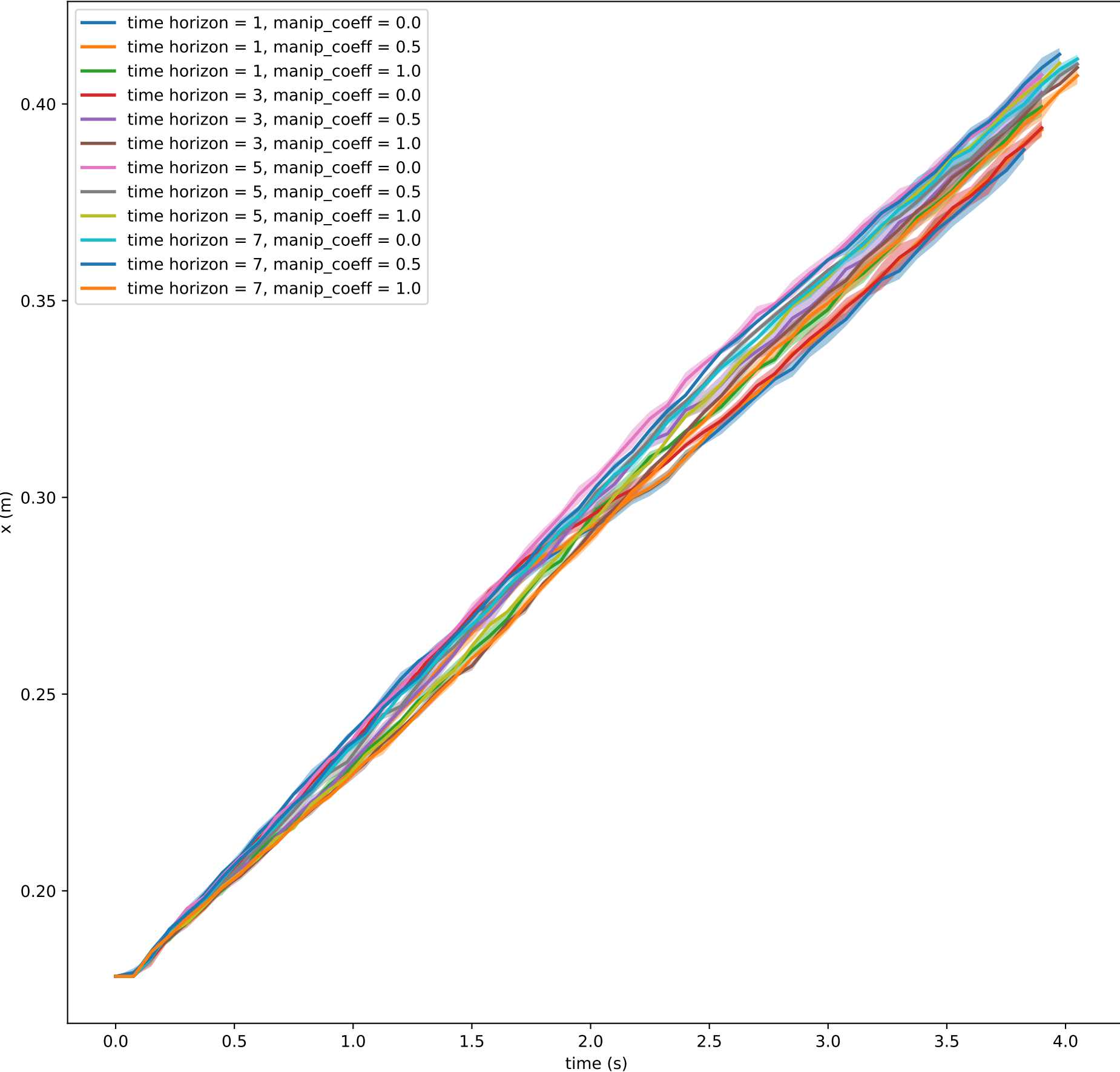
trajectory (orientation)



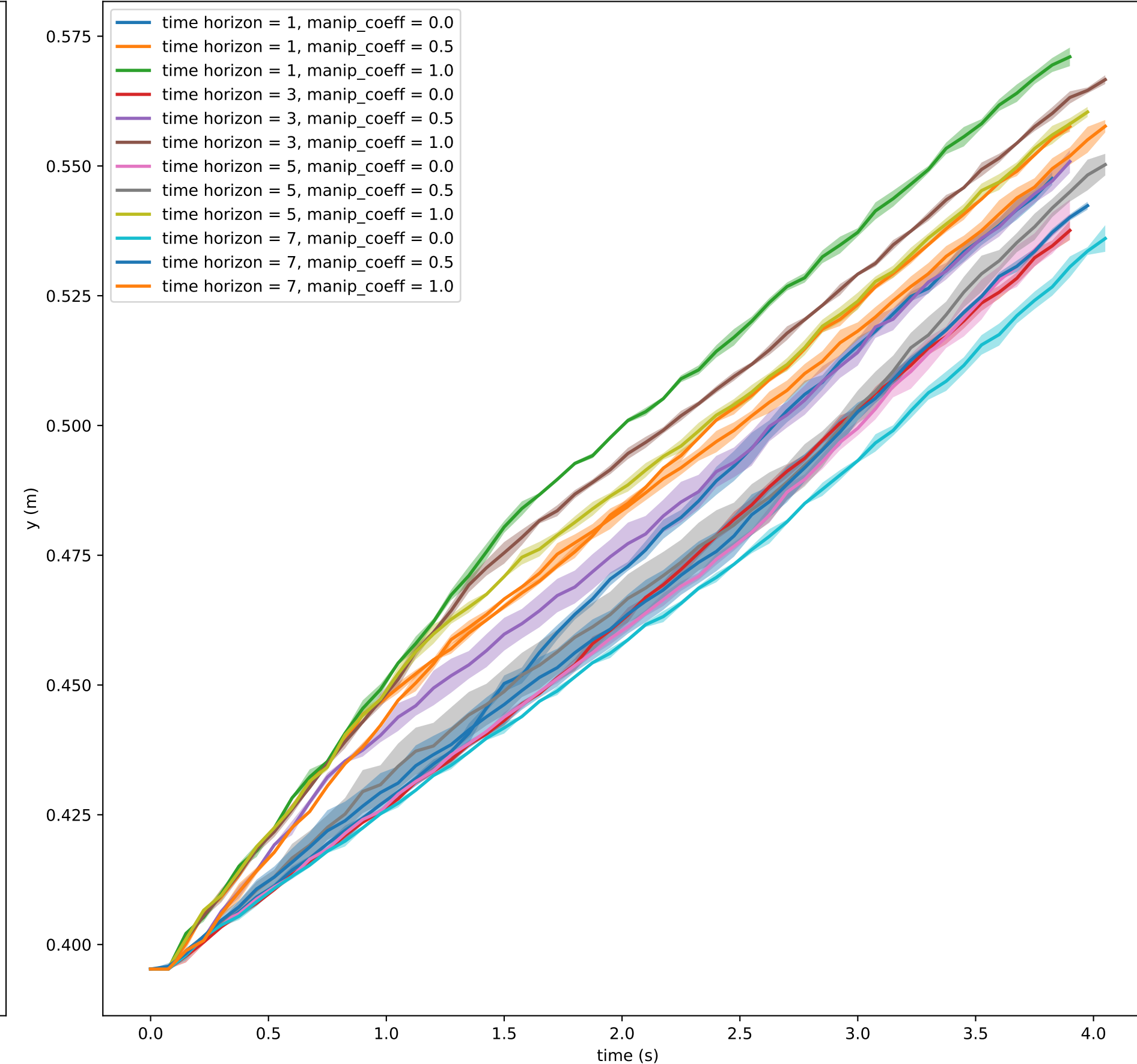
manipulability index



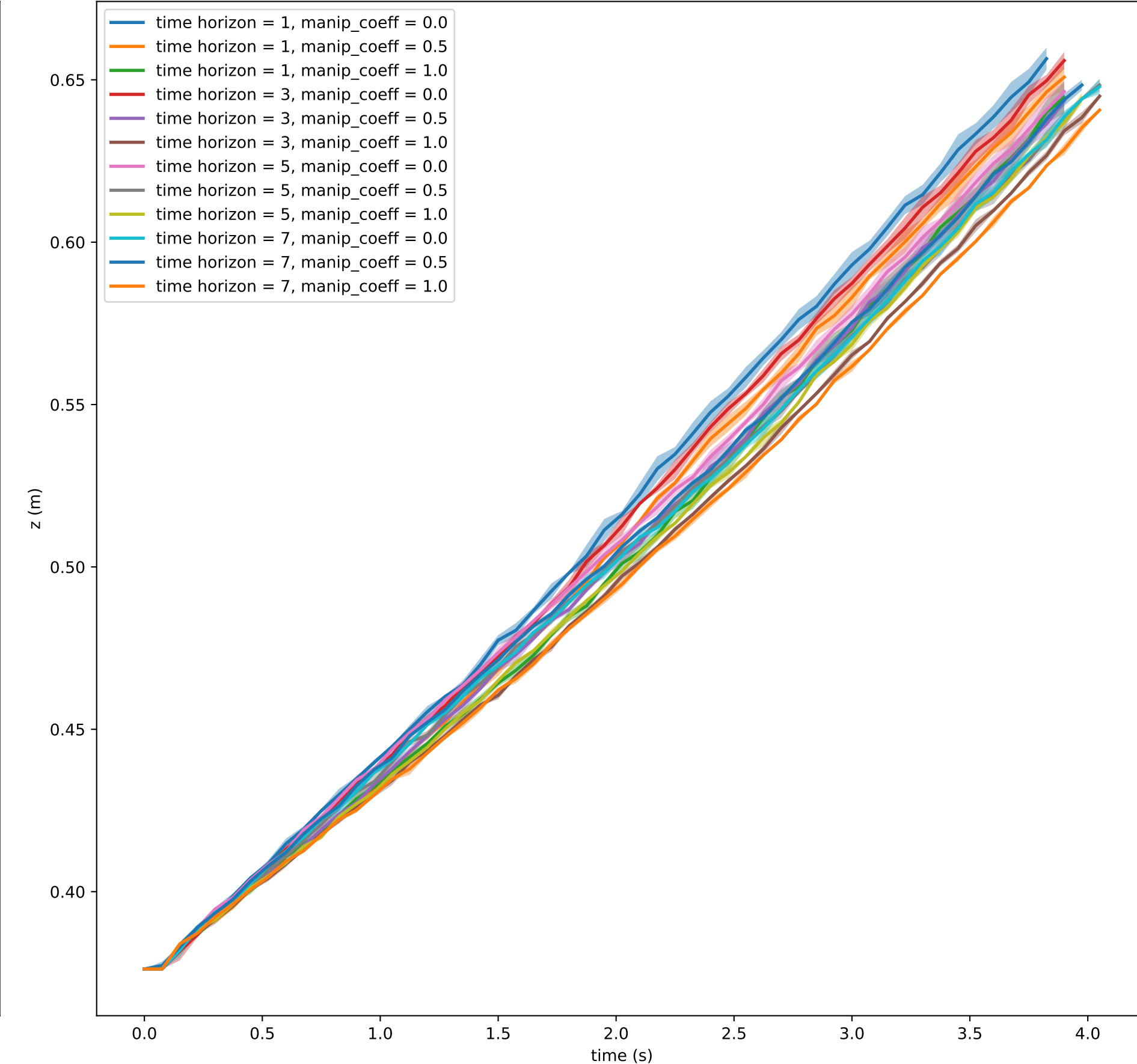
trajectory (x)



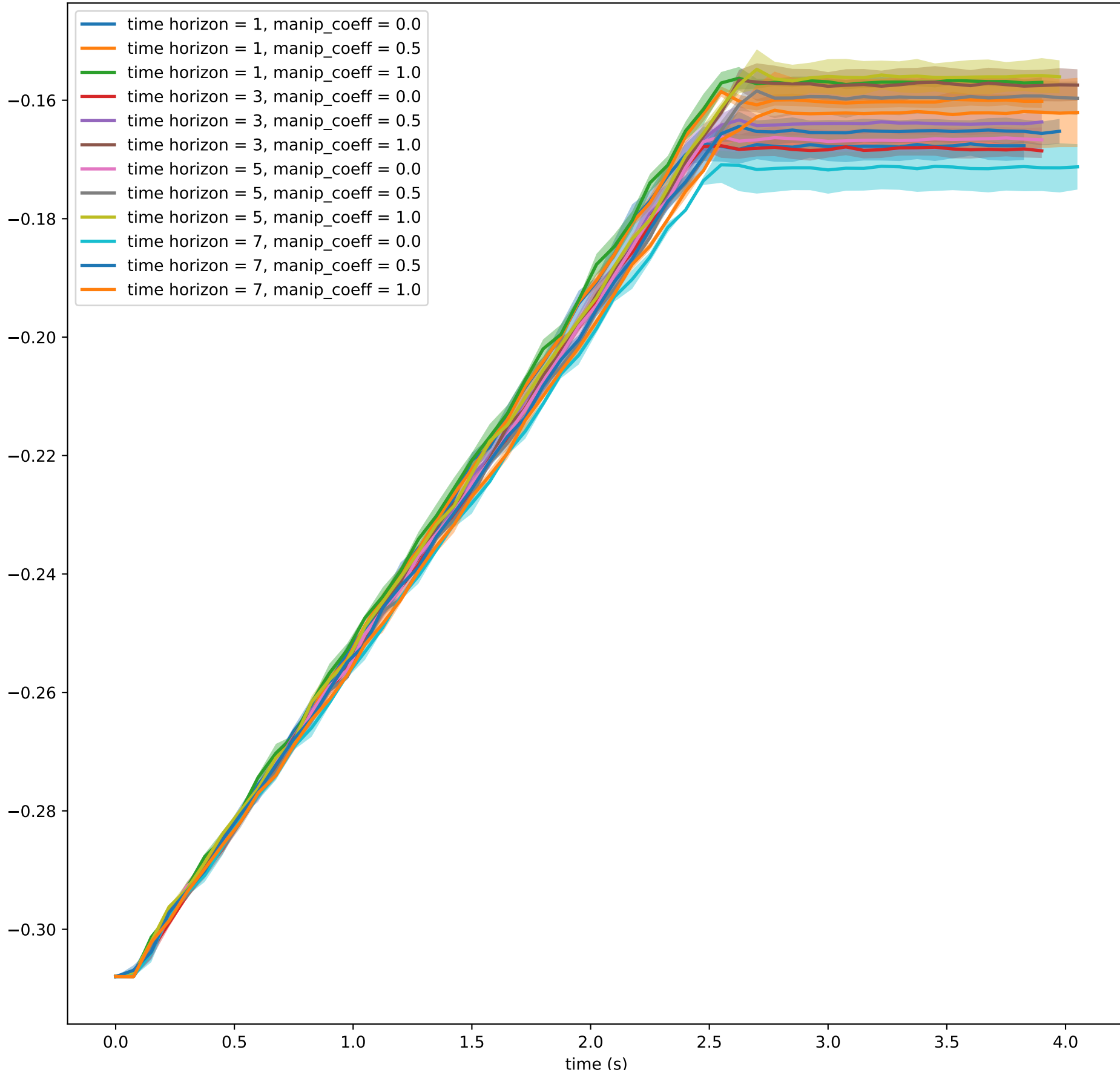
trajectory (y)



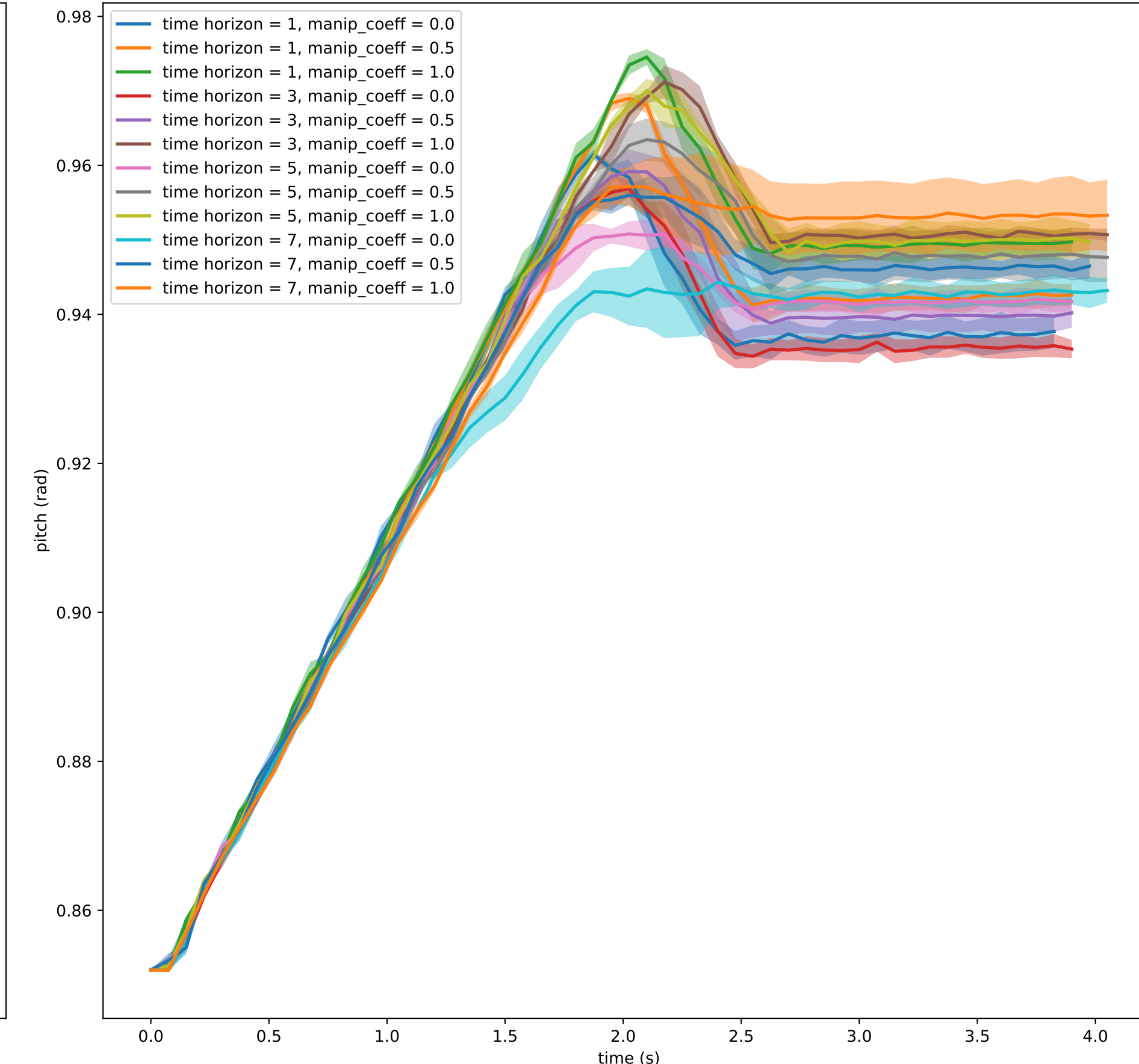
trajectory (z)



trajectory (roll)



trajectory (pitch)



trajectory (yaw)

