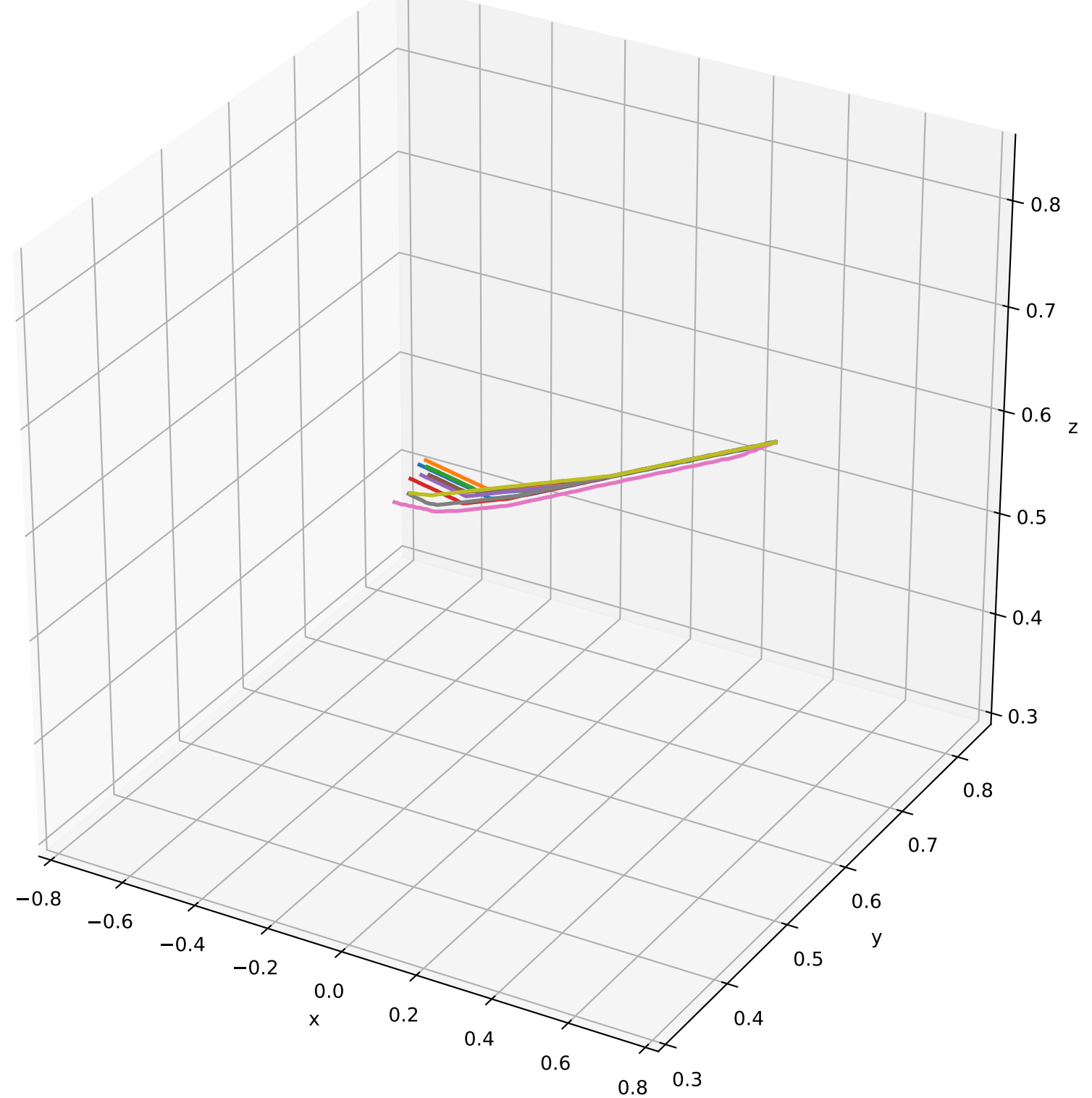
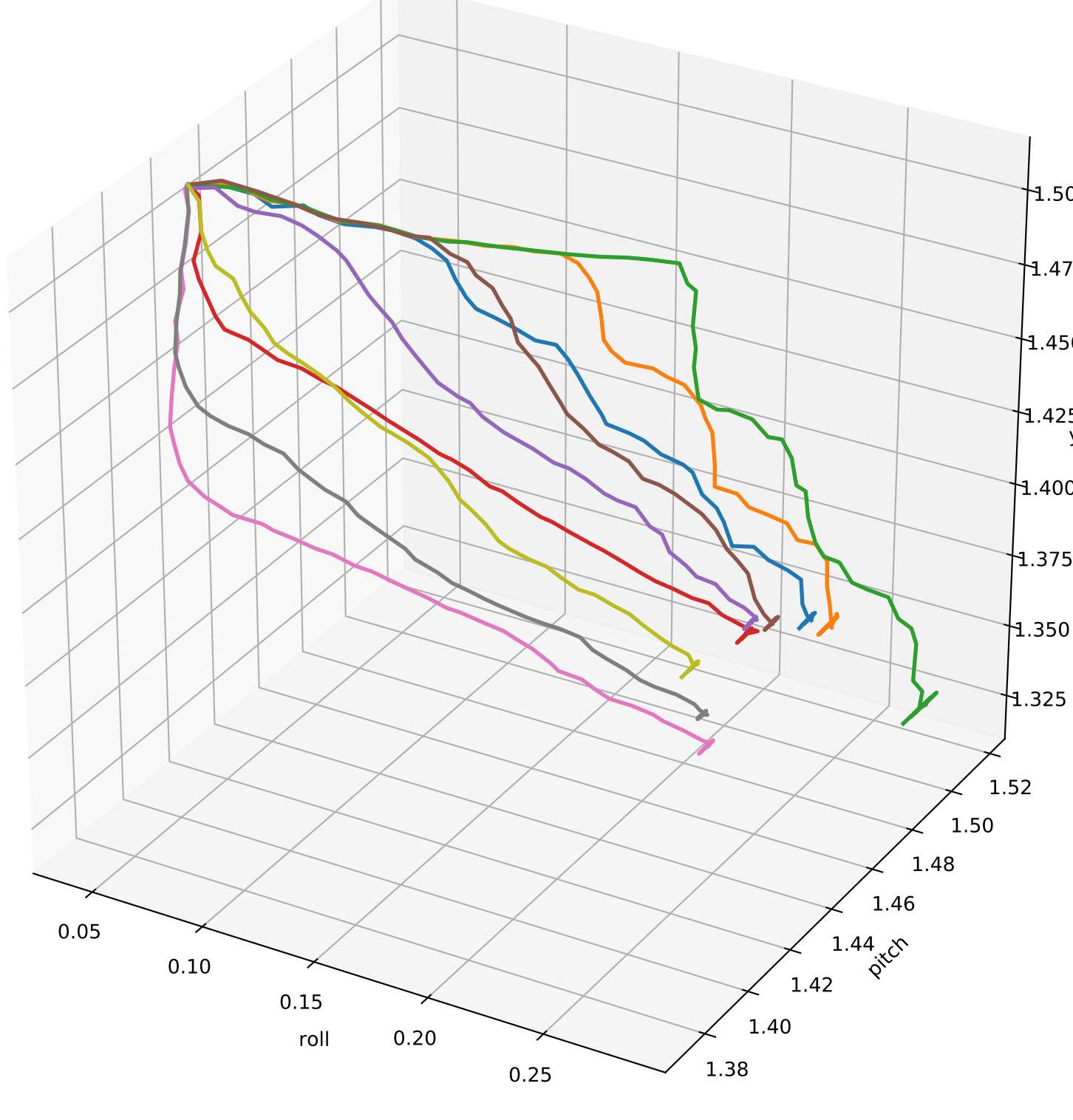


Naive learning method, experiment 1
init_pose = [0.306, 0.809, 0.544, 0.040, 1.418, 1.512]
goal_pose = [-0.378, 0.584, 0.618, 0.188, 1.511, 1.286]

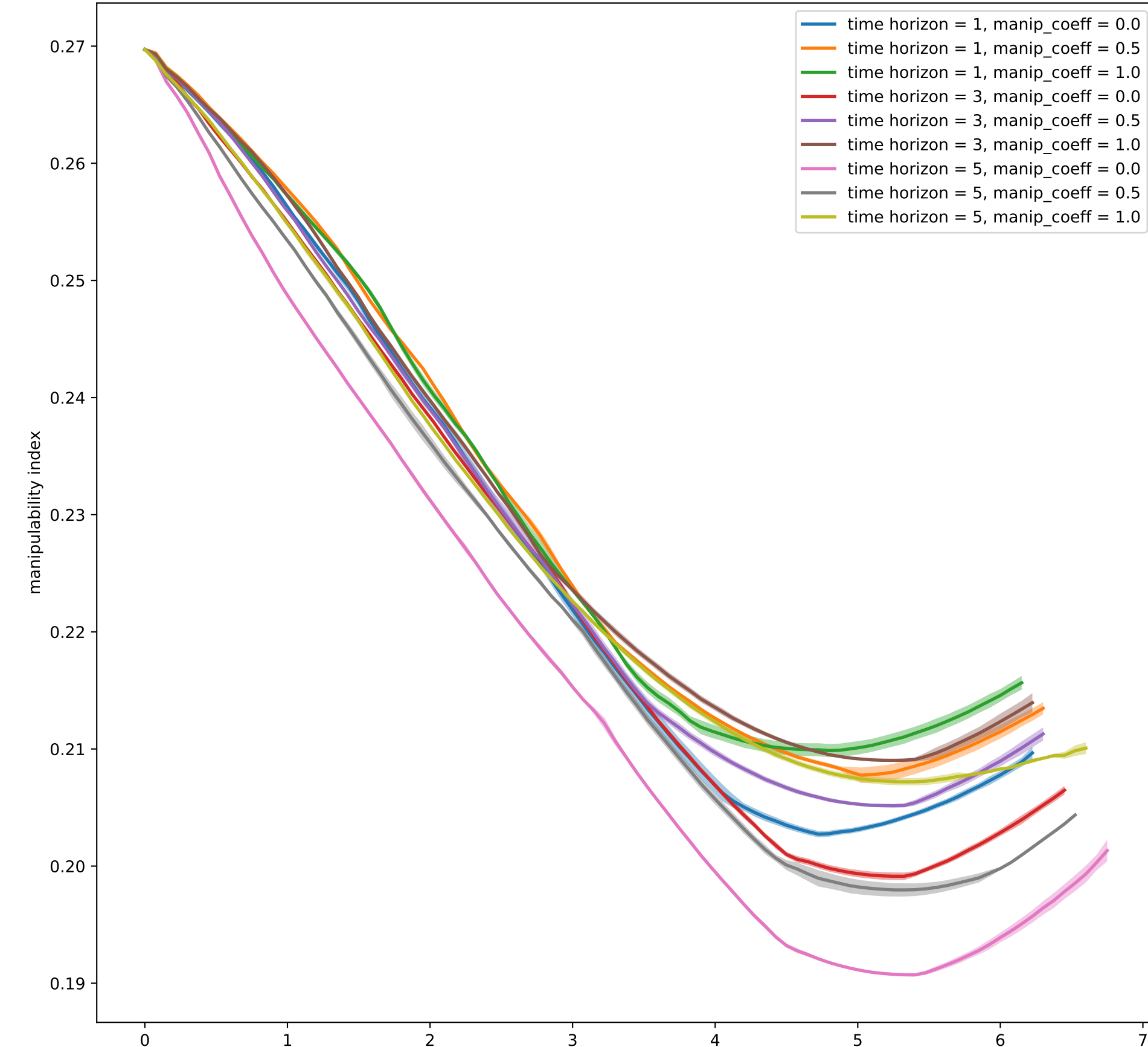
trajectory (translation)



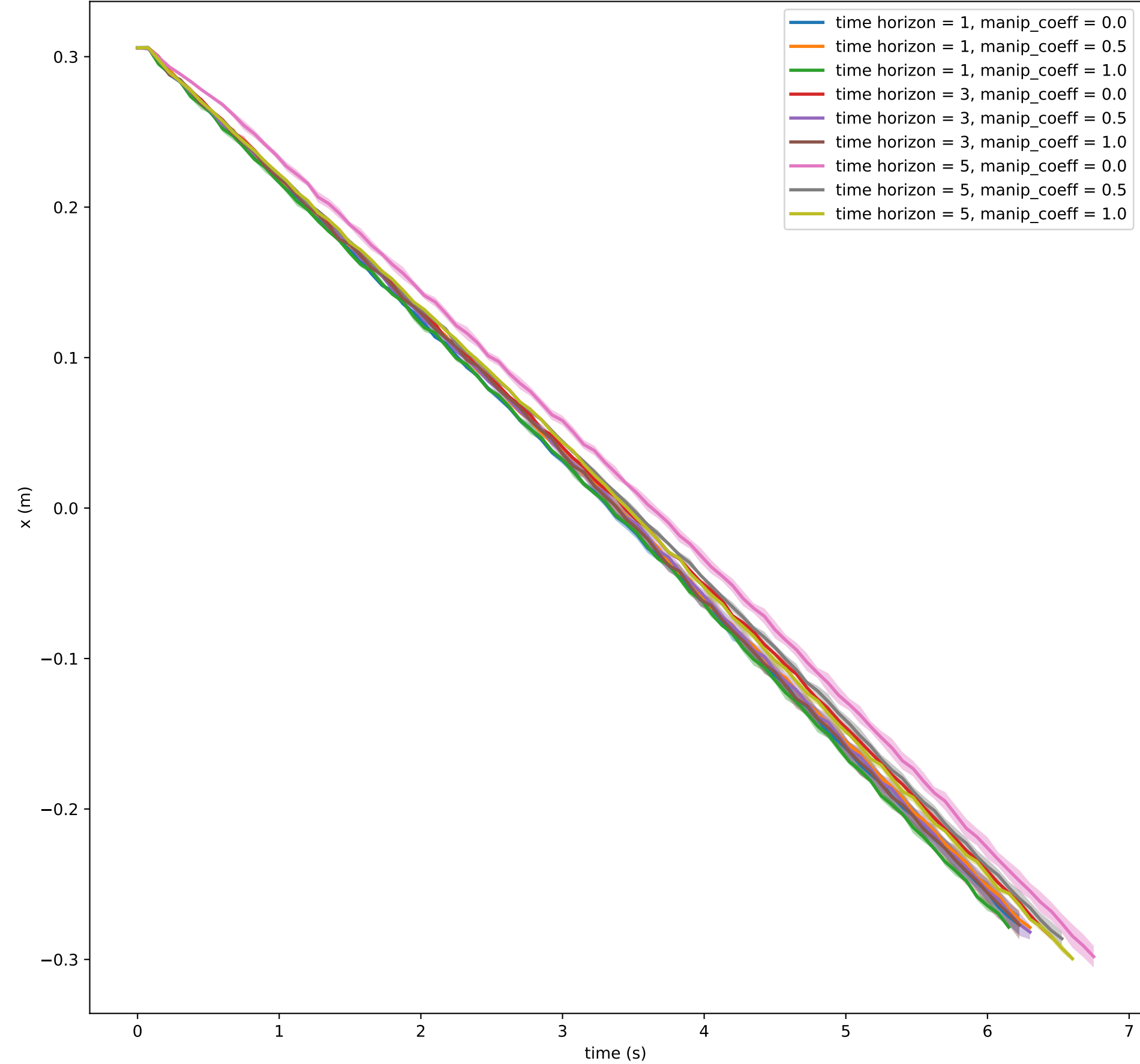
trajectory (orientation)



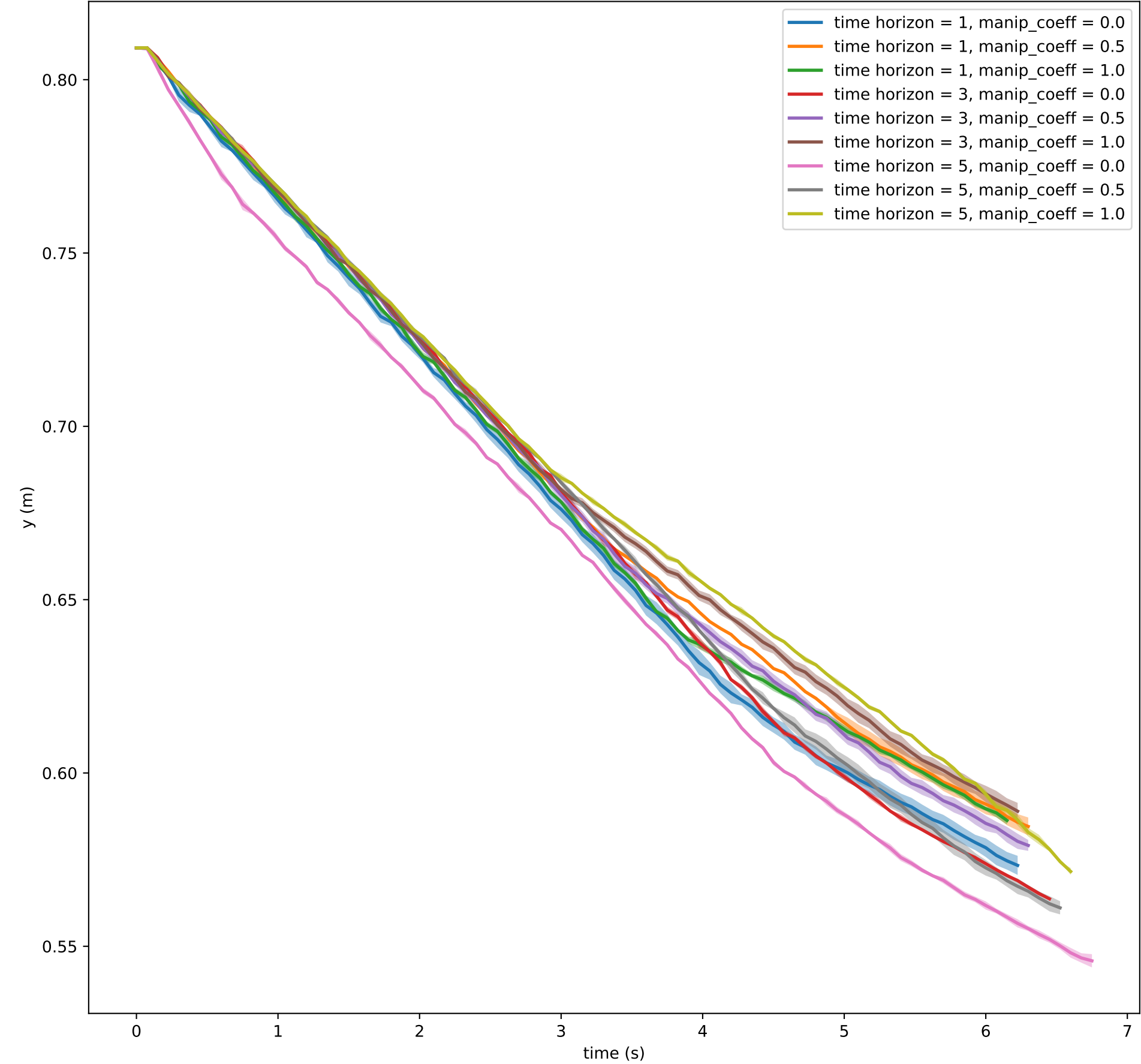
manipulability index



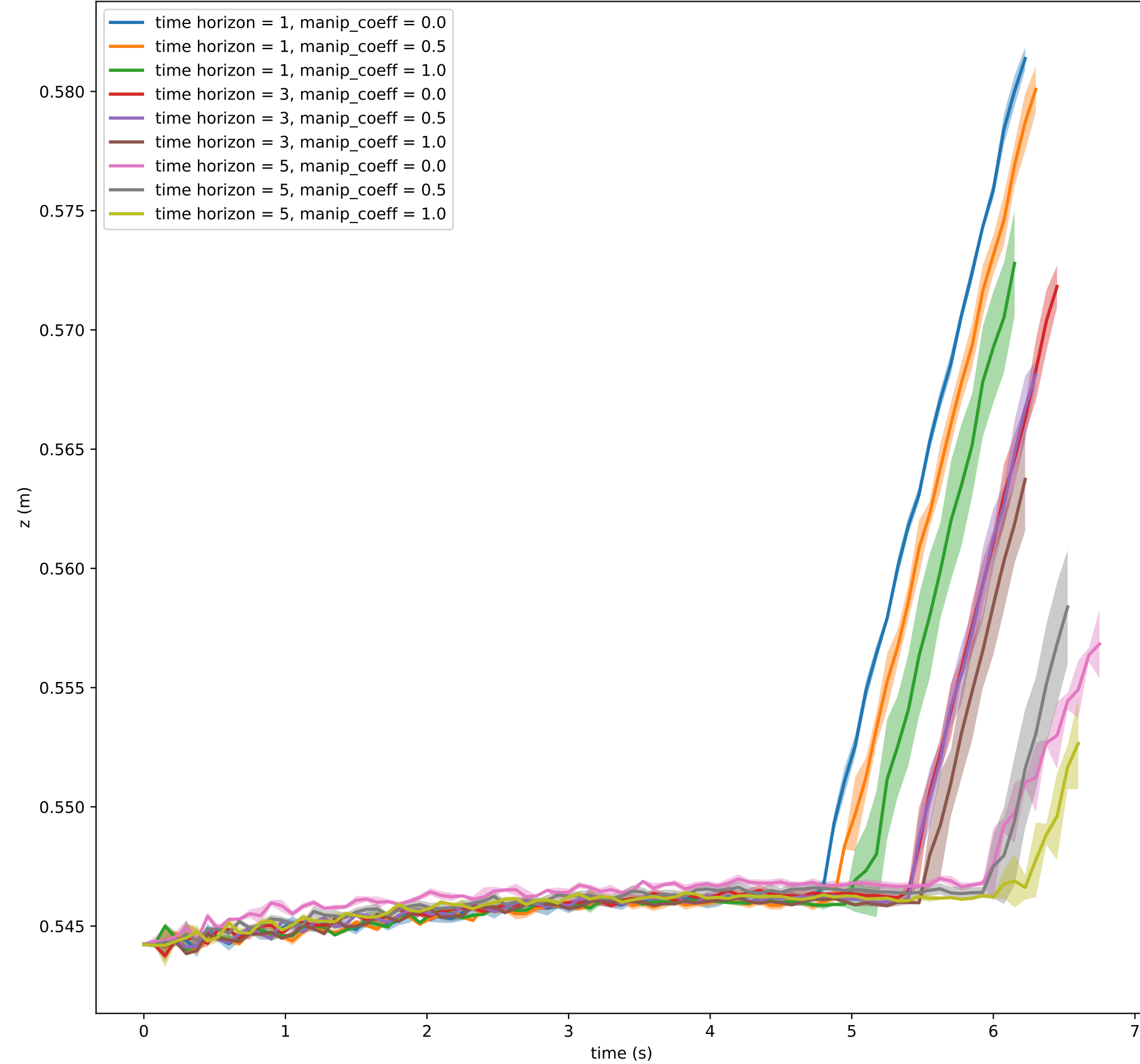
trajectory (x)



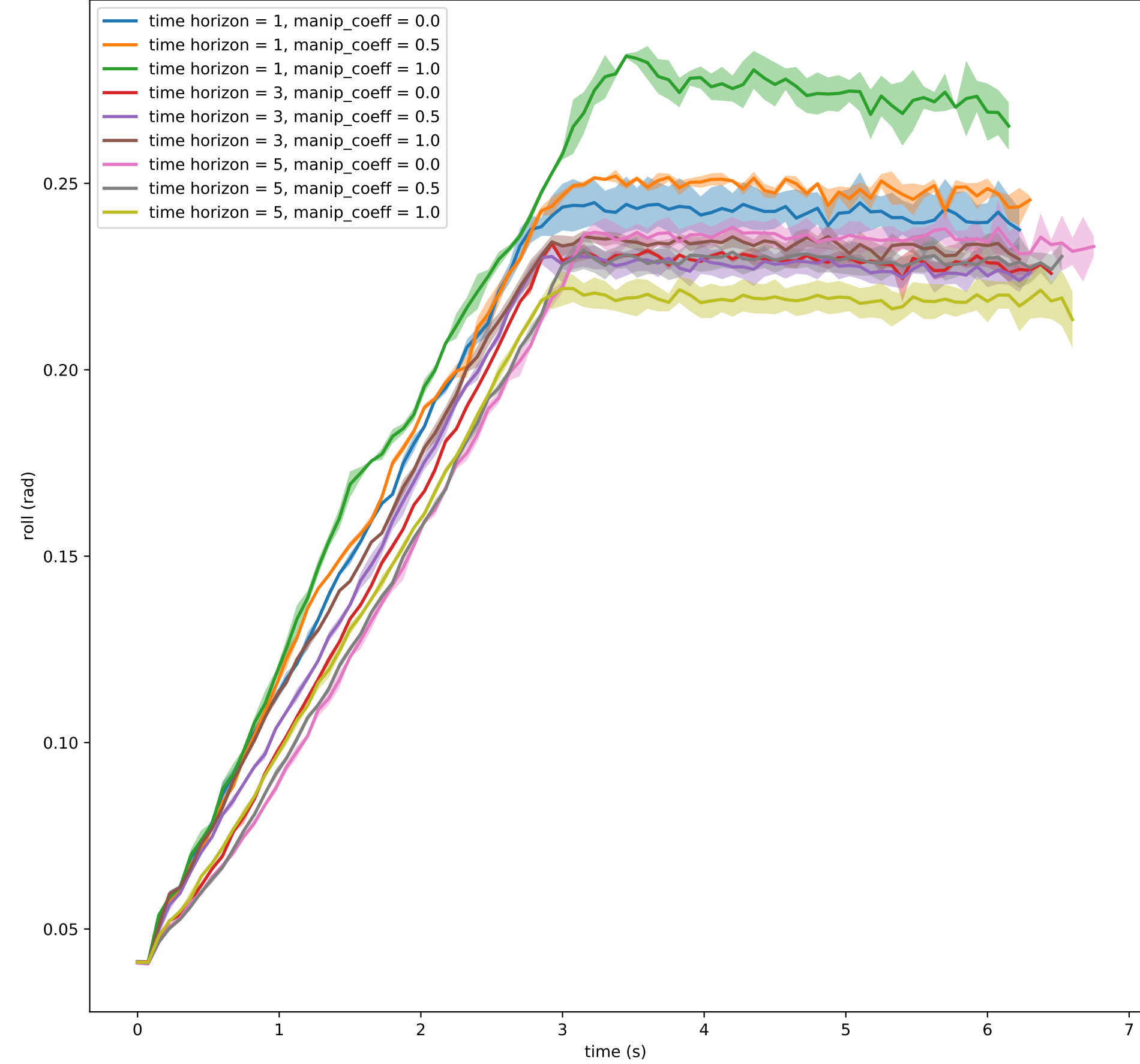
trajectory (y)



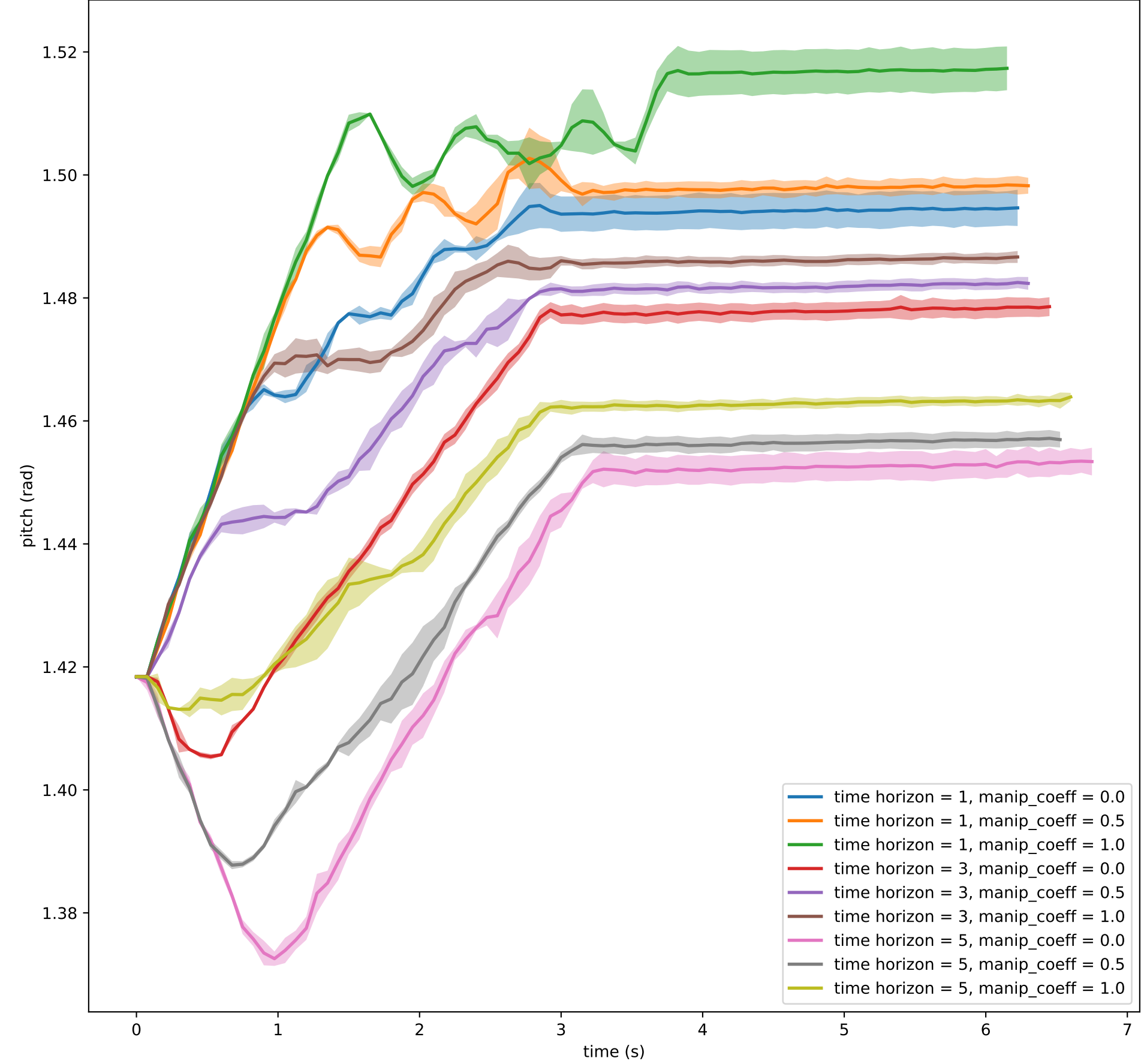
trajectory (z)



trajectory (roll)



trajectory (pitch)



trajectory (yaw)

