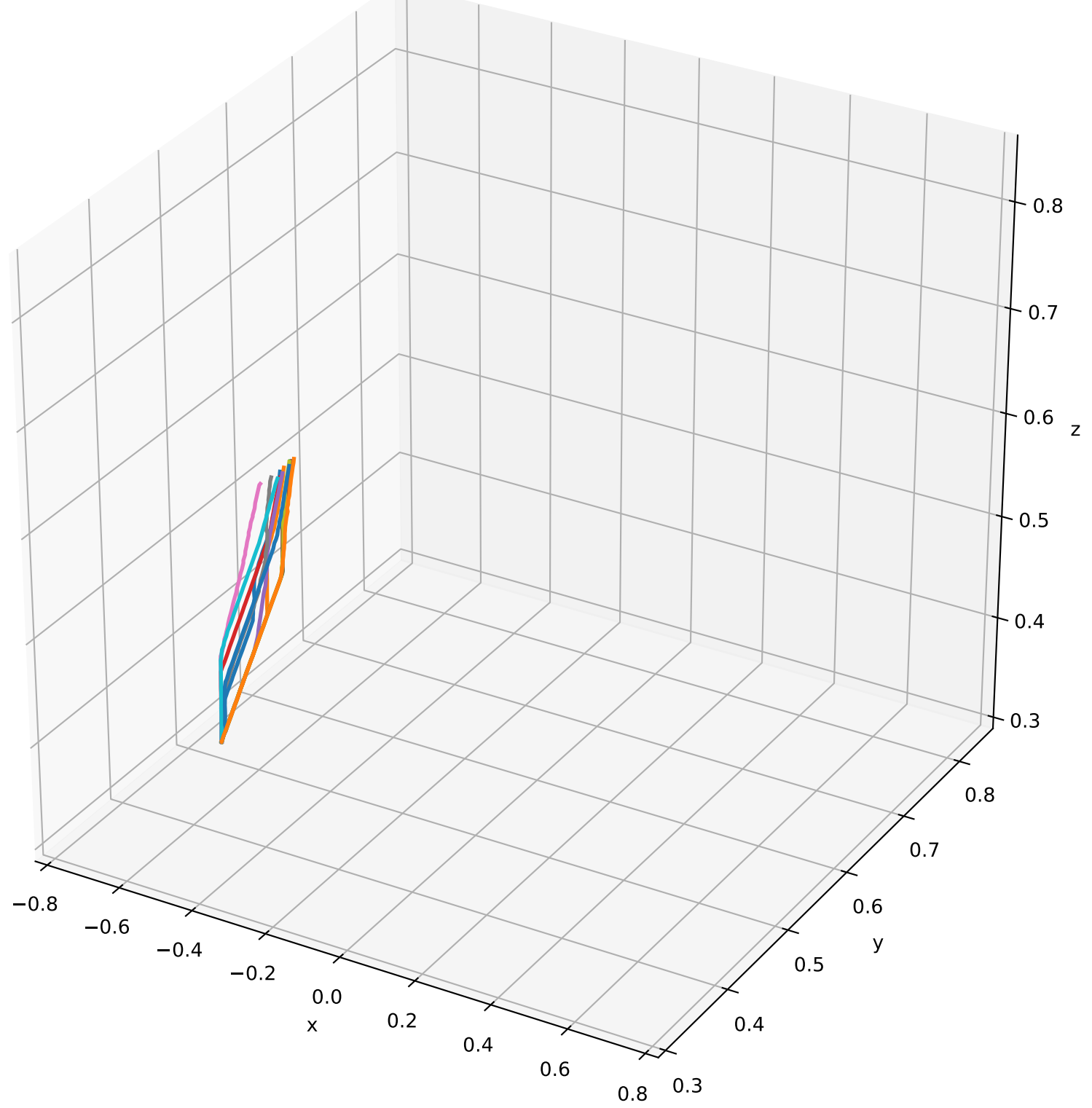
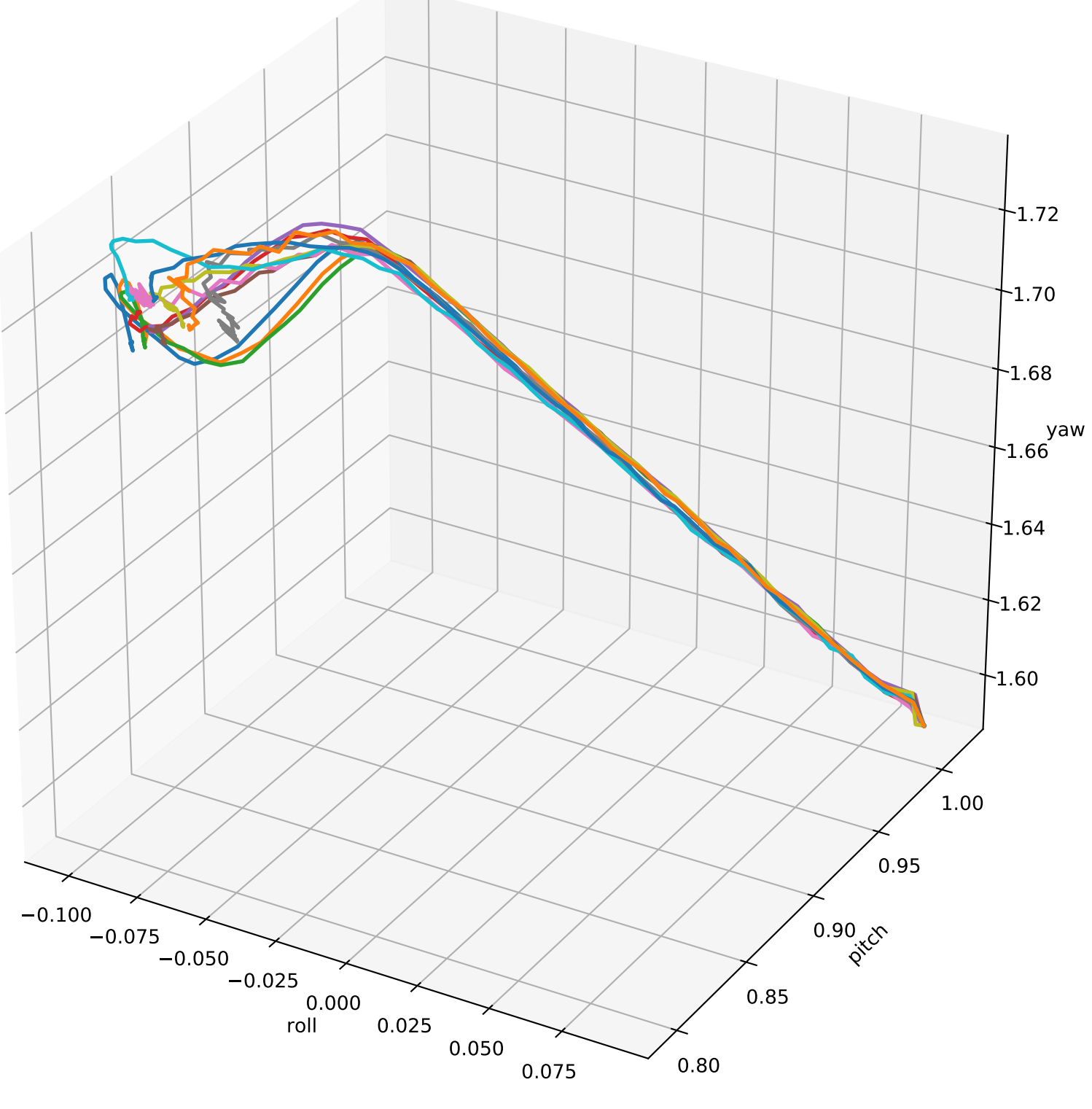


Naive learning method, experiment 1
init_pose = [-0.622, 0.456, 0.337, 0.090, 1.017, 1.588]
goal_pose = [-0.242, 0.366, 0.752, -0.019, 0.737, 1.708]

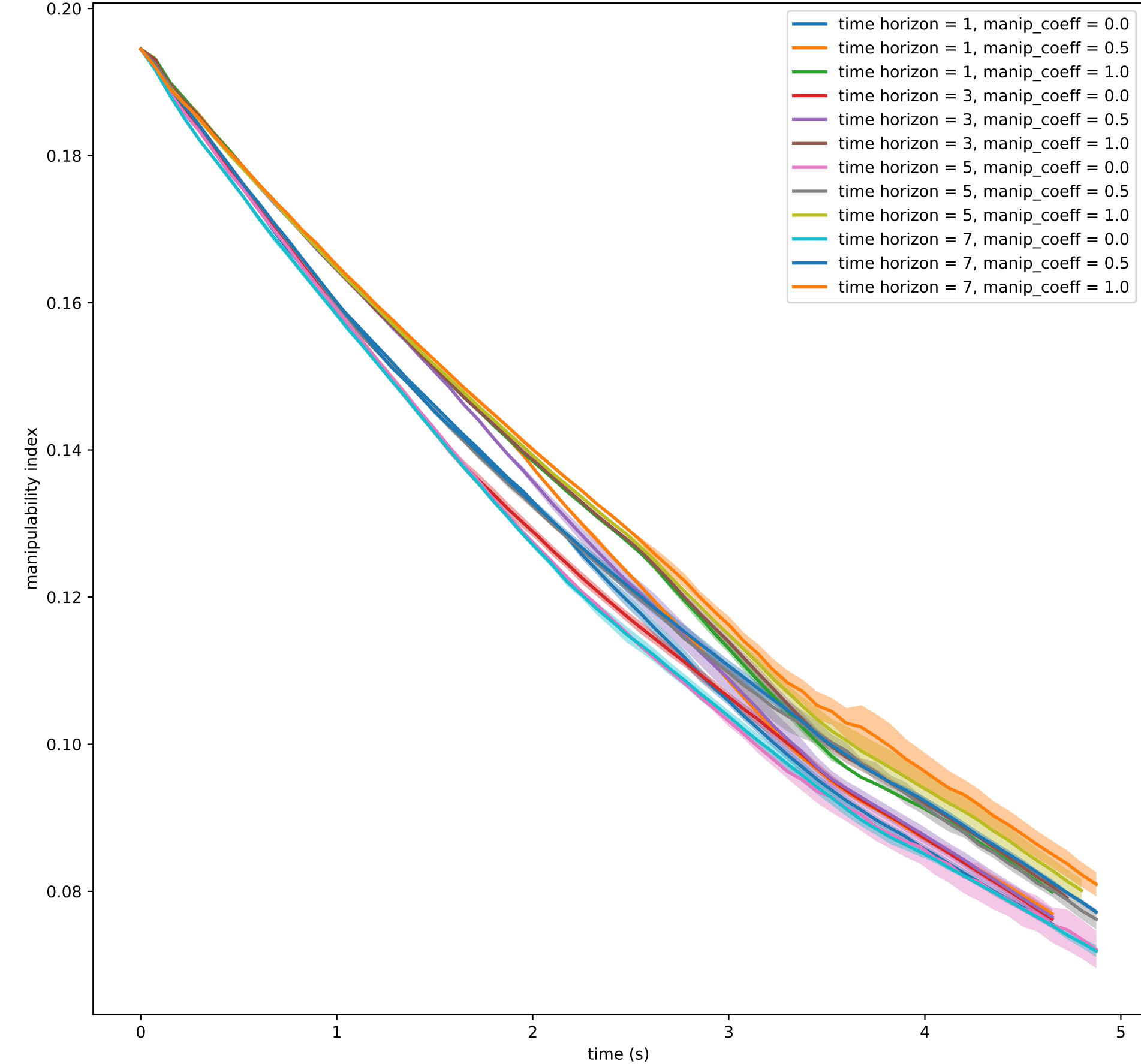
trajectory (translation)



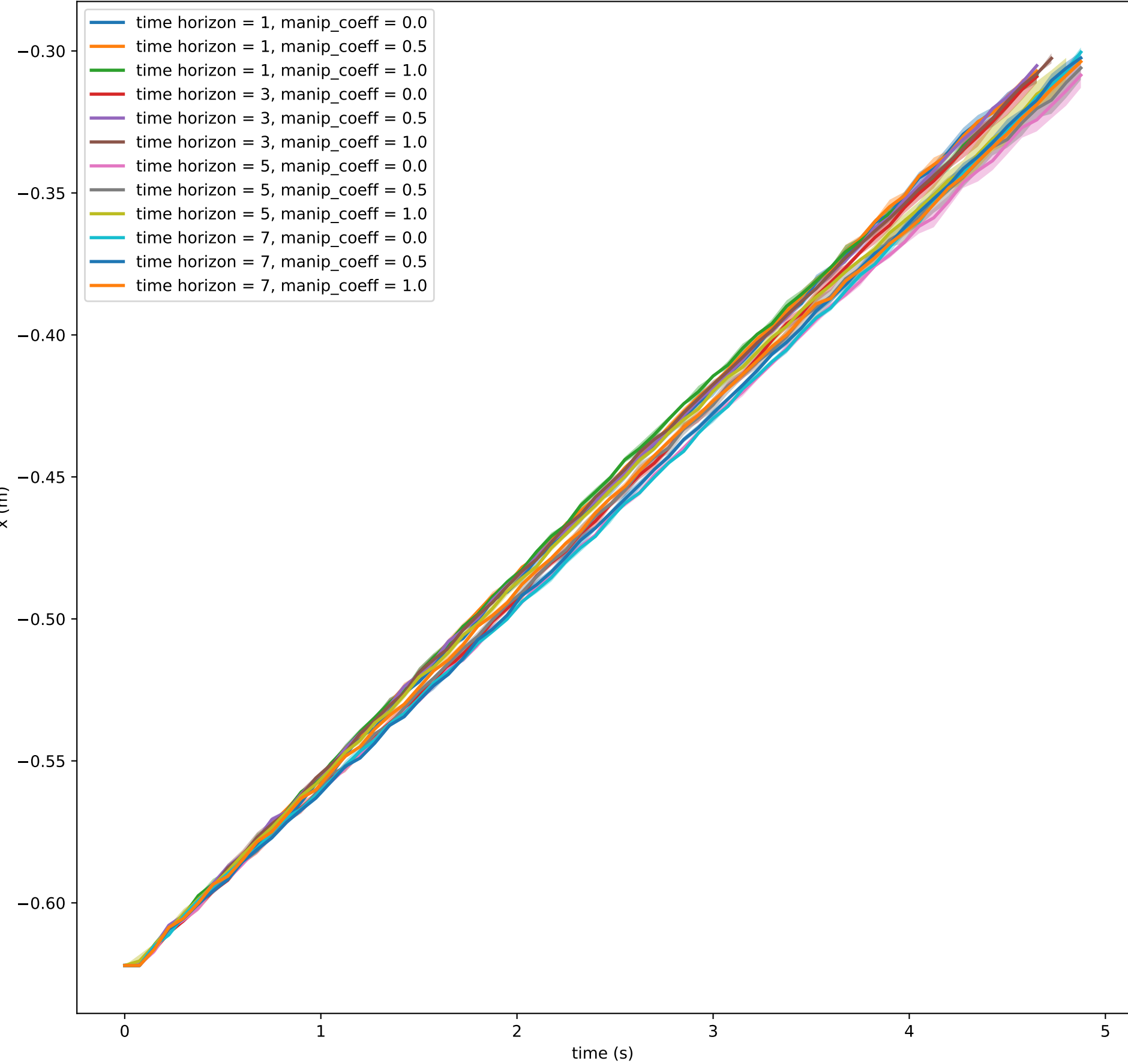
trajectory (orientation)



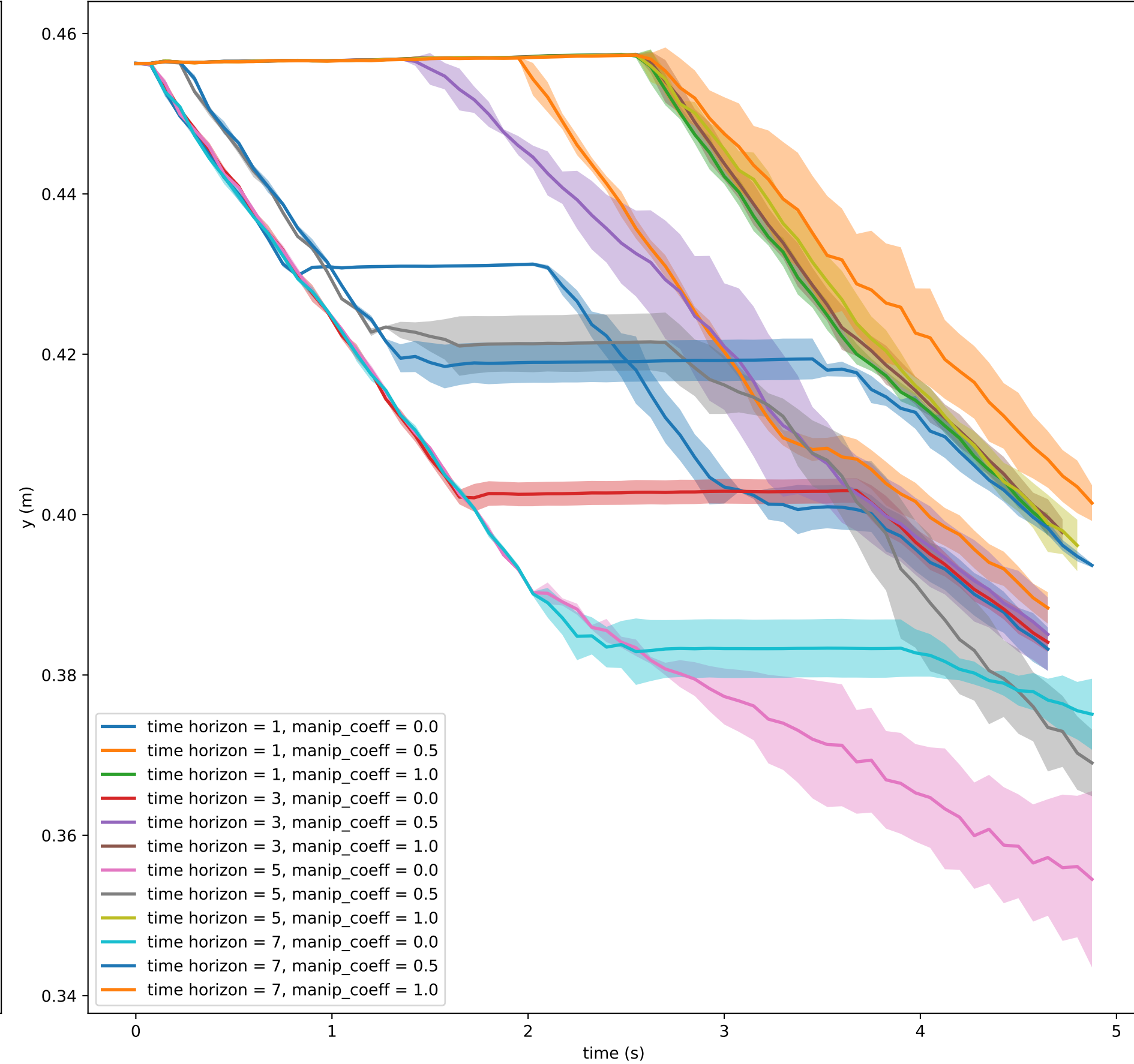
manipulability index



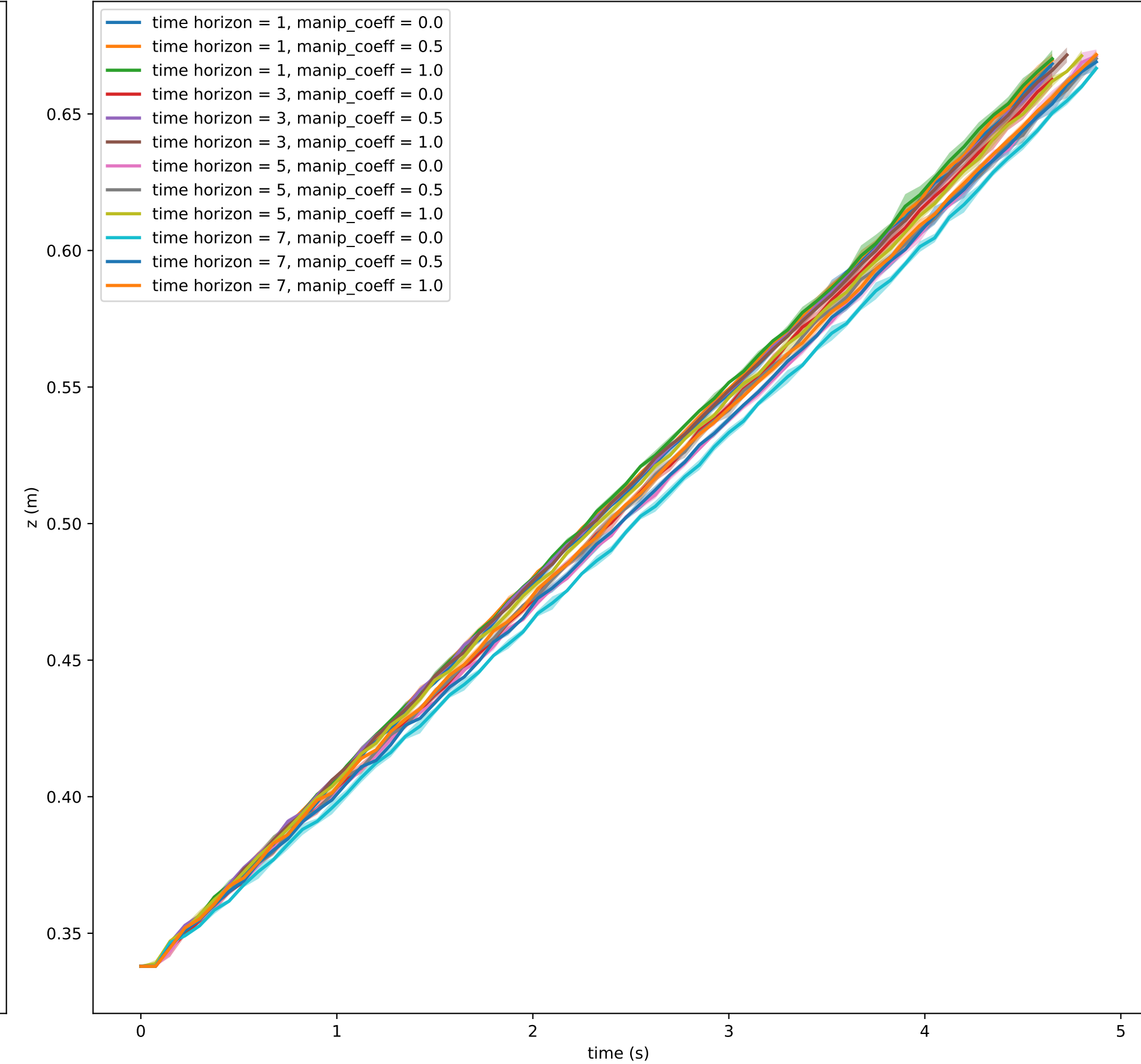
trajectory (x)



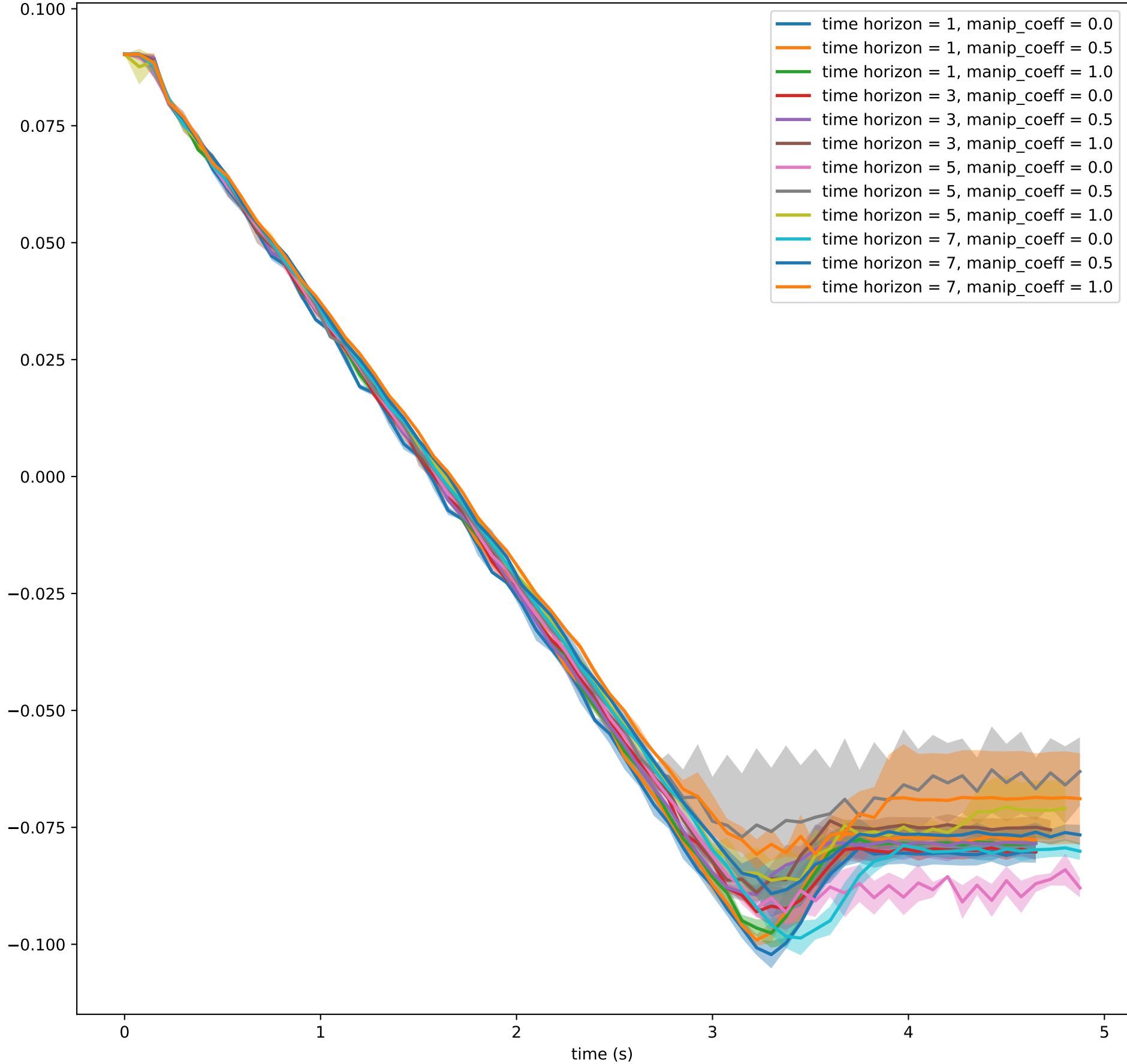
trajectory (y)



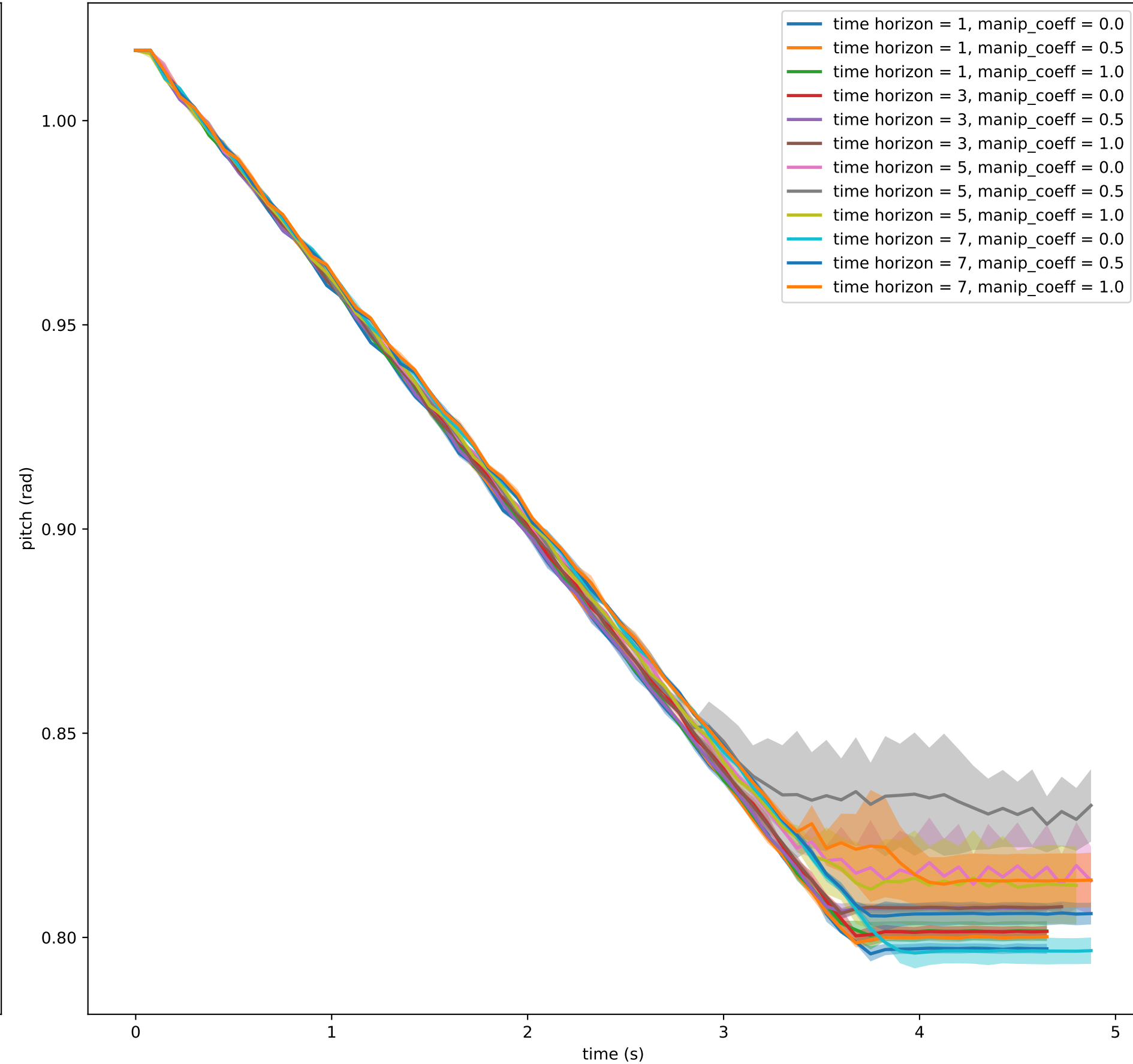
trajectory (z)



trajectory (roll)



trajectory (pitch)



trajectory (yaw)

